Lecture 8: Query Execution

Wednesday, November 17, 2010

Outline

- · Relational Algebra: Ch. 4.2
- Overview of query evaluation: Ch. 12
- Evaluating relational operators: Ch. 14

The WHAT and the HOW

 In SQL we write WHAT we want to get form the data

- The database system needs to figure out HOW to get the data we want
- The passage from WHAT to HOW goes through the Relational Algebra

Data

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SQL = WHAT

Product(<u>pid</u>, name, price)
Purchase(<u>pid</u>, <u>cid</u>, store)
Customer(<u>cid</u>, name, city)

SELECT DISTINCT x.name, z.name
FROM Product x, Purchase y, Customer z
WHERE x.pid = y.pid and y.cid = y.cid and
x.price > 100 and z.city = 'Seattle'

It's clear WHAT we want, unclear HOW to get it

Relational Algebra = HOW

Final answer Product(pid, name, price) Purchase(pid, cid, store) T4(name,name) Customer(cid, name, city) x.name,z.name T3(...) T2(. . . .) σ price>100 and city='Seattle' T1(pid,name,price,pid,cid,store) cid=cid Temporary pid=pid tables Customer T1, T2, . . . **Purchase** 5 **Product**

Relational Algebra = HOW

The order is now clearly specified:

```
Iterate over PRODUCT...
...join with PURCHASE...
...join with CUSTOMER...
...select tuples with Price>100 and
City='Seattle'...
...eliminate duplicates...
and that's the final answer!
```

Sets v.s. Bags

- Sets: {a,b,c}, {a,d,e,f}, { }, . . .
- Bags: {a, a, b, c}, {b, b, b, b, b}, . . .

Relational Algebra has two semantics:

- Set semantics
- Bag semantics

Extended Algebra Operators

- Union ^ , intersection ⁻ , difference -
- · Selection o
- Projection □
- · Join 🔀
- · Rename p
- Duplicate elimination δ
- Grouping and aggregation γ
- · Sorting τ

Relational Algebra (1/3)

The Basic Five operators:

- · Union: ^
- · Difference: -
- · Selection: σ
- · Projection: ∏
- · Join:

Relational Algebra (2/3)

Derived or auxiliary operators:

- · Renaming: p
- · Intersection, complement
- Variations of joins
 - natural, equi-join, theta join, semi-join, cartesian product

Relational Algebra (3/3)

Extensions for bags:

- · Duplicate elimination: δ
- Group by: γ
- · Sorting: τ

Union and Difference

What do they mean over bags?

What about Intersection?

Derived operator using minus

$$R1 = R2 = R1 - (R1 - R2)$$

· Derived using join will explain later)

$$R1 = R2 = R1 \bowtie R2$$

Selection

 Returns all tuples which satisfy a condition

- Examples
 - σSalary > 40000 (Employee)
 - σname = "Smith" (Employee)
- · The condition c can be =, <, ᅰ, >, ᇁ, <>

Employee

SSN	Name	Salary
1234545	John	200000
5423341	Smith	600000
4352342	Fred	500000

σSalary > 40000 (Employee)

SSN	Name	Salary
5423341	Smith	600000
4352342	Fred	500000

Projection

Eliminates columns

$$\Pi$$
 A1,...,An(R)

- Example: project social-security number and names:
 - Π SSN, Name (Employee)
 - Answer(SSN, Name)

Semantics differs over set or over

bags

Employee

SSN	Name	Salary
1234545	John	20000
5423341	John	60000
4352342	John	20000

 Π Name, Salary (Employee)

Name	Salary
John	20000
John	60000
John	20000

Name	Salary
John	20000
John	60000

Bag semantics

Set semantics

Which is more efficient to implement?

Cartesian Product

Each tuple in R1 with each tuple in R2

 Very rare in practice; mainly used to express joins

Employee

Dependent

Name	SSN
John	99999999
Tony	77777777

EmpSSN	DepName
99999999	Emily
77777777	Joe

Employee X Dependent

Name	SSN	EmpSSN	DepName
John	99999999	99999999	Emily
John	99999999	77777777	Joe
Tony	77777777	99999999	Emily
Tony	77777777	77777777	Joe

Renaming

· Changes the schema, not the instance

- · Example:
 - ρN, S(Employee) _ Answer(N, S)

Natural Join

• Meaning: R1 \bowtie R2 = Π A(σ (R1 × R2))

- · Where:
 - The selection σ checks equality of all common attributes
 - The projection eliminates the duplicate common attributes

Natural Join

R

Α	В
X	Υ
X	Z
Υ	Z
Z	V

S

В	С
Z	U
V	W
Z	V

 $R \bowtie S = \Pi ABC(\sigma R.B=S.B(R \times S))$

Α	В	С
X	Z	U
X	Z	V
Y	Z	U
Υ	Z	V
Z	V	W

Natural Join

Given the schemas R(A, B, C, D), S(A, C, E), what is the schema of R ⋈ S?

Given R(A, B, C), S(D, E), what is R \bowtie S?

• Given R(A, B), S(A, B), what is R \bowtie S?

Theta Join

· A join that involves a predicate

$$R1 \bowtie \theta R2 = \sigma \theta (R1 = R2)$$

• Here θ can be any condition

Eq-join

• A theta join where θ is an equality

$$R1 \bowtie A=B R2 = \sigma A=B (R1 = R2)$$

 This is by far the most used variant of join in practice

So Which Join Is It?

