

# Graph Representation Learning

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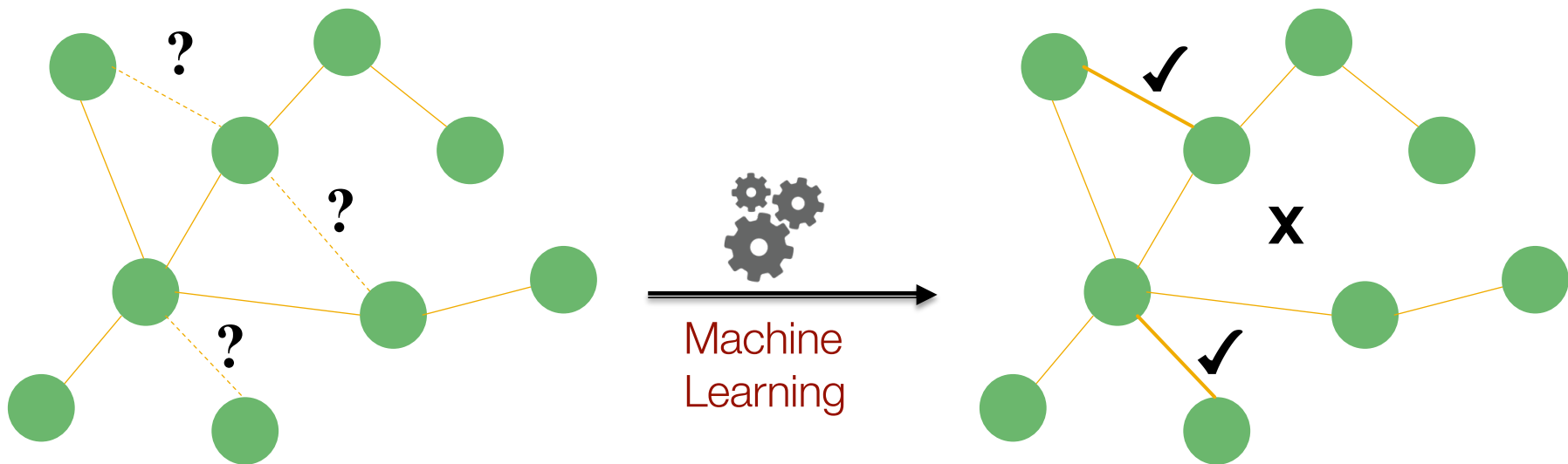
CSEP590A Machine Learning for Big Data

Tim Althoff

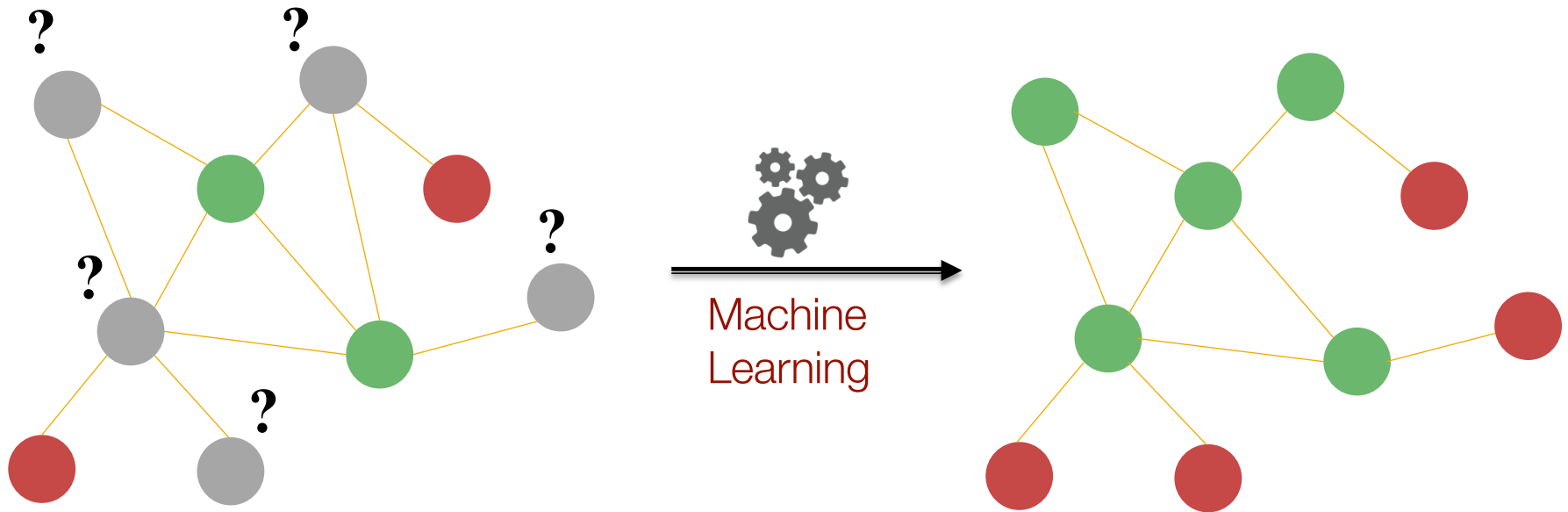


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OF COMPUTER SCIENCE & ENGINEERING

# Example: Link Prediction



# Machine Learning in Networks



Node classification

# Example: Node Classification

Classifying the function of proteins in the interactome

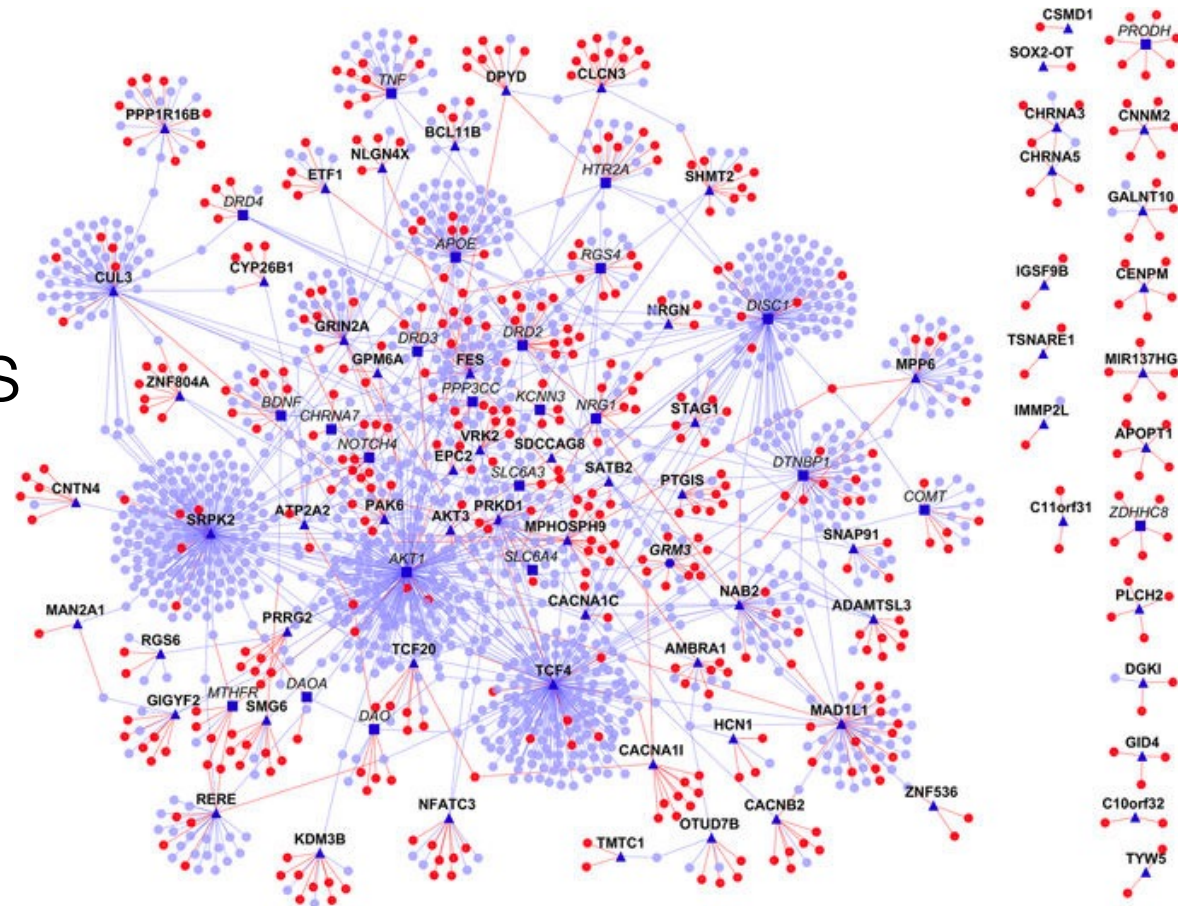
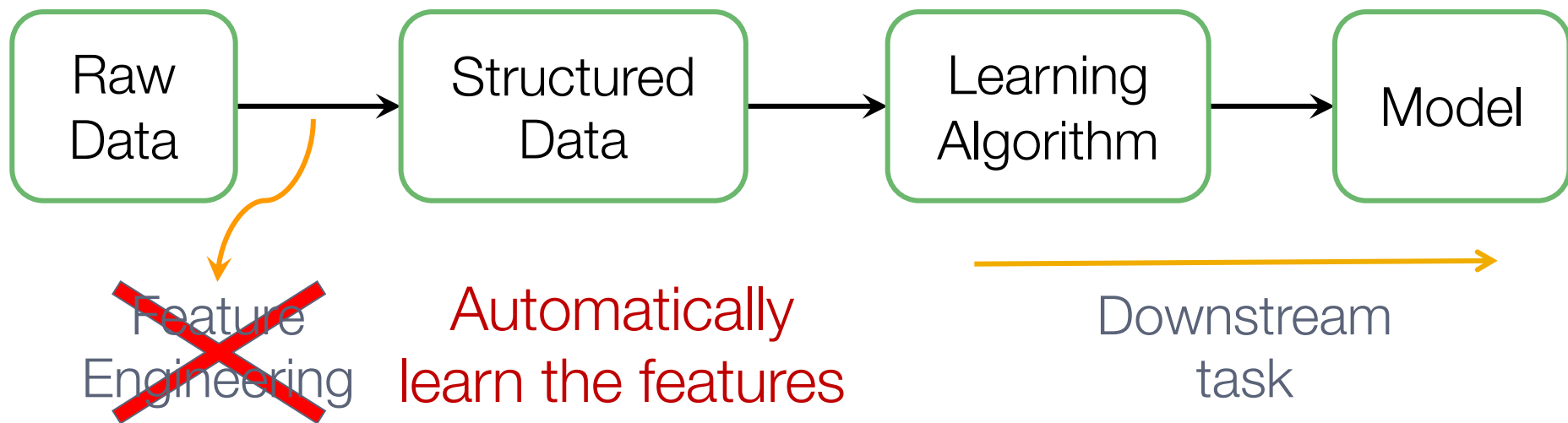


