check out all these logos



Verb Physics and factor graphs

Max Forbes pretending to be Yejin Choi

January 29, 2020 CSE 447 / 547

Today's takeaways

1. NLP needs commonsense

2. We can learn (some) commonsense from text!

Today's takeaways

1. NLP needs commonsense PART I

2. We can learn (some) commonsense from text! **PART II**

Today's takeaways

1. NLP needs commonsense PART I

2. We can learn (some) commonsense from text! **PART II**

Factor graphs PART II — INTERLUDE

PART I NLP needs commonsense

COMMONSENSE IN: SYNTACTIC PARSING





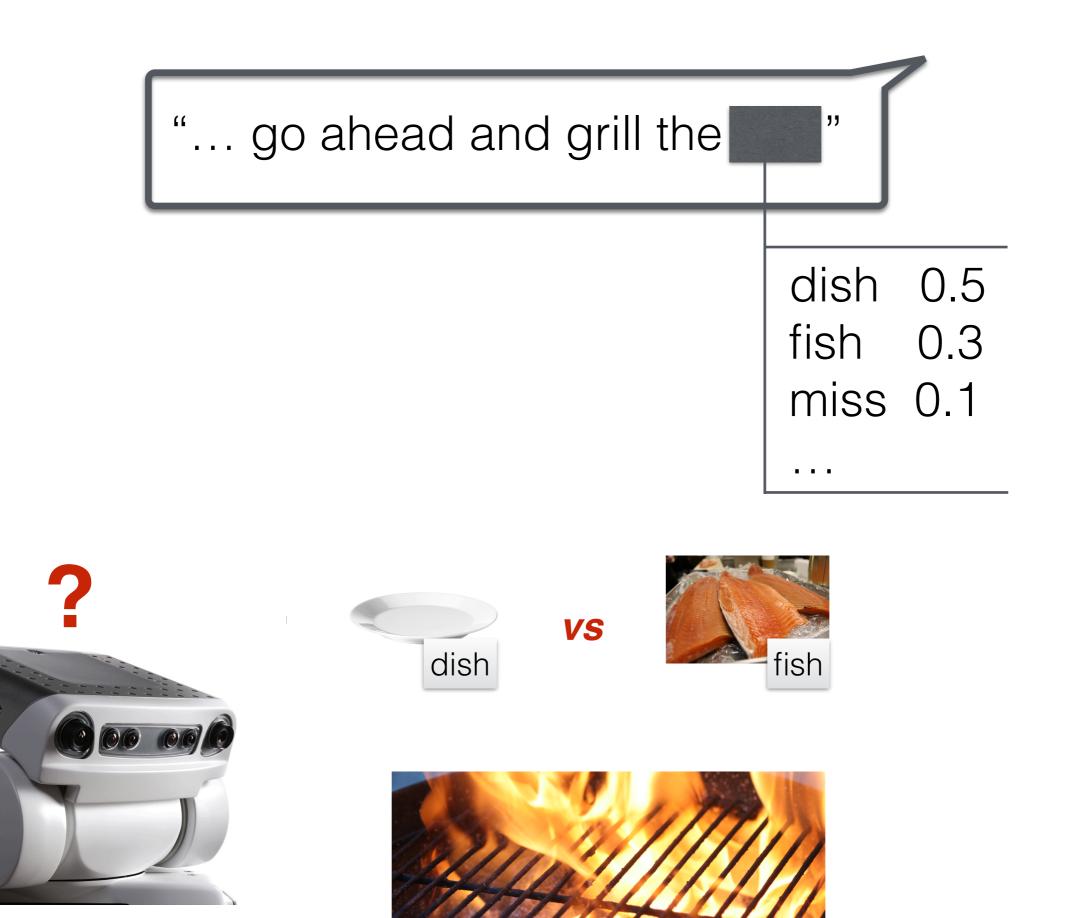


COMMONSENSE IN: COREFERENCE RESOLUTION

Obama met Jobs to discuss the economy, technology, and education. After the meeting he signed a bill to introduce [...]



COMMONSENSE IN: SPEECH RECOGNITION



COMMONSENSE IN: NATURAL LANGUAGE GENERATION

- Preheat the oven to 350 F.
- Tenderize the chicken with a large mallet.
- Season the chicken with the spice mixture.
- Serve chicken on top of a bed of rice.

Done!?





The large ball crashed right through the table because it was made of **steel**.

What was made of **steel**?

The large ball crashed right through the table because it was made of **styrofoam**.

What was made of **styrofoam**?

[Levesque 2012]

PART II Verb Physics

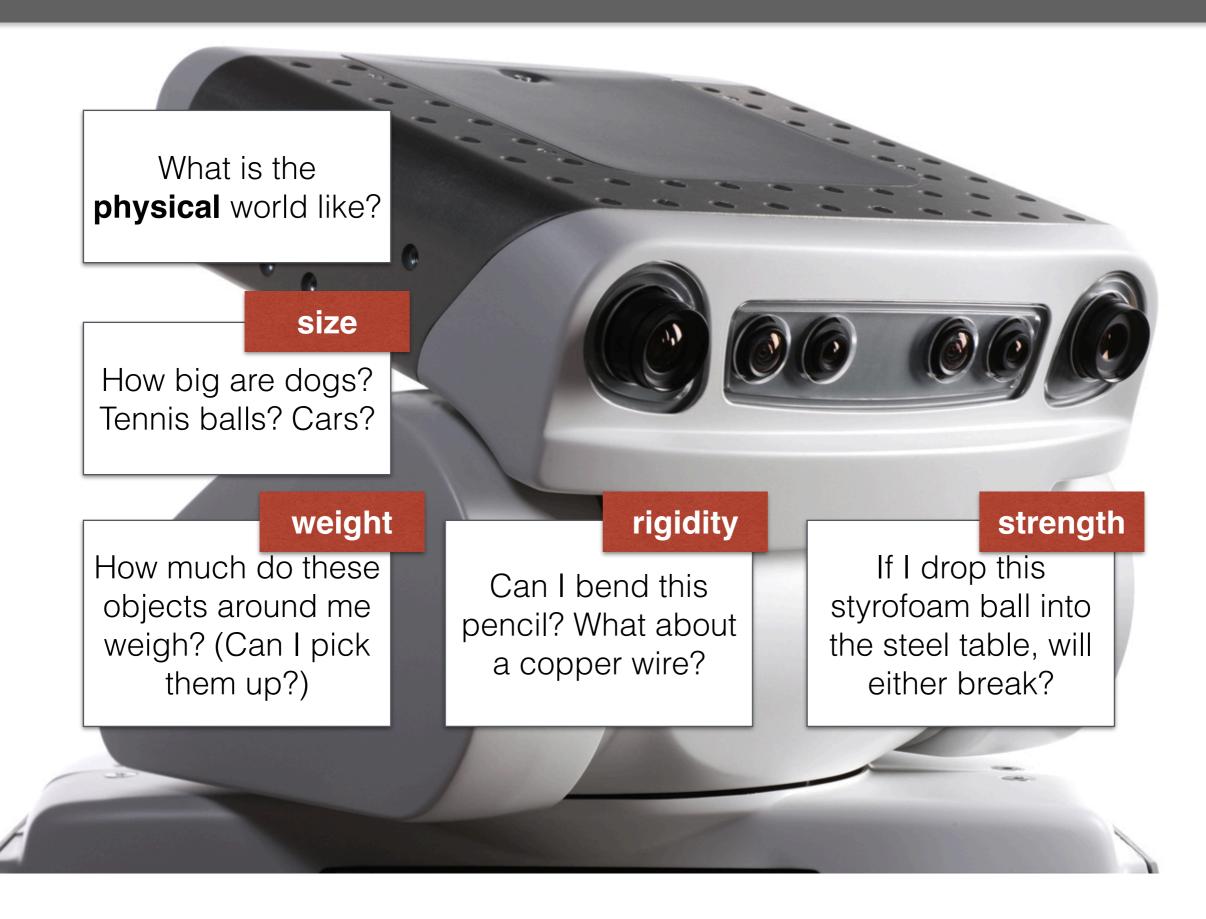








Physical properties of objects



"I am larger than a chair"



"Ham larger than a pen"

"Ham larger than a stone"

"Ham larger than a chair"

"I am larger than a ball"

"I am larger than a towel"

[Grice, 1975] [Sorower et al., 2011] [Misra et al., 2016]

"The horse was as small as a dog!"

 \implies horse =^{size} dog ?

"Hey robot, pass me the <unk>."

"OK." (attempts to pick up table)

C

" *picked up* the <thing>."

"I took a **drink from** the <thing>."

"The <thing> **shattered** when it hit the ground





Two related problems

Physical properties implied by predicates

Physical properties of objects

"I picked up the <thing>."

"I took a **drink from** the <thing>."

"The <thing> **shattered** when it hit the ground







1. Introduction 2. Related work 3. Approach 4. Model 5. Data 6. Evaluation

Two related problems

Physical properties implied by predicates

Physical properties of objects

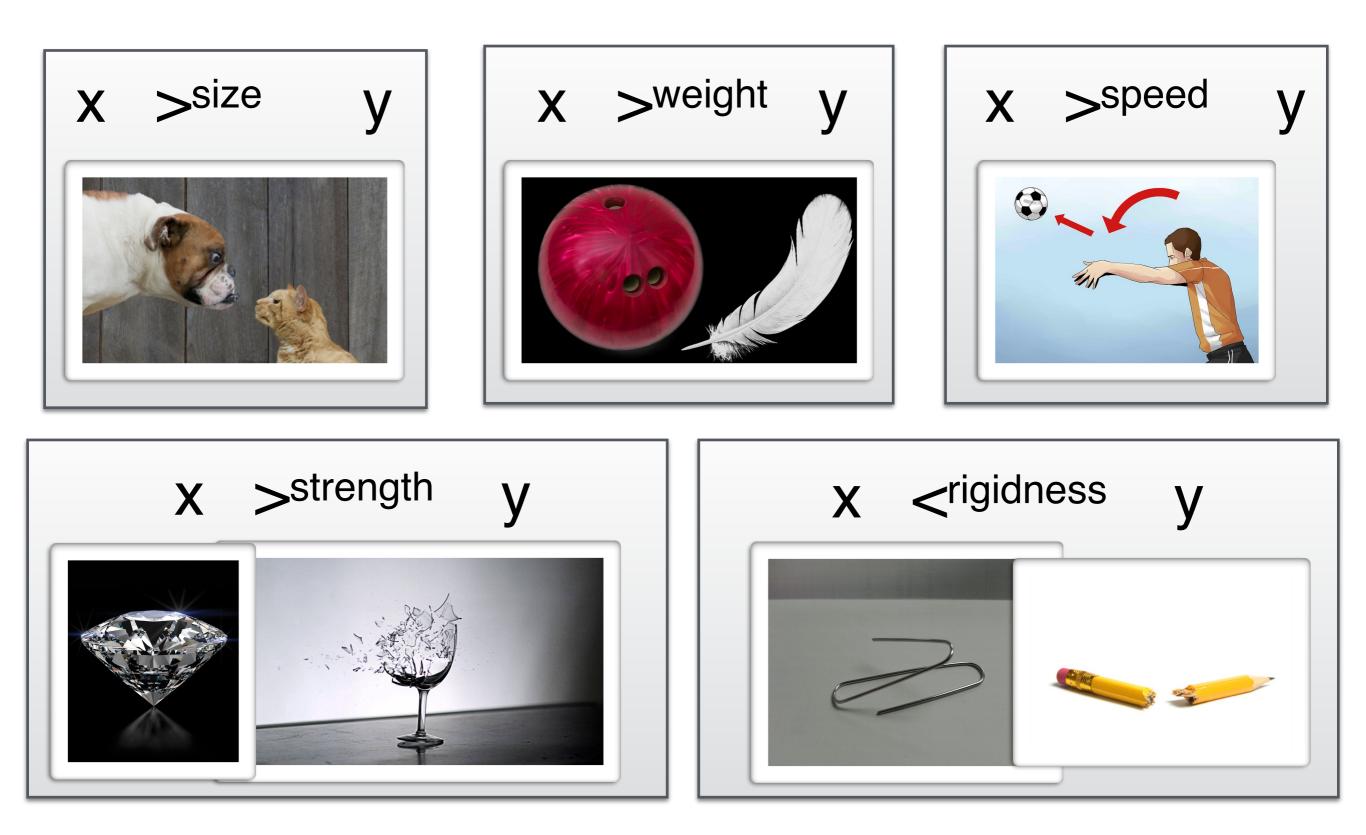
"I picked up the <unk>."

"I took a **drink from** the <unk>."

"The <unk> **shattered** when it hit the ground



Attributes



X >weight V X <rigidness У X <strength У X <speed Stage-level У

Y

X >^{size}

Individual-level

Always true

True in window surrounding predicate

[Carlson, 1977]

ball stone chair



chair game party

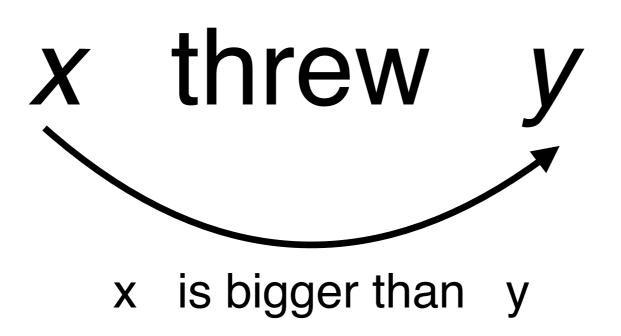
stone

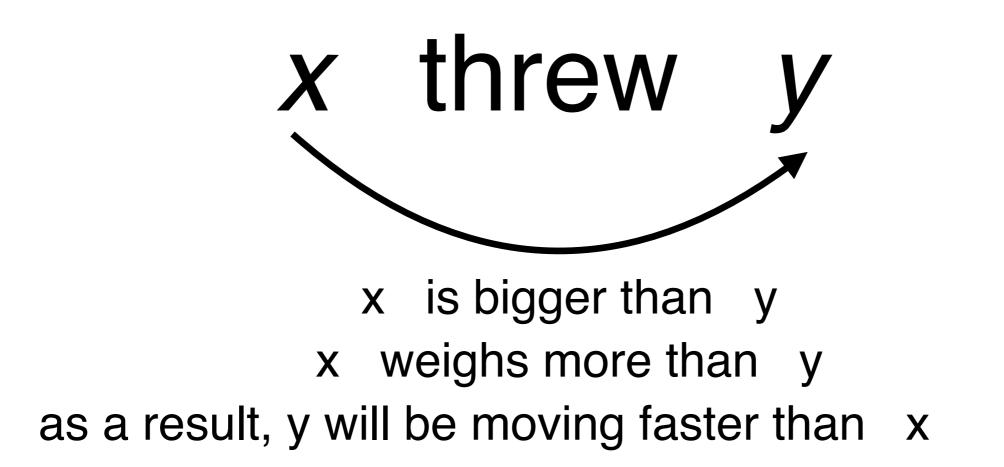
ball



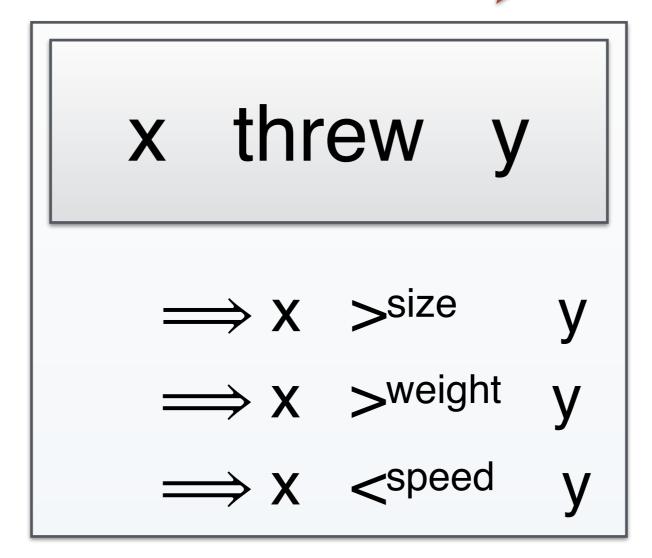
ball stone chair

x threw y









Terminology

Action frames — simple syntax-based verb constructions that compare two objects

Terminology

Action frames — simple syntax-based verb constructions that compare two objects

x threw *y* PERSON threw *x* into *y* PERSON threw on *x*

> distinct action frames for the same verb

Terminology

Action frames — simple syntax-based verb constructions that compare two objects PERSON threw x into y PERSON threw on x

Objects — non-abstract nouns

- ✓ ball X evil
- √ train X time

Two related problems

Physical properties implied by predicates

Physical properties of objects

"I picked up the <thing>."

"I took a **drink from** the <thing>."