 When we write R ⋈ S we usually mean an eq-join, but we often omit the equality predicate when it is clear from the context

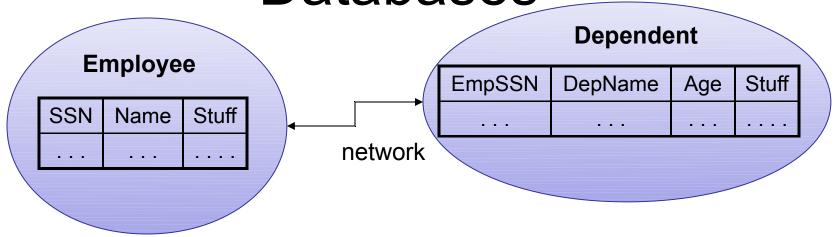
Semijoin

$$R \bowtie C S = \prod A1,...,An (R \bowtie C S)$$

· Where A1, ..., An are the attributes in R

Formally, R KC S means this: retain from R only those tuples that have some matching tuple in S

- Duplicates in R are preserved
- Duplicates in S don't matter



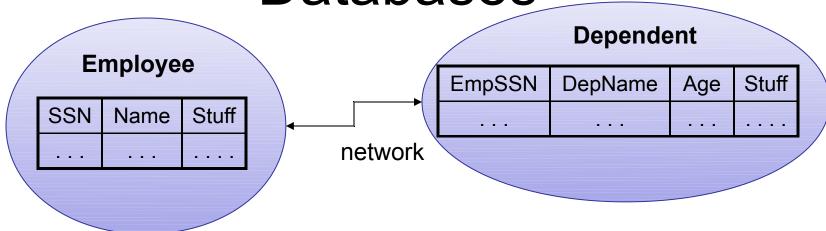
Employee ⊠SSN=EmpSSN (σ age>71 (Depender

Assumptions: Very few Employees have dependents.

Very few dependents have age > 71.

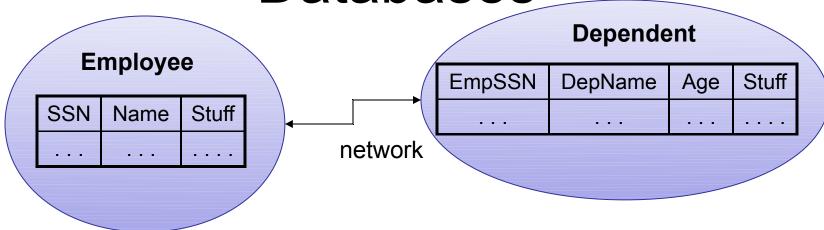
"Stuff" is big.

Task: compute the query with minimum amount of data transfer



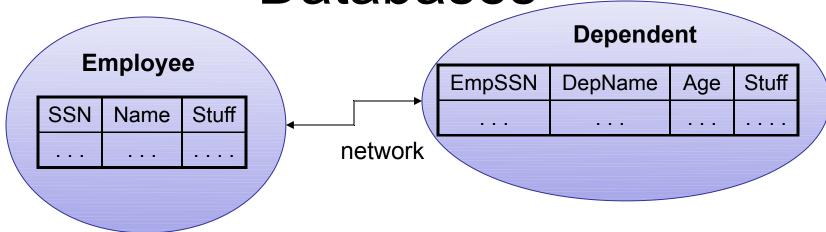
Employee ⊠SSN=EmpSSN (σ age>71 (Depender

 $T(SSN) = \Pi SSN \sigma age>71 (Dependents)$

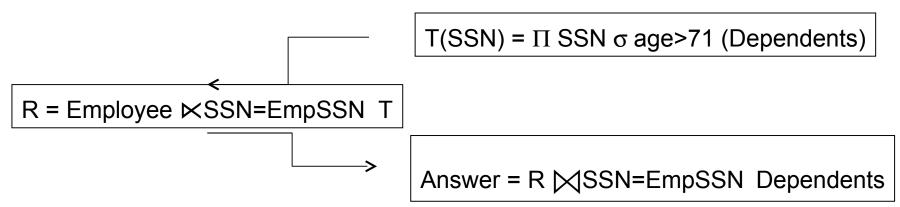


Employee ⊠SSN=EmpSSN (σ age>71 (Depender

```
T(SSN) = Π SSN σ age>71 (Dependents)
R = \text{Employee} \bowtie \text{SSN=EmpSSN T}
= \text{Employee} \bowtie \text{SSN=EmpSSN (σ age>71 (Dependents))}
30
```



Employee ⊠SSN=EmpSSN (σ age>71 (Depender



Joins R US

The join operation in all its variants (eqjoin, natural join, semi-join, outer-join) is at the *heart* of relational database systems

· WHY?

