

CSE 417: Algorithms and Computational Complexity

Winter 2001
Lecture 1
Instructor: Paul Beame
TA: Gidon Shavit

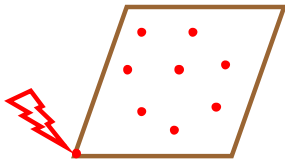
1

A problem

- Printed circuit-board company has a robot arm that solders components to the board
- Time to do it depends on
 - total distance the arm must move from initial rest position around the board and back to the initial positions
- For each board design, must figure out good order to do the soldering

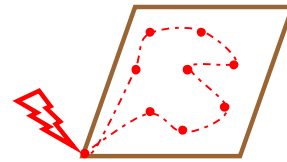
2

Printed Circuit Board



3

Printed Circuit Board



4

A well-defined Problem

- Input: Given a set S of n points in the plane
- Output: The shortest cycle tour that visits each point in the set S .
- How might you solve it?

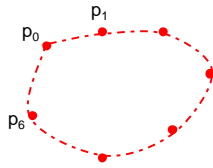
5

Nearest Neighbor Heuristic

- Start at some point p_0
- Walk first to its nearest neighbor p_1
- Repeatedly walk to the nearest unvisited neighbor until all points have been visited
- Then walk back to p_0

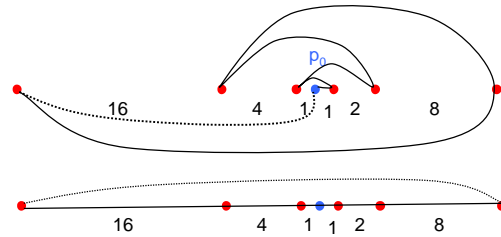
6

Nearest Neighbor Heuristic



7

An input where it works badly



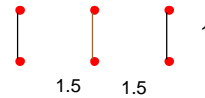
8

Revised idea - Closest Pairs first

- Repeatedly pick the closest pair of points to join so that the result can still be part of a single loop in the end
 - pick endpoints of line segments already created
 - initially line segments consist of single points
 - choose the closest pair of these endpoints that lie on different segments.
- How does this work on our bad example?

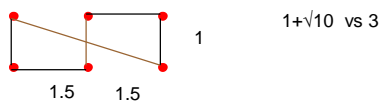
9

Another bad example



10

Another bad example



11

Something that works

- For each of the $n!$ orderings of the points check the length of the cycle you get
- Keep the best one

12

Efficiency

- The two incorrect algorithms were **greedy**
 - ▮ they made choices and never reconsidered their choices
 - ▮ often it does not work
 - ▮ when it does the algorithms are typically efficient
- Our correct algorithm is incredibly slow
 - ▮ $20!$ is so large that counting to one billion in a second it would still take 2.4 billion seconds
 - ▮ (around 70 years!)

13

Measuring efficiency: The RAM model

- RAM = Random Access Machine
- Time \approx # of instructions executed in an ideal assembly language
 - ▮ each simple operation (+, *, -, =, if, call) takes one time step
 - ▮ each memory access takes one time step
- No bound on the memory

14

We left out things but...

- Things we've dropped
 - ▮ memory hierarchy
 - ▮ disk, caches, registers have many orders of magnitude differences in access time
 - ▮ not all instructions take the same time in practice
- However,
 - ▮ the RAM model is very useful for understanding how to design algorithms and get a good sense of how quickly they will work
 - ▮ one can usually tune implementations so that the hierarchy etc is not a huge factor

15

What kind of analysis?

- Problem size n
 - ▮ **Worst-case complexity:** **max** # steps algorithm takes on any input of size n
 - ▮ **Best-case complexity:** **min** # steps algorithm takes on any input of size n
 - ▮ **Average-case complexity:** **avg** # steps algorithm takes on inputs of size n

16

Pros and cons:

- Best-case
 - ▮ unrealistic overselling
 - ▮ can tune an algorithm so it works on one easy input
 - ▮ guarantee isn't comforting
- Worst-case
 - ▮ a fast algorithm has a comforting guarantee
 - ▮ no way to cheat by hard-coding special cases
 - ▮ maybe too pessimistic
- Average-case
 - ▮ over what distribution?
 - ▮ different people may have different average problems

17