

CSE 332 Winter 2024

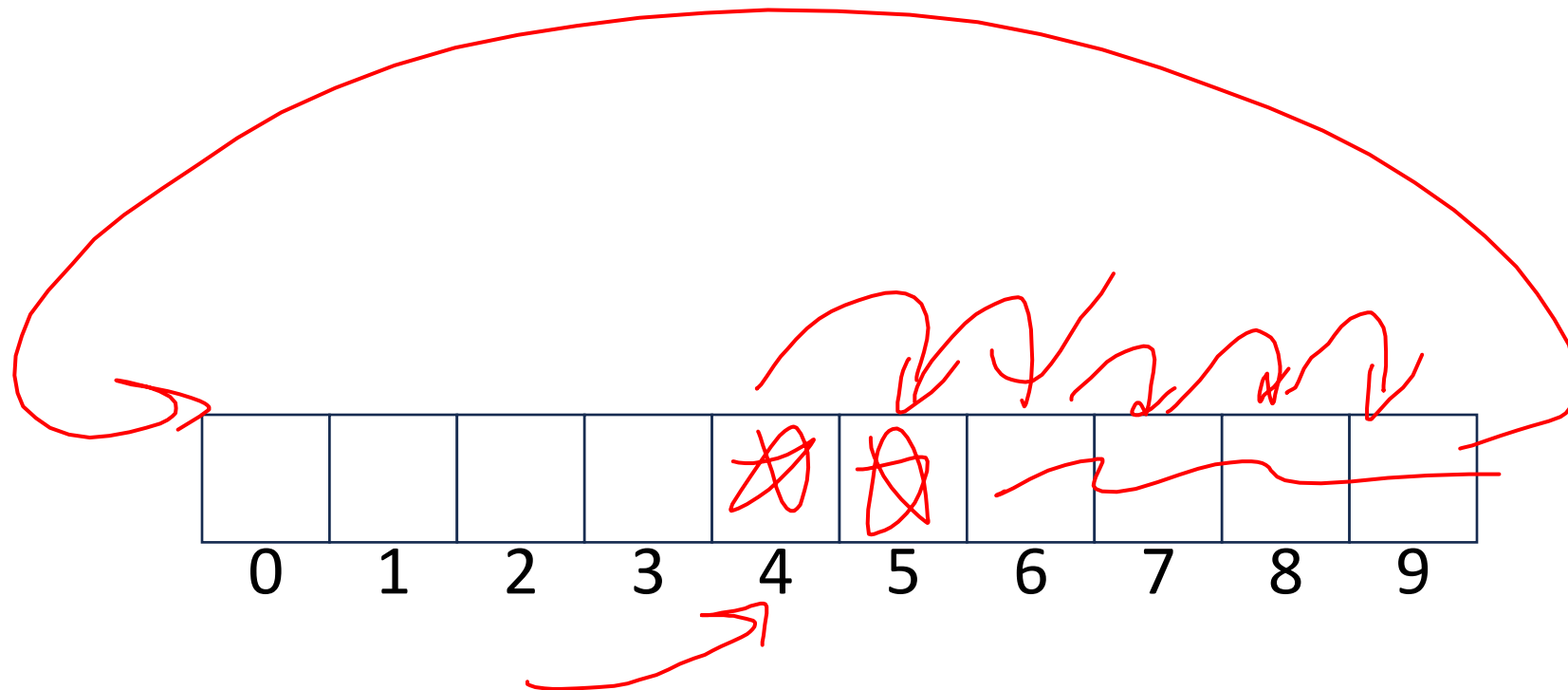
Lecture 13: Hashing and Sorting

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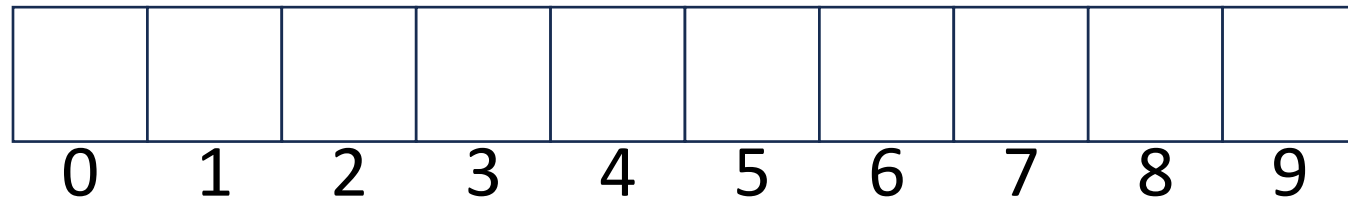
Collision Resolution: Linear Probing

- When there's a collision, use the next open space in the table



Linear Probing: Insert Procedure

- To insert k, v
 - Calculate $i = h(k) \% arrsize$
 - If $table[i]$ is occupied then try $(i + 1) \% arrsize$
 - If that is occupied try $(i + 2) \% arrsize$
 - If that is occupied try $(i + 3) \% arrsize$
 - ...



Linear Probing: Find

- $i = h(k) \% arrsize$
 - If i has the key or it's empty, then we're done
 - Otherwise:
 - Check $(i + 1) \% arrsize$ if it's there, done else
 - Check $(i + 2) \% arrsize$ if it's there, done else
 - Check $(i + 3) \% arrsize$
 - ...
 - Until we hit an empty cell

Linear Probing: Find

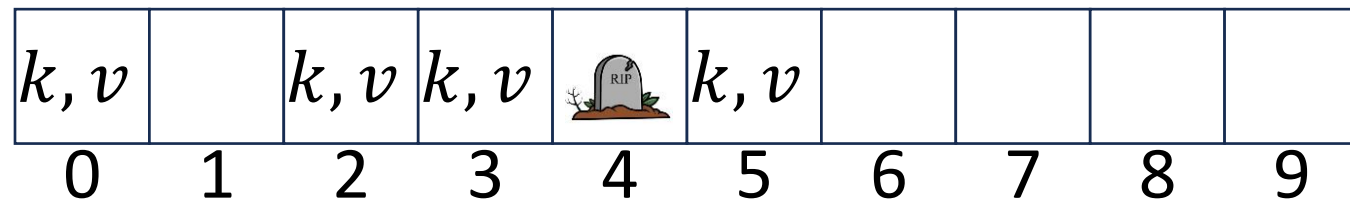
- To find key k
 - Calculate $i = h(k) \% arrsize$
 - If $table[i]$ is occupied and does not contain k then look at $(i + 1) \% arrsize$
 - If that is occupied and does not contain k then look at $(i + 2) \% arrsize$
 - If that is occupied and does not contain k then look at $(i + 3) \% arrsize$
 - Repeat until you either find k or else you reach an empty cell in the table

Linear Probing: Delete

- Problem: don't want to leave an empty space when deleting
- Option 1: when we delete, move the “last thing” with a matching hash to that location
- Option 2: “tombstone” deletion. When deleting something, leave a special marker to indicate something used to be there
-

Linear Probing: Delete

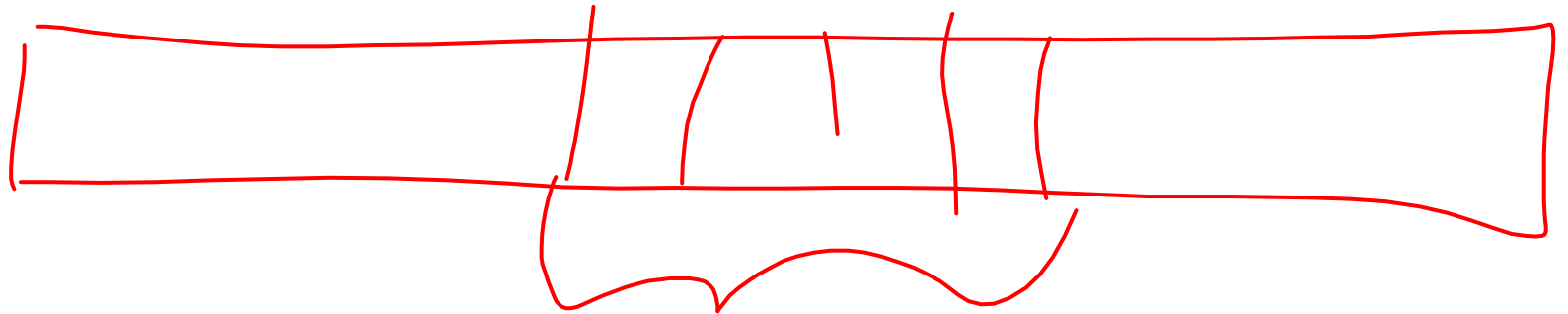
- Option 1: Find the last thing with a matching hash, move that into the spot you deleted from
- Option 2: Called “tombstone” deletion. Leave a special object that indicates an object was deleted from there
 - The tombstone does not act as an open space when finding (so keep looking after its reached)
 - When inserting you can replace a tombstone with a new item



