## CSEP 521 - Spring 2005 Assignment 1

## Due 3/7/05

1. In this problem you will modify a basic depth-first search (DFS) algorithm to find connected components of an undirected graph. Assume we are given the adjacency list representation of an undirected graph. There is an array M[1..n], with entries initially 0, that is used to indicate if a vertex has been visited. The basic recursive DFS algorithm is

```
DFS(i: vertex)
   M[i] := 1;
   for each vertex j adjacent to i do
        if M[j] = 0 then DFS(j)
end{DFS}
```

This DFS algorithm will only search the vertices that are reachable from the vertex where the algorithm is first called. Thus, we need to apply it to all the vertices.

```
Main
   for each vertex i do
        if M[i] = 0 then DFS(i)
end{Main}
```

Modify these algorithms so that i and j are in the same connected component if and only if M[i] = M[j].

- 2. Problem 23-4 on page 577 of CLRS.
- 3. One of the most famous algorithms in computer science is Dijkstra's algorithm which finds the shortest path from a single source in a weighted directed graph. This algorithms is used to find "best" routes in the Internet. Let G = (V, E) be a directed graph with weight w(i, j) > 0 for each (i, j) ∈ E. Let s ∈ V be the source vertex. We will compute d(i) and p(i) for each vertex i where d(i) is the length of the shortest past from s to i and p(i) is the predecessor of i on a shortest path from s to i. Initially, d(s) = 0 and d(i) = ∞ for all other i. Initially p(i) = 0 for all i. Initially, let Q = V

```
Dijkstra
while Q is not empty do
    choose i from Q with minimal d(i);
    remove i from Q;
    for each j adjacent to i
```

It can be shown as an invariant that if i is not in Q then the current value of d(i) is the length of the shortest path from s to i and p(i) is the predecessor on such a path.

In this problem you will show how Dijkstra's algorithm can be adapted to solve the problem of *maximally reliable path*. In this problem we are give a weighted directed graph where the weight of the edge (i, j) represents the probability that the edge (i, j) will be available for any path. This probability is just a real number r(i, j) where  $0 \le r(i, j) \le 1$ . The value 1-r(i, j) is the probability that edge (i, j) will fail. We assume that edges fail independently. Modify Dijkstra's algorithm to solve the problem, given s and t determine the most reliable path from s to t. The reliability of a path is the product of availability probabilities of the edges on the path.