

Graphs: More on Shortest Paths, Plus Minimum Spanning Trees

CSE 373
Data Structures and Algorithms

Correctness: The Cloud Proof

How does Dijkstra's decide which vertex to add to the Known set next?

- If path to **V** is shortest, path to **W** must be *at least as long* (or else we would have picked **W** as the next vertex)
- So the path through **W** to **V** cannot be any shorter!

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Correctness: Inside the Cloud

Prove by induction on # of nodes in the cloud:
Initial cloud is just the source with shortest path 0

Assume: Everything inside the cloud has the correct shortest path

Inductive step: Only when we prove the shortest path to some node *v* (which is not in the cloud) is correct, we add it to the cloud

When does Dijkstra's algorithm not work?

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Dijkstra's vs BFS

<p>At each step:</p> <ol style="list-style-type: none"> Pick closest unknown vertex Add it to finished vertices Update distances <p style="text-align: center;"><i>Dijkstra's Algorithm</i></p>	<p>At each step:</p> <ol style="list-style-type: none"> Pick vertex from queue Add it to visited vertices Update queue with neighbors <p style="text-align: center;"><i>Breadth-first Search</i></p>
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Some Similarities:

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The Trouble with Negative Weight Cycles

What's the shortest path from A to E?

Problem?

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Minimum Spanning Trees

Given an undirected graph $G=(V,E)$, find a graph $G'=(V, E')$ such that:

- E' is a subset of E
- $|E'| = |V| - 1$
- G' is connected
- G' is minimal

G' is a **minimum spanning tree.**

$$\sum_{(u,v) \in E'} c_{uv}$$

Applications: wiring a house, power grids, Internet connections

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Student Activity

Find the MST

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Two Different Approaches

Prim's Algorithm
Almost identical to Dijkstra's

Kruskals's Algorithm
Completely different!

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Prim's algorithm

Idea: Grow a tree by adding an edge from the "known" vertices to the "unknown" vertices. Pick the edge with the smallest weight.

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Prim's Algorithm for MST

A node-based greedy algorithm
Builds MST by greedily adding nodes

- Select a node to be the "root"
 - mark it as known
 - Update cost of all its neighbors
- While there are unknown nodes left in the graph
 - Select an unknown node b with the smallest cost from some known node a
 - Mark b as known
 - Add (a, b) to MST
 - Update cost of all nodes adjacent to b

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Student Activity

Start with V_1

Find MST using Prim's

V	Kwn	Distance	path
v1			
v2			
v3			
v4			
v5			
v6			
v7			

Order Declared Known:
 V_1

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Prim's Algorithm Analysis

Running time:
Same as Dijkstra's: $O(|E| \log |V|)$

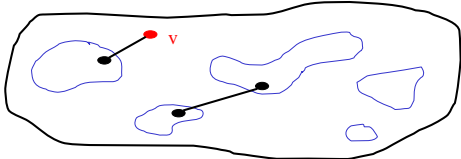
Correctness:
Proof is similar to Dijkstra's

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Kruskal's MST Algorithm

Idea: Grow a **forest** out of edges that do not create a cycle. Pick an edge with the smallest weight.

$G=(V,E)$



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Kruskal's Algorithm for MST

An edge-based greedy algorithm
Builds MST by greedily adding edges

1. Initialize with
 - empty MST
 - all vertices marked unconnected
 - all edges unmarked
2. While there are still unmarked edges
 - a. Pick the **lowest cost edge** (u, v) and mark it
 - b. If u and v are not already connected, add (u, v) to the MST and mark u and v as connected to each other

Doesn't it sound familiar?

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Kruskal code

```
void Graph::kruskal(){
    int edgesAccepted = 0;
    DisjSet s(NUM_VERTICES);

    while (edgesAccepted < NUM_VERTICES - 1){
        e = smallest weight edge not deleted yet;
        // edge e = (u, v)
        uset = s.find(u);
        vset = s.find(v);
        if (uset != vset){
            edgesAccepted++;
            s.unionSets(uset, vset);
        }
    }
}
```

$|E|$ heap ops

$2|E|$ finds

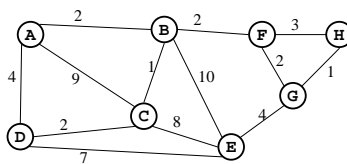
$|V|$ unions

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Student Activity

Find MST using Kruskal's



Total Cost:

- Now find the MST using Prim's method.
- Under what conditions will these methods give the same result?

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