

CSEP 573: Artificial Intelligence

Winter 2016

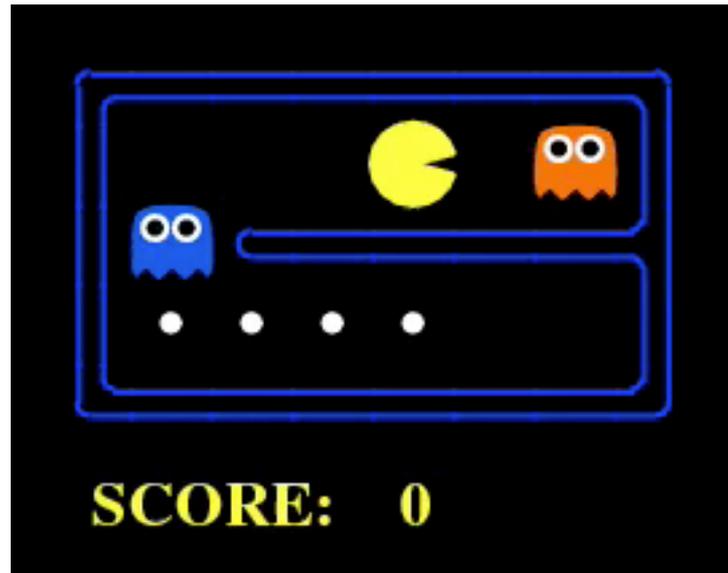
Expectimax Search

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Based on slides from Dan Klein, Ali Farhadi

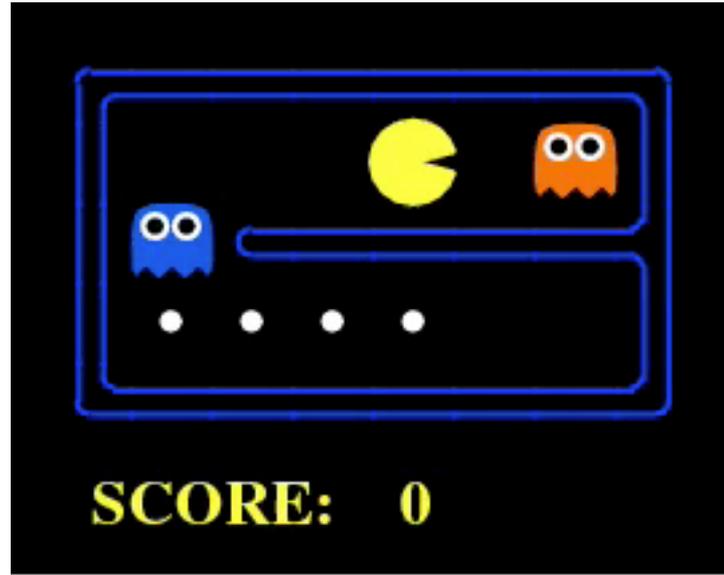
Many slides over the course adapted from either Stuart Russell
or Andrew Moore

Minimax Example



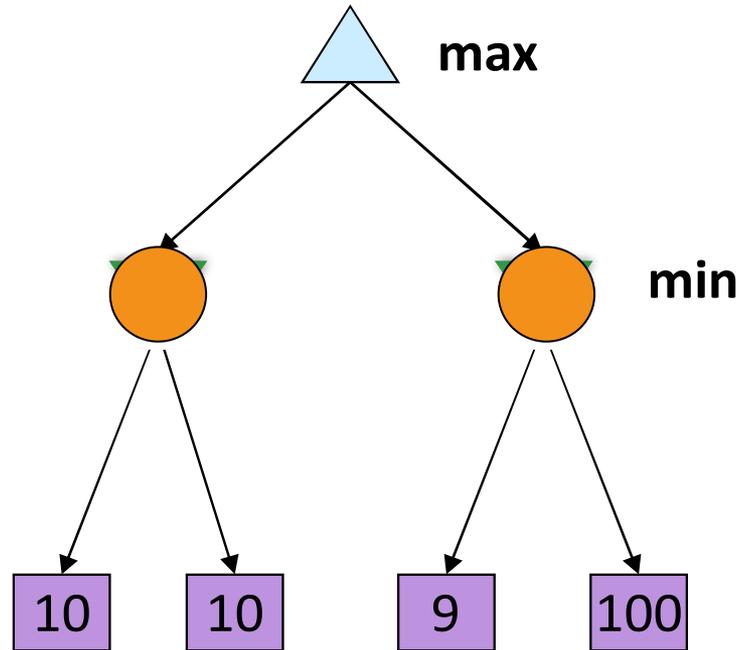
Suicidal agent

Expectimax



- Uncertain outcomes are controlled by chance not an adversary
- Chance nodes are new types of nodes (instead of Min nodes)

