

CSE 332 Autumn 2023  
Lecture 25: Minimum Spanning  
Trees, P & NP

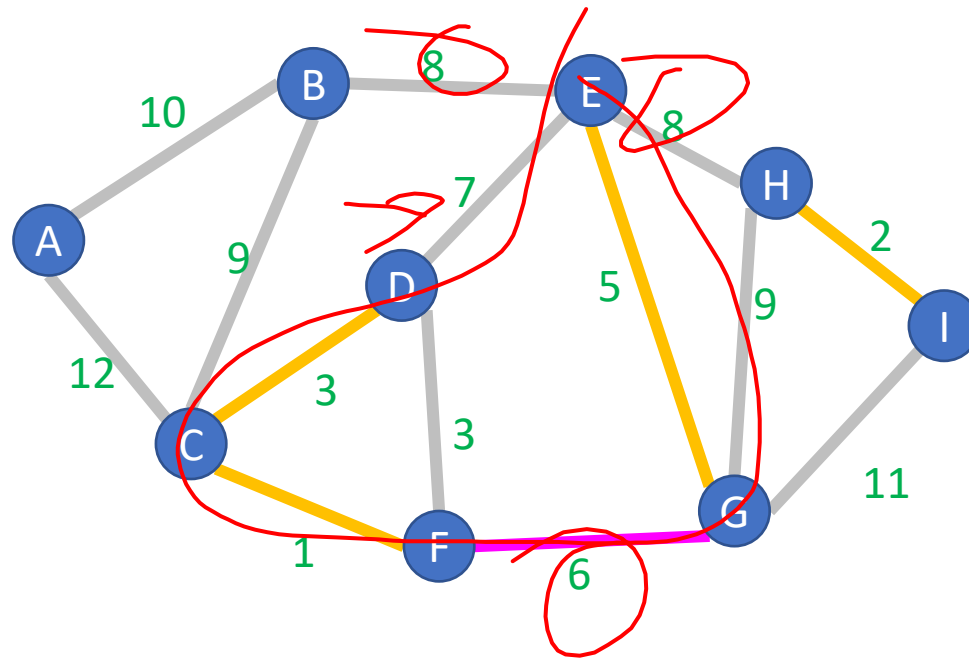
Nathan Brunelle

<http://www.cs.uw.edu/332>

# Kruskal's Algorithm

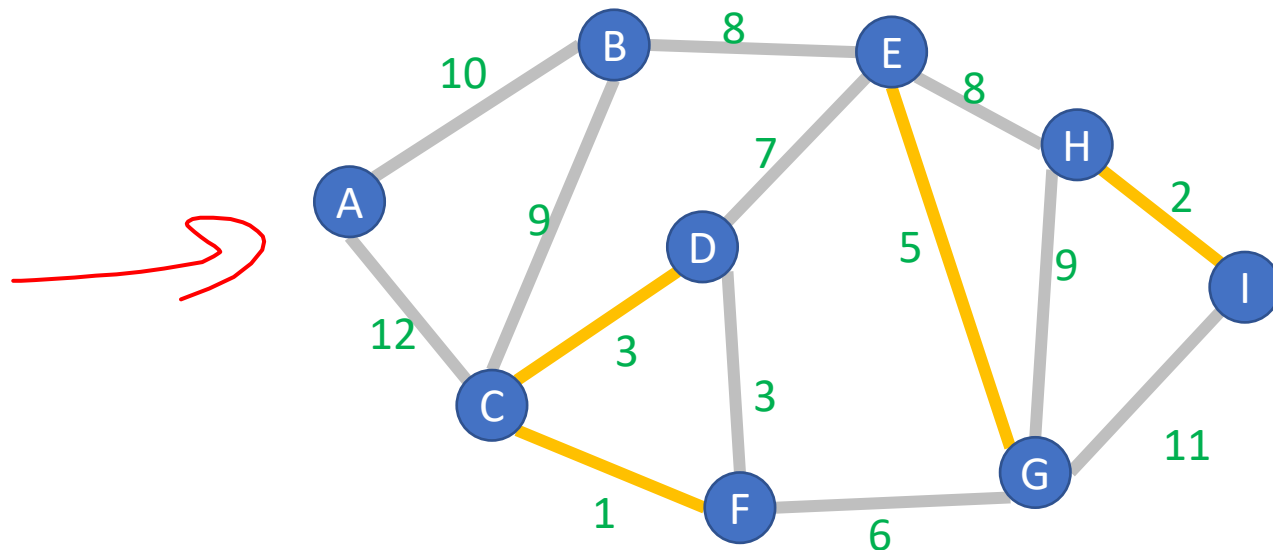
Start with an empty tree  $A$

Add to  $A$  the lowest-weight edge that does not create a cycle



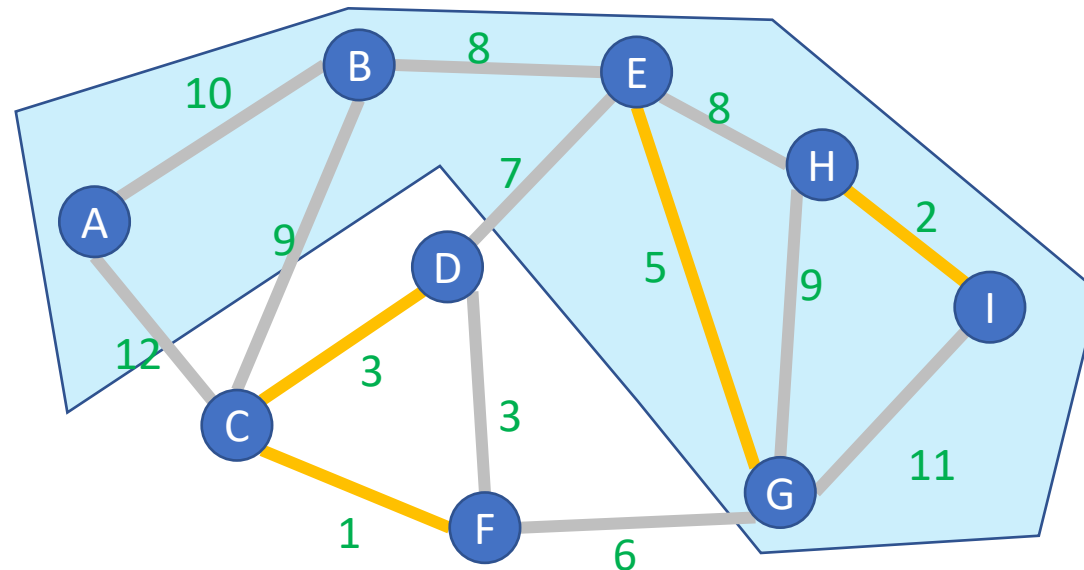
# Cut Theorem

If a set of edges  $A$  is a subset of a minimum spanning tree  $T$ , let  $(S, V - S)$  be any cut which  $A$  respects. Let  $e$  be the least-weight edge which crosses  $(S, V - S)$ .  $A \cup \{e\}$  is also a subset of a minimum spanning tree.



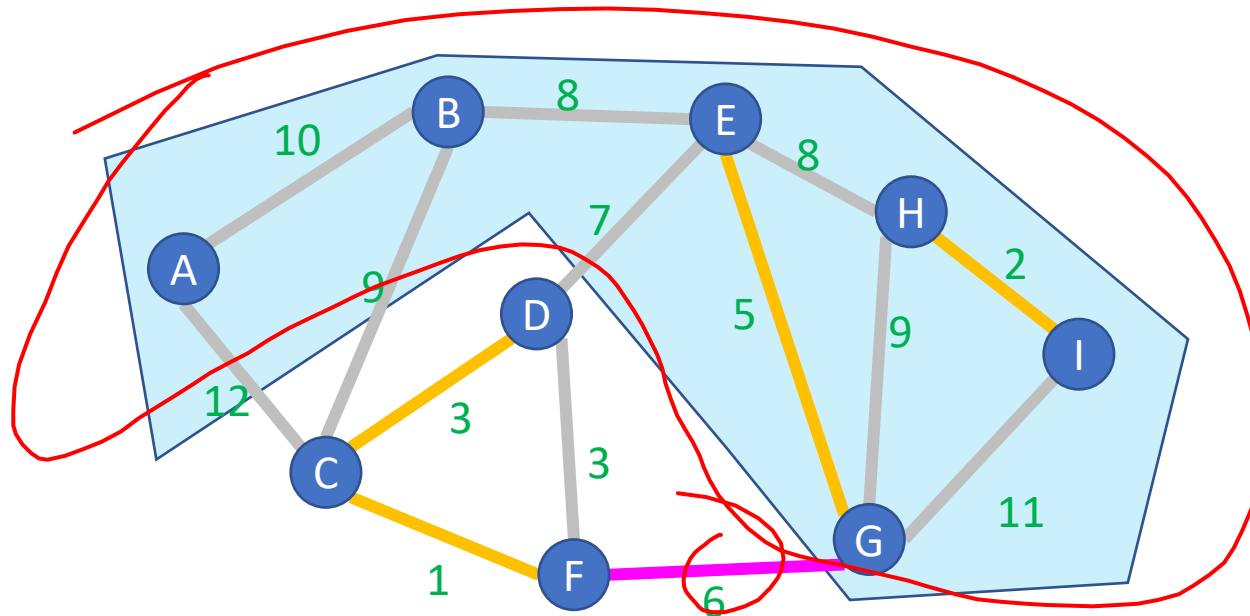
# Cut Theorem

If a set of edges  $A$  is a subset of a minimum spanning tree  $T$ , let  $(S, V - S)$  be any cut which  $A$  respects. Let  $e$  be the least-weight edge which crosses  $(S, V - S)$ .  $A \cup \{e\}$  is also a subset of a minimum spanning tree.



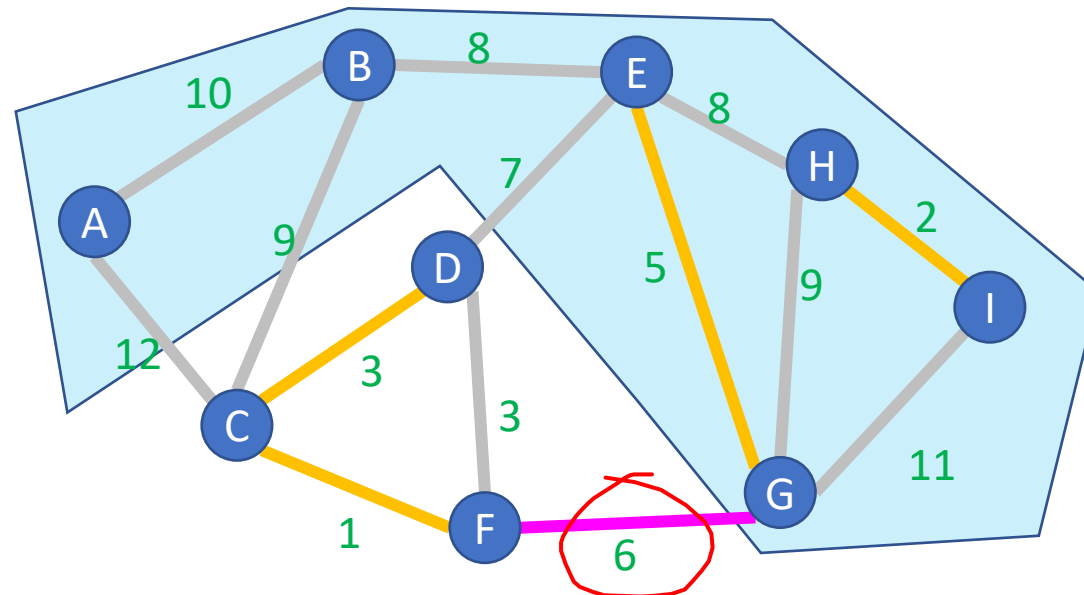
# Cut Theorem

If a set of edges  $A$  is a subset of a minimum spanning tree  $T$ , let  $(S, V - S)$  be any cut which  $A$  respects. Let  $e$  be the least-weight edge which crosses  $(S, V - S)$ .  $A \cup \{e\}$  is also a subset of a minimum spanning tree.



# Cut Theorem

If a set of edges  $A$  is a subset of a minimum spanning tree  $T$ , let  $(S, V - S)$  be any cut which  $A$  respects. Let  $e$  be the least-weight edge which crosses  $(S, V - S)$ .  $A \cup \{e\}$  is also a subset of a minimum spanning tree.

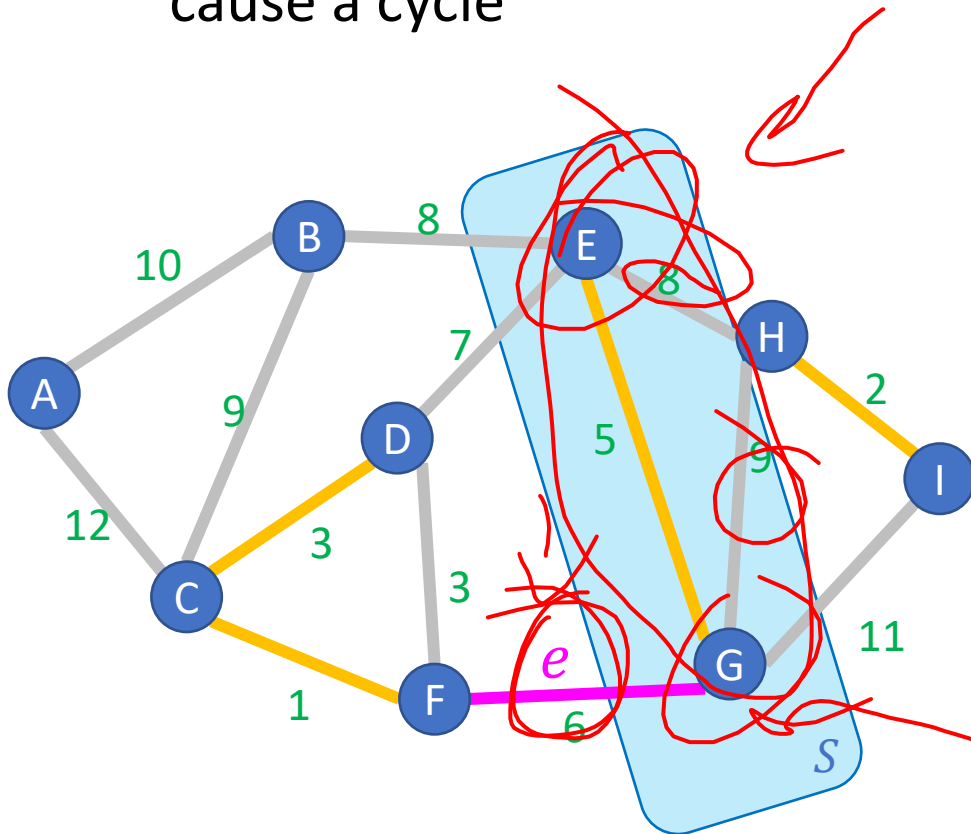


# Proof of Kruskal's Algorithm

Start with an empty tree  $A$

Repeat  $V - 1$  times:

Add the min-weight edge that doesn't cause a cycle



**Proof:** Suppose we have some arbitrary set of edges  $A$  that Kruskal's has already selected to include in the MST.  $e = (F, G)$  is the edge Kruskal's selects to add next