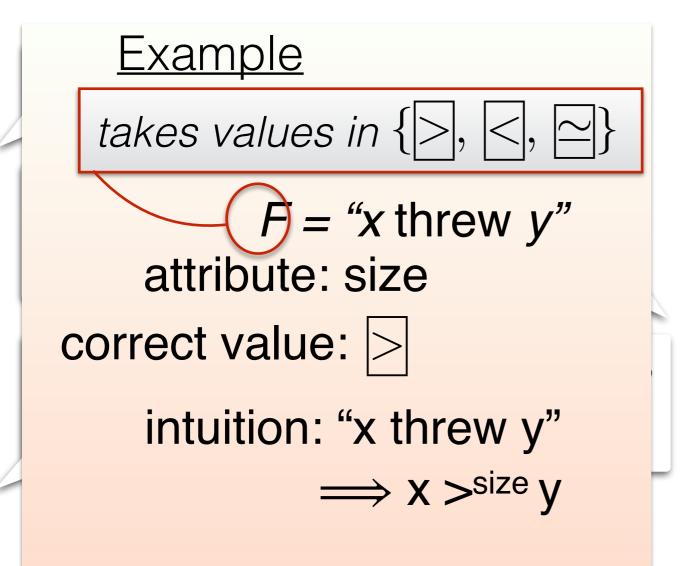
"The <thing> **shattered** when it hit the ground



Two related problems

Physical properties implied by predicates

Physical properties of objects

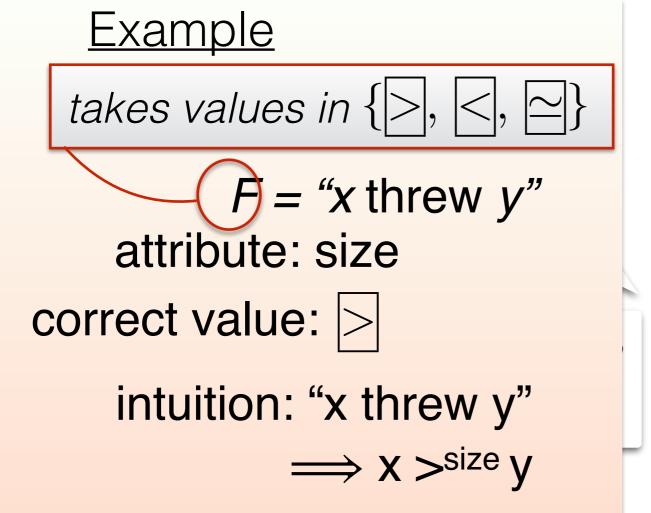


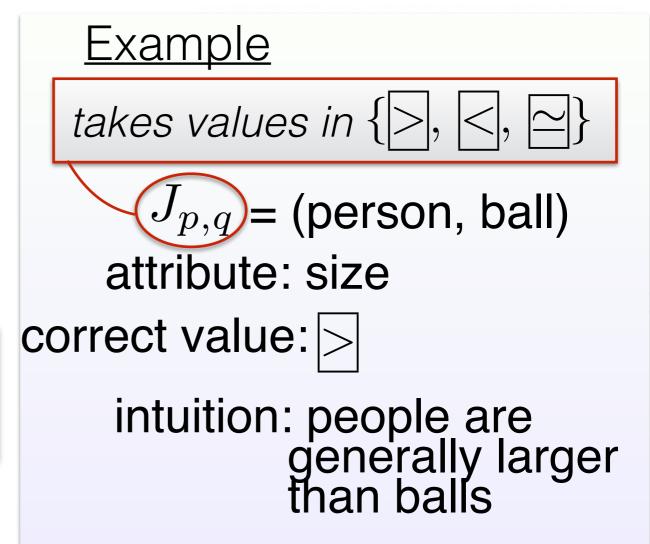


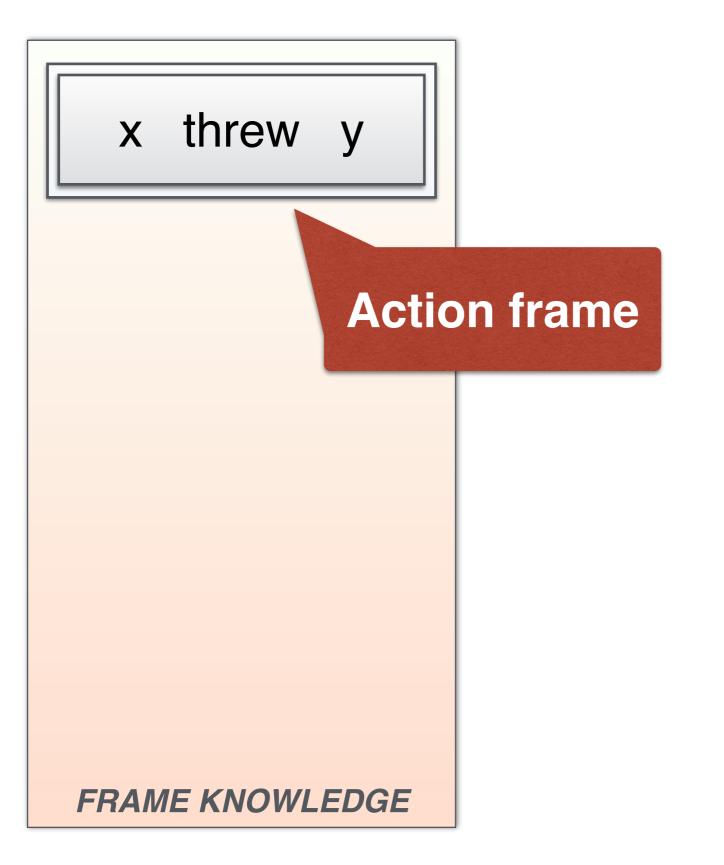
Two related problems

Physical properties implied by predicates

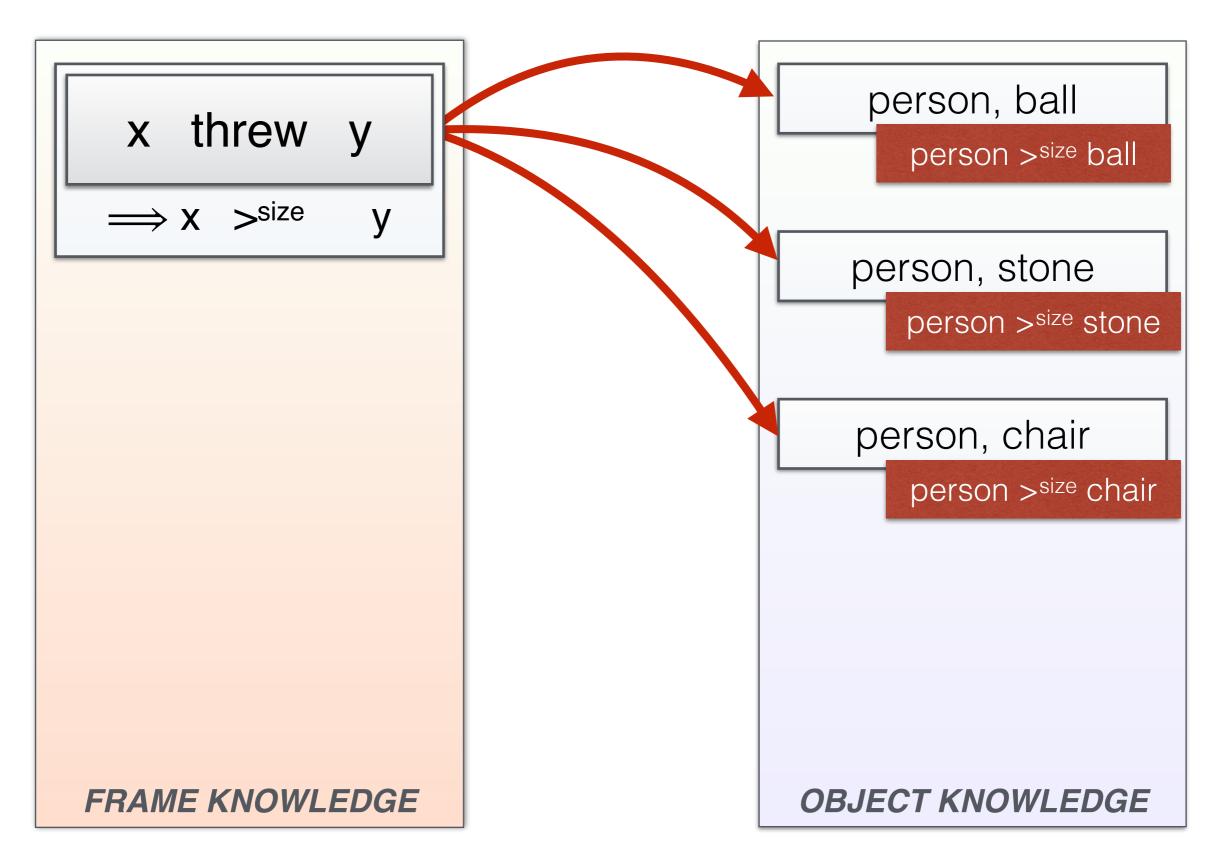
Physical properties of objects

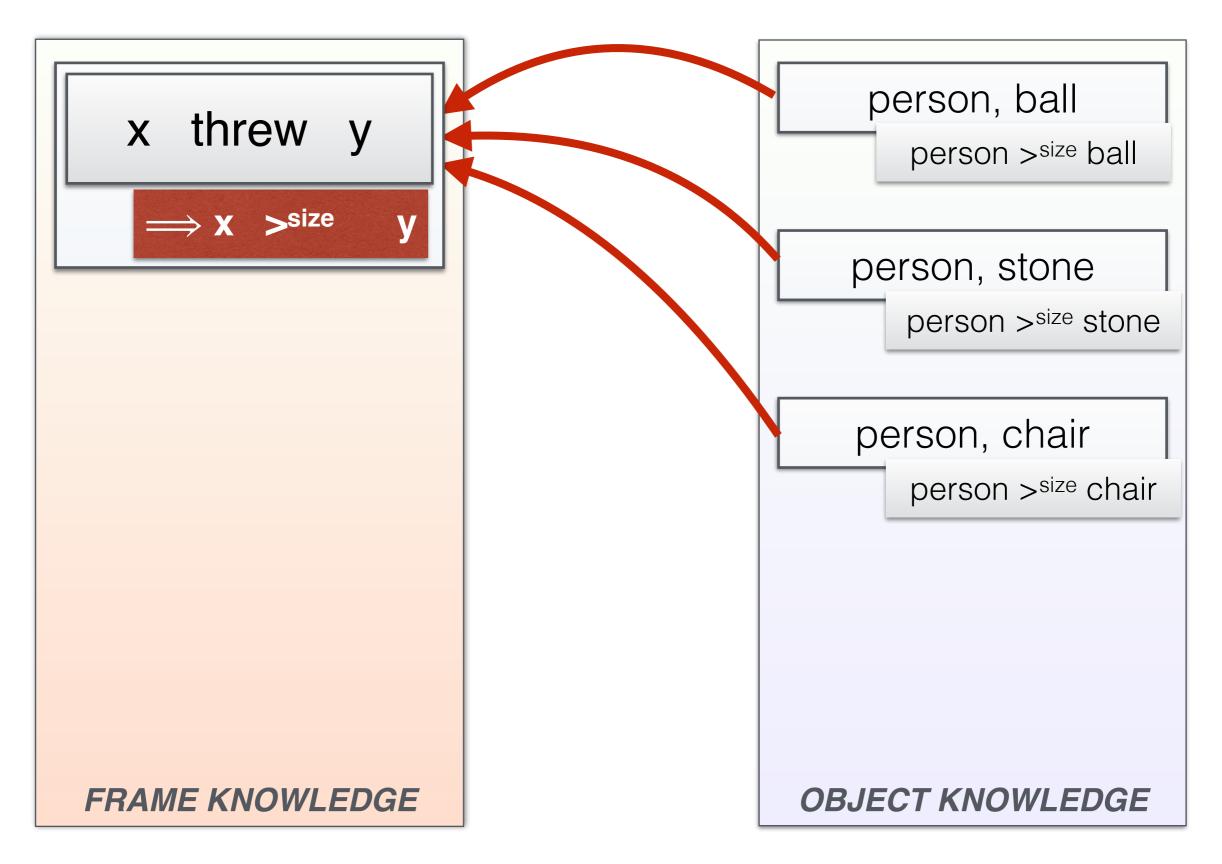


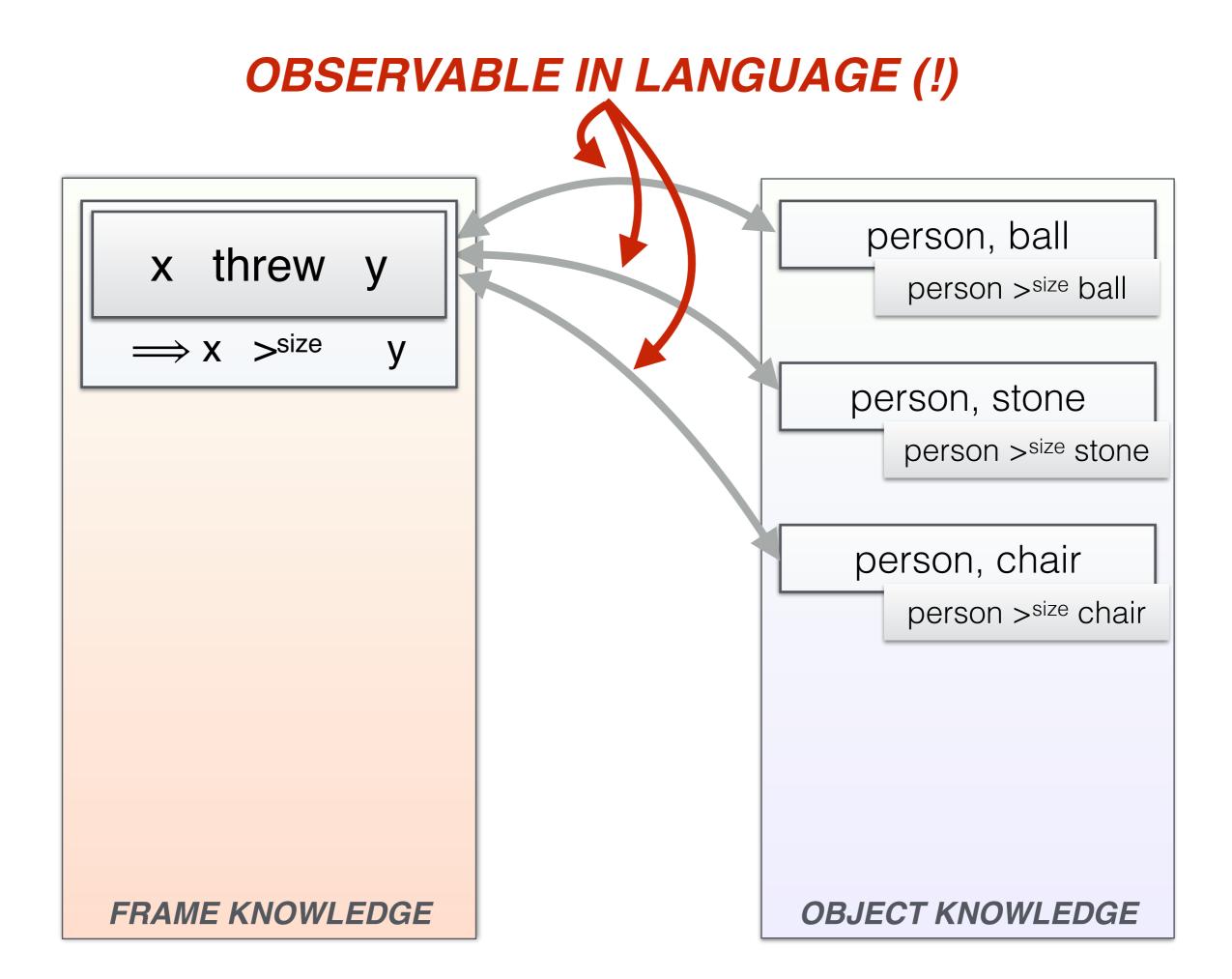




x threw y	person, ball		
		person, stone	
		person, chair	
FRAME KNOWLEDGE		OBJECT KNOWLEDGE	