Image from: Ganapathiraju et al. 2016. [Schizophrenia interactome with 504 novel protein-protein interactions](#). *Nature*.

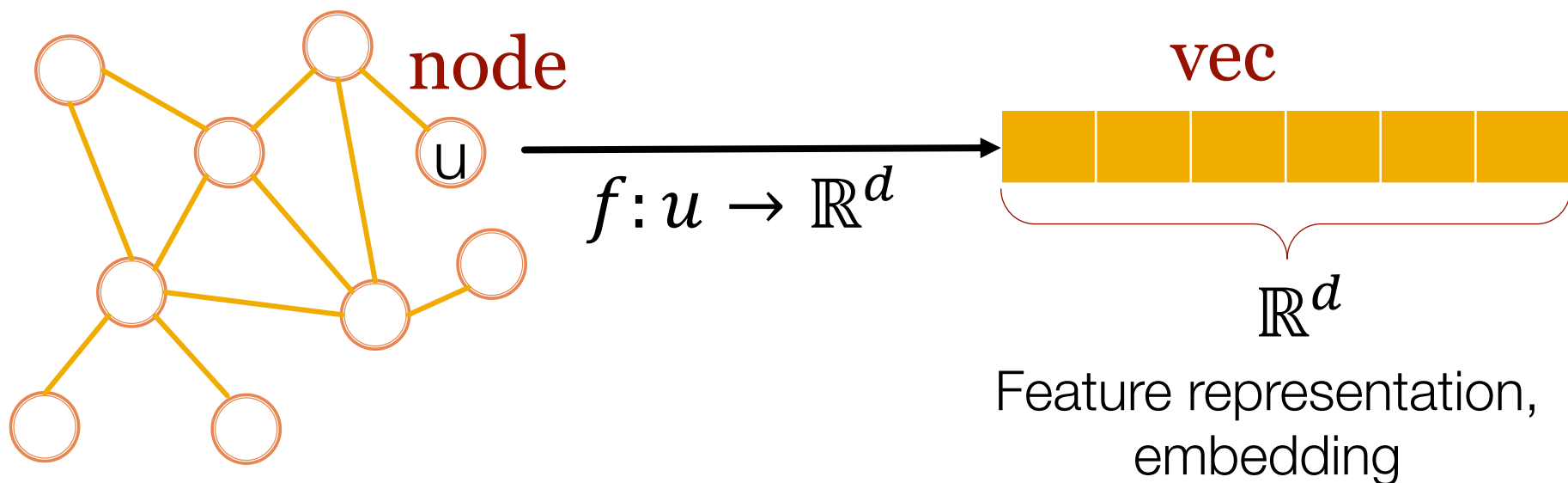
# Machine Learning Lifecycle

- **(Supervised) Machine Learning Lifecycle requires feature engineering **every single time!****



# Feature Learning in Graphs

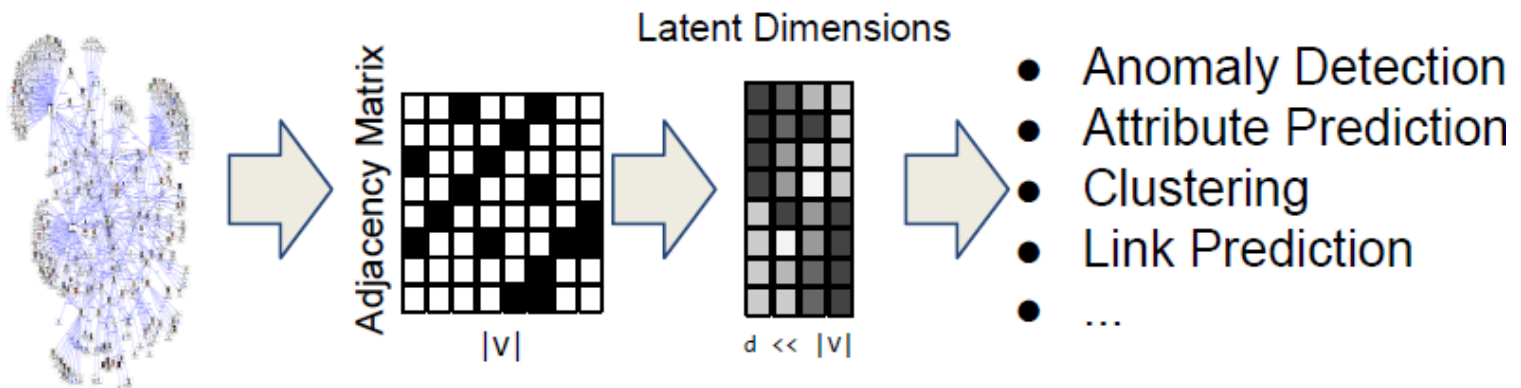
**Goal:** Efficient **task-independent** feature learning for machine learning in networks!