We know that there cannot exist a path from  $F$  to  $G$  using only edges in  $A$  because  $e$  does not cause a cycle

We can cut the graph therefore into 2 disjoint sets:

- nodes reachable from  $G$  using edges in  $A$
- All other nodes

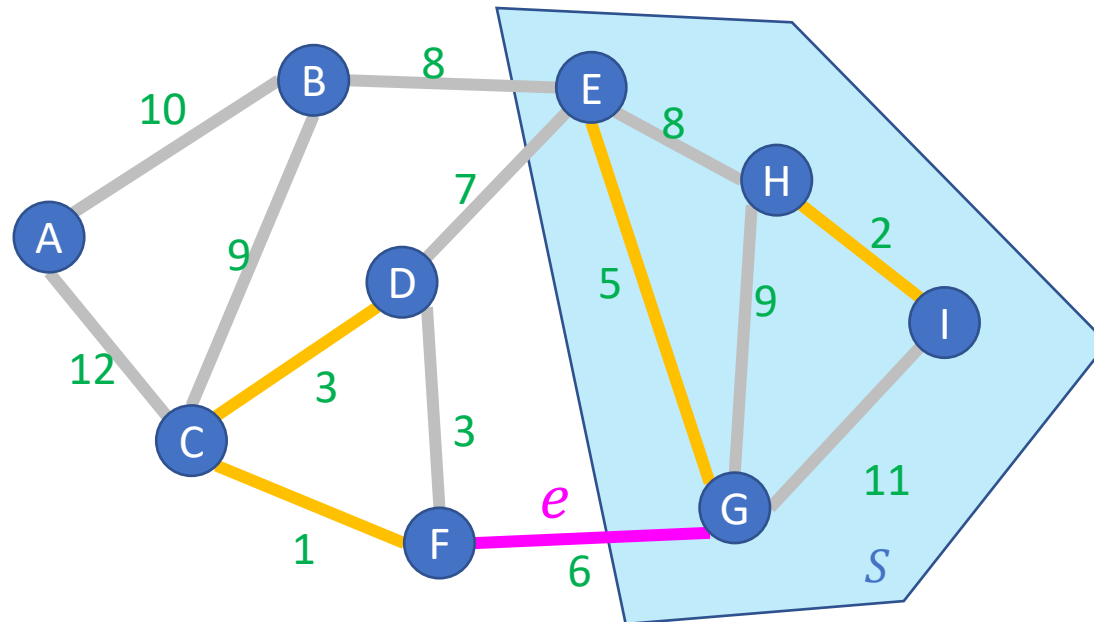
$e$  is the minimum cost edge that crosses this cut, so by the Cut Theorem, Kruskal's is optimal!

# Kruskal's Algorithm Runtime

Start with an empty tree  $A$

Repeat  $V - 1$  times:

Add the min-weight edge that doesn't cause a cycle



Keep edges in a Disjoint-set  
data structure (very fancy)

$$O(E \log V)$$



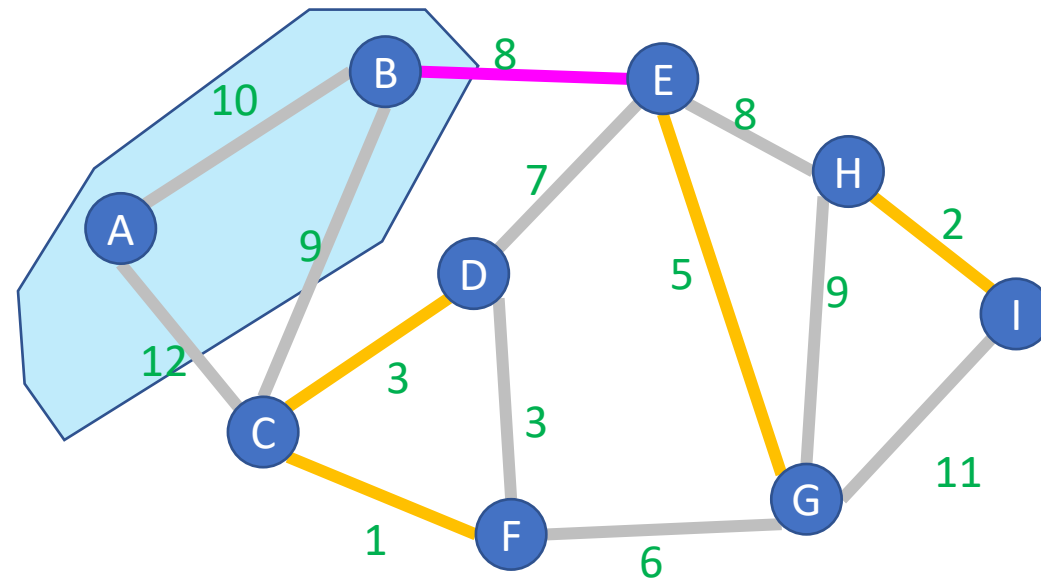
# General MST Algorithm

Start with an empty tree  $A$

Repeat  $V - 1$  times:

Pick a cut  $(S, V - S)$  which  $A$  respects (typically implicitly)

Add the **min-weight edge which crosses  $(S, V - S)$**



# Prim's Algorithm

Start with an empty tree  $A$

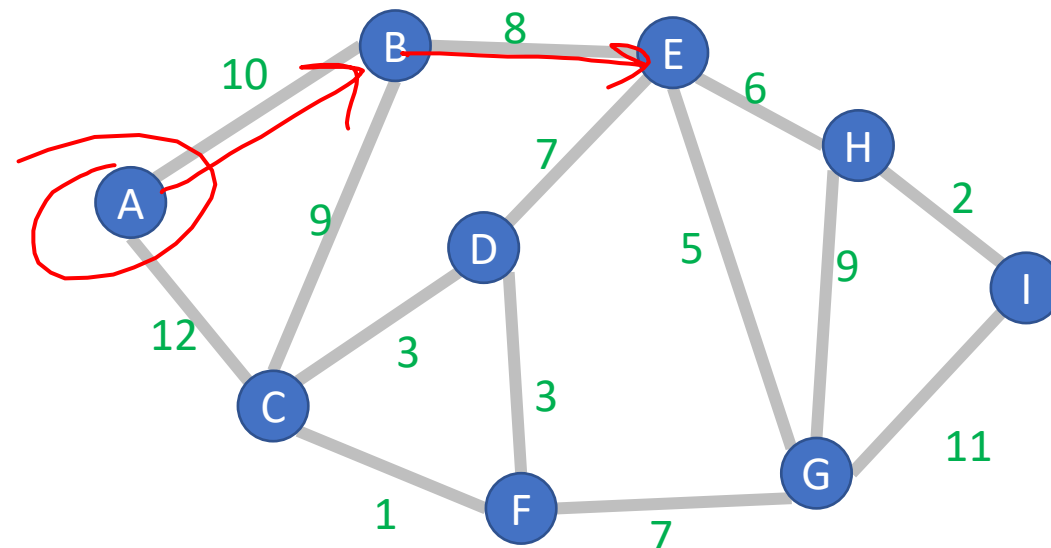
Repeat  $V - 1$  times:

Pick a cut  $(S, V - S)$  which  $A$  respects

Add the min-weight edge which crosses  $(S, V - S)$

$S$  is all endpoint of edges in  $A$

$e$  is the min-weight edge that grows the tree



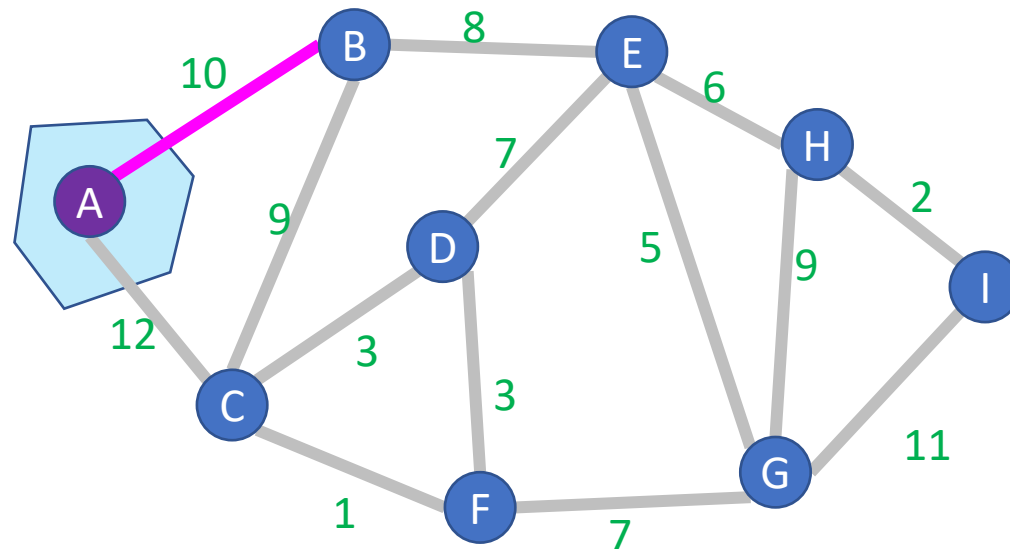
# Prim's Algorithm

Start with an empty tree  $A$

Pick a **start node**

Repeat  $V - 1$  times:

Add **the min-weight edge** which connects to node  
in  $A$  with a node not in  $A$



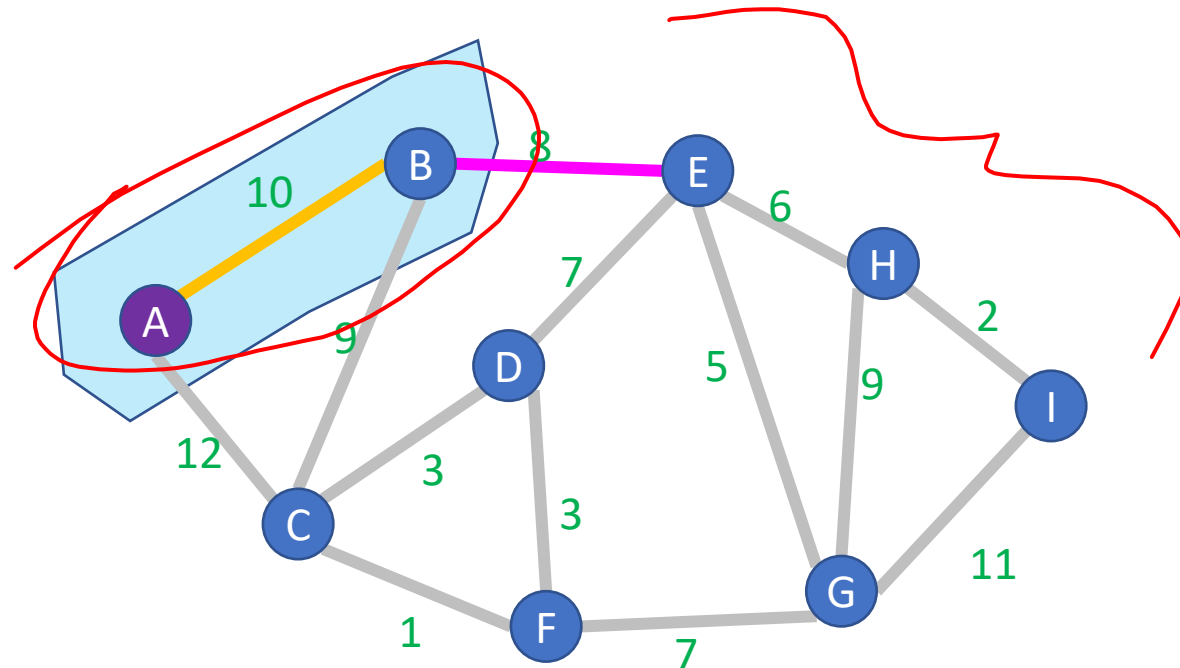
# Prim's Algorithm

Start with an empty tree  $A$

Pick a **start node**

Repeat  $V - 1$  times:

Add **the min-weight edge** which connects to node  
in  $A$  with a node not in  $A$



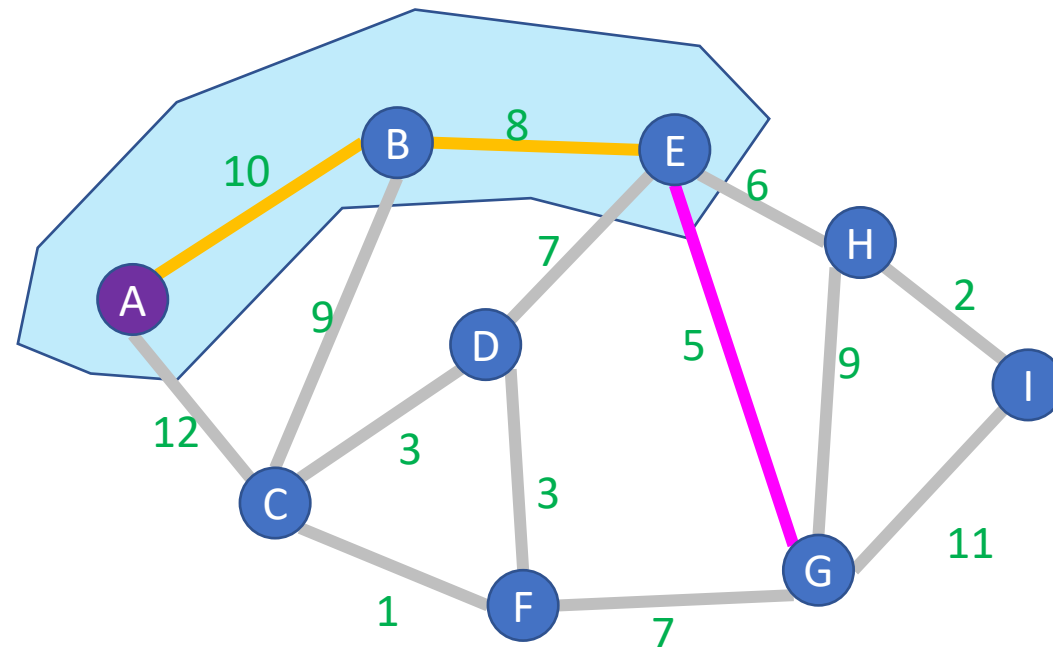
# Prim's Algorithm

Start with an empty tree  $A$

Pick a **start node**

Repeat  $V - 1$  times:

Add **the min-weight edge** which connects to node  
in  $A$  with a node not in  $A$