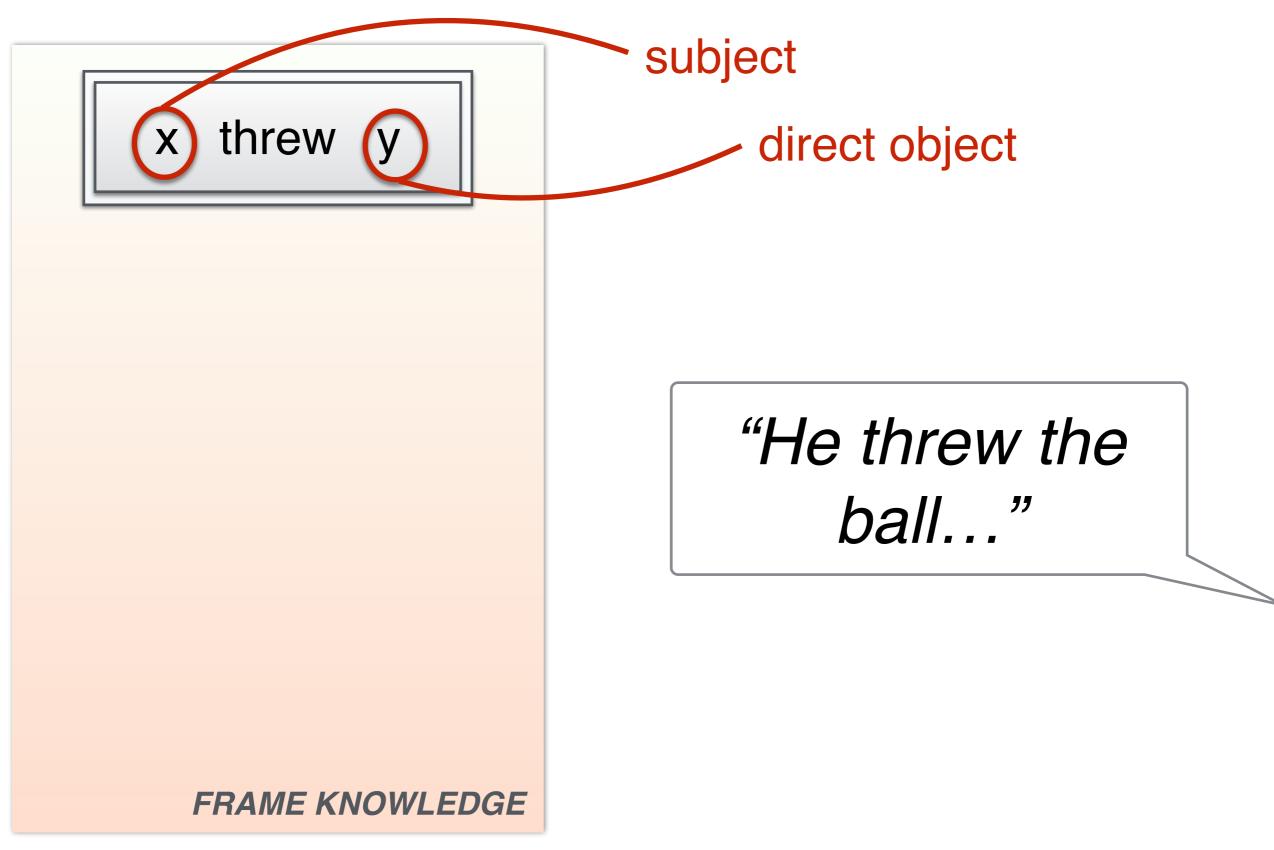


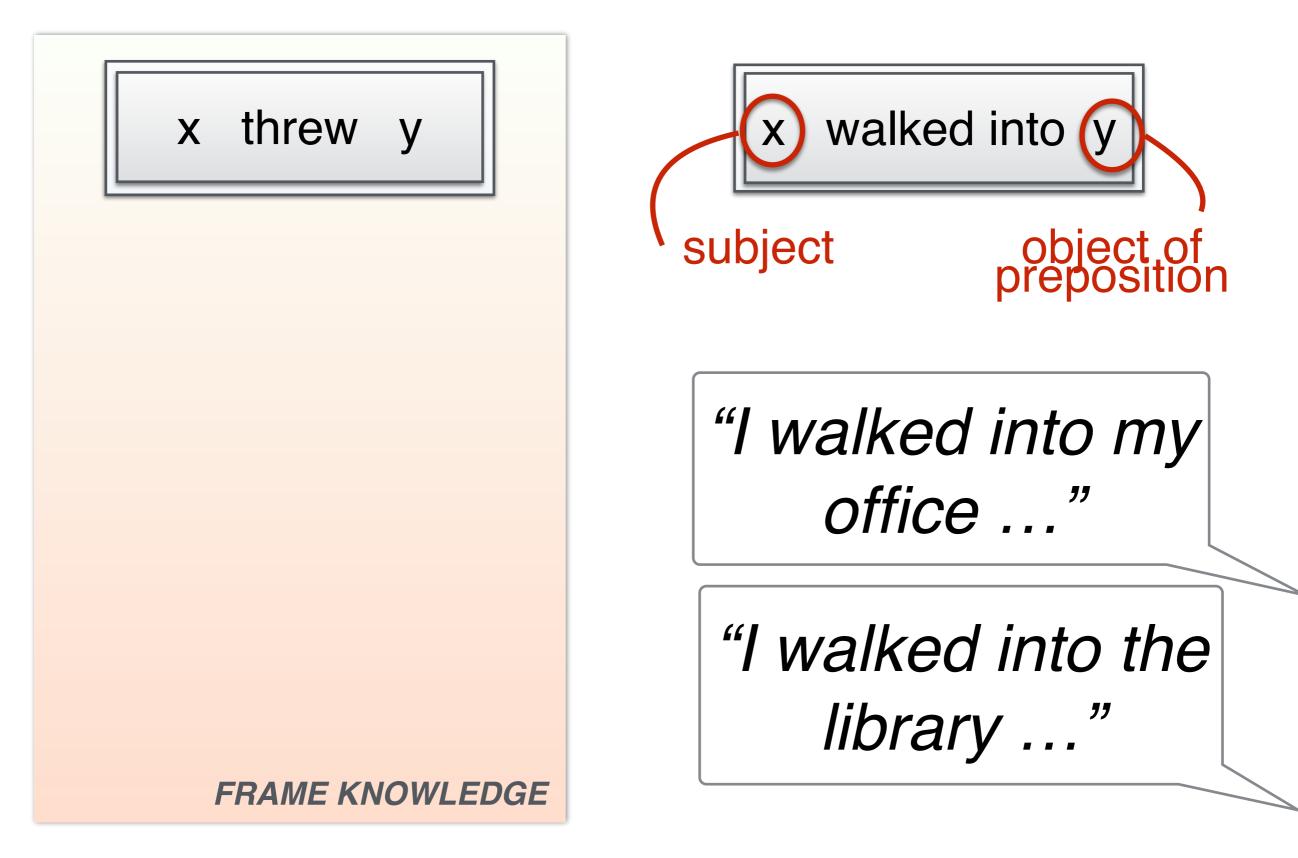


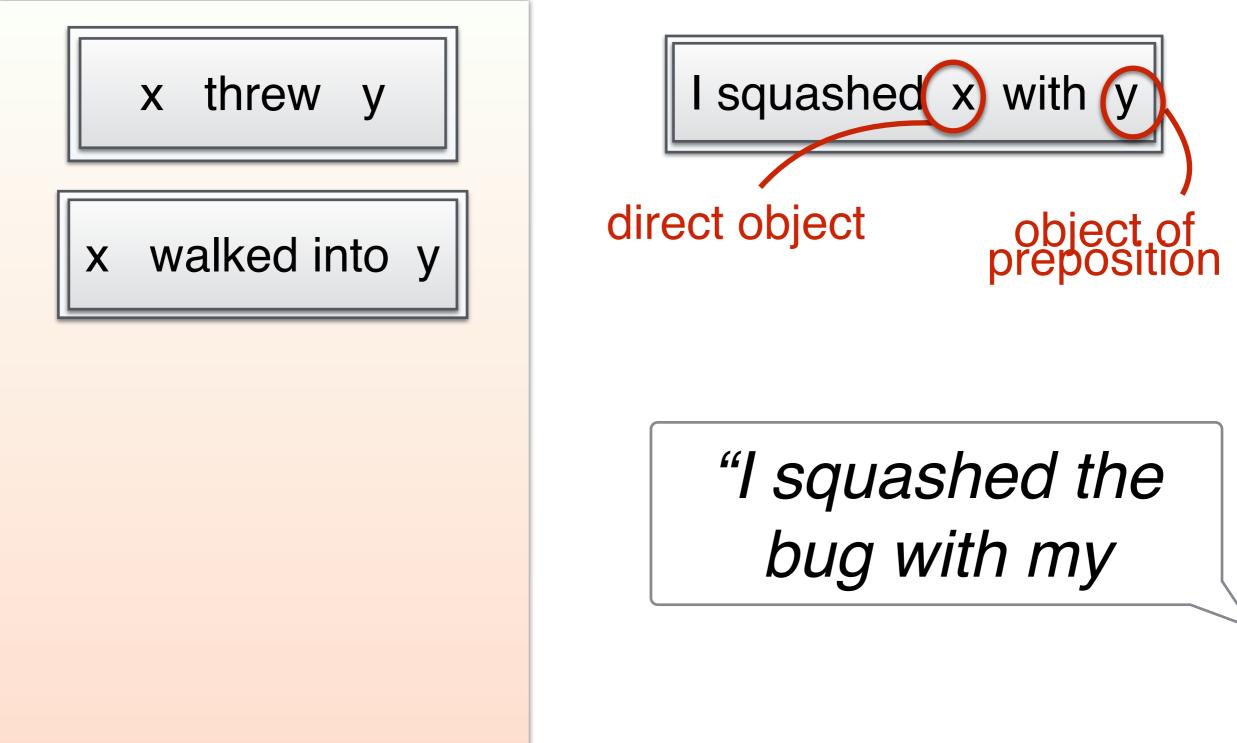
x threw y

"He threw the ball..."

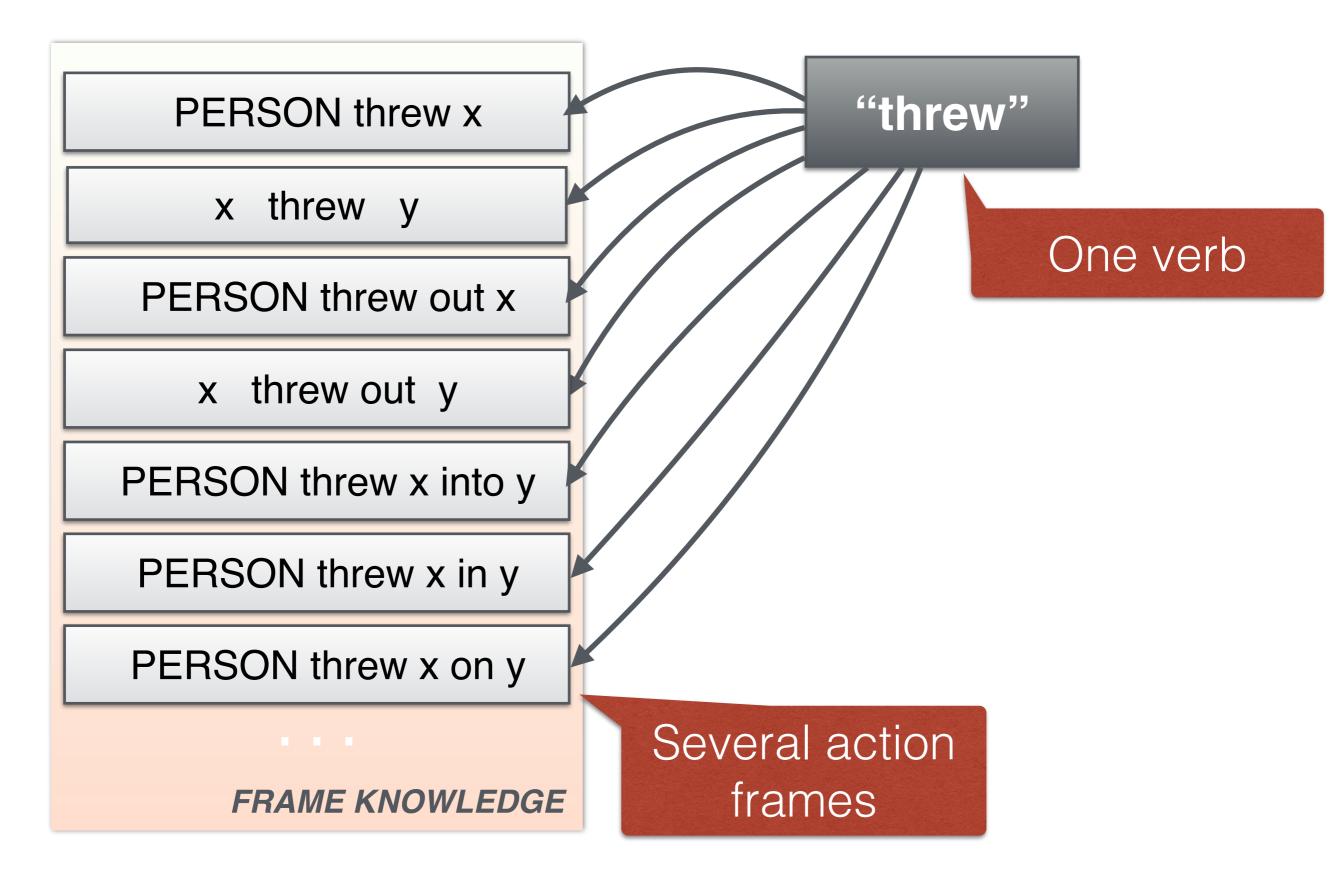
FRAME KNOWLEDGE



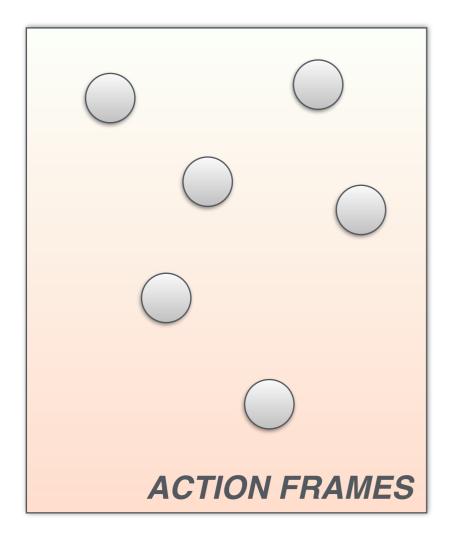


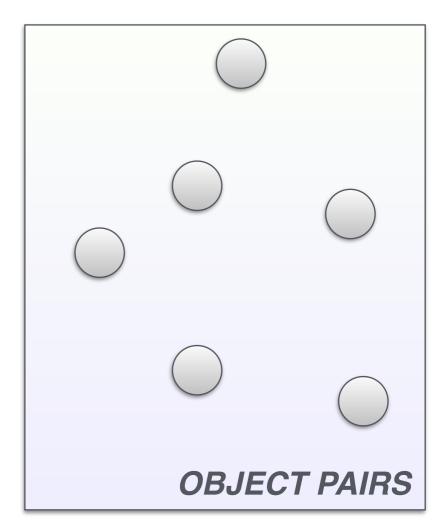


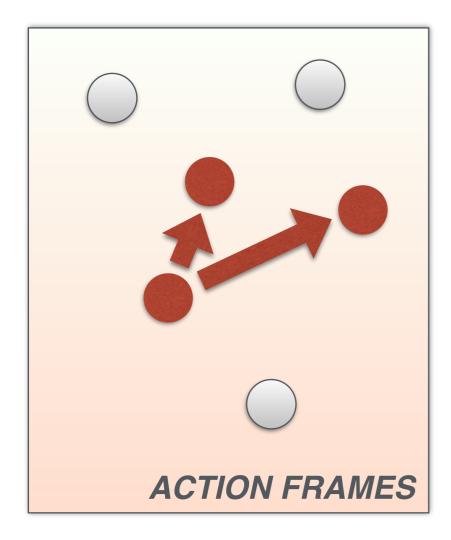
FRAME KNOWLEDGE

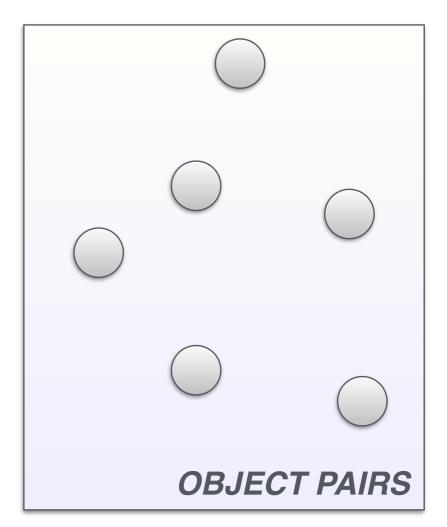


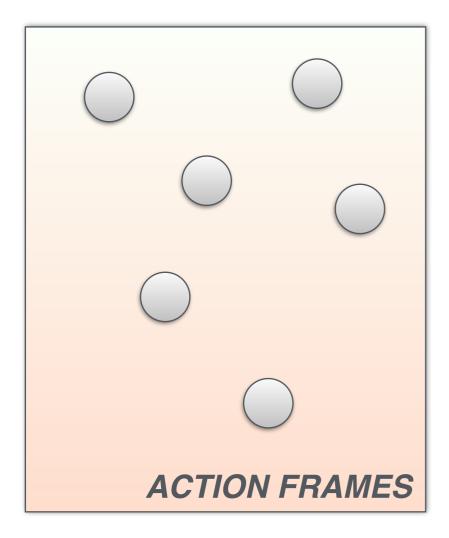
1. Introduction 2. Related work 3. Approach 4. Model 5. Data 6. Evaluation