# Why network embedding?

**Task: We map each node in a network to a point in a low-dimensional space**

- Distributed representation for nodes
- Similarity of embedding between nodes indicates their network similarity
- Encode network information and generate node representation



# Example Node Embedding

2D embedding of nodes of the Zachary's Karate Club network:

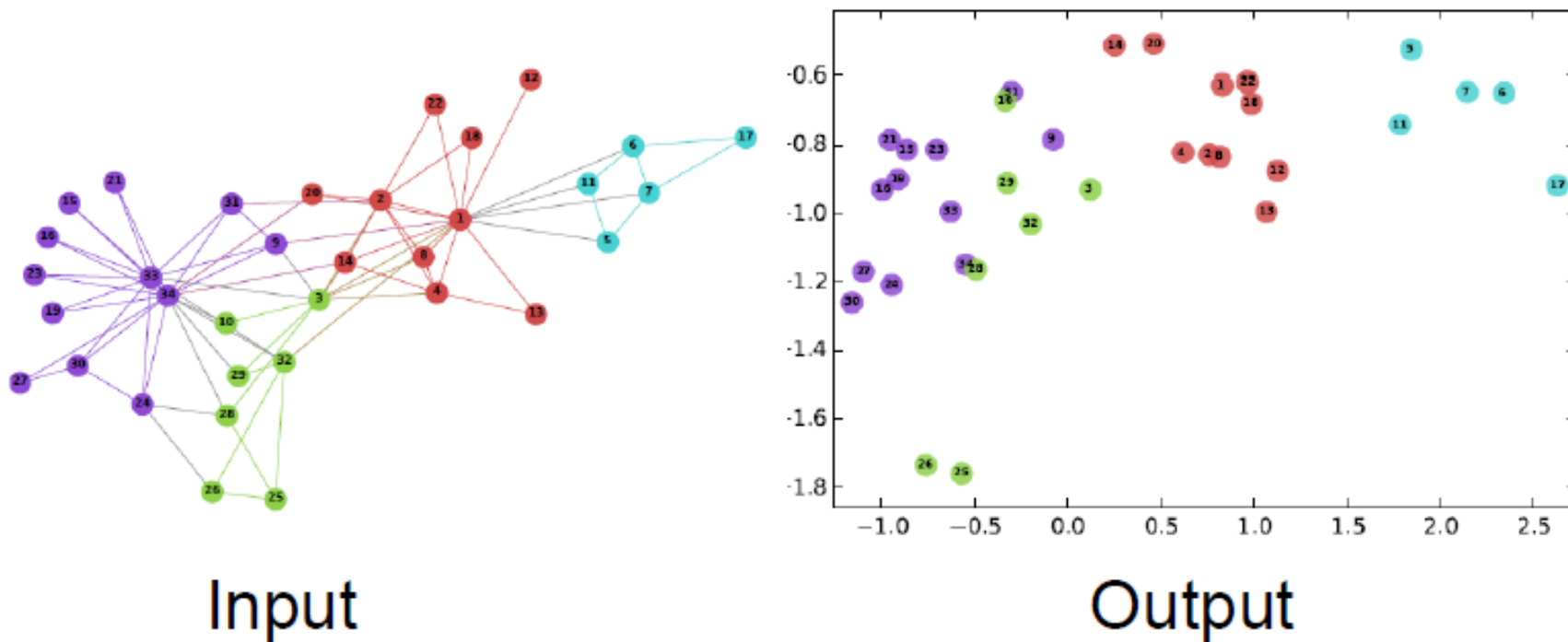
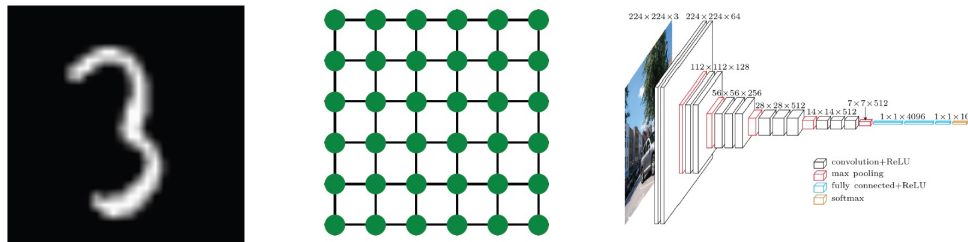


Image from: [Perozzi et al.](#) DeepWalk: Online Learning of Social Representations. *KDD 2014*.

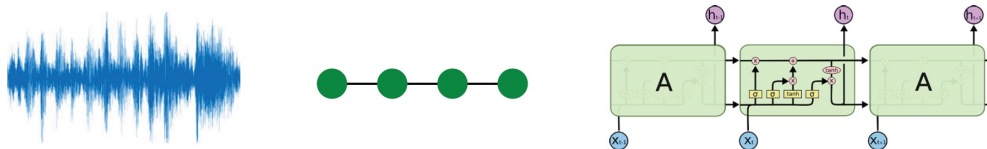


# Why Is It Hard?

- **Modern deep learning toolbox is designed for simple sequences or grids**
  - CNNs for fixed-size images/grids....



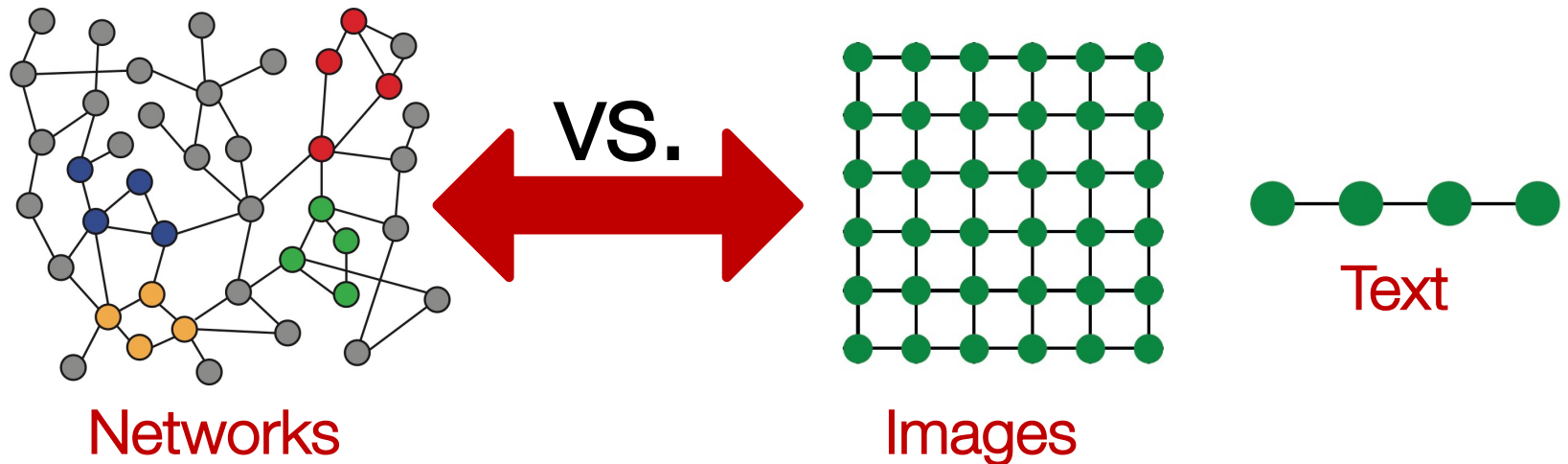
- RNNs or word2vec for text/sequences...



# Why Is It Hard?

**But networks are far more complex!**

- Complex topographical structure (no spatial locality like grids)



- No fixed node ordering or reference point
- Often dynamic and have multimodal features.

# Embedding Nodes

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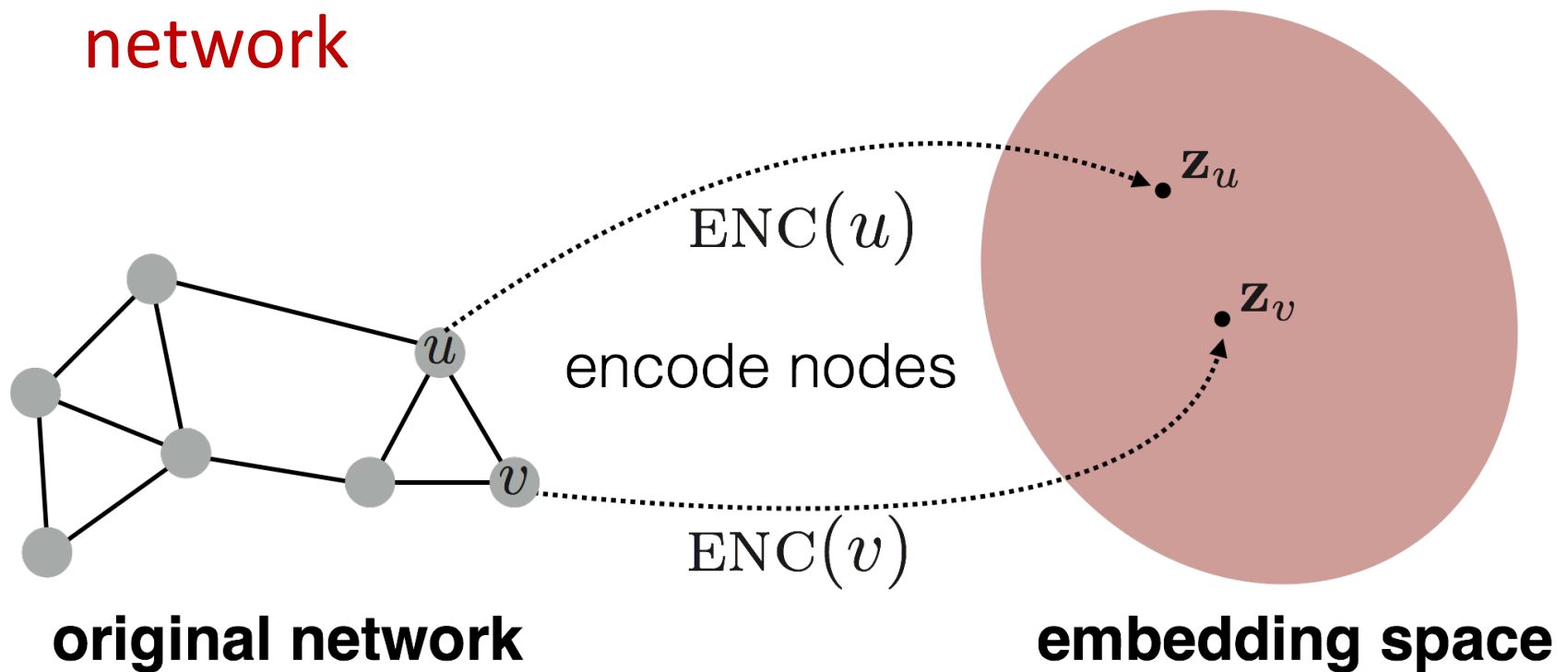
# Setup