Downsides of Linear Probing

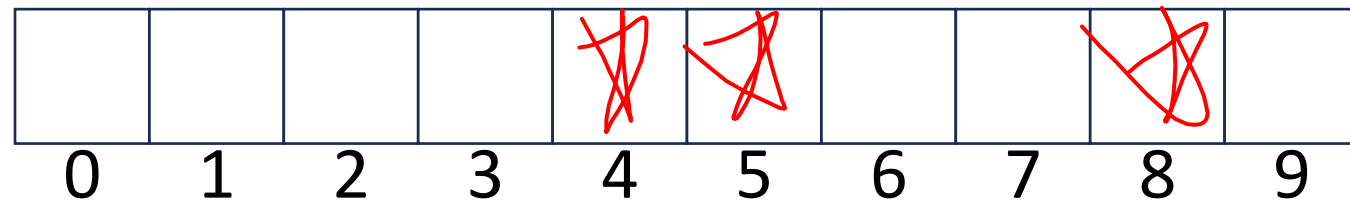
- What happens when λ approaches 1?
 - Longer and longer clusters of items
 - Running times get longer and longer

λ
length L



Quadratic Probing: Insert Procedure

- To insert k, v
 - Calculate $i = h(k) \% arrsize$
 - If $table[i]$ is occupied then try $(i + 1^2) \% arrsize$
 - If that is occupied try $(i + 2^2) \% arrsize$
 - If that is occupied try $(i + 3^2) \% arrsize$
 - If that is occupied try $(i + 4^2) \% arrsize$
 - ...



Quadratic Probing: Example

- Insert:

- 76 $107 = 6$

- 40 $407 = 5$

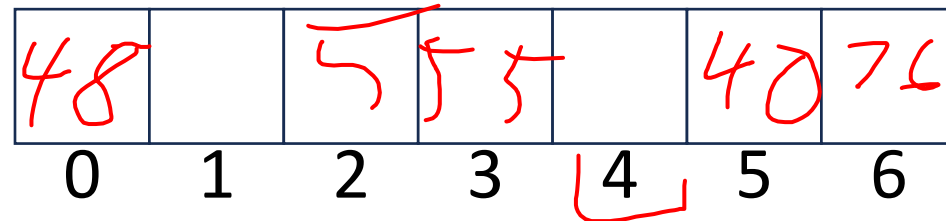
→

- 48 $2107 = 6$

- 5 $\rightarrow 5 + 1^2 \rightarrow 5 + 2^2$

- 55 $\rightarrow 6 + 1^2 \rightarrow 6 + 2^2$
- 47

↳ $5 + 1^2 \neq 5 + 2^2 \rightarrow 5 + 3^2 \rightarrow 5 + 4^2$
 $\rightarrow 5 + 5^2$



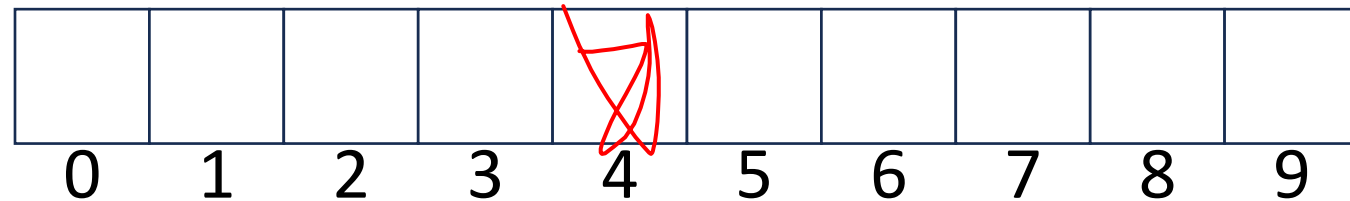
Using Quadratic Probing

- If you probe *tablesize* times, you start repeating the same indices
- If *tablesize* is prime and $\lambda < \frac{1}{2}$ then you're guaranteed to find an open spot in at most *tablesize*/2 probes
- Helps with the clustering problem of linear probing, but does not help if many things hash to the same value

Double Hashing: Insert Procedure

$$g(k) = \delta$$

- Given h and g are both good hash functions
- To insert k, v
 - Calculate $i = h(k) \% \text{size}$
 - If $table[i]$ is occupied then try $(i + g(k)) \% \text{size}$
 - If that is occupied try $(i + 2 \cdot g(k)) \% \text{size}$
 - If that is occupied try $(i + 3 \cdot g(k)) \% \text{size}$
 - If that is occupied try $(i + 4 \cdot g(k)) \% \text{size}$
 - ...



Rehashing

← Rehashing

- If your load factor λ gets too large, copy everything over to a larger hash table
 - To do this: make a new array with a new hash function (maybe just a new modulus)
 - Re-insert all items into the new hash table with the new hash function
 - New hash table should be “roughly” double the size (but probably still want it to be prime)

General Guideline:

- Separate Chaining: rehash when $\lambda = 2$
- Open Addressing: rehash when $\lambda = \frac{1}{2}$

← 2, 5, 11, 23, 47

←
←

Sorting

- Rearrangement of items into some defined sequence
 - Usually: reordering a list from smallest to largest according to some metric
- Why sort things?

- makes other things faster

- Bin search
- PD
- min/max / percentiles

More Formal Definition

$$A[i] = 15$$

• Input:

- An array A of items
- A comparison function for these items
 - Given two items x and y , we can determine whether $x < y$, $x > y$, or $x = y$

• Output:

- A permutation of A such that if $i \leq j$ then $A[i] \leq A[j]$
- Permutation: a sequence of the same items but perhaps in a different order

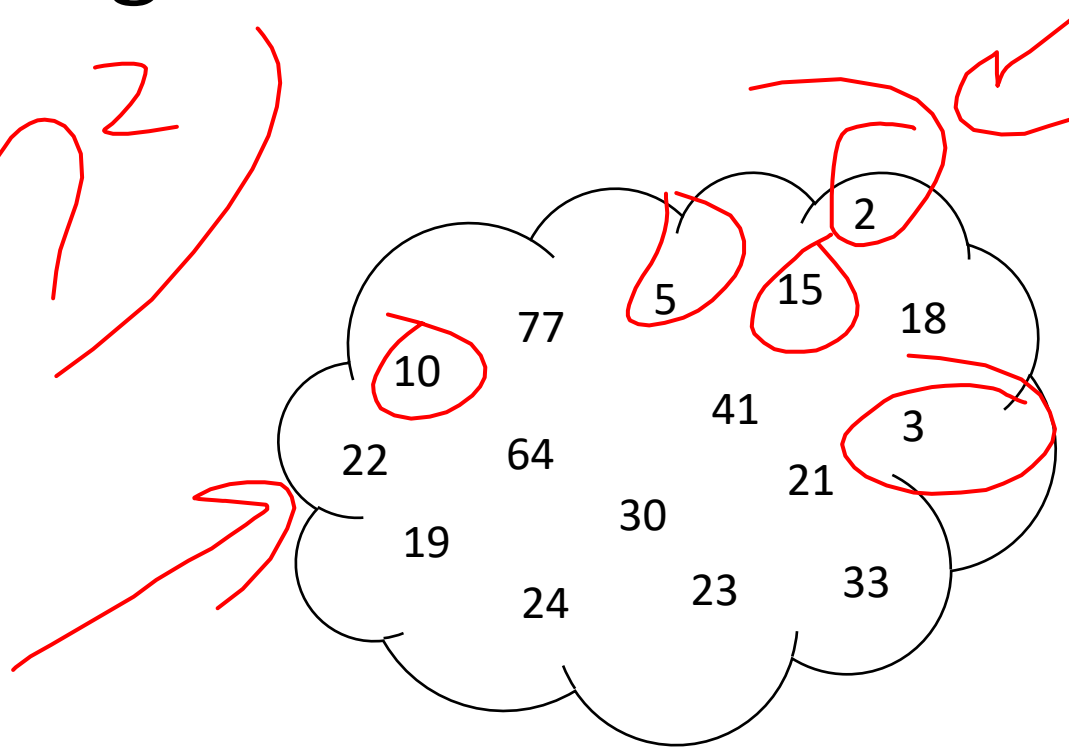
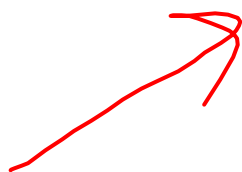
Sorting “Landscape”

- There is no singular best algorithm for sorting
- Some are faster, some are slower
- Some use more memory, some use less
- Some are super extra fast if your data matches particular assumptions
- Some have other special properties that make them valuable
- No sorting algorithm can have only all the “best” attributes



