

# CSE 332 Autumn 2023

## Lecture 16: Sorting

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<http://www.cs.uw.edu/332>

# Quicksort

- Like Mergesort:
  - Divide and conquer
  - $O(n \log n)$  run time (kind of...)
- Unlike Mergesort:
  - Divide step is the “hard” part
  - *Typically* faster than Mergesort

# Quicksort

Idea: pick a **pivot** element, recursively sort two sublists around that element

- **Divide:** select **pivot** element  $p$ , **Partition( $p$ )**
- **Conquer:** recursively sort left and right sublists
- **Combine:** Nothing!

# Partition (Divide step)

Given: a list, a pivot  $p$

Start: unordered list

8	5	7	3	12	10	1	2	4	9	6	11
---	---	---	---	----	----	---	---	---	---	---	----

Goal: All elements  $< p$  on left, all  $> p$  on right

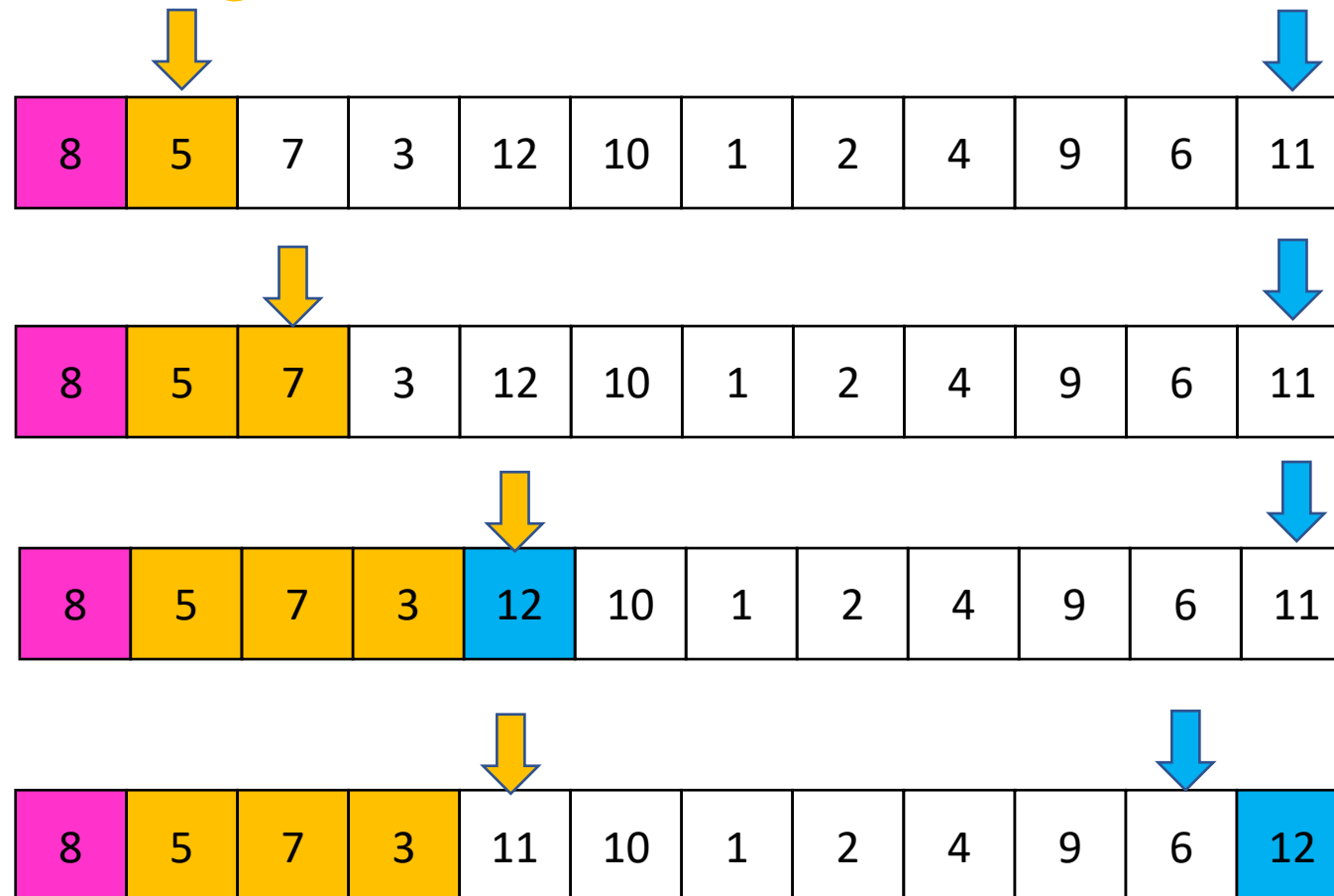
5	7	3	1	2	4	6	8	12	10	9	11
---	---	---	---	---	---	---	---	----	----	---	----

# Partition, Procedure

If **Begin** value  $< p$ , move **Begin** right

Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**

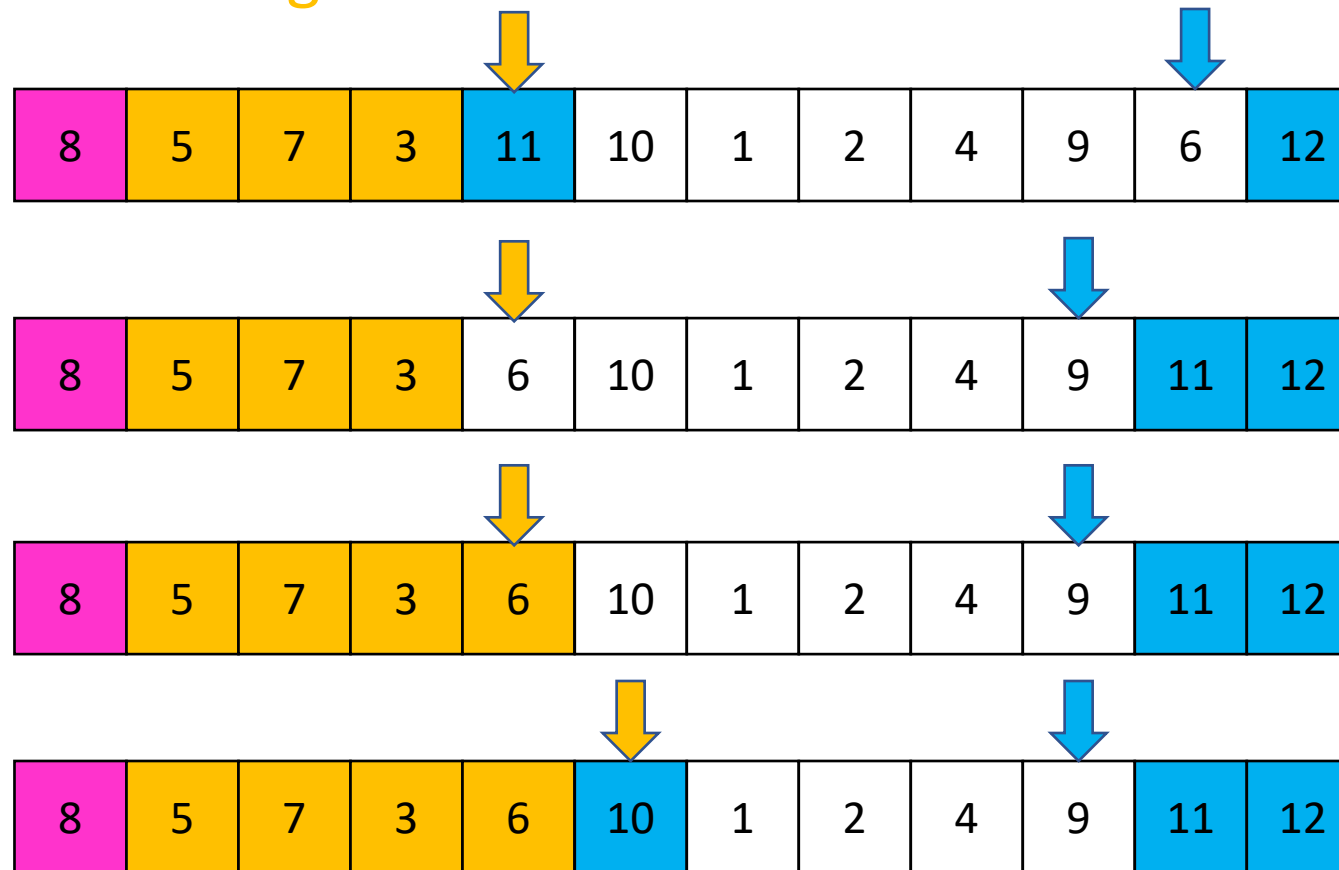


# Partition, Procedure

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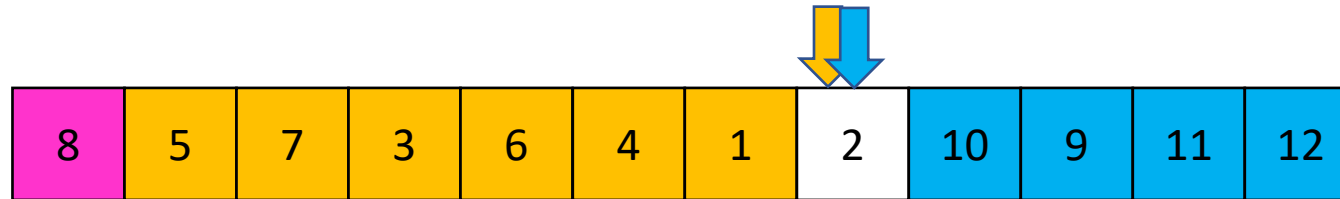