**Assume we have a graph  $G$ :**

- $V$  is the vertex set
- $A$  is the adjacency matrix (assume binary)
- **No node features or extra information is used!**

# Embedding Nodes

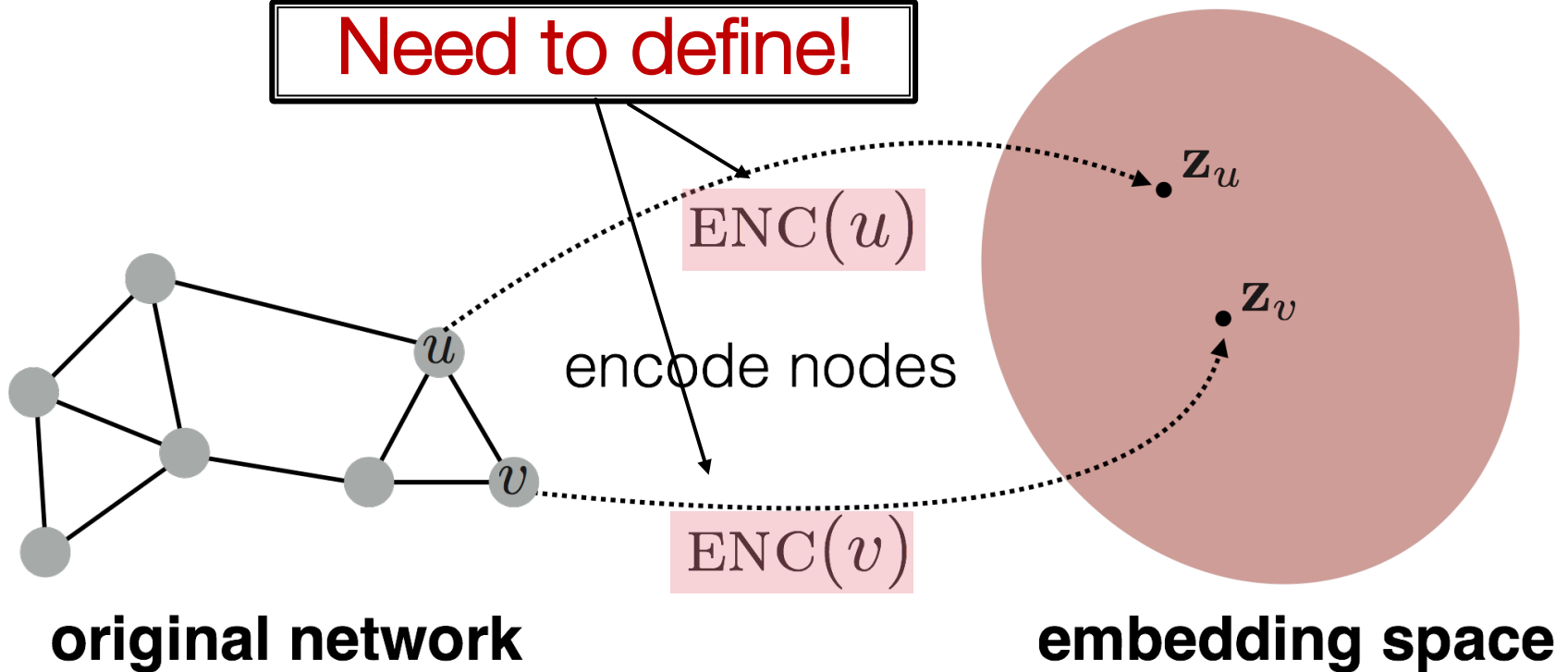
- Goal is to encode nodes so that **similarity in the embedding space** (e.g., dot product) approximates **similarity in the original network**



# Embedding Nodes

Goal:  $\text{similarity}(u, v)$  in the original network  $\approx \mathbf{z}_v^\top \mathbf{z}_u$  Similarity of the embedding

**Need to define!**



# Learning Node Embeddings

1. **Define an encoder** (i.e., a mapping from nodes to embeddings)
2. **Define a node similarity function** (i.e., a measure of similarity in the original network)
3. **Optimize the parameters of the encoder so that:**

$$\text{similarity}_{\text{in the original network}}(u, v) \approx \mathbf{z}_v^\top \mathbf{z}_u$$

Similarity of the embedding

# Two Key Components

- **Encoder** maps each node to a low-dimensional vector

$$\text{ENC}(v) = \mathbf{z}_v$$

node in the input graph

d-dimensional embedding

- **Similarity function** specifies how relationships in vector space map to relationships in the original network

$$\text{similarity}(u, v) \approx \mathbf{z}_v^T \mathbf{z}_u$$

Similarity of  $u$  and  $v$  in the original network

dot product between node embeddings



# “Shallow” Encoding

- Simplest encoding approach: **encoder is just an embedding-lookup**

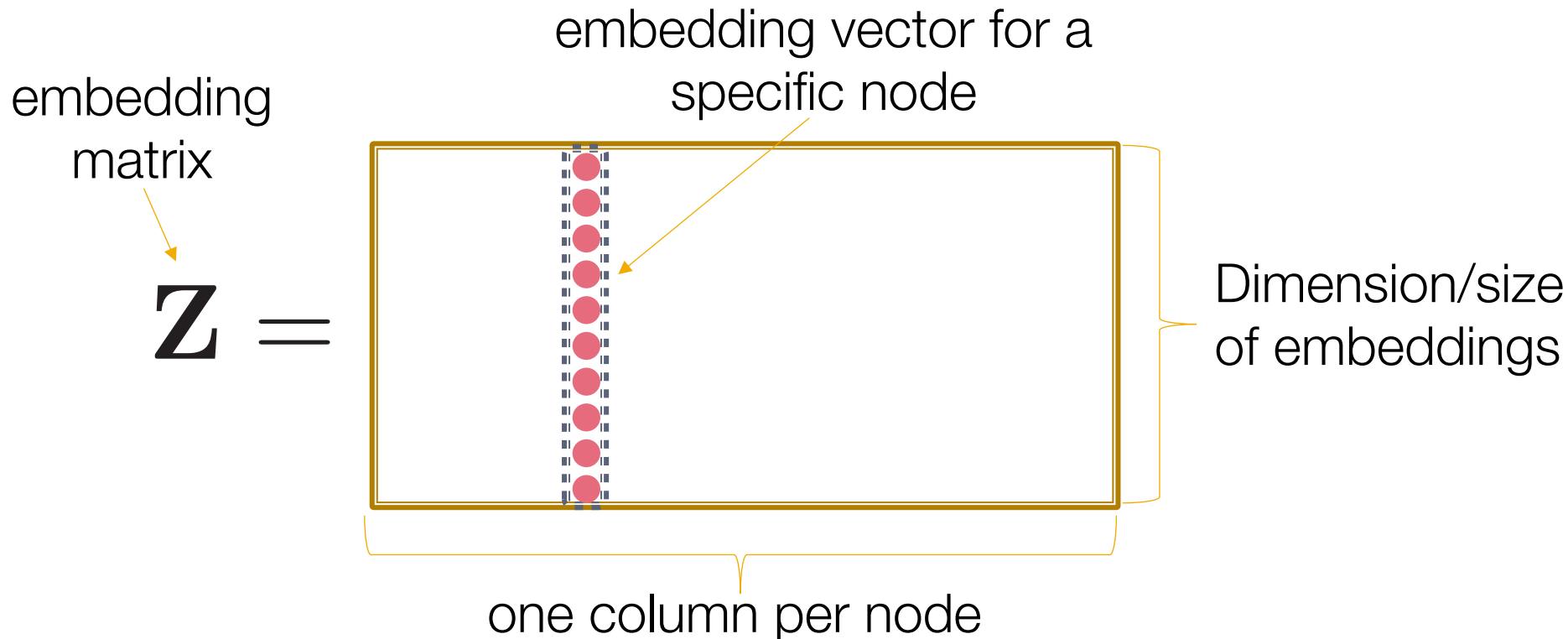
$$\text{ENC}(v) = \mathbf{Z}\mathbf{v}$$

$\mathbf{Z} \in \mathbb{R}^{d \times |\mathcal{V}|}$  Matrix, each column is  $d$ -dim node embedding [what we learn!]