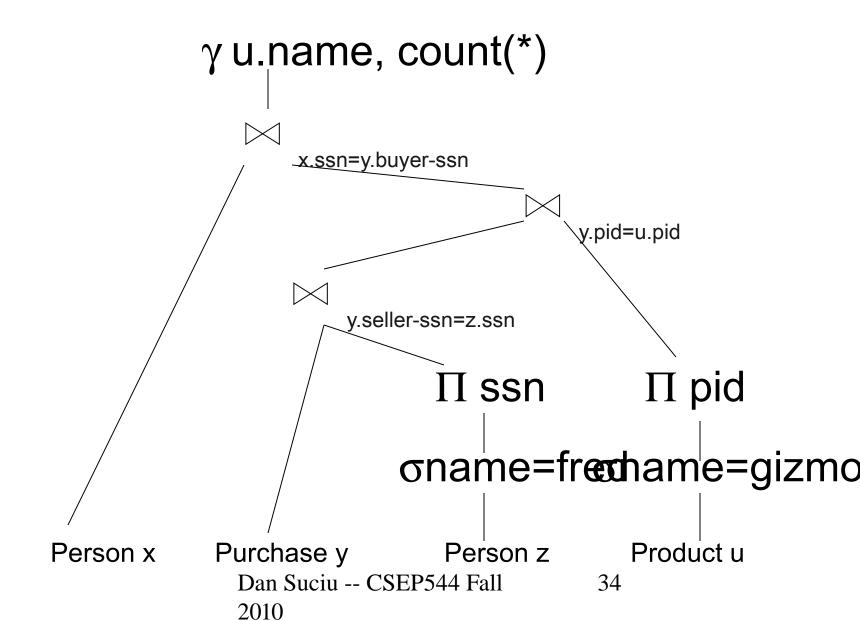
Operators on Bags

• Duplicate elimination δ $\delta(R)$ = select distinct * from R

• Grouping γ γ A,sum(B) (R) = select A,sum(B) from R group by A

· Sorting τ

Complex RA Expressions



RA = Dataflow Program

 Several operations, plus strictly specified order

 In RDBMS the dataflow graph is always a tree

 Novel applications (s.a. PIG), dataflow graph may be a DAG

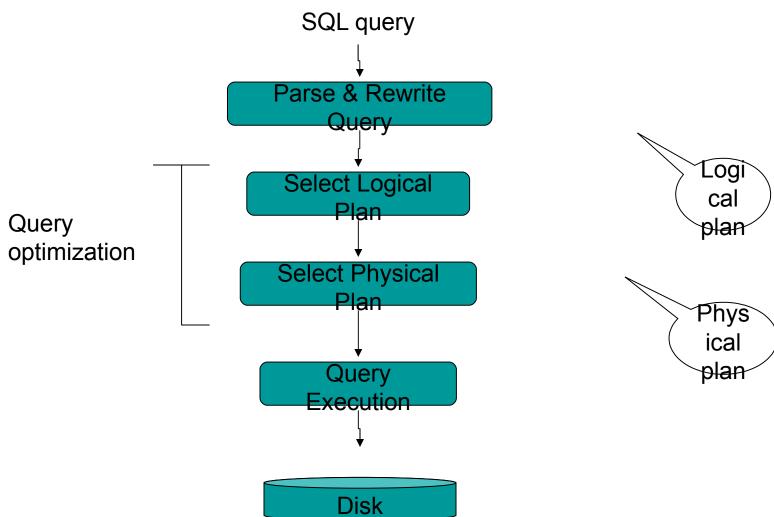
Limitations of RA

Cannot compute "transitive closure"

Name1	Name2	Relationship
Fred	Mary	Father
Mary	Joe	Cousin
Mary	Bill	Spouse
Nancy	Lou	Sister

- Find all direct and indirect relatives of Fred
- · Cannot express in RA !!! Need to write Java program
- Remember the Bacon number? Needs TC too!

Steps of the Query Processor



Example Database Schema

Supplier(sno,sname,scity,sstate)
Part(pno,pname,psize,pcolor)
Supply(sno,pno,price)

View: Suppliers in Seattle

CREATE VIEW NearbySupp AS
SELECT sno, sname
FROM Supplier
WHERE scity='Seattle' AND sstate='WA'

Example Query

Find the names of all suppliers in Seattle who supply part number 2

```
SELECT sname FROM NearbySupp
WHERE sno IN ( SELECT sno
FROM Supplies
WHERE pno = 2 )
```

Steps in Query Evaluation

Step 0: Admission control

- User connects to the db with username, password
- User sends query in text format

Step 1: Query parsing

- Parses query into an internal format
- Performs various checks using catalog
 - Correctness, authorization, integrity constraints

Step 2: Query rewrite

View rewriting, flattening, etc.

Rewritten Version of Our Query

Original query:

SELECT sname
FROM NearbySupp
WHERE sno IN (SELECT sno
FROM Supplies
WHERE pno = 2)

Rewritten query:

SELECT S.sname
FROM Supplier S, Supplies U
WHERE S.scity='Seattle' AND S.sstate='WA'
AND S.sno = U.sno
AND U.pno = 2;

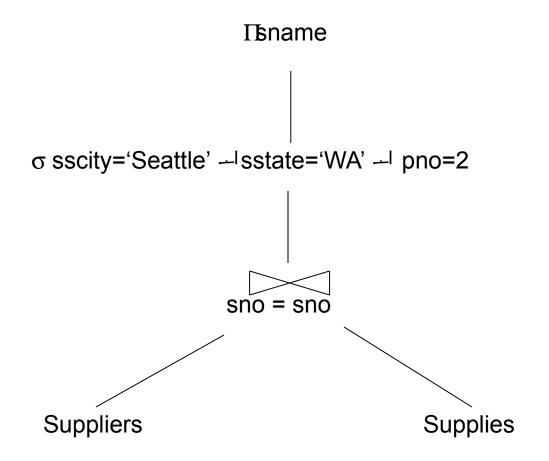
Continue with Query Evaluation

- Step 3: Query optimization
 - Find an efficient query plan for executing the query
- · A query plan is
 - Logical query plan: an extended relational algebra tree
 - Physical query plan: with additional annotations at each node
 - Access method to use for each relation
 - Implementation to use for each relational operator