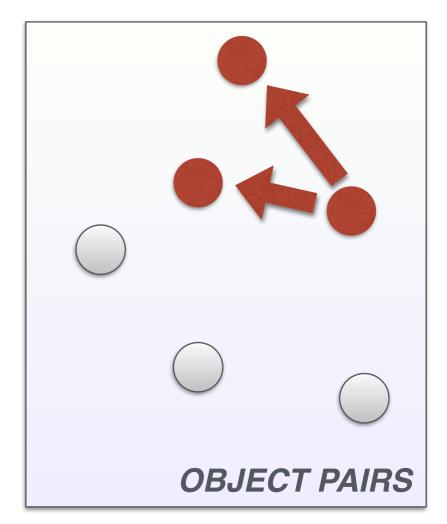


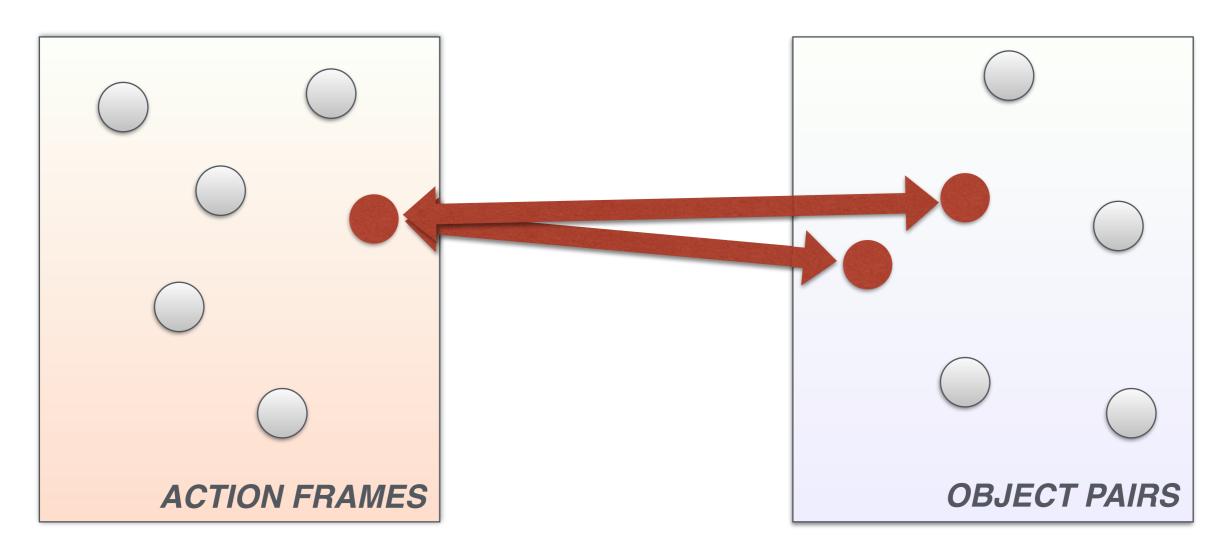




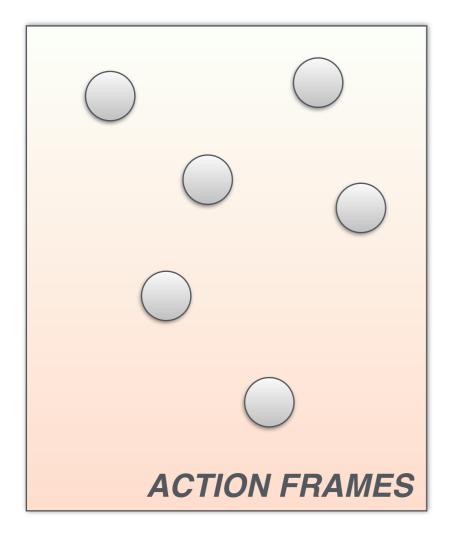


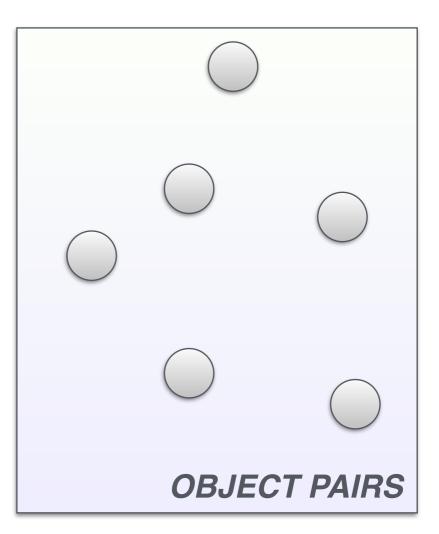




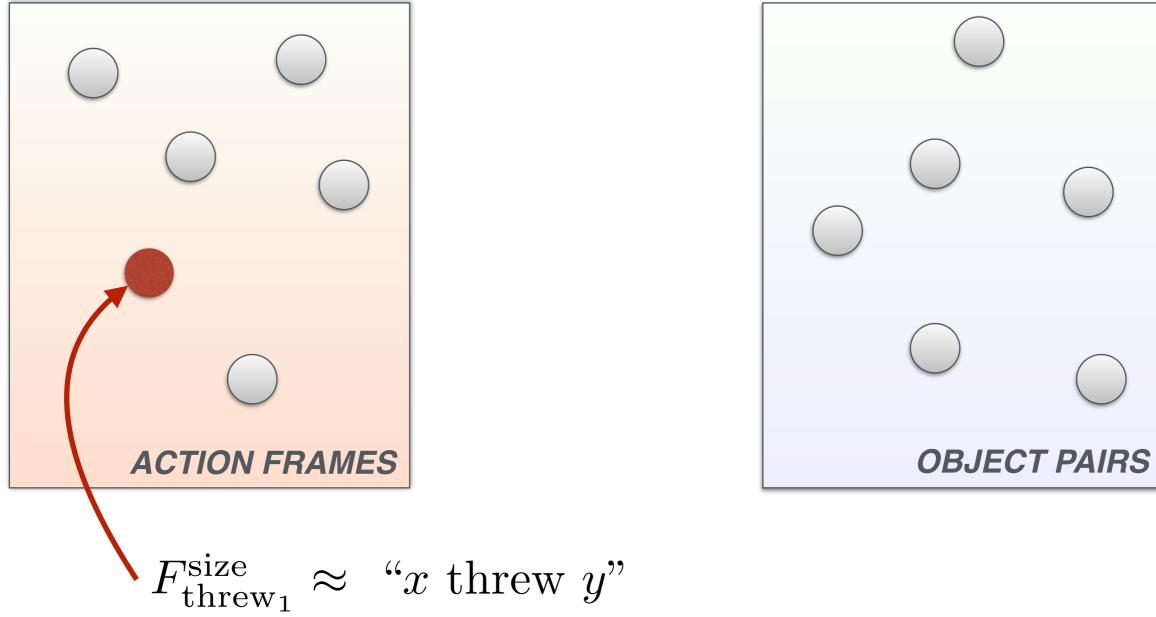


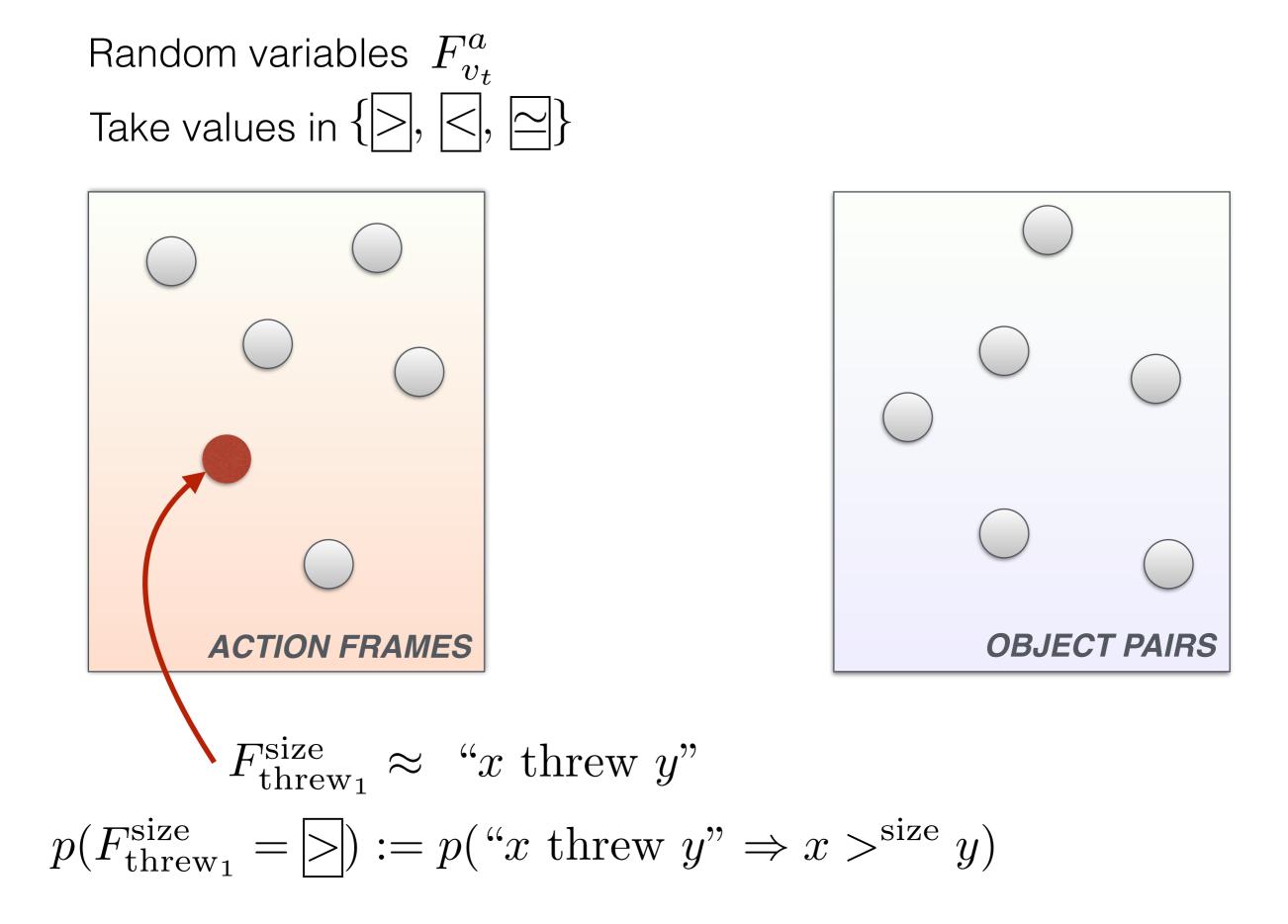




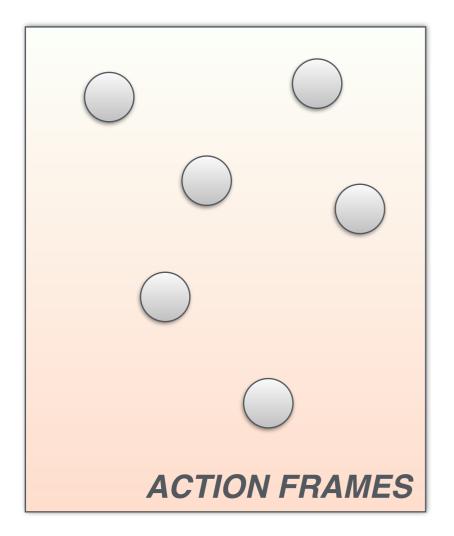




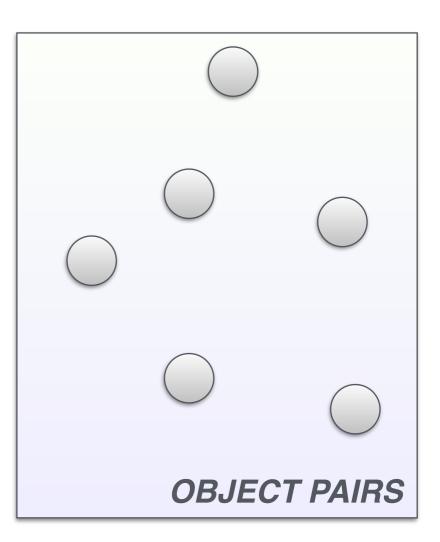


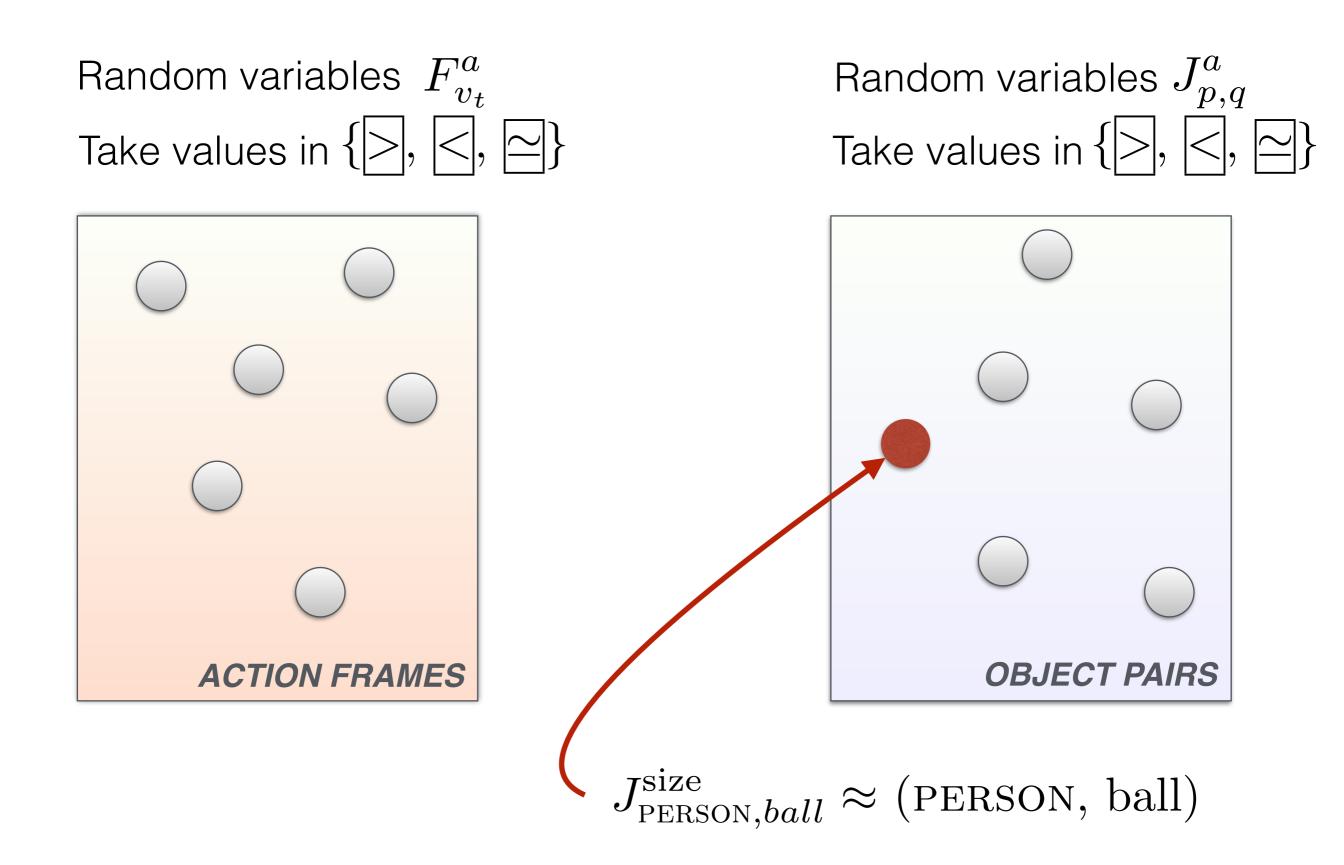


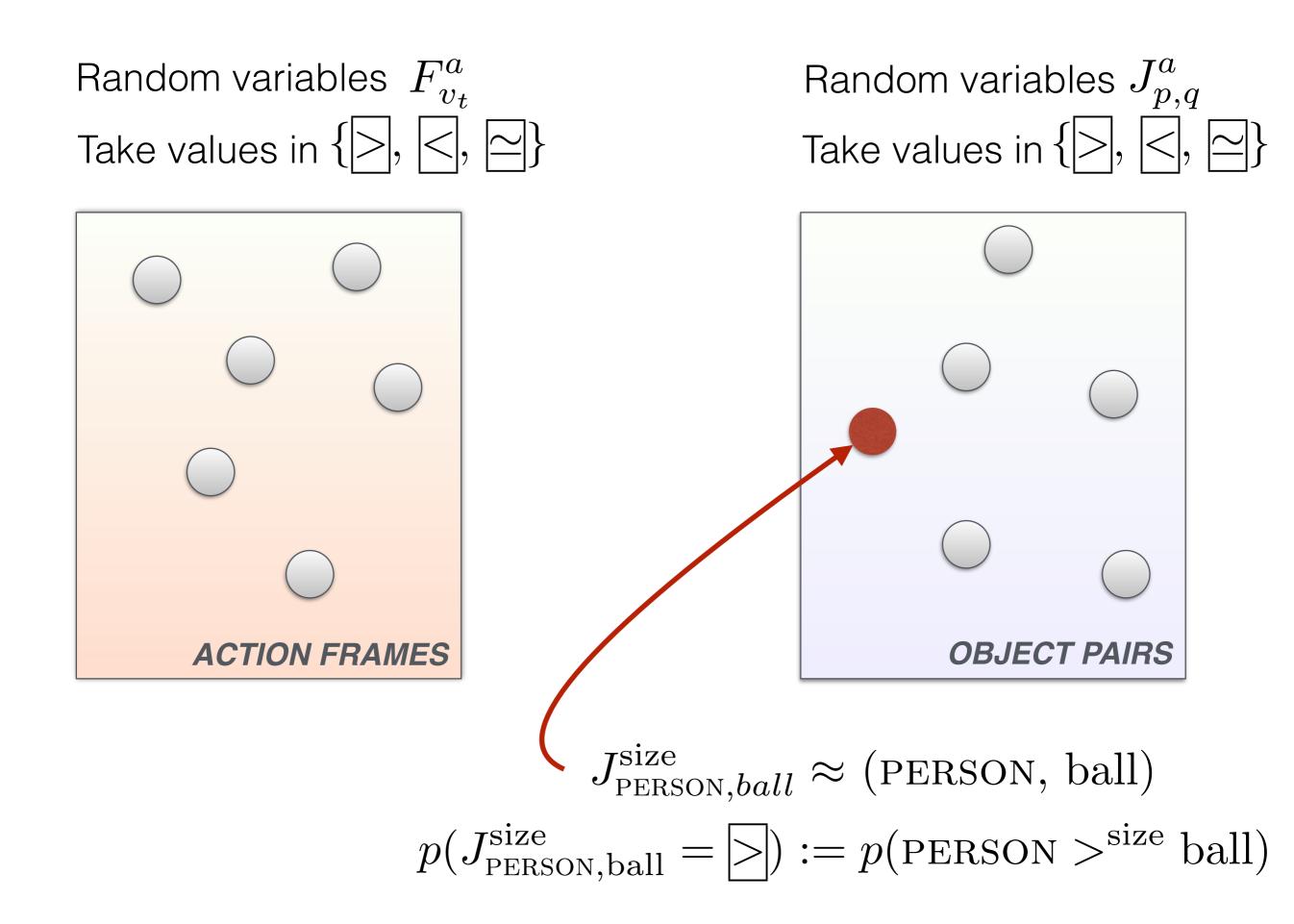




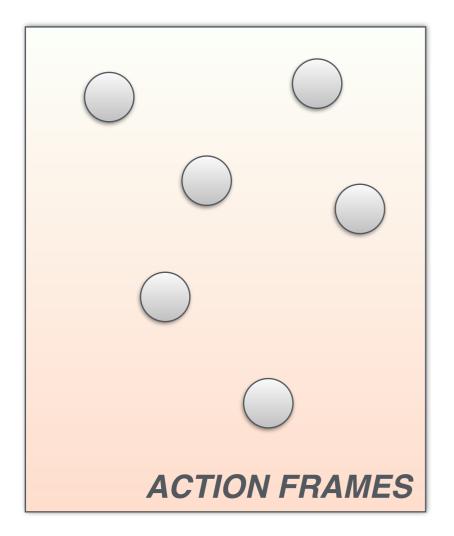
Random variables $J^a_{p,q}$ Take values in $\{\geq, \leq, \cong\}$



