

CSEP 521  
Applied Algorithms  
Spring 2005

Research Projects  
of  
Richard Ladner

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## Outline for Tonight

- Reduction of subset sum optimization to subset sum decision.
- Windows scheduling for periodic jobs.
- Student Evaluations
- Cache efficient dynamic programming
- Tactile graphics

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## Windows Scheduling

with  
Amotz Bar-Noy  
Tami Tamir

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## Windows Scheduling Problem Definition

- $n$  unit length repetitive jobs with positive integer windows  $w_1, w_2, \dots, w_n$
- $m$  processors.
- Scheduling goal: assign jobs on processors so that
  - Job  $i$  is scheduled on some processor at least once every  $w_i$  time slots.
  - No two jobs are scheduled in the same time slot on the same processor.
- Optimization goal: Given  $w_1, w_2, \dots, w_n$  minimize the number of processors.

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## Applications

- Video broadcast scheduling
  - On one channel a video can be broadcast so that the worst case waiting time is strictly smaller than the video length
- Periodic maintenance
  - Maintenance must be done at least so often
- Push systems
  - Ads, sports scores, DJ average must be displayed at least so often

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## Basic Lower Bound

- Let  $W = w_1, w_2, \dots, w_n$  and define

$$h(W) = \sum_{i=1}^n \frac{1}{w_i}$$

- Theorem:  $\lceil h(W) \rceil$  is a lower bound on the number of number of processors needed to schedule  $W$ .
- Proof: Job  $i$  requires  $1/w_i$  of a processor

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### Example 1

- $W = 1,2,3$  and  $m = 2$

$P_1$ : 1 1 1 1 1 1 ...

$P_2$ : 2 3 2 3 2 3 ...

- This is a perfect schedule, that is, each job  $i$  is scheduled every  $w_i$  slots for  $w_i \leq w_i$
- 3 is scheduled more often than its window requirement

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### Example 2

- $W = 4,5,6,7,8$  and  $m = 1$

$P_1$ :

4 6 5 7 4 8 5 6 4 7 5 8 4 6 5 ...

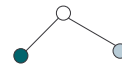
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### Tree Representation of Perfect Schedules



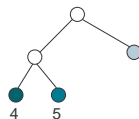
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### Tree Representation of Perfect Schedules



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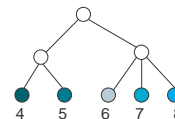
### Tree Representation of Perfect Schedules



Each node is scheduled periodically every  $p$  times where  $p$  is the product of degrees of its ancestors.

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### Tree Representation of Perfect Schedules



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## The Rest of the Talk

- Buffer scheme
- Approximation
- Video-on-demand

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## Are Perfect Schedules Sufficient?

- No!
- $W = 3, 5, 8, 8, 8$  and  $m = 1$
- There is no perfect schedule on one processor
- Non-perfect windows schedule

3 5 8a 3 8b 5 3 8c 8a 3 5 8b 3 8c 5 3 8a 8b 3 5 8c ...

- Non-perfect schedules can be found using a search technique call the buffer scheme.

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## Impossibility of Perfect 3,5,8,8,8

- 3 must have period 1,2, or 3
- But,  $1/2 + 1/5 + 3/8 > 1$
- Hence 3 has period 3.
- 5 must have period 1,2,3,4, or 5
- But,  $1/3 + 1/3 + 3/8 > 1$
- 5 must have period 4 or 5.
- But,  $\gcd(4,3) = 1$  and  $\gcd(5,3) = 1$ , Chinese remainder theorem implies there must be a slot in common to the schedules of both 4 and 3, and 5 and 3.  $\Rightarrow \Leftarrow$

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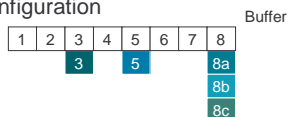
## Buffer Scheme

- A technique for searching all possible schedules.
- Can find non-perfect schedules.
- Can be used to prove impossibility.
- By adding deterministic rules it can be used as an on-line scheduler (jobs can inserted and deleted at each slot).

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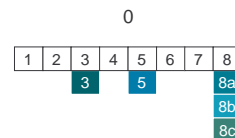
## Buffer Scheme by Example

- If job  $i$  is in buffer location  $j$ , then  $i$  must be scheduled within  $j$  slots.
- Non-deterministic
- Complete - every schedule can be modeled
- Initial configuration



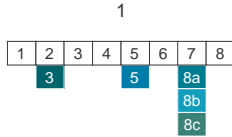
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## Buffer Scheme Example



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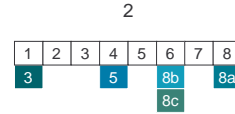
### Buffer Scheme Example



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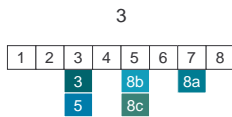
### Buffer Scheme Example



5 8a

20

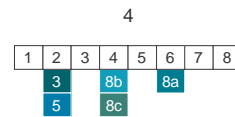
### Buffer Scheme Example



5 8a 3

21

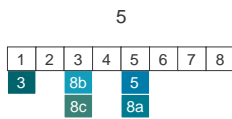
### Buffer Scheme Example



5 8a 3 x

22

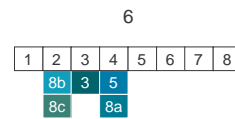
### Buffer Scheme Example



5 8a 3 x 5

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### Buffer Scheme Example



5 8a 3 x 5 3

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## Buffer Scheme Properties

- Generalize to multiple processors.
  - Schedule  $\leq m$  at each slot.
- Non-deterministic finite state machine.
- A cycle reachable from the start state is a schedule.
- Exhaustive search leads to impossibility.
  - Requires early dead-end detection for speed
- By adding a priority scheme it can be made into an on-line windows scheduling algorithm.