Extended Algebra Operators

- Union ^ , intersection = , difference -
- · Selection o
- · Projection -
- · Join 🔀
- Duplicate elimination δ
- Grouping and aggregation γ
- · Sorting τ
- · Rename p

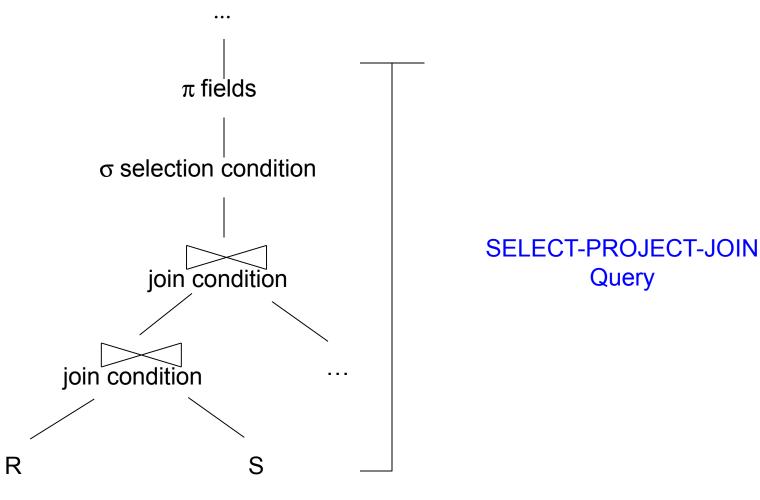
Logical Query Plan



Query Block

- Most optimizers operate on individual query blocks
- · A query block is an SQL query with no nesting
 - Exactly one
 - SELECT clause
 - FROM clause
 - At most one
 - WHERE clause
 - GROUP BY clause
 - HAVING clause

Typical Plan for Block (1/2)



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Typical Plan For Block (2/2)

σhaving-ondition γ fields, sum/count/min/max(fields) σ selection condition join condition Dan Suciu -- CSEP544 Fall

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How about Subqueries?

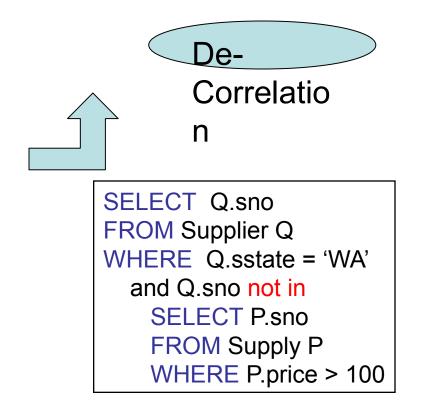
```
SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA'
and not exists
SELECT *
FROM Supply P
WHERE P.sno = Q.sno
and P.price > 100
```

How about Subqueries?

```
SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate ≤ 'WA'
and not exists
SELECT *
FROM Supply P
WHERE P.sno = Q.sno
and P.price > 100
```

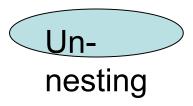
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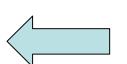
SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA'
and not exists
SELECT *
FROM Supply P
WHERE P.sno = Q.sno
and P.price > 100



How about Subqueries?

(SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA')
EXCEPT
(SELECT P.sno
FROM Supply P
WHERE P.price > 100)

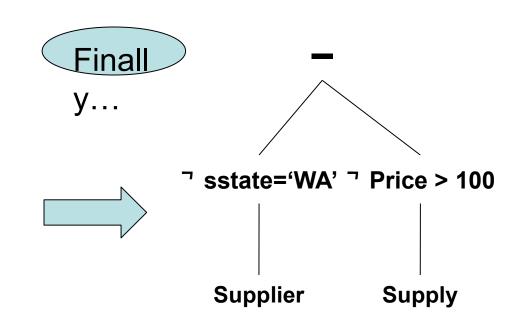




SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA'
and Q.sno not in
SELECT P.sno
FROM Supply P
WHERE P.price > 100

How about Subqueries?

(SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA')
EXCEPT
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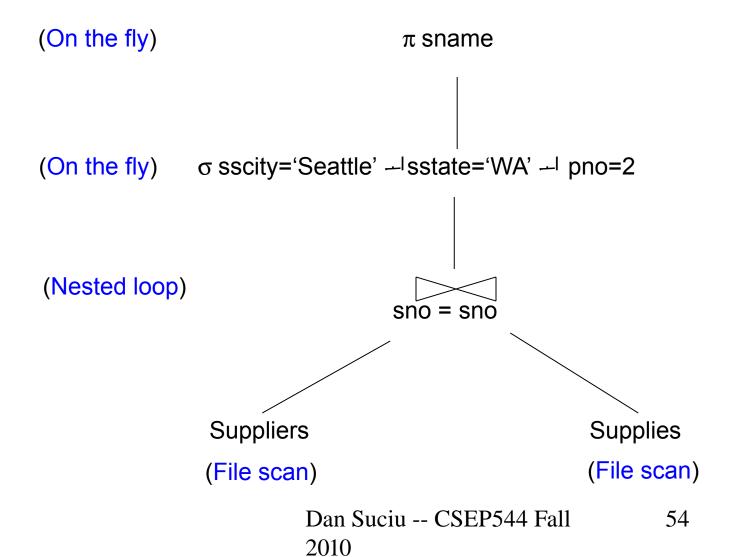


Physical Query Plan

- Logical query plan with extra annotations
- Access path selection for each relation
 - Use a file scan or use an index