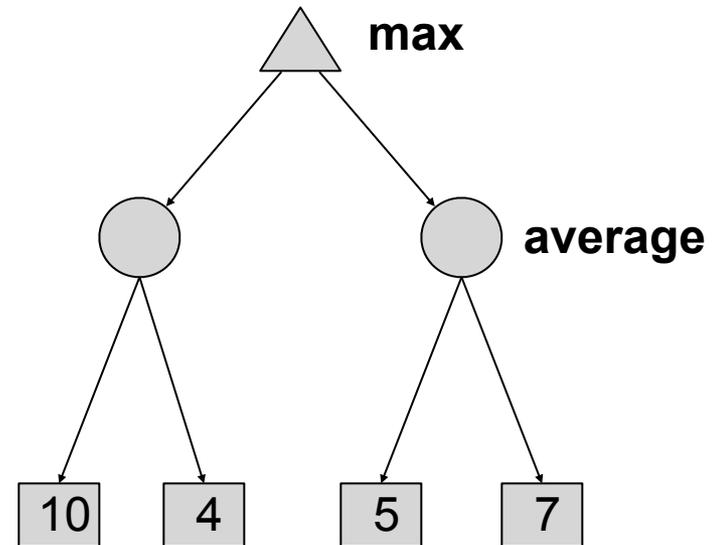
Worst-case vs. Average



- Uncertain outcomes controlled by chance not an adversary

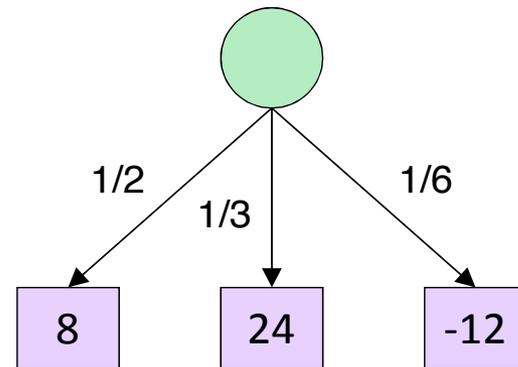
Stochastic Single-Player

- What if we don't know what the result of an action will be? E.g.,
 - In solitaire, shuffle is unknown
 - In minesweeper, mine locations
- Can do **expectimax search**
 - Chance nodes, like actions except the environment controls the action chosen
 - Max nodes as before
 - Chance nodes take average (expectation) of value of children



Expectimax Pseudocode

```
def exp-value(state):  
    initialize v = 0  
    for each successor of state:  
        p = probability(successor)  
        v += p * value(successor)  
    return v
```



$$v = (1/2)(8) + (1/3)(24) + (1/6)(-12)$$

Maximum Expected Utility

- Why should we average utilities? Why not minimax?
- Principle of maximum expected utility: an agent should choose the action which **maximizes its expected utility, given its knowledge**
 - General principle for decision making
 - Often taken as the definition of rationality
 - We'll see this idea over and over in this course!
- Let's decompress this definition...

Reminder: Probabilities

- A **random variable** represents an event whose outcome is unknown
- A **probability distribution** is an assignment of weights to outcomes
- Example: traffic on freeway?
 - Random variable: T = whether there's traffic
 - Outcomes: T in {none, light, heavy}
 - Distribution: $P(T=\text{none}) = 0.25$, $P(T=\text{light}) = 0.55$, $P(T=\text{heavy}) = 0.20$
- Some laws of probability (more later):
 - Probabilities are always non-negative
 - Probabilities over all possible outcomes sum to one
- As we get more evidence, probabilities may change:
 - $P(T=\text{heavy}) = 0.20$, $P(T=\text{heavy} \mid \text{Hour}=8\text{am}) = 0.60$
 - We'll talk about methods for reasoning and updating probabilities later

What are Probabilities?

