# CSE373: Data Structure \& Algorithms Lecture 22: More Sorting 

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## Admin

- Homework 5 partner selection due TODAY!
- Catalyst link posted on the webpage
- Homework 5 due next Wednesday at 11 pm!


## The comparison sorting problem

Assume we have $n$ comparable elements in an array and we want to rearrange them to be in increasing order

Input:

- An array A of data records
- A key value in each data record
- A comparison function (consistent and total)

Effect:

- Reorganize the elements of $\mathbf{A}$ such that for any $\mathbf{i}$ and $\mathbf{j}$, if $\mathrm{i}<\mathrm{j}$ then $\mathrm{A}[\mathrm{i}] \leq \mathrm{A}[\mathrm{j}]$
- (Also, A must have exactly the same data it started with)
- Could also sort in reverse order, of course

An algorithm doing this is a comparison sort

## Sorting: The Big Picture

Surprising amount of neat stuff to say about sorting:
Simple
algorithms:
$\mathbf{O}\left(n^{2}\right)$

Insertion sort
Selection sort Shell sort
Fancier
algorithms:
$O(n \log n)$

Heap sort
Merge sort Quick sort


Bucket sort
Radix sort

Handling huge data sets

External sorting

## Divide and conquer

Very important technique in algorithm design

1. Divide problem into smaller parts
2. Independently solve the simpler parts

- Think recursion
- Or potential parallelism

3. Combine solution of parts to produce overall solution

## Divide-and-Conquer Sorting

Two great sorting methods are fundamentally divide-and-conquer

1. Merge sort: Sort the left half of the elements (recursively) Sort the right half of the elements (recursively) Merge the two sorted halves into a sorted whole
2. Quick sort: Pick a "pivot" element

Divide elements into less-than pivot and greater-than pivot
Sort the two divisions (recursively on each) Answer is sorted-less-than then pivot then sorted-greater-than

## Merge sort



- To sort array from position lo to position hi:
- If range is 1 element long, it is already sorted! (Base case)
- Else:
- Sort from lo to (hi+lo) /2
- Sort from (hi+lo)/2 to hi
- Merge the two halves together
- Merging takes two sorted parts and sorts everything
- $O(n)$ but requires auxiliary space...


## Some details: saving a little time

- What if the final steps of our merge looked like this:

- Wasteful to copy to the auxiliary array just to copy back...


## Some details: saving a little time

- If left-side finishes first, just stop the merge and copy back:

- If right-side finishes first, copy dregs into right then copy back



## Some details: Saving Space and Copying

Simplest / Worst:
Use a new auxiliary array of size (hi-lo) for every merge

Better:
Use a new auxiliary array of size n for every merging stage

Better:
Reuse same auxiliary array of size n for every merging stage

Best (but a little tricky):
Don't copy back - at $2^{\text {nd }}, 4^{\text {th }}, 6^{\text {th }}, \ldots$ merging stages, use the original array as the auxiliary array and vice-versa

- Need one copy at end if number of stages is odd


## Swapping Original / Auxiliary Array ("best")

- First recurse down to lists of size 1
- As we return from the recursion, swap between arrays

$\downarrow$ Copy if Needed
(Arguably easier to code up without recursion at all)

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## Linked lists and big data

We defined sorting over an array, but sometimes you want to sort linked lists

One approach:

- Convert to array: $O(n)$
- Sort: O( $n \log n$ )
- Convert back to list: $O(n)$

Or merge sort works very nicely on linked lists directly

- Heapsort and quicksort do not
- Insertion sort and selection sort do but they're slower

Merge sort is also the sort of choice for external sorting

- Linear merges minimize disk accesses
- And can leverage multiple disks to get streaming accesses


## Quick sort

- A divide-and-conquer algorithm
- Recursively chop into two pieces
- Instead of doing all the work as we merge together, we will do all the work as we recursively split into halves
- Unlike merge sort, does not need auxiliary space
- $O(n \log n)$ on average $\cdot$, but $O\left(n^{2}\right)$ worst-case $\cdot$
- Faster than merge sort in practice?
- Often believed so
- Does fewer copies and more comparisons, so it depends on the relative cost of these two operations!