- · Implementation choice for each operator
- Scheduling decisions for operators

Physical Query Plan



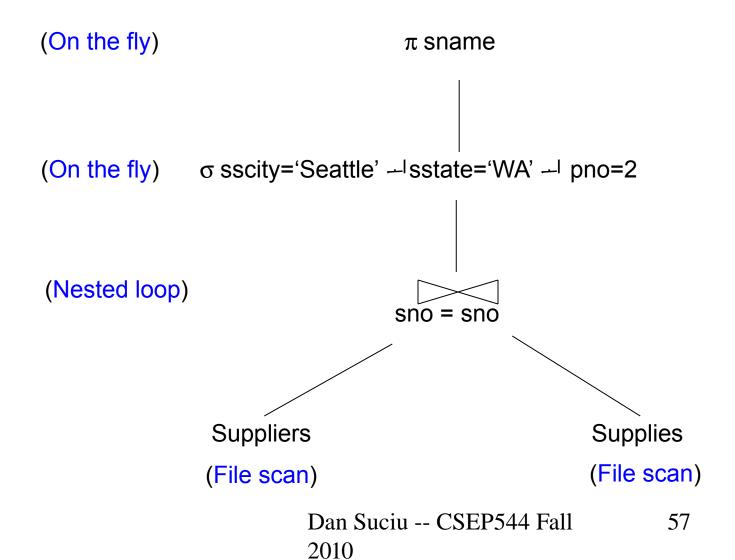
Final Step in Query Processing Step 4: Query execution

- How to synchronize operators?
- How to pass data between operators?
- What techniques are possible?
 - One thread per query
 - Iterator interface
 - Pipelined execution
 - Intermediate result materialization

Iterator Interface

- Each operator implements this interface
- Interface has only three methods
- open()
 - Initializes operator state
 - Sets parameters such as selection condition
- get_next()
 - Operator invokes get_next() recursively on its inputs
 - Performs processing and produces an output tuple
- · close(): cleans-up state

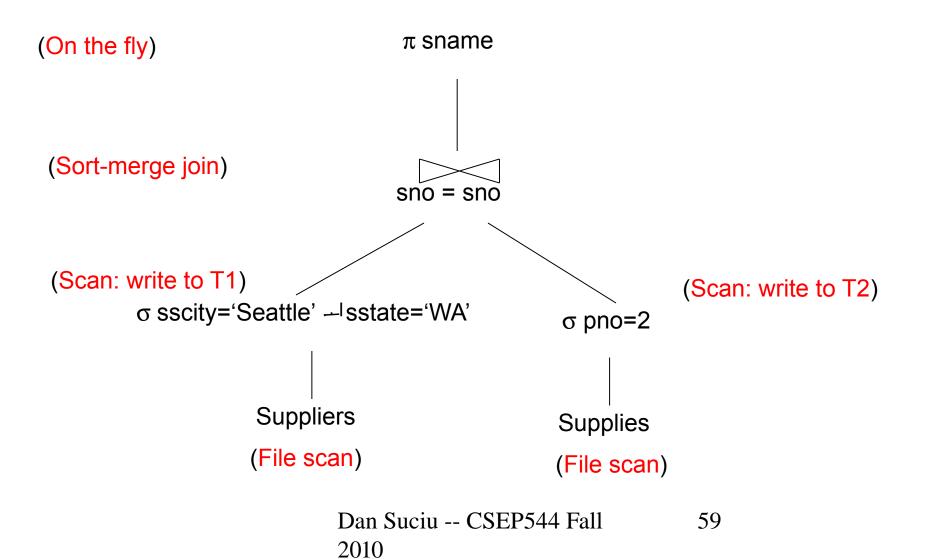
Pipelined Execution



Pipelined Execution

- Applies parent operator to tuples directly as they are produced by child operators
- · Benefits
 - No operator synchronization issues
 - Saves cost of writing intermediate data to disk
 - Saves cost of reading intermediate data from disk
 - Good resource utilizations on single processor
- This approach is used whenever possible

Intermediate Tuple Materialization



Intermediate Tuple Materialization

Writes the results of an operator to an intermediate table on disk

- No direct benefit but
- Necessary data is larger than main memory
- Necessary when operator needs to examine the same tuples multiple times

Physical Operators

Each of the logical operators may have one or more implementations = physical operators

Will discuss several basic physical operators, with a focus on join

Question in Class

Logical operator:

Supply(sno,pno,price) pno=pno Part(pno,pname,psize,pcolor)

Propose three physical operators for the join, assuming the tables are in main memory:

1.

2.

3

Question in Class

Logical operator:

Supply(sno,pno,price) pno=pno Part(pno,pname,psize,pcolor)

Propose three physical operators for the join, assuming the tables are in main memory:

- Nested Loop Join
- Merge join
- Hash join

1. Nested Loop Join

```
for S in Supply do {
   for P in Part do {
     if (S.pno == P.pno) output(S,P);
   }
}
```

Supply = outer relation
Part = inner relation
Note: sometimes
terminology is switched

Would it be more efficient to choose Part=inner, Supply=outer?
What if we had an index on Part.pno?

It's more complicated...