# Partition, Procedure

If **Begin** value  $< p$ , move **Begin** right

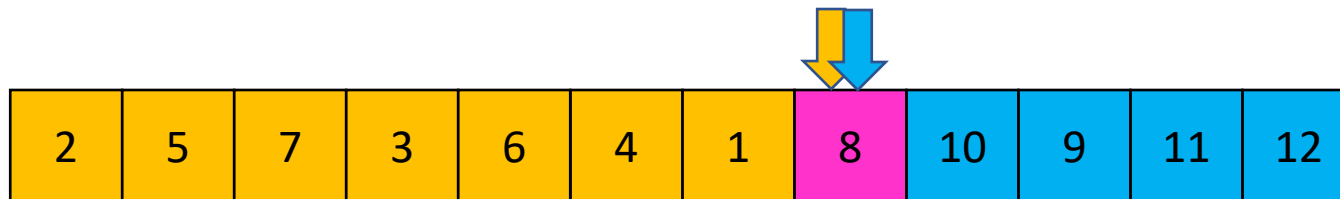
Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**



Case 1: meet at element  $< p$

Swap  $p$  with **pointer position** (2 in this case)

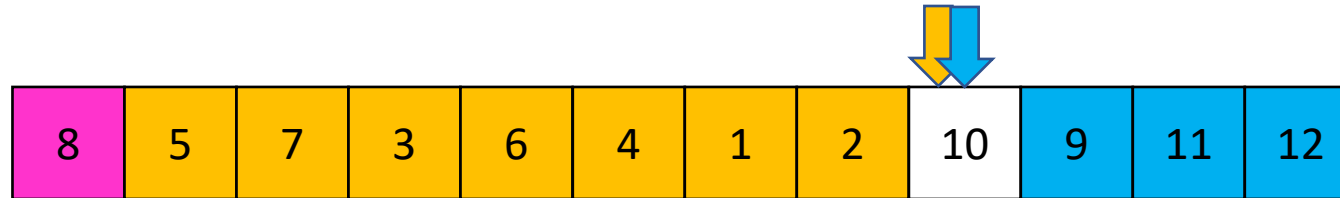


# Partition, Procedure

If **Begin** value  $< p$ , move **Begin** right

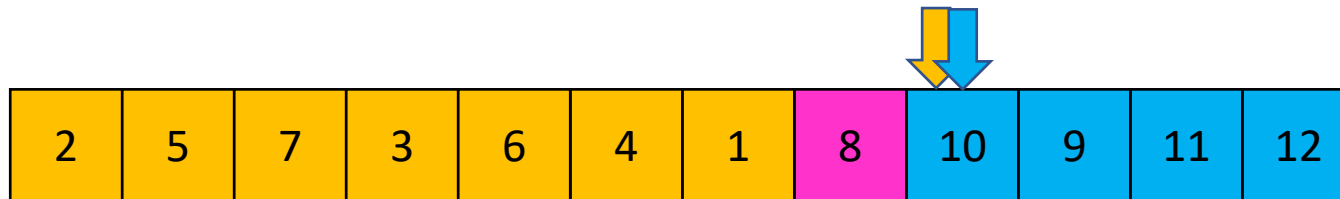
Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**



Case 2: meet at element  $> p$

Swap  $p$  with **value to the left** (2 in this case)



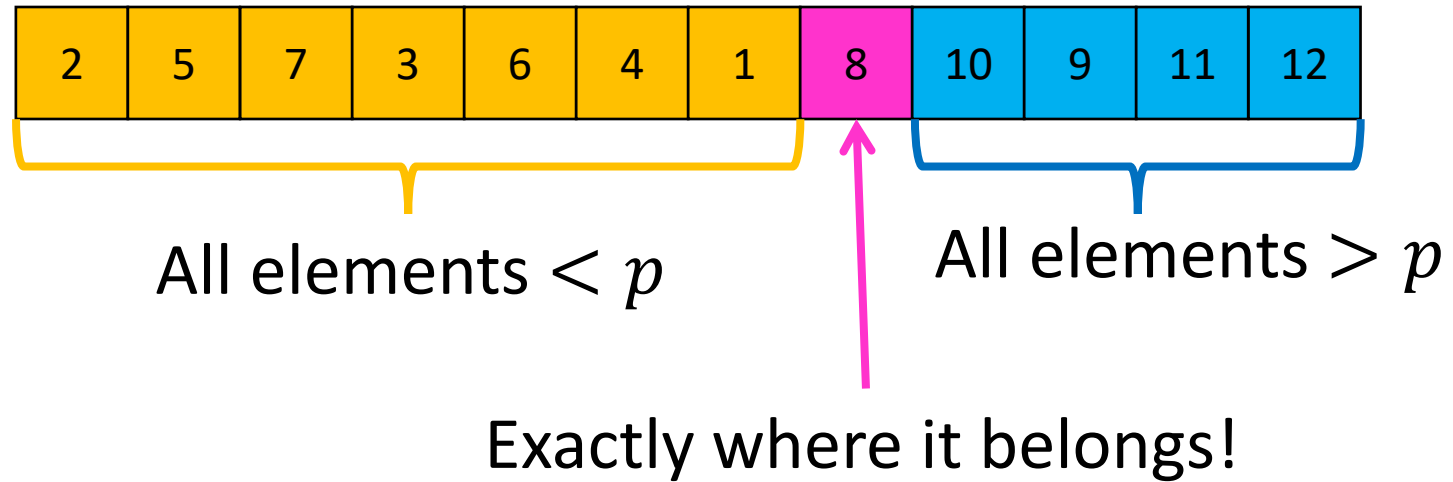


# Partition Summary

1. Put  $p$  at beginning of list
2. Put a pointer (**Begin**) just after  $p$ , and a pointer (**End**) at the end of the list
3. While **Begin** < **End**:
  1. If **Begin** value <  $p$ , move **Begin** right
  2. Else swap **Begin** value with **End** value, move **End** Left
4. If pointers meet at element <  $p$ : Swap  $p$  with **pointer position**
5. Else If pointers meet at element >  $p$ : Swap  $p$  with **value to the left**

Run time?  $O(n)$

# Conquer



Recursively sort **Left** and **Right** sublists

# Quicksort Run Time (Best)

If the **pivot** is always the median:



Then we divide in half each time

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

$$T(n) = O(n \log n)$$

# Quicksort Run Time (Worst)

If the pivot is always at the extreme:



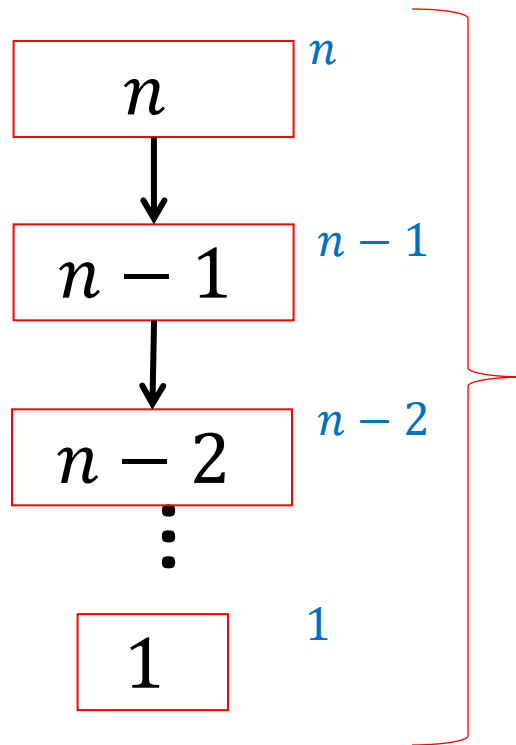
Then we shorten by 1 each time

$$T(n) = T(n - 1) + n$$

$$T(n) = O(n^2)$$

# Quicksort Run Time (Worst)

$$T(n) = T(n - 1) + n$$



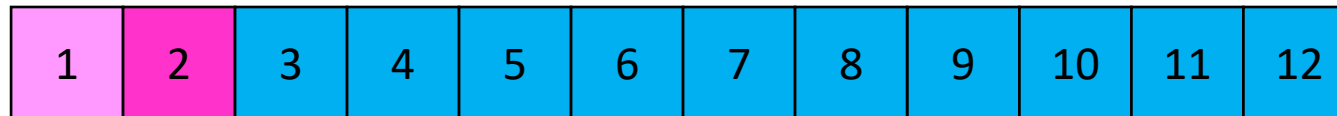
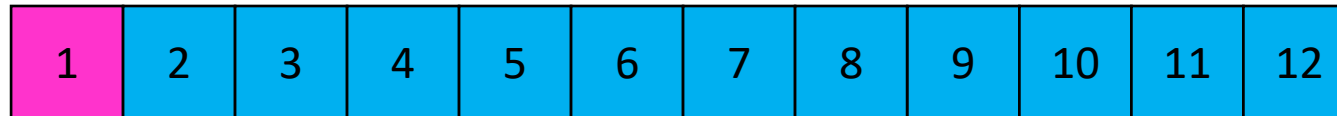
$$T(n) = 1 + 2 + 3 + \dots + n$$

$$T(n) = \frac{n(n + 1)}{2}$$

$$T(n) = O(n^2)$$

# Quicksort on a (nearly) Sorted List

First element always yields unbalanced pivot



So we shorten by 1 each time

$$T(n) = T(n - 1) + n$$

$$T(n) = O(n^2)$$

# Good Pivot

- What makes a good Pivot?
  - Roughly even split between left and right
  - Ideally: median
- There are ways to find the median in linear time, but it's complicated and slow and you're better off using mergesort
- In Practice:
  - Pick a random value as a pivot
  - Pick the middle of 3 random values as the pivot

# Properties of Quick Sort

- Worst Case Running time:
  - $\Theta(n^2)$
  - But  $\Theta(n \log n)$  average! And typically faster than mergesort!
- In-Place?
  - ....Debatable
- Adaptive?
  - No!
- Stable?
  - No!



