Ray Tracer

CSEP557 2019 Spring

Ray Tracer

- Given a ray "caster", you have to implement:
 - Shading
 - Reflection and Refraction
 - Sphere Intersection
 - Triangle Intersection
 - Complex objects consist of a 3D mesh made up of triangles
 - Anti-Aliasing
- In this project, you will implement all of these!

Requirements

- Sphere intersection
- Triangle intersection
- Barycentric interpolation of Normals and UVs (for Trimesh)
- Blinn-Phong Specular-Reflection Shading Model
- Light Contribution
- Shadow attenuation
- Reflection
- Refraction
- Anti-Aliasing

The Debugger Tool

• USE THIS, IT WILL SAVE YOUR LIFE!

- Click a pixel in your rendered frame, and observe the scene view in the UI, it will show
 - Reflection Rays (if happened)
 - Refraction Rays (if happened)
 - Normal (at the intersection points)
 - Shadow/Light rays (intersection point to the light source)
 - COP ray (intersection point to the COP)

The Debugger Tool

• Demo



2) Observe scene view



Requirement: Sphere Intersection

- Fill in Sphere::IntersectLocal in scene\components\sphere.cpp
- The sphere is centered at the origin with radius 0.5
- If the ray r intersects this sphere:
 - 1) Put the hit parameter in i.t
 - 2) Put the normal in i.normal
 - 3) Put the texture coordinates in i.uv (Not a Requirement;You will get 1 whistle if you implement this)
 - 4) Return true

Requirement: Triangle Intersection

- Fill in TriangleFace::IntersectLocal in Scene\components\triangleface.cpp
- See the <u>triangle-intersection handout</u> to get all equations you need.

Requirement: Triangle Intersection

- Access triangle vertices (class members)
 - glm::dvec3 a, b, c
- Interpolate normal and UV
 - Barycentric interpolation
- If the ray r intersects this sphere:
 - 1) Put the hit parameter in i.t
 - 2) Put the normal in i.normal
 - 3) Put the texture coordinates in i.uv
 - 4) Return true

Requirement: Blinn-Phong Specular-Reflection Model

Refer to the lecture slides to get the formula

$$I_{\text{direct}} = k_e + \sum_j k_d I_{La,j} + A_j^{\text{shadow}} A_j^{\text{dist}} I_{L,j} B_j \left(k_d (\mathbf{N} \cdot \mathbf{L}_j) + k_s (\mathbf{N} \cdot \mathbf{H}_j)_+^{n_s} \right)$$
$$A_j^{\text{dist}} = \min\left(1, \frac{1}{a_j r_j^2 + b_j r_j + c_j} \right)$$

Requirement: Light Contributions

- To sum over the light sources, use a for loop to iterate all light sources as described in the code
- Access the light
 - Light* scene_light = trace_light->light
- Determine the type of light
 - Use dynamic casting

```
if (PointLight* point_light = dynamic_cast<PointLight*>(scene_light)) {
    // do something
} else if (DirectionalLight* directional_light = dynamic_cast<DirectionalLight*>(scene_light)) {
    // do something
}
```

Requirement: Light Contributions

- For Point Light: Get Light Position
 - TraceLight::GetTransformPos()
- For Directional Light: Get Light Direction
 - TraceLight::GetTransformDirection

Requirement: Light Contributions

- For Point Light:
 - Consider Distance Attenuation
 - First, check if the light type is AttenuatingLight

if (AttenuatingLight* attenuating_light = dynamic_cast<AttenuatingLight*>(scene_light))

- Second, get a, b, and c
 - a = attenuating_light->AttenA.Get();
 - b = attenuating_light->AttenB.Get();
 - c = attenuating_light->AttenC.Get();

Requirement: Shadow Attenuation

- Rather than simply setting the attenuation to zero if an object blocks the light, accumulate the product of k_t's for objects which block the light
- See lecture slides to get more details

Requirement: Reflection

- Modify RayTracer::TraceRay in raytracer.cpp to implement recursive ray tracing
- Get reflection direction

$$\mathbf{R} = 2(\mathbf{V} \cdot \mathbf{N})\mathbf{N} - \mathbf{V}$$

Consider UI setting in your implementation

```
if (settings.reflections)
{
    // Put your reflection codes here
}
```

Requirement: Refraction

- Apply Snell's law
- Get refraction direction

$$\eta = \frac{\eta_i}{\eta_t}$$
$$\cos \theta_i = \mathbf{N} \cdot \mathbf{V}$$
$$\cos \theta_t = \sqrt{1 - \eta^2 (1 - \cos^2 \theta_i)}$$
$$\mathbf{T} = (\eta \cos \theta_i - \cos \theta_t) \mathbf{N} - \eta \mathbf{V}$$

Note that Total Internal Reflection (TIR) occurs when the square root term above is negative.