“Moving Day” Sorting Algorithm

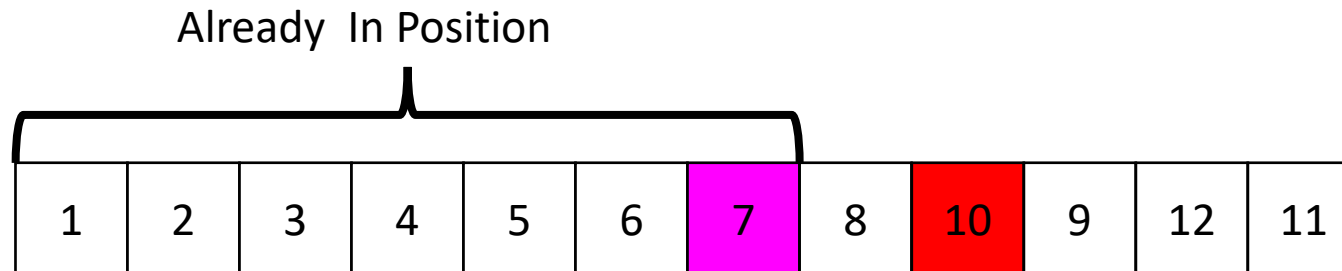
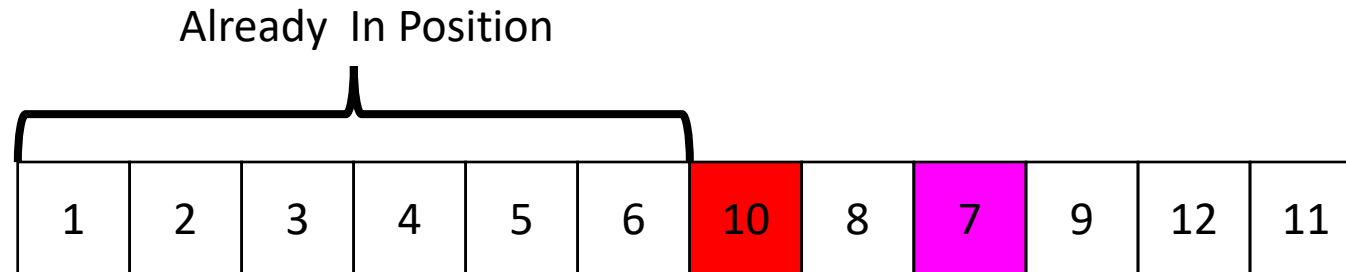
$O(n^2)$



2	3	5	10	15															
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15				

Selection Sort

- Idea: Find the **next smallest** element, swap it into the **next index** in the array



Selection Sort

- Swap the thing at index 0 with the smallest thing in the array
- Swap the thing at index 1 with the smallest thing after index 0
- ...
- Swap the thing at index i with the smallest thing after index $i - 1$

```
for (i=0; i<a.length; i++){  
    smallest = i;  
    for (j=i; j<a.length; j++){  
        if (a[j]<a[smallest]){ smallest=j;}  
    }  
    temp = a[i];  
    a[i] = a[smallest];  
    a[smallest] = temp;  
}
```

Running Time:

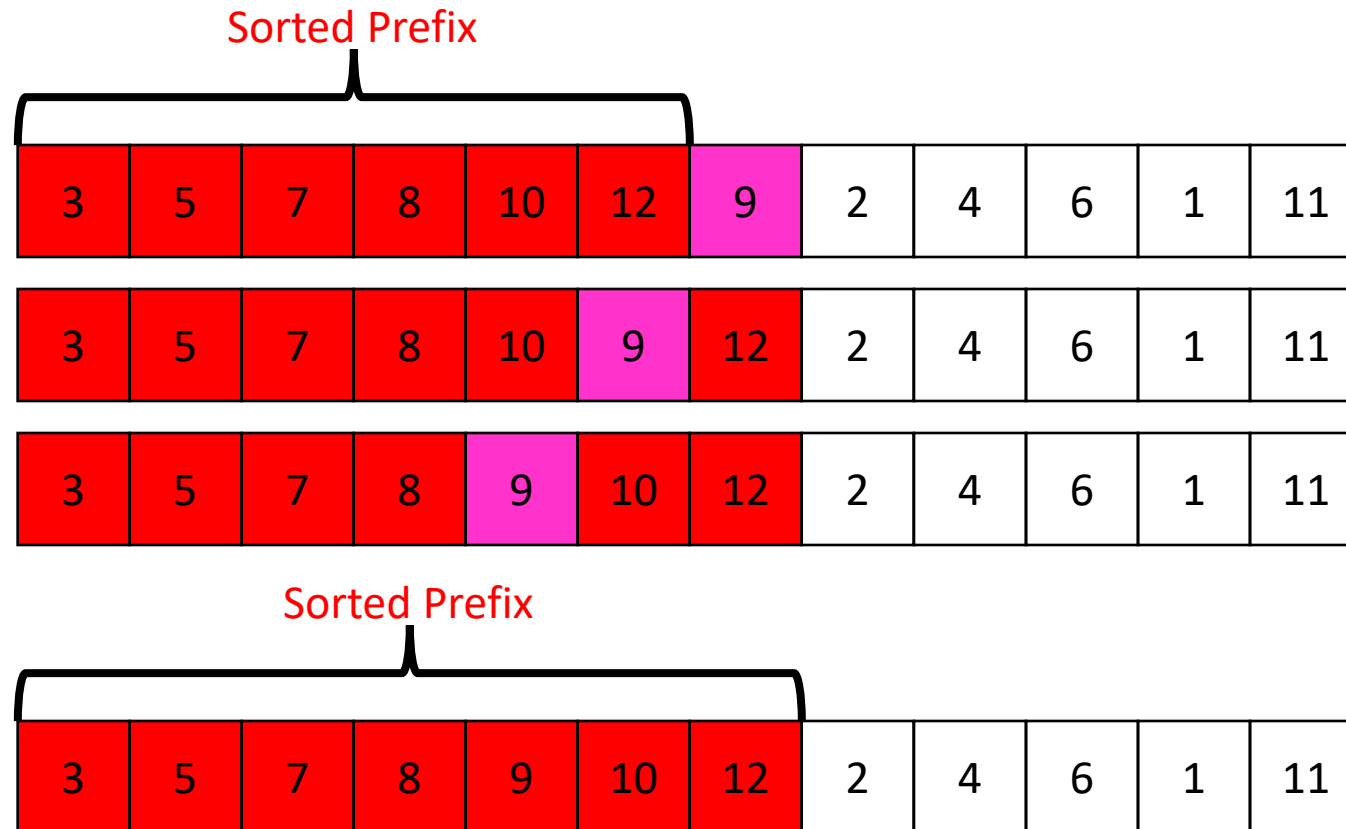
Worst Case: $\Theta(n^2)$

Best Case: $\Theta(n^2)$

10	77	5	15	2	22	64	41	18	19	30	21	3	24	23	33
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

Insertion Sort

- **Idea:** Maintain a **sorted list prefix**, extend that prefix by “inserting” the **next element**



Insertion Sort

- If the items at index 0 and 1 are out of order, swap them
- Keep swapping the item at index 2 with the thing to its left as long as the left thing is larger
- ...
- Keep swapping the item at index i with the thing to its left as long as the left thing is larger

```
for (i=1; i<a.length; i++){  
  prev = i-1;  
  while(a[i] < a[prev] && prev > -1){  
    temp = a[i];  
    a[i] = a[prev];  
    a[prev] = temp;  
    i--;  
    prev--;  
  }  
}
```

Running Time:

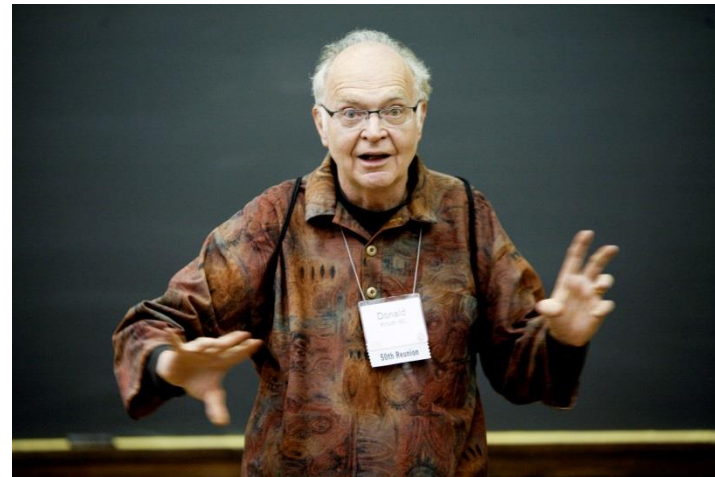
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Best Case: $\Theta(n)$

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0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