## Quicksort Overview

1. Pick a pivot element
2. Partition all the data into:
A. The elements less than the pivot
B. The pivot
C. The elements greater than the pivot
3. Recursively sort A and C
4. The answer is, "as simple as $A, B, C$ "

## Think in Terms of Sets



Quicksort( $\mathrm{S}_{1}$ ) and Quicksort( $\mathbf{S}_{2}$ )


$\mathbf{S}$| 0 | 13 | 26 | 31 | 43 | 57 | 65 | 75 | 81 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Presto! S is sorted
[Weiss]

## Example, Showing Recursion



## Details

Have not yet explained:

- How to pick the pivot element
- Any choice is correct: data will end up sorted
- But as analysis will show, want the two partitions to be about equal in size
- How to implement partitioning
- In linear time
- In place


## Pivots

- Best pivot?
- Median
- Halve each time
- Worst pivot?
- Greatest/least element
- Problem of size n-1
- $O\left(n^{2}\right)$


## Potential pivot rules

While sorting arr from lo to hi-1 ...

- Pick arr [lo] or arr [hi-1]
- Fast, but worst-case occurs with mostly sorted input
- Pick random element in the range
- Does as well as any technique, but (pseudo)random number generation can be slow
- Still probably the most elegant approach
- Median of 3, e.g., arr[lo], arr[hi-1], arr[(hi+lo)/2]
- Common heuristic that tends to work well


## Partitioning

- Conceptually simple, but hardest part to code up correctly
- After picking pivot, need to partition in linear time in place
- One approach (there are slightly fancier ones):

1. Swap pivot with arr[lo]
2. Use two fingers $i$ and $j$, starting at $10+1$ and hi-1
3. while (i < j)
if (arr[j] > pivot) j--
else if (arr[i] < pivot) i++
else swap arr[i] with arr[j]
4. Swap pivot with arr [i] *
*skip step 4 if pivot ends up being least element

## Example

- Step one: pick pivot as median of 3
- $\mathrm{lo}=0, \mathrm{hi}=10$

| 0 | 1 |  | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 1 |  | 4 | 9 | 0 | 3 | 5 | 2 | 7 | 6 |  |

- Step two: move pivot to the lo position



## Often have more than one swap during partition this is a short example

Example

Now partition in place


Move fingers


Swap


Move fingers


Move pivot

$$
\begin{array}{|l|l|l|l|l|l|l|l|l|l|}
\hline 5 & 1 & 4 & 2 & 0 & 3 & 6 & 9 & 7 & 8 \\
\hline
\end{array}
$$

## Quick sort visualization

- http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html


## Analysis

- Best-case: Pivot is always the median
$\mathrm{T}(0)=\mathrm{T}(1)=1$
$\mathrm{T}(n)=2 \mathrm{~T}(n / 2)+n \quad$-- linear-time partition
Same recurrence as merge sort: $O(n \log n)$
- Worst-case: Pivot is always smallest or largest element

$$
\begin{aligned}
& \mathrm{T}(0)=\mathrm{T}(1)=1 \\
& \mathrm{~T}(n)=1 \mathrm{~T}(n-1)+n
\end{aligned}
$$

Basically same recurrence as selection sort: $O\left(n^{2}\right)$

- Average-case (e.g., with random pivot)
- O( $n \log n$ ), not responsible for proof (in text)


## Cutoffs

- For small $n$, all that recursion tends to cost more than doing a quadratic sort
- Remember asymptotic complexity is for large $n$
- Common engineering technique: switch algorithm below a cutoff
- Reasonable rule of thumb: use insertion sort for $n<10$
- Notes:
- Could also use a cutoff for merge sort
- Cutoffs are also the norm with parallel algorithms
- Switch to sequential algorithm
- None of this affects asymptotic complexity


## Cutoff pseudocode

```
void quicksort(int[] arr, int lo, int hi) {
    if(hi - lo < CUTOFF)
        insertionSort(arr,lo,hi) ;
    else
}
```

Notice how this cuts out the vast majority of the recursive calls

- Think of the recursive calls to quicksort as a tree
- Trims out the bottom layers of the tree


## How Fast Can We Sort?

- Heapsort \& mergesort have $O(n \log n)$ worst-case running time
- Quicksort has $O(n \log n)$ average-case running time
- These bounds are all tight, actually $\Theta(n \log n)$
- Comparison sorting in general is $\Omega(n \log n)$
- An amazing computer-science result: proves all the clever programming in the world cannot comparison-sort in linear time


## The Big Picture

Surprising amount of juicy computer science: 2-3 lectures...