Requirement: Refraction

- Watch out for total internal refraction
- Consider the case when the ray is exiting a material into air (think about the direction of the normal)
- Consider UI setting in your implementation

```
if (settings.refractions)
{
    // Put your refraction codes here
}
```

Direct + Indirect Illumination

Direct Illumination + Reflection + Refraction

 $I_{\text{total}} = I_{\text{direct}} + k_r I_{\text{reflectedRay}} + k_t I_{\text{transmittedRay}}$ Use Ks (specular coefficients) in our case

Requirement: Anti-Aliasing

- Gets rid of jaggies
- Implement using oversampling.
 - Equally divide each pixel, trace the ray, and average the results

Requirement: Anti-Aliasing

• Fill code in Raytracer::ComputePixel(...)

```
switch (settings.samplecount_mode) {
    case Camera::TRACESAMPLING_CONSTANT:
        // Put Your anti-alasing code here
        color = SampleCamera(x_corner, y_corner, settings.pixel_size_x, settings.pixel_size_y, debug_camera);
        break;
    default:
        break;
}
```

- Get the number of samples you need to shoot in each pixel
 - Settings.constant_samples_per_pixel
- Call SampleCamera() when shooting a ray at different positions of a pixel.

Data Structure: Ray

- Direction: r.direction
- Position: r.position
- r.at(t) r.position + (t * r.direction)
 - Returns the end position of the ray r after going a distance of t from its start position

Take Care of Normals

- Interpolated Normal
 - Used for shading

glm::vec3 N = i.normal;

- True/Geometric Normal
 - Used for everything except for shading, like entering/leaving a object, computing reflection/refraction rays

glm::vec3 GeometricN = i.GetTrueNormal();

Take Care of Normals

- Flip both (interpolated and true) normals if you are on the inside of an object, for any shading, reflection, or refraction.
 - As we said before, use True Normal to determine if you're a on the inside/outside the object (i.e. use the sign of glm::dot(-r.direction, GeometricN))

Test Your Implementation

- Start from simpler case: assets/trace/simple
 - Sphere: sphere_xxx.yaml
 - Trimesh: box_xxx.yaml, cube_xxx.yaml
 - Texture: texture_reflection.yaml
 - Distance attenuation: box_dist_atten.yaml
 - Opaque shadow: box_cyl_opaque_shadow.yaml
 - Transparent shadow:
 - box_cyl_trans_shadow.yaml, cube_transparent.yaml
 - Reflection
 - box_cyl_reflect.yaml, texture_reflection.yaml
 - Refraction
 - box_cyl_trans_shadow.yaml, cube_transparent.yaml
 - cylinder_refract.yaml, sphere_refract.yaml

Test Your Implementation

- Then test more complicated case in
 - assets/trace/trimeshes
 - assets/trace/more
 - In particular, try
 - trimeshes/revolution_texture.yaml to see your trimesh texture
 - more/lecture.yaml to see the effect of direct illumination + reflection + refraction
 - trimeshes/dragon.yaml to test your anti-aliasing

Tips and Tricks

- Don't write too much code without testing!
 - Lots of dependencies, think carefully before writing any codes
- Use RAY_EPSILON (which is defined as 0.00001) to account for computer precision error when checking for intersections



Memory Leaks

- A memory leak can (and probably will) ruin your night hours before your artifact is due
- To test, try to ray trace a complex model (the dragon) with depth 10, anti-aliasing, HUGE Image
- Cause: not calling free after allocating memory
 - Object constructors, vector (array) creation
- Solution: free stuff!
 - Call the "delete [object]" on ANYTHING you create that is temporary
 - i.e. 3 byte temporary vectors in the rayTrace function
- It is HIGHLY RECOMMENDED you have no memory leaks

Comparison Tool

- We will be using this tool (link on the course webpage) to evaluate your solution versus the sample. So you should check too !!
- See the class announcement letter and course page for the details
 - Will announce this soon ...

That's all. Good luck!