- Each operator implements this interface
- · open()
- get_next()
- · close()

Main Memory Nested Loop Join Revisited

```
close ( ) {
Supply.open( );
Part.open( );
S = Supply.get_next( );

close ( ) {
Supply.close ( );
Part.close ( );
```

```
get next() {
 repeat {
   P= Part.get_next();
   if (P== NULL)
     { Part.close();
       S= Supply.get_next();
       if (S== NULL) return NULL;
       Part.open();
       P= Part.get next();
 until (S.pno == P.pno);
 return (S, P)
```

BRIEF Review of Hash Tables

Separate chaining:

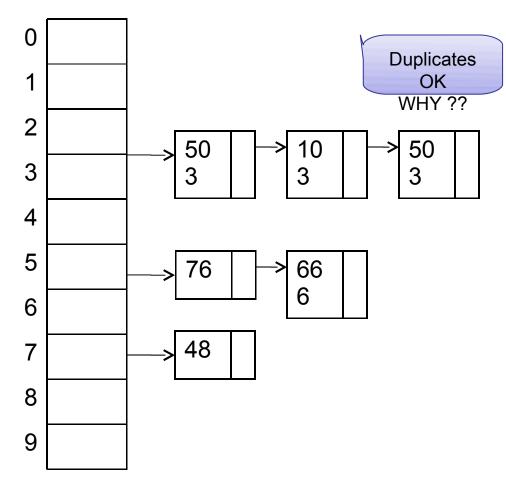
A (naïve) hash function:

$$h(x) = x \mod 10$$

Operations:

$$find(103) = ??$$

 $insert(488) = ??$



BRIEF Review of Hash Tables

insert(k, v) = inserts a key k with value v

- Many values for one key
 - Hence, duplicate k's are OK

 find(k) = returns the <u>list</u> of all values v associated to the key k

2. Hash Join (main memory)

```
for S in Supply do insert(S.pno, S);

pha
se

for P in Part do {
    LS = find(P.pno);
    ing
    for S in LS do { output(S, P); }
}
```

```
Supply=
outer
Part=inn
er
```

3. Merge Join (main memory)

```
Part1 = sort(Part, pno);
Supply1 = sort(Supply,pno);
P=Part1.get_next(); S=Supply1.get_next();
While (P!=NULL and S!=NULL) {
  case:
    P.pno > S.pno: P = Part1.get_next();
    P.pno < S.pno: S = Supply1.get next();
    P.pno == S.pno { output(P,S);
                     S = Supply1.get next();
```



Main Memory Group By

Grouping:

Product(name, department, quantity)
γdepartment, sum(quantity) (Product) —
Answer(department, sum)

Main memory hash table Question: How?

Duplicate Elimination IS Group By

Duplicate elimination $\delta(R)$ is <u>the same</u> as group by $\gamma(R)$ WHY ???

Hash table in main memory

- · Cost: B(R)
- · Assumption: $B(\delta(R)) \leq M$

Selections, Projections

 Selection = easy, check condition on each tuple at a time

 Projection = easy (assuming no duplicate elimination), remove extraneous attributes from each tuple

Review (1/2)

- Each operator implements this interface
- open()
 - Initializes operator state
 - Sets parameters such as selection condition
- get_next()
 - Operator invokes get_next() recursively on its inputs
 - Performs processing and produces an output tuple
- · close()
 - Cleans-up state

Review (2/2)

- Three algorithms for main memory join:
 - Nested loop join
 - Hash join
 - Merge join

If |R| = m and |S| = n, what is the asymptotic complexity for computing $R \bowtie S$?

 Algorithms for selection, projection, group-by

External Memory Algorithms

Data is too large to fit in main memory

 Issue: disk access is 3-4 orders of magnitude slower than memory access

 Assumption: runtime dominated by # of disk I/O's; will ignore the main memory part of the runtime

Cost Parameters

The *cost* of an operation = total number of I/Os Cost parameters:

- B(R) = number of blocks for relation R
- T(R) = number of tuples in relation R
- V(R, a) = number of distinct values of attribute a
- M = size of main memory buffer pool, in blocks

```
Facts: (1) B(R) << T(R):
(2) When a is a key, V(R,a) = T(R)
When a is not a key, V(R,a) << T(R)
```

Ad-hoc Convention

- We assume that the operator reads the data from disk
- We assume that the operator does not write the data back to disk (e.g.: pipelining)
- · Thus:

Any main memory join algorithms for $R \bowtie S$: Cost = B(R)+B(S)

```
Any main memory grouping \gamma(R): Cost = B(R)

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```

Sequential Scan of a Table R

- When R is clustered
 - Blocks consists only of records from this table
 - $B(R) \ll T(R)$
 - Cost = B(R)

- When R is unclustered
 - Its records are placed on blocks with other tables
 - B(R) = T(R)
 - Cost = T(R)

Nested Loop Joins

Tuple-based nested loop R ⋈ S

for each tuple r in R do
for each tuple s in S do
if r and s join then output (r,s)

R=outer relation S=inner relation

- Cost: T(R) B(S) when S is clustered
- · Cost: T(R) T(S) when S is unclustered

Examples

M = 4; R, S are clustered

- · Example 1:
 - B(R) = 1000, T(R) = 10000
 - B(S) = 2, T(S) = 20
 - Cost = ?

Can you do better?

- Example 2:
 - B(R) = 1000, T(R) = 10000
 - B(S) = 4, T(S) = 40
 - Cost = ?

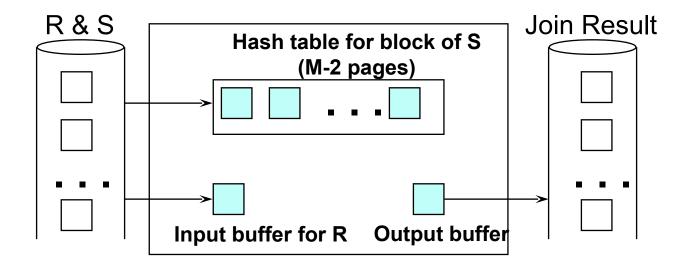
Block-Based Nested-loop Join