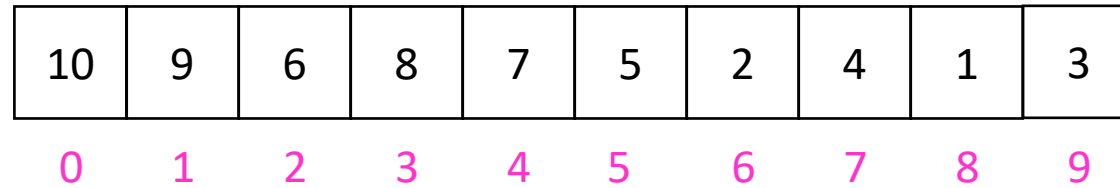
Aside: Bubble Sort – we won't cover it

"the bubble sort seems to have nothing to recommend it, except a catchy name and the fact that it leads to some interesting theoretical problems" –Donald Knuth, The Art of Computer Programming



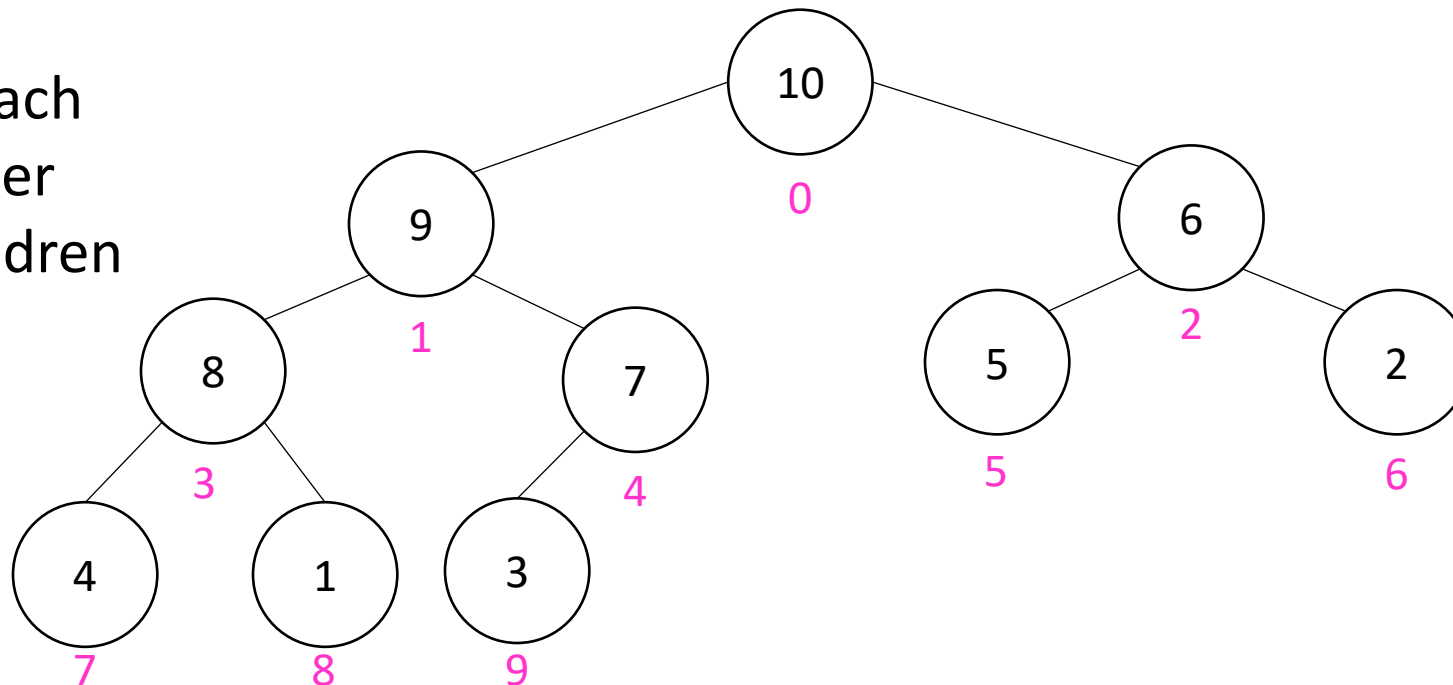
Heap Sort

- **Idea:** Build a maxHeap, repeatedly delete the max element from the heap to build sorted list Right-to-Left



