

# CSE 332 Winter 2024

## Lecture 7: Dictionaries, BSTs

Nathan Brunelle

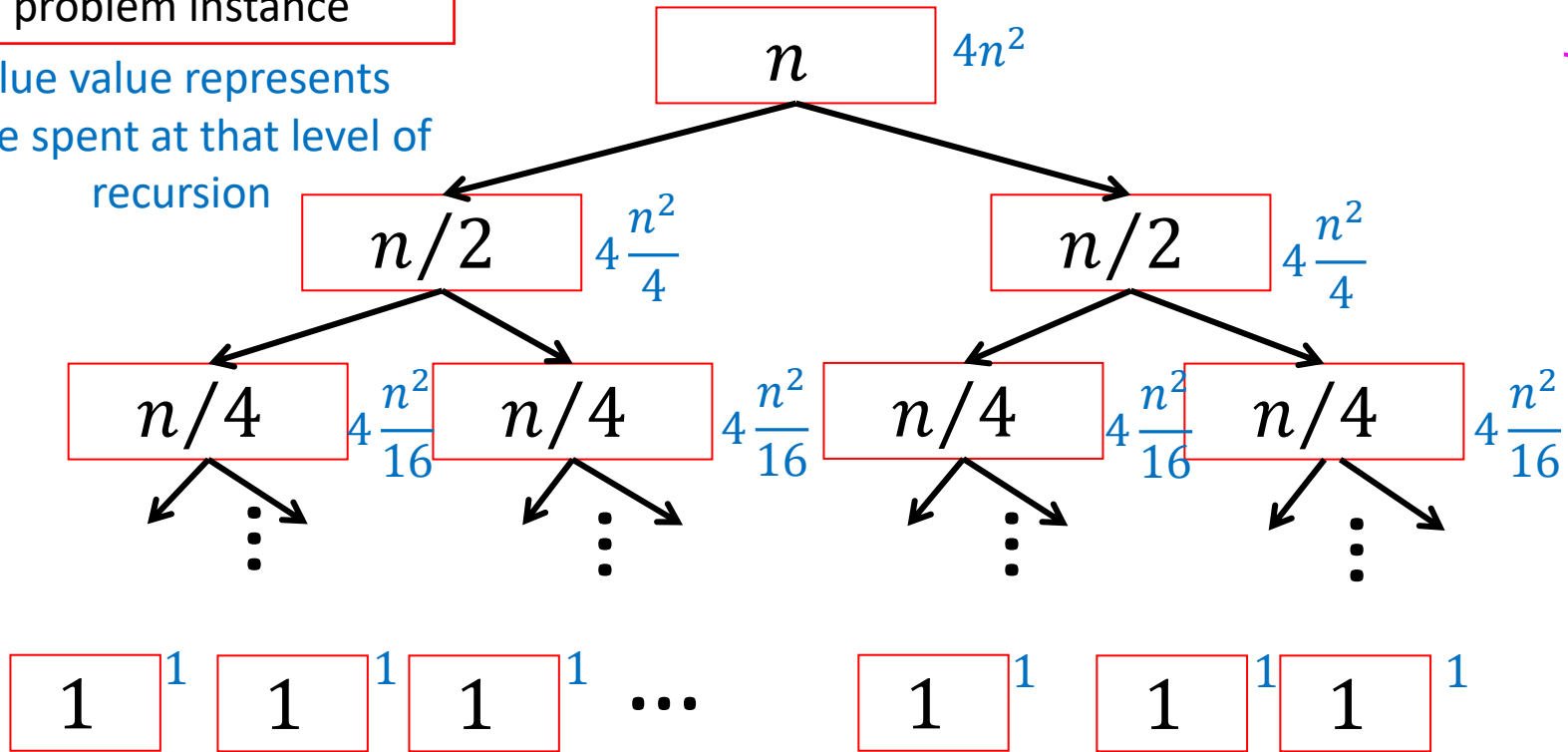
<http://www.cs.uw.edu/332>

# Warm Up: Tree Method

$$T(n) = 2T\left(\frac{n}{2}\right) + 4n^2$$

Red box represents a problem instance

Blue value represents time spent at that level of recursion



$\Rightarrow 4 \frac{n^2}{4^i}$  work at level  $i$

$\log_2 n$  levels of recursion

$$T(n) = \sum_{i=1}^{\log_2 n} 4 \frac{n^2}{4^i} = 4n^2 \sum_{i=1}^{\log_2 n} \frac{1}{4^i} = \Theta(n^2)$$