# More Formal Definition

- Input:
  - An array  $A$  of items
  - A comparison function for these items
    - Given two items  $x$  and  $y$ , we can determine whether  $x < y$ ,  $x > y$ , or  $x = y$
- Output:
  - A permutation of  $A$  such that if  $i \leq j$  then  $A[i] \leq A[j]$
  - Permutation: a sequence of the same items but perhaps in a different order

# Improving Running time

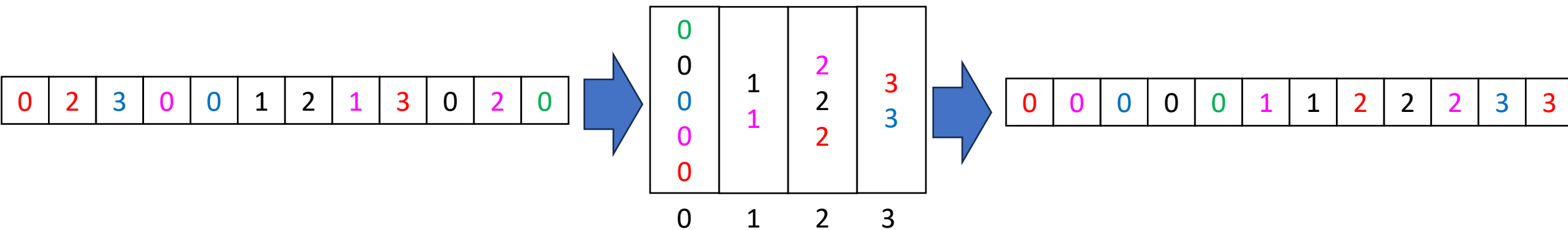
- Recall our definition of the sorting problem:
  - Input:
    - An array  $A$  of items
    - A comparison function for these items
      - Given two items  $x$  and  $y$ , we can determine whether  $x < y$ ,  $x > y$ , or  $x = y$
  - Output:
    - A permutation of  $A$  such that if  $i \leq j$  then  $A[i] \leq A[j]$
- Under this definition, it is impossible to write an algorithm faster than  $n \log n$  asymptotically.
- Observation:
  - Sometimes there might be ways to determine the position of values without comparisons!

# “Linear Time” Sorting Algorithms

- Useable when you are able to make additional assumptions about the contents of your list (beyond the ability to compare)
  - Examples:
    - The list contains only positive integers less than  $k$
    - The number of distinct values in the list is much smaller than the length of the list
- The running time expression will always have a term other than the list's length to account for this assumption
  - Examples:
    - Running time might be  $\Theta(k \cdot n)$  where  $k$  is the range/count of values

# BucketSort

- Assumes the array contains integers between 0 and  $k - 1$  (or some other small range)
- Idea:
  - Use each value as an index into an array of size  $k$
  - Add the item into the “bucket” at that index (e.g. linked list)
  - Get sorted array by “appending” all the buckets



# BucketSort Running Time

- Create array of  $k$  buckets
  - Either  $\Theta(k)$  or  $\Theta(1)$  depending on some things...
- Insert all  $n$  things into buckets
  - $\Theta(n)$
- Empty buckets into an array
  - $\Theta(n + k)$
- Overall:
  - $\Theta(n + k)$
- When is this better than mergesort?

# Properties of BucketSort

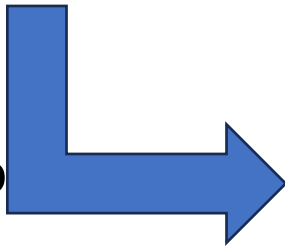
- In-Place?
  - No
- Adaptive?
  - No
- Stable?
  - Yes!

# RadixSort

- Radix: The base of a number system
  - We'll use base 10, most implementations will use larger bases
- Idea:
  - BucketSort by each digit, one at a time, from least significant to most significant

103	801	401	323	255	823	999	101	113	901	555	512	245	800	018	121
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

Place each element into  
a "bucket" according to  
its 1's place



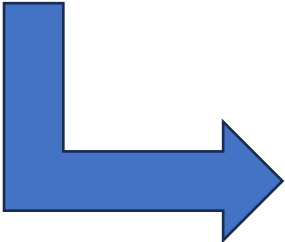
800	801 401 101 901 121	512	103 323 823 113		255 555 245			018	999
0	1	2	3	4	5	6	7	8	9

# RadixSort

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	801		103		255				
800	401	512	323		555			018	999
	101		823		245				
	901		113						
	121								
0	1	2	3	4	5	6	7	8	9

Place each element into a "bucket" according to its 10's place



800									
801	512	121							
401	113	323		245	255				999
101	018	823			555				
901									
103									
0	1	2	3	4	5	6	7	8	9

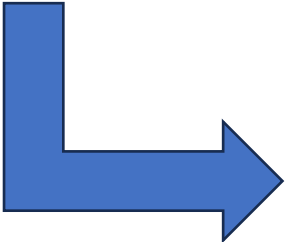


# RadixSort

- Radix: The base of a number system
  - We'll use base 10, most implementations will use larger bases
- Idea:
  - BucketSort by each digit, one at a time, from least significant to most significant

800									
801									
401	512	121			255				999
101	113	323		245	555				
901	018	823							
103									
0	1	2	3	4	5	6	7	8	9

Place each element into a "bucket" according to its 100's place

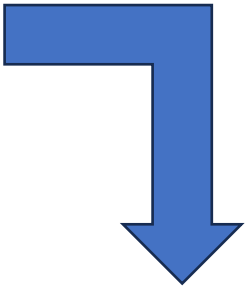


	101							800	901
	103							801	999
018	113	245	323	401	512			823	
	121	255			555				
0	1	2	3	4	5	6	7	8	9

# RadixSort

- Radix: The base of a number system
  - We'll use base 10, most implementations will use larger bases
- Idea:
  - BucketSort by each digit, one at a time, from least significant to most significant

018	101 103 113 121	245 255	323	401	512 555			800 801 823	901 999
0	1	2	3	4	5	6	7	8	9



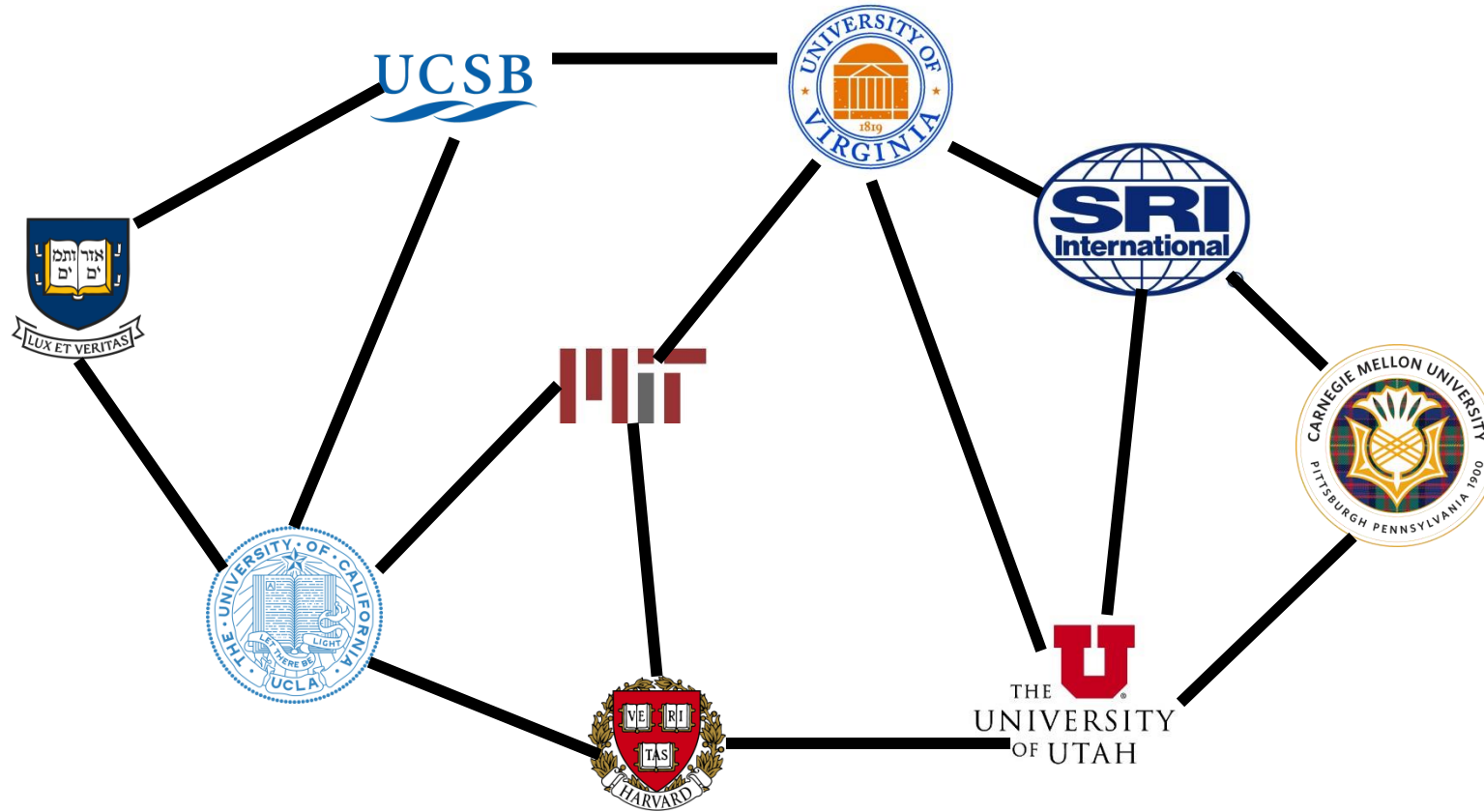
Convert back into an array

018	811	103	113	121	245	255	323	401	512	555	800	801	823	901	999
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