- **Objectivist / frequentist answer:**
 - Averages over repeated *experiments*
 - E.g. empirically estimating $P(\text{rain})$ from historical observation
 - E.g. pacman's estimate of what the ghost will do, given what it has done in the past
 - Assertion about how future experiments will go (in the limit)
 - Makes one think of *inherently random* events, like rolling dice
- **Subjectivist / Bayesian answer:**
 - Degrees of belief about unobserved variables
 - E.g. an agent's belief that it's raining, given the temperature
 - E.g. pacman's belief that the ghost will turn left, given the state
 - Often *learn* probabilities from past experiences (more later)
 - New evidence *updates beliefs* (more later)

Uncertainty Everywhere

- Not just for games of chance!
 - I'm sick: will I sneeze this minute?
 - Email contains "FREE!": is it spam?
 - Tooth hurts: have cavity?
 - 60 min enough to get to the airport?
 - Robot rotated wheel three times, how far did it advance?
 - Safe to cross street? (Look both ways!)
- Sources of uncertainty in random variables:
 - Inherently random process (dice, etc)
 - Insufficient or weak evidence
 - Ignorance of underlying processes
 - Unmodeled variables
 - The world's just noisy – it doesn't behave according to plan!

Reminder: Expectations

- We can define function $f(X)$ of a random variable X
- The expected value of a function is its average value, weighted by the probability distribution over inputs
- Example: How long to get to the airport?
 - Length of driving time as a function of traffic:
 $L(\text{none}) = 20$, $L(\text{light}) = 30$, $L(\text{heavy}) = 60$
 - What is my expected driving time?
 - Notation: $E_{P(T)}[L(T)]$
 - Remember, $P(T) = \{\text{none: } 0.25, \text{light: } 0.5, \text{heavy: } 0.25\}$
 - $E[L(T)] = L(\text{none}) * P(\text{none}) + L(\text{light}) * P(\text{light}) + L(\text{heavy}) * P(\text{heavy})$
 - $E[L(T)] = (20 * 0.25) + (30 * 0.5) + (60 * 0.25) = 35$

Review: Expectations

- Real valued functions of random variables:

$$f : X \rightarrow R$$

- Expectation of a function of a random variable

$$E_{P(X)}[f(X)] = \sum_x f(x)P(x)$$

- Example: Expected value of a fair die roll

X	P	f
1	1/6	1
2	1/6	2
3	1/6	3
4	1/6	4
5	1/6	5
6	1/6	6

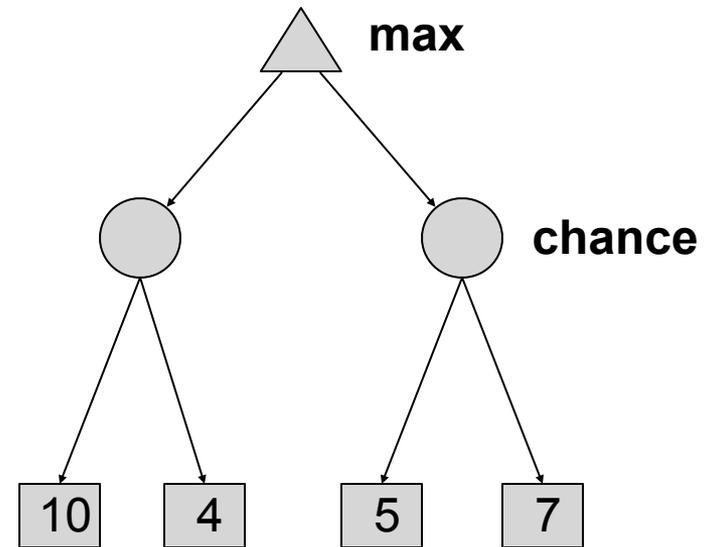
$$1 \times \frac{1}{6} + 2 \times \frac{1}{6} + 3 \times \frac{1}{6} + 4 \times \frac{1}{6} + 5 \times \frac{1}{6} + 6 \times \frac{1}{6} \\ = 3.5$$

Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences
- Where do utilities come from?
 - In a game, may be simple (+1/-1)
 - Utilities summarize the agent's goals
 - Theorem: any set of preferences between outcomes can be summarized as a utility function (provided the preferences meet certain conditions)
- In general, we hard-wire utilities and let actions emerge
- More on utilities soon...