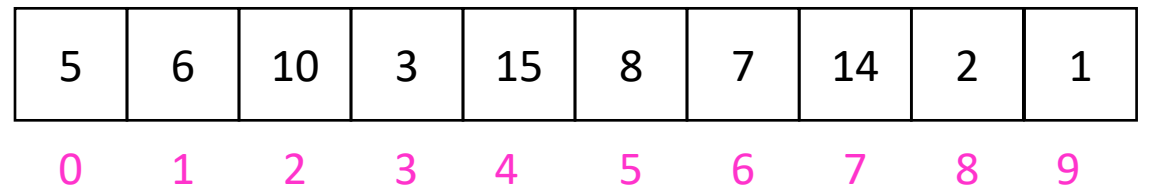
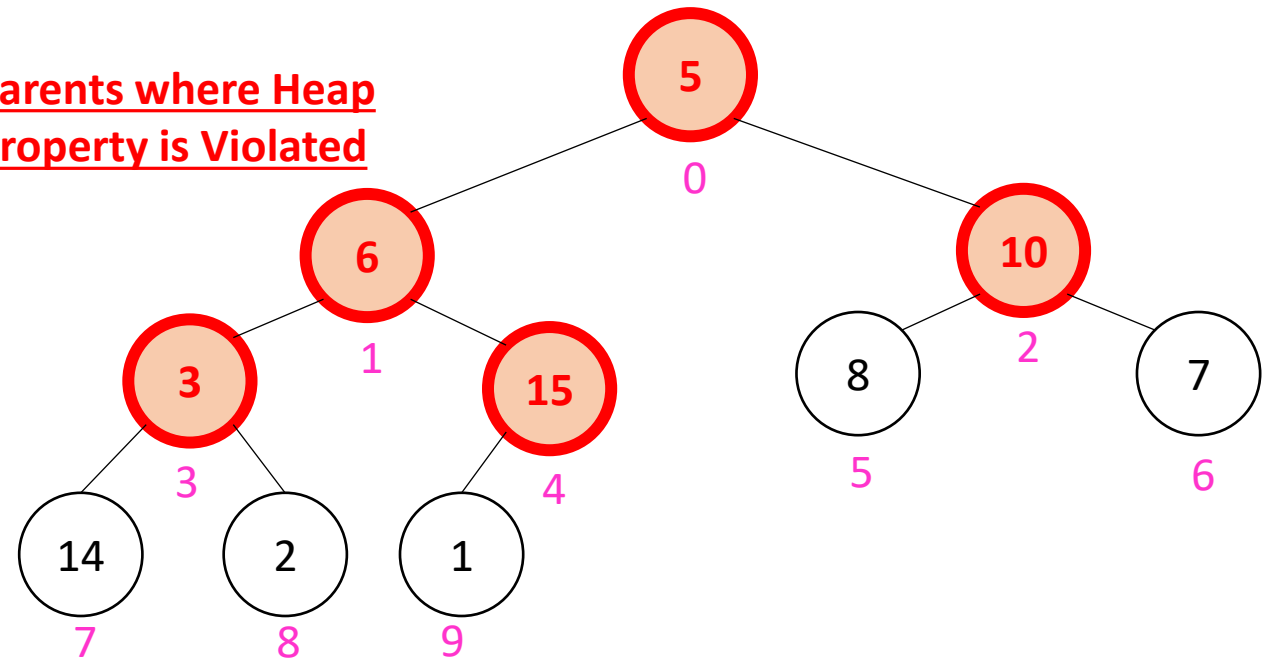
# Warm Up: Which is better?

Both of the following build a binary heap within an unordered array.  
Which is better?

```
buildHeapDown(arr){  
  for(int i = arr.length; i>0; i--){  
    percolateDown(arr, i);  
  }  
}
```

```
buildHeapUp(arr){  
  for(int i = 0; i<arr.length; i++){  
    percolateUp(arr, i);  
  }  
}
```

Parents where Heap  
Property is Violated



# Dictionary (Map) ADT

- Contents:
  - Sets of key+value pairs
  - Keys must be comparable
- Operations:
  - insert(key, value)
    - Adds the (key,value) pair into the dictionary
    - If the key already has a value, overwrite the old value
      - Consequence: Keys cannot be repeated
  - find(key)
    - Returns the value associated with the given key
  - delete(key)
    - Remove the key (and its associated value)

# Naïve attempts

| Data Structure       | Time to insert | Time to find     | Time to delete |
|----------------------|----------------|------------------|----------------|
| Unsorted Array       | $\Theta(n)$    | $\Theta(n)$      | $\Theta(n)$    |
| Unsorted Linked List | $\Theta(n)$    | $\Theta(n)$      | $\Theta(n)$    |
| Sorted Array         | $\Theta(n)$    | $\Theta(\log n)$ | $\Theta(n)$    |
| Sorted Linked List   | $\Theta(n)$    | $\Theta(n)$      | $\Theta(n)$    |

# Less Naïve attempts

- Binary Search Trees (today)
- Tries (Project)
- AVL Trees (next week)
- B-Trees (next week)
- HashTables (week after)
- Red-Black Trees (not included in this course)
- Splay Trees (not included in this course)