# RadixSort Running Time

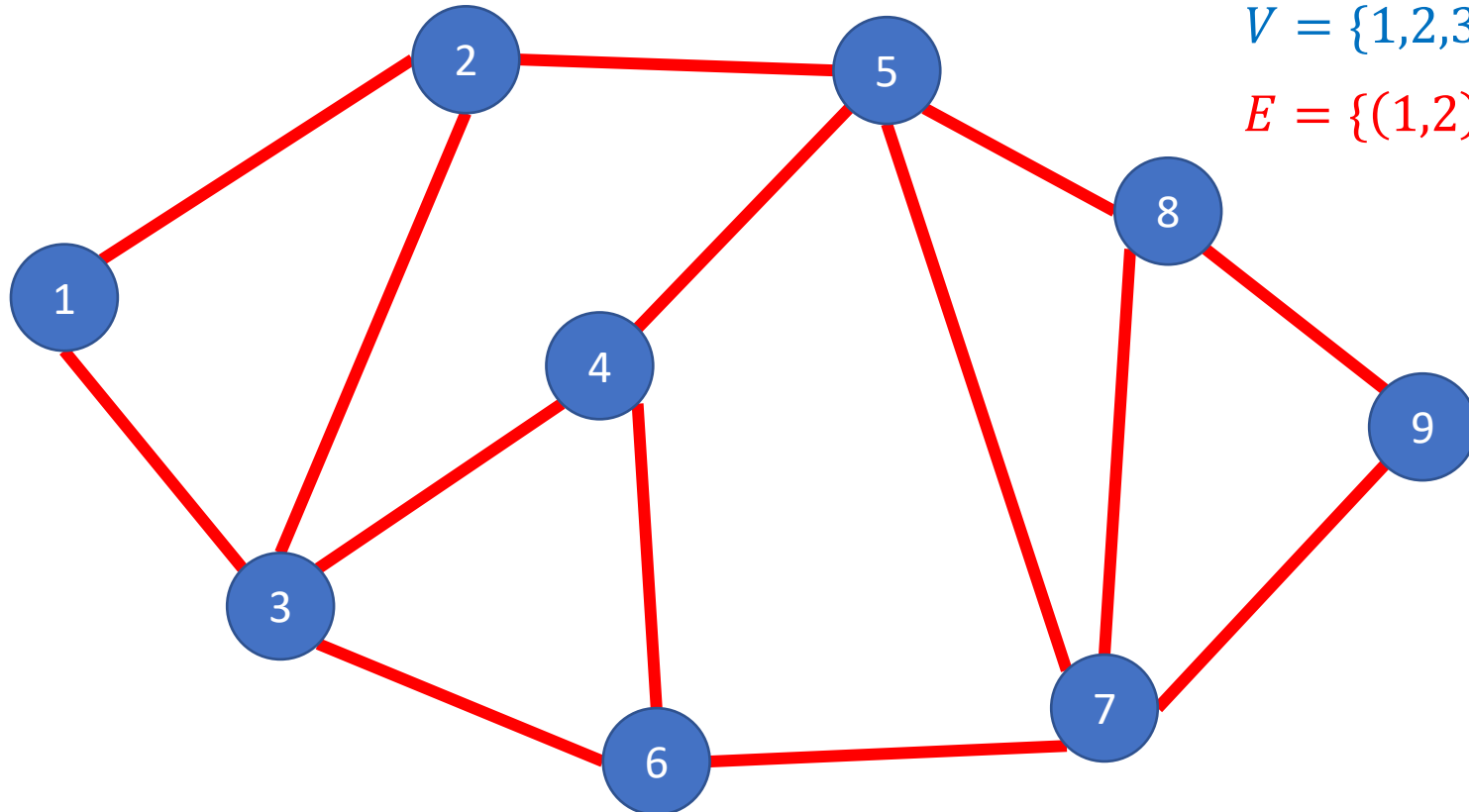
- Suppose largest value is  $m$
- Choose a radix (base of representation)  $b$
- BucketSort all  $n$  things using  $b$  buckets
  - $\Theta(n + k)$
- Repeat once per each digit
  - $\log_b m$  iterations
- Overall:
  - $\Theta(n \log_b m + b \log_b m)$
- In practice, you can select the value of  $b$  to optimize running time
- When is this better than mergesort?