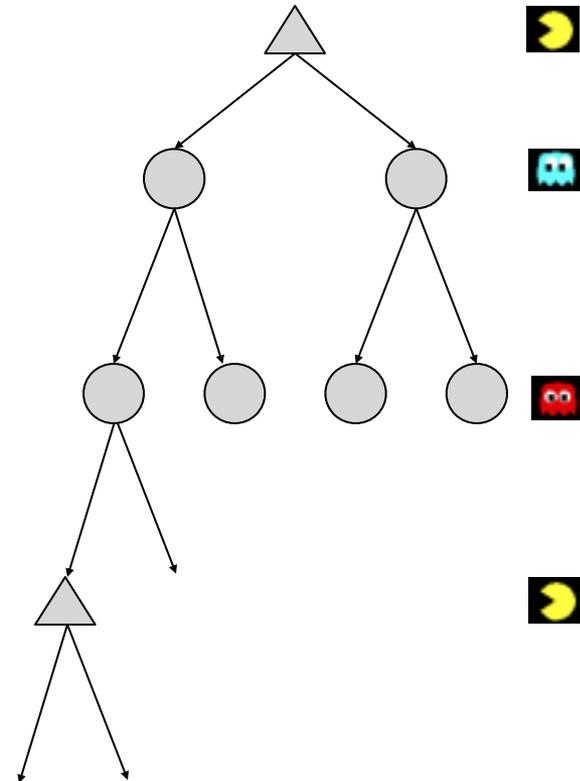
Expectimax Search Trees

- What if we don't know what the result of an action will be? E.g.,
 - In solitaire, next card is unknown
 - In minesweeper, mine locations
 - In pacman, the ghosts act randomly
- Can do **expectimax search**
 - Chance nodes, like min nodes, except the outcome is uncertain
 - Calculate **expected utilities**
 - Max nodes as in minimax search
 - Chance nodes take average (expectation) of value of children
- Later, we'll learn how to formalize the underlying problem as a **Markov Decision Process**