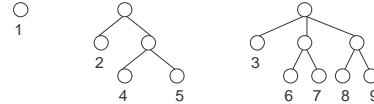
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## Buffer Scheme Impossibility

- $W_{10} = 1, 2, 3, 4, 5, 6, 7, 8, 9, 10$  and  $m = 3$

$$1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{10} = 2.929$$

- Exhaustive search proves there is no windows schedule for  $W_{10}$  on 3 processors.
- There is a perfect schedule for  $W_9$



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## Approximate Windows Scheduling

- Given  $W$ , define  $H(W)$  to be the minimum number of processors needed to schedule  $W$ .
- Theorem:  $H(W) = h(W) + O(\log(h(W)))$ .
- The schedule can be found in polynomial time.
- Corollary: As  $h(W) \rightarrow \infty$ , windows scheduling is polynomial time approximable with approximation ratio 1.

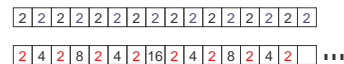
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## Special Case: Powers of Two

- Special Case: if all  $w_i$  are powers of two then

$$H(W) = \lceil h(W) \rceil = \left\lceil \sum_{i=1}^n \frac{1}{w_i} \right\rceil$$

- Example:  $W = 2, 2, 2, 4, 8, 16$

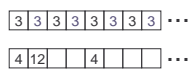


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## Upper Bound by Rounding

$$H(W) \leq \lceil 2h(W) \rceil$$

- Proof: Schedule page  $i$  every  $2^k$  slots where  $2^k$  is the largest power of two  $\leq w_i$ . (Rounding)
- Example:  $W = 3, 3, 4, 12$   
Use  $W' = 2, 2, 4, 8$  for scheduling



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## Asymptotic Upper Bound

$$H(W) \leq h(W) + e \cdot \ln(h(W)) + \eta$$

where  $h(W) = \sum_{i=1}^n \frac{1}{w_i} > 1$      $e \approx 2.71828$   
 $\eta \approx 7.3595$

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## Main Ideas in the Upper Bound

- Expand Special Case: If all  $w_i$  are of the form  $u2^k$  for a fixed  $u$ , then

$$H(W) = \lceil h(W) \rceil$$

- Multiple Rounding
- Schedule some windows to fill processors and schedule the residual recursively
- Do all this “optimally”

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## Multiple Rounding

$$W = 2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19$$

Round using 3,4,5

$$W_3 = 3,6,7,12,13,14,15$$

$$W'_3 = 3,6,6,12,12,12,12$$

$$W_4 = 2,4,8,9,16,17,18,19$$

$$W'_4 = 2,4,8,8,16,16,16,16$$

$$W_5 = 5,10,11$$

$$W'_5 = 5,10,10$$

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## Find Residual

$$W = 2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19$$

Round using 3,4,5

$$W_3 = 3,6,7,12,13,14,15$$

$$W'_3 = 3,6,6,12,12,12,12$$

1 processor

$$W_4 = 2,4,8,9,16,17,18,19$$

$$W'_4 = 2,4,8,8,16,16,16,16$$

$$W_5 = 5,10,11$$

$$W'_5 = 5,10,10$$

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## Find Residual

$$W = 2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19$$

Round using 3,4,5

$$W_3 = 3,6,7,12,13,14,15$$

$$W'_3 = 3,6,6,12,12,12,12$$

1 processor

$$W_4 = 2,4,8,9,16,17,18,19$$

$$W'_4 = 2,4,8,8,16,16,16,16$$

1 processor + 16,17,18,19

$$W_5 = 5,10,11$$

$$W'_5 = 5,10,10$$

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## Find Residual

$$W = 2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19$$

Round using 3,4,5

$$W_3 = 3,6,7,12,13,14,15$$

$$W'_3 = 3,6,6,12,12,12,12$$

1 processor

$$W_4 = 2,4,8,9,16,17,18,19$$

$$W'_4 = 2,4,8,8,16,16,16,16$$

1 processor + 16,17,18,19

$$W_5 = 5,10,11$$

$$W'_5 = 5,10,10$$

0 processors + 5,10,11

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## Solve Residual

$$W' = 5,10,11,16,17,18,19$$

Round using 2

$$W_2 = 5,10,11,16,17,18,19$$

$$W'_2 = 4, 8, 8, 16,16,16,16$$

1 processor

Total is 3 processors, while simple rounding needs 4.

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## Summary Asymptotic Bounds

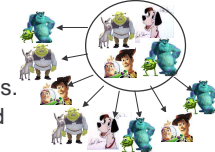
$$\lceil h(W) \rceil \leq H(W) \leq h(W) + e \cdot \ln(h(W)) + \eta$$

- Upper bound is polynomial time
- Rounding sets optimized for the construction

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## Video-on-Demand Systems

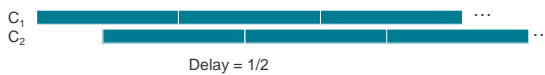
- A database of media objects (movies).
- A limited number of channels.
- Movies are broadcast based on customer demand
- The goal: Minimizing clients' maximum waiting time (delay).
- Broadcasting schemes: For popular movies, the system does not wait for client requests, but broadcasts these movies continuously.



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## Background

- Staggered broadcasting, [Dan, Sitaram, Shahabuddin, 96]:

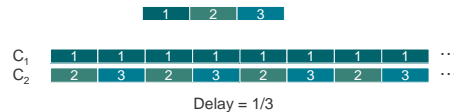


Note: each channel is at the playback bandwidth.