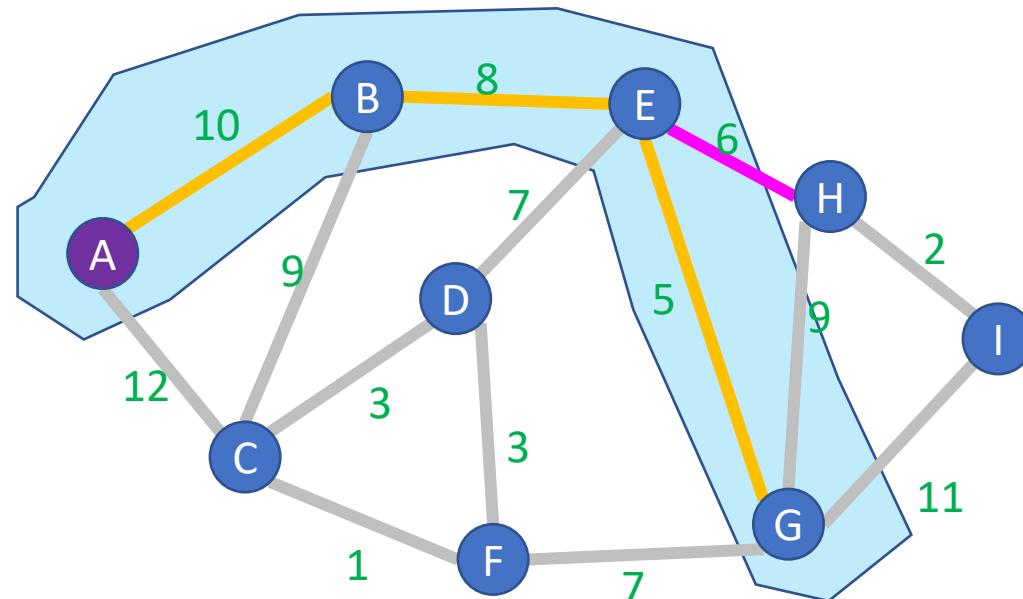
# Prim's Algorithm

Start with an empty tree  $A$

Pick a **start node**

Repeat  $V - 1$  times:

Add **the min-weight edge** which connects to node  
in  $A$  with a node not in  $A$



# Prim's Algorithm

Start with an empty tree  $A$

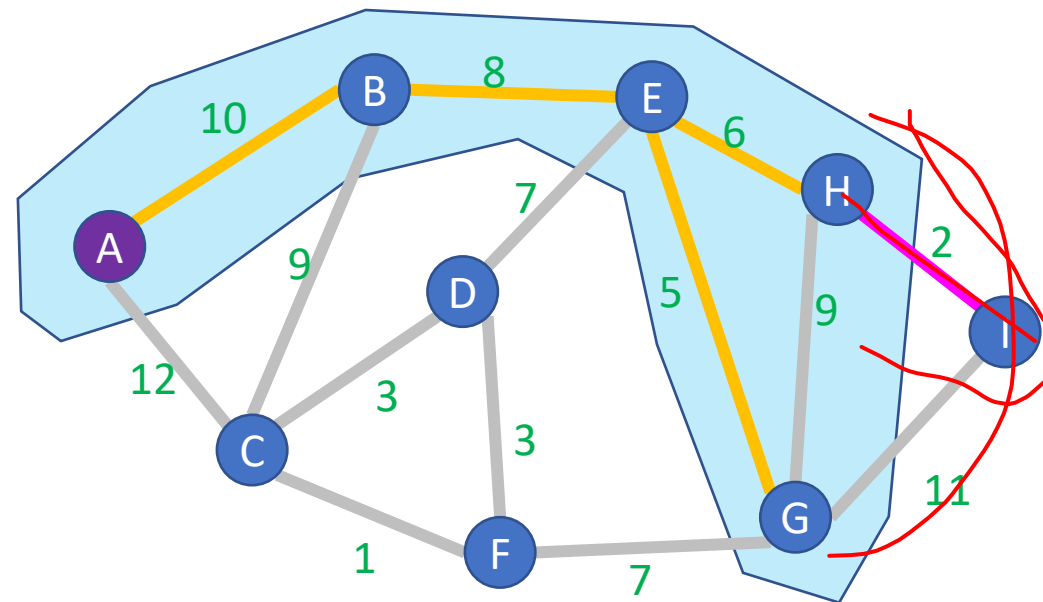
Pick a **start node**

Repeat  $V - 1$  times:

Add **the min-weight edge** which connects to node  
in  $A$  with a node not in  $A$

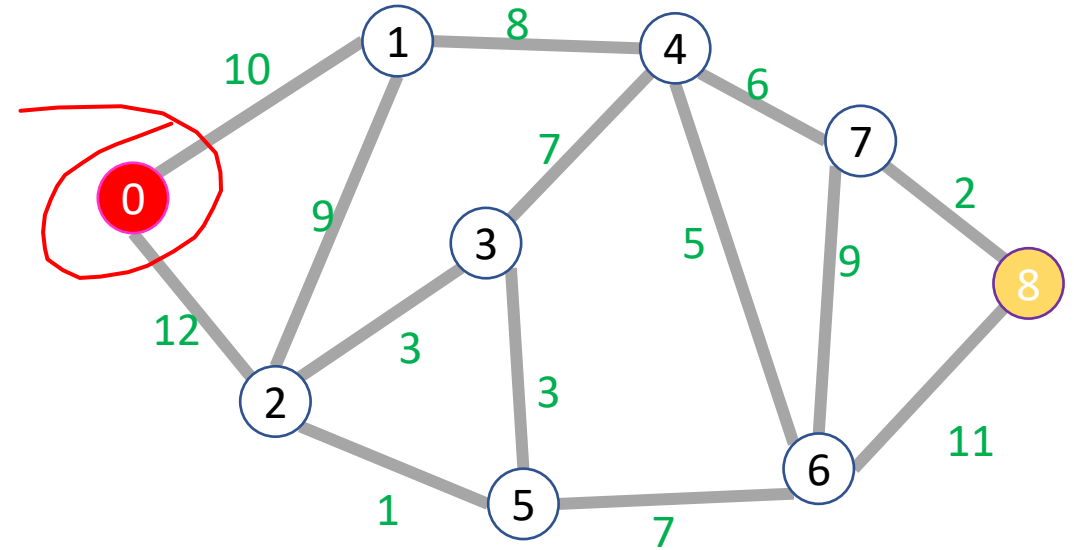
Keep edges in a Heap

$O(E \log V)$



# Dijkstra's Algorithm

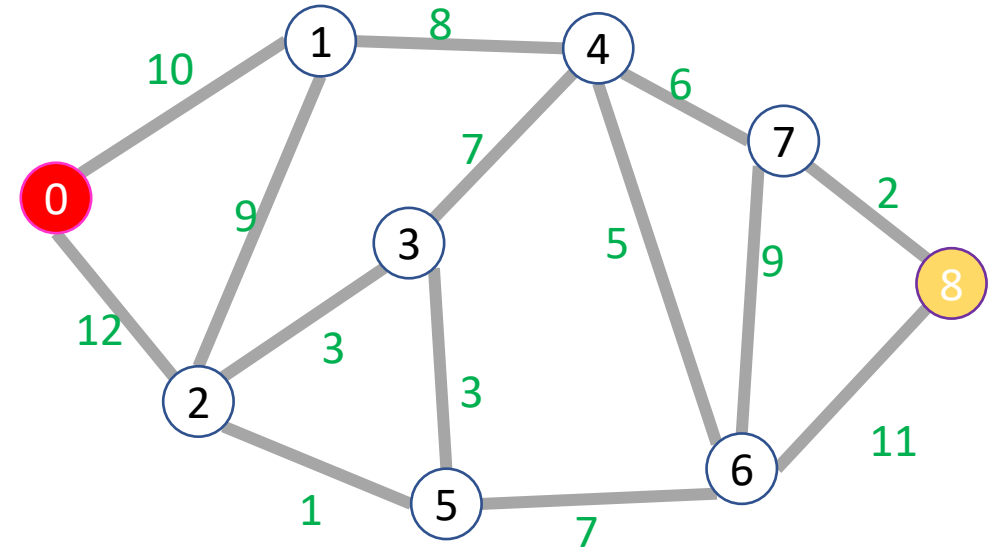
```
int dijkstras(graph, start, end){
    PQ = new minheap();
    PQ.insert(0, start); // priority=0, value=start
    start.distance = 0;
    while (!PQ.isEmpty){
        current = PQ.extractmin();
        if (current.known){ continue;}
        current.known = true;
        for (neighbor : current.neighbors){
            if (!neighbor.known){
                new_dist = current.distance + weight(current,neighbor);
                if(neighbor.dist != ∞){ PQ.insert(new_dist, neighbor);}
                else if (new_dist < neighbor. distance){
                    neighbor. distance = new_dist;
                    PQ.decreaseKey(new_dist,neighbor); }
            }
        }
    }
    return end.distance;
}
```





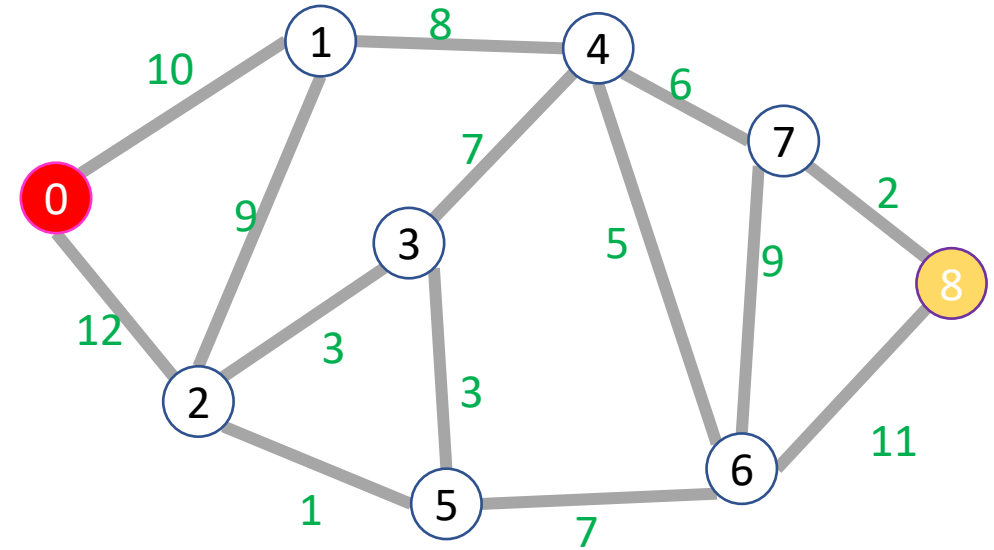
# Prim's Algorithm

```
int dijkstras(graph, start, end){
    PQ = new minheap();
    PQ.insert(0, start); // priority=0, value=start
    start.distance = 0;
    while (!PQ.isEmpty){
        current = PQ.extractmin();
        if (current.known){ continue;}
        current.known = true;
        for (neighbor : current.neighbors){
            if (!neighbor.known){
                new_dist = weight(current,neighbor);
                if(neighbor.dist != ∞){ PQ.insert(new_dist, neighbor);}
                else if (new_dist < neighbor. distance){
                    neighbor. distance = new_dist;
                    PQ.decreaseKey(new_dist,neighbor); }
            }
        }
    }
    return end.distance;
}
```



# Dijkstra's Algorithm

```
int dijkstras(graph, start, end){
    PQ = new minheap();
    PQ.insert(0, start); // priority=0, value=start
    start.distance = 0;
    while (!PQ.isEmpty){
        current = PQ.extractmin();
        if (current.known){ continue;}
        current.known = true;
        for (neighbor : current.neighbors){
            if (!neighbor.known){
                new_dist = current.distance + weight(current,neighbor);
                if(neighbor.dist != ∞){ PQ.insert(new_dist, neighbor);}
                else if (new_dist < neighbor. distance){
                    neighbor. distance = new_dist;
                    PQ.decreaseKey(new_dist,neighbor); }
            }
        }
    }
    return end.distance;
}
```



$new\_dist = current.distance + weight(current,neighbor);$

if(neighbor.dist != ∞){ PQ.insert(new\_dist, neighbor);}

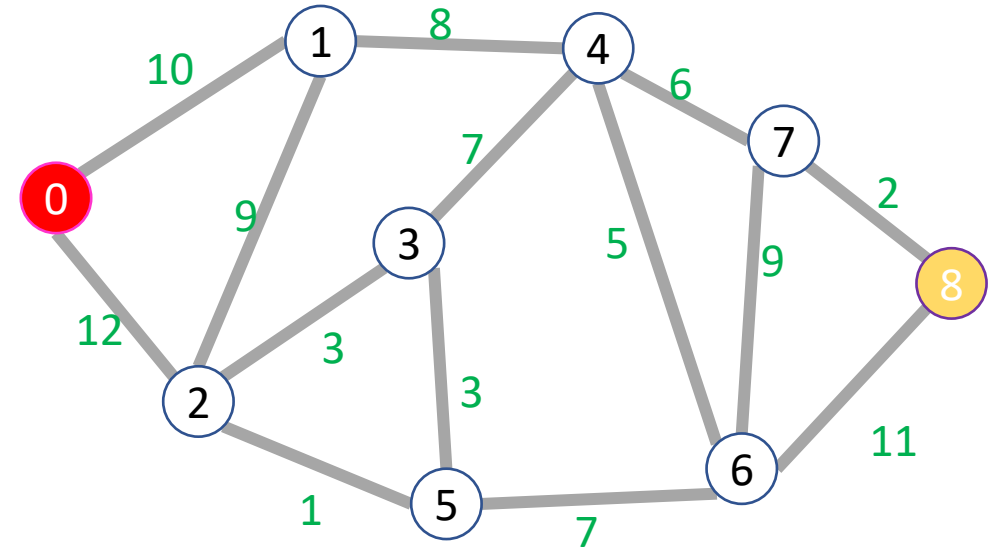
else if (new\_dist < neighbor. distance){

neighbor. distance = new\_dist;

PQ.decreaseKey(new\_dist,neighbor); }

# Prim's Algorithm

```
int dijkstras(graph, start, end){
    PQ = new minheap();
    PQ.insert(0, start); // priority=0, value=start
    start.distance = 0;
    while (!PQ.isEmpty){
        current = PQ.extractmin();
        if (current.known){ continue;}
        current.known = true;
        for (neighbor : current.neighbors){
            if (!neighbor.known){
                new_dist = weight(current,neighbor);
                if(neighbor.dist != ∞){ PQ.insert(new_dist, neighbor);}
                else if (new_dist < neighbor. distance){
                    neighbor. distance = new_dist;
                    PQ.decreaseKey(new_dist,neighbor); }
            }
        }
    }
    return end.distance;
}
```



*new\_dist = weight(current,neighbor);*

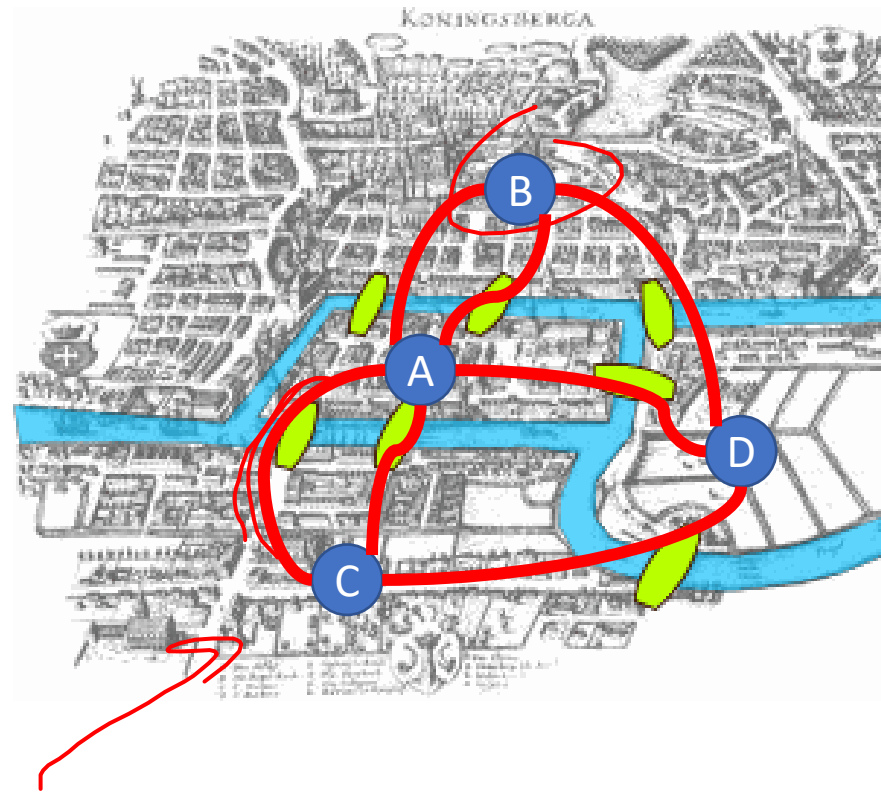
if(neighbor.dist != ∞){ PQ.insert(new\_dist, neighbor);}

else if (new\_dist < neighbor. distance){

neighbor. distance = new\_dist;