```
Why not
```

```
for each (M-2) blocks bs of S do
for each block br of R do
for each tuple s in bs
for each tuple r in br do
if "r and s join" then output(r,s)
```

Terminology alert: book calls S the *inner* relation

Block Nested-loop Join



Examples

M = 4; R, S are clustered

- · Example 1:
 - B(R) = 1000, T(R) = 10000
 - B(S) = 2, T(S) = 20
 - Cost = B(S) + B(R) = 1002
- · Example 2:
 - -B(R) = 1000, T(R) = 10000
 - B(S) = 4, T(S) = 40
 - Cost = B(S) + 2B(R) = 2004

Note: T(R) and T(S) are irrelevant here.

Cost of Block Nested-loop Join

- Read S once: cost B(S)
- Outer loop runs B(S)/(M-2) times, and each time need to read R: costs B(S)B(R)/(M-2)

$$Cost = B(S) + B(S)B(R)/(M-2)$$

Index Based Selection

Recall IMDB; assume indexes on Movie.id, Movie.year

SELET *
FROM Movie
WHERE id = '12345'

B(Movie) = 10kT(Movie) = 1M

SELET *
FROM Movie
WHERE year = '1995'

What is your estimate of the I/O cost?

Index Based Selection

Selection on equality: $\sigma a = v(R)$

Clustered index on a: cost B(R)/V(R,a)

Unclustered index : cost T(R)/V(R,a)

Index Based Selection

· Example:

$$B(R) = 10k$$

 $T(R) = 1M$
 $V(R, a) = 100$

cost of $\sigma a = v(R) = ?$

- Table scan (assuming R is clustered):
 - B(R) = 10k I/Os
- Index based selection:
 - If index is clustered: B(R)/V(R,a) = 100 I/Os
 - If index is unclustered: T(R)/V(R,a) = 10000 I/Os

Rule of thumb:

don't build unclustered indexes when V(R,a) is small!

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Index Based Join

- · R ⋈ S
- Assume S has an index on the join attribute

for each tuple r in R do lookup the tuple(s) s in S using the index output (r,s)

Index Based Join

Cost (Assuming R is clustered):

- If index is clustered: B(R) + T(R)B(S)/V(S,a)
- If unclustered: B(R) + T(R)T(S)/V(S,a)

Operations on Very Large Tables

 Compute R ⋈ S when each is larger than main memory

- Two methods:
 - Partitioned hash join (many variants)
 - Merge-join

Similar for grouping

Partitioned Hash-based Algorithms

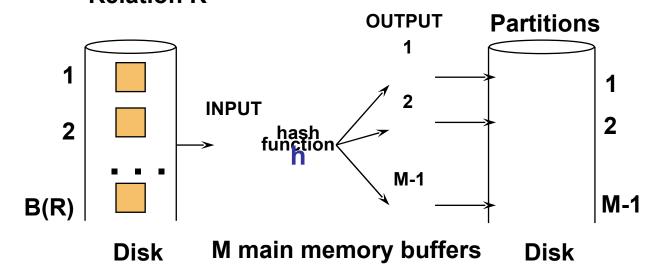
Idea:

- If B(R) > M, then partition it into smaller files: R1, R2, R3, ..., Rk
- Assuming B(R1)=B(R2)=...= B(Rk), we have
 B(Ri) = B(R)/k
- Goal: each Ri should fit in main memory:
 B(Ri) ≤ M

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Partitioned Hash Algorithms

- · Idea: partition a relation R into M-1 buckets, on disk
- Each bucket has size approx. B(R)/(M-1) ≈ B(R)/M