$\mathbf{v} \in \mathbb{I}^{|\mathcal{V}|}$  Indicator vector, all zeroes except a one in column indicating node  $v$

# “Shallow” Encoding

- Simplest encoding approach: **encoder is just an embedding-lookup**



# “Shallow” Encoding

Simplest encoding approach: **encoder is just an embedding-lookup**

**Each node is assigned a unique embedding vector**

Many methods: node2vec, DeepWalk, LINE

# How to Define Node Similarity?

Key choice of methods is **how they define node similarity.**

E.g., should two nodes have similar embeddings if they....

- are connected?
- share neighbors?
- have similar “structural roles”?
- ...?

# Random Walk Approaches to Node Embeddings

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Material based on:

- Perozzi et al. 2014. DeepWalk: Online Learning of Social Representations. *KDD*.
- Grover et al. 2016. node2vec: Scalable Feature Learning for Networks. *KDD*.

# Random-walk Embeddings

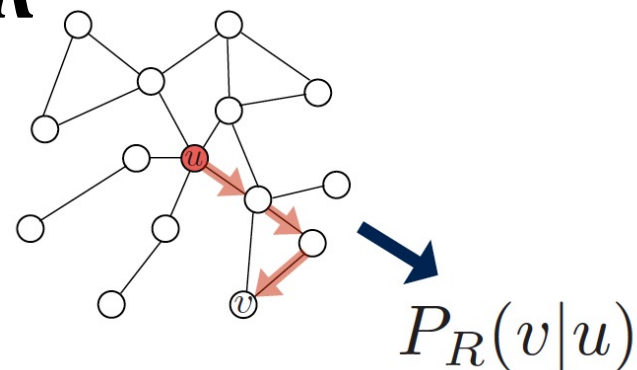
$$\mathbf{z}_u^\top \mathbf{z}_v \approx$$

Probability that  $u$   
and  $v$  co-occur on  
a random walk over  
the network

$z_u$  ... embedding of node  $u$

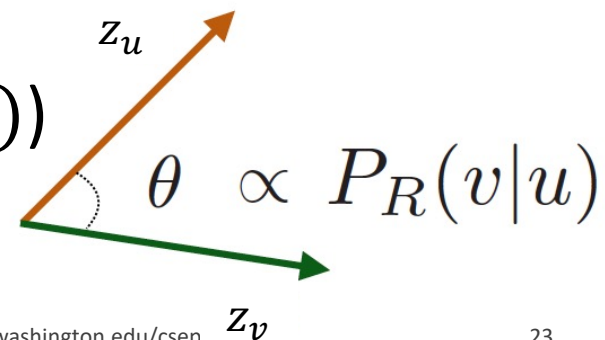
# Random-walk Embeddings

1. Estimate probability of visiting node  $v$  on a random walk starting from node  $u$  using some random walk strategy  $R$



2. Optimize embeddings to encode these random walk statistics:

Similarity (here: dot product  $\approx \cos(\theta)$ ) encodes random walk “similarity”



# Why Random Walks?

- 1. Expressivity:** Flexible stochastic definition of node similarity that incorporates both local and higher-order neighborhood information
- 2. Efficiency:** Do not need to consider all node pairs when training; only need to consider pairs that co-occur on random walks



# Unsupervised Feature Learning

- **Intuition:** Find embedding of nodes to  $d$ -dimensional space so that node similarity is preserved
- **Idea:** Learn node embedding such that **nearby** nodes are close together in the network
- **Given a node  $u$ , how do we define nearby nodes?**
  - $N_R(u)$  ... neighbourhood of  $u$  obtained by some strategy  $R$

# Feature learning as optimization

- Given  $G = (V, E)$
- Our goal is to learn a mapping  $z: u \rightarrow \mathbb{R}^d$
- Maximize log-likelihood objective:

$$\max_z \sum_{u \in V} \log P(N_R(u) | z_u)$$

- where  $N_R(u)$  is neighborhood of node  $u$
- Given node  $u$ , we want to learn feature representations predictive of nodes in its neighborhood  $N_R(u)$

# Random Walk Optimization

1. Run **short fixed-length random walks** starting from each node on the graph using some strategy  $R$
2. For each node  $u$  collect  $N_R(u)$ , the multiset\* of nodes visited on random walks starting from  $u$
3. Optimize embeddings according to: **Given node  $u$ , predict its neighbors  $N_R(u)$**

$$\max_{\mathbf{z}} \sum_{u \in V} \log P(N_R(u) | \mathbf{z}_u)$$

\* $N_R(u)$  can have repeat elements since nodes can be visited multiple times on random walks

# Random Walk Optimization

$$\max_{\mathbf{z}} \sum_{u \in V} \log P(N_R(u) | z_u)$$

- **Assumption:** Conditional likelihood factorizes over the set of neighbors:

$$\log P(N_R(u) | z_u) = \sum_{v \in N_R(u)} \log P(z_v | z_u)$$

- **Softmax parametrization:**

$$\Pr(z_v | z_u) = \frac{\exp(z_v \cdot z_u)}{\sum_{n \in V} \exp(z_n \cdot z_u)}$$

## Why softmax?

We want node  $v$  to be most similar to node  $u$  (out of all nodes  $n$ ).

**Intuition:**  $\sum_i \exp(x_i) \approx \max_i \exp(x_i)$

# Random Walk Optimization

Putting it all together:

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} - \log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

sum over all nodes  $u$

sum over nodes  $v$  seen on random walks starting from  $u$

predicted probability of  $u$  and  $v$  co-occurring on random walk

Optimizing random walk embeddings =

Finding node embeddings  $\mathbf{z}$  that minimize  $\mathcal{L}$

# Random Walk Optimization

But doing this naively is too expensive!!

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

Nested sum over nodes gives  
 $O(|V|^2)$  complexity!

# Random Walk Optimization

But doing this naively is too expensive!!

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

The normalization term from the softmax is the culprit... can we approximate it?

# Negative Sampling

- **Solution: Negative sampling**

$$\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

$$\approx \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_v)) - \sum_{i=1}^k \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_{n_i})), n_i \sim P_V$$

**sigmoid function**  
(makes each term a “probability”  
between 0 and 1)

random distribution over  
all nodes

## Why is the approximation valid?

Technically, this is a different objective. But Negative Sampling is a form of Noise Contrastive Estimation (NCE) which approx. maximizes the log probability of softmax.

New formulation corresponds to using a logistic regression (sigmoid func.) to distinguish the target node  $v$  from nodes  $n_i$  sampled from background distribution  $P_V$ .

More at <https://arxiv.org/pdf/1402.3722.pdf> and <https://arxiv.org/pdf/1410.8251.pdf>

Instead of normalizing w.r.t. all nodes, just normalize against  $k$  random “**negative samples**”  $n_i$



# Negative Sampling

$$\log \left( \frac{\exp(\mathbf{z}_u^\top \mathbf{z}_v)}{\sum_{n \in V} \exp(\mathbf{z}_u^\top \mathbf{z}_n)} \right)$$

random distribution  
over all nodes



$$\approx \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_v)) - \sum_{i=1}^k \log(\sigma(\mathbf{z}_u^\top \mathbf{z}_{n_i})), n_i \sim P_V$$

- Sample  $k$  negative nodes proportional to degree
- Two considerations for  $k$  (# negative samples):
  1. Higher  $k$  gives more robust estimates
  2. Higher  $k$  corresponds to higher prior on negative events

In practice  $k = 5-20$

# Random Walks: Stepping Back

1. Run **short fixed-length** random walks starting from each node on the graph using some strategy  $R$ .
2. For each node  $u$  collect  $N_R(u)$ , the multiset of nodes visited on random walks starting from  $u$
3. Optimize embeddings using Stochastic Gradient Descent:

$$\mathcal{L} = \sum_{u \in V} \sum_{v \in N_R(u)} -\log(P(v|\mathbf{z}_u))$$

We can efficiently approximate this using  
negative sampling!