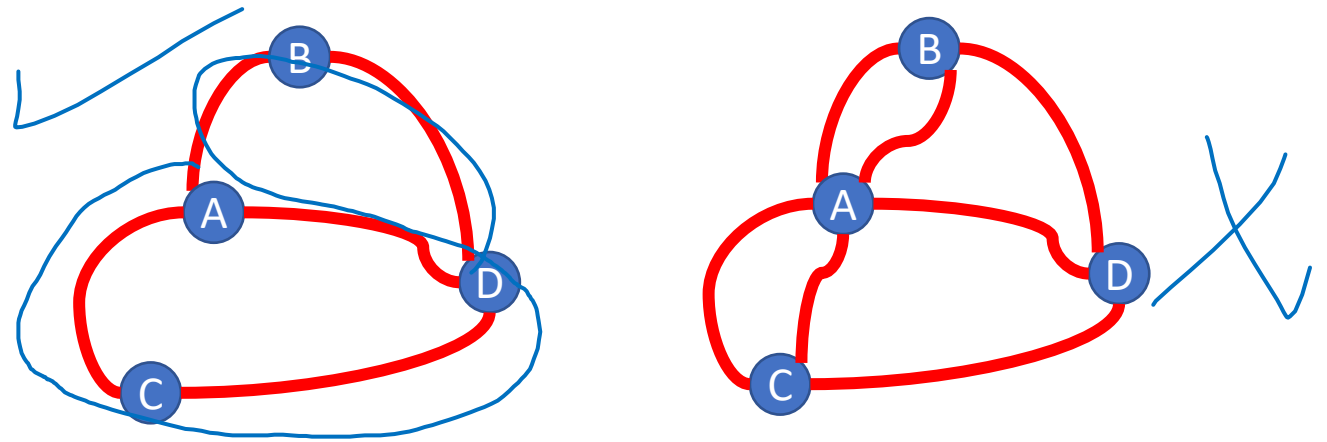
PQ.decreaseKey(new\_dist,neighbor); }

# 7 Bridges of Königsberg



The Pregel River runs through the city of Koenigsberg, creating 2 islands. Among these 2 islands and the 2 sides of the river, there are 7 bridges. Is there any path starting at one landmass which crosses each bridge exactly once?

# Euler Path Problem



- Path:

- A sequence of nodes  $v_1, v_2, \dots$  such that for every consecutive pair are connected by an edge (i.e.  $(v_i, v_{i+1})$  is an edge for each  $i$  in the path)

- Euler Path:

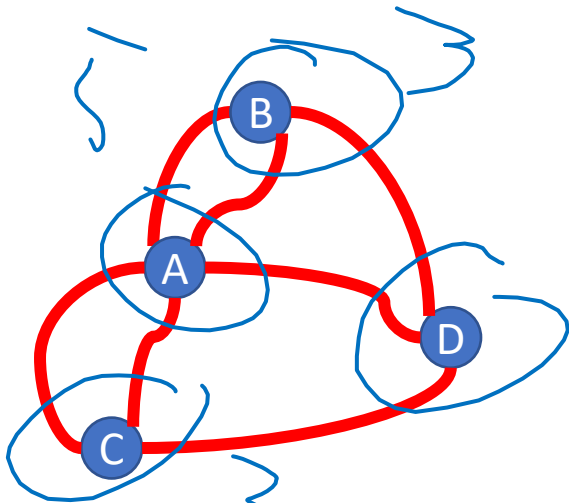
- A path such that every edge in the graph appears exactly once
  - If the graph is not simple then some pairs need to appear multiple times!

- Euler path problem:

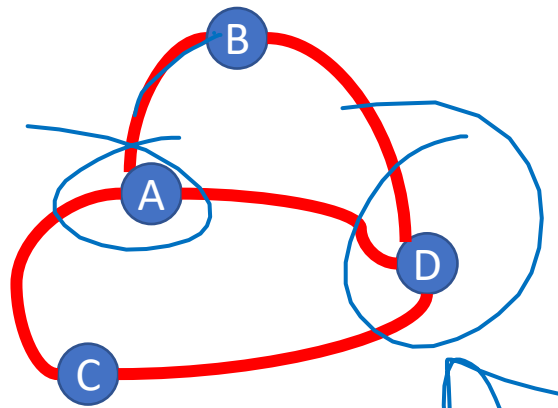
- Given an undirected graph  $G = (V, E)$ , does there exist an Euler path for  $G$ ?

# Examples

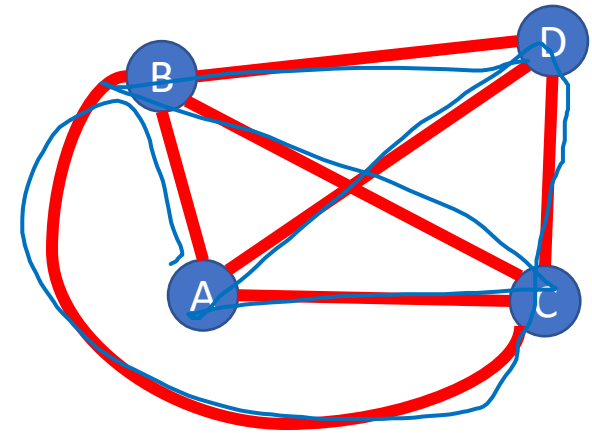
- Which of the graphs below have an Euler path?



No Euler path exists!



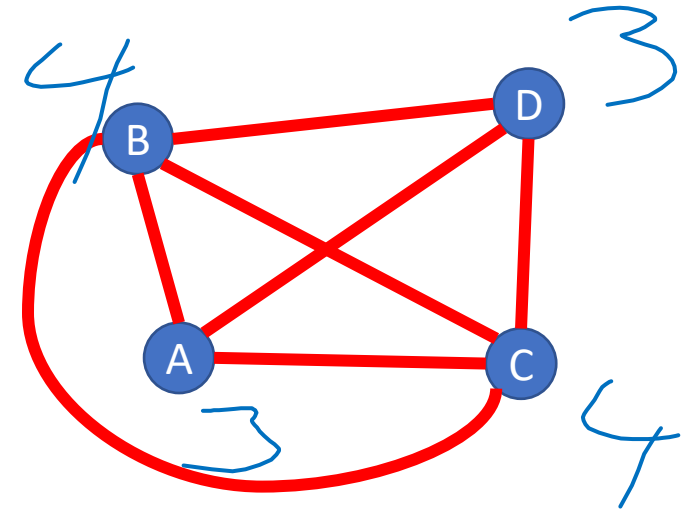
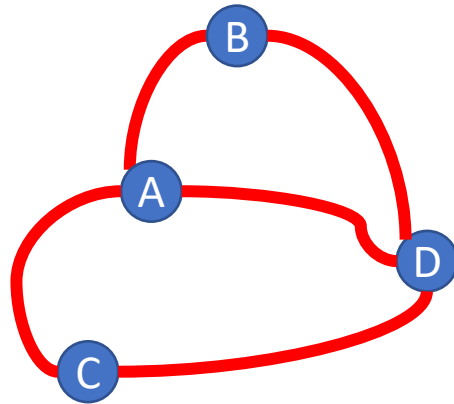
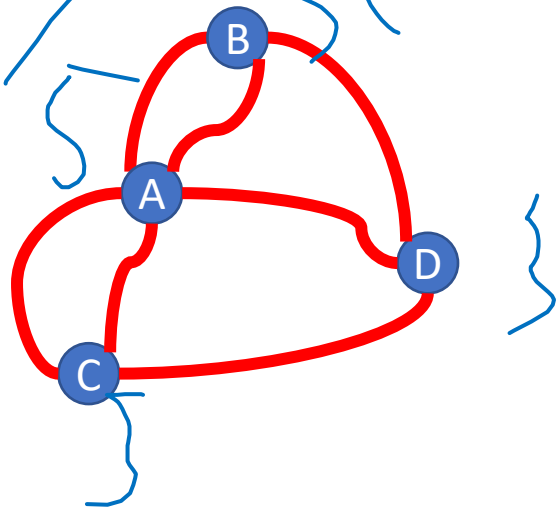
Euler path exists!  
 $A, B, D, A, C, D$



Euler path exists!  
 $A, B, C, D, A, C, B, D$

# Euler's Theorem

- A graph has an Euler Path if and only if it is connected and has exactly 0 or 2 nodes with odd degree.



# Algorithm for the Euler Path Problem

- Given an undirected graph  $G = (V, E)$ , does there exist an Euler path for  $G$ ?

- Algorithm:

- Check if the graph is connected
  - Check the degree of each node
  - If the number of nodes with odd degree is 0 or 2, return true
  - Otherwise return false

$\rightarrow V + E$   
 $V \neq E$

- Running time?

$V + E$



# A Seemingly Similar Problem

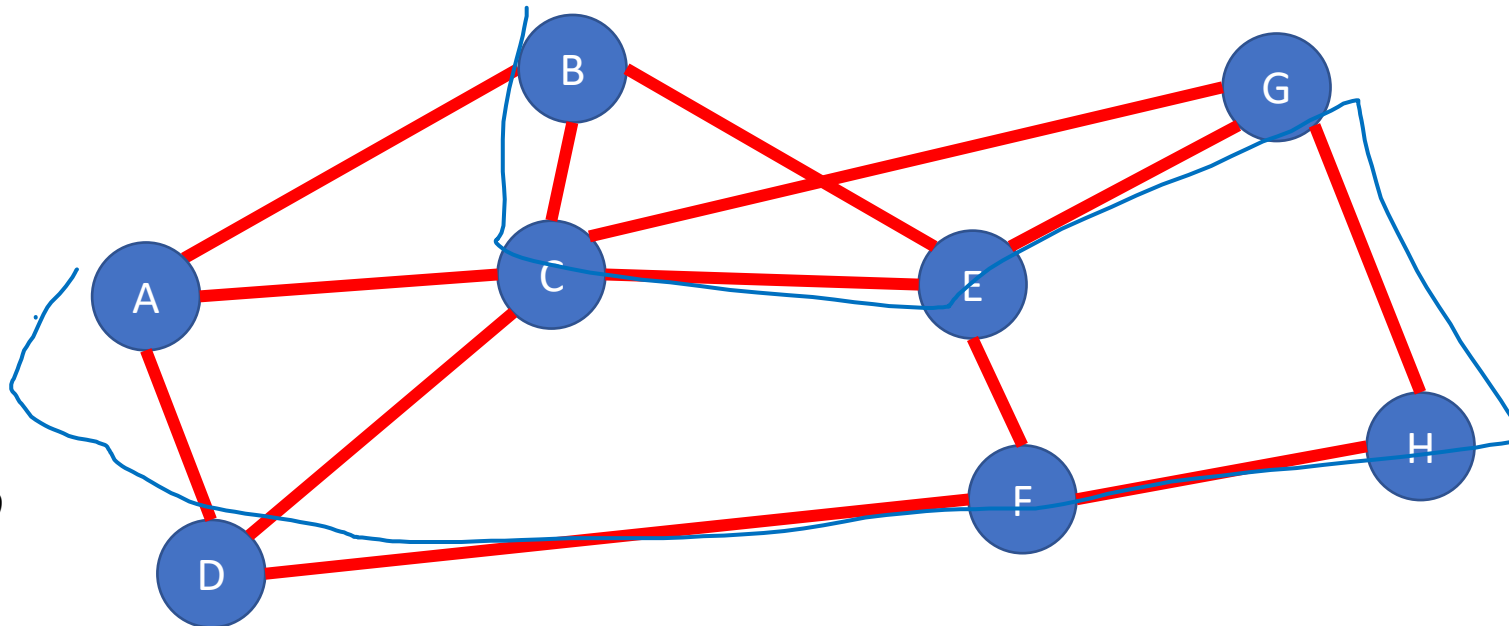
- Hamiltonian Path:

- A path that includes every node in the graph exactly once

- Hamiltonian Path Problem:

- Given a graph  $G = (V, E)$ , does that graph have a Hamiltonian Path?

True!  
*A, B, C, E, G, H, F, D*



# Algorithms for the Hamiltonian Path Problem

- Option 1:

- Explore all possible simple paths through the graph
- Check to see if any of those are length  $V$

- Option 2:

- Write down every sequence of nodes
- Check to see if any of those are a path

- Both options are examples of an **Exhaustive Search (“Brute Force”)**  
**algorithm**

# Option 2: List all sequences, look for a path

- Running time:

- $G = (V, E)$

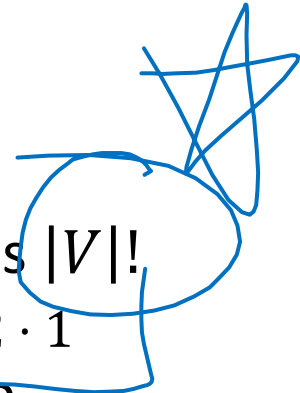
- Number of permutations of  $V$  is  $|V|!$

- $n! = n \cdot (n-1) \cdot (n-2) \cdot \dots \cdot 2 \cdot 1$

- How does  $n!$  compare with  $2^n$ ?

- $n! \in \Omega(2^n)$

- Exponential running time!