# Naïve attempts

| Data Structure               | Time to insert   | Time to find     | Time to delete   |
|------------------------------|------------------|------------------|------------------|
| Unsorted Array               | $\Theta(n)$      | $\Theta(n)$      | $\Theta(n)$      |
| Unsorted Linked List         | $\Theta(n)$      | $\Theta(n)$      | $\Theta(n)$      |
| Sorted Array                 | $\Theta(n)$      | $\Theta(\log n)$ | $\Theta(n)$      |
| Sorted Linked List           | $\Theta(n)$      | $\Theta(n)$      | $\Theta(n)$      |
| Binary Search Tree (W.C.)    | $\Theta(n)$      | $\Theta(n)$      | $\Theta(n)$      |
| Binary Search Tree (average) | $\Theta(\log n)$ | $\Theta(\log n)$ | $\Theta(\log n)$ |

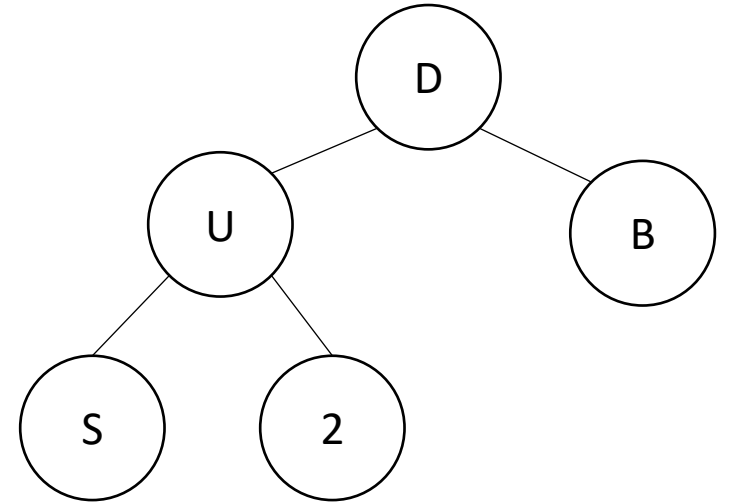
# Tree Height

```
treeHeight(root){
    height = 0;
    if (root.left != Null){
        height = max(height, treeHeight(root.left));
    }
    if (root.right != Null){
        height = max(height, treeHeight(root.right));
    }
    return height;
}
```



# More Tree “Vocab”

- Traversal:
  - An algorithm for “visiting/processing” every node in a tree
- Pre-Order Traversal:
  - Root, Left Subtree, Right Subtree
- In-Order Traversal:
  - Left Subtree, Root, Right Subtree
- Post-Order Traversal
  - Left Subtree, Right Subtree, Root



# Name that Traversal!

```
AorderTraversal(root){  
    if (root.left != Null){  
        process(root.left);  
    }  
    if (root.right != Null){  
        process(root.right);  
    }  
    process(root);  
}
```

```
BorderTraversal(root){  
    process(root);  
    if (root.left != Null){  
        process(root.left);  
    }  
    if (root.right != Null){  
        process(root.right);  
    }  
}
```

```
CorderTraversal(root){  
    if (root.left != Null){  
        process(root.left);  
    }  
    process(root)  
    if (root.right != Null){  
        process(root.right);  
    }  
}
```