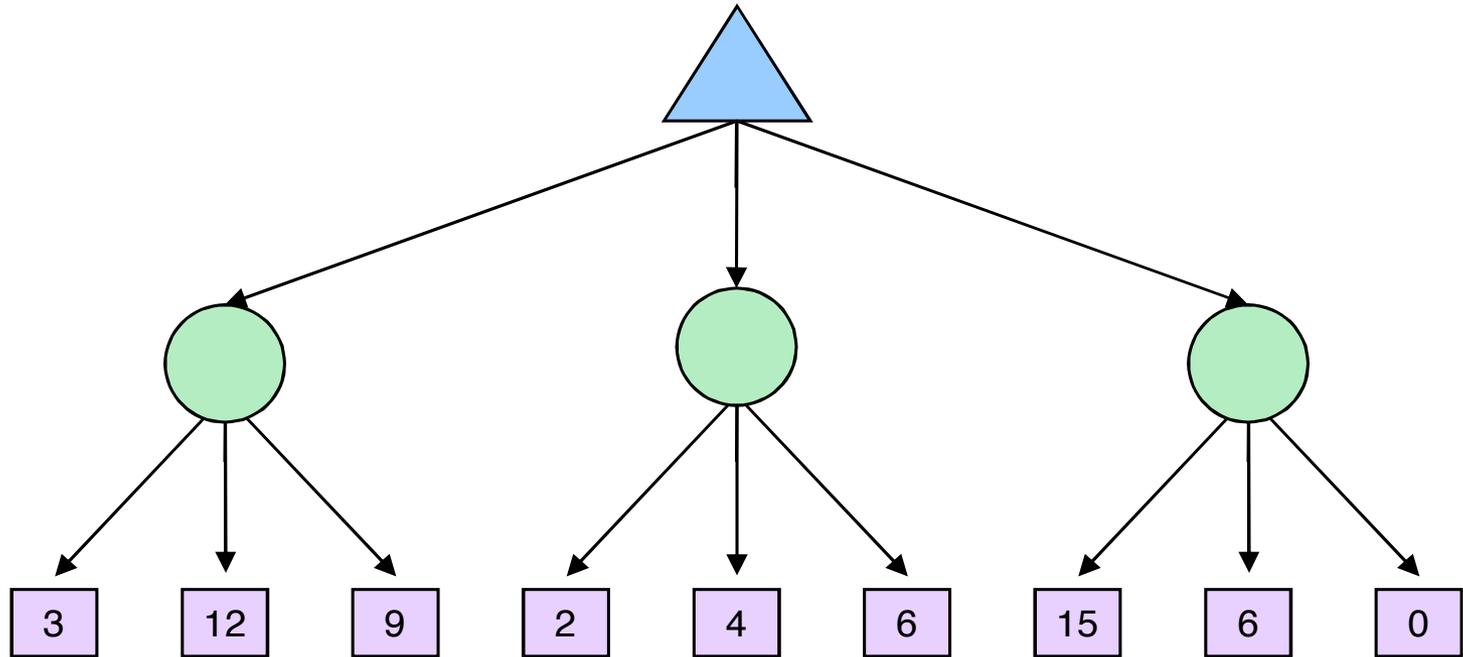


Expectimax Search

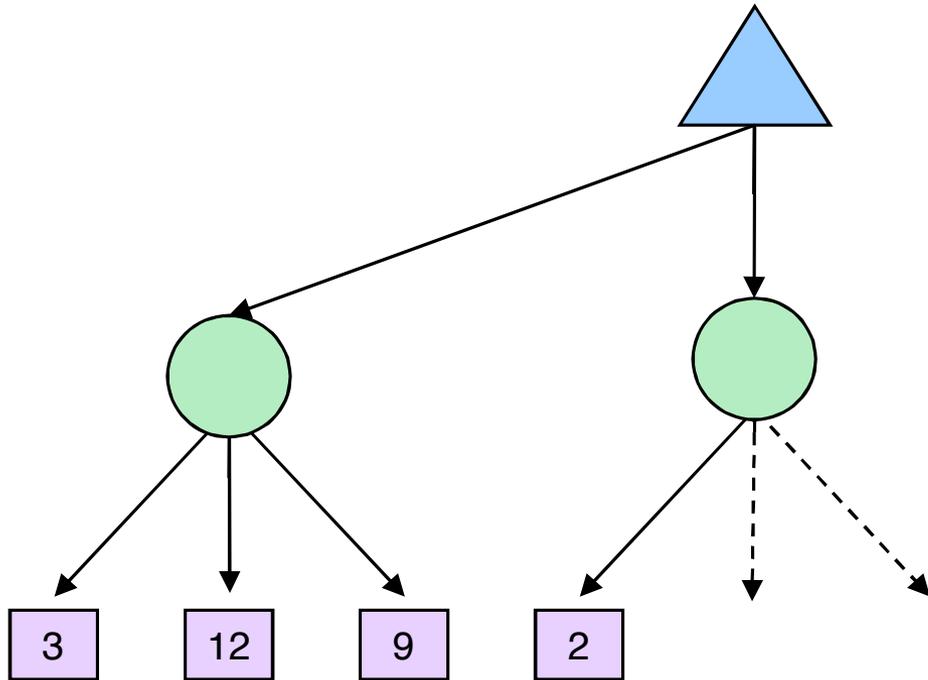
- In expectimax search, we have a probabilistic model of how the opponent (or environment) will behave in any state
 - Model could be a simple uniform distribution (roll a die)
 - Model could be sophisticated and require a great deal of computation
 - We have a node for every outcome out of our control: opponent or environment
 - The model might say that adversarial actions are likely!
- For now, assume for any state we magically have a distribution to assign probabilities to opponent actions / environment outcomes



