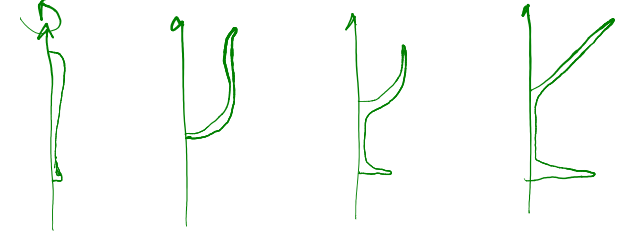


Surfaces of Revolution

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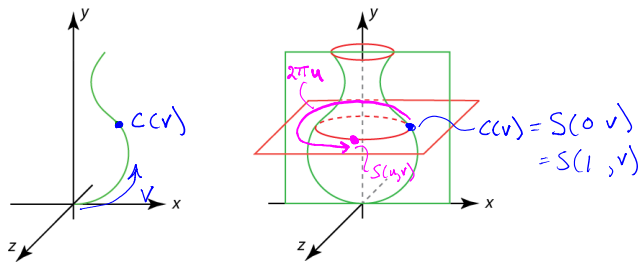
Surfaces of revolution



Idea: rotate a 2D **profile curve** around an axis.

What kinds of shapes can you model this way?

Constructing surfaces of revolution



Given: A curve $C(v)$ in the xy -plane:

$$C(v) = \begin{bmatrix} C_x(v) \\ C_y(v) \\ 0 \\ 1 \end{bmatrix}$$

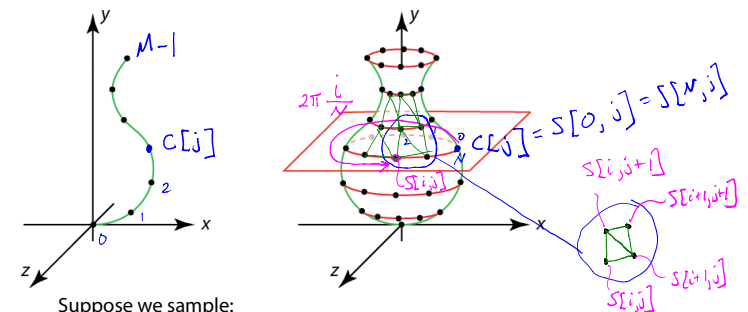
Let $R_y(\theta)$ be a rotation about the y -axis.

Find: A surface $S(u, v)$ which is $C(v)$ rotated about the y -axis, where $u, v \in [0, 1]$.

Solution: $S(u, v) = R_y(2\pi u) C(v)$

Constructing surfaces of revolution

We can sample in u and v to get a grid of points over the surface.



Suppose we sample:

- in v , to give $C[j]$ where $j \in [0..M-1]$
- in u , to give rotation angle $\theta[i] = 2\pi i/N$ where $i \in [0..N]$

We can now write the surface as:

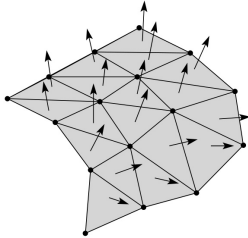
$$S[i, j] = R_y\left(\frac{2\pi i}{N}\right) C[j]$$

How would we turn this into a mesh of triangles?
How do we assign per-vertex normals?

Surface normals

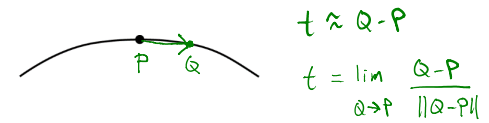
Now that we describe the surface as a triangle mesh, we need to provide surface normals. As we'll see later, these normals are important for drawing and shading the surface (i.e., for "rendering").

One approach is to compute the normal to each triangle. How do we compute these normals?



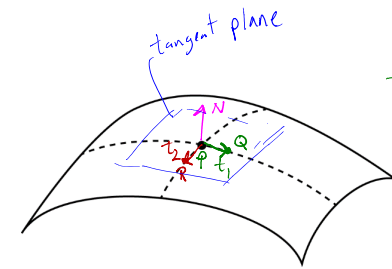
For surfaces of revolution, we can get better-looking results by analytically computing the normal at each vertex...

Tangent vectors, tangent planes, and normals



$$t \approx Q - P$$

$$t = \lim_{Q \rightarrow P} \frac{Q - P}{\|Q - P\|}$$

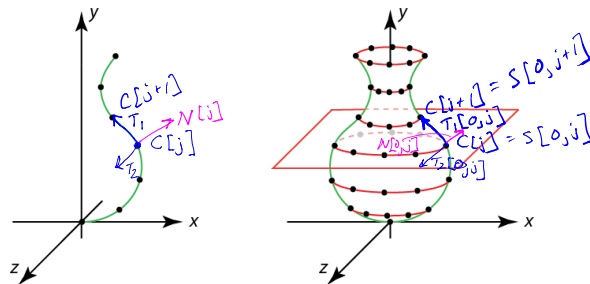


$$t_1 \approx Q - P$$

$$t_2 \approx R - P$$

$$N = \frac{t_2 \times t_1}{\|t_2 \times t_1\|}$$

Normals on a surface of revolution



We can compute tangents to the curve points in the x - y plane:

$$T_1[0, j] \approx C[j+1] - C[j]$$

$$T_2[0, j] = [0 \ 0 \ 1]^T$$

to get the normal in that plane:

$$N[0, j] = T_1[0, j] \times T_2[0, j] \leftarrow \text{normalize this}$$

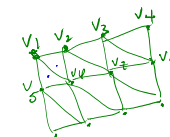
and then rotate it around:

$$N[i, j] = R_y(2\pi \frac{i}{n}) N[0, j]$$

Triangle meshes

How should we generally represent triangle meshes?

Δ by Δ list
 V_1, N_1
 V_5, N_5
 V_4, N_0



vertex list + Δ index list

V_1, N_1	1, 5, 6
V_2, N_2	1, 6, 2
V_3, N_3	
V_4, N_4	
V_5, N_5	
V_6, N_0	

Do this

Summary

What to take away from this lecture:

- ♦ All the names in boldface.
- ♦ How to compute a surface of revolution given a profile curve.
- ♦ How to represent a surface of revolution as a triangle mesh.
- ♦ How to compute per-vertex normals for a surface of revolution.