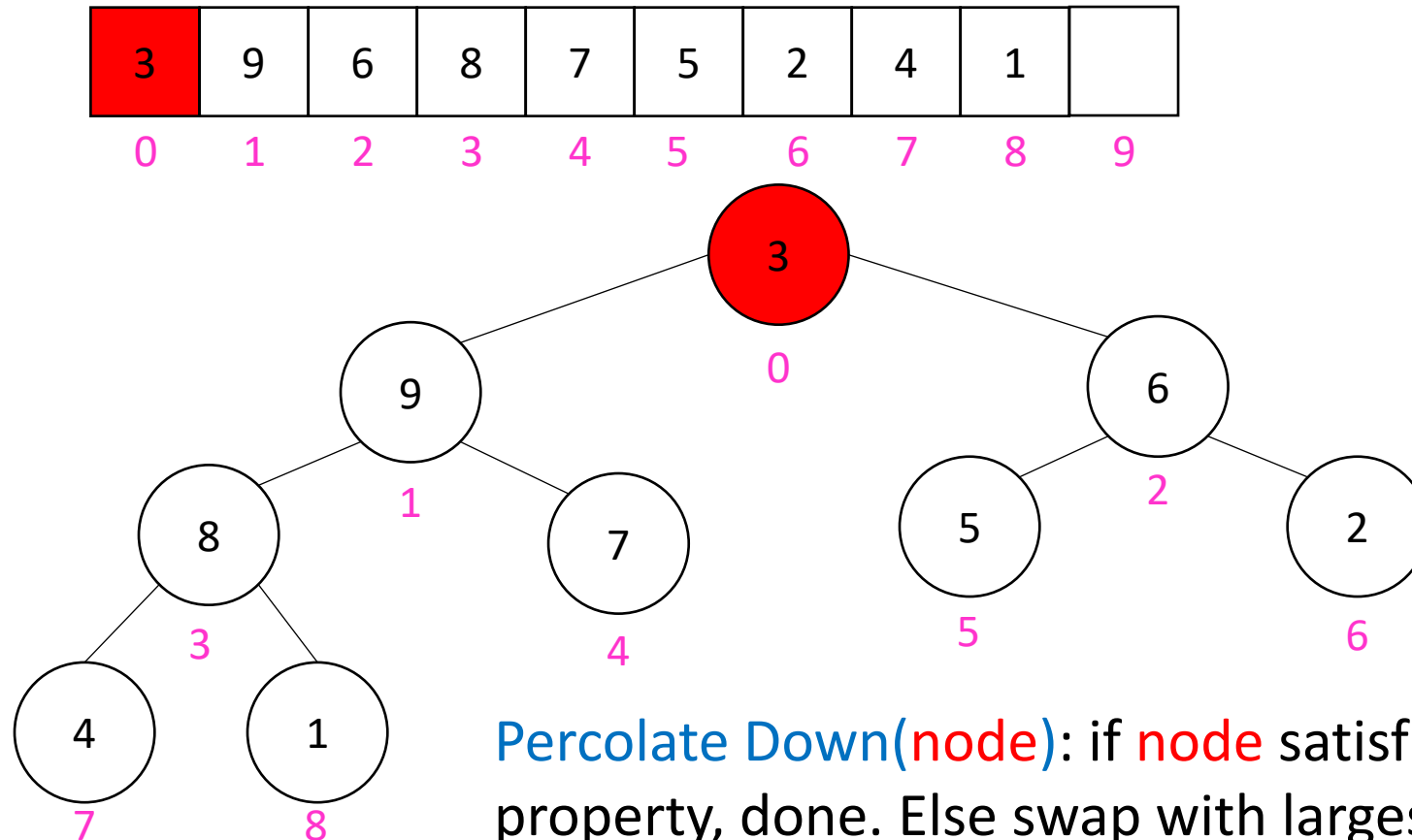
Max Heap

Property: Each node is larger than its children



Heap Sort

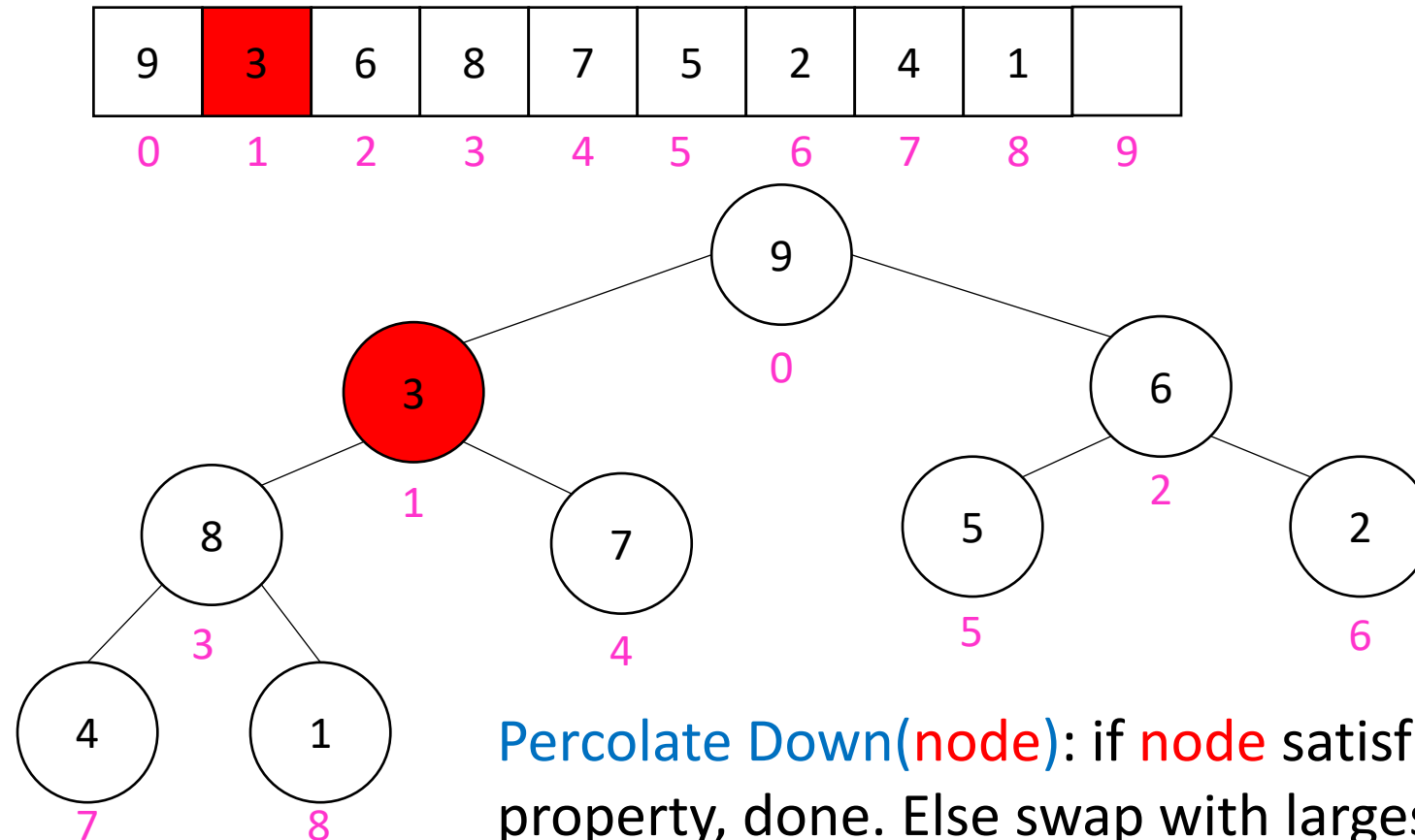
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call `percolateDown(root)`



Percolate Down(node): if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort

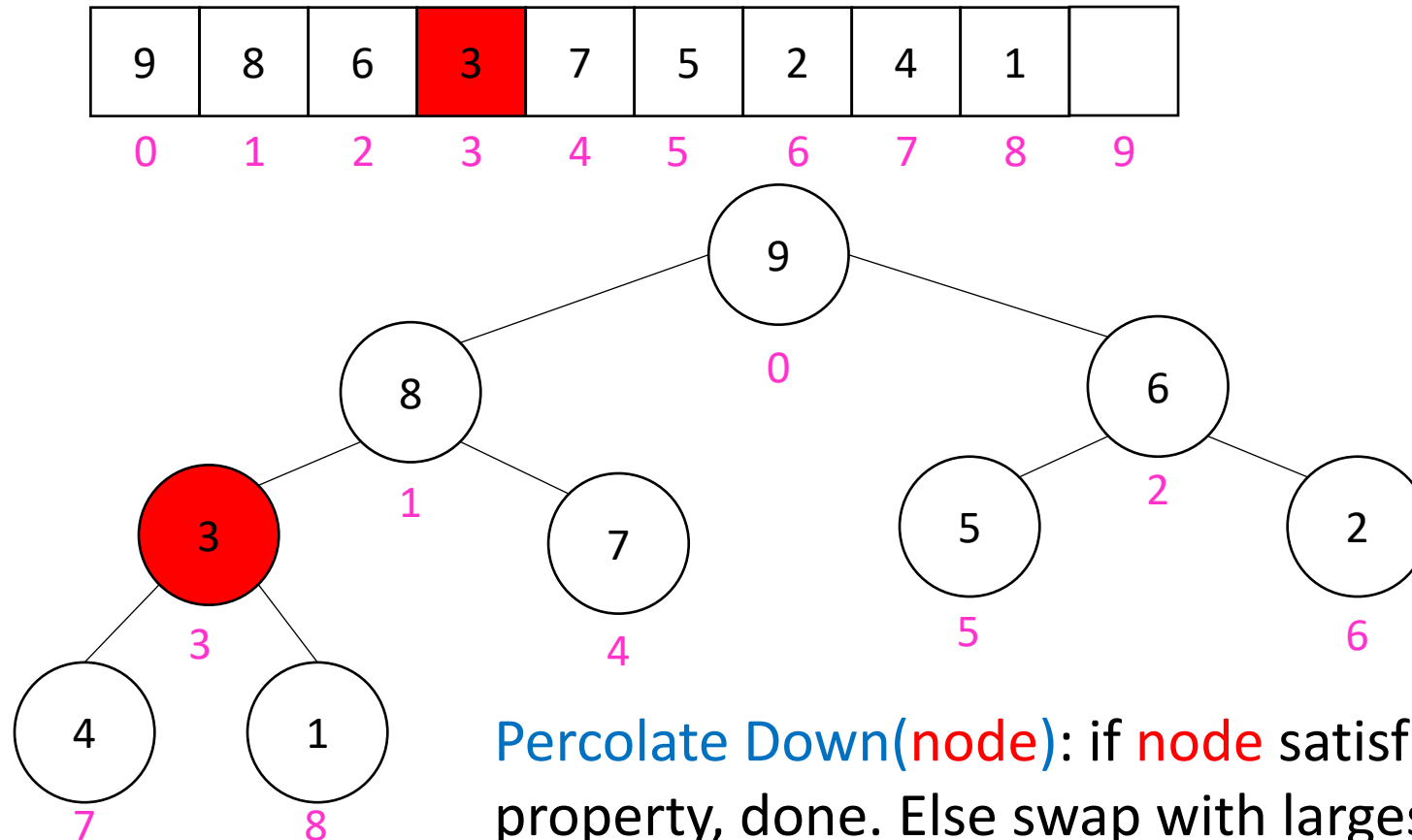
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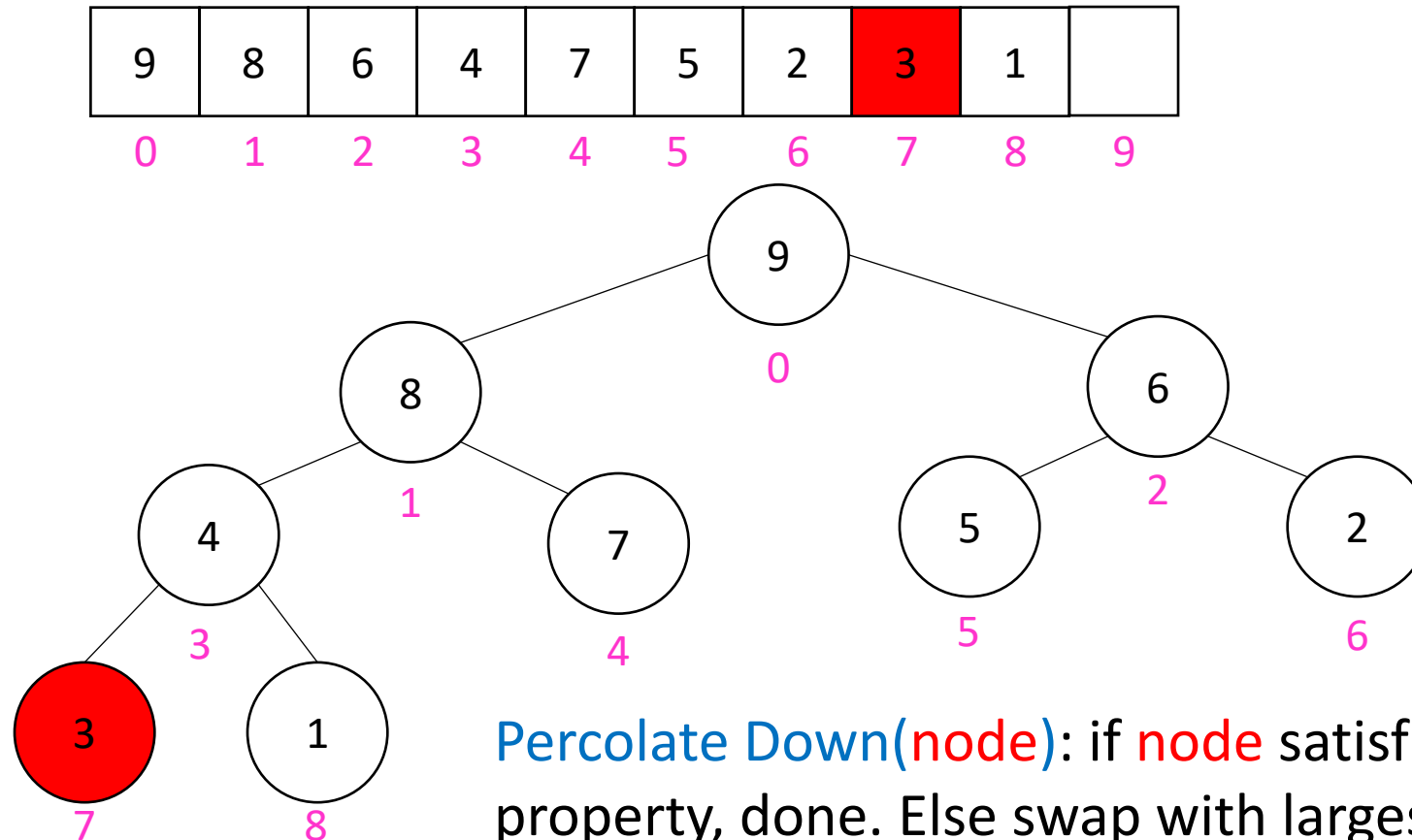
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Heap Sort

