# Ray Tracer 

CSEP557 2019 Spring

## Ray Tracer

- Given a ray "caster", you have to implement:
- Shading
- Reflection and Refraction
- Sphere Intersection
- Triangle Intersection
- Complex objects consist of a 3D mesh made up of triangles
- Anti-Aliasing
- In this project, you will implement all of these!


## Requirements

- Sphere intersection
- Triangle intersection
- Barycentric interpolation of Normals and UVs (for Trimesh)
- Blinn-Phong Specular-Reflection Shading Model
- Light Contribution
- Shadow attenuation
- Reflection
- Refraction
- Anti-Aliasing


## The Debugger Tool

- USE THIS, IT WILL SAVE YOUR LIFE!
- Click a pixel in your rendered frame, and observe the scene view in the UI, it will show
- Reflection Rays (if happened)
- Refraction Rays (if happened)
- Normal (at the intersection points)
- Shadow/Light rays (intersection point to the light source)
- COP ray (intersection point to the COP)


## The Debugger Tool

- Demo



## Requirement: Sphere Intersection

- Fill in Sphere::IntersectLocal in scene\components\sphere.cpp
- The sphere is centered at the origin with radius 0.5
- If the ray $r$ intersects this sphere:

1) Put the hit parameter in i.t
2) Put the normal in i.normal
3) Put the texture coordinates in i.uv (Not a Requirement; You will get 1 whistle if you implement this)
4) Return true

## Requirement: Triangle Intersection

- Fill in TriangleFace::IntersectLocal in Scene\components\triangleface.cpp
- See the triangle-intersection handout to get all equations you need.


## Requirement: Triangle Intersection

- Access triangle vertices (class members)
- glm::dvec3 a, b, c
- Interpolate normal and UV
- Barycentric interpolation
- If the ray $r$ intersects this sphere:

1) Put the hit parameter in i.t
2) Put the normal in i.normal
3) Put the texture coordinates in i.uv
4) Return true

## Requirement: Blinn-Phong Specular-Reflection Model

- Refer to the lecture slides to get the formula

$$
\begin{gathered}
I_{\text {direct }}=k_{e}+\sum_{j} k_{d} I_{L a, j}+A_{j}^{\text {shadow }} A_{j}^{\text {dist }} I_{L, j} B_{j}\left(k_{d}\left(\mathbf{N} \cdot \mathbf{L}_{j}\right)+k_{s}\left(\mathbf{N} \cdot \mathbf{H}_{j}\right)_{+}^{n_{s}}\right) \\
A_{j}^{\text {dist }}=\min \left(1, \frac{1}{a_{j} r_{j}^{2}+b_{j} r_{j}+c_{j}}\right)
\end{gathered}
$$

## Requirement: Light Contributions

- To sum over the light sources, use a for loop to iterate all light sources as described in the code
- Access the light
- Light* scene_light = trace_light->light
- Determine the type of light
- Use dynamic casting

```
if (PointLight* point_light = dynamic_cast<PointLight*>(scene_light)) {
} else if (DirectionalLight* directional_light = dynamic_cast<DirectionalLight*>(scene_light)) {
}
```


## Requirement: Light Contributions

- For Point Light: Get Light Position
- TraceLight::GetTransformPos()
- For Directional Light: Get Light Direction
- TraceLight::GetTransformDirection


## Requirement: Light Contributions

- For Point Light:
- Consider Distance Attenuation
- First, check if the light type is AttenuatingLight
if (AttenuatingLight* attenuating_light = dynamic_cast<AttenuatingLight*>(scene_light))
- Second, get a, b, and c

$$
\begin{aligned}
& \mathrm{a}=\text { attenuating_light->AttenA.Get(); } \\
& \mathrm{b}=\text { attenuating_light->AttenB.Get( }) ; \\
& \mathrm{c}=\text { attenuating_light->AttenC.Get(); }
\end{aligned}
$$

## Requirement: Shadow Attenuation

- Rather than simply setting the attenuation to zero if an object blocks the light, accumulate the product of k_t's for objects which block the light
- See lecture slides to get more details


## Requirement: Reflection

- Modify RayTracer::TraceRay in raytracer.cpp to implement recursive ray tracing
- Get reflection direction

$$
\mathbf{R}=2(\mathbf{V} \cdot \mathbf{N}) \mathbf{N}-\mathbf{V}
$$

- Consider UI setting in your implementation

```
if (settings.reflections)
    // Put your reflection codes here
```