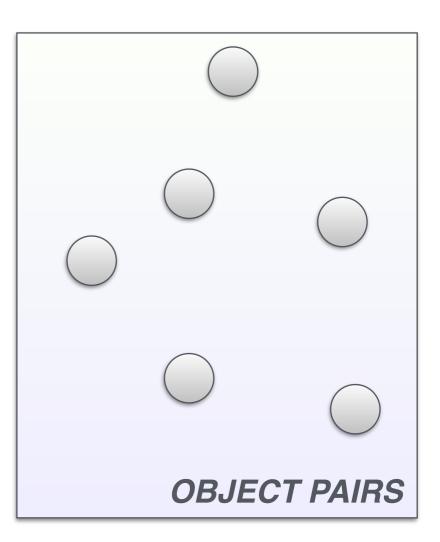


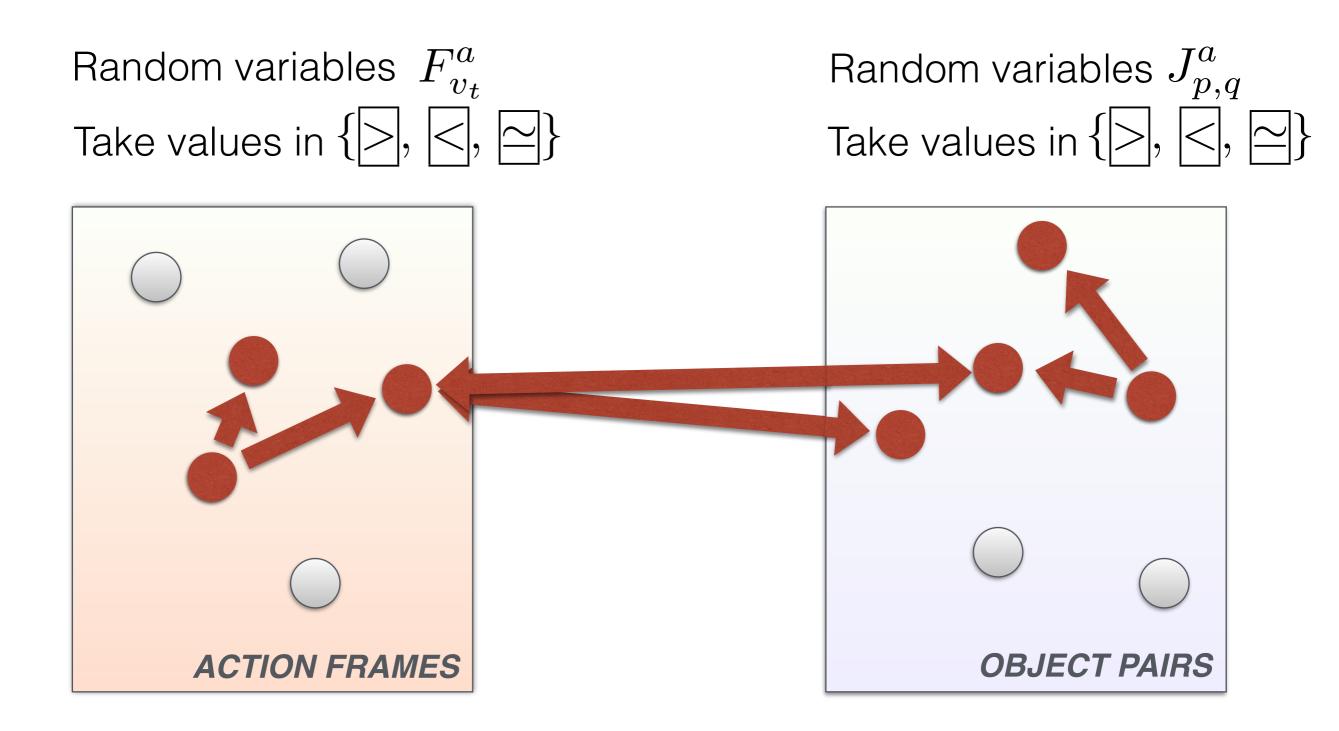






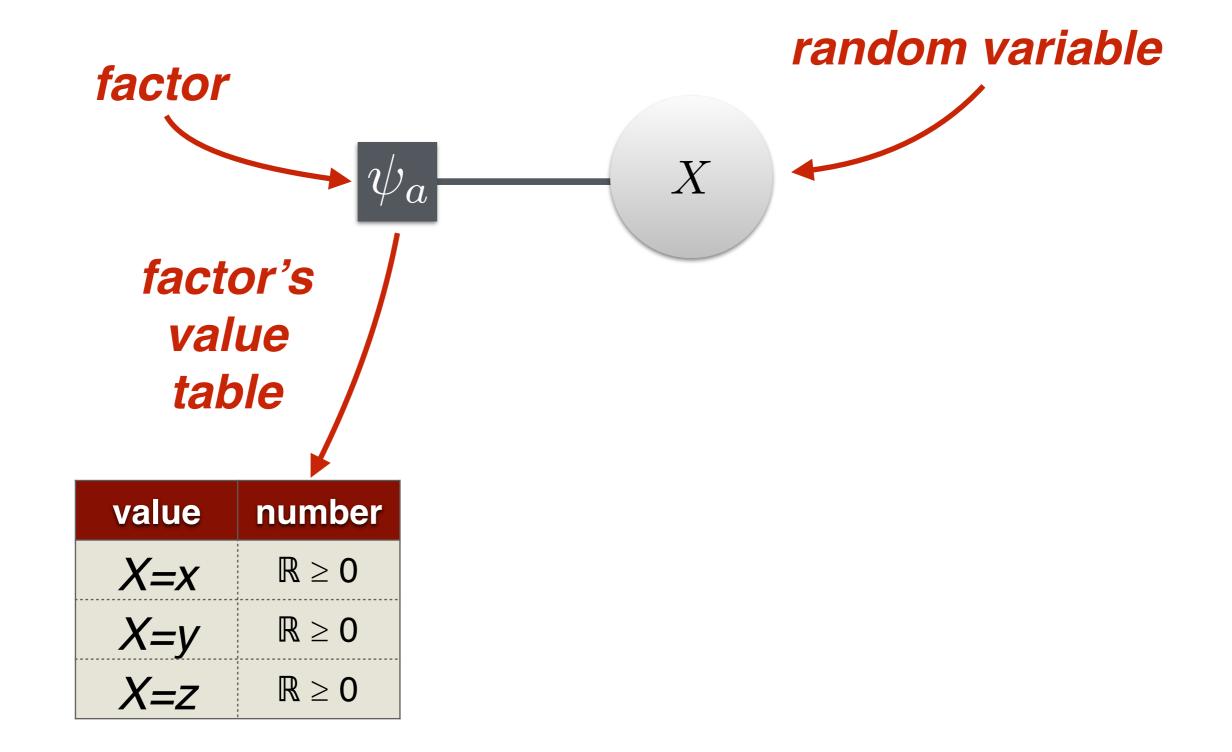
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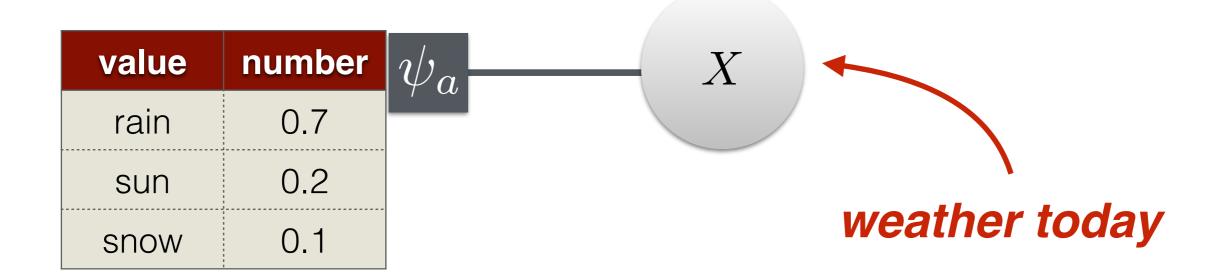


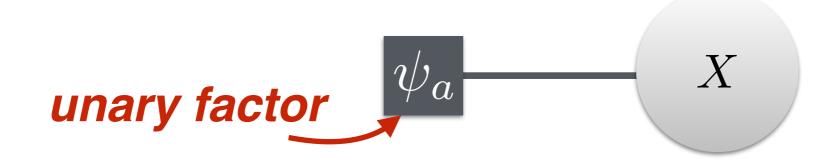
PART II — INTERLUDE Factor graphs

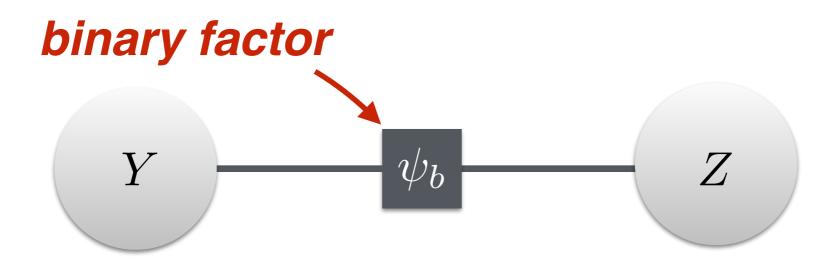
FACTOR GRAPHS BASICS

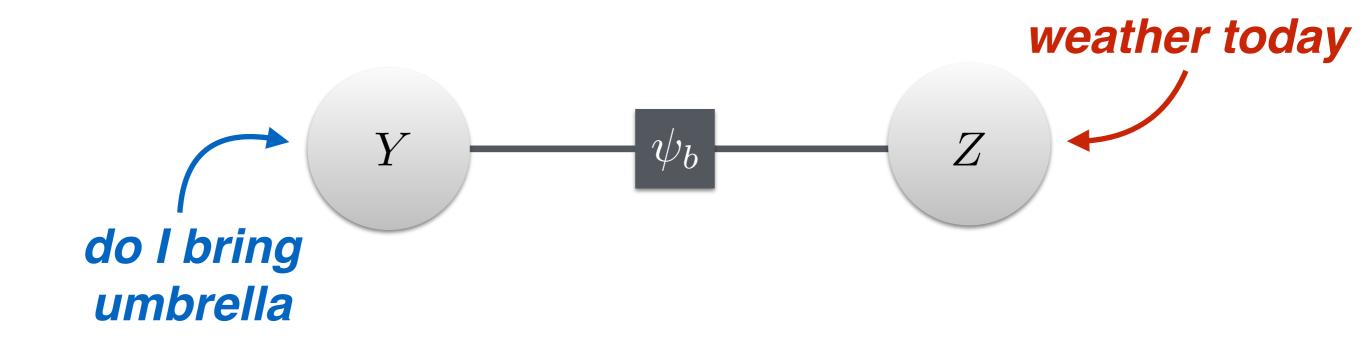


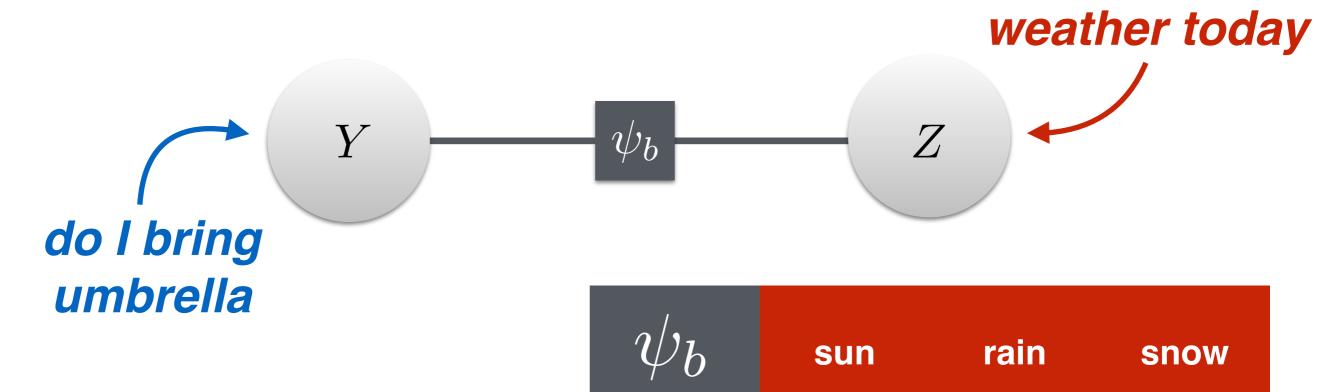
FACTOR GRAPHS BASICS



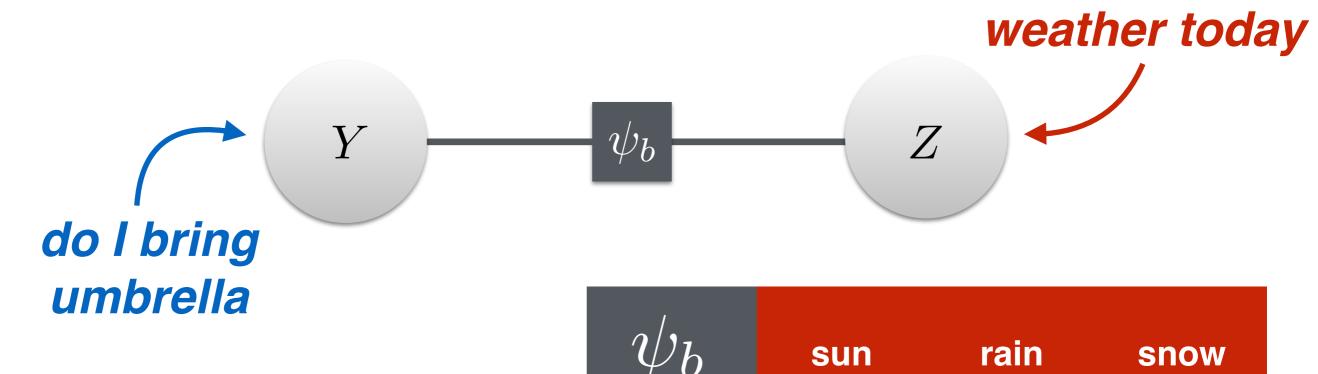








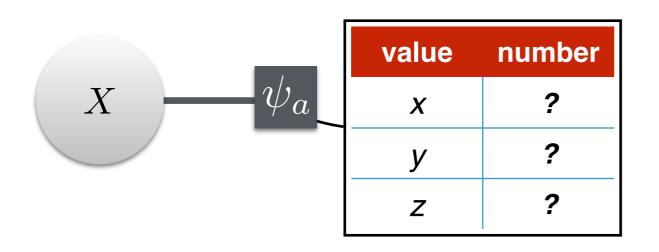
ψ_b	sun	rain	snow
yes	?	?	?
no	?	?	?

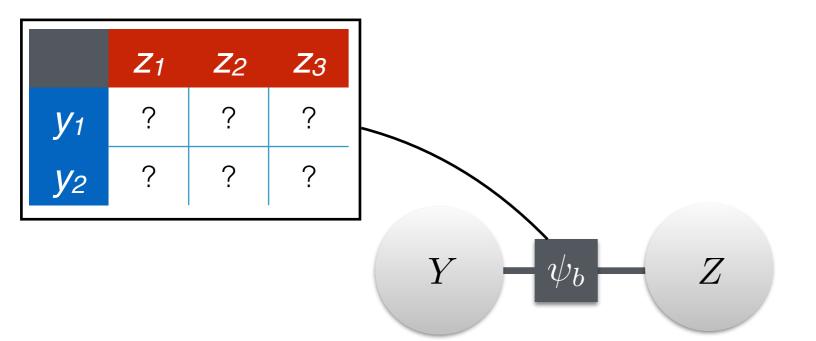


ψ_b	sun	rain	snow		
yes	0.1	0.8	0.7		
no	0.9	0.2	0.3		
n/umbrollolucether)					

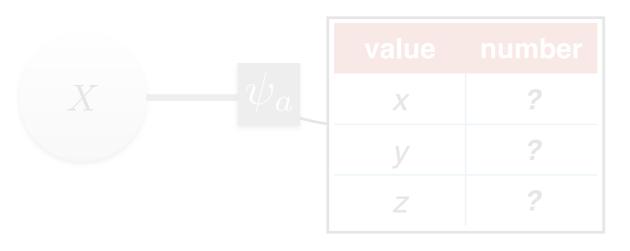
p(umbrellalweather)

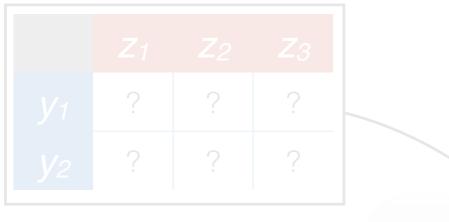
What numbers are in the factors' value tables?

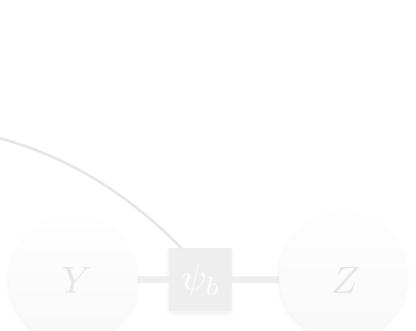




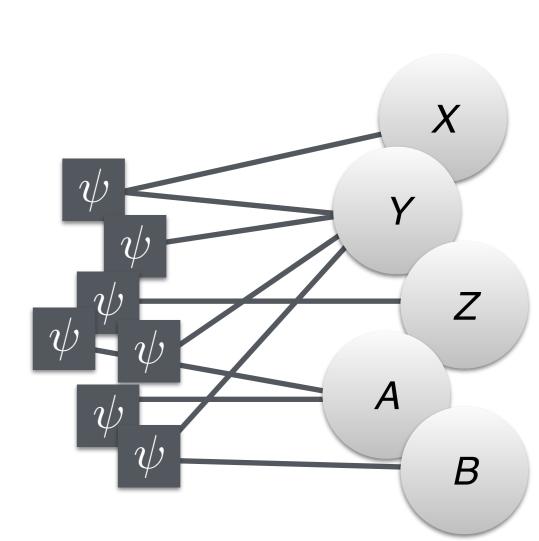
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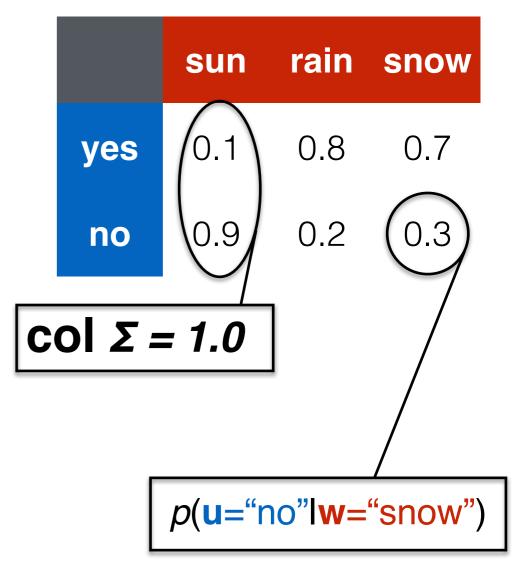
What is the graph structure?