# How should we randomly walk?

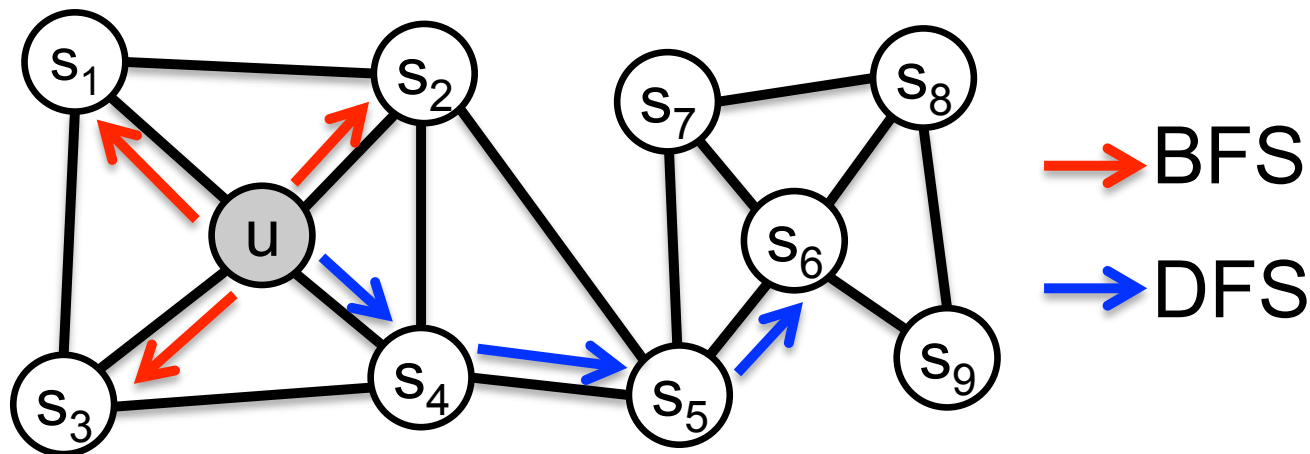
- So far we have described how to optimize embeddings given random walk statistics
- **What strategies should we use to run these random walks?**
  - Simplest idea: **Just run fixed-length, unbiased random walks starting from each node** (i.e., [DeepWalk from Perozzi et al., 2013](#)).
    - The issue is that such notion of similarity is too constrained
  - How can we generalize this?

# Overview of node2vec

- **Goal:** Embed nodes with similar network neighborhoods close in the feature space
- We frame this goal as prediction-task independent maximum likelihood optimization problem
- **Key observation:** Flexible notion of network neighborhood  $N_R(u)$  of node  $u$  leads to rich node embeddings
- Develop **biased 2<sup>nd</sup> order random walk**  $R$  to generate network neighborhood  $N_R(u)$  of node  $u$

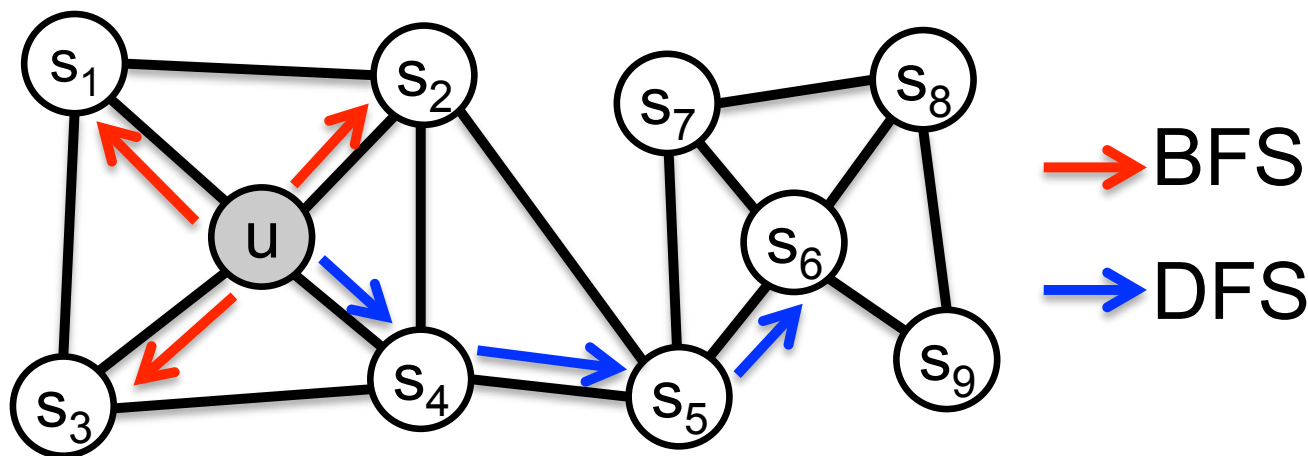
# node2vec: Biased Walks

**Idea:** use flexible, biased random walks that can trade off between **local** and **global** views of the network ([Grover and Leskovec, 2016](#)).



# node2vec: Biased Walks

Two classic strategies to define a neighborhood  $N_R(u)$  of a given node  $u$ :



**Walk of length 3 ( $N_R(u)$  of size 3):**

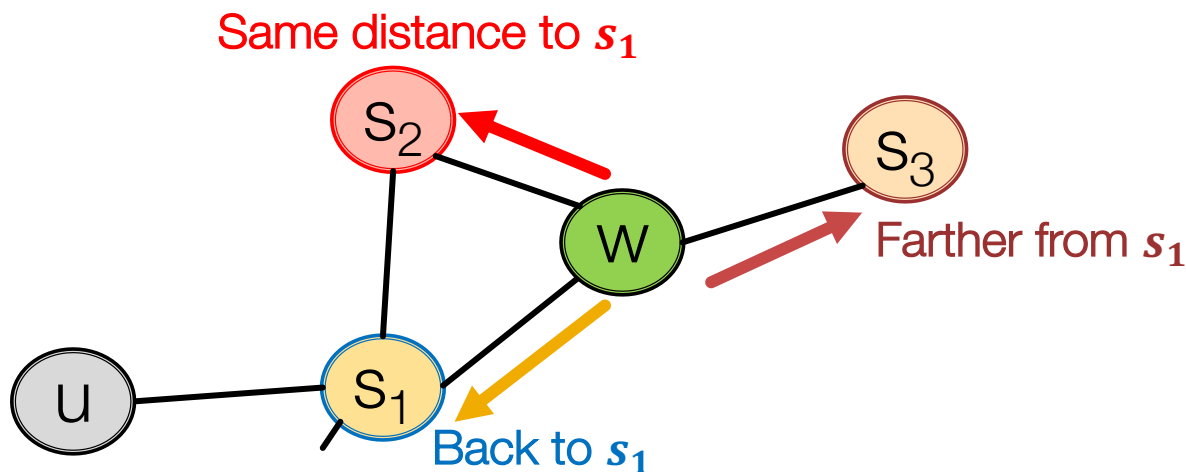
$N_{BFS}(u) = \{s_1, s_2, s_3\}$  **Local** microscopic view

$N_{DFS}(u) = \{s_4, s_5, s_6\}$  **Global** macroscopic view

# Biased Random Walks

Biased 2<sup>nd</sup>-order random walks explore network neighborhoods:

- Rnd. walk just traversed edge  $(s_1, w)$  and is now at  $w$
- **Insight:** Neighbors of  $w$  can only be:



**Idea:** Remember where that walk came from

# Interpolating BFS and DFS

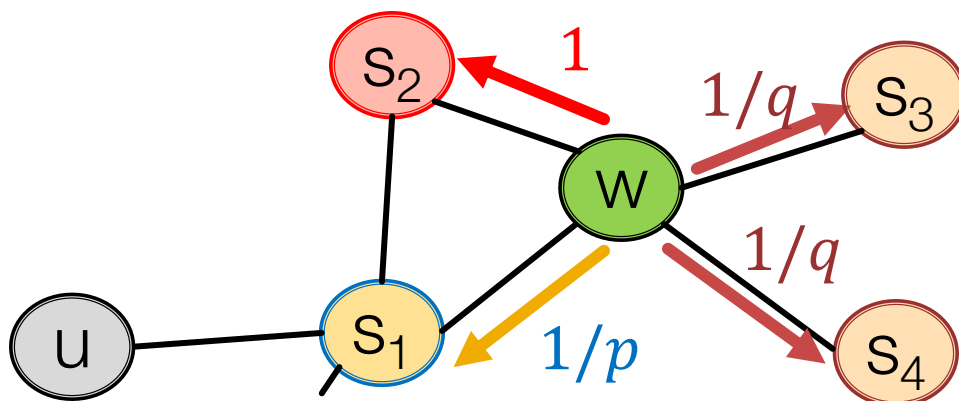
**Biased fixed-length random walk  $R$  that given a node  $u$  generates neighborhood  $N_R(u)$**

- Two parameters:
  - **Return parameter  $p$ :**
    - Return back to the previous node
  - **In-out parameter  $q$ :**
    - Moving outwards (DFS) vs. inwards (BFS)
    - Intuitively,  $q$  is the “ratio” of BFS vs. DFS



# Biased Random Walks

- Walker came over edge  $(s_1, w)$  and is at  $w$ .  
Where to go next?



