

13. Texture Mapping

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Reading

Required

- ♦ Watt, intro to Chapter 8 and intros to 8.1, 8.4, 8.6, 8.8.

Recommended

- ♦ Paul S. Heckbert. Survey of texture mapping. **IEEE Computer Graphics and Applications** 6(11): 56--67, November 1986.

Optional

- ♦ Watt, the rest of Chapter 8
- ♦ Woo, Neider, & Davis, Chapter 9
- ♦ James F. Blinn and Martin E. Newell. Texture and reflection in computer generated images. **Communications of the ACM** 19(10): 542--547, October 1976.

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Texture mapping



Texture mapping (Woo et al., fig. 9-1)

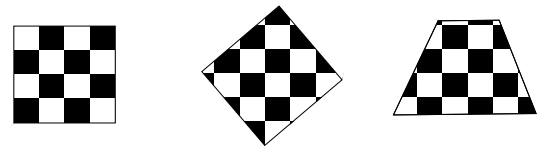
Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.

- ♦ Due to Ed Catmull, PhD thesis, 1974
- ♦ Refined by Blinn & Newell, 1976

Texture mapping ensures that “all the right things” happen as a textured polygon is transformed and rendered.

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Non-parametric texture mapping

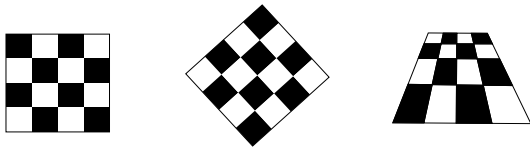


With “non-parametric texture mapping”:

- ♦ Texture size and orientation are fixed
- ♦ They are unrelated to size and orientation of polygon
- ♦ Gives cookie-cutter effect

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Parametric texture mapping



With “parametric texture mapping,” texture size and orientation are tied to the polygon.

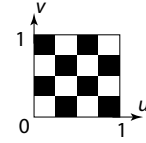
Idea:

- ◆ Separate “texture space” and “screen space”
- ◆ Texture the polygon as before, but in texture space
- ◆ Deform (render) the textured polygon into screen space

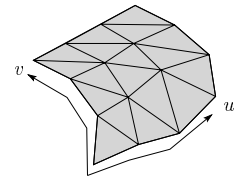
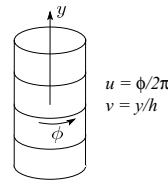
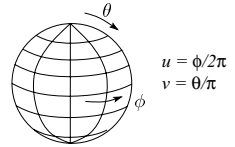
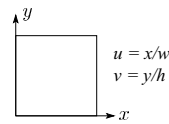
A texture can modulate just about any parameter – diffuse color, specular color, specular exponent, ...

Implementing texture mapping

A texture lives in its own image coordinates parameterized by (u,v) in the range $([0..1], [0..1])$:



It can be wrapped around many different surfaces:



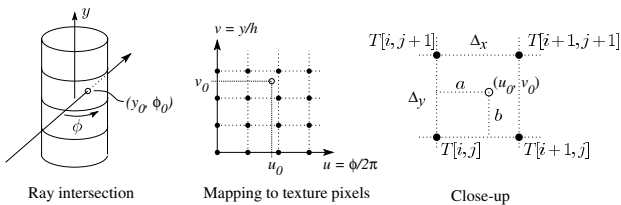
Computing (u,v) texture coordinates in a ray tracer is fairly straightforward.

Note: if the surface moves/deforms, the texture goes with it.

Texture resampling

The texture is usually stored as an image.

Q: What do you do when the texture sample you need lands between texture pixels?



Where:

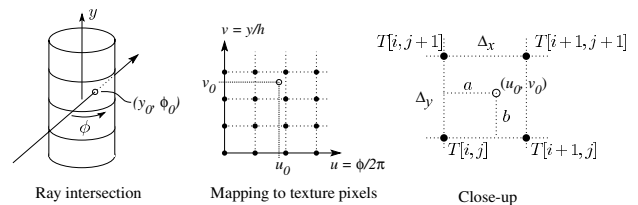
$$(u_0, v_0) = (i\Delta_x + a\Delta_x, j\Delta_y + b\Delta_y)$$

$$\Delta_x = 1/w_{\text{tex}}$$

$$\Delta_y = 1/h_{\text{tex}}$$

Texture resampling

To get the “in between” values, we need to **resample** the texture.