# ARPANET



# Undirected Graphs

Definition:  $G = (V, E)$   
Vertices/Nodes  
Edges

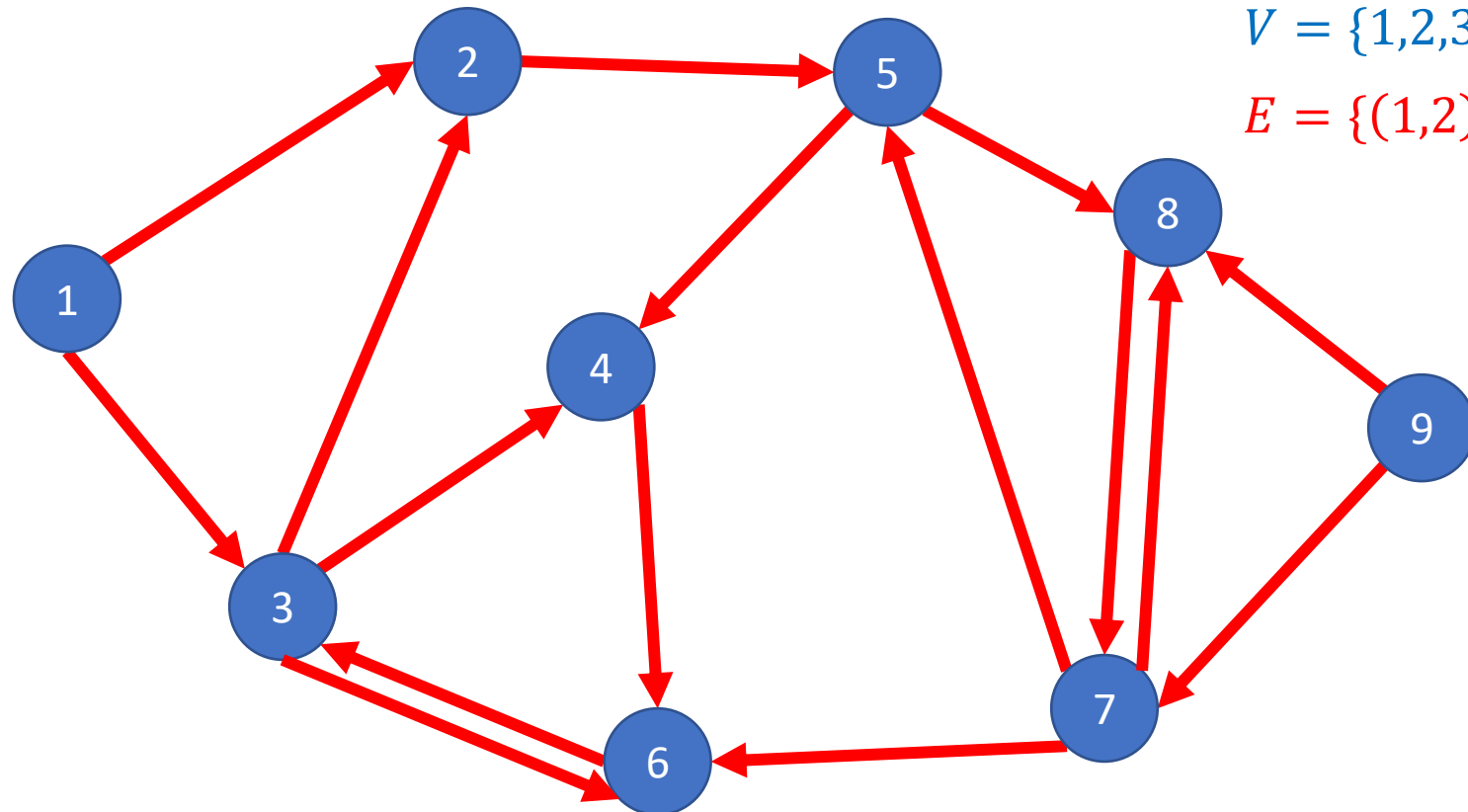


$V = \{1,2,3,4,5,6,7,8,9\}$

$E = \{(1,2), (2,3), (1,3), \dots\}$

# Directed Graphs

Definition:  $G = (V, E)$   
Vertices/Nodes  
Edges

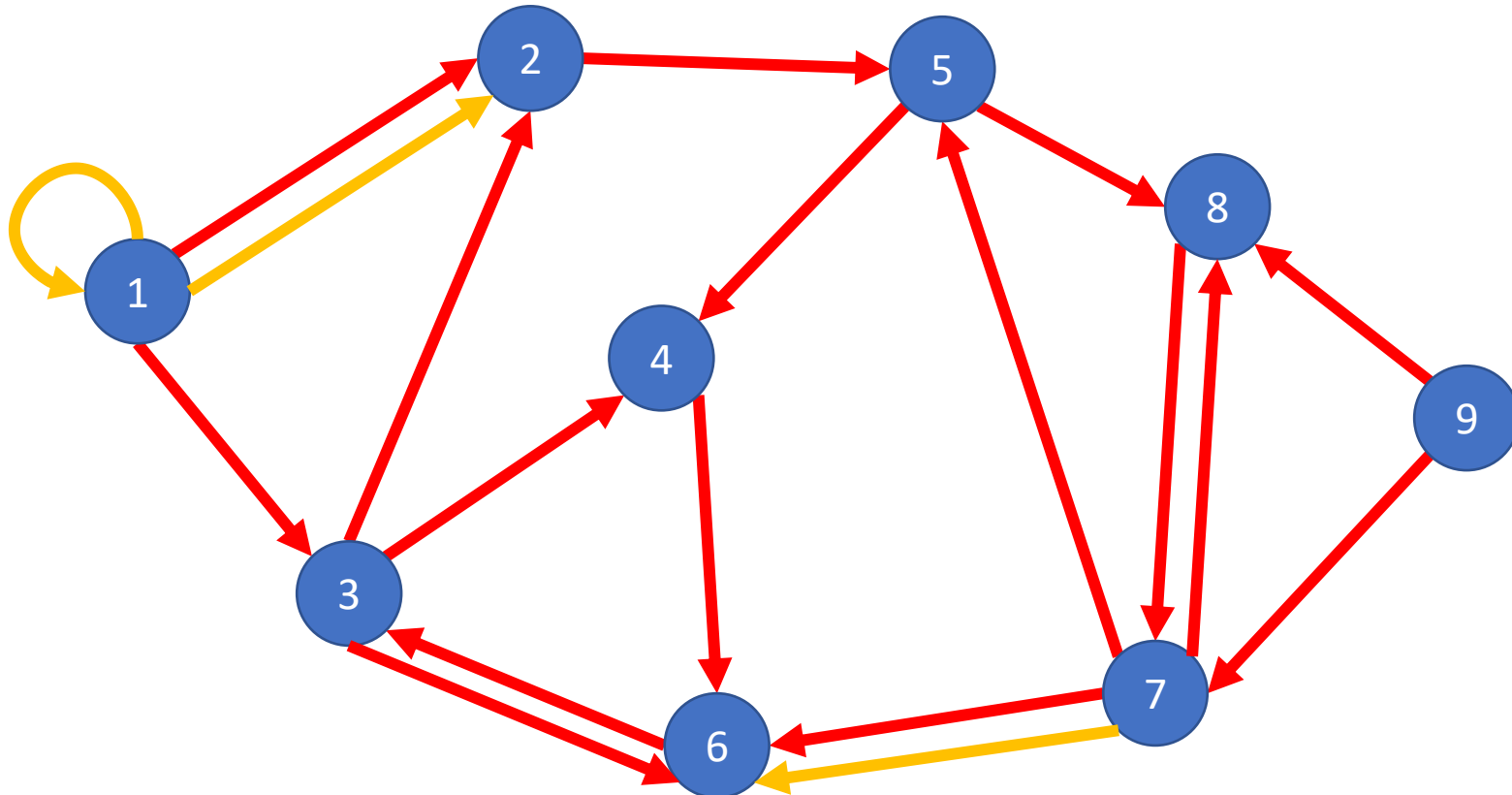


$V = \{1,2,3,4,5,6,7,8,9\}$

$E = \{(1,2), (2,3), (1,3), \dots\}$

# Self-Edges and Duplicate Edges

Some graphs may have duplicate edges (e.g. here we have the edge (1,2) twice).  
Some may also have self-edges (e.g. here there is an edge from 1 to 1).  
Graph with Neither self-edges nor duplicate edges are called **simple graphs**



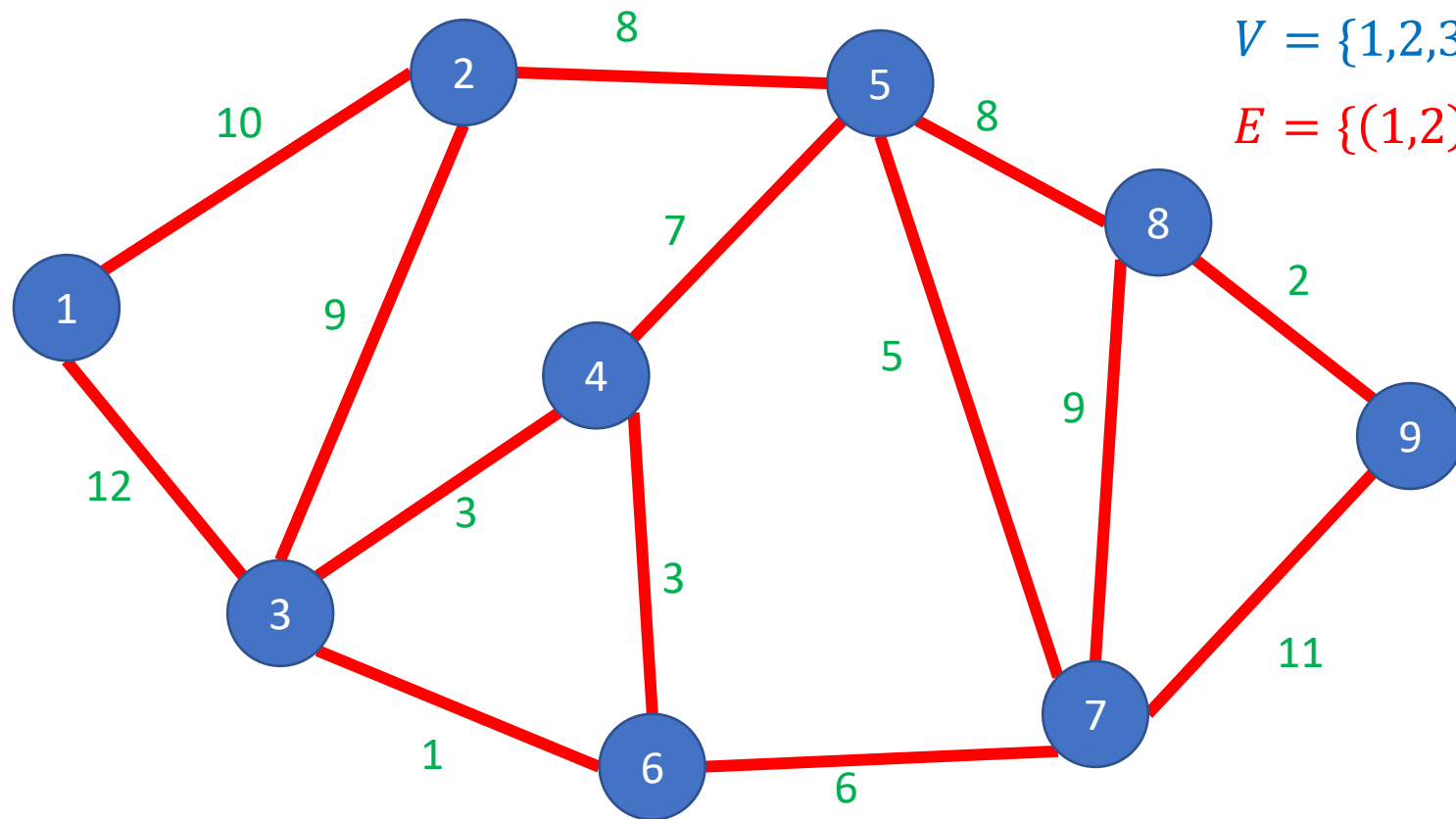
# Weighted Graphs

Vertices/Nodes

Definition:  $G = (V, E)$

Edges

$w(e)$  = weight of edge  $e$



$V = \{1,2,3,4,5,6,7,8,9\}$

$E = \{(1,2), (2,3), (1,3), \dots\}$

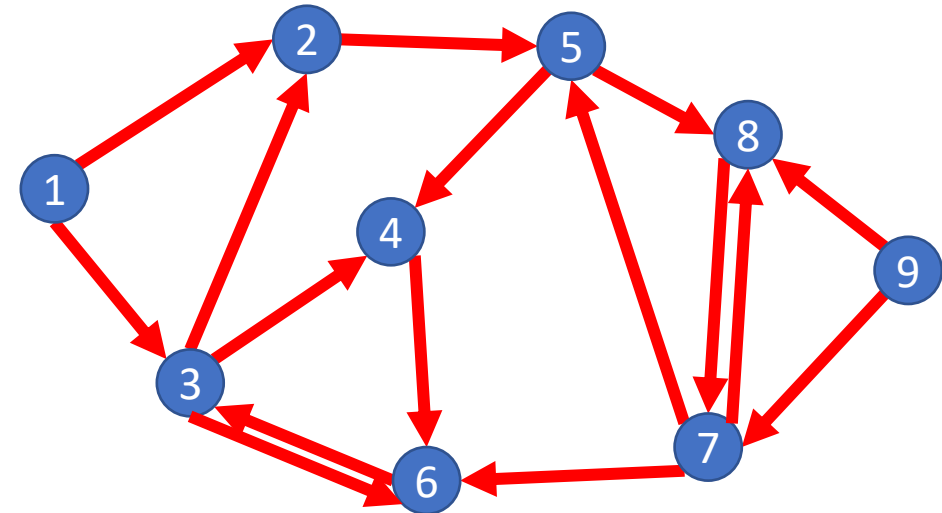
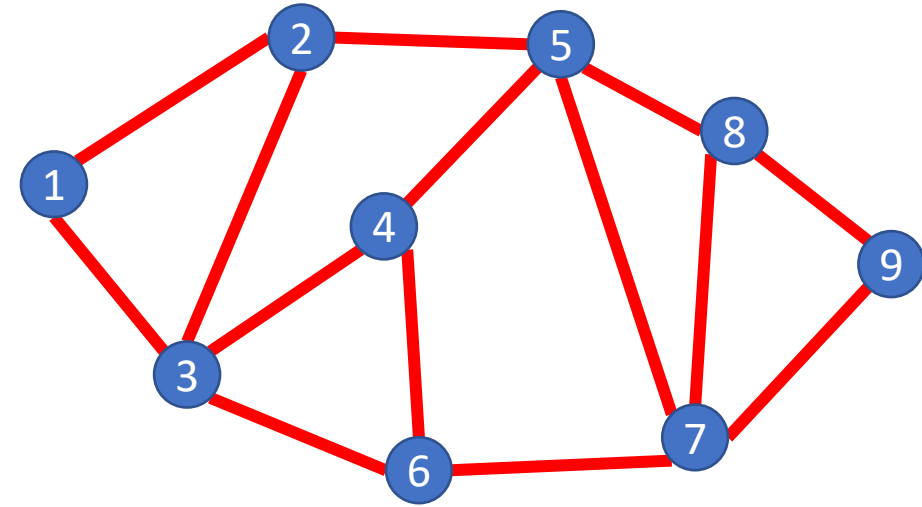