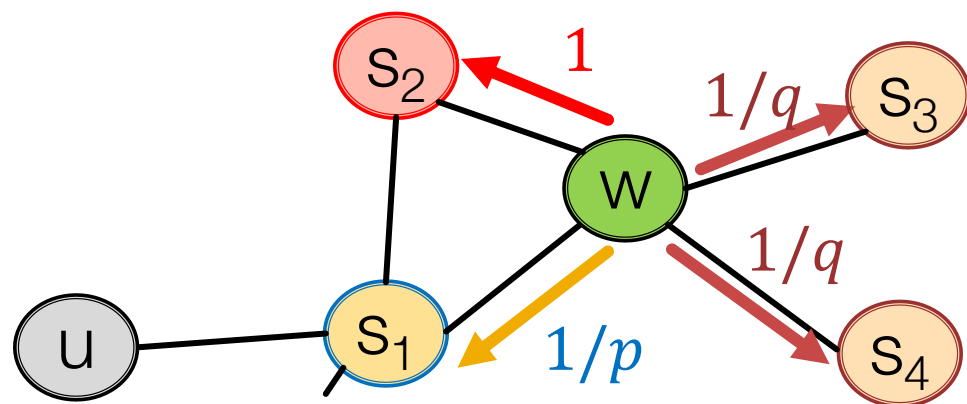
$1/p, 1/q, 1$  are  
“unnormalized”  
probabilities (weights  
we later convert to  
probability distribution)

- $p, q$  model transition probabilities
  - $p$  ... return parameter
  - $q$  ... “walk away” parameter

# Biased Random Walks

- Walker came over edge  $(s_1, w)$  and is at  $w$ .

Where to go next?



$w \rightarrow$

Target $t$	Prob.	Dist. $(s_1, t)$
$s_1$	$1/p$	0
$s_2$	1	1
$s_3$	$1/q$	2
$s_4$	$1/q$	2

Unnormalized transition prob. segmented based on distance from  $s_1$

- BFS-like** walk: Low value of  $p$
- DFS-like** walk: Low value of  $q$

$N_R(u)$  are the nodes visited by the biased walk

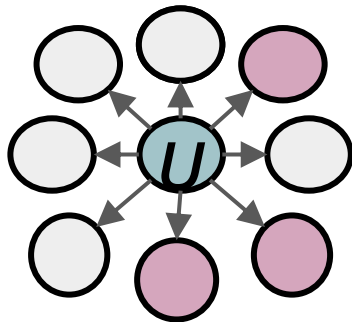
# node2vec algorithm

- 1) Compute random walk probabilities
- 2) Simulate  $r$  random walks of length  $l$  starting from each node  $u$
- 3) Optimize the node2vec objective using Stochastic Gradient Descent

Linear-time complexity.

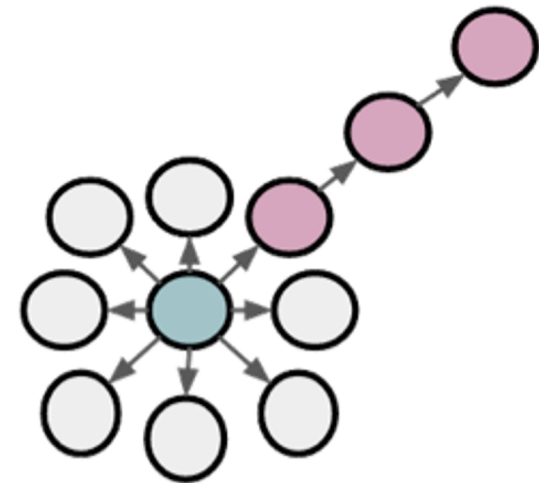
All 3 steps are individually parallelizable

# BFS vs. DFS



**BFS:**

Micro-view of  
neighbourhood

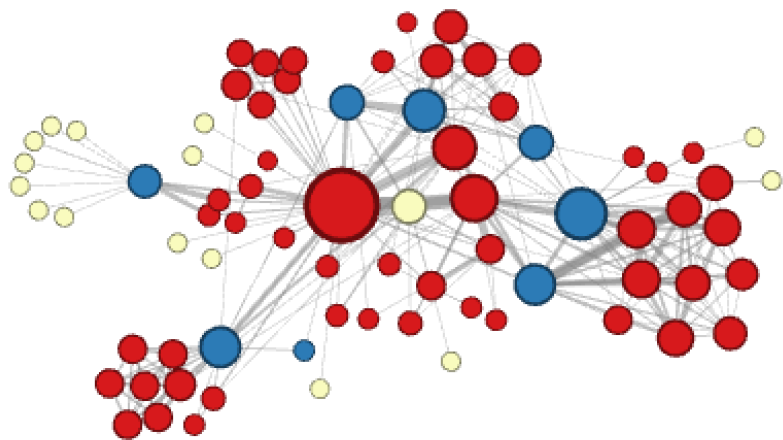


**DFS:**

Macro-view of  
neighbourhood

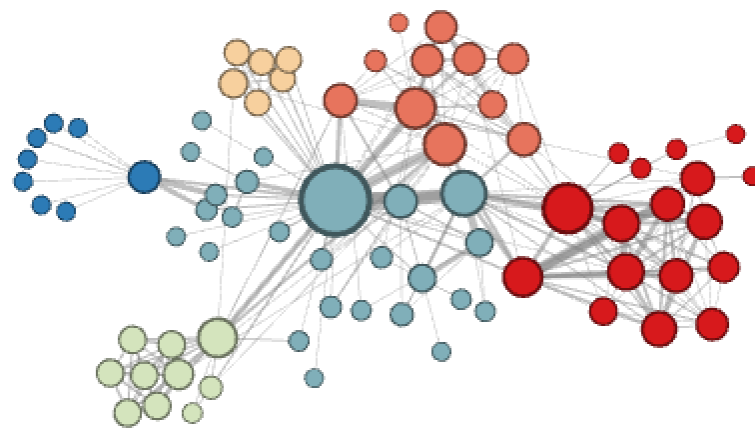
# Experiments: Micro vs. Macro

**Small network of interactions of characters in a novel:**



$$p=1, q=2$$

Microscopic view of the network neighbourhood



$$p=1, q=0.5$$

Macroscopic view of the network neighbourhood

# Other random walk ideas

(not covered in detailed here but for your reference)

- **Different kinds of biased random walks:**
  - Based on node attributes ([Dong et al., 2017](#)).
  - Based on a learned weights ([Abu-El-Haija et al., 2017](#))
- **Alternative optimization schemes:**
  - Directly optimize based on 1-hop and 2-hop random walk probabilities (as in [LINE from Tang et al. 2015](#)).
- **Network preprocessing techniques:**
  - Run random walks on modified versions of the original network (e.g., [Ribeiro et al. 2017's struct2vec](#), [Chen et al. 2016's HARP](#)).

# How to Use Embeddings

- **How to use embeddings  $z_i$  of nodes:**
  - **Clustering/community detection:** Cluster nodes/points based on  $z_i$
  - **Node classification:** Predict label  $f(z_i)$  of node  $i$  based on  $z_i$
  - **Link prediction:** Predict edge  $(i, j)$  based on  $f(z_i, z_j)$ 
    - Where we can: concatenate, avg, product, or take a difference between the embeddings:
      - Concatenate:  $f(z_i, z_j) = g([z_i, z_j])$
      - Hadamard:  $f(z_i, z_j) = g(z_i * z_j)$  (per coordinate product)
      - Sum/Avg:  $f(z_i, z_j) = g(z_i + z_j)$
      - Distance:  $f(z_i, z_j) = g(\|z_i - z_j\|_2)$

# Summary so far

- **So what method should I use..?**
- No one method wins in all cases....
  - E.g., node2vec performs better on node classification while multi-hop methods performs better on link prediction ([Goyal and Ferrara, 2017 survey](#))
- Random walk approaches are generally more efficient
- **In general:** Must choose def'n of node similarity that matches your application!