- Remove the Max element (i.e. the root) from the Heap: replace with last element, call percolateDown(root)



Percolate Down(node): if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort

- Build a heap
- Call deleteMax
- Put that at the end of the array

```
myHeap = buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    item = myHeap.deleteMax();  
    a[i] = item;  
}
```

Running Time:

Worst Case: $\Theta(\cdot)$

Best Case: $\Theta(\cdot)$

“In Place” Sorting Algorithm

- A sorting algorithm which requires no extra data structures
- Idea: It sorts items just by swapping things in the same array given
- Definition: it only uses $\Theta(1)$ extra space

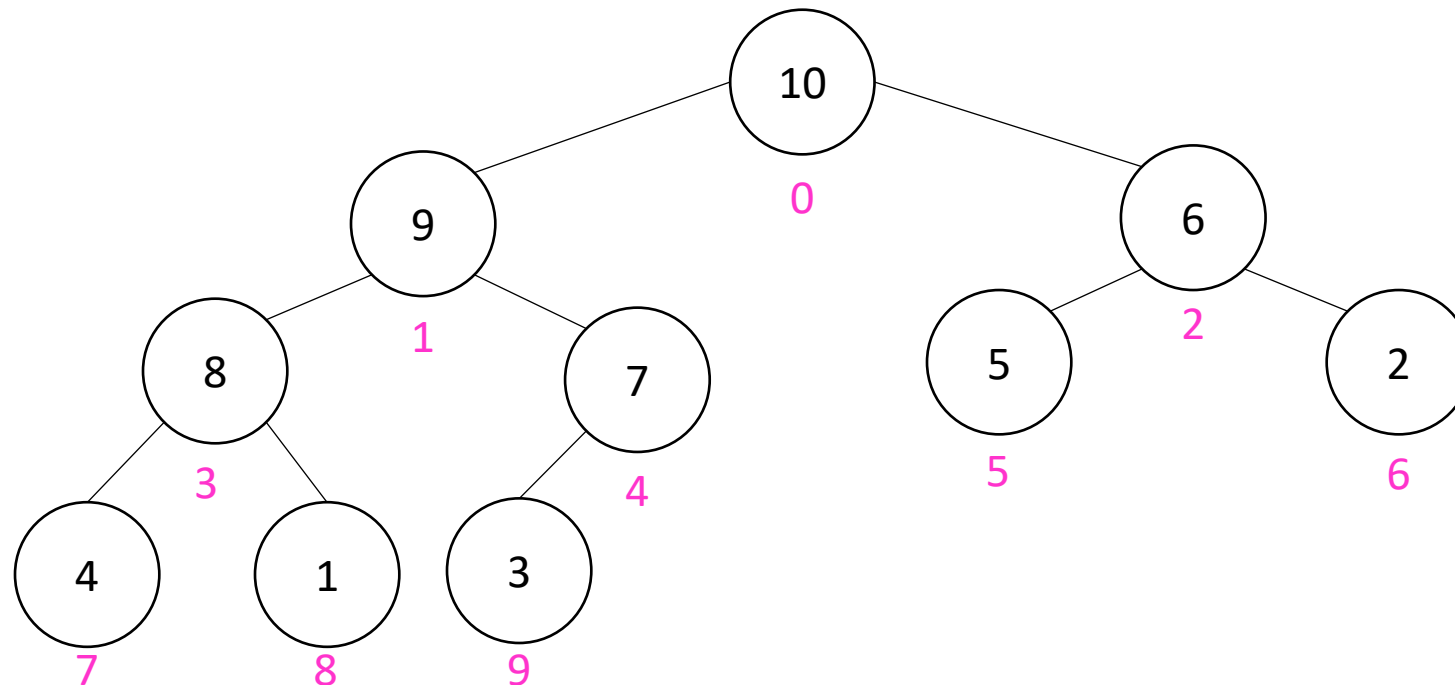
- Selection sort: In Place!
- Insertion sort: In Place!
- Heap sort: Not In Place!
 - But we can fix that!

In Place Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

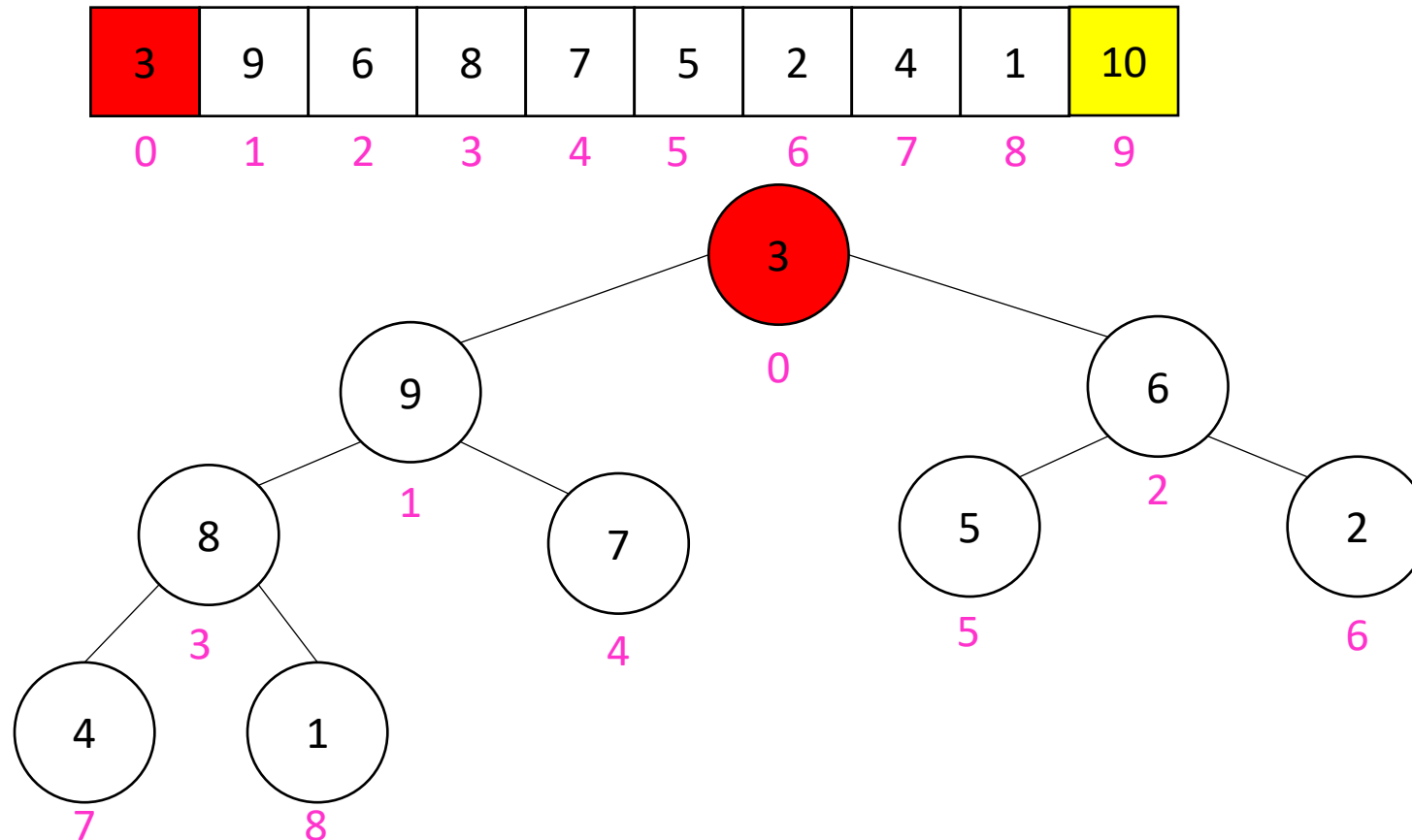
10	9	6	8	7	5	2	4	1	3
----	---	---	---	---	---	---	---	---	---

