CSE 326: Data Structures Graphs

James Fogarty Autumn 2007

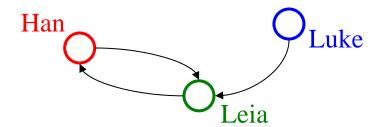
Graph... ADT?

- Not quite an ADT... operations not clear
- A formalism for representing relationships between objects

Graph g = (v, E)

$$\mathbf{v} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$$

- Set of edges: E = {e₁,e₂,...,e_m} where each e_i connects two vertices (v_{i1},v_{i2})

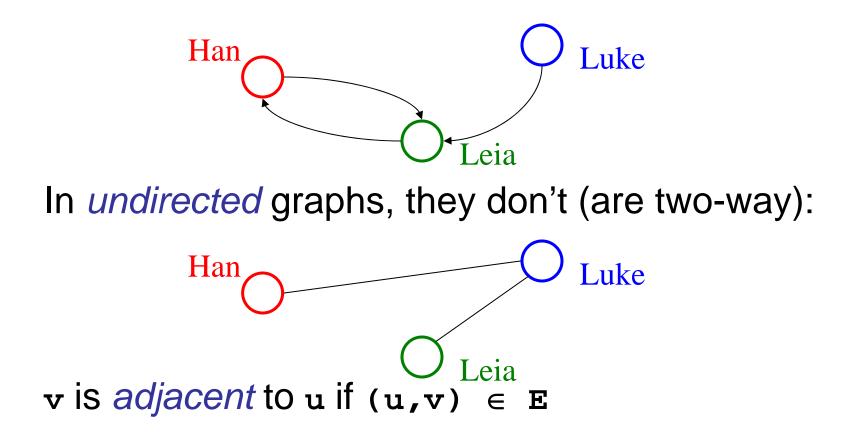


Examples of Graphs

- The web
 - Vertices are webpages
 - Each edge is a link from one page to another
- Call graph of a program
 - Vertices are subroutines
 - Edges are calls and returns
- Social networks
 - Vertices are people
 - Edges connect friends

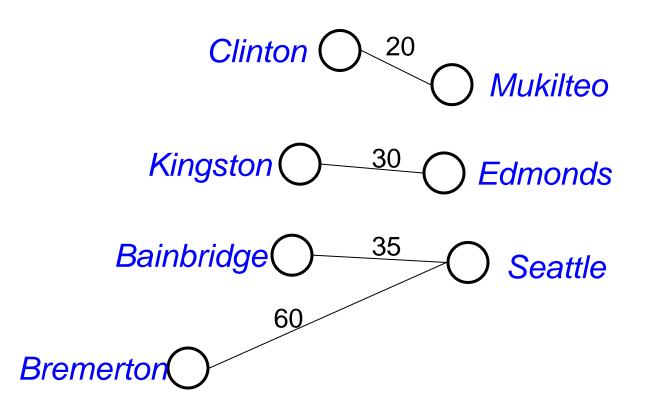
Graph Definitions

In *directed* graphs, edges have a direction:



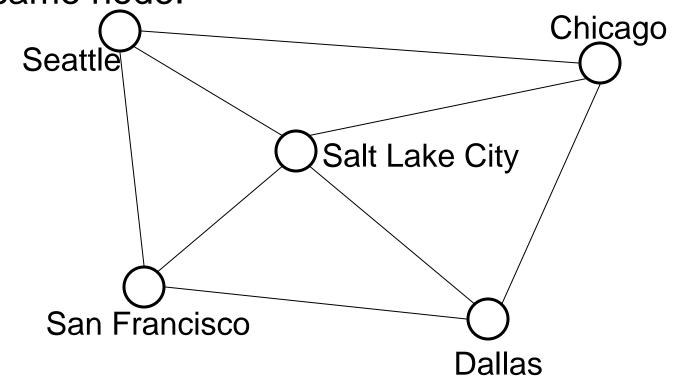
Weighted Graphs

Each edge has an associated weight or cost.