Factors can contain

1. conditional probability tables can use to construct "old-school" graphical models

p(umbrellalweather)



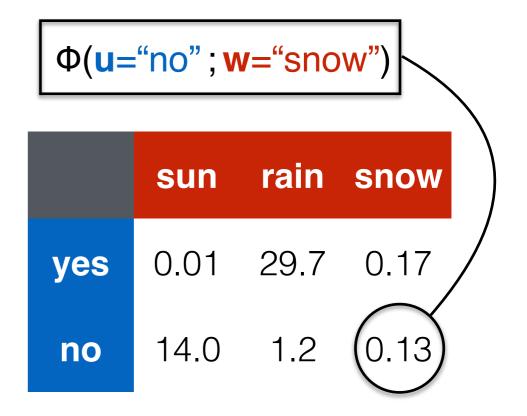
Factors can contain

1. conditional probability tables can use to construct "old-school"

graphical models

2. potential functions (arbitrary nonnegative values)

can use to construct Markov random fields (MRFs) (AKA "Markov networks")



Φ(umbrella; weather)

FACTOR GRAPHS DESIGN SPACE

Factors can contain

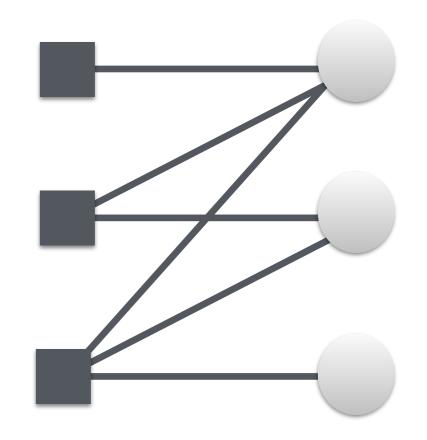
1. conditional probability tables can use to construct "old-school" graphical models

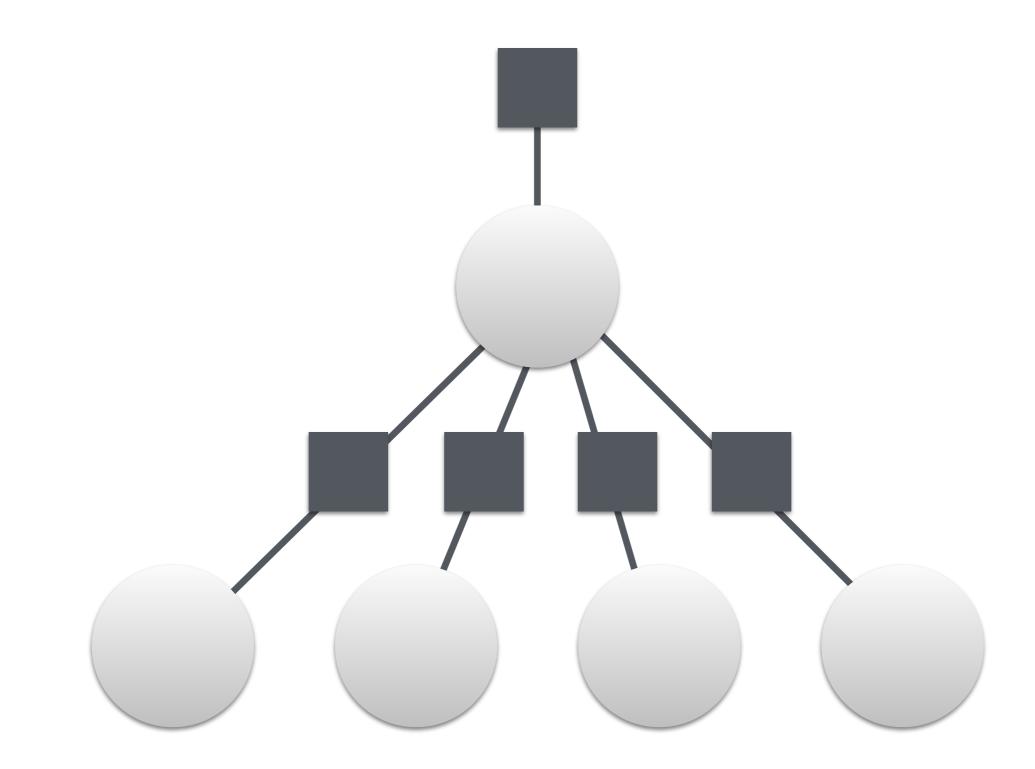
2. potential functions (arbitrary nonnegative values)

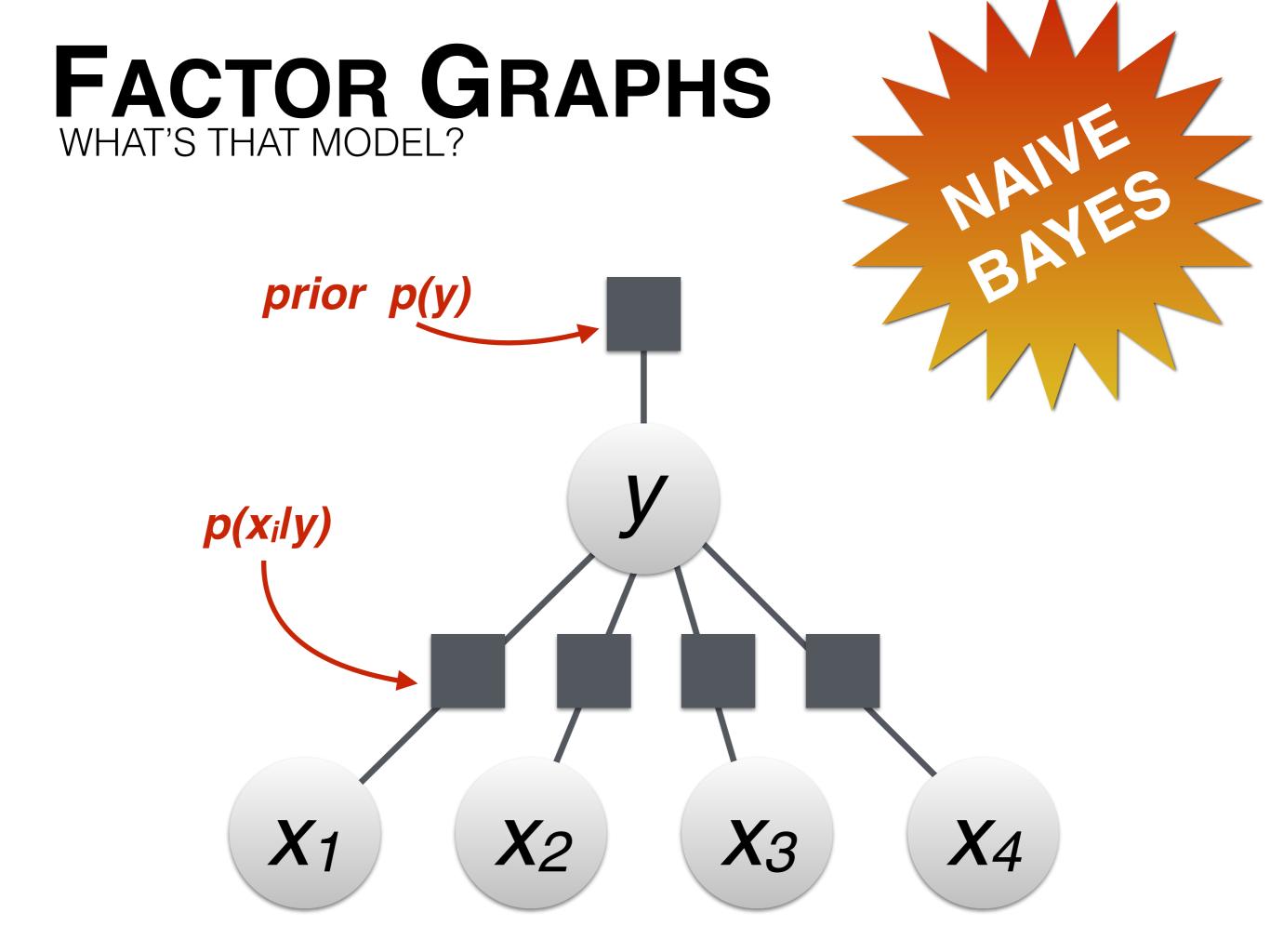
can use to construct Markov random fields (MRFs) (AKA "Markov networks")

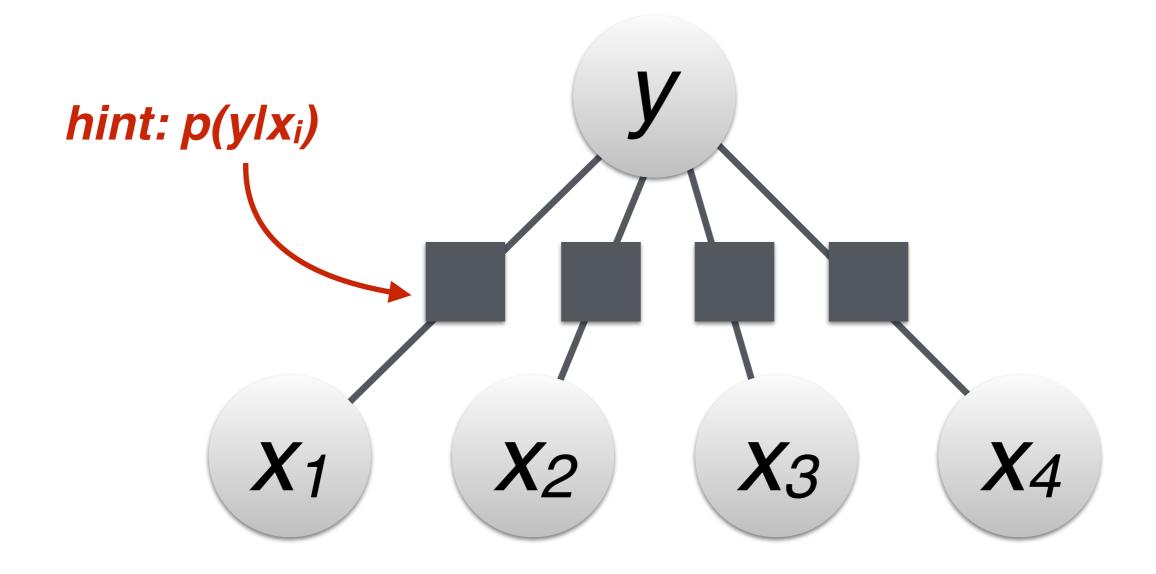
Graph structure

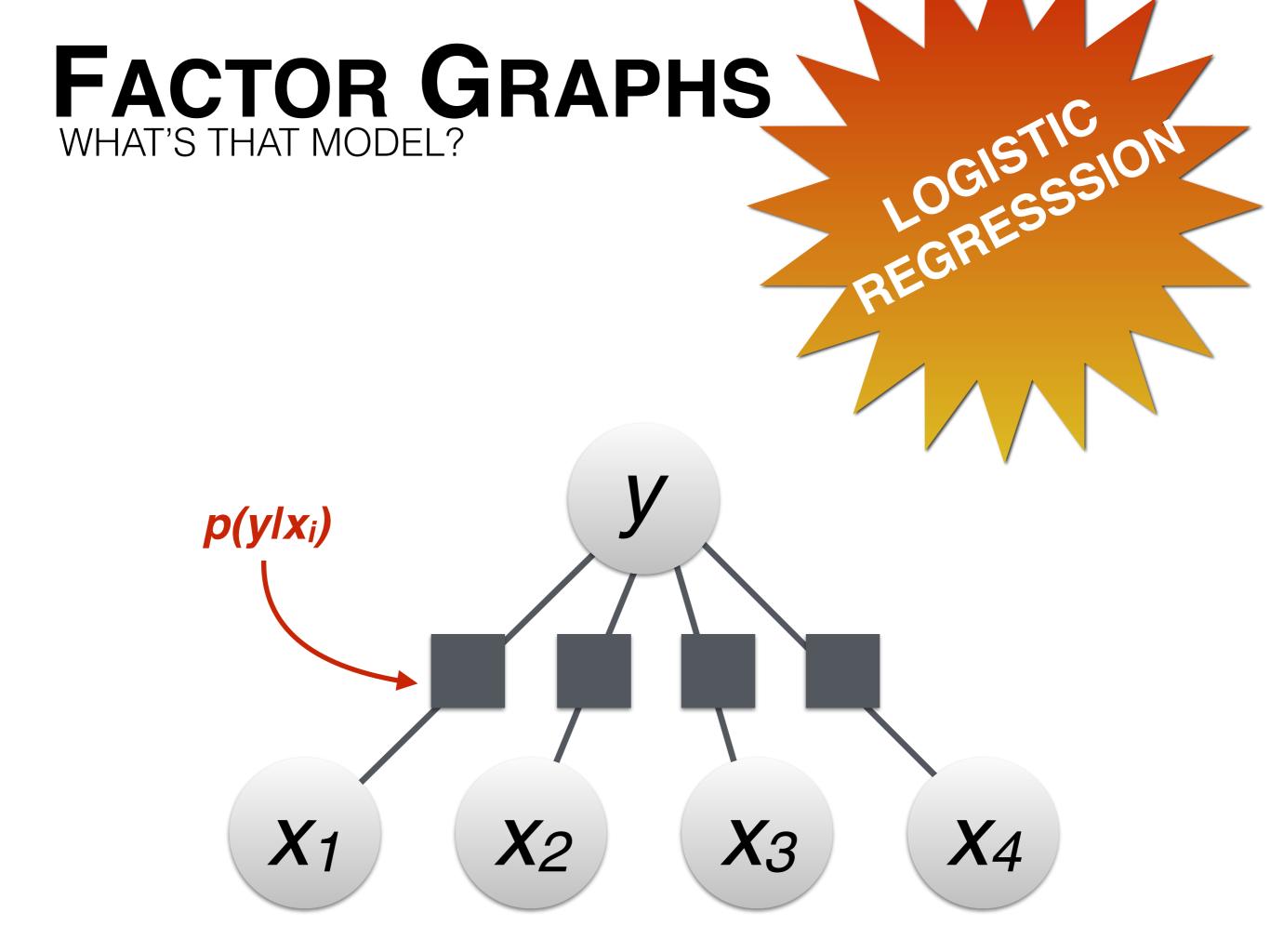
arbitrary bipartite graphs!

