



CSE 332: Data Abstractions Lecture 4: Priority Queues

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#### **Announcements**

- Project 1 phase A due Wed Jan 16th, 11pm via catalyst
- Homework 1 due Friday Jan 18<sup>th</sup> at <u>beginning</u> of class
- Links to materials from section useful for project 1
- · Info sheets?

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## Today

- Finish up Asymptotic Analysis
- New ADT! Priority Queues

#### Scenario

What is the difference between waiting for service at a pharmacy versus an ER?

Pharmacies usually follow the rule First Come, First Served

Emergency Rooms assign priorities based on each individual's need

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## Scenario

What is the difference between waiting for service at a pharmacy versus an ER?

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Queue

Emergency Rooms assign priorities based on each individual's need

**Priority Queue** 

## A new ADT: Priority Queue

- Textbook Chapter 6
  - We will go back to binary search trees (ch4) and hash tables (ch5) later
  - Nice to see a new and surprising data structure first
- A priority queue holds compare-able data
  - Unlike stacks and queues need to compare items
    - Given x and y, is x less than, equal to, or greater than y
    - What this means can depend on your data
  - Much of course will require comparable data: e.g. sorting
     Integers are comparable, so will use them in examples
    - ntegers are comparable, so will use them in examples
    - But the priority queue ADT is much more genera
    - Typically two fields, the *priority* and the *data*

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## Priority Queue ADT

- · Assume each item has a "priority"
  - The *lesser* item is the one with the *greater* priority
  - So "priority 1" is more important than "priority 4"
  - Just a convention, could also do a maximum priority

• Main Operations:
- insert
- deleteMin

- Key property: deleteMin returns and deletes from the queue the item with greatest priority (lowest priority value)
  - Can resolve ties arbitrarily

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## Aside: We will use ints as data and priority

For simplicity in lecture, we'll often suppose items are just ints and the int is also the priority

So an operation sequence could be

```
insert 6
insert 5
x = deleteMin // Now x = 5.
```

- int priorities are common, but really just need comparable
- Not having "other data" is very rare
  - Example: print job has a priority and the file to print is the data

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# Priority Queue Example

To simplify our examples, we will just use the priority values from now on

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```
insert a with priority 5
insert b with priority 3
insert c with priority 4
w = deleteMin
x = deleteMin
insert d with priority 2
insert e with priority 6
y = deleteMin
z = deleteMin
```

Analogy: insert is like enqueue, deleteMin is like dequeue But the whole point is to use priorities instead of FIFO

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# Priority Queue Example

To simplify our examples, we will just use the priority values from now on