Paths and Cycles

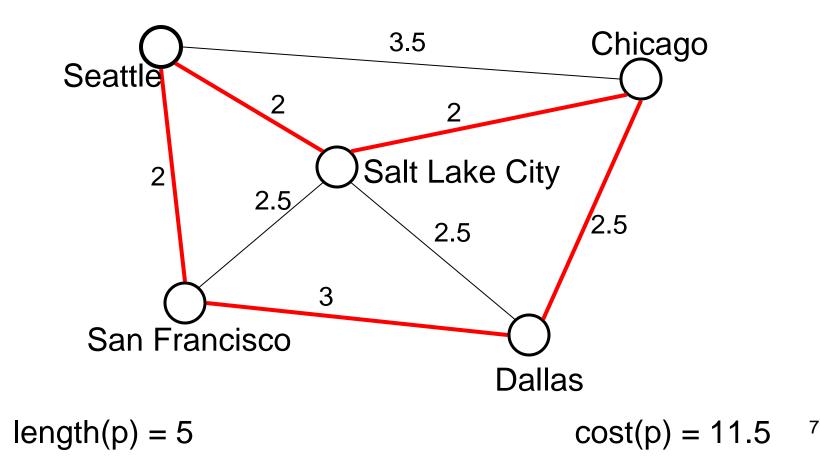
- A *path* is a list of vertices {v₁, v₂, ..., v_n} such that (v_i, v_{i+1}) ∈ E for all 0 ≤ i < n.
- A *cycle* is a path that begins and ends at the same node.



• *p* = {Seattle, Salt Lake City, Chicago, Dallas, San Francisco, Seattle} 6

Path Length and Cost

- Path length: the number of edges in the path
- Path cost: the sum of the costs of each edge

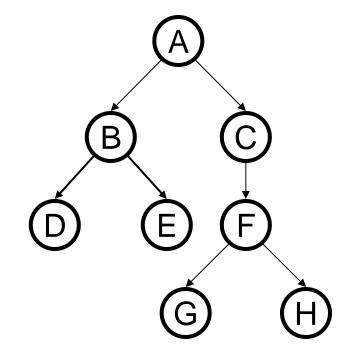


More Definitions: Simple Paths and Cycles

- A *simple path* repeats no vertices (except that the first can also be the last):
 - p = {Seattle, Salt Lake City, San Francisco, Dallas}
 - p = {Seattle, Salt Lake City, Dallas, San Francisco, Seattle}
- A *cycle* is a path that starts and ends at the same node: p = {Seattle, Salt Lake City, Dallas, San Francisco, Seattle} p = {Seattle, Salt Lake City, Seattle, San Francisco, Seattle}
- A *simple cycle* is a cycle that is also a simple path (in undirected graphs, no edge can be repeated)

Trees as Graphs

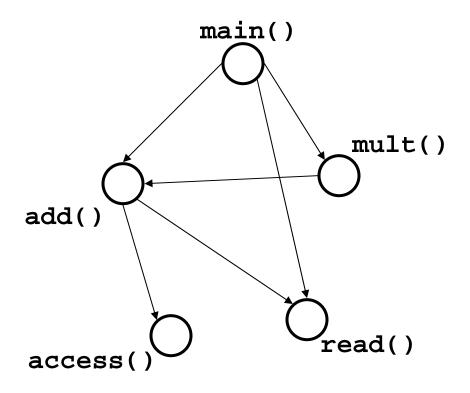
- Every tree is a graph with some restrictions:
 - -the tree is *directed*
 - -there are *no cycles* (directed or undirected)
 - -there is a *directed path from the* root *to every node*



Directed Acyclic Graphs (DAGs)

DAGs are directed graphs with no (directed) cycles.

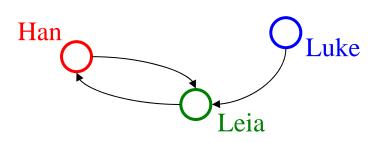
Aside: If program callgraph is a DAG, then all procedure calls can be inlined



 $\{\text{Tree}\} \subset \{\text{DAG}\} \subset \{\text{Graph}\}$

Rep 1: Adjacency Matrix

A $|v| \ge |v|$ array in which an element (u,v) is true if and only if there is an edge from u to v Han Luke Leia



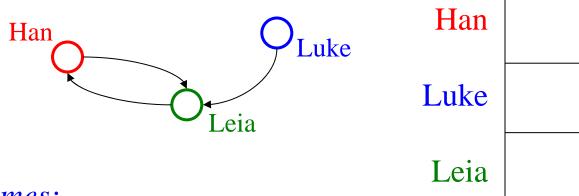
Runtimes: Iterate over vertices? Iterate over edges? Iterate edges adj. to vertex? Existence of edge?



Space requirements?