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## Background

- Pyramid Broadcasting, [Viswanathan, Imielinski, 96]:
- Partition the movie into segments. Early segments are transmitted more frequently.
- As segments are received either playback or buffer for future playback



Note that  $W = 1, 2, 3$  and  $m = 2$

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## Windows Scheduling for Video

- Shifting, [Bar-noy, Ladner, Tamir, 2003], Polyharmonic Broadcasting [Paris, 1999]
- Video divided into  $s$  equal size segments.
- For a constant  $d > 0$  define  $W = d, d+1, d+2, \dots, d+s-1$ , that is,  $w_i = d+i-1$
- Theorem: A windows schedule for  $W$  on  $m$  processors is a video schedule with  $s$  segments on  $m$  channels with delay  $d/s$ .

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## Example

- $W = 4, 5, 6, 7, 8$  and  $m = 1$  (c.f. Example 2)

Windows Schedule



Video Schedule



Delay = 4/5

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## Lower Bounds

- Lowerbound [Engebretsen, Sudan, 2002], [Gao, Kurose, Towsley, 2002], [Hu, 2001]  
Delay for  $m$  channels is bounded below by

$$\frac{1}{e^m - 1}$$

m	1	2	3	4	5	6
$1/(e^m - 1)$	.582	.157	.052	.019	.007	.002
1 hour video	35 min	9.5 min	3 min	1 min	25 sec	7 sec

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## Asymptotic Upper Bound

- For every  $m$  and  $\epsilon > 0$ , there is a video schedule that achieves delay

$$(1 + \epsilon) \frac{1}{e^m - 1}$$

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## Limiting the Number of Segments

- Given  $s$  segments what is the best delay possible on one channel. Use the buffer scheme!

segments	range	delay
5	4..8	0.800
6	5..10	0.883
7	5..11	0.714
8	6..13	0.750
120*	75..194	0.625

\* Uses RR<sup>2</sup> algorithm, 0.582 optimal  
not buffer scheme

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## Additional Work

- Receive  $k$  channels out of  $m$  for video scheduling. [Evans, Kirkpatrick, 2004]
- On-line windows scheduling
  - Buffer scheme - insertions and deletions
  - $H(W) + O(H(W)^{1/2})$  - insertions only
- Windows scheduling with lengths
  - Roughly a 2-approximation algorithm

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## Cache Efficient Dynamic Programming

with  
Cary Cherng

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## Problem Statement

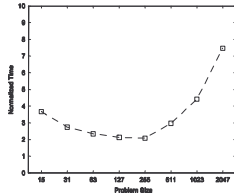
- Given  $x_1, x_2, \dots, x_n$  in nonassociative semiring
  - Multiplication is nonassociative
  - Additive inverses not required
- Find the sum of all ways  $x_1 x_2 \dots x_n$  can be completely parenthesized
  - $n = 4$   
 $x_1((x_2 x_3) x_4) + x_1(x_2(x_3 x_4)) + (x_1 x_2)(x_3 x_4) + ((x_1 x_2) x_3) x_4 + (x_1(x_2 x_3)) x_4$
- Examples of nonassociative semirings:
  - Matrix Chain Product
  - Context-free Language Recognition

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## Standard Dynamic Programming Solution - CYK

- Runs in  $O(n^3)$
- Poor cache behavior for large  $n$
- Normalized Time = Time/ $n^3$



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## Outline

- The Cache
- Dynamic Programming
  - Standard Dynamic Programming Solution - CYK (Cocke, Younger, Kasami 1965)
  - Valiant's Algorithm (1975)
- Experiments
  - Timing comparison
  - Cache misses

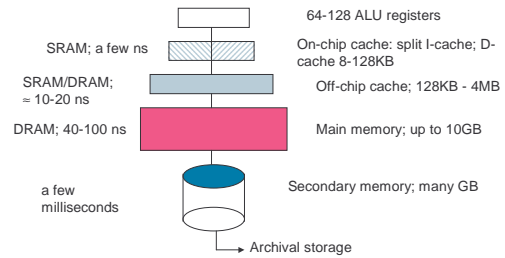
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## The Cache

- Standard dynamic programming has poor cache locality
- Divide and conquer algorithms typically have good cache locality

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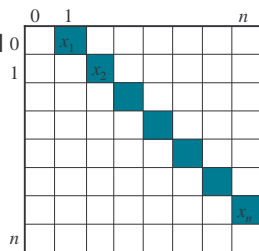
## Memory Hierarchy



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## Standard Dynamic Programming

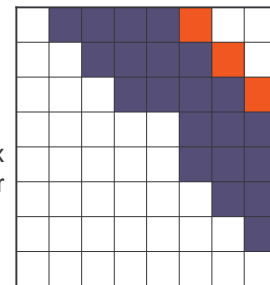
- Matrix of size  $n+1$
- Input off the diagonal
- For  $i = 1$  to  $n$ 
  - $D_{i-1,i} = x_i$
- For  $j = 2$  to  $n$ 
  - For  $i = j - 2$  to 0
    - For  $k = i + 1$  to  $j - 1$ 
      - $D_{ij} = D_{ij} + D_{ik}D_{kj}$



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## Dynamic Programming

- Computing  $D_{ij}$  requires accessing blue region
- Many cache misses if the matrix is large due to poor locality



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## Valiant's Algorithm

- Valiant proved in 1975 that context-free language recognition could be done in  $O(n^{2.81})$  using Strassen's matrix multiplication algorithm [1969]
- Current fastest Boolean matrix multiplication runs in  $O(n^{2.376})$  due to Coppersmith and Winograd [1987;1990]
- Implies  $O(n^{2.376})$  for context-free language recognition using Valiant's Algorithm