Handwritten notes in blue ink:

$$n! = n \cdot (n-1) \cdot (n-2) \cdot \dots \cdot 1$$

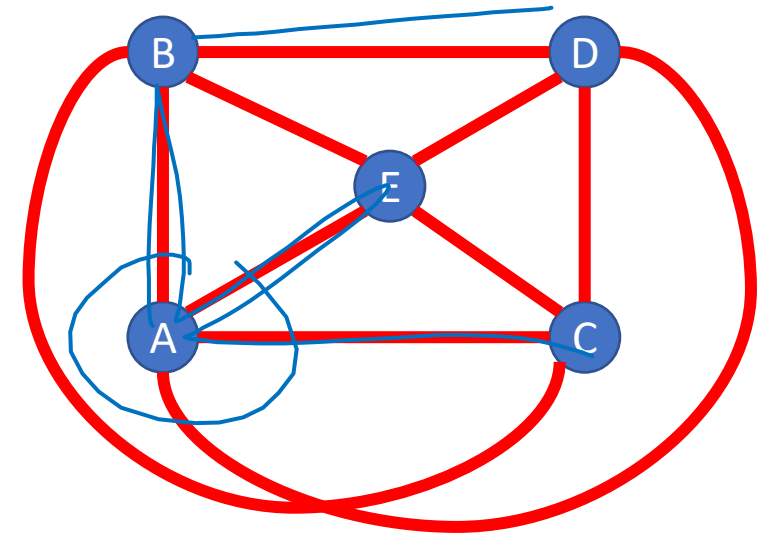
↑  
n terms

Handwritten notes in blue ink:

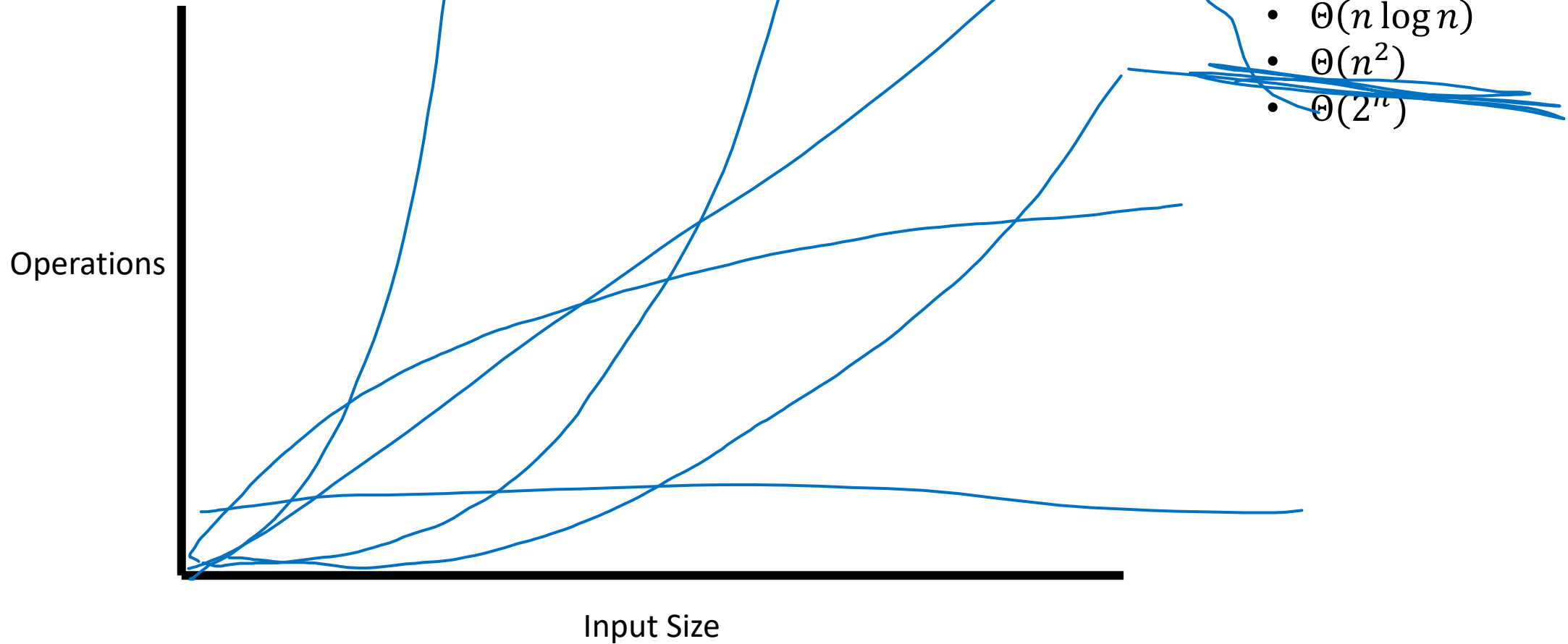
$$2^n =$$

# Option 1: Explore all simple paths, check for one of length $V$

- Running time:
  - $G = (V, E)$
  - Number of paths
    - Pick a first node ( $|V|$  choices)
    - Pick a neighbor (up to  $|V| - 1$  choices)
    - Pick a neighbor (up to  $|V| - 2$  choices)
    - .... Repeat  $|V| - 1$  total times
    - Overall:  $|V|!$  paths
  - Exponential running time



# Running Times



Running times we've seen:

- $\Theta(1)$
- $\Theta(\log n)$
- $\Theta(n)$
- $\Theta(n \log n)$
- $\Theta(n^2)$
- $\Theta(2^n)$

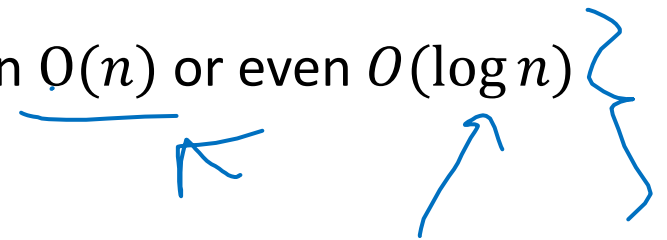
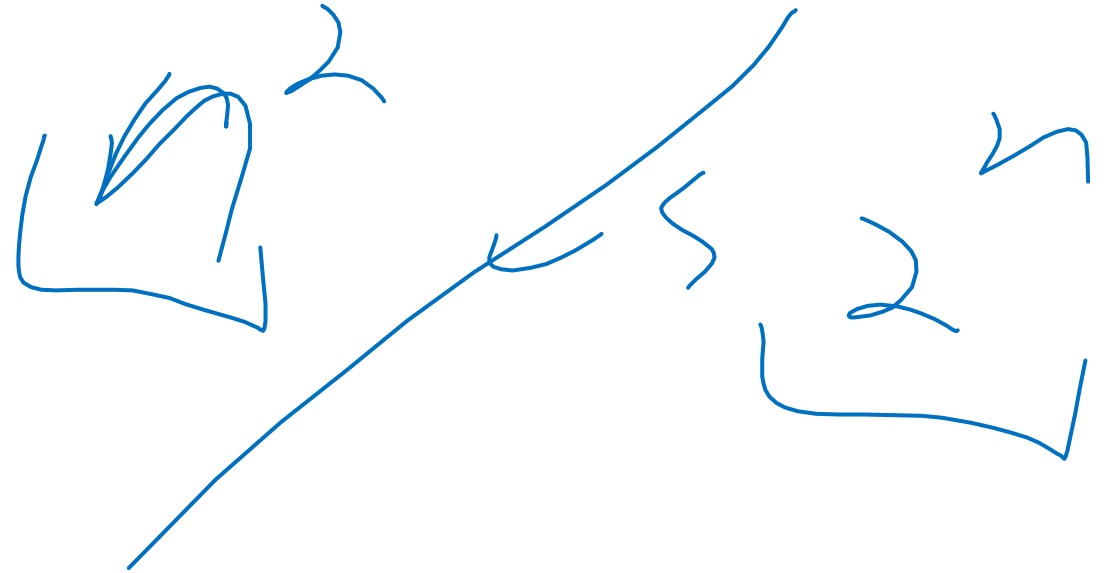
# Running Times

**Table 2.1** The running times (rounded up) of different algorithms on inputs of increasing size, for a processor performing a million high-level instructions per second. In cases where the running time exceeds  $10^{25}$  years, we simply record the algorithm as taking a very long time.

	$n$	$n \log_2 n$	$n^2$	$n^3$	$1.5^n$	$2^n$	$n!$
$n = 10$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	4 sec
$n = 30$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	18 min	$10^{25}$ years
$n = 50$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	11 min	36 years	very long
$n = 100$	< 1 sec	< 1 sec	< 1 sec	1 sec	12,892 years	$10^{17}$ years	very long
$n = 1,000$	< 1 sec	< 1 sec	1 sec	18 min	very long	very long	very long
$n = 10,000$	< 1 sec	< 1 sec	2 min	12 days	very long	very long	very long
$n = 100,000$	< 1 sec	2 sec	3 hours	32 years	very long	very long	very long
$n = 1,000,000$	1 sec	20 sec	12 days	31,710 years	very long	very long	very long

# Tractability

- Tractable:
  - Feasible to solve in the “real world”
- Intractable:
  - Infeasible to solve in the “real world”
- Whether a problem is considered “tractable” or “intractable” depends on the use case
  - For machine learning, big data, etc. tractable might mean  $O(n)$  or even  $O(\log n)$
  - For most applications it's more like  $O(n^3)$  or  $O(n^2)$
- A strange pattern:
  - Most “natural” problems are either done in small-degree polynomial (e.g.  $n^2$ ) or else exponential time (e.g.  $2^n$ )
  - It's rare to have problems which require a running time of  $n^5$ , for example



# Complexity Classes

- A Complexity Class is a set of problems (e.g. sorting, Euler path, Hamiltonian path)
  - The problems included in a complexity class are those whose most efficient algorithm has a specific upper bound on its running time (or memory use, or...)
- Examples:
  - The set of all problems that can be solved by an algorithm with running time  $O(n)$ 
    - Contains: Finding the minimum of a list, finding the maximum of a list, buildheap, summing a list, etc.
  - The set of all problems that can be solved by an algorithm with running time  $O(n^2)$ 
    - Contains: everything above as well as sorting, Euler path
  - The set of all problems that can be solved by an algorithm with running time  $O(n!)$ 
    - Contains: everything we've seen in this class so far



# Complexity Classes and Tractability

- To explore what problems are and are not tractable, we give some complexity classes special names:
- Complexity Class  $P$ :
  - Stands for “Polynomial”
  - The set of problems which have an algorithm whose running time is  $O(n^p)$  for some choice of  $p \in \mathbb{R}$ .
  - We say all problems belonging to  $P$  are “Tractable”
- Complexity Class  $EXP$ :
  - Stands for “Exponential”
  - The set of problems which have an algorithm whose running time is  $O(2^{n^p})$  for some choice of  $p \in \mathbb{R}$
  - We say all problems belonging to  $EXP - P$  are “Intractable”
    - Disclaimer: Really it’s all problems outside of  $P$ , and there are problems which do not belong to  $EXP$ , but we’re not going to worry about those in this class

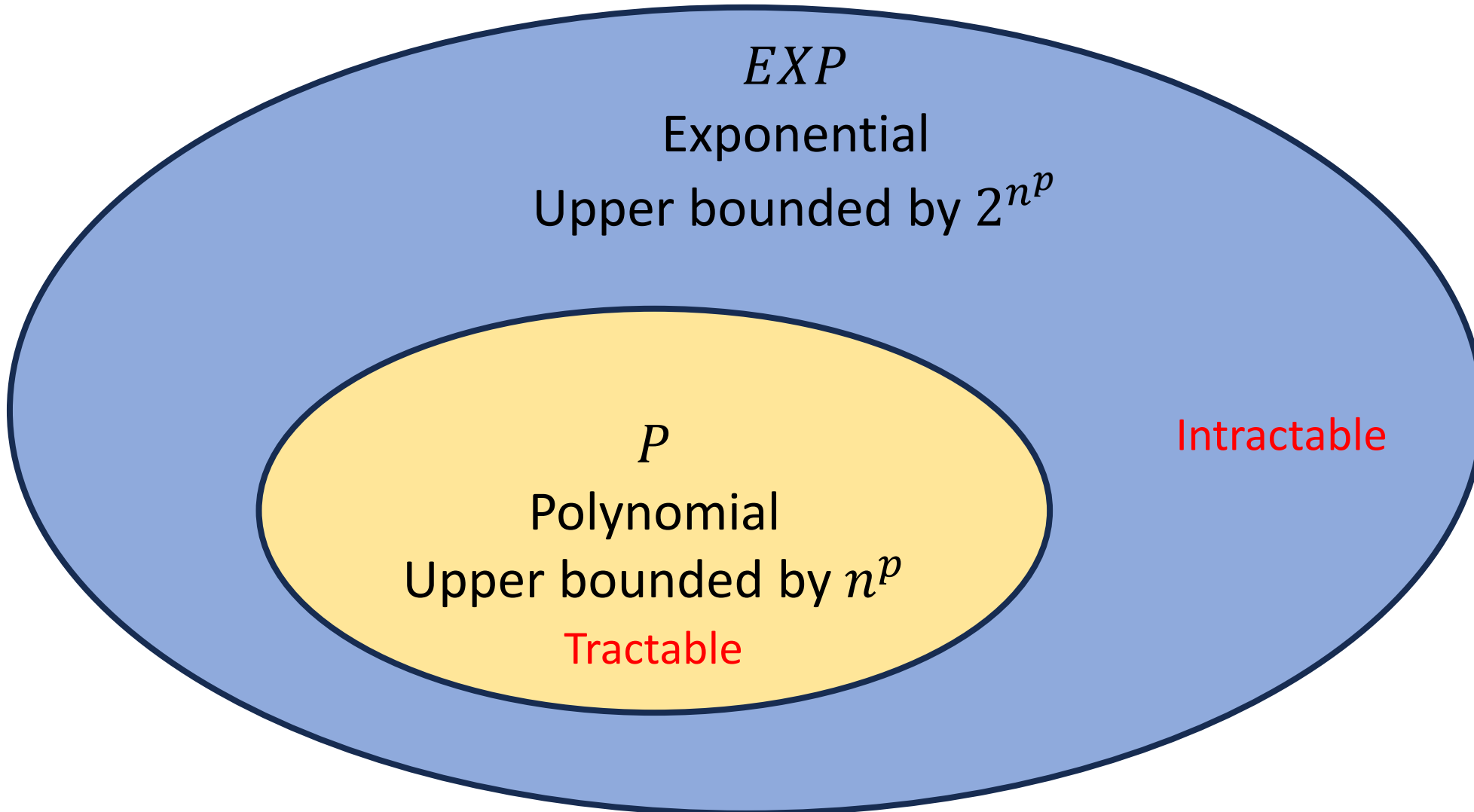
# *EXP* and *P*

Important!