# Graph Applications

- For each application below, consider:
  - What are the nodes, what are the edges?
  - Is the graph directed?
  - Is the graph simple?
  - Is the graph weighted?
- Facebook friends
- Twitter followers
- Java inheritance
- Airline Routes

# Some Graph Terms

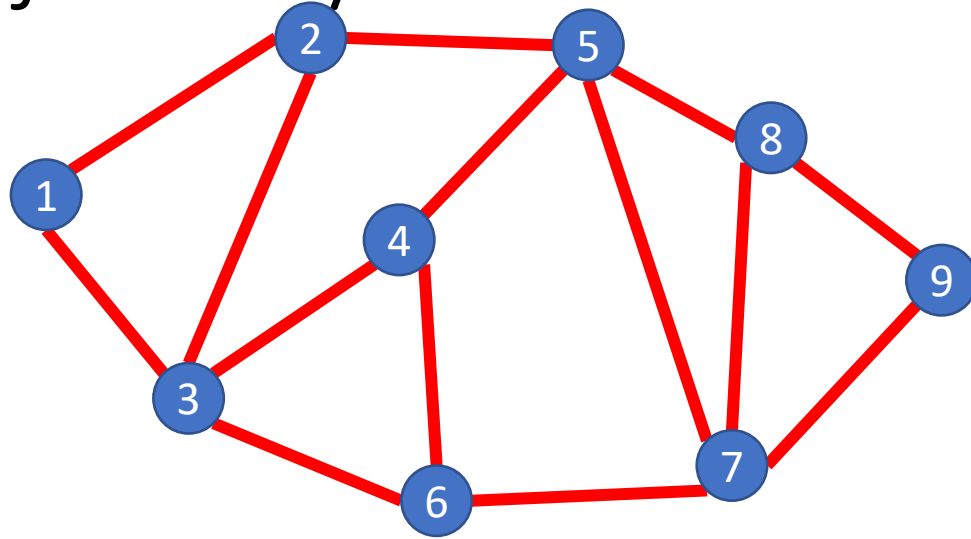
- **Adjacent/Neighbors**
  - Nodes are adjacent/neighbors if they share an edge
- **Degree**
  - Number of “neighbors” of a vertex
- **Indegree**
  - Number of incoming neighbors
- **Outdegree**
  - Number of outgoing neighbors



# Graph Operations

- To represent a Graph (i.e. build a data structure) we need:
  - Add Edge
  - Remove Edge
  - Check if Edge Exists
  - Get Neighbors (incoming)
  - Get Neighbors (outgoing)

# Adjacency List



## Time/Space Tradeoffs

Space to represent:  $\Theta(n + m)$

Add Edge:  $\Theta(1)$

Remove Edge:  $\Theta(1)$

Check if Edge Exists:  $\Theta(n)$

Get Neighbors (incoming):  $\Theta(n + m)$

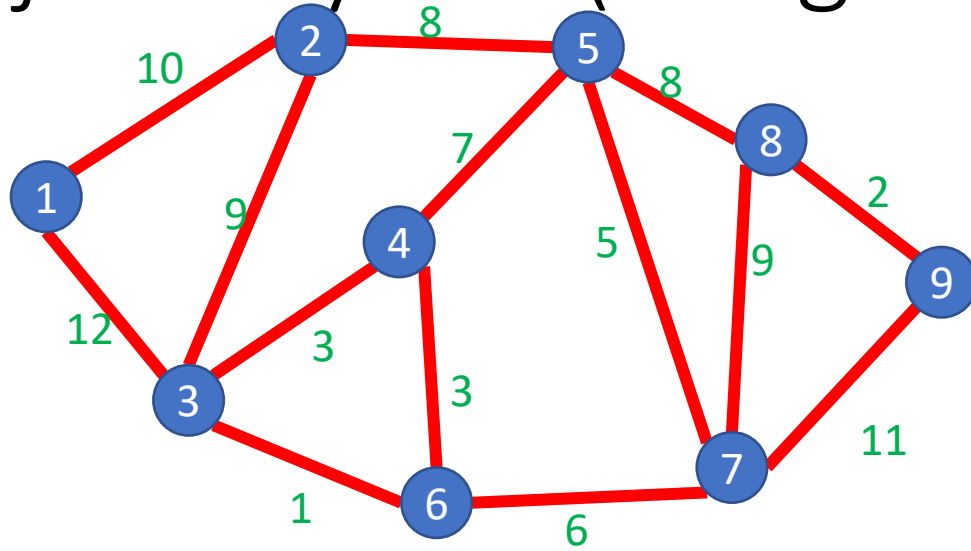
Get Neighbors (outgoing):  $\Theta(\deg(v))$

$$|V| = n$$

$$|E| = m$$

1	2	3		
2	1	3	5	
3	1	2	4	6
4	3	5	6	
5	2	4	7	8
6	3	4	7	
7	5	6	8	9
8	5	7	9	
9	7	8		

# Adjacency List (Weighted)



## Time/Space Tradeoffs

Space to represent:  $\Theta(n + m)$

Add Edge:  $\Theta(1)$

Remove Edge:  $\Theta(1)$

Check if Edge Exists:  $\Theta(n)$

Get Neighbors (incoming):  $\Theta(?)$

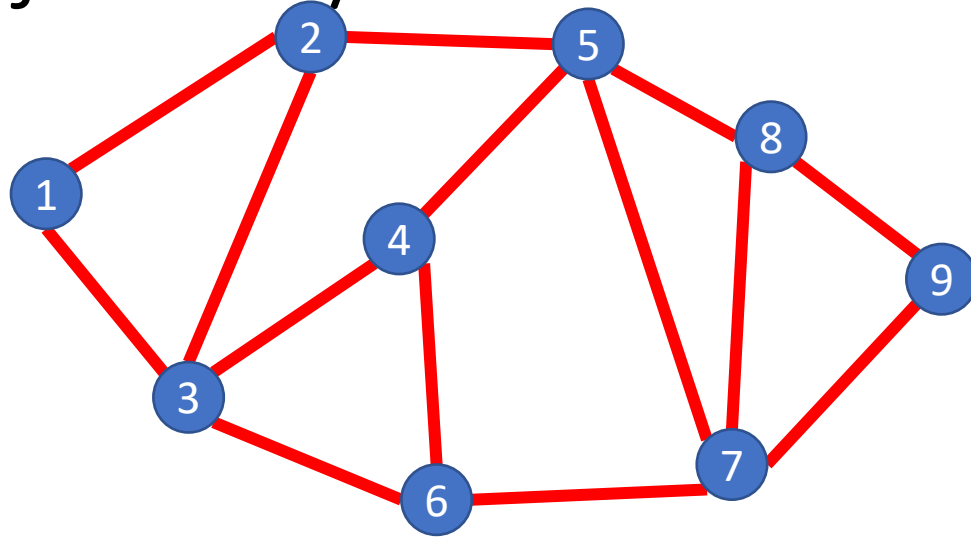
Get Neighbors (outgoing):  $\Theta(?)$

$$|V| = n$$

$$|E| = m$$

1	2	3		
2	1	3	5	
3	1	2	4	6
4	3	5	6	
5	2	4	7	8
6	3	4	7	
7	5	6	8	9
8	5	7	9	
9	7	8		

# Adjacency Matrix



## Time/Space Tradeoffs

Space to represent:  $\Theta(?)$

Add Edge:  $\Theta(?)$

Remove Edge:  $\Theta(?)$

Check if Edge Exists:  $\Theta(?)$

Get Neighbors (incoming):  $\Theta(?)$

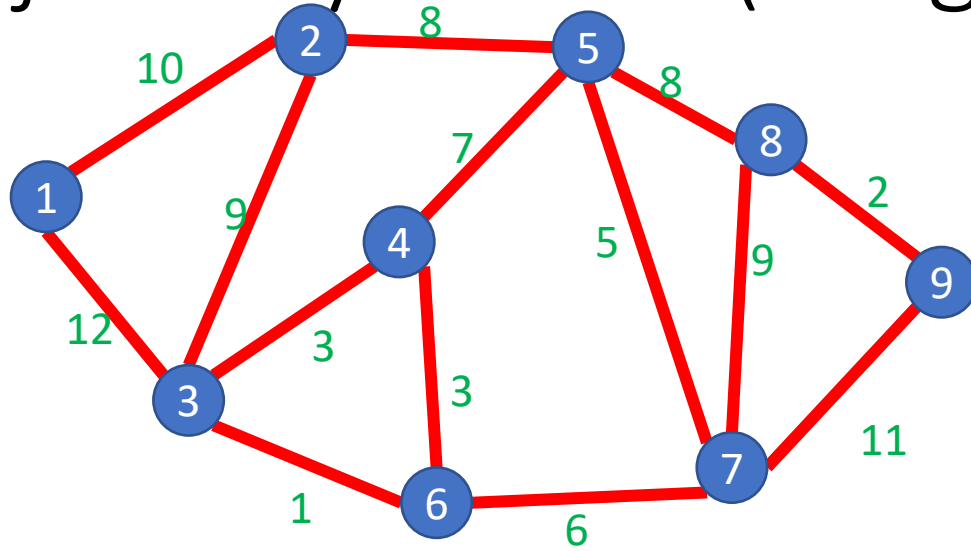
Get Neighbors (outgoing):  $\Theta(?)$

$$|V| = n$$

$$|E| = m$$

	A	B	C	D	E	F	G	H	I
A		1	1						
B	1		1		1				
C	1	1		1		1			
D			1		1	1			
E		1		1			1	1	
F			1	1			1		
G					1	1		1	1
H					1		1		1
I							1	1	