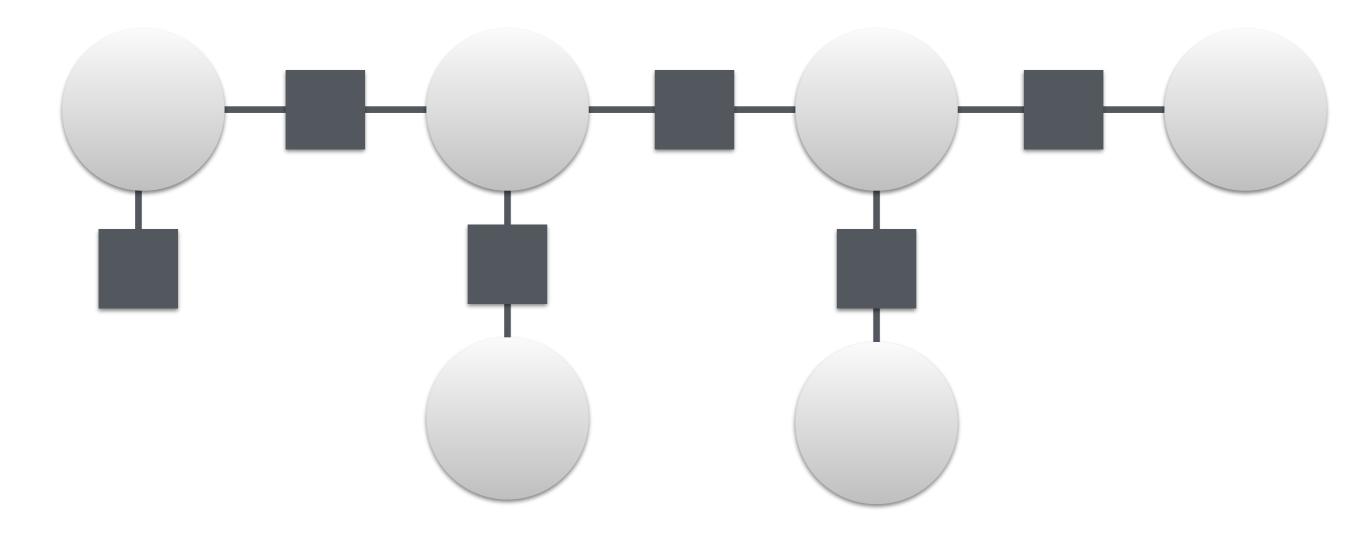


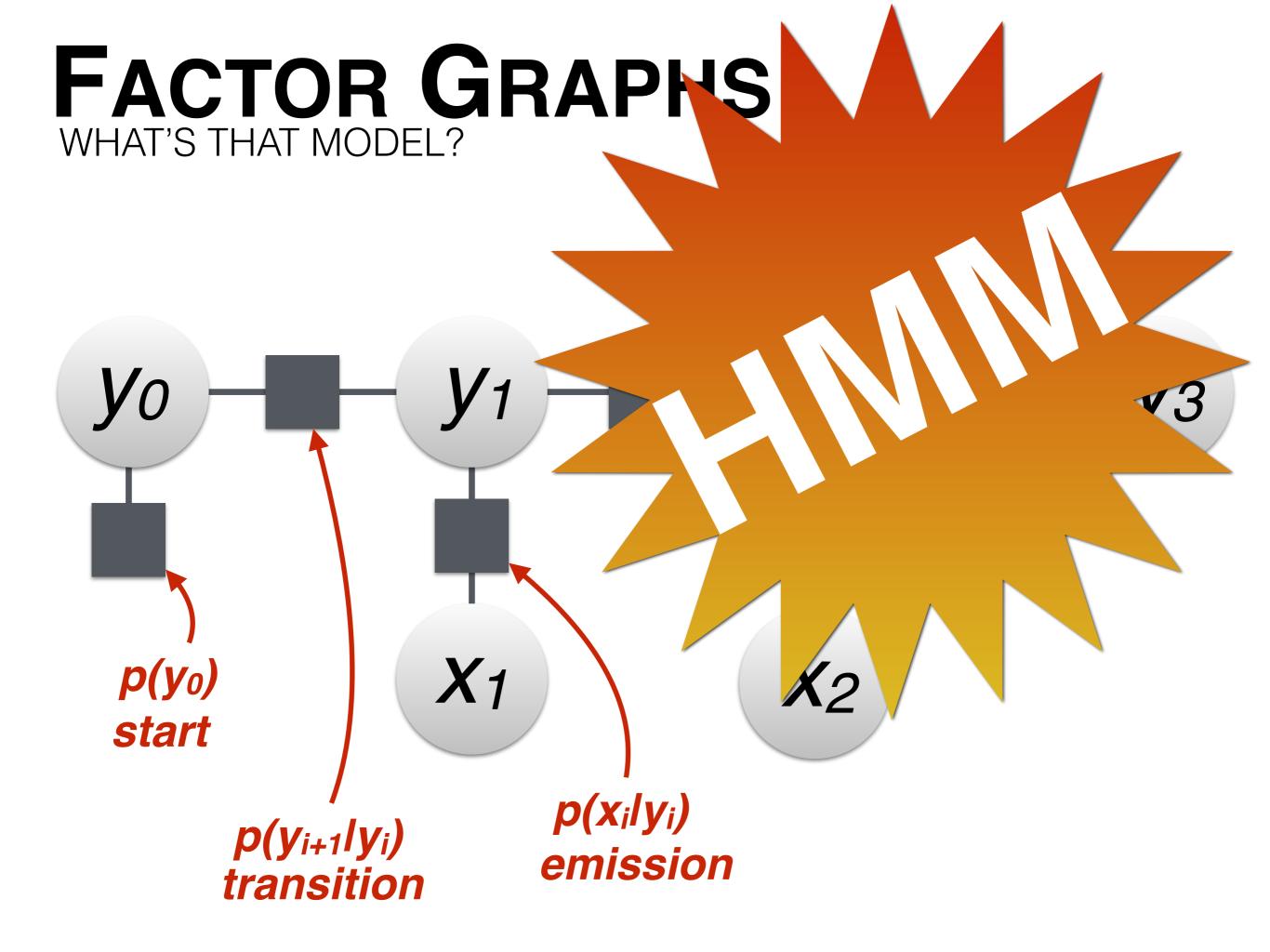


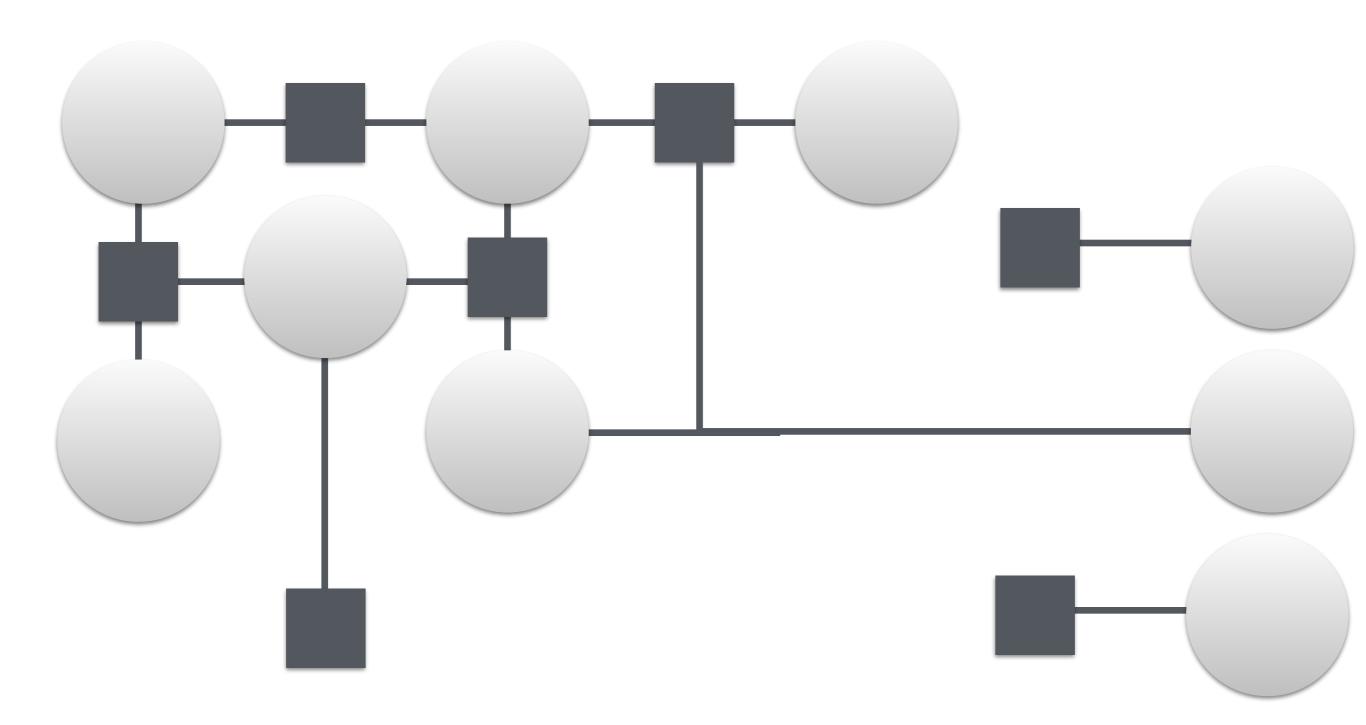




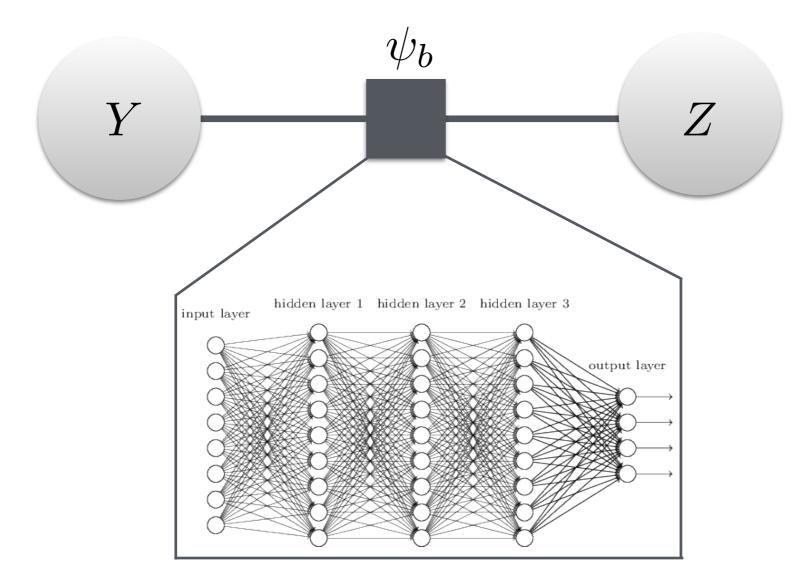


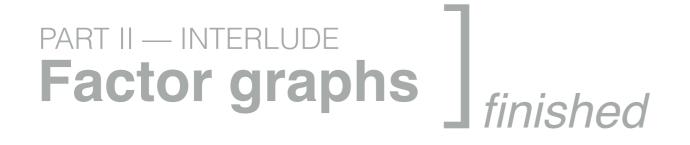






FACTOR GRAPHS IT'S 2020. PUT A NEURAL NET ON IT.



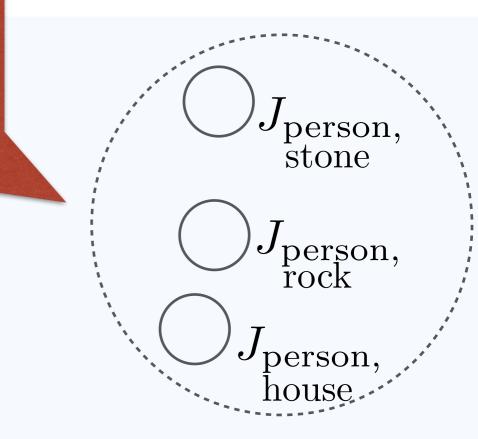


PART II Verb Physics] resuming

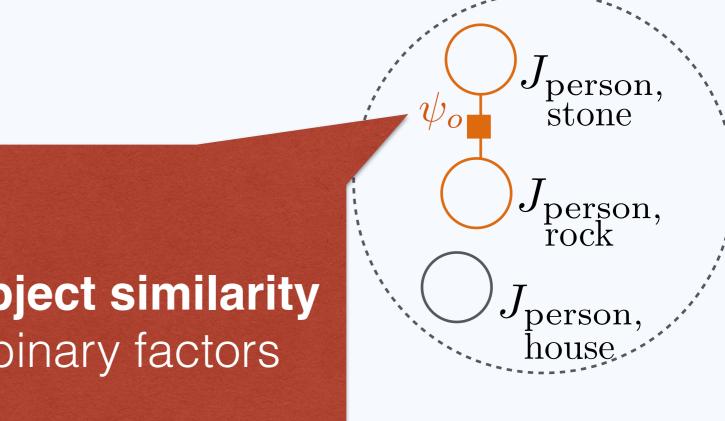
1. Introduction 2. Related work 3. Approach 4. Model 5. Data 6. Evaluation

Object pair random variables

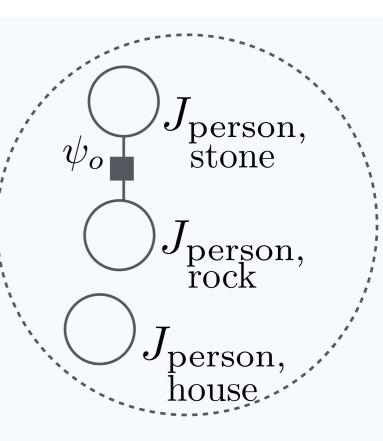
size



Object similarity binary factors



Verb similarity binary factors



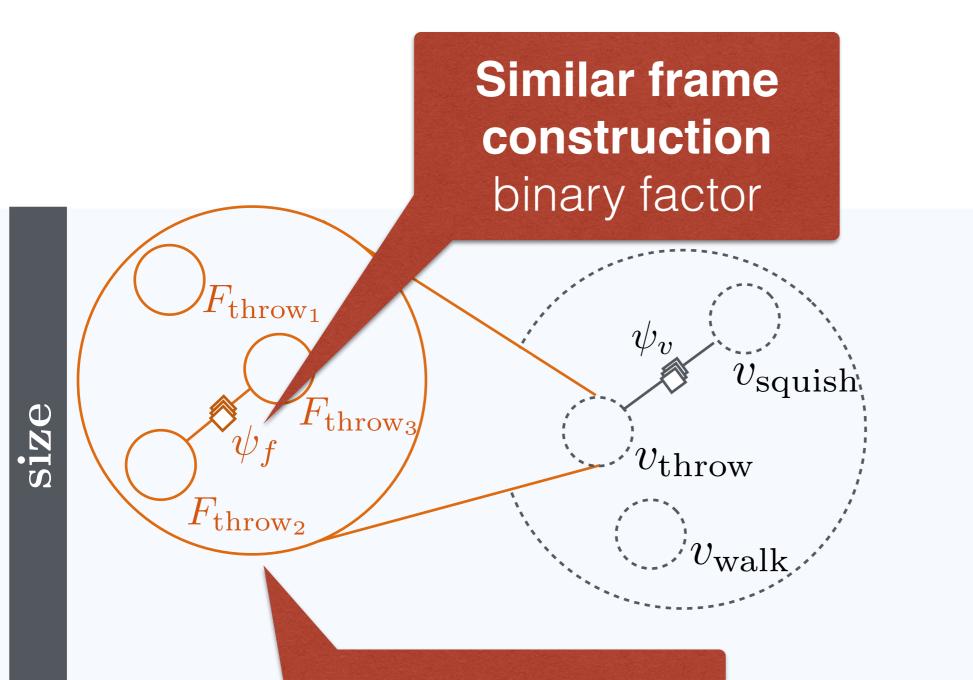
Action frames grouped by **verb**

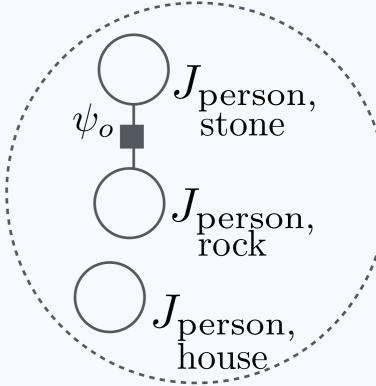
 ψ_n

 v_{throw}

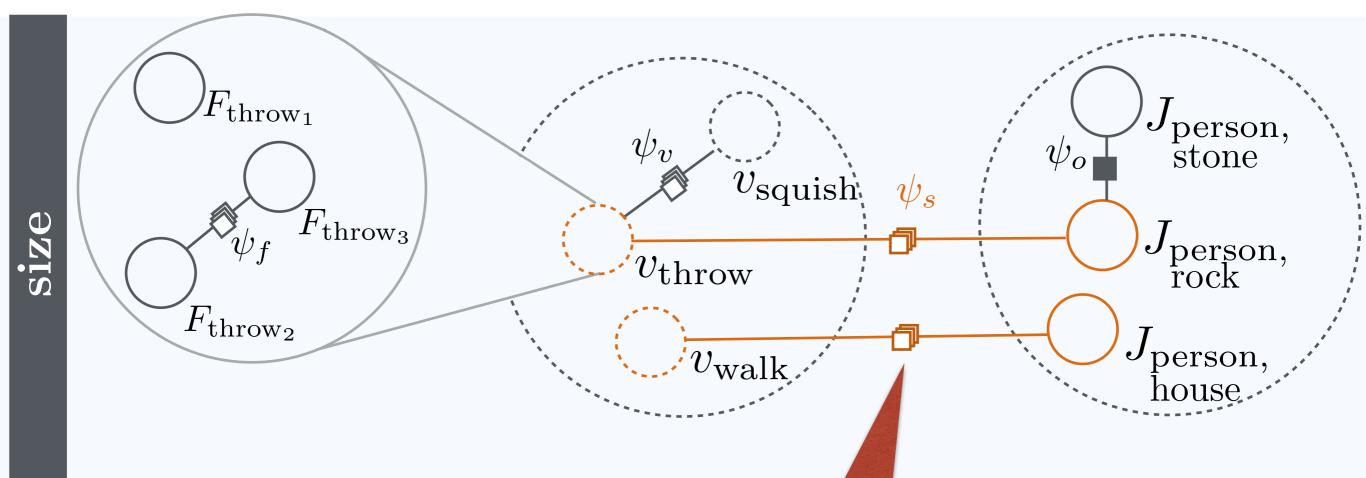
 v_{wall}

 $v_{\rm squish}$

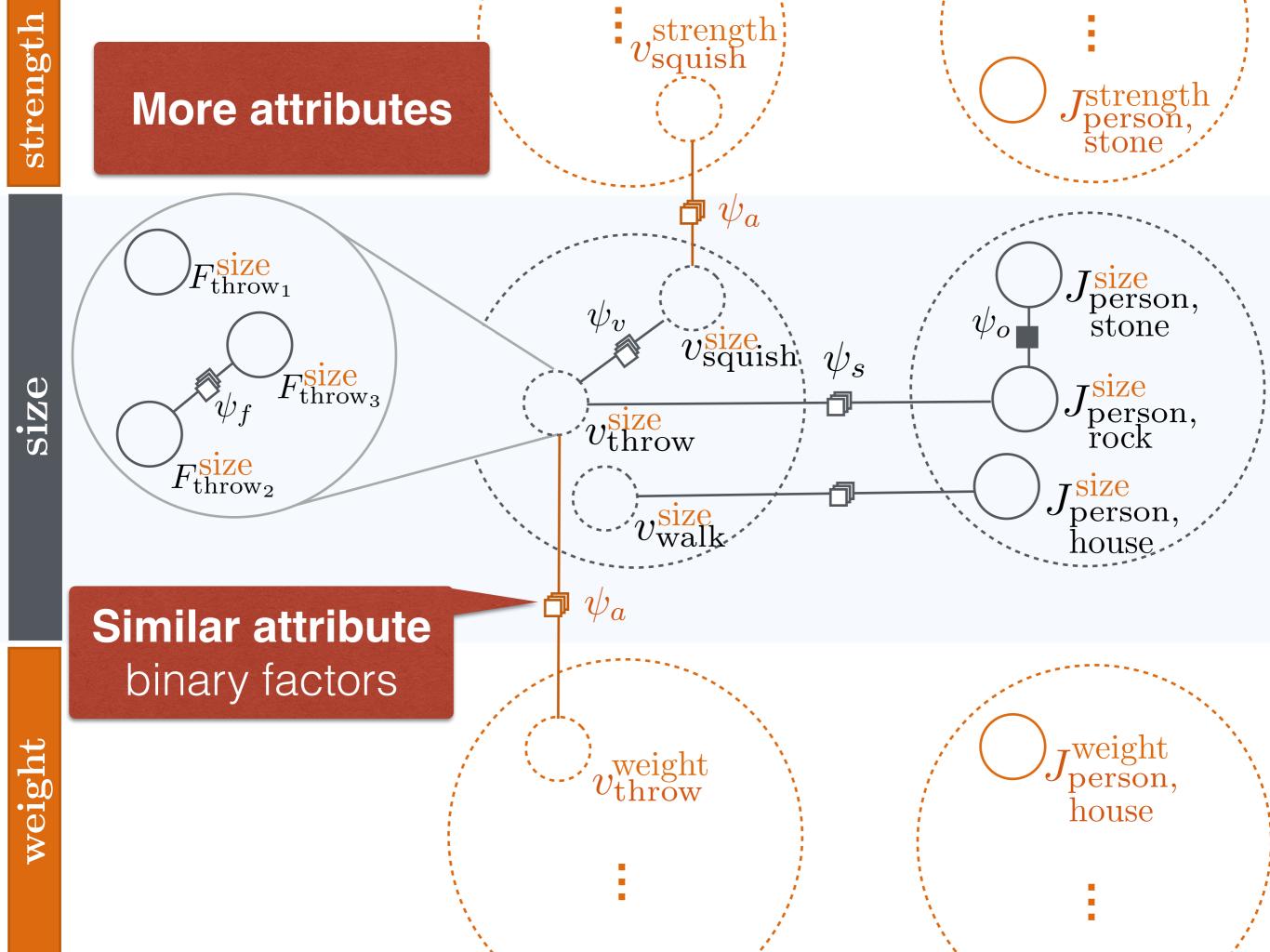




Several action frames per verb



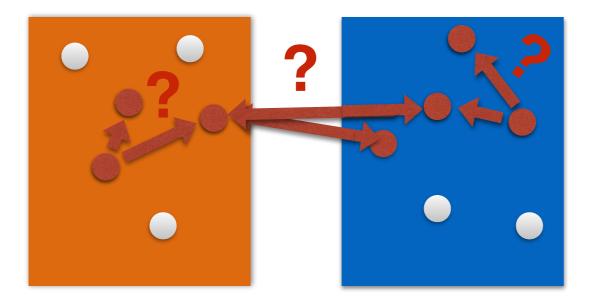
Action-object compatibility binary factors

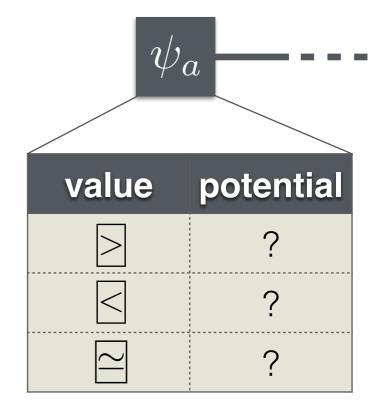


Two main model questions

(1) What subset of nodes should we **connect** with each type of factor?