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## Valiant's Algorithm

- Divide and Conquer giving good cache locality
- Reorganizes the computation of CKY
- The algorithm can be applied to nonassociative semirings

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## Matrix Multiply and Accumulate

- Basic building block for the new algorithm.
- $U$ ,  $W$ , and  $Z$  are square arrays of power of 2 size.

$$U := U + W \cdot Z$$

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## Blocked Matrix Multiply and Accumulate

- Reduces the number of cache misses
- Recursive

$$\begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix} := \begin{bmatrix} U_{11} & U_{12} \\ U_{21} & U_{22} \end{bmatrix} + \begin{bmatrix} W_{11} & W_{12} \\ W_{21} & W_{22} \end{bmatrix} \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix}$$

- 8 matrix multiplies
- $U_{11}$  is computed as
 
$$U_{11} := U_{11} + W_{11} Z_{11}$$

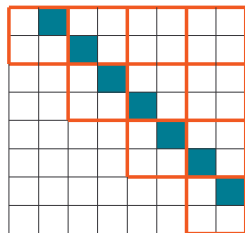
$$U_{11} := U_{11} + W_{12} Z_{21}$$

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## Valiant's Algorithm

- View  $X$  as blocked

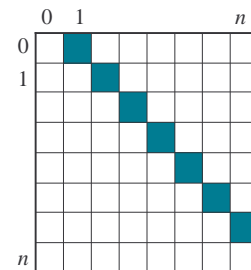
$$X = \begin{bmatrix} X_{11} & X_{12} & & & \\ & X_{22} & X_{23} & & \\ & & X_{33} & X_{34} & \\ & & & & X_{44} \end{bmatrix}$$



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## Valiant's Algorithm

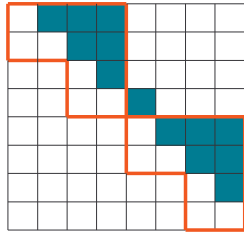
- Directly applies only when  $n = 2^k - 1$
- Matrix  $X$  of size  $n+1$
- $X^+$  means the result of applying Valiant's algorithm to  $X$



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## Star Function Input

- A helper function
- Precondition:  
upper left and lower right quadrants are finished.
- $X^*$  completes the dynamic program

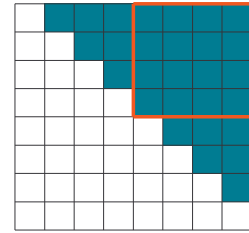


$X$

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## Star Function Result

- A helper function
- Precondition:  
upper left and lower right quadrants are finished.
- $X^*$  completes the dynamic program



$X^*$

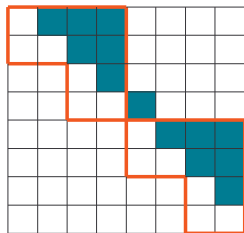
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## Valiant's Algorithm

- First step:  
Two recursive calls

$$\begin{bmatrix} X_{11} & X_{12} \\ & X_{22} \end{bmatrix} := \begin{bmatrix} X_{11} & X_{12} \\ & X_{22} \end{bmatrix}^+$$

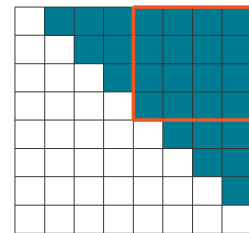
$$\begin{bmatrix} X_{33} & X_{34} \\ & X_{44} \end{bmatrix} := \begin{bmatrix} X_{33} & X_{34} \\ & X_{44} \end{bmatrix}^+$$



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## Valiant's Algorithm

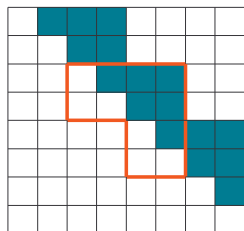
- Second step: apply the Star Function  
 $X := X^*$
- The end of Valiant's algorithm
- But what is the Star Function?



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## Star Function

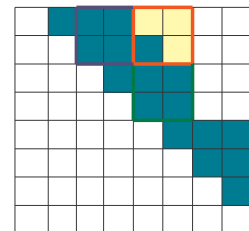
- First step:
- $$\begin{bmatrix} X_{22} & X_{23} \\ & X_{33} \end{bmatrix} := \begin{bmatrix} X_{22} & X_{23} \\ & X_{33} \end{bmatrix}^*$$
- Finishes the center quadrant



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## Star Function

- Second step:
- $X_{13} := X_{13} + X_{12} X_{23}$
-  means unfinished



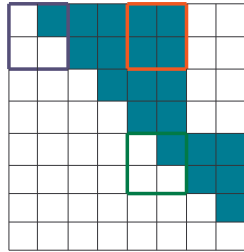
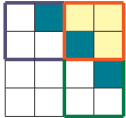
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## Star Function

- Third Step:  
Recursive Star call

$$\begin{bmatrix} X_{11} & X_{13} \\ & X_{33} \end{bmatrix} := \begin{bmatrix} X_{11} & X_{13} \\ & X_{33} \end{bmatrix}^*$$

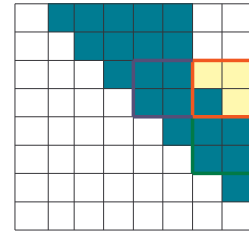
- Finishes  $X_{13}$



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## Star Function

- Fourth step:  
 $X_{24} := X_{24} + X_{23} X_{34}$   
•  means unfinished



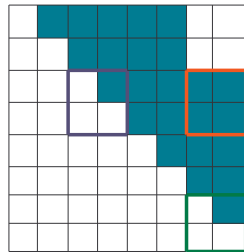
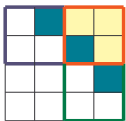
68