 Relation R



Assumption: $B(R)/M \le M$, i.e. $B(R) \le M2$

Grouping

- $\gamma(R)$ = grouping and aggregation
- Step 1. Partition R into buckets
- Step 2. Apply γ to each bucket (may read in main memory)

- · Cost: 3B(R)
- Assumption: B(R) <= M2

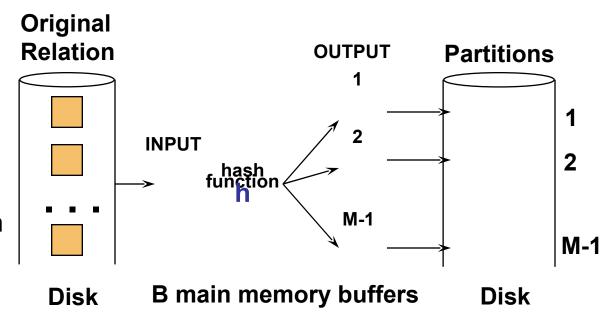
Partitioned Hash Join

$R \bowtie S$

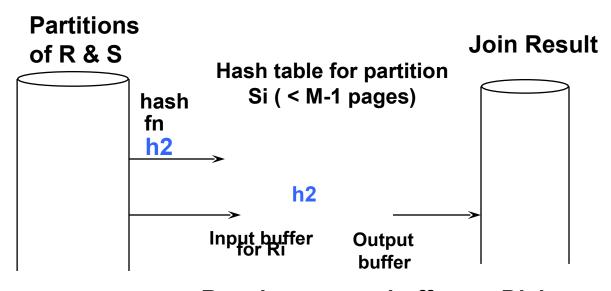
- · Step 1:
 - Hash S into M buckets
 - send all buckets to disk
- · Step 2
 - Hash R into M buckets
 - Send all buckets to disk
- Step 3
 - Join every pair of buckets

Hash-Join

Partition both relations using hash fn h: R tuples in partition i will only match S tuples in partition i.



Read in a partition of R, hash it using h2 (<> h!).
Scan matching partition of S, search for matches.



Dan Street - CSEP544 Fall memory buffers Disk

Partitioned Hash Join

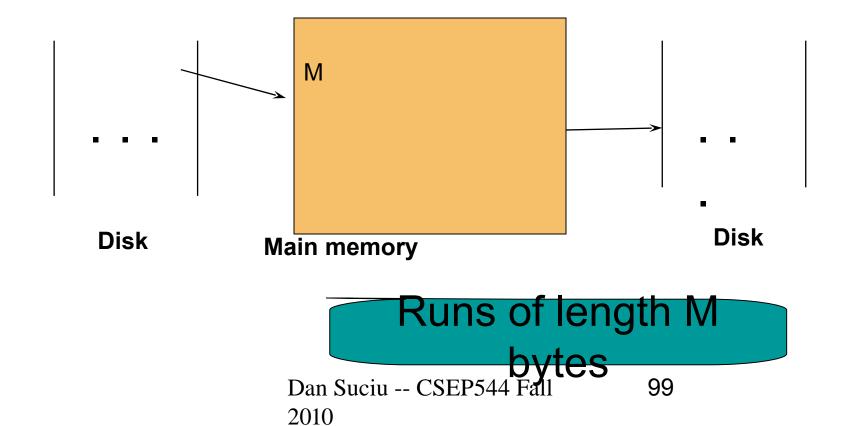
- Cost: 3B(R) + 3B(S)
- Assumption: min(B(R), B(S)) <= M2

External Sorting

- · Problem:
- Sort a file of size B with memory M
- · Where we need this:
 - ORDER BY in SQL queries
 - Several physical operators
 - Bulk loading of B+-tree indexes.
- · Will discuss only 2-pass sorting, when B < M2

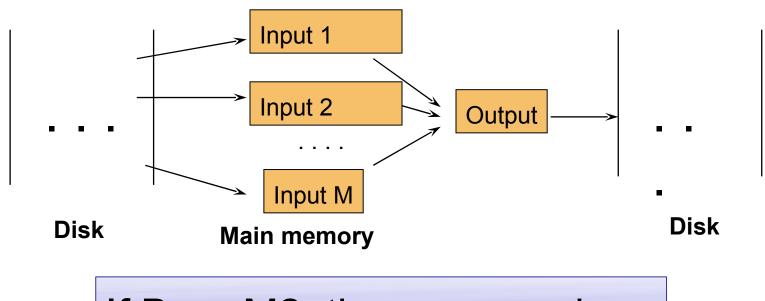
External Merge-Sort: Step 1

· Phase one: load M bytes in memory, sort



External Merge-Sort: Step 2

- Merge M 1 runs into a new run
- · Result: runs of length M (M 1) ≥ M2



If B <= M2 then we are done

Cost of External Merge Sort

· Read+write+read = 3B(R)

Assumption: B(R) <= M2

Grouping

Grouping: γ a, sum(b) (R)

- Idea: do a two step merge sort, but change one of the steps
- Question in class: which step needs to be changed and how?

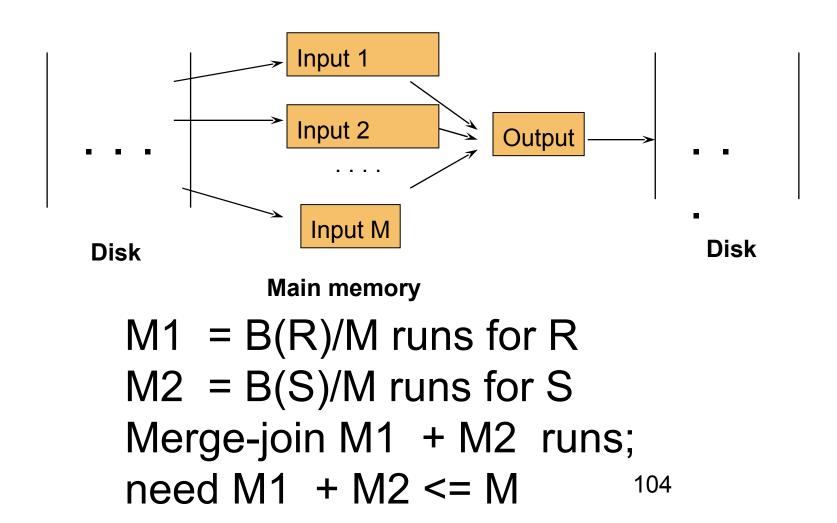
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Cost = 3B(R)
Assumption: B(\delta(R)) <= M2
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Merge-Join

Join R ⋈ S

- Step 1a: initial runs for R
- Step 1b: initial runs for S
- Step 2: merge and join

Merge-Join



Two-Pass Algorithms Based on Sorting

Join R ⋈ S

- If the number of tuples in R matching those in S is small (or vice versa) we can compute the join during the merge phase
- Total cost: 3B(R)+3B(S)
- · Assumption: $B(R) + B(S) \le M2$

Summary of External Join Algorithms

- Block Nested Loop: B(S) + B(R)*B(S)/M
- Index Join: B(R) + T(R)B(S)/V(S,a)
- Partitioned Hash: 3B(R)+3B(S);
 - $\min(B(R),B(S)) \leq M2$
- Merge Join: 3B(R)+3B(S)
 - B(R) + B(S) <= M2