```
insert a with priority 5
insert b with priority 3
insert c with priority 4
w = b
w = deleteMin
x = c
x = deleteMin
insert d with priority 2
insert e with priority 6
y = deleteMin
z = deleteMin
```

Analogy: insert is like enqueue, deleteMin is like dequeue But the whole point is to use priorities instead of FIFO

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# **Applications**

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Like all good ADTs, the priority queue arises often

- Sometimes "directly", sometimes less obvious
- Run multiple programs in the operating system
  - "critical" before "interactive" before "compute-intensive"
  - Maybe let users set priority level
- Treat hospital patients in order of severity (or triage)
- Select print jobs in order of decreasing length?
- Forward network packets in order of urgency
- Select most frequent symbols for data compression (cf. CSE143)
- Sort: insert all, then repeatedly deleteMin
  - Much like Project 1 uses a stack to implement reverse

More applications

- "Greedy" algorithms
  - Select the 'best-looking' choice at the moment
  - Will see an example when we study graphs in a few weeks
- Discrete event simulation (system modeling, virtual worlds, ...)
  - Simulate how state changes when events fire
  - Each event e happens at some time t and generates new events e1, ..., en at times t+t1, ..., t+tn
  - Naïve approach: advance "clock" by 1 unit at a time and process any events that happen then
  - Better:
    - Pending events in a priority queue (priority = time happens)
    - Repeatedly: deleteMin and then insert new events
    - Effectively, "set clock ahead to next event"

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### Preliminary Implementations of Priority Queue ADT

	insert	deleteMin
Unsorted Array		
Unsorted Linked-List		
Sorted Circular Array		
Sorted Linked-List		
Binary Search Tree (BST)		

 $_{1/14/2013}$   $\,$  Notes: Worst case, Assume arrays have enough space  $_{13}$ 

# Need a good data structure!

- · Next we will show an efficient, non-obvious data structure for this ADT
  - But first let's analyze some "obvious" ideas for *n* data items
  - All times worst-case; assume arrays "have room"

data	insert algorithm / time		deleteMin algorithm / time	
unsorted array	add at end	O(1)	search	O(n)
unsorted linked list	add at front	O(1)	search	O( <i>n</i> )
sorted circular array	search / shift	O(n)	move front	O(1)
sorted linked list	put in right place	O(n)	remove at front	O(1)
binary search tree	put in right place	O(n)	leftmost	O(n)

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## Aside: More on possibilities

- Note: If priorities are inserted in random order, binary search tree will likely do better than O(n)
  - $O(\log n)$  insert and  $O(\log n)$  deleteMin on average
  - Could get same performance from a balanced binary search tree (e.g. AVL tree we will study later)
- One more idea: if priorities are 0, 1, ..., k can use array of lists
  - insert: add to front of list at arr[priority], O(1)
  - deleteMin: remove from lowest non-empty list O(k)

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## Our Data Structure: The Heap

#### The Heap:

- Worst case: O(log n) for insert
- Worst case: O(log n) for deleteMin
- If items arrive in random order, then the average-case of insert is O(1)
- · Very good constant factors

Key idea: Only pay for functionality needed

- We need something better than scanning unsorted items
- But we do not need to maintain a full sorted list
- We will visualize our heap as a tree, so we need to review some tree terminology

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## Reviewing Some Tree Terminology

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root(T):

leaves(T):

children(B):

parent(H):

siblings(E):

ancestors(F):

descendents(G):

subtree(G):

Tree T

A

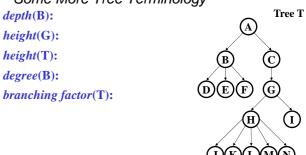
DEF

G

JKLMN

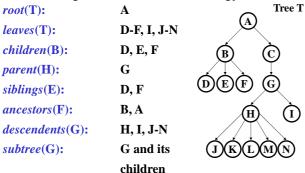
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Some More Tree Terminology



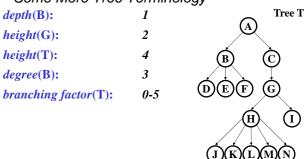
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# Reviewing Some Tree Terminology



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## Some More Tree Terminology



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# Types of Trees

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Binary tree: Every node has ≤2 children

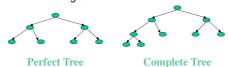
n-ary tree: Every node as ≤n children

Perfect tree: Every row is completely full

Complete tree: All rows except possibly the bottom are

completely full, and it is filled from left to

right



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#### Some Basic Tree Properties

Nodes in a perfect binary tree of height h?

2h+1-1

Leaf nodes in a perfect binary tree of height h?

2<sup>h</sup>

Height of a perfect binary tree with n nodes?

 $[\log_2 n]$ 

Height of a complete binary tree with n nodes?

[log<sub>2</sub> n]

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### Properties of a Binary Min-Heap

More commonly known as a binary heap or simply a heap

- Structure Property:
  - A complete [binary] tree
- Heap Property:

The priority of every non-root node is greater than the priority of its parent

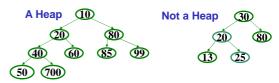
How is this different from a binary search tree?

### Properties of a Binary Min-Heap

More commonly known as a binary heap or simply a heap

- Structure Property:
  - A complete [binary] tree
- Heap Order Property:

The priority of every non-root node is greater than the priority of its parent



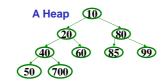
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## Properties of a Binary Min-Heap

- Where is the minimum priority item?
   At the root
- What is the height of a heap with n items?

[log<sub>2</sub> n]



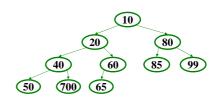
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## Heap Operations

• findMin:

• deleteMin: percolate down.

insert(val): percolate up.



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## Operations: basic idea

findMin:

return root.data

- deleteMin:
  - 1. answer = root.data
  - Move right-most node in last row to root to restore structure property
  - "Percolate down" to restore heap order property
- insert:
  - Put new node in next position on bottom row to restore structure property
  - 2. "Percolate up" to restore heap order property

20 80 40 60 85 99 50 700

#### Overall strategy:

- Preserve complete tree structure property
- This may break heap order property
- Percolate to restore heap order property

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## DeleteMin Implementation

 Delete value at root node (and store it for later return)

 There is now a "hole" at the root. We must "fill" the hole with another value, must have a tree with one less node, and it must still be a complete tree

 The "last" node is the is obvious choice, but now the heap order property is violated

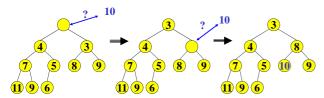
4. We percolate down to fix the heap order:
While greater than either child

Swap with smaller child

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#### Percolate Down



#### Percolate down:

- Keep comparing with both children
- Move smaller child up and go down one level
- Done if both children are ≥ item or reached a leaf node
- Why does this work? What is the run time?

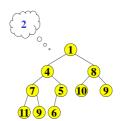
DeleteMin: Run Time Analysis

- Run time is O(height of heap)
- A heap is a complete binary tree
- Height of a complete binary tree of n nodes?
   height = Llog<sub>2</sub>(n) Llog<sub>2</sub>(n)
- Run time of deleteMin is  $O(\log n)$

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#### Insert

- Add a value to the tree
- Structure and heap order properties must still be correct afterwards

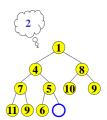


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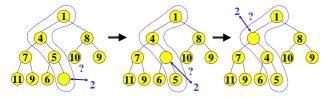
## Insert: Maintain the Structure Property

- There is only one valid tree shape after we add one more node!
- So put our new data there and then focus on restoring the heap order property



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### Maintain the heap order property



#### Percolate up:

- Put new data in new location
- If parent larger, swap with parent, and continue
- Done if parent ≤ item or reached root
- · Why does this work? What is the run time?

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## A Clever Trick for Storing the Heap...

Clearly, insert and deleteMin are worst-case O(log n)

• But we promised average-case O(1) insert (how??)

Insert requires access to the "next to use" position in the tree

- Walking the tree from root to leaf requires O(log n) steps
- Insert and Deletemin would have to update the "next to use" reference each time: O(log n)

We should only pay for the functionality we need!!

• Why have we insisted the tree be complete? ©

All complete trees of size n contain the same edges

So why are we even representing the edges?

Here comes the really clever bit about implementing heaps!!!

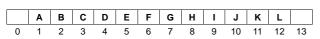
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### Array Representation of a Binary Heap

1 (A)

## From node i:

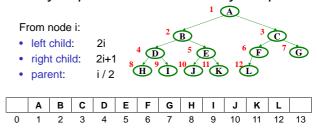
- · left child:
- right child:
- parent:



- · We skip index 0 to make the math simpler
- Actually, it can be a good place to store the current size of the heap

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### Array Representation of a Binary Heap



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- Actually, it can be a good place to store the current size of the heap

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