## Star Function

- Fifth Step:  
Recursive Star call

$$\begin{bmatrix} X_{22} & X_{24} \\ & X_{44} \end{bmatrix} := \begin{bmatrix} X_{22} & X_{24} \\ & X_{44} \end{bmatrix}^*$$

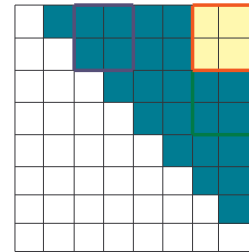
- Finishes  $X_{24}$



69

## Star Function

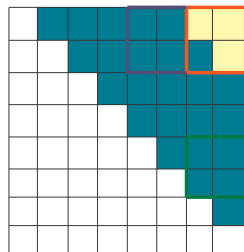
- Fifth Step:  
 $X_{14} := X_{14} + X_{12} X_{24}$



70

## Star Function

- Sixth Step:  
 $X_{14} := X_{14} + X_{13} X_{34}$



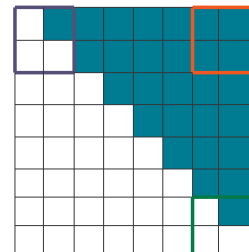
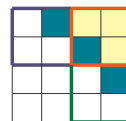
71

## Star Function

- Seventh Step:  
Recursive Star call

$$\begin{bmatrix} X_{11} & X_{14} \\ & X_{44} \end{bmatrix} := \begin{bmatrix} X_{11} & X_{14} \\ & X_{44} \end{bmatrix}^*$$

- Finishes  $X_{44}$



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## Time bounds

- $n$  refers to matrix size not problem size
- $T(n)$ : Valiant's algorithm
- $S(n)$ : Star function
- $M(n)$ : Block Matrix Multiplication
- All are  $O(n^3)$

$$T(n) \leq 2T(n/2) + S(n)$$

$$S(n) \leq 4S(n/2) + 4M(n/4)$$

$$M(n) \leq 8M(n/2)$$

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## Cache-aware Algorithms

- Cache-oblivious algorithms do not depend on cache parameters
- Cache-aware algorithms have a tuning parameter depending on cache size, line size, etc

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## Blocked Valiant's Algorithm

- Valiant's algorithm incurs overhead from recursive calls and blocked matrix multiplication
- Recursion unnecessary for small problems
- Make Valiant's algorithm cache-aware
- If matrix is sufficiently small use
  - normal matrix multiplication
  - CKY

75

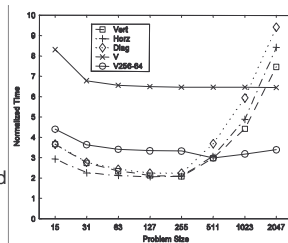
## Experiments

- Compared
  - Valiant's algorithm
  - Blocked Valiant's algorithm
  - Three variants of standard dynamic programming
- Time comparison
- Instruction Count
- Cache simulations using Valgrind
- 1 GHz AMD Athlon
  - 64 KByte L1 data cache (2-way)
  - 256 KByte L2 data cache (16-way)

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## Time Comparison

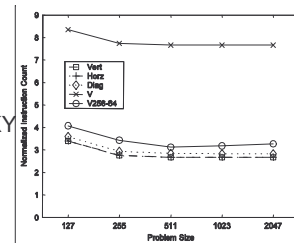
- Normalized Time =  $\text{Time}/n^3$
- V256-64
  - Blocked Valiant's algorithm
  - $n \leq 256$  use CKY
  - $n \leq 64$  use standard matrix multiplication



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## Instruction Count

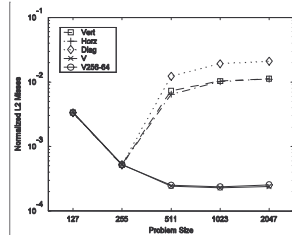
- Valiant's algorithm uses the most instructions
- Blocked Valiant's algorithm is near CKY



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## L2 Cache Misses

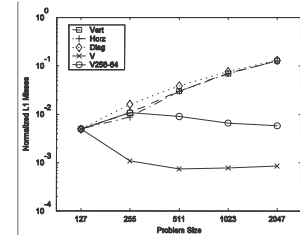
- Nearly 100 times more L2 cache misses in standard dynamic programming



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## L1 Cache Misses

- Blocked Valiant's algorithm trades instructions for more L1 cache misses



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## Conclusion

- Instruction count not the only important thing
- Cache misses matter
- Divide and conquer gives good cache behavior

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## Automatic Tactilization of Graphical Images

With  
Matt Renzelman  
Satria Krisnandi

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## The Tactilization Problem

- Graphical images are heavily used in math, science and engineering textbooks and papers
  - Line graphs and bar charts
  - Diagrams
  - Illustrations
- Tactual perception is the best modality for the blind to understand such images
- Tactilization of graphical images
  - Currently done manually
  - Labor-intensive and time consuming
  - How much of this process can be automated?

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## Outline

- Tactual Perception
- Overview of tactilization process
- Text segmentation
- Braille text placement
- Other subprojects
- Demonstration

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## Tactile Perception

- Resolution of human fingertip: 25 dpi
- Tactual field of perception is no bigger than the size of the fingertips of two hands
- Color information is replaced by texture information
- Visual bandwidth is  $10^6$  bits per second, tactile is  $10^2$  bits per second

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## Braille

- System to read text by feeling raised dots on paper (or on electronic displays). Invented in 1820s by Louis Braille, a French blind man.

a    b    c    z

and    the    with    mother

th    ch    gh

Z    3

Mode characters: cap and num.