## Requirement: Refraction

- Apply Snell's law
- Get refraction direction

$$
\begin{gathered}
\eta=\frac{\eta_{i}}{\eta_{t}} \\
\cos \theta_{i}=\mathbf{N} \cdot \mathbf{V} \\
\cos \theta_{t}=\sqrt{1-\eta^{2}\left(1-\cos ^{2} \theta_{i}\right)} \\
\mathbf{T}=\left(\eta \cos \theta_{i}-\cos \theta_{t}\right) \mathbf{N}-\eta \mathbf{V}
\end{gathered}
$$

Note that Total Internal Reflection (TIR) occurs when the square root term above is negative.

## Requirement: Refraction

- Watch out for total internal refraction
- Consider the case when the ray is exiting a material into air (think about the direction of the normal)
- Consider UI setting in your implementation



## Direct + Indirect Illumination

- Direct Illumination + Reflection + Refraction

$$
I_{\text {total }}=I_{\text {direct }}+k_{r} I_{\text {reflectedRay }}+k_{t} I_{\text {transmittedRay }}
$$

Use Ks (specular coefficients) in our case

## Requirement: Anti-Aliasing

- Gets rid of jaggies
- Implement using oversampling.
- Equally divide each pixel, trace the ray, and average the results


## Requirement: Anti-Aliasing

- Fill code in Raytracer::ComputePixel(...)
color $=$ SampleCamera(x_corner, y_corner, settings.pixel_size_x, settings.pixel_size_y, debug_camera);
break;
default:
break;
- Get the number of samples you need to shoot in each pixel
- Settings.constant_samples_per_pixel
- Call SampleCamera() when shooting a ray at different positions of a pixel.


## Data Structure: Ray

- Direction: r.direction
- Position: r.position
- r.at(t) - r.position + (t * r.direction)
- Returns the end position of the ray $r$ after going a distance of t from its start position


## Take Care of Normals

- Interpolated Normal
- Used for shading
glm::vec3 N = i.normal;
- True/Geometric Normal
- Used for everything except for shading, like entering/leaving a object, computing reflection/refraction rays
glm::vec3 GeometricN = i.GetTrueNormal();


## Take Care of Normals

- Flip both (interpolated and true) normals if you are on the inside of an object, for any shading, reflection, or refraction.
- As we said before, use True Normal to determine if you're a on the inside/outside the object (i.e. use the sign of glm::dot(-r.direction, GeometricN))


## Test Your Implementation

- Start from simpler case: assets/trace/simple
- Sphere: sphere_xxx.yaml
- Trimesh: box_xxx.yaml, cube_xxx.yaml
- Texture: texture_reflection.yaml
- Distance attenuation: box_dist_atten.yaml
- Opaque shadow: box_cyl_opaque_shadow.yaml
- Transparent shadow:
- box_cyl_trans_shadow.yaml, cube_transparent.yaml
- Reflection
- box_cyl_reflect.yaml, texture_reflection.yaml
- Refraction
- box_cyl_trans_shadow.yaml, cube_transparent.yaml
- cylinder_refract.yaml, sphere_refract.yaml


## Test Your Implementation

- Then test more complicated case in
- assets/trace/trimeshes
- assets/trace/more
- In particular, try
- trimeshes/revolution_texture.yaml to see your trimesh texture
- more/lecture.yaml to see the effect of direct illumination + reflection + refraction
- trimeshes/dragon.yaml to test your anti-aliasing


## Tips and Tricks

- Don't write too much code without testing!
- Lots of dependencies, think carefully before writing any codes
- Use RAY_EPSILON (which is defined as 0.00001) to account for computer precision error when checking for intersections



## Memory Leaks

- A memory leak can (and probably will) ruin your night hours before your artifact is due
- To test, try to ray trace a complex model (the dragon) with depth 10, anti-aliasing, HUGE Image
- Cause: not calling free after allocating memory
- Object constructors, vector (array) creation
- Solution: free stuff!
- Call the "delete [object]" on ANYTHING you create that is temporary
- i.e. 3 byte temporary vectors in the rayTrace function
- It is HIGHLY RECOMMENDED you have no memory leaks


## Comparison Tool

- We will be using this tool (link on the course webpage) to evaluate your solution versus the sample. So you should check too !!
- See the class announcement letter and course page for the details
- Will announce this soon ...

That's all. Good luck!