$$P \subset EXP$$

Every problem within *P* is also within *EXP*

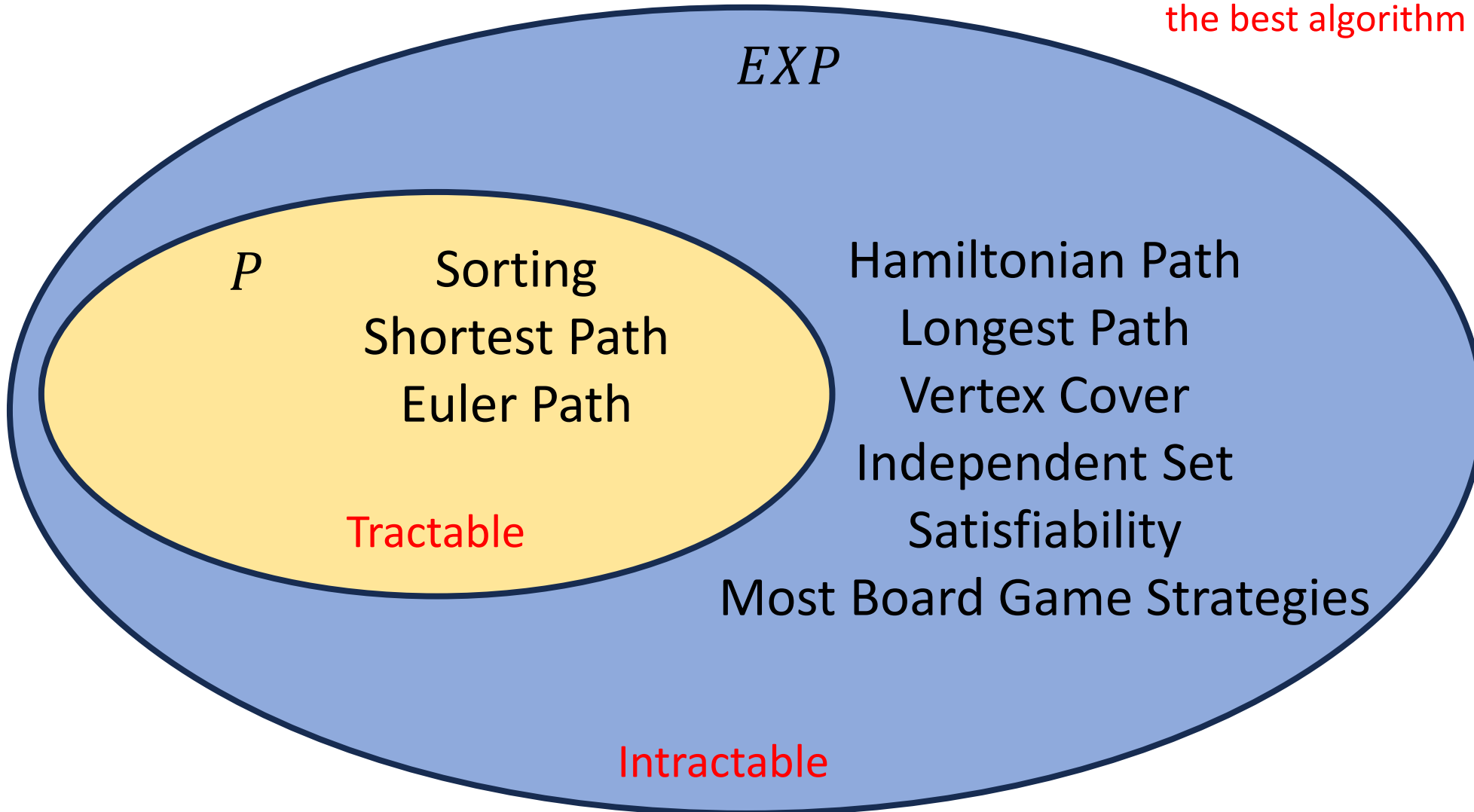
The intractable ones are the problems within *EXP* but NOT *P*



# Members

## Important!

Some of the problems listed in  $EXP$  could also be members of  $P$   
Since membership is determined by a problem's most efficient algorithm, knowing if a problem belongs to  $P$  requires knowing the best algorithm possible!



# Studying Complexity and Tractability

- Organizing problems into complexity classes helps us to reason more carefully and flexibly about tractability
- The goal for each problem is to either
  - Find an efficient algorithm if it exists
    - i.e. show it belongs to  $P$
  - Prove that no efficient algorithm exists
    - i.e. show it does not belong to  $P$
- Complexity classes allow us to reason about sets of problems at a time, rather than each problem individually
  - If we can find more precise classes to organize problems into, we might be able to draw conclusions about the entire class
  - It may be easier to show a problem belongs to class  $C$  than to  $P$ , so it may help to show that  $C \subseteq P$

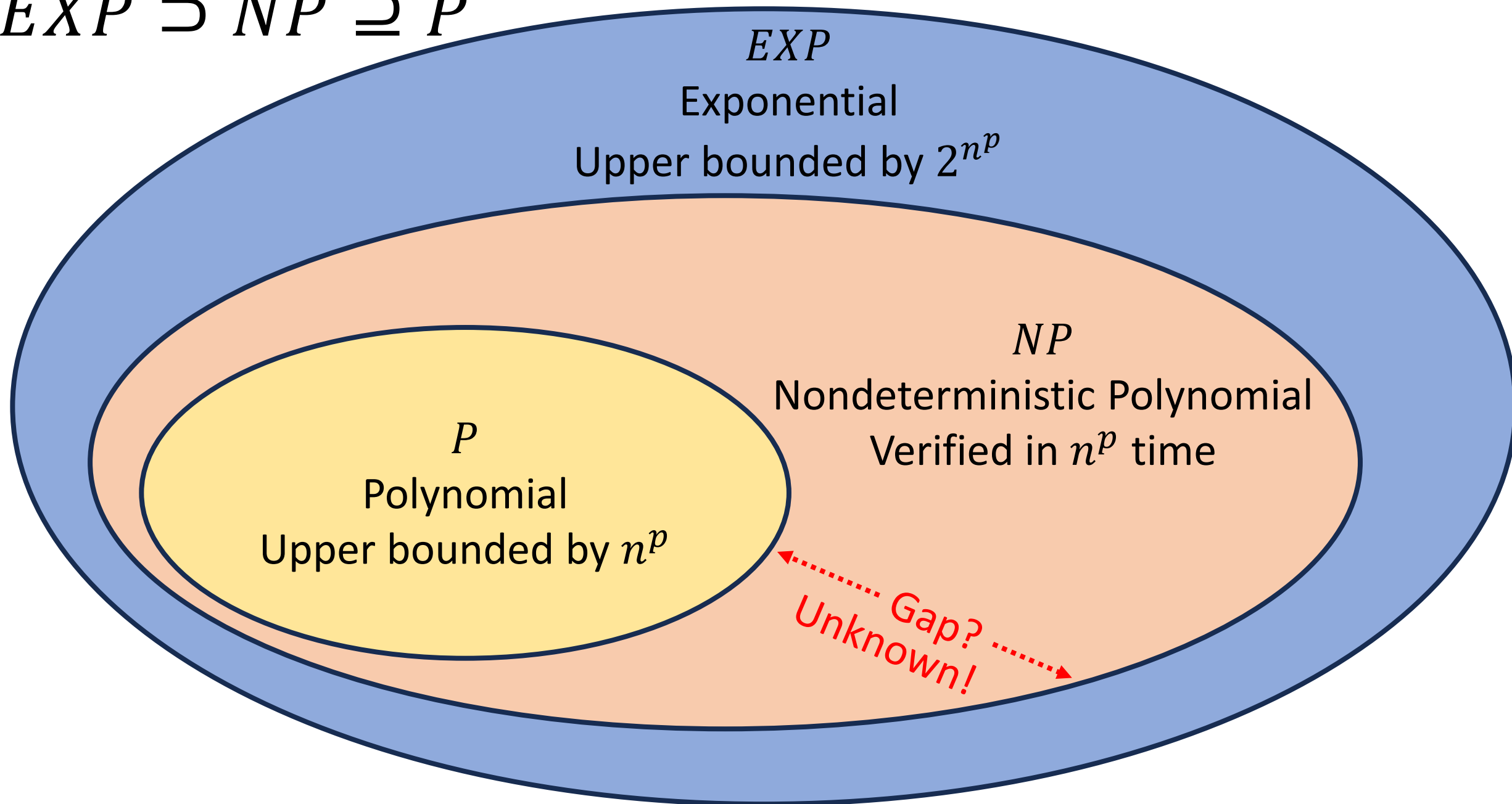
# Some problems in *EXP* seem “easier”

- There are some problems that we do not have polynomial time algorithms to solve, but provided answers are easy to check
- Hamiltonian Path:
  - It’s “hard” to look at a graph and determine whether it has a Hamiltonian Path
  - It’s “easy” to look at a graph and a candidate path together and determine whether THAT path is a Hamiltonian Path
    - It’s easy to **verify** whether a given path is a Hamiltonian path

# Class $NP$

- $NP$ 
  - The set of problems for which a candidate solution can be verified in polynomial time
  - Stands for “Non-deterministic Polynomial”
    - Corresponds to algorithms that can guess a solution (if it exists), that solution is then verified to be correct in polynomial time
    - Can also think of as allowing a special operation that allows the algorithm to magically guess the right choice at each step of an exhaustive search
- $P \subseteq NP$ 
  - Why?

$$EXP \supset NP \supseteq P$$

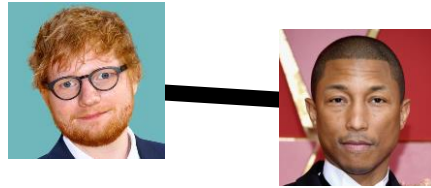


# Solving and Verifying Hamiltonian Path

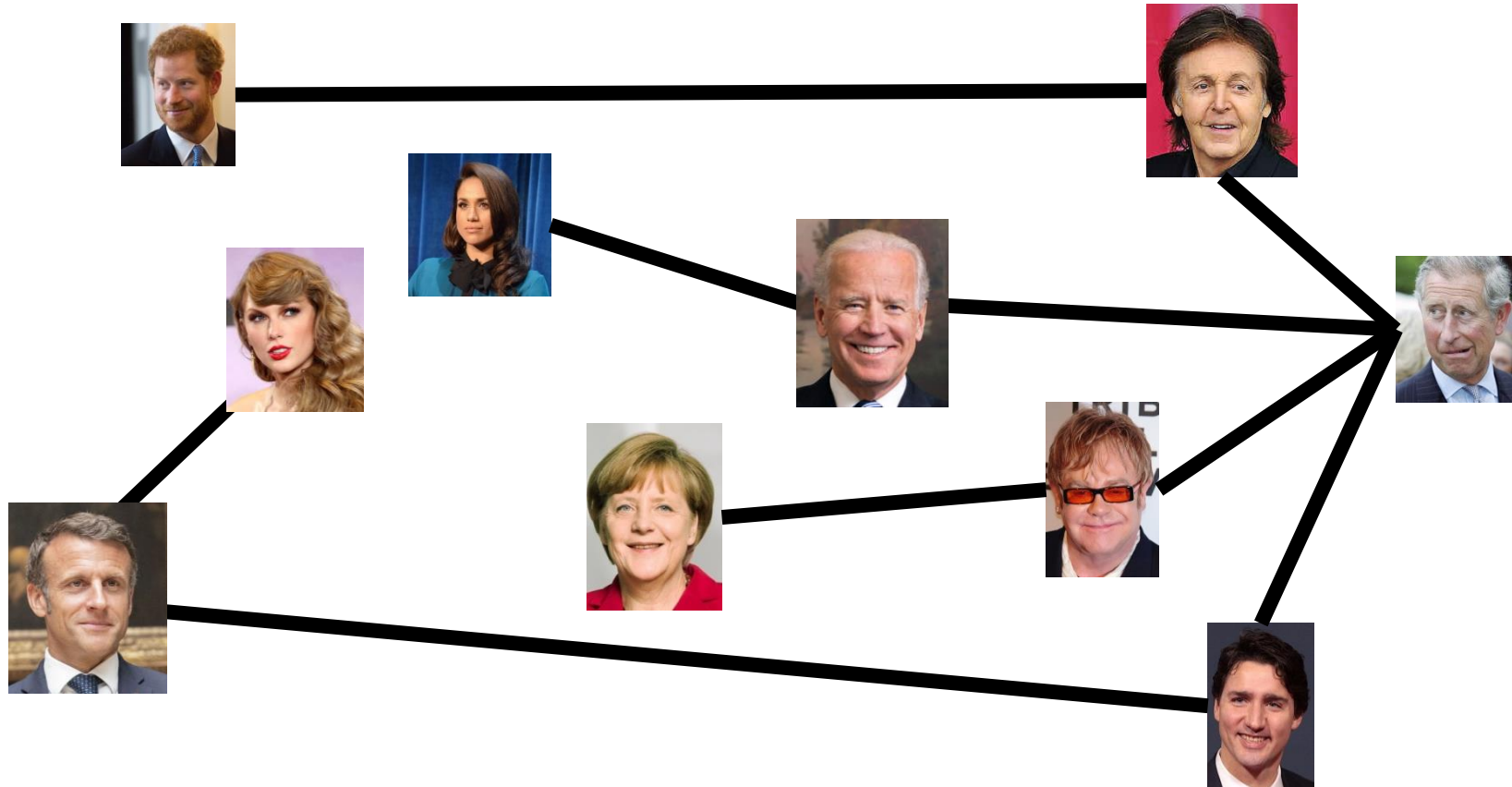
- Give an algorithm to solve Hamiltonian Path
  - Input:  $G = (V, E)$
  - Output: True if  $G$  has a Hamiltonian Path
  - Algorithm: Check whether each permutation of  $V$  is a path.
    - Running time:  $|V|!$ , so does not show whether it belongs to  $P$
- Give an algorithm to verify Hamiltonian Path
  - Input:  $G = (V, E)$  and a sequence of nodes
  - Output: True if that sequence of nodes is a Hamiltonian Path
  - Algorithm:
    - Check that each node appears in the sequence exactly once
    - Check that the sequence is a path
    - Running time:  $O(V \cdot E)$ , so it belongs to  $NP$



# Party Problem



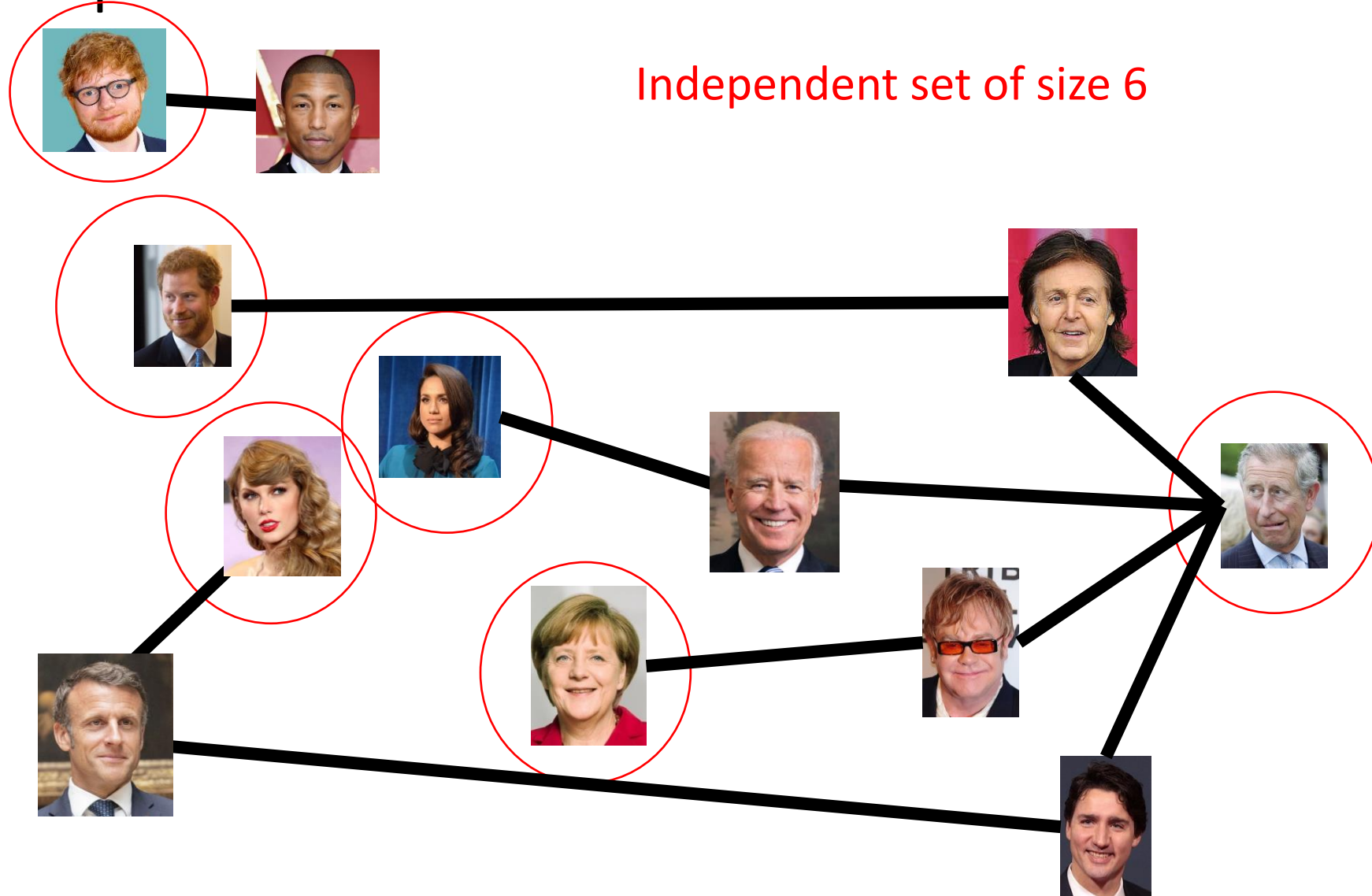
Draw Edges between people who don't get along  
How many people can I invite to a party if everyone must get along?