Rep 2: Adjacency List

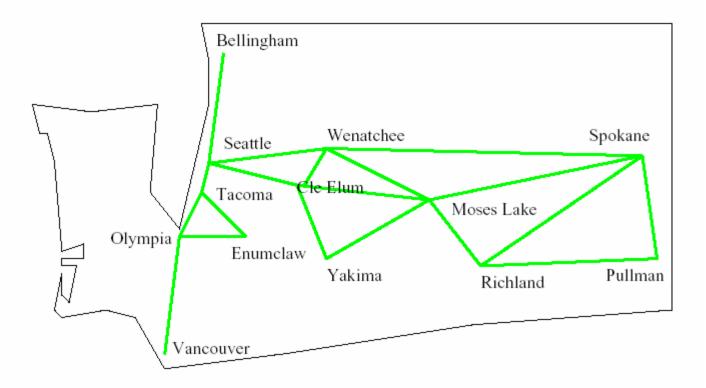
A [v]-ary list (array) in which each entry stores a list (linked list) of all adjacent vertices



Runtimes: Iterate over vertices? Iterate over edges? Iterate edges adj. to vertex? Existence of edge?

Space requirements?

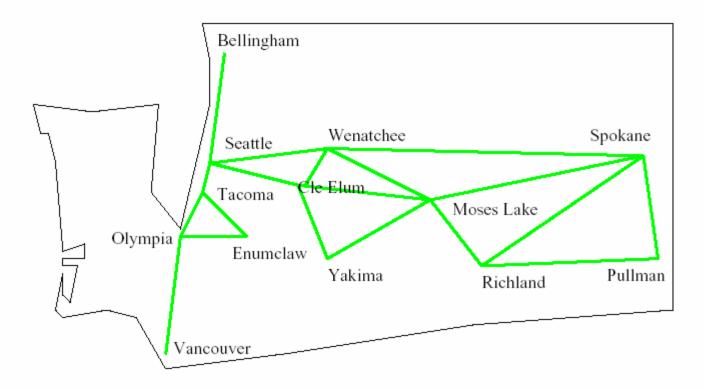
Some Applications: Moving Around Washington



What's the *shortest way* to get from Seattle to Pullman? Edge labels:

Distance

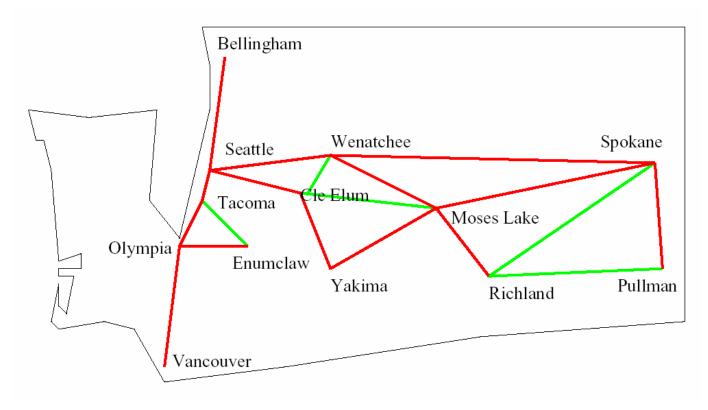
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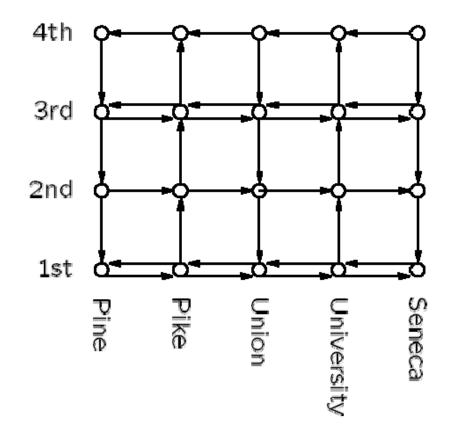
Distance, speed limit

Some Applications: Reliability of Communication



If Wenatchee's phone exchange *goes down*, can Seattle still talk to Pullman?