**Critical fact:** Fixed height and width

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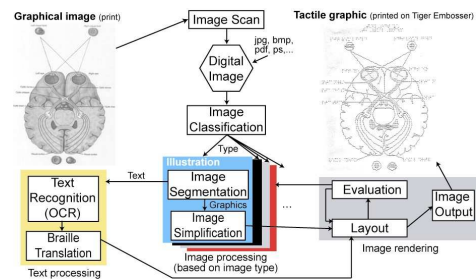
## Tiger Embosser

- 20 dpi (raised dots per inch)
- 7 height levels (only 3 or 4 are distinguishable)
- Prints Braille text and graphics
- Prints dot patterns for texture
- Invented by a blind man, John Gardner



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## Automatic Tactilization Process



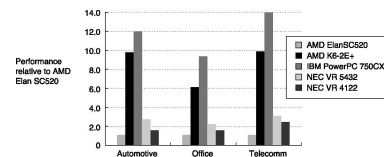
88

## Key Problems

- Graphical images meant for the visual mode must be modified for the tactual mode.
  - Text  $\Rightarrow$  Braille
  - Colors  $\Rightarrow$  replace with textures or reduce number
  - Area  $\Rightarrow$  Larger for Braille text to fit
  - Resolution  $\Rightarrow$  Lower to 20 dpi
  - Shading or 3-D effects  $\Rightarrow$  replace with outlines
  - Noise  $\Rightarrow$  remove noise, enhance contrast
- Classification of graphical images for mass production
  - Images in the same class require similar processes.

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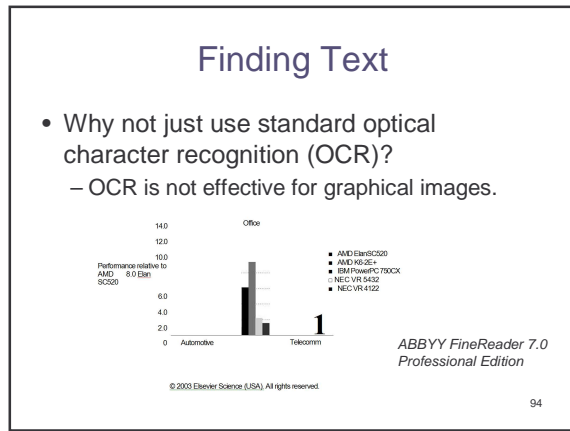
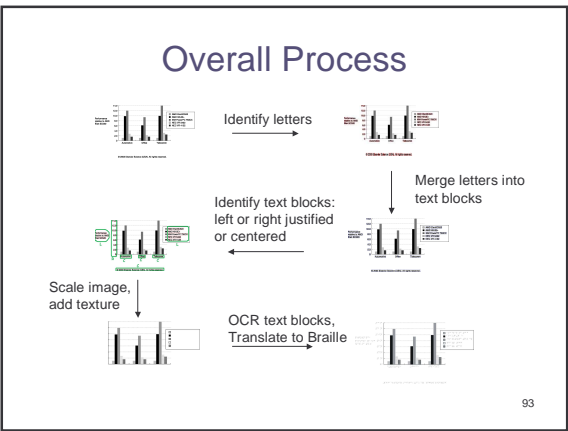
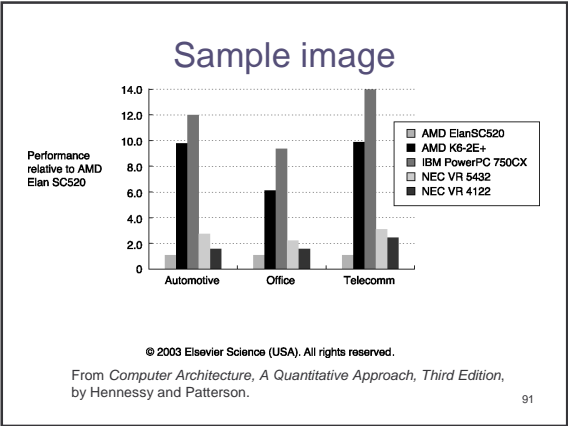
## Example



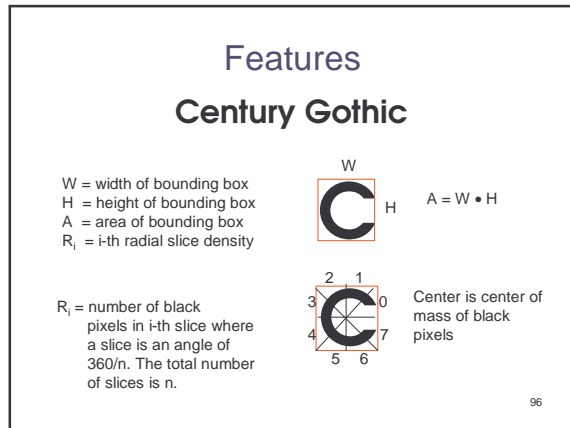
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From *Computer Architecture, A Quantitative Approach, Third Edition*, by Hennessy and Patterson.

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- ### Finding Text Letters
- Uses the following principles
    - Text in an image is usually in one font
    - Fonts are designed to have a uniform density at a distance.
    - In the absence of noise an individual letter tends to be connected component of one color. Exceptions are i and j.
  - Train on some simple features of letters. Connected components with similar features are also letters.