# Independent Set

- Independent set:
  - $S \subseteq V$  is an independent set if no two nodes in  $S$  share an edge
- Independent Set Problem:
  - Given a graph  $G = (V, E)$  and a number  $k$ , determine whether there is an independent set  $S$  of size  $k$

# Example

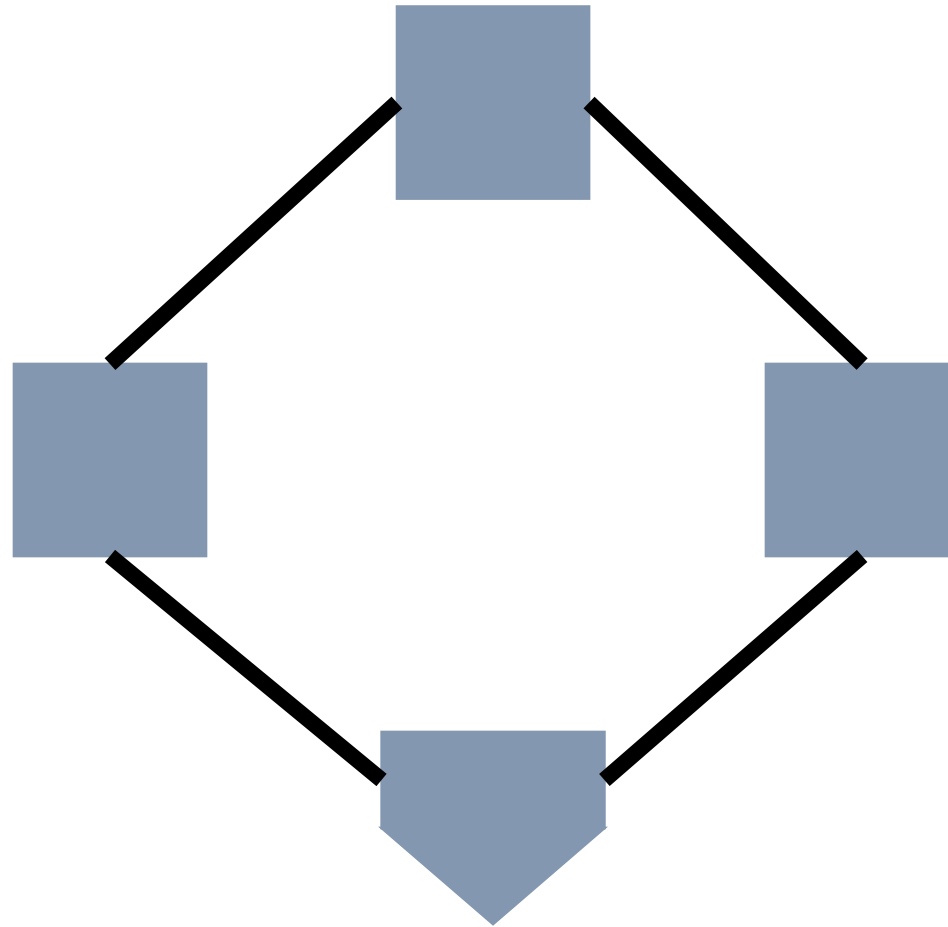


Independent set of size 6

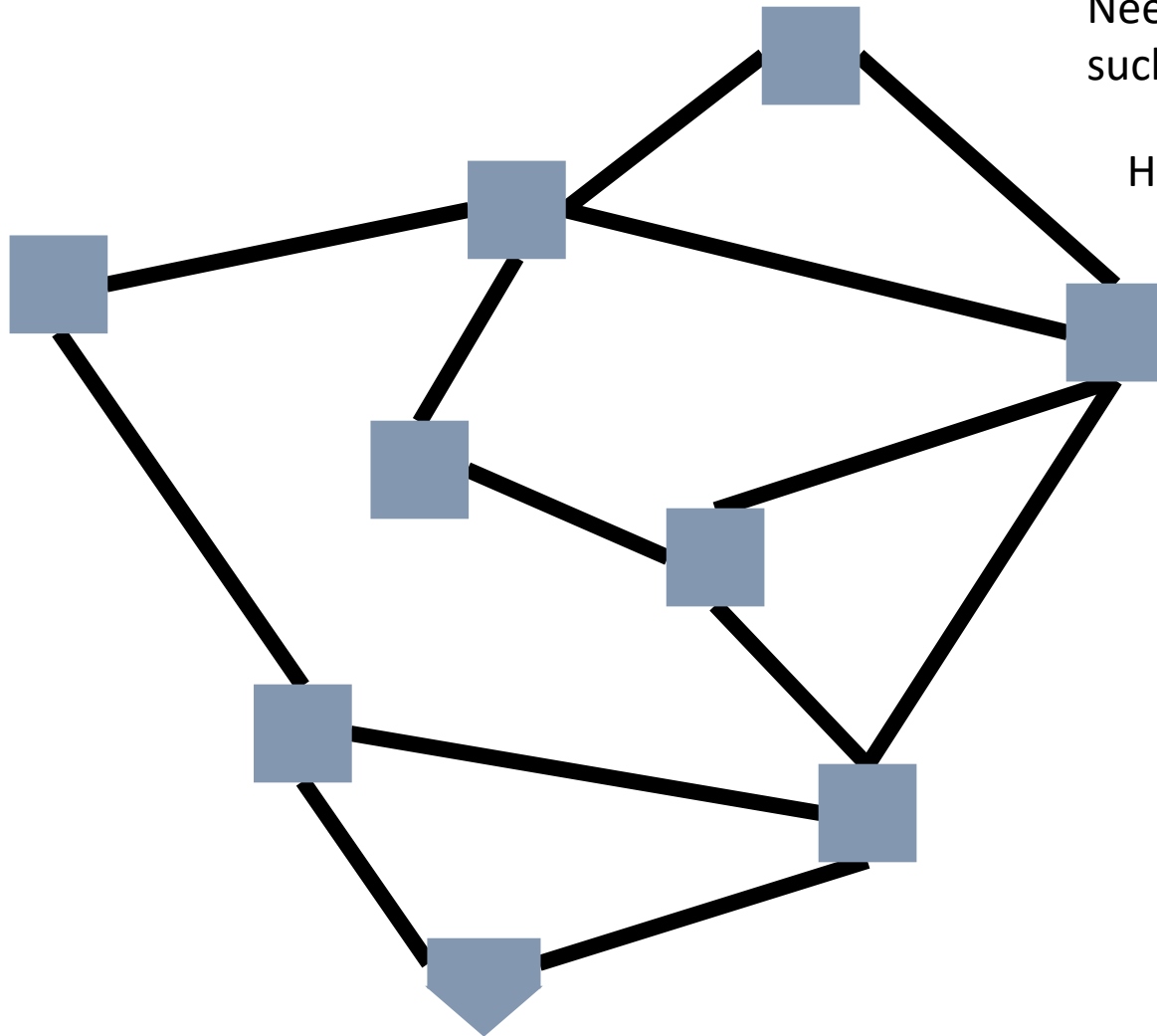
# Solving and Verifying Independent Set

- Give an algorithm to solve independent set
  - Input:  $G = (V, E)$  and a number  $k$
  - Output: True if  $G$  has an independent set of size  $k$
- Give an algorithm to verify independent set
  - Input:  $G = (V, E)$ , a number  $k$ , and a set  $S \subseteq V$
  - Output: True if  $S$  is an independent set of size  $k$

# Generalized Baseball



# Generalized Baseball



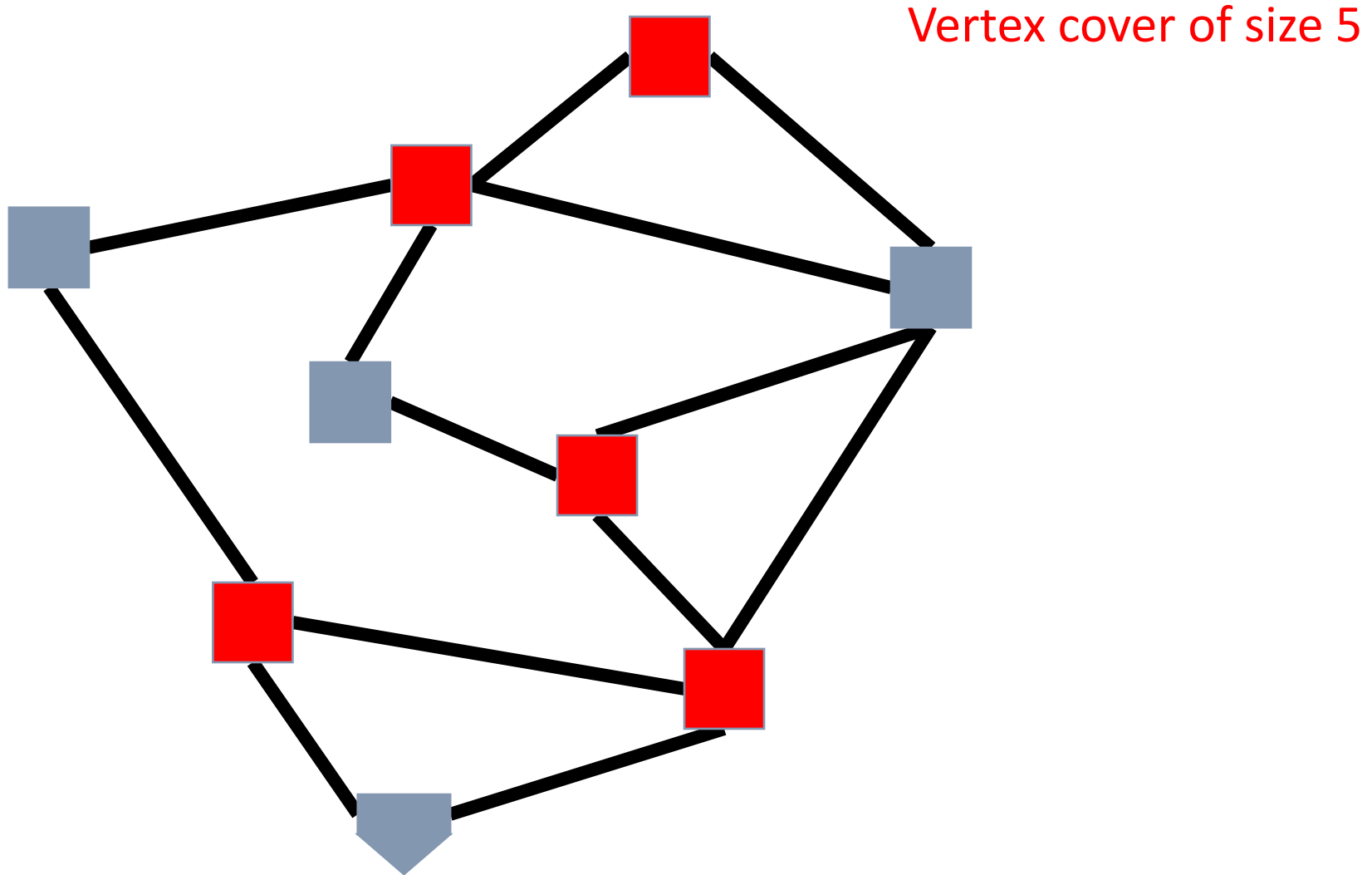
Need to place defenders on bases such that every edge is defended

How many defenders would suffice?

# Vertex Cover

- Vertex Cover:
  - $C \subseteq V$  is a vertex cover if every edge in  $E$  has one of its endpoints in  $C$
- Vertex Cover Problem:
  - Given a graph  $G = (V, E)$  and a number  $k$ , determine if there is a vertex cover  $C$  of size  $k$

# Example



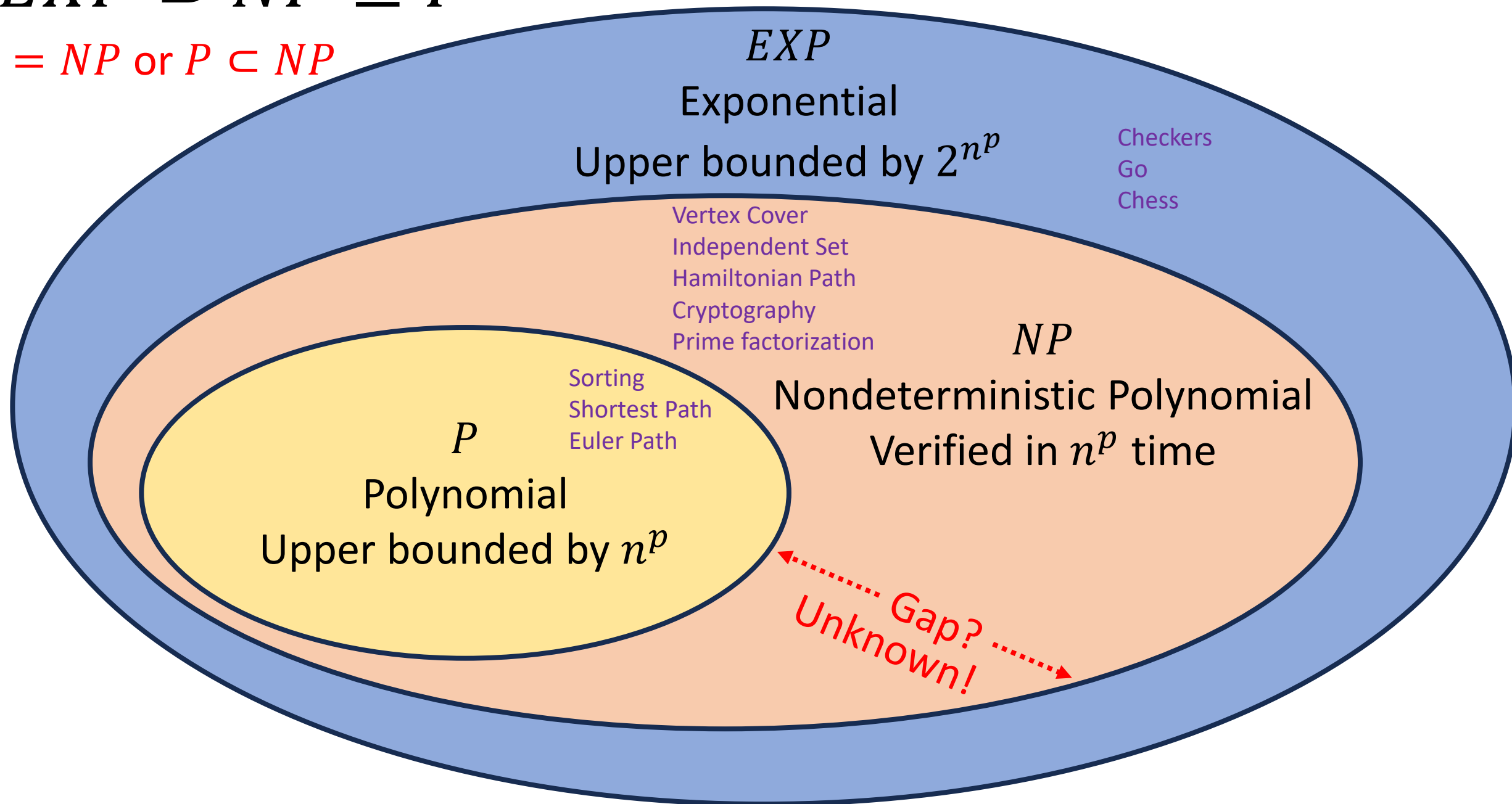


# Solving and Verifying Vertex Cover

- Give an algorithm to solve vertex cover
  - Input:  $G = (V, E)$  and a number  $k$
  - Output: True if  $G$  has a vertex cover of size  $k$
- Give an algorithm to verify vertex cover
  - Input:  $G = (V, E)$ , a number  $k$ , and a set  $S \subseteq E$
  - Output: True if  $S$  is a vertex cover of size  $k$