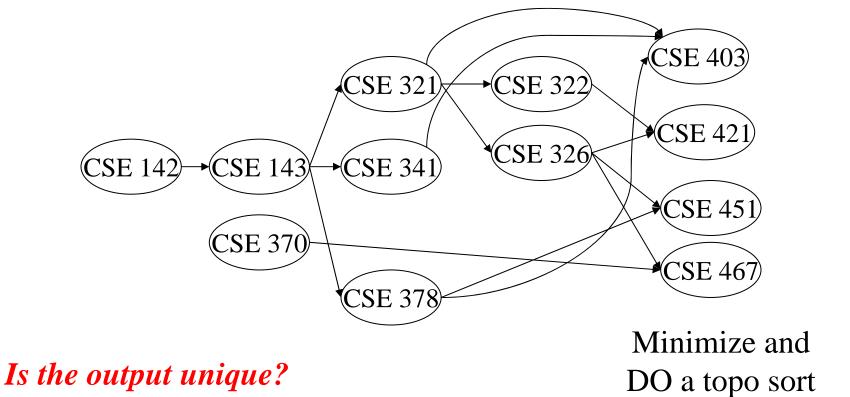
Some Applications: Bus Routes in Downtown Seattle



If we're at 3rd and Pine, how can we get to 1st and University using Metro? How about 4th and Seneca? This is a partial ordering, for sorting we had a total ordering

Application: Topological Sort

Given a directed graph, G = (v, E), output all the vertices in v such that no vertex is output before any other vertex with an edge to it.



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Topological Sort: Take One

- 1. Label each vertex with its *in-degree* (# of inbound edges)
- 2. While there are vertices remaining:
 - a. Choose a vertex *v* of *in-degree zero*; output *v*
 - b. Reduce the in-degree of all vertices adjacent to *v*
 - c. Remove *v* from the list of vertices

Runtime:

```
void Graph::topsort(){
Vertex v, w;
                                         Time?
labelEachVertexWithItsIn-degree();
for (int counter=0; counter < NUM_VERTICES;</pre>
                                     counter++){
  v = findNewVertexOfDegreeZero();
                                         Time?
  v.topologicalNum = counter;
  for each w adjacent to v
                                   Time?
    w.indegree--;
                           What's the bottleneck?
```



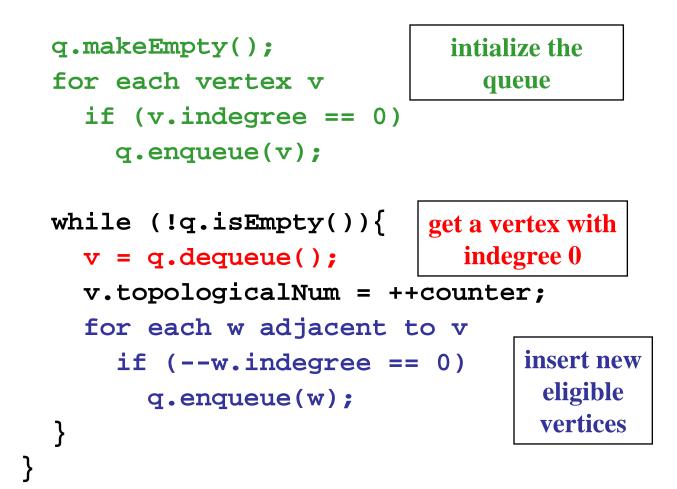
Topological Sort: Take Two

- 1. Label each vertex with its in-degree
- 2. Initialize a queue Q to contain all in-degree zero vertices
- 3. While Q not empty
 - a. v = Q.dequeue; output v
 - b. Reduce the in-degree of all vertices adjacent to v
 - c. If new in-degree of any such vertex *u* is zero *Q*.enqueue(*u*)

<u>Note</u>: could use a stack, list, set, box, ... instead of a queue

Runtime:

```
void Graph::topsort(){
  Queue q(NUM_VERTICES); int counter = 0; Vertex v, w;
  labelEachVertexWithItsIn-degree();
```



O(|V| + |E|)

Runtime:

Graph Connectivity

Undirected graphs are *connected* if there is a path between any two vertices

Directed graphs are *strongly connected* if there is a path from any one vertex to any other

Directed graphs are *weakly connected* if there is a path between any two vertices, *ignoring direction*

A complete graph has an edge between every pair of vertices

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Graph Traversals

- Breadth-first search (and depth-first search) work for arbitrary (directed or undirected) graphs - not just mazes!
 - Must mark visited vertices so you do not go into an infinite loop!
- Either can be used to determine connectivity:
 - Is there a path between two given vertices?
 - Is the graph (weakly) connected?
- Which one:
 - Uses a queue?
 - Uses a stack?
 - Always finds the shortest path (for unweighted graphs)?