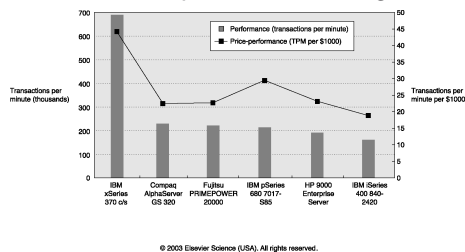
## Training/Finding

- Training:
  - Sample the connected components and compute their features.
- Finding:
  - For a new connected component compute its features.
  - If there is a close enough match of features with some member of the database then declare the component to be a letter.
- Parameters
  - How close is close enough
  - How many slices

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## Step 1: training

- Number of components in training set: 271



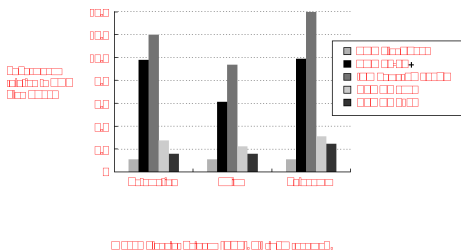
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Ch.1, Figure 23

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## Step 2: results (1/3)

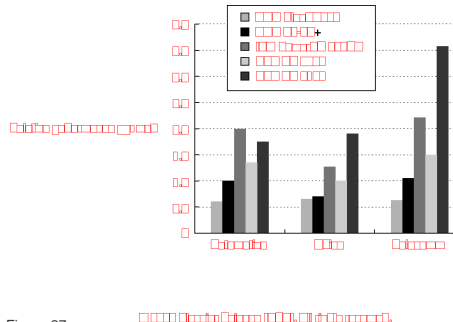
- No false positives



Ch.1, Figure 25

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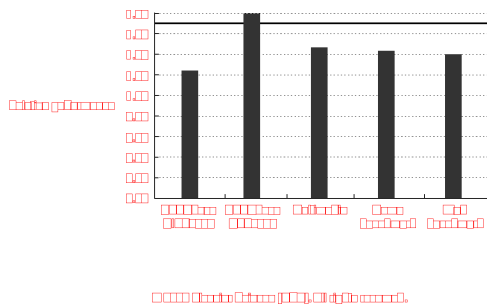
## Step 2: results (2/3)



Ch.1, Figure 27

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## Step 2: results (3/3)



Ch.1, Figure 28

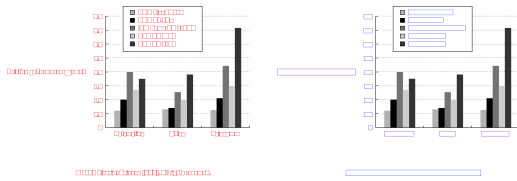
101

## Finding Text Blocks

- Principles
  - Most text tends to be in horizontal lines
  - Some text is vertical
  - Some text is diagonal
- We are developing methods that find lines using the centroids of the letters found.
  - Minimum spanning tree
  - Merge test using linear regression

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## Group characters logically



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## Group characters logically

- Extracting a set of isolated characters from an image is insufficient
  - Need groups of Braille characters for easier placement
- Challenges
  - Text can be at many angles
  - Individual characters may be aligned along multiple axes

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## Our approach

- Step 1: User provides training set
  - Software examines defining characteristics
- Step 2: Automatically find similar groups in remaining images
  - A. Minimum spanning tree
  - B. Discard useless edges
  - C. Discard inconsistent edges
  - D. Create merged groups

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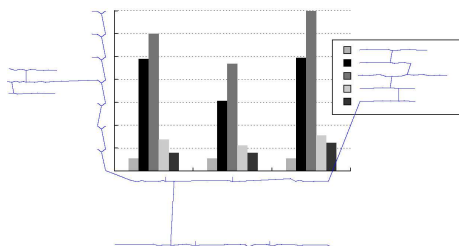
## Defining characteristics

- Inter-character spacing
- Line of best fit
  - Perpendicular regression vs. linear regression
  - Mean squared error
  - Angle

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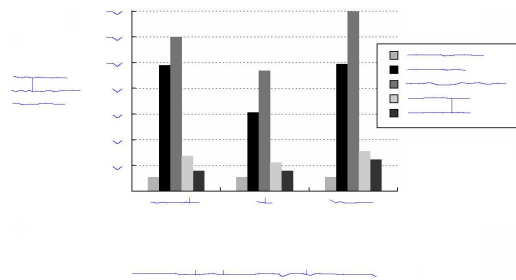
## Minimum spanning tree (1)

Treat the centroid of each connected component as a node



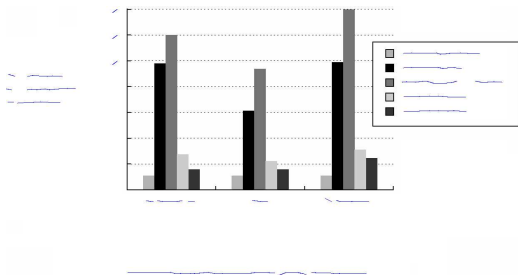
107

## Discard useless edges (2)



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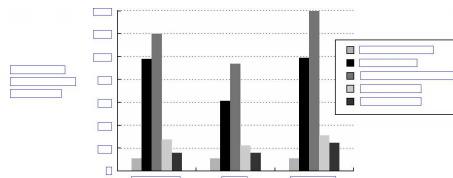
### Discard inconsistent edges (3)



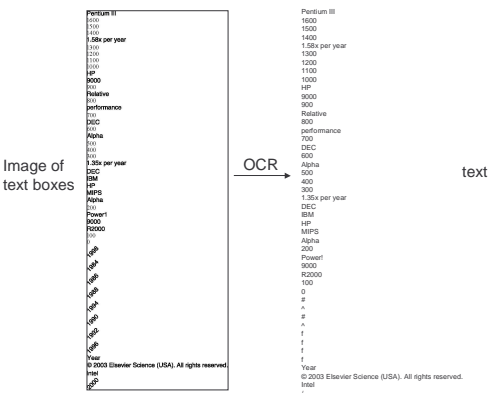
109

### Final merge step (4)

Merge only if the resultant group is consistent



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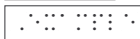