# Adjacency Matrix (weighted)



## Time/Space Tradeoffs

Space to represent:  $\Theta(n^2)$

Add Edge:  $\Theta(1)$

Remove Edge:  $\Theta(1)$

Check if Edge Exists:  $\Theta(1)$

Get Neighbors (incoming):  $\Theta(n)$

Get Neighbors (outgoing):  $\Theta(n)$

$$|V| = n$$

$$|E| = m$$

	A	B	C	D	E	F	G	H	I
A		1	1						
B	1		1		1				
C	1	1		1		1			
D			1		1	1			
E		1		1			1	1	
F			1	1			1		
G					1	1		1	1
H					1		1		1
I							1	1	

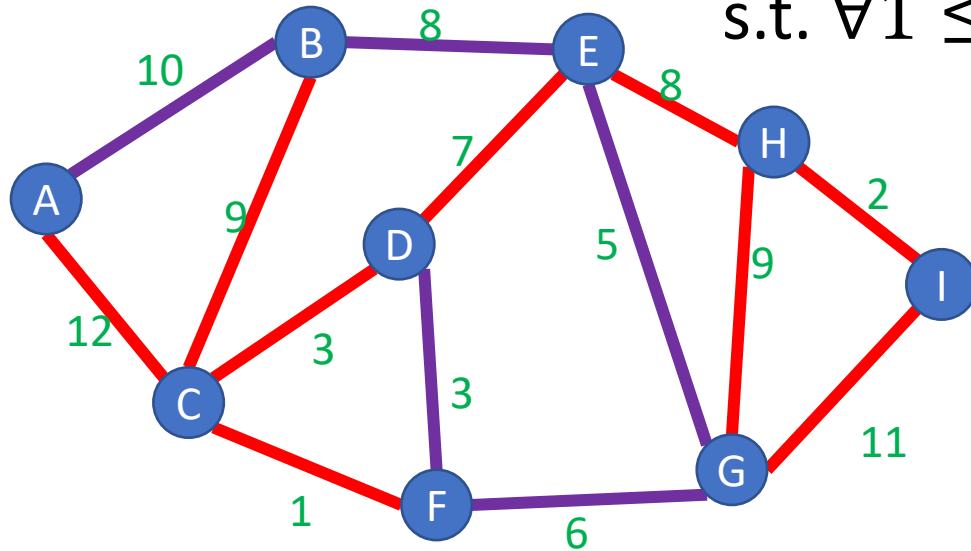
# Aside

- Almost always, adjacency lists are the better choice
- Most graphs are missing most of their edges, so the adjacency list is much more space efficient and the slower operations aren't that bad



# Definition: Path

A sequence of nodes  $(v_1, v_2, \dots, v_k)$   
s.t.  $\forall 1 \leq i \leq k - 1, (v_i, v_{i+1}) \in E$



## Simple Path:

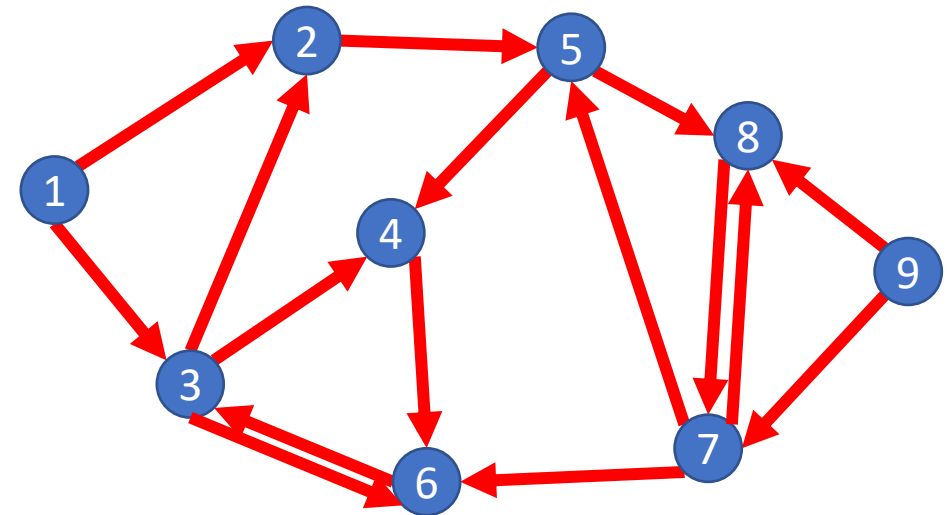
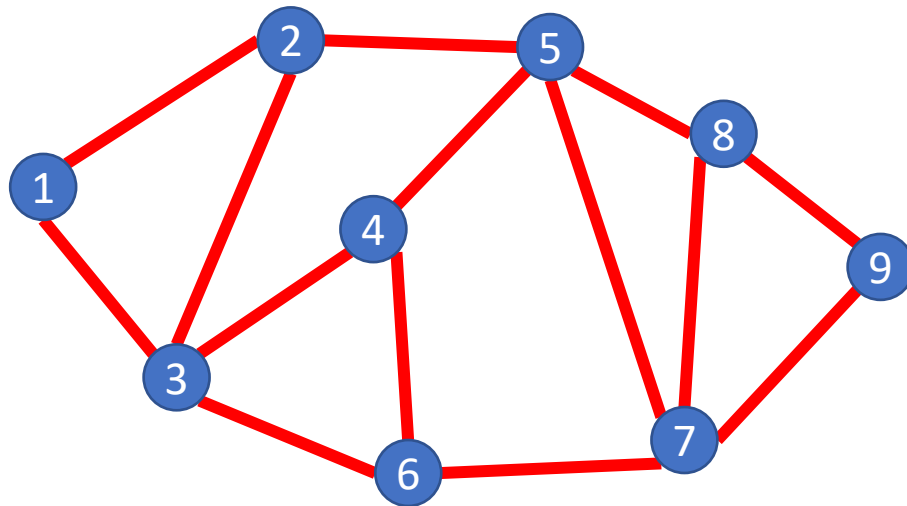
A path in which each node appears at most once

## Cycle:

A path which starts and ends in the same place

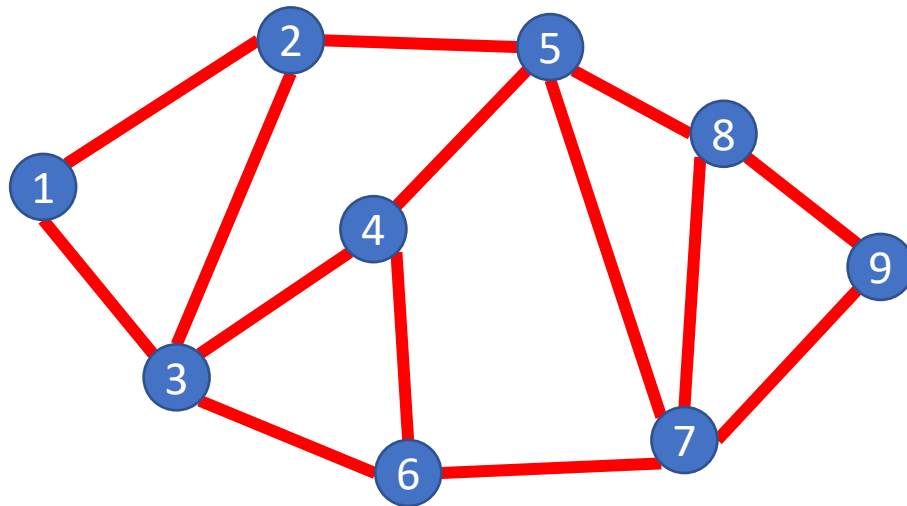
# Definition: (Strongly) Connected Graph

A Graph  $G = (V, E)$  s.t. for any pair of nodes  $v_1, v_2 \in V$  there is a path from  $v_1$  to  $v_2$

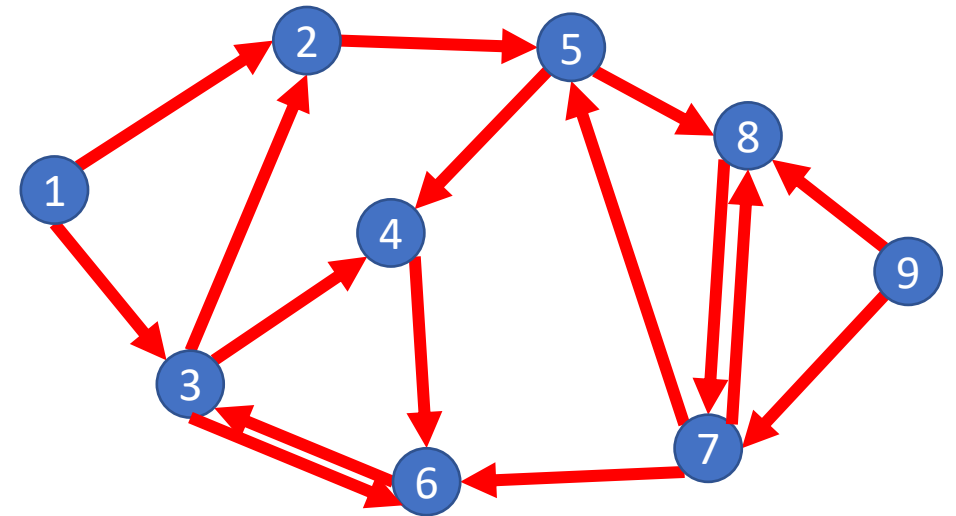


# Definition: (Strongly) Connected Graph

A Graph  $G = (V, E)$  s.t. for any pair of nodes  $v_1, v_2 \in V$  there is a path from  $v_1$  to  $v_2$