A common choice is **bilinear resampling**:

$$T(u_0, v_0) = T(i\Delta_x + a\Delta_x, j\Delta_y + b\Delta_y)$$

$$= \text{_____} T[i, j] +$$

$$\text{_____} T[i+1, j] +$$

$$\text{_____} T[i, j+1] +$$

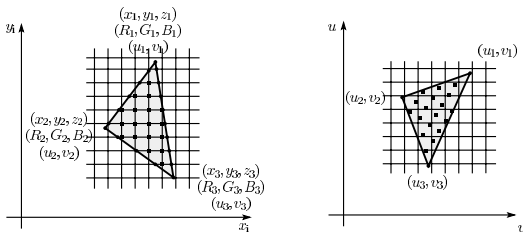
$$\text{_____} T[i+1, j+1]$$

Texture mapping and the z-buffer

Texture-mapping can also be handled in z-buffer algorithms.

Method:

- Scan conversion is done in screen space, as usual
- Each pixel is colored according to the texture
- Texture coordinates are found by Gouraud-style interpolation

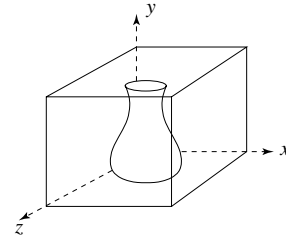


Note: Mapping is more complicated if you want to do perspective right!

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Solid textures

Q: What kinds of artifacts might you see from using a marble veneer instead of real marble?



One solution is to use **solid textures**:

- Use model-space coordinates to index into a 3D texture
- Like “carving” the object from the material

One difficulty of solid texturing is coming up with the textures.

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Solid textures (cont'd)

Here's an example for a vase cut from a solid marble texture:



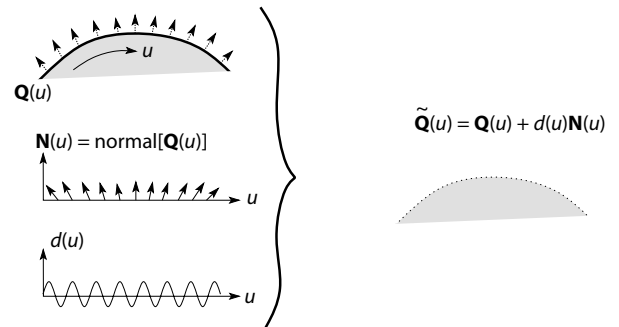
Solid marble texture by Ken Perlin, (Foley, IV-21)

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Displacement mapping

Textures can be used for more than just color.

In **displacement mapping**, a texture is used to perturb the surface geometry itself:



- These displacements “animate” with the surface

Q: Do you have to do hidden surface calculations on $\tilde{\mathbf{Q}}$?

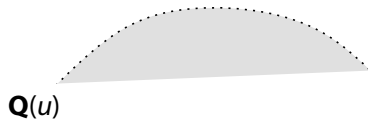
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Bump mapping

In **bump mapping**, a texture is used to perturb the normal:

- ♦ Use the original, simpler geometry, $Q(u)$, for hidden surfaces
- ♦ Use the normal from the displacement map for shading:

$$\tilde{\mathbf{N}} = \text{normal}[\tilde{Q}(u)]$$

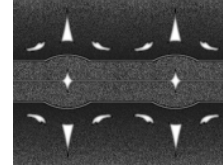


Q: What artifacts in the images would reveal that bump mapping is a fake?

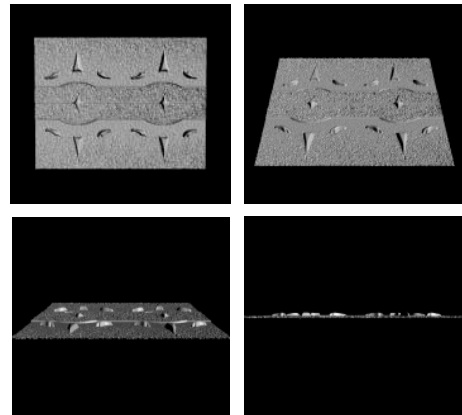
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Displacement vs. bump mapping