$$EXP \supset NP \supseteq P$$

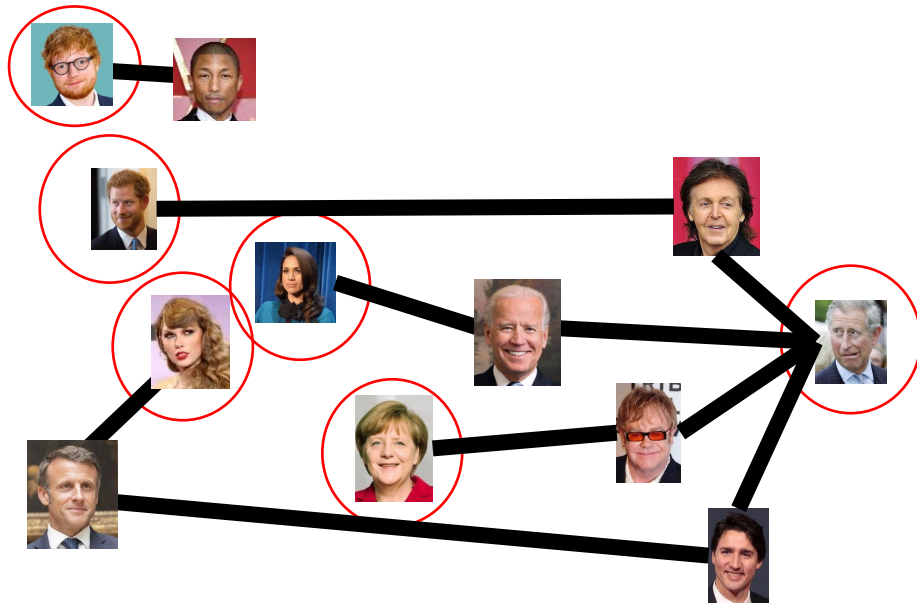
$P = NP$  or  $P \subset NP$



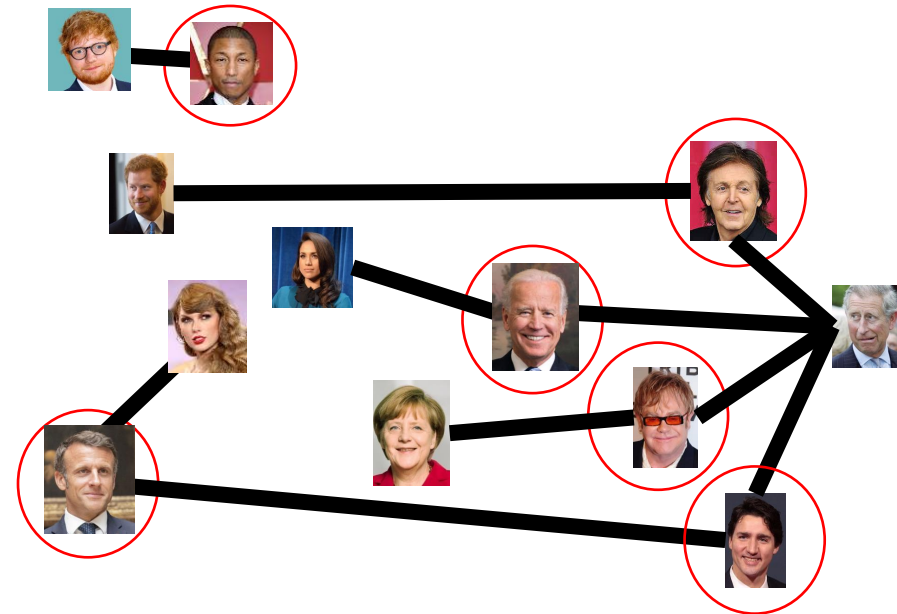
# Way Cool!

$S$  is an independent set of  $G$  iff  $V - S$  is a vertex cover of  $G$

Independent Set



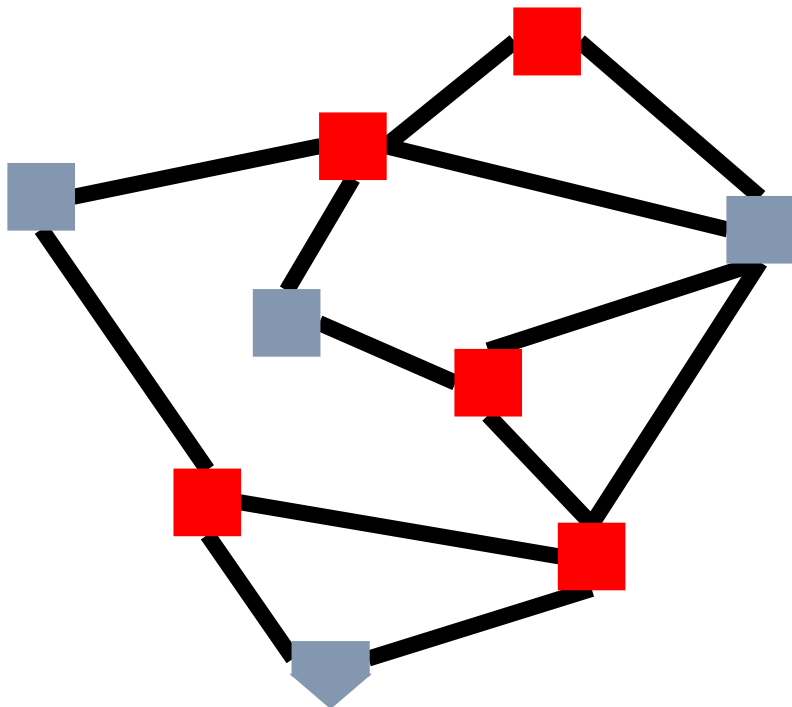
Vertex Cover



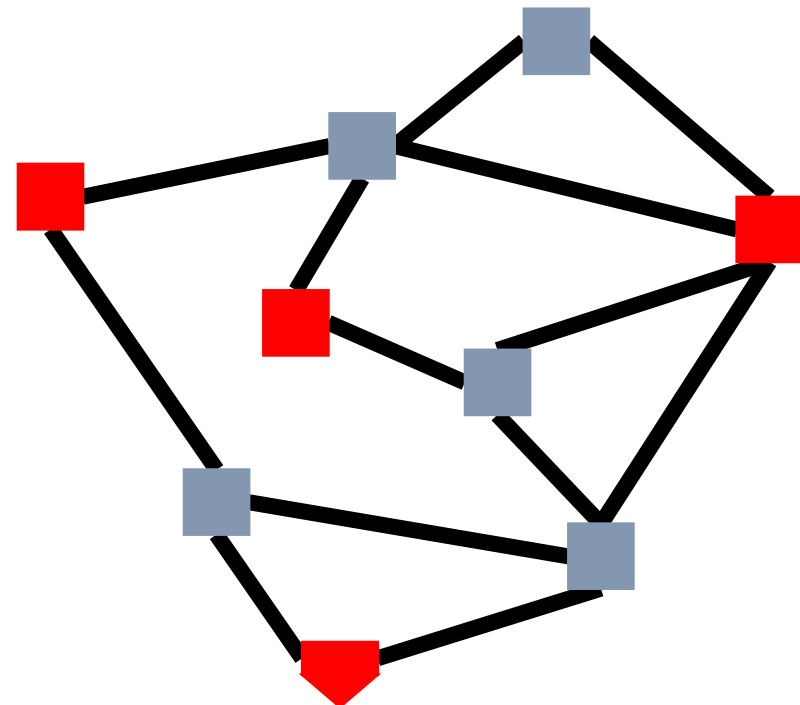
# Way Cool!

$S$  is an independent set of  $G$  iff  $V - S$  is a vertex cover of  $G$

Vertex Cover



Independent Set



# Solving Vertex Cover and Independent Set

- Algorithm to solve vertex cover
  - Input:  $G = (V, E)$  and a number  $k$
  - Output: True if  $G$  has a vertex cover of size  $k$ 
    - Check if there is an Independent Set of  $G$  of size  $|V| - k$
- Algorithm to solve independent set
  - Input:  $G = (V, E)$  and a number  $k$
  - Output: True if  $G$  has an independent set of size  $k$ 
    - Check if there is a Vertex Cover of  $G$  of size  $|V| - k$

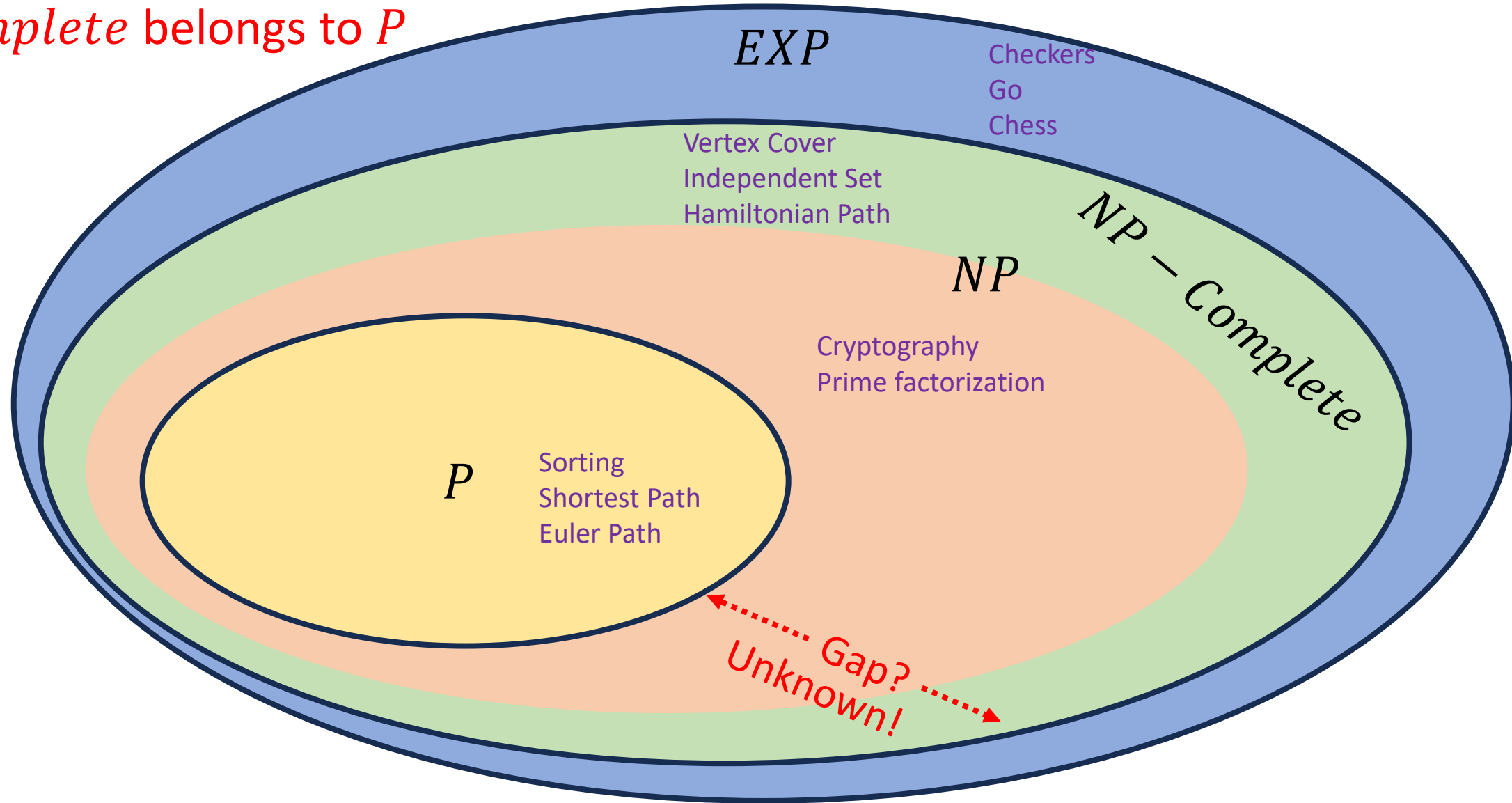
Either both problems belong to  $P$ , or else neither does!

# NP-Complete

- A set of “together they stand, together they fall” problems
- The problems in this set either all belong to  $P$ , or none of them do
- Intuitively, the “hardest” problems in NP
- Collection of problems from  $NP$  that can all be “transformed” into each other in polynomial time
  - Like we could transform independent set to vertex cover, and vice-versa
  - We can also transform vertex cover into Hamiltonian path, and Hamiltonian path into independent set, and ...

$$EXP \supset NP - Complete \supseteq NP \supseteq P$$

$P = NP$  iff some problem from  
 $NP - Complete$  belongs to  $P$



# Overview

- Problems not belonging to  $P$  are considered intractable
- The problems within  $NP$  have some properties that make them seem like they might be tractable, but we've been unsuccessful with finding polynomial time algorithms for many
- The class  $NP - Complete$  contains problems with the properties:
  - All members are also members of  $NP$
  - All members of  $NP$  can be transformed into every member of  $NP - Complete$
  - Therefore if any one member of  $NP - Complete$  belongs to  $P$ , then  $P = NP$



# Why should YOU care?

- If you can find a polynomial time algorithm for any *NP – Complete* problem then:
  - You will win \$1million
  - You will win a Turing Award
  - You will be world famous
  - You will have done something that no one else on Earth has been able to do in spite of the above!
- If you are told to write an algorithm a problem that is *NP – Complete*
  - You can tell that person everything above to set expectations
  - Change the requirements!
  - **Approximate the solution:** Instead of finding a path that visits every node, find a path that visits at least 75% of the nodes
  - **Add Assumptions:** problem might be tractable if we can assume the graph is acyclic, a tree
  - **Use Heuristics:** Write an algorithm that’s “good enough” for small inputs, ignore edge cases