# Embedding Entire Graphs

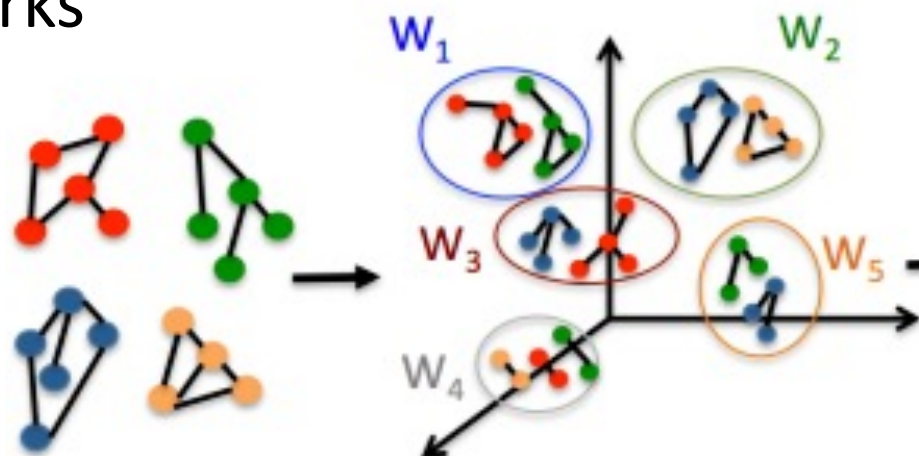
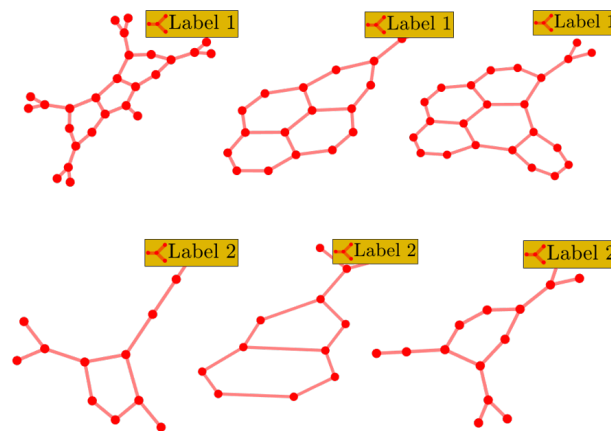
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# Graph Classification

## ■ Tasks:

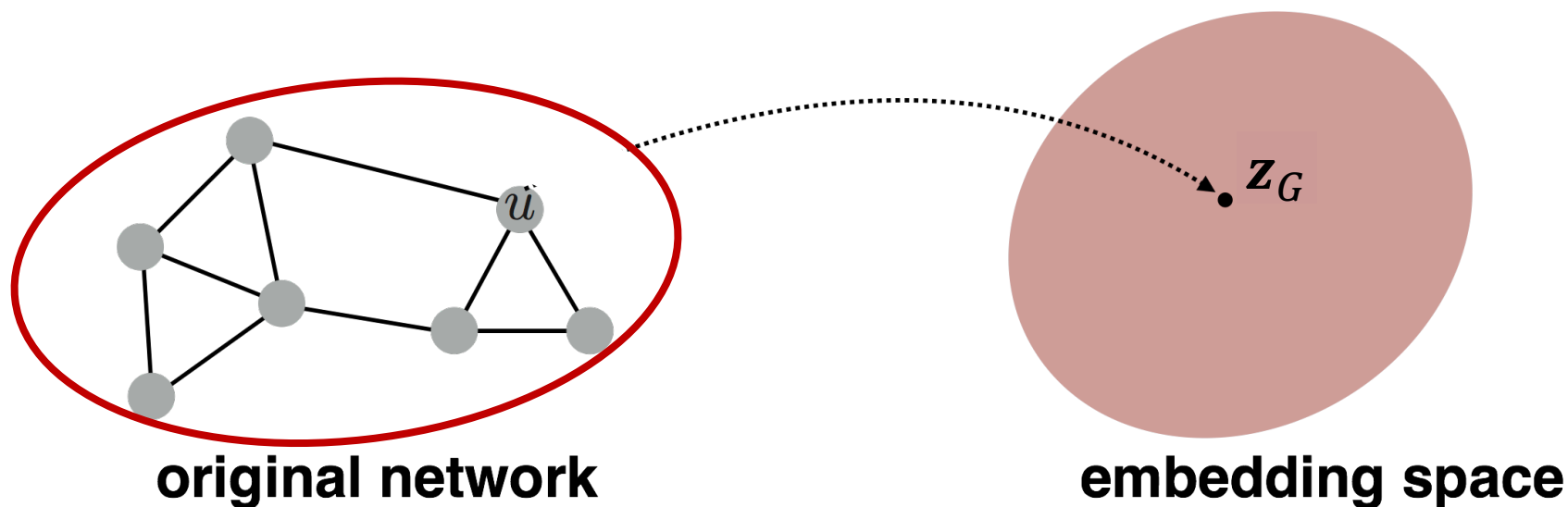
- Classifying toxic vs. non-toxic molecules
- Identifying cancerogenic molecules
- Graph anomaly detection
- Classifying social networks

Graph Classification



# Embedding Entire Graphs

- **Goal:** Want to embed an entire graph  $G$



# Approach 1

## Simple idea:

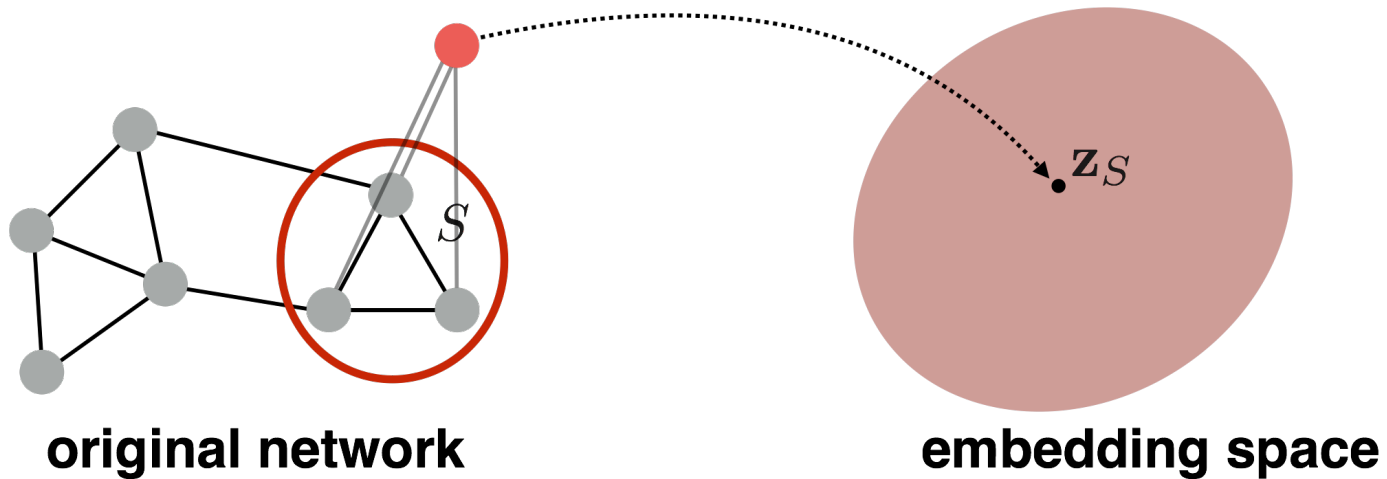
- Run a standard node embedding technique *on* the (sub)graph  $G$
- Then just sum (or average) the node embeddings in the (sub)graph  $G$

$$z_G = \sum_{v \in G} z_v$$

- Used by [Duvenaud et al., 2016](#) to classify molecules based on their graph structure

# Approach 2

- **Idea:** Introduce a “**virtual node**” to represent the (sub)graph and run a standard graph embedding technique



- Proposed by [Li et al., 2016](#) as a general technique for subgraph embedding