# Binary Search Tree

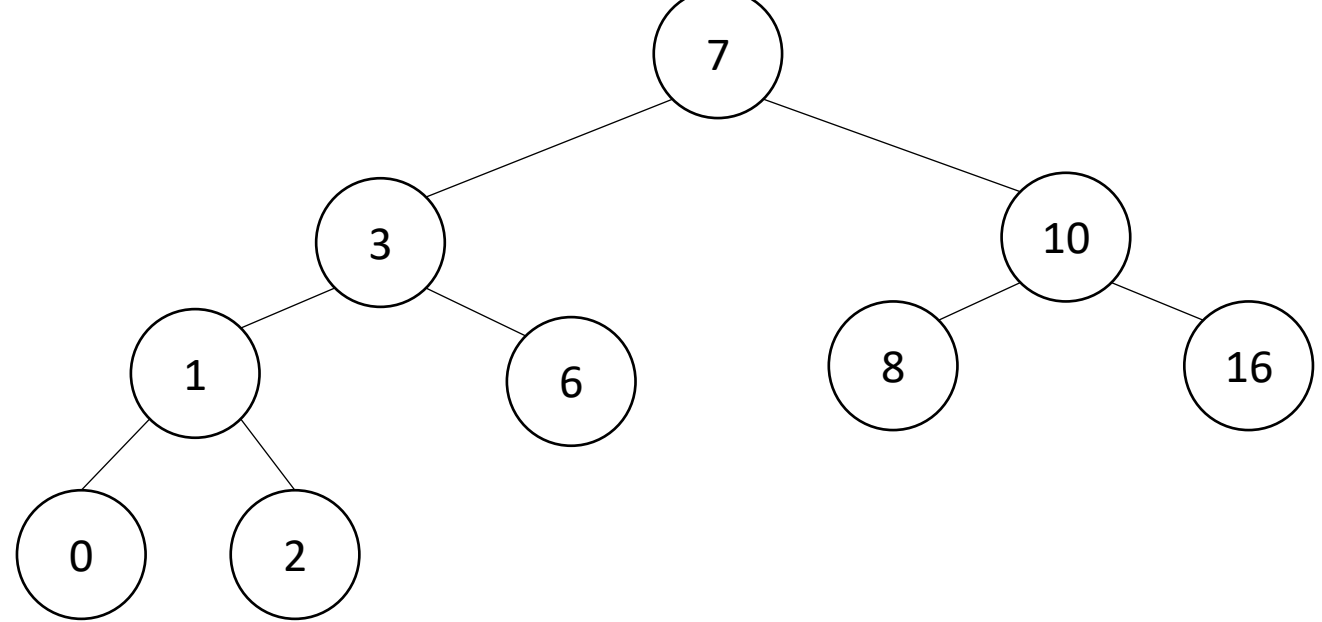
- Binary Tree

- Definition:

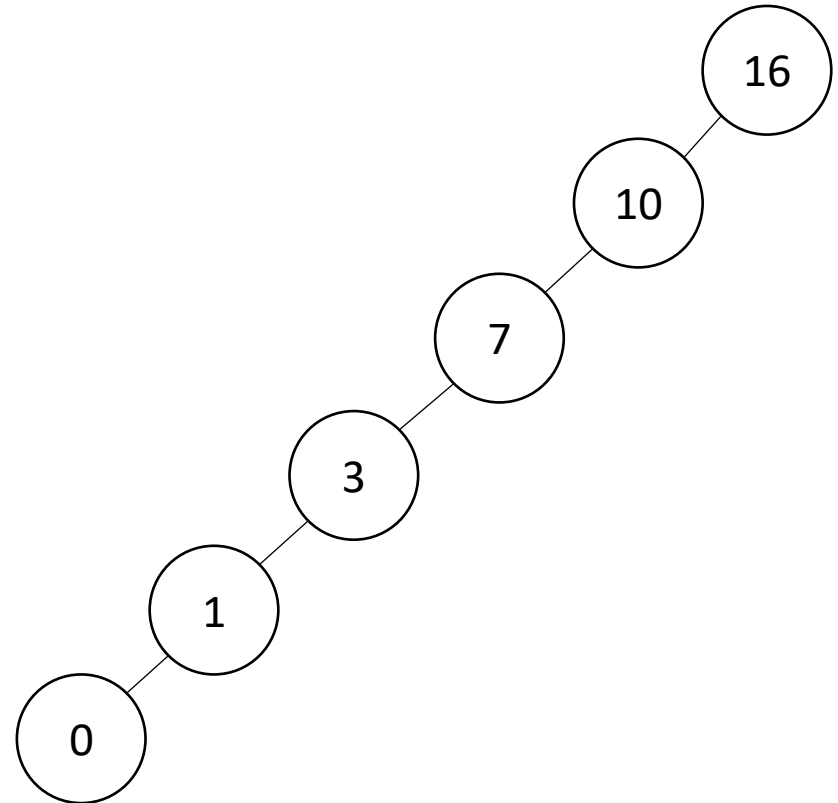
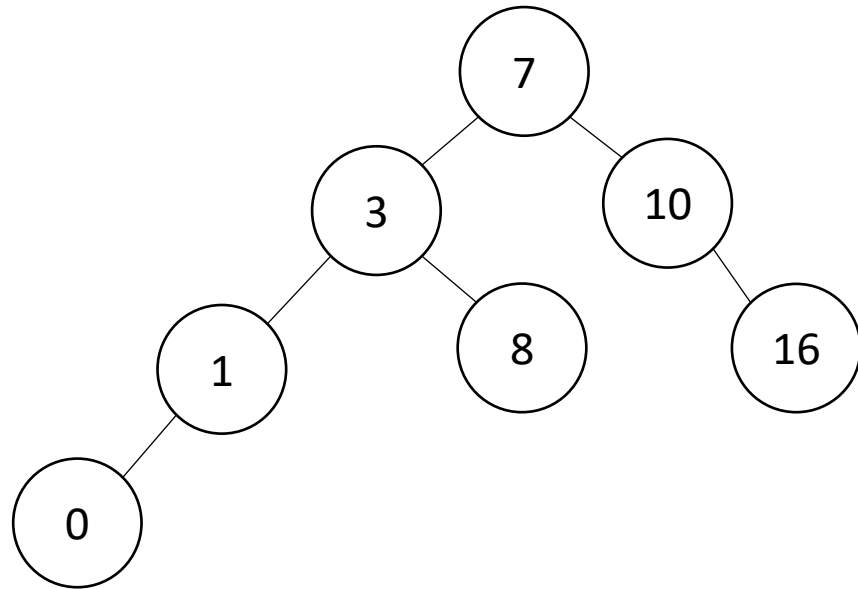
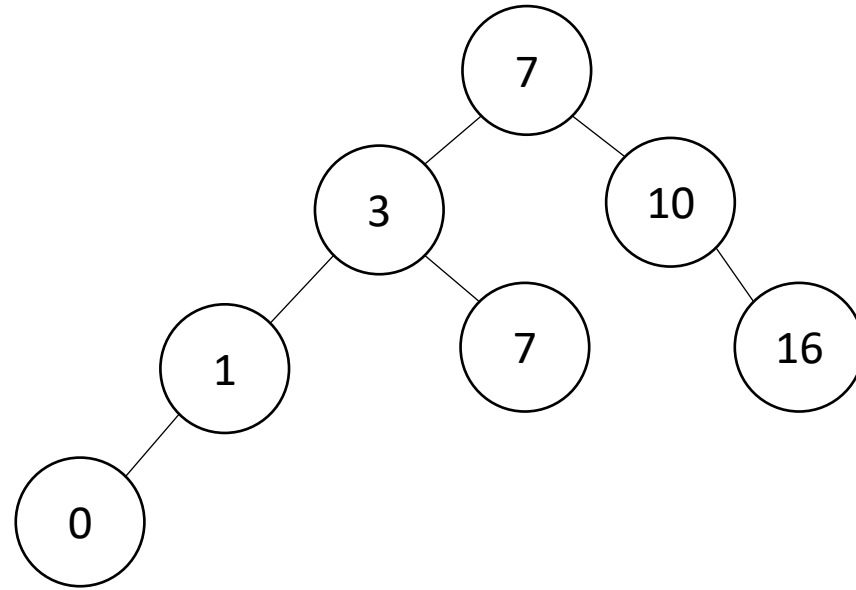
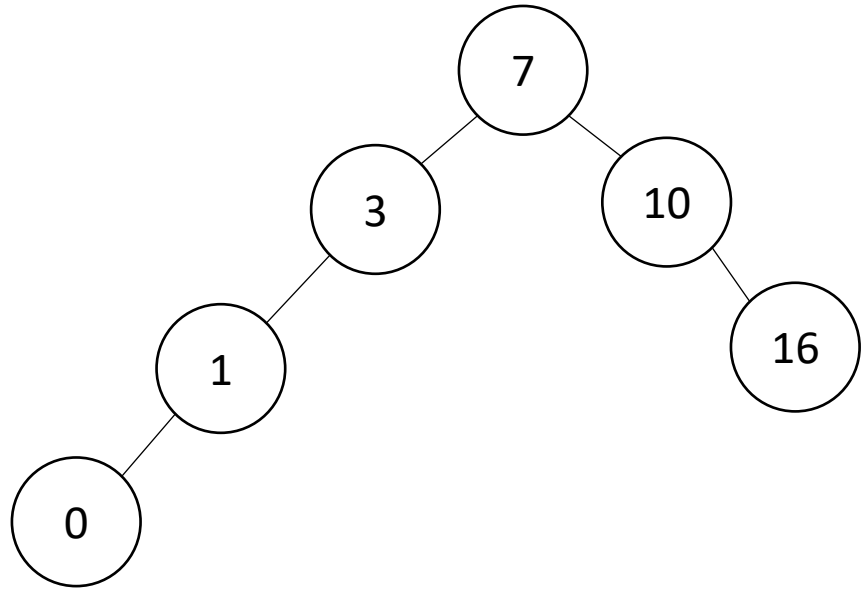
- Order Property

- All keys in the left subtree are smaller than the root
  - All keys in the right subtree are larger than the root

- Why?