0 1 2 3 4 5 6 7 8 9



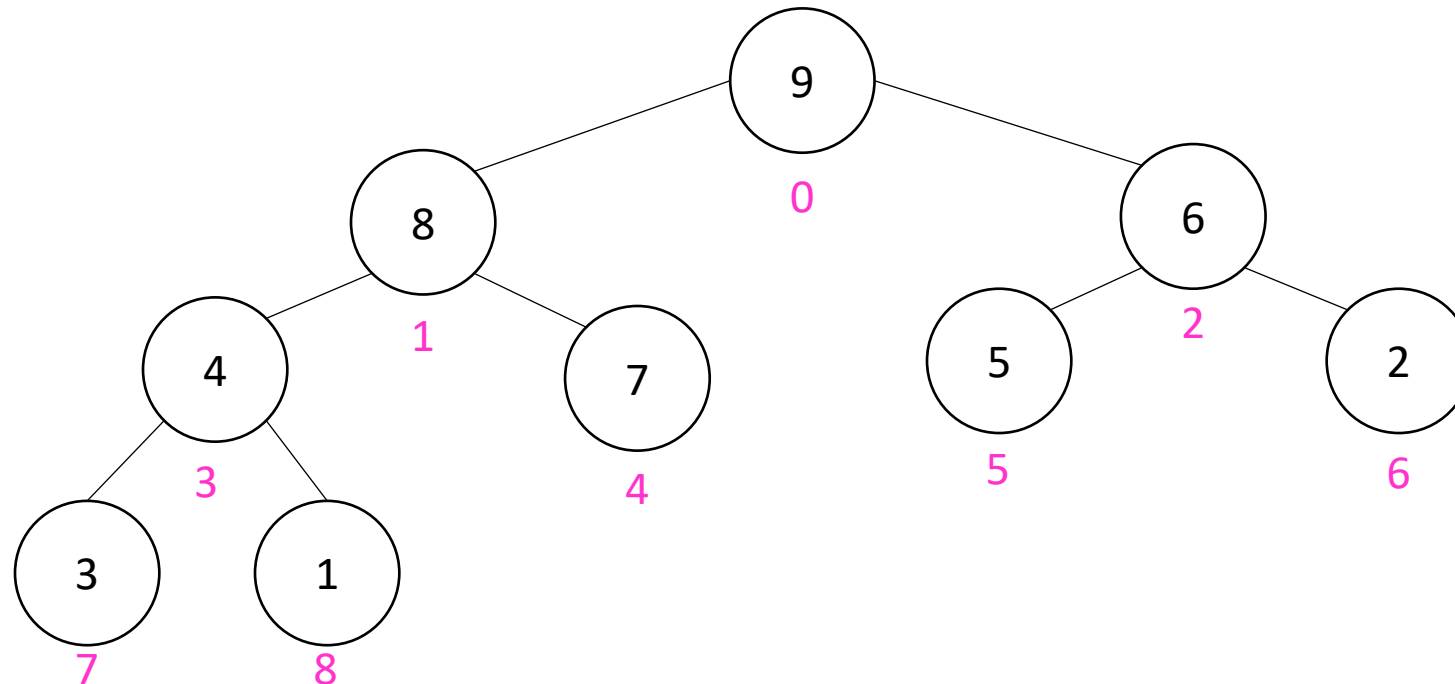
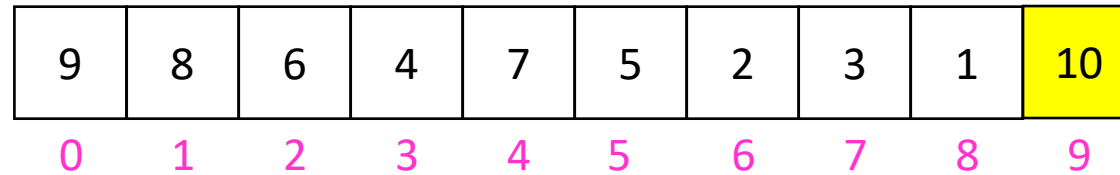
Heap Sort

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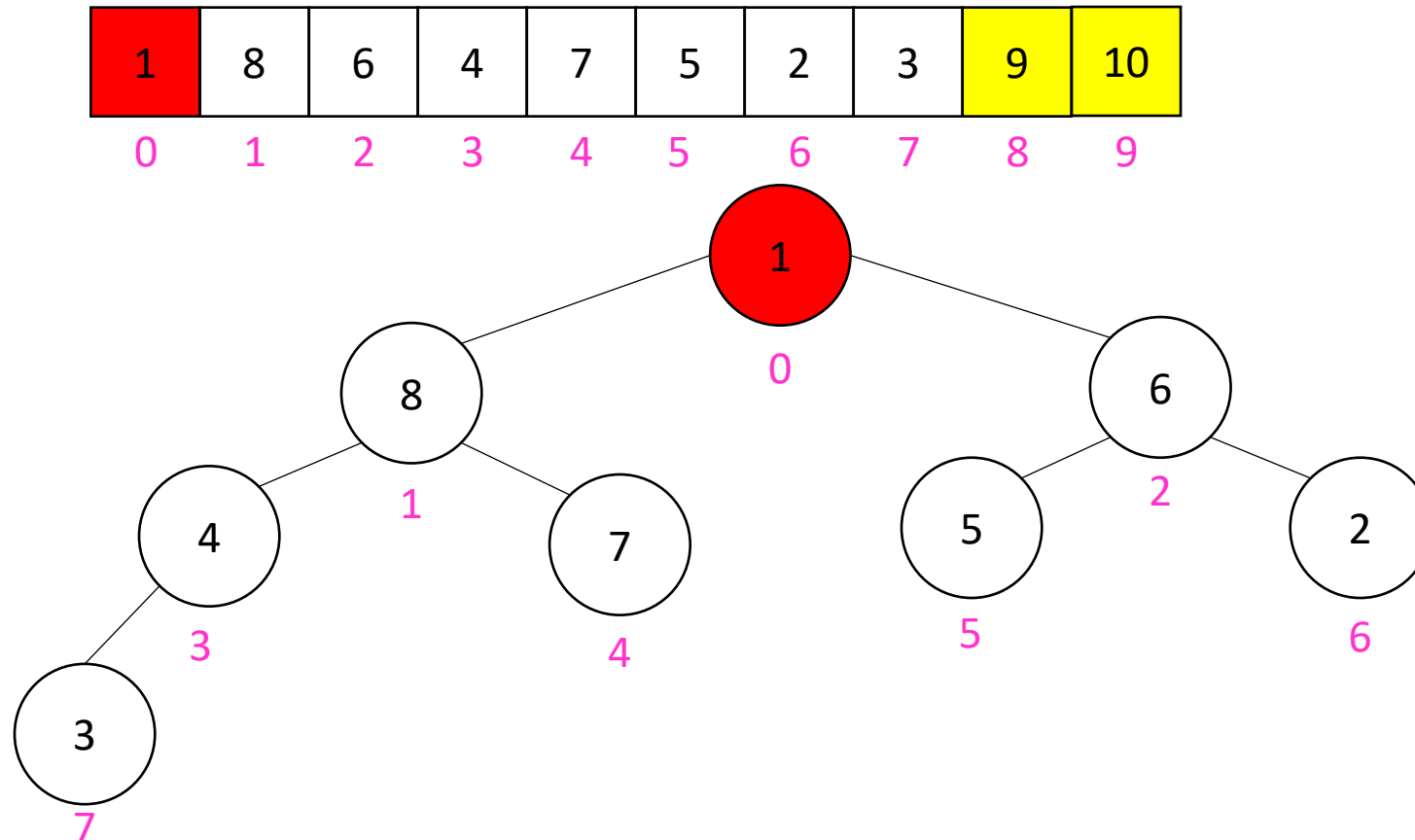
Heap Sort