Expectimax Pruning

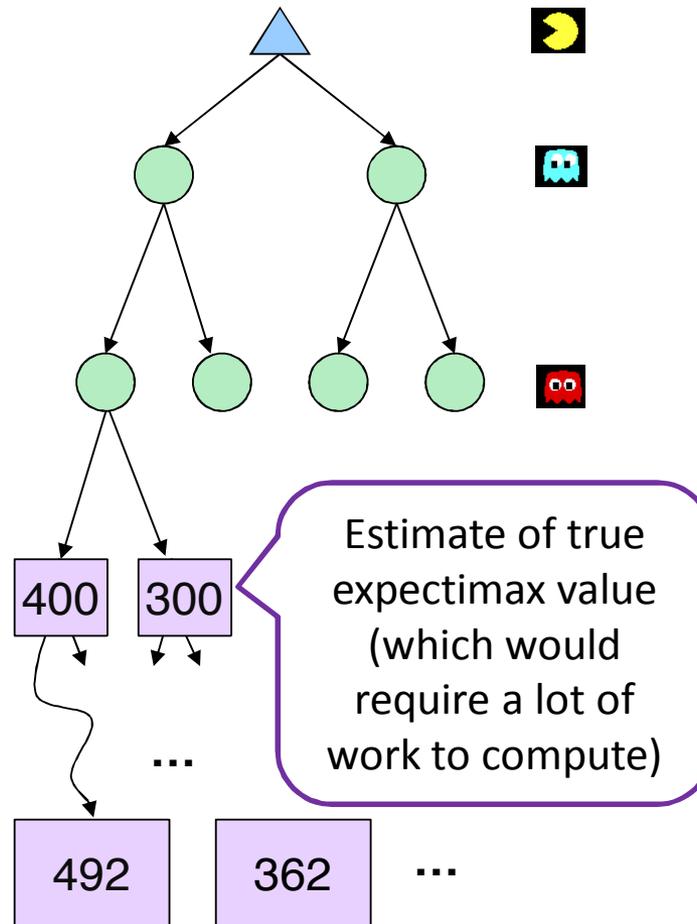


Expectimax Pruning



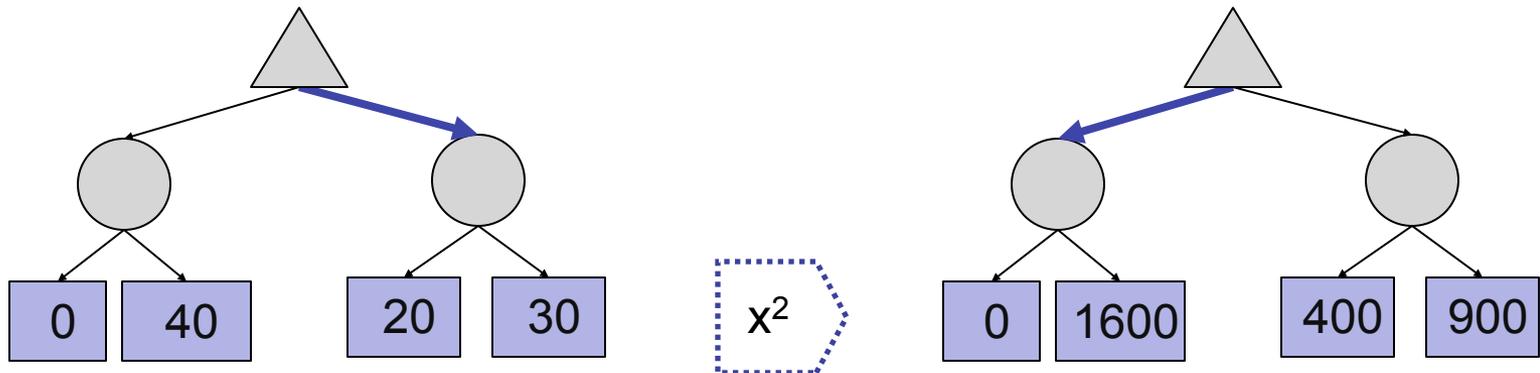
- Not easy
 - exact: need bounds on possible values
 - approximate: sample high-probability branches

Depth-limited Expectimax



Expectimax Evaluation

- Evaluation functions quickly return an estimate for a node's true value (which value, expectimax or minimax?)
- For minimax, evaluation function scale doesn't matter
 - We just want better states to have higher evaluations (get the ordering right)
 - We call this **insensitivity to monotonic transformations**
- For expectimax, we need *magnitudes* to be meaningful

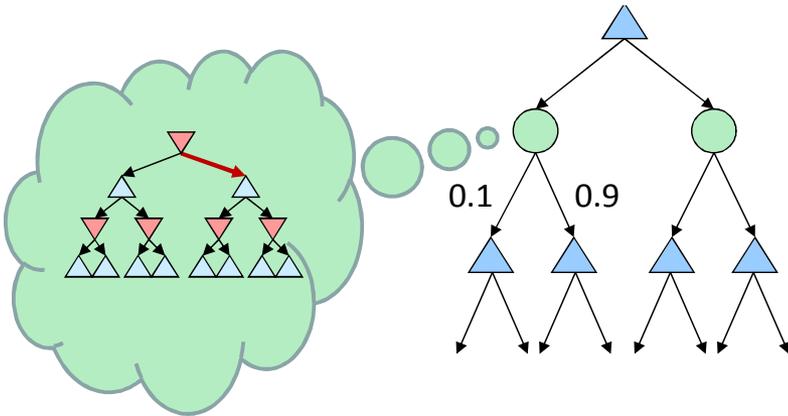


Expectimax for Pacman

- Notice that we've gotten away from thinking that the ghosts are trying to minimize pacman's score
- Instead, they are now a part of the environment
- Pacman has a belief (distribution) over how they will act
- Quiz: Can we see minimax as a special case of expectimax?