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### Classification of Text Boxes

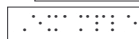
- Text boxes of Braille will be of different size than the original text boxes
  - Mode characters
  - Contractions
  - Braille is fixed width

Example



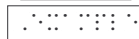
Left justified

Example



Right justified

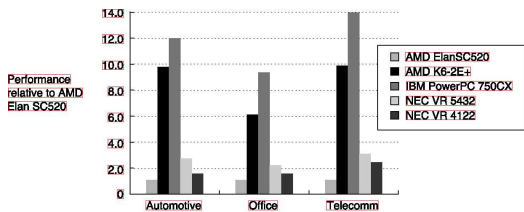
Example



Centered

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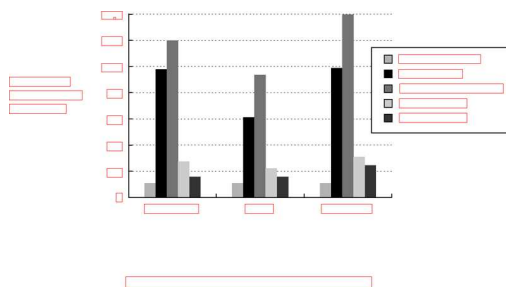
### Perfect Text Boxes



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### Text Boxes Only



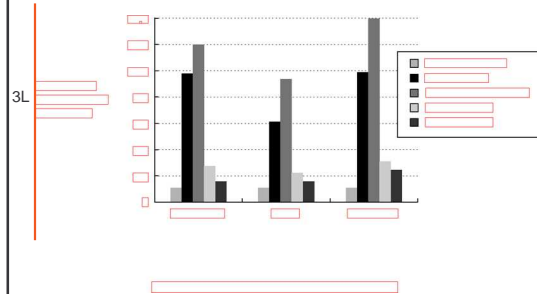
114

## Justification Process

- **Sort** the upper left and lower right points of text boxes first by x then by y. Use a plane sweep algorithm.
- **Left justify** - runs (in y) of text boxes with the same (or similar) left x coordinates.
- **Right justify** - runs (in y) of text boxes with the same (or similar) right x coordinates.
- **Center** - otherwise

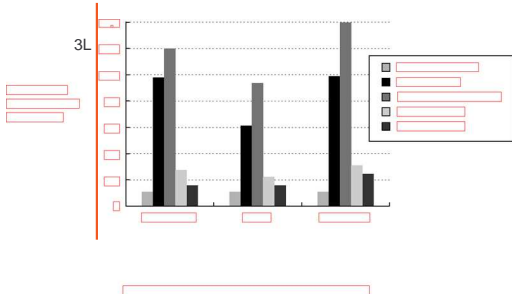
115

## Example Plane Sweep



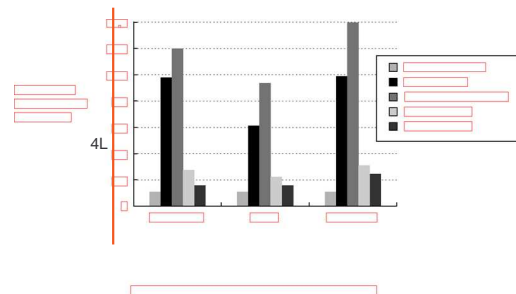
116

## Example Plane Sweep



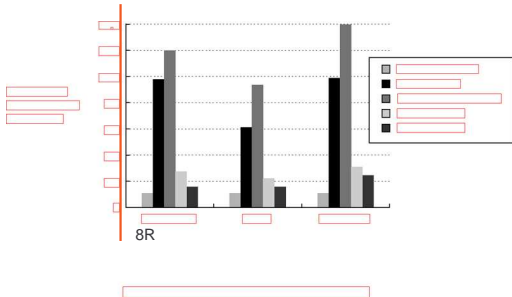
117

## Example Plane Sweep



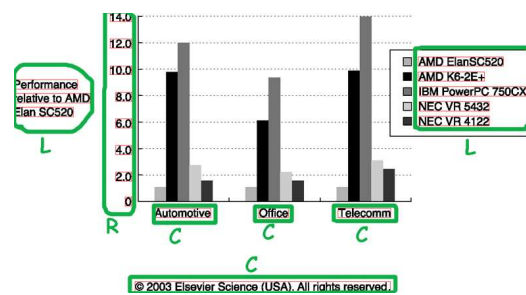
118

## Example Plane Sweep



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## Classification



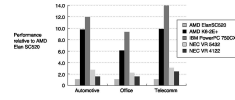
120

## Scaling

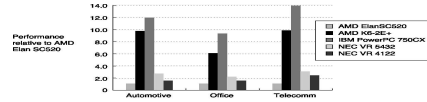
- General Procedure
  - Scale in y until the the text height is an acceptable Braille height
  - Scale in x until the Braille correctly justified fits
- The scale factor in x and y may differ, but the distorted image is usually readable.
  - The Braille text is fully readable.
- Scaling procedure is not always successful because of limited paper size.
  - Automatic abbreviations

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## Scaling Example



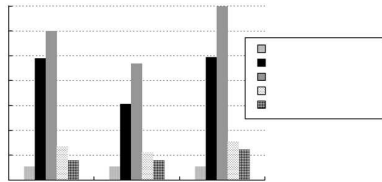
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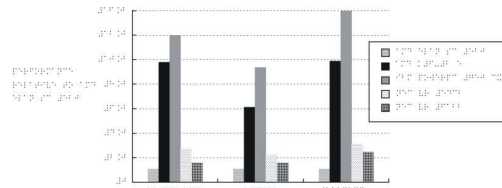
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## Color Replacement with Texture



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## Final Result



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