Input texture

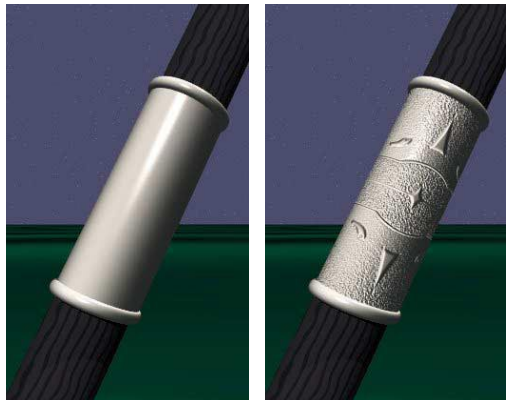


Rendered as displacement map over a rectangular surface



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Displacement vs. bump mapping (cont'd)



Original rendering

Rendering with bump map wrapped around a cylinder

Bump map and rendering by Wyvern Aldinger

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Environment mapping



In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:

- ♦ Rays are bounced off objects into environment
- ♦ Color of the environment used to determine color of the illumination
- ♦ Really, a simplified form of ray tracing
- ♦ Environment mapping works well when there is just a single object – or in conjunction with ray tracing

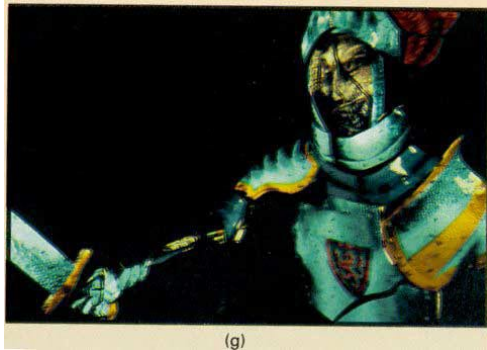
Under simplifying assumptions, environment mapping can be implemented in hardware.

With a ray tracer, the concept is easily extended to handle refraction as well as reflection.

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Combining texture maps

Using texture maps in combination gives even better effects, as *Young Sherlock Holmes* demonstrated ...



(g)
Construction of the glass knight, (Foley, IV-24)

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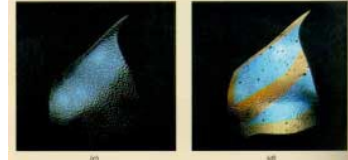
Combining texture maps (cont'd)

Phong lighting with diffuse texture



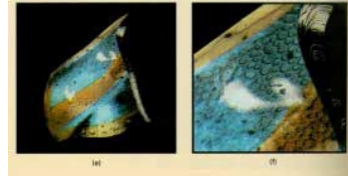
Environment-mapped mirror reflection

Bump mapping + Glossy reflection



Combine textures and add dirt

Rivet stains + Shinier reflections



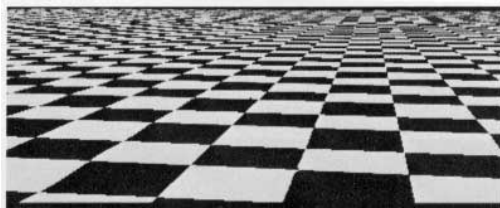
Close-up

Construction of the glass knight, (Foley, IV-24)

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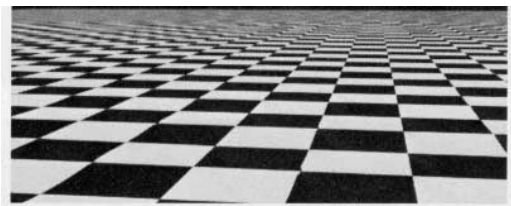
Antialiasing

If you point-sample the texture map, you get aliasing:



From Crow, SIGGRAPH '84

Proper antialiasing requires area averaging in the texture:



From Crow, SIGGRAPH '84

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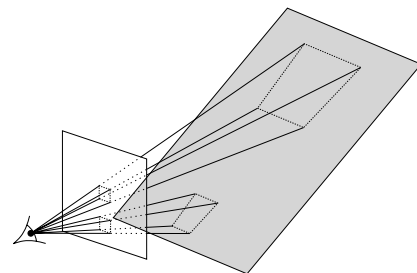
Computing the average color

The computationally difficult part is summing over the covered pixels.

Several methods have been used:

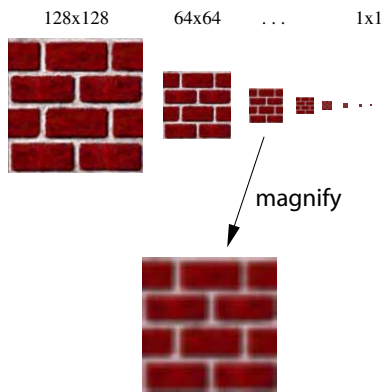
The simplest is **brute force**:

- ◆ Figure out which texels are covered and add up their colors to compute the average.