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Heap Sort

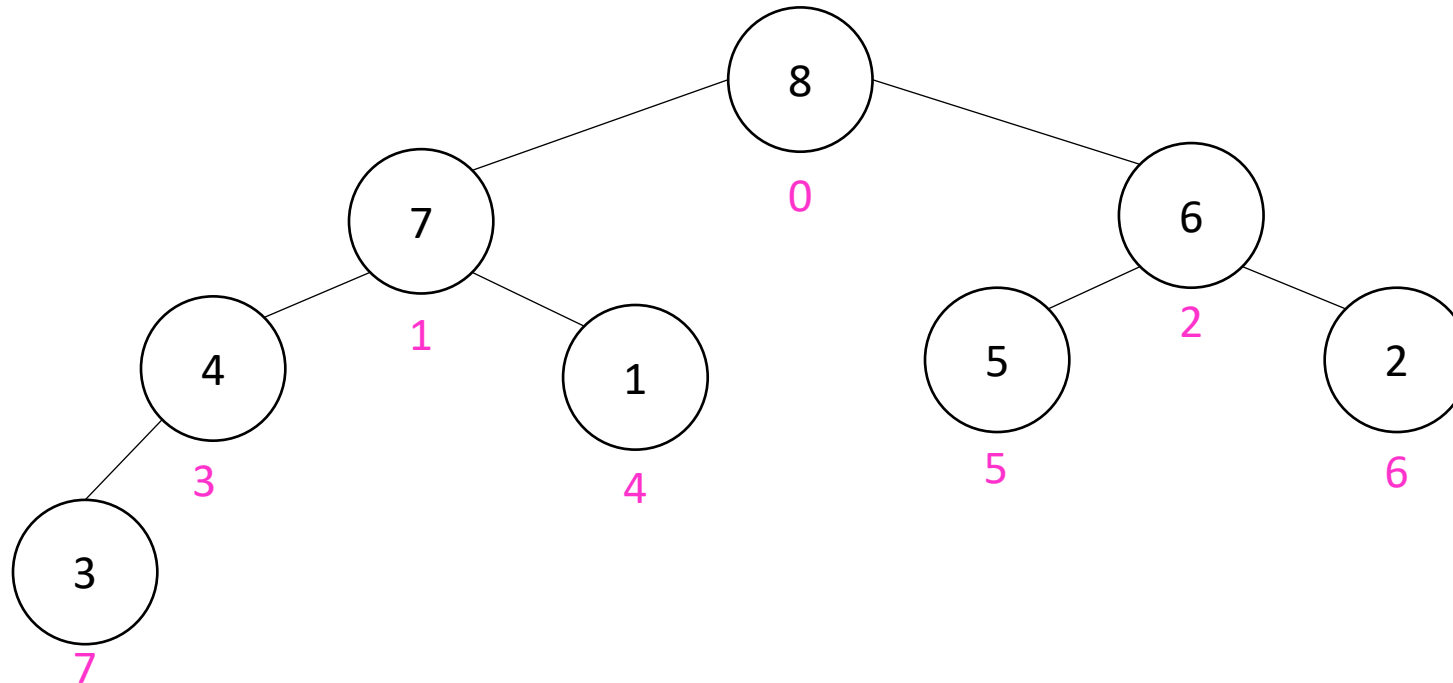
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Heap Sort

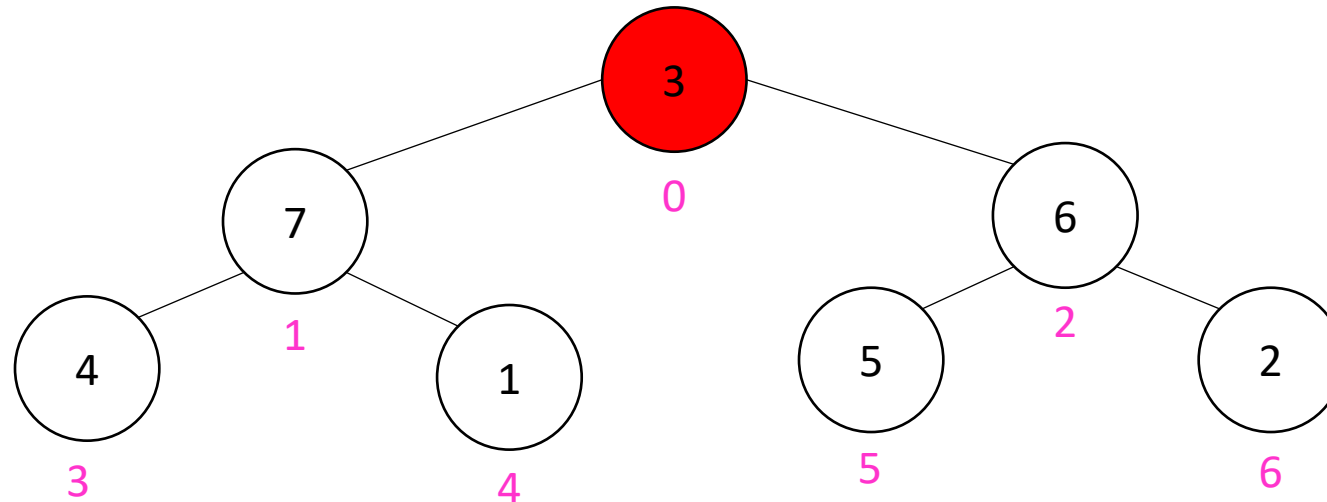
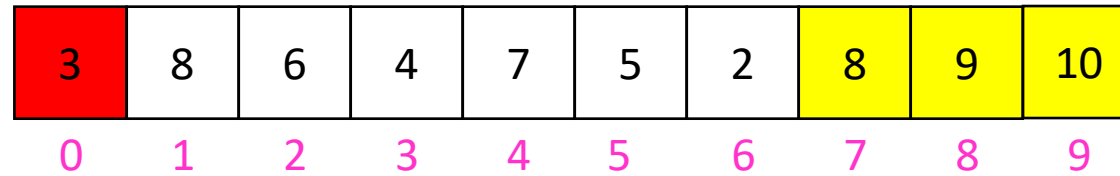
- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

1	8	6	4	7	5	2	3	9	10
0	1	2	3	4	5	6	7	8	9



Heap Sort

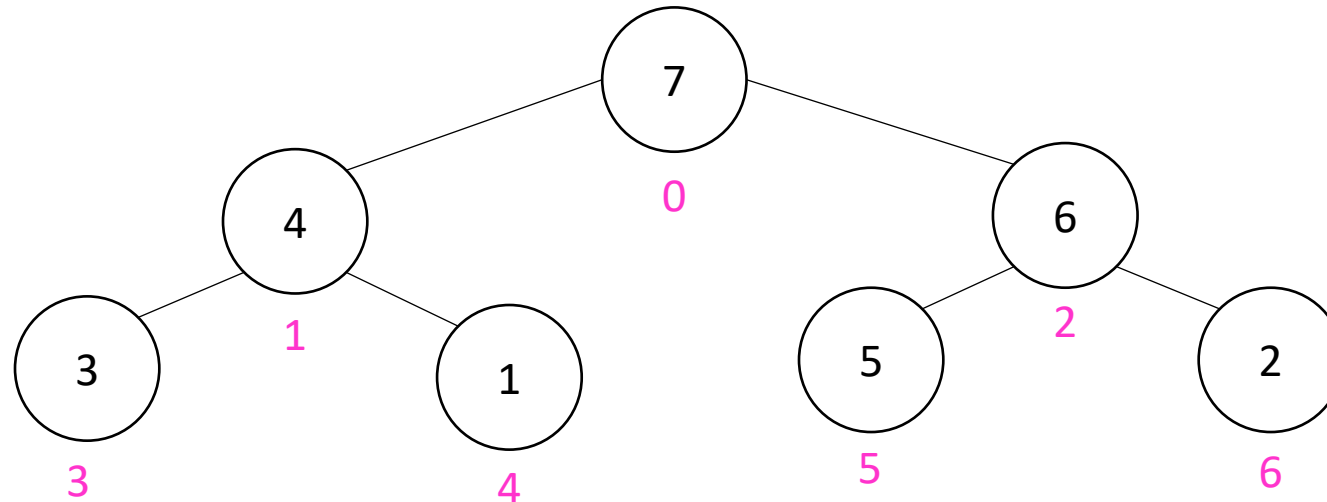
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Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

3	8	6	4	7	5	2	8	9	10
0	1	2	3	4	5	6	7	8	9



In Place Heap Sort

- Build a heap using the same array (Floyd's build heap algorithm works)
- Call deleteMax
- Put that at the end of the array

```
buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    temp=a[i]  
    a[i] = a[0];  
    a[0] = temp;  
    percolateDown(0);  
}
```

Running Time:

Worst Case: $\Theta(\cdot)$

Best Case: $\Theta(\cdot)$

Floyd's buildHeap method

- Working towards the root, one row at a time, percolate down

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```