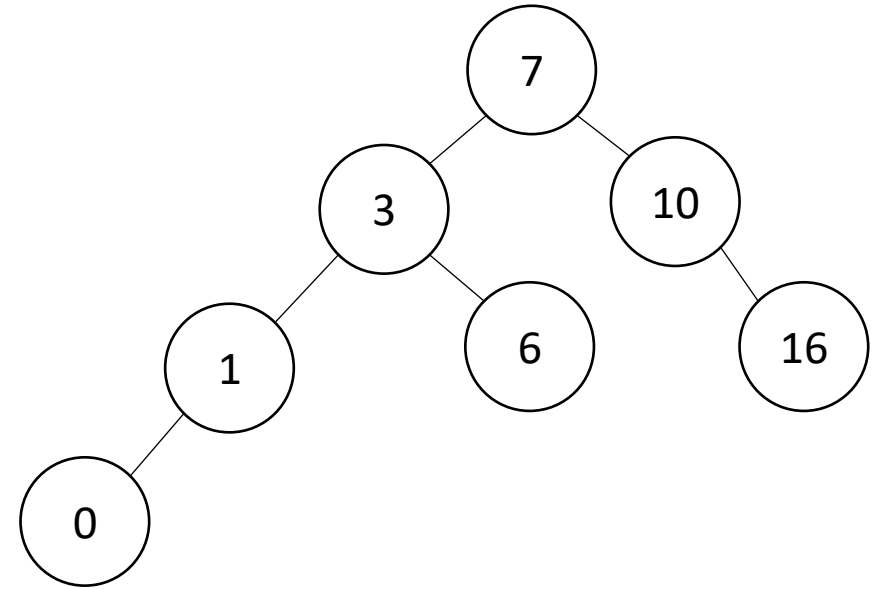


# Are these BSTs?



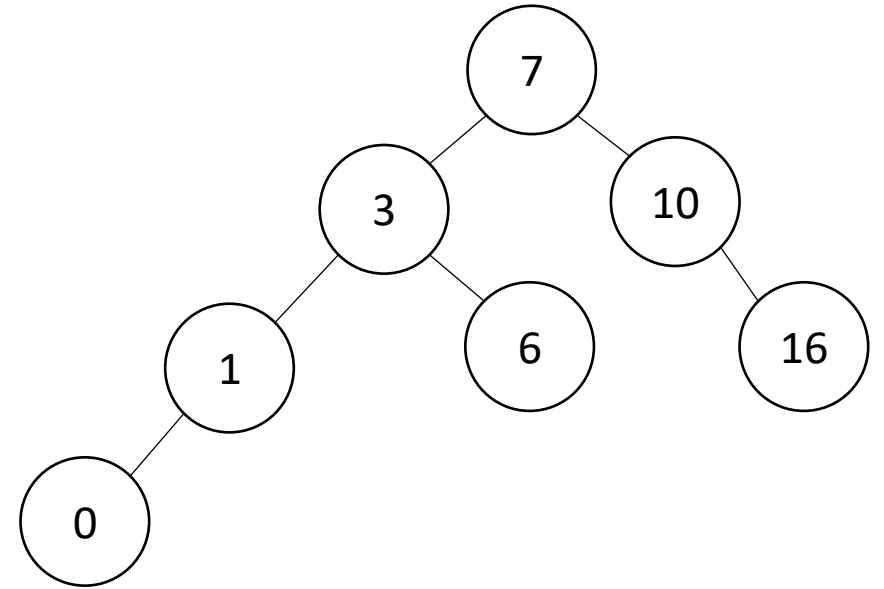
# Find Operation (recursive)

```
find(key, root){  
    if (root == Null){  
        return Null;  
    }  
    if (key == root.key){  
        return root.value;  
    }  
    if (key < root.key){  
        return find(key, root.left);  
    }  
    if (key > root.key){  
        return find(key, root.right);  
    }  
    return Null;  
}
```



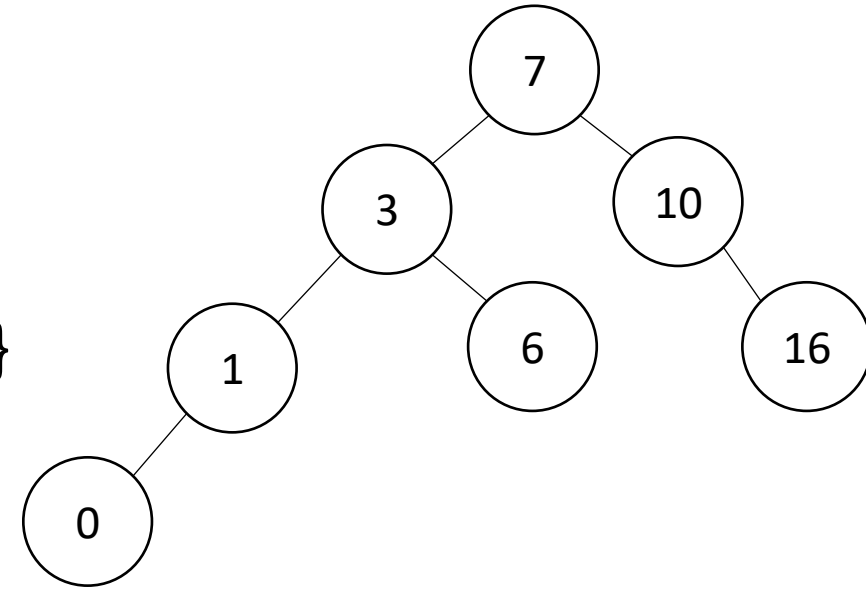
# Find Operation (iterative)

```
find(key, root){  
    while (root != Null && key != root.key){  
        if (key < root.key){  
            root = root.left;  
        }  
        else if (key > root.key){  
            root = root.right;  
        }  
    }  
    if (root == Null){  
        return Null;  
    }  
    return root.value;  
}
```