Quiz

- Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise
- Question: What tree search should you use?



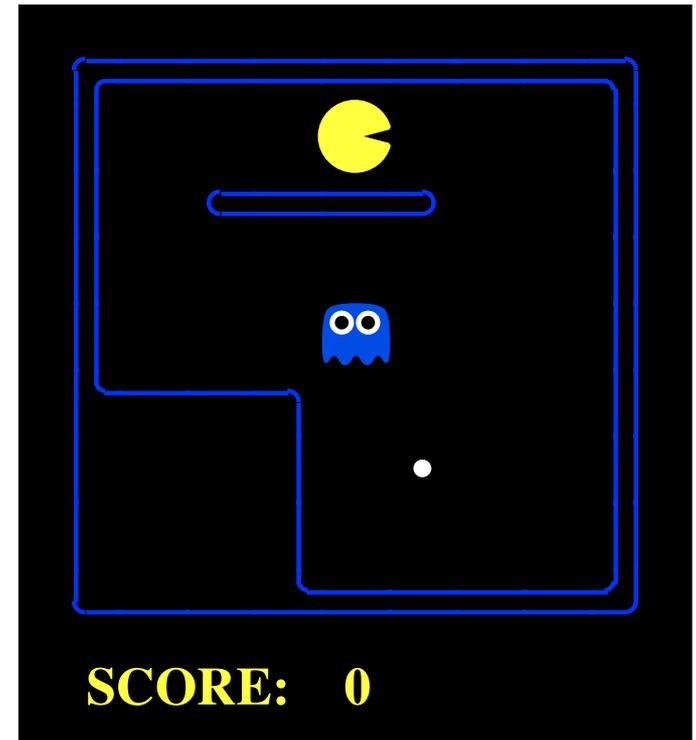
- **Answer: Expectimax!**

- To figure out EACH chance node's probabilities, you have to run a simulation of your opponent
- This kind of thing gets very slow very quickly
- Even worse if you have to simulate your opponent simulating you...
- ... except for minimax, which has the nice property that it all collapses into one game tree

Expectimax for Pacman

Results from playing 5 games

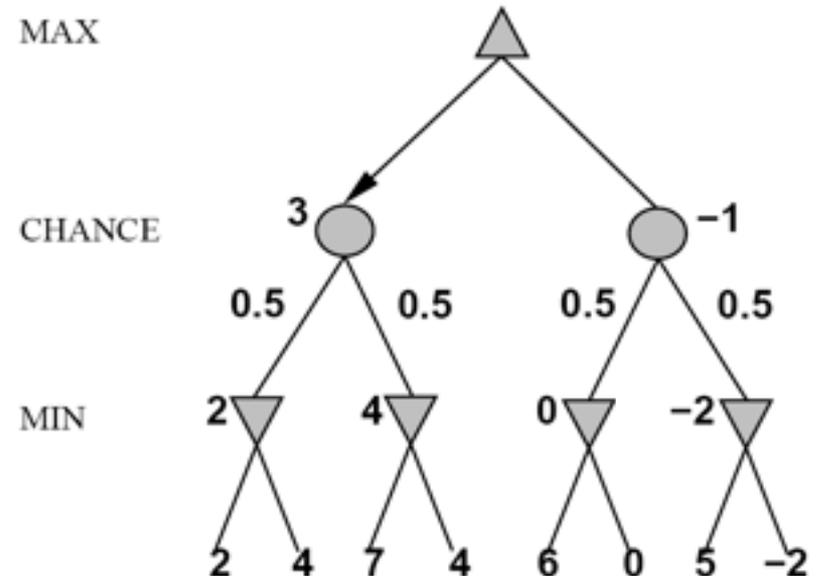
	Minimizing Ghost	Random Ghost
Minimax Pacman	Won 5/5 Avg. Score: 493	Won 5/5 Avg. Score: 483
Expectimax Pacman	Won 1/5 Avg. Score: -303	Won 5/5 Avg. Score: 503



Pacman does depth 4 search with an eval function that avoids trouble
Minimizing ghost does depth 2 search with an eval function that seeks Pacman