## Bucket Sort (a.k.a. BinSort)

- If all values to be sorted are known to be integers between 1 and $K$ (or any small range):
- Create an array of size $K$
- Put each element in its proper bucket (a.k.a. bin)
- If data is only integers, no need to store more than a count of how times that bucket has been used
- Output result via linear pass through array of buckets

| count array |  |
| :--- | :--- |
| 1 | 3 |
| 2 | 1 |
| 3 | 2 |
| 4 | 2 |
| 5 | 3 |

- Example:

$$
K=5
$$

input (5, 1,3,4,3,2,1,1,5,4,5)
output: $1,1,1,2,3,3,4,4,5,5,5$

## Visualization

- htto://www.cs.usfca.edu/~galles/visualization/CountingSort.html


## Analyzing Bucket Sort

- Overall: $O(n+K)$
- Linear in $n$, but also linear in $K$
- $\Omega(n \log n)$ lower bound does not apply because this is not a comparison sort
- Good when $K$ is smaller (or not much larger) than $n$
- We don't spend time doing comparisons of duplicates
- Bad when $K$ is much larger than $n$
- Wasted space; wasted time during linear $O(K)$ pass
- For data in addition to integer keys, use list at each bucket


## Bucket Sort with Data

- Most real lists aren't just keys; we have data
- Each bucket is a list (say, linked list)
- To add to a bucket, insert in $O(1)$ (at beginning, or keep pointer to last element)

| count array |  |
| :--- | :--- | |  |
| :--- |

- Example: Movie ratings; scale 1-5;1=bad, 5=excellent Input=

5: Casablanca
3: Harry Potter movies
5: Star Wars Original Trilogy
1: Rocky V
-Result: 1: Rocky V, 3: Harry Potter, 5: Casablanca, 5: Star Wars
-Easy to keep 'stable'; Casablanca still before Star Wars

## Radix sort

- Radix = "the base of a number system"
- Examples will use 10 because we are used to that
- In implementations use larger numbers
- For example, for ASCII strings, might use 128
- Idea:
- Bucket sort on one digit at a time
- Number of buckets = radix
- Starting with least significant digit
- Keeping sort stable
- Do one pass per digit
- Invariant: After $k$ passes (digits), the last $k$ digits are sorted
- Aside: Origins go back to the 1890 U.S. census


## Example

Radix $=10$

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 721 |  | 3 |  |  |  | 537 | 478 | 9 |
|  |  |  | 143 |  |  |  | 67 | 38 |  |

Input: 478
537
9
721
3
38
143
67

First pass:
bucket sort by ones digit
Order now: 721

143
537
67
478


## Example

Radix $=10$

Order was:

| 3 |
| ---: |
| 9 |
| 721 |
| 537 |
| 38 |
| 143 |
| 67 |
| 478 |


| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3 |  | 721 | 537 | 143 |  | 67 | 478 |  |  |
| 9 |  |  | 38 |  |  |  |  |  |  |

Third pass:
stable bucket sort by 100s digit

## Visualization

- http://www.cs.usfca.edu/~galles/visualization/RadixSort.html


## Analysis

Input size: $n$
Number of buckets = Radix: $B$
Number of passes = "Digits": $P$
Work per pass is 1 bucket sort: $O(B+n)$
Total work is $O(P(B+n))$
Compared to comparison sorts, sometimes a win, but often not

- Example: Strings of English letters up to length 15
- Run-time proportional to: $15^{*}(52+n)$
- This is less than $n$ log $n$ only if $n>33,000$
- Of course, cross-over point depends on constant factors of the implementations
- And radix sort can have poor locality properties


## Sorting massive data

- Need sorting algorithms that minimize disk/tape access time:
- Quicksort and Heapsort both jump all over the array, leading to expensive random disk accesses
- Merge sort scans linearly through arrays, leading to (relatively) efficient sequential disk access
- Merge sort is the basis of massive sorting
- Merge sort can leverage multiple disks


## External Merge Sort

- Sort 900 MB using 100 MB RAM
- Read 100 MB of data into memory
- Sort using conventional method (e.g. quicksort)
- Write sorted 100MB to temp file
- Repeat until all data in sorted chunks (900/100 = 9 total)
- Read first 10 MB of each sorted chuck, merge into remaining 10MB
- writing and reading as necessary
- Single merge pass instead of $\log n$
- Additional pass helpful if data much larger than memory
- Parallelism and better hardware can improve performance
- Distribution sorts (similar to bucket sort) are also used


## Last Slide on Sorting

- Simple $O\left(n^{2}\right)$ sorts can be fastest for small $n$
- Selection sort, Insertion sort (latter linear for mostly-sorted)
- Good for "below a cut-off" to help divide-and-conquer sorts
- $O(n \log n)$ sorts
- Heap sort, in-place but not stable nor parallelizable
- Merge sort, not in place but stable and works as external sort
- Quick sort, in place but not stable and $O\left(n^{2}\right)$ in worst-case
- Often fastest, but depends on costs of comparisons/copies
- $\Omega(n \log n)$ is worst-case and average lower-bound for sorting by comparisons
- Non-comparison sorts
- Bucket sort good for small number of possible key values
- Radix sort uses fewer buckets and more phases
- Best way to sort? It depends!