# Insert Operation (iterative)

```
insert(key, value, root){  
  if (root == Null){ this.root = new Node(key, value); }  
  parent = Null;  
  while (root != Null && key != root.key){  
    parent = root;  
    if (key < root.key){ root = root.left; }  
    else if (key > root.key){ root = root.right; }  
  }  
  if (root != Null){ root.value = value; }  
  else if (key < parent.key){ parent.left = new Node(key, value); }  
  else{ parent.right = new Node (key, value); }  
}
```



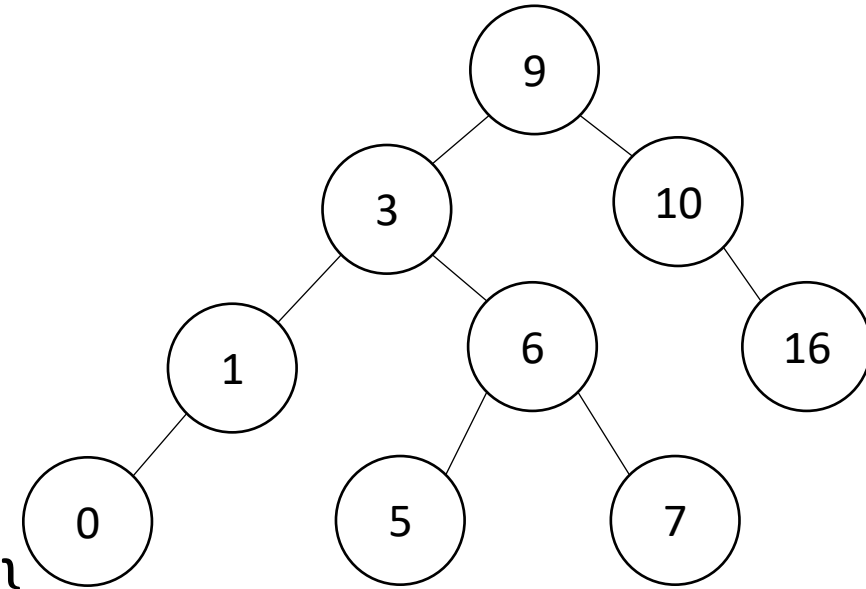
**Note: Insert happens only at the leaves!**





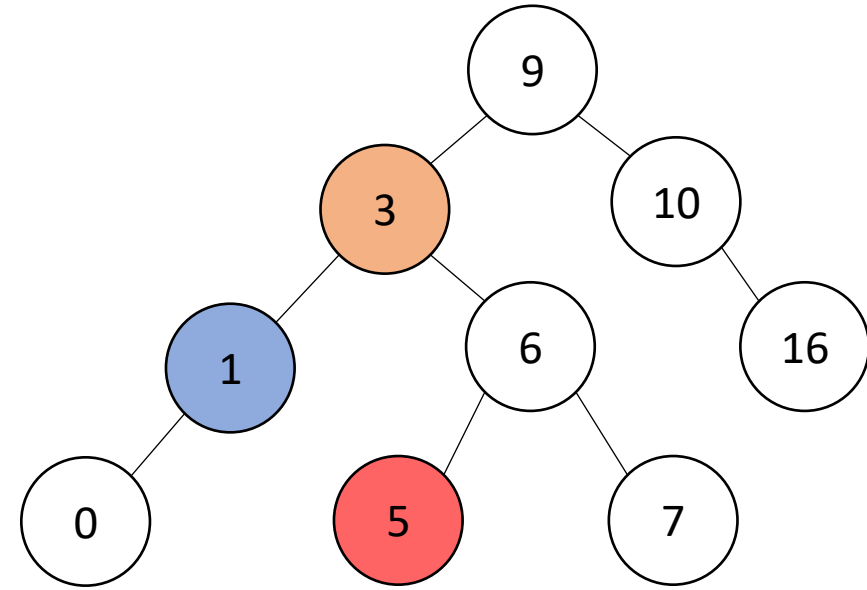
# Delete Operation (iterative)

```
delete(key, root){  
  while (root != Null && key != root.key){  
    if (key < root.key){ root = root.left; }  
    else if (key > root.key){ root = root.right; }  
  }  
  if (root == Null){ return; }  
  // Now root is the node to delete, what happens next?  
}
```