Mixed Layer Types

- E.g. Backgammon
- Expectiminimax
 - Environment is an extra player that moves after each agent
 - Chance nodes take expectations, otherwise like minimax



if *state* is a MAX node then

return the highest EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)

if *state* is a MIN node then

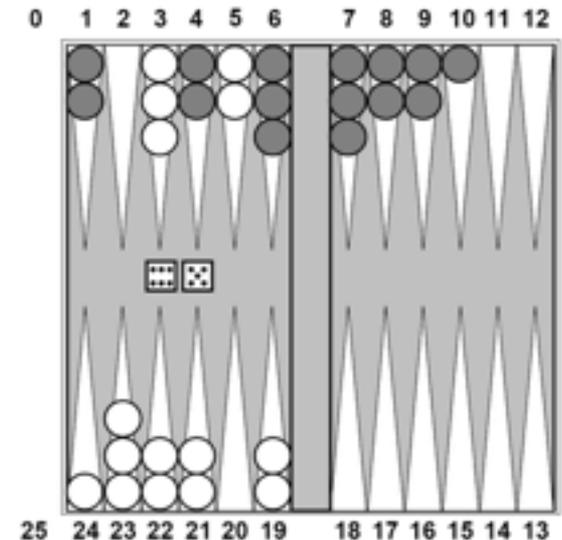
return the lowest EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)

if *state* is a chance node then

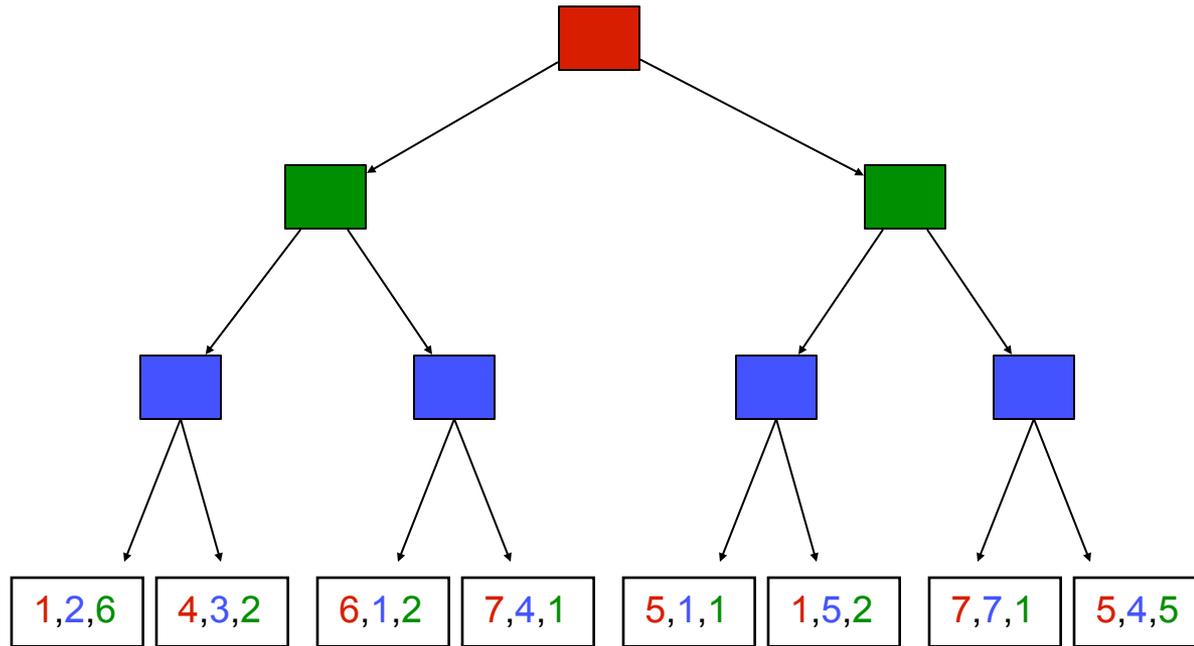
return average of EXPECTIMINIMAX-VALUE of SUCCESSORS(*state*)

Stochastic Two-Player

- Dice rolls increase b : 21 possible rolls with 2 dice
 - Backgammon \approx 20 legal moves
 - Depth 4 = $20 \times (21 \times 20)^3 \approx 1.2 \times 10^9$
- As depth increases, probability of reaching a given node shrinks
 - So value of lookahead is diminished
 - So limiting depth is less damaging
 - But pruning is less possible...
- TDGammon uses depth-2 search + very good eval function + reinforcement learning: world-champion level play



Multi-player Non-Zero-Sum Games



- Similar to minimax:
 - Utilities are now tuples
 - Each player maximizes their own entry at each node
 - Propagate (or back up) nodes from children
 - Can give rise to cooperation and competition dynamically...