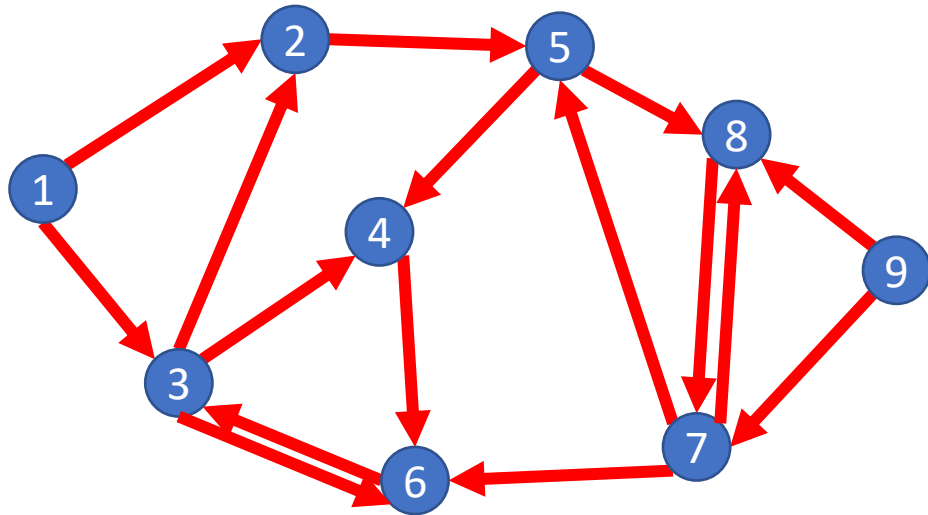
Connected



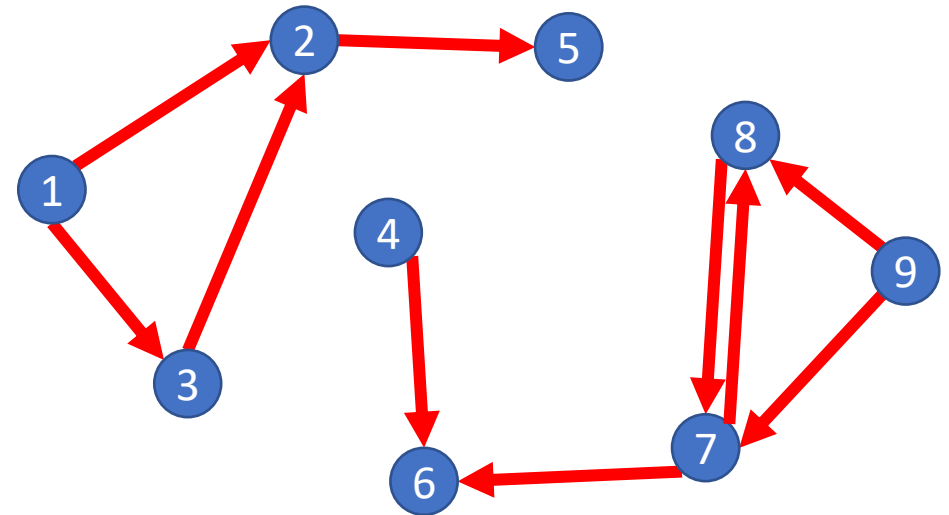
Not (strongly) Connected

# Definition: Weakly Connected Graph

A Graph  $G = (V, E)$  s.t. for any pair of nodes  $v_1, v_2 \in V$  there is a path from  $v_1$  to  $v_2$  ignoring direction of edges



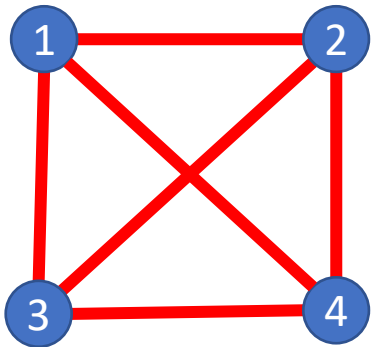
Weakly Connected



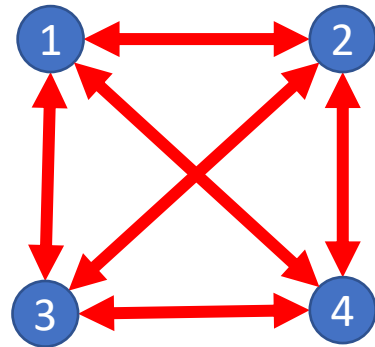
Weakly Connected

# Definition: Complete Graph

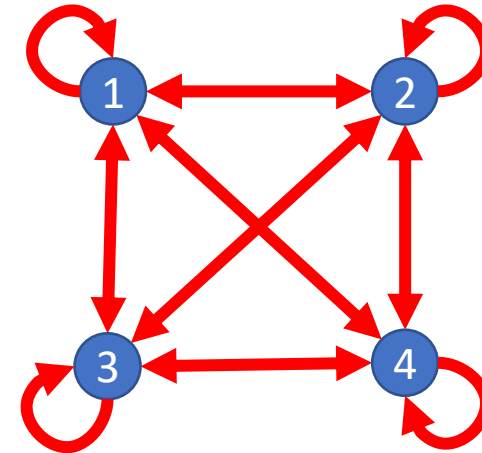
A Graph  $G = (V, E)$  s.t. for any pair of nodes  $v_1, v_2 \in V$  there is an edge from  $v_1$  to  $v_2$



Complete  
Undirected Graph



Complete  
Directed Graph



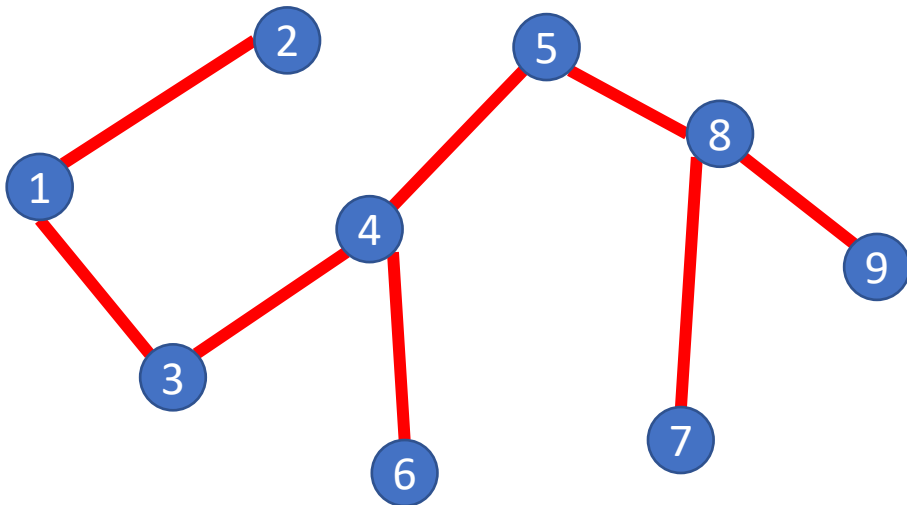
Complete Directed  
Non-simple Graph

# Graph Density, Data Structures, Efficiency

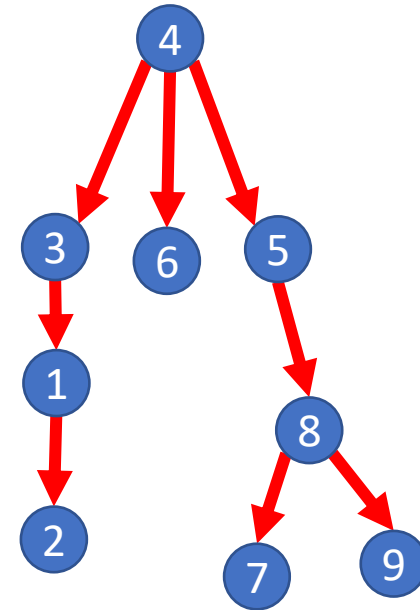
- The maximum number of edges in a graph is  $\Theta(|V|^2)$ :
  - Undirected and simple:  $\frac{|V|(|V|-1)}{2}$
  - Directed and simple:  $|V|(|V| - 1)$
  - Direct and non-simple (but no duplicates):  $|V|^2$
- If the graph is connected, the minimum number of edges is  $|V| - 1$
- If  $|E| \in \Theta(|V|^2)$  we say the graph is **dense**
- If  $|E| \in \Theta(|V|)$  we say the graph is **sparse**
- Because  $|E|$  is not always near to  $|V|^2$  we do not typically substitute  $|V|^2$  for  $|E|$  in running times, but leave it as a separate variable

# Definition: Tree

A Graph  $G = (V, E)$  is a tree if it is undirect, connected, and has no cycles (i.e. is acyclic). Often one node is identified as the “root”



A Tree



A Rooted Tree