# Delete – 3 Cases

- 0 Children (i.e. it's a leaf)
- 1 Child
- 2 Children

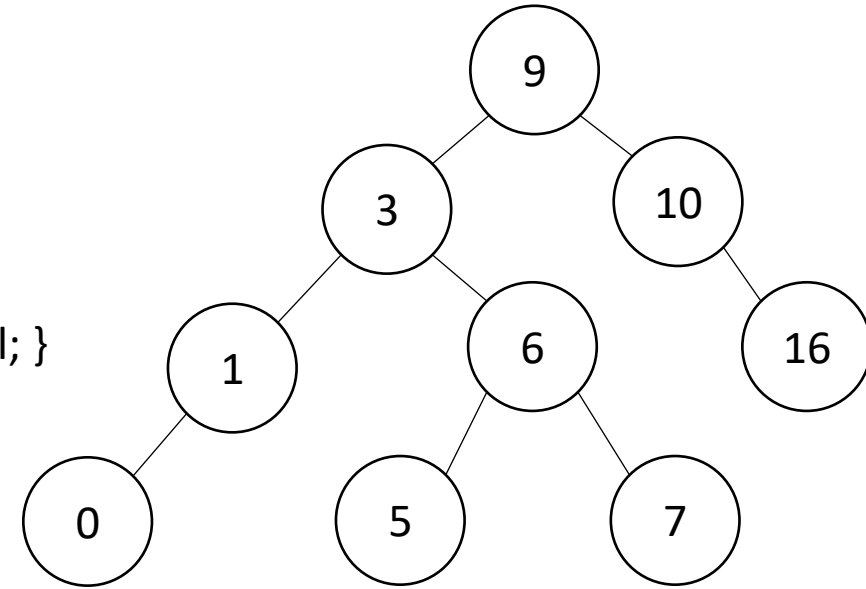


# Finding the Max and Min

- Max of a BST:
  - Right-most Thing
- Min of a BST:
  - Left-most Thing

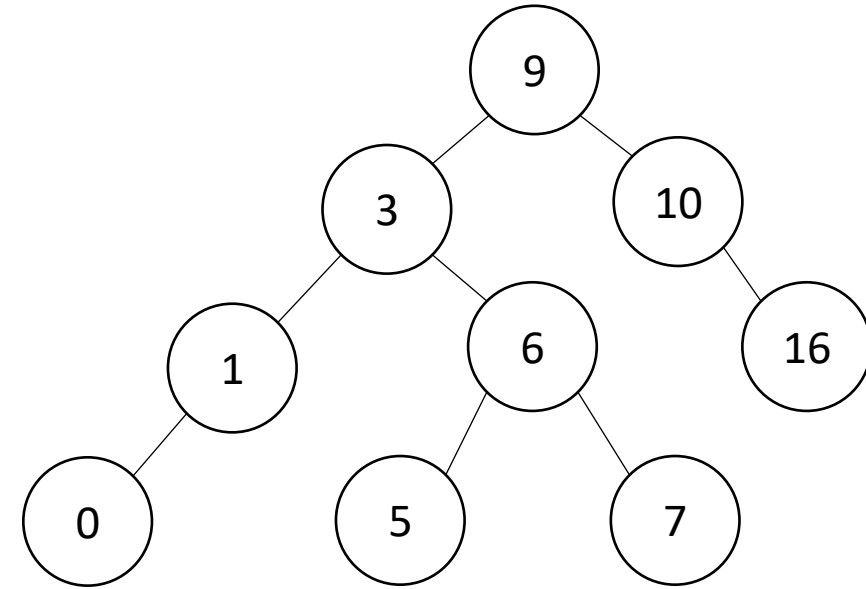
```
maxNode(root){  
    if (root == Null){ return Null; }  
    while (root.right != Null){  
        root = root.right;  
    }  
    return root;  
}
```

```
minNode(root){  
    if (root == Null){ return Null; }  
    while (root.left != Null){  
        root = root.left;  
    }  
    return root;  
}
```



# Delete Operation (iterative)

```
delete(key, root){  
  while (root != Null && key != root.key){  
    if (key < root.key){ root = root.left; }  
    else if (key > root.key){ root = root.right; }  
  }  
  if (root == Null){ return; }  
  if (root has no children){  
    make parent point to Null Instead;  
  }  
  if (root has one child){  
    make parent point to that child instead;  
  }  
  if (root has two children){  
    make parent point to either the max from the left or min from the right  
  }  
}
```



# Worst Case Analysis

- For each of Find, insert, Delete:
  - Worst case running time matches height of the tree
- What is the maximum height of a BST with  $n$  nodes?

# Improving the worst case

- How can we get a better worst case running time?

# “Balanced” Binary Search Trees

- We get better running times by having “shorter” trees
- Trees get tall due to them being “sparse” (many one-child nodes)
- Idea: modify how we insert/delete to keep the tree more “full”

Idea 1: Both Subtrees of Root have same #  
Nodes



Idea 2: Both Subtrees of Root have same height

Idea 3: Both Subtrees of every Node have same # Nodes

Idea 4: Both Subtrees of every Node have same height

# Teaser: AVL Tree

- A Binary Search tree that maintains that the left and right subtrees of every node have heights that differ by at most one.
  - Not too weak (ensures trees are short)
  - Not too strong (works for any number of nodes)