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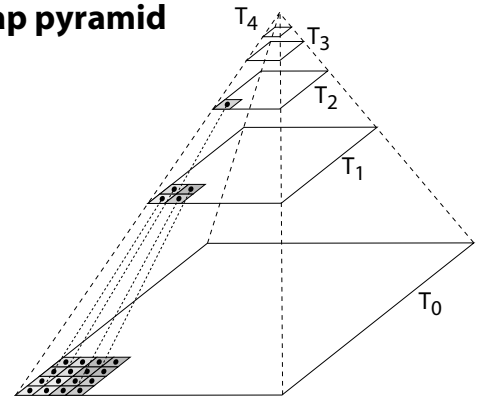
Mip maps



A faster method is **mip maps** developed by Lance Williams in 1983:

- Stands for “multum in parvo” – many things in a small place
- Keep textures prefiltered at multiple resolutions
- Has become the graphics hardware standard

Mip map pyramid

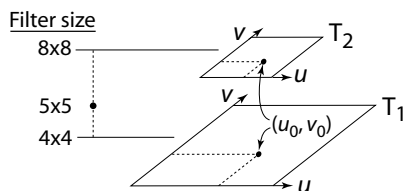


The mip map hierarchy can be thought of as an image pyramid:

- Level 0 ($T_0[i,j]$) is the original image.
- Level 1 ($T_1[i,j]$) averages over 2×2 neighborhoods of original.
- Level 2 ($T_2[i,j]$) averages over 4×4 neighborhoods of original
- Level 3 ($T_3[i,j]$) averages over 8×8 neighborhoods of original

What's a fast way to pre-compute the texture map for each level?

Mip map resampling



What would the mip-map return for an average over a 5×5 neighborhood at location (u_0, v_0) ?

How do we measure the fractional distance between levels?

What if you need to average over a non-square region?

Summed area tables

A more accurate method than mip maps is **summed area tables** invented by Frank Crow in 1984.

Recall from calculus:

$$\int_a^b f(x) dx = \int_{-\infty}^b f(x) dx - \int_{-\infty}^a f(x) dx$$

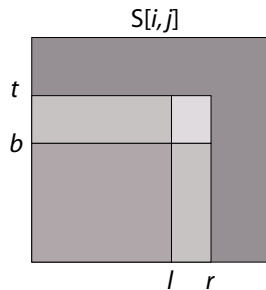
In discrete form:

$$\sum_{i=k}^m f[i] = \sum_{i=0}^m f[i] - \sum_{i=0}^k f[i]$$

Q: If we wanted to do this real fast, what might we pre-compute?

Summed area tables (cont'd)

We can extend this idea to 2D by creating a table, $S[i,j]$, that contains the sum of everything below and to the left.



Q: How do we compute the average over a region from (l, b) to (r, t) ?

Characteristics:

- ◆ Requires more memory
- ◆ Gives less blurry textures

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Comparison of techniques

Point sampled

MIP-mapped

Summed area table

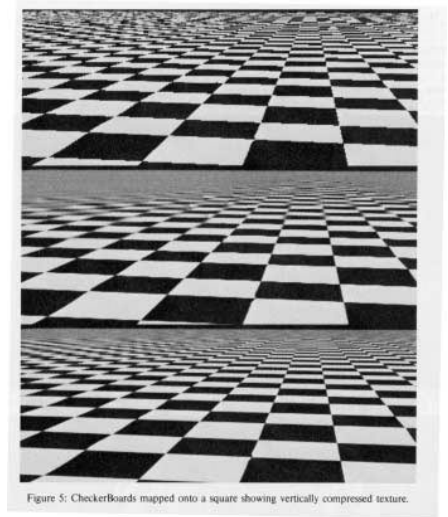


Figure 5: Checkerboards mapped onto a square showing vertically compressed texture.

From Crow, SIGGRAPH '84

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Summary

What to take home from this lecture:

1. The meaning of the boldfaced terms.
2. Familiarity with the various kinds of texture mapping, including their strengths and limitations.
3. Understanding of the various approaches to antialiased texture mapping:
 - ◆ Brute force
 - ◆ Mip maps
 - ◆ Summed area tables

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