(2) What should the **potential** functions be?





Unary factors



Unary factors



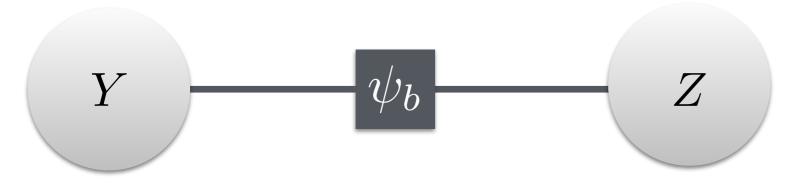
Max-ent factors (all nodes)
Seed factors (nodes in seed set)

Unary factors

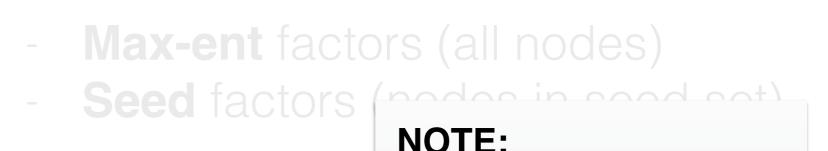


Max-ent factors (all nodes) Seed factors (nodes in seed set)

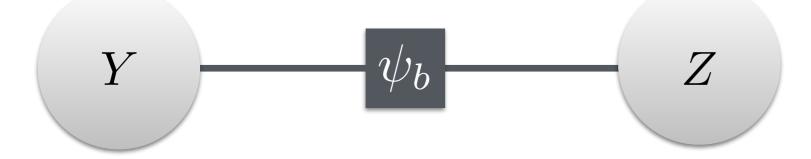
Binary factors



Unary factors



Binary factors



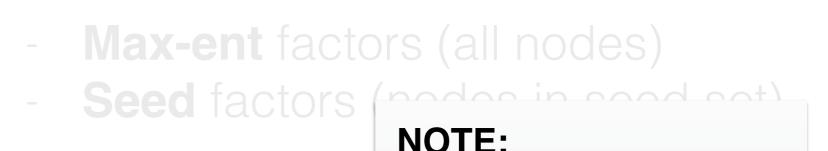
Similarity metrics

(e.g., cosine similarity of word embeddings)

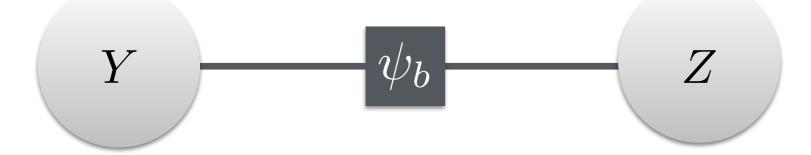
advanced topic

not covered today

Unary factors



Binary factors



Similarity metrics

(e.g., cosine similarity of word embeddings)

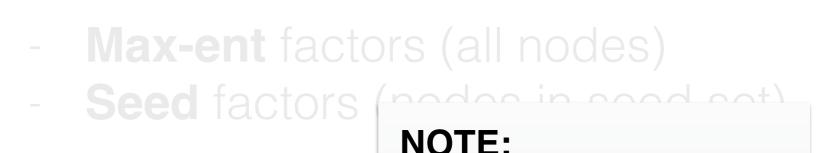
advanced topic

not covered today

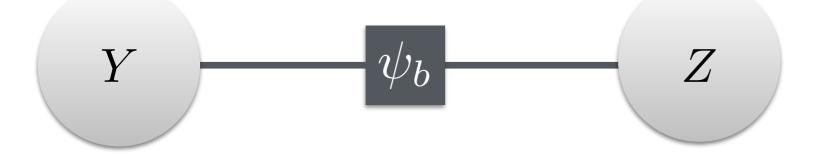
Empirical agreement

(on seed set)

Unary factors



Binary factors



Similarity metrics

(e.g., cosine similarity of word embeddings)

advanced topic

not covered today

Empirical agreement

Usage in text

(on seed set)

(e.g., high PMI using Google Syntax Ngrams; for action-object compatibility)



Log-linear classifier $p(X^a = v) \propto e^{w_a \cdot f(X^a)}$



Log-linear classifier $p(X^a = v) \propto e^{w_a \cdot f(X^a)}$

Object feature function $f(O_{p,q}^{a}) := \langle g(p), g(q) \rangle$



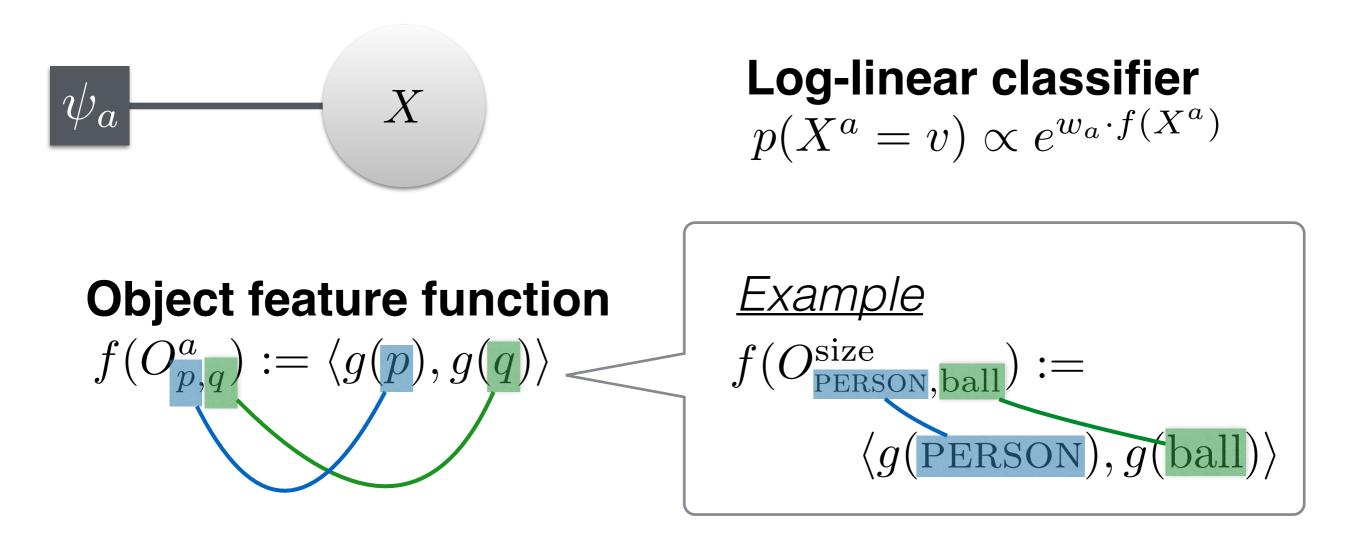


Log-linear classifier $p(X^a = v) \propto e^{w_a \cdot f(X^a)}$

Object feature function

 $f(O_{p,q}^{a}) := \langle g(p), g(q) \rangle$









Log-linear classifier $p(X^a = v) \propto e^{w_a \cdot f(X^a)}$

Object feature function $f(O_{p,q}^{a}) := \langle g(p), g(q) \rangle$

Frame feature function

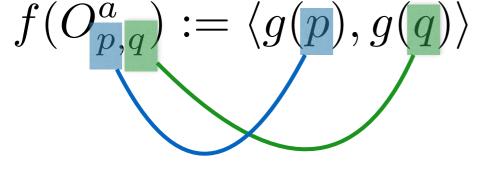
$$f(F_{v_t}^a) := \langle h(t), g(v), g(t) \rangle$$





Log-linear classifier $p(X^a = v) \propto e^{w_a \cdot f(X^a)}$

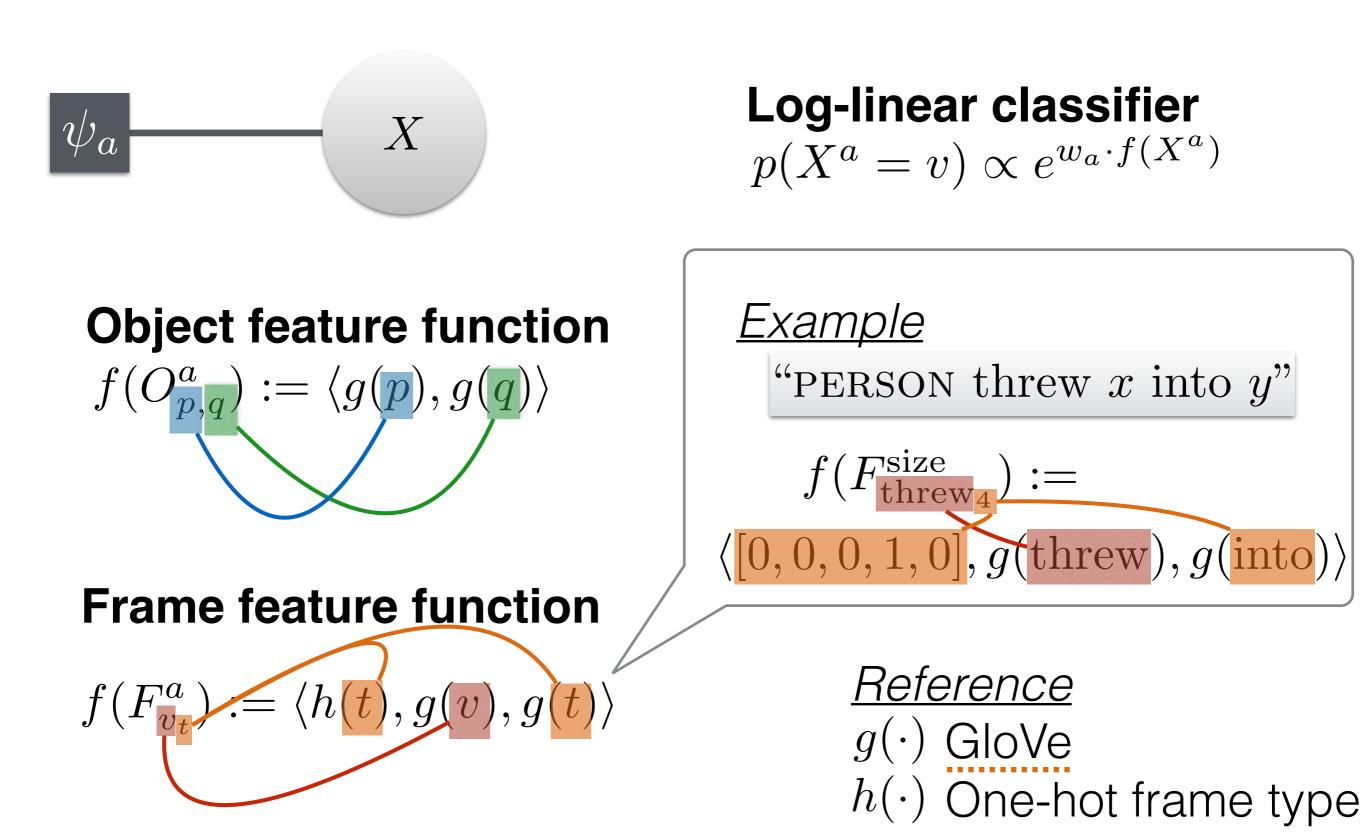
Object feature function



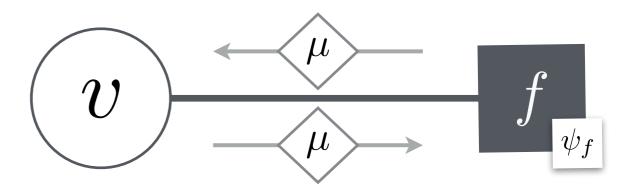
Frame feature function

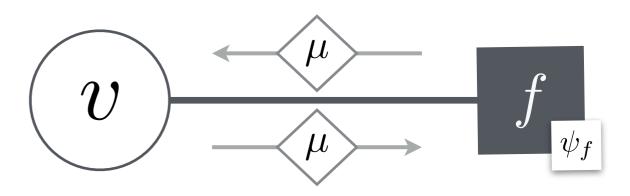
 $\langle h(t), g(v), g(t) \rangle$

 $\begin{array}{l} \underline{Reference}\\ g(\cdot) \ \text{GloVe}\\ h(\cdot) \ \text{One-hot frame type} \end{array}$

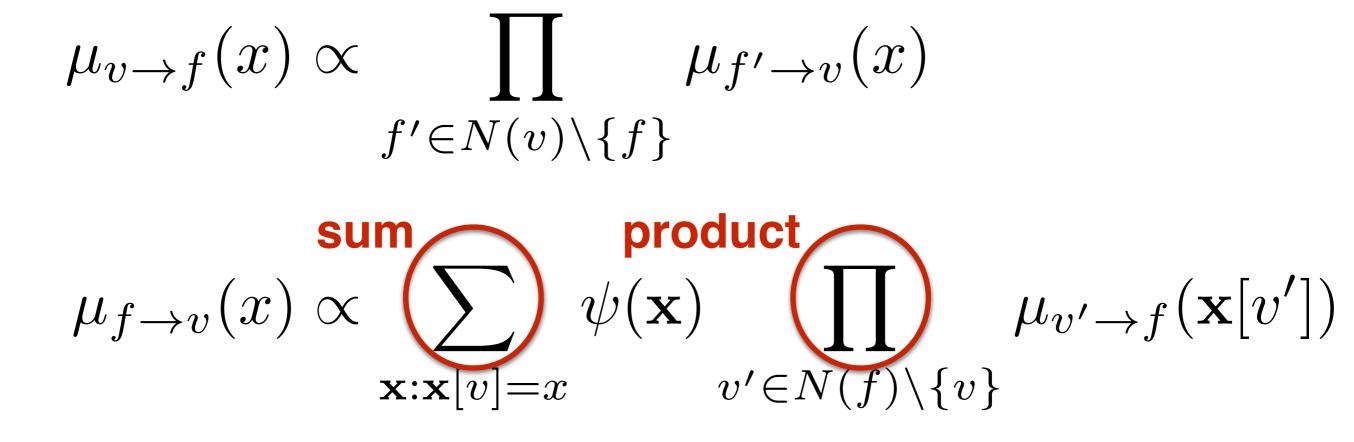


Loopy belief propagation



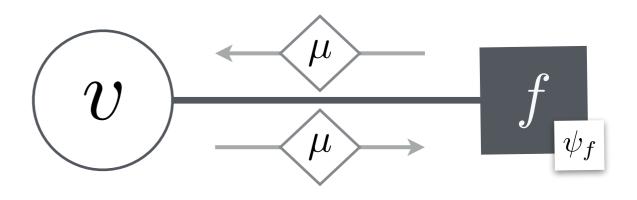


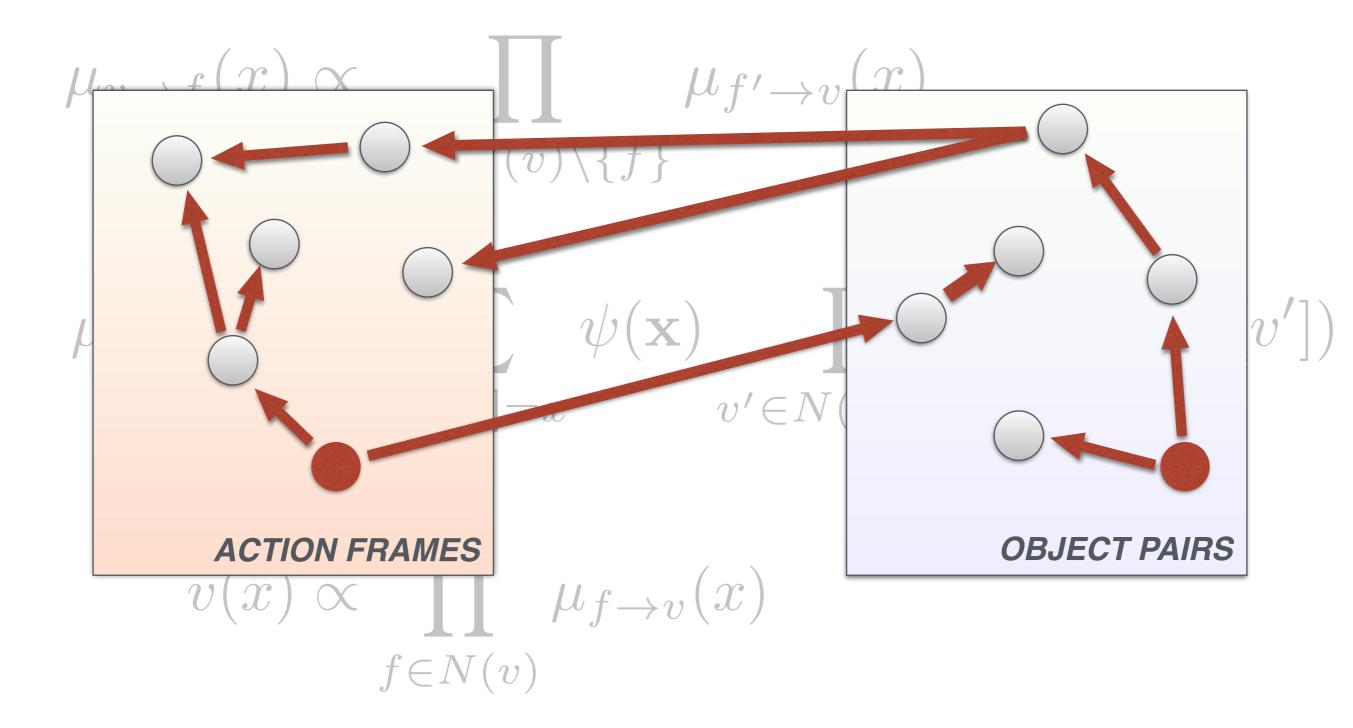
Loopy belief propagation



 $v(x) \propto \mu_{f \to v}(x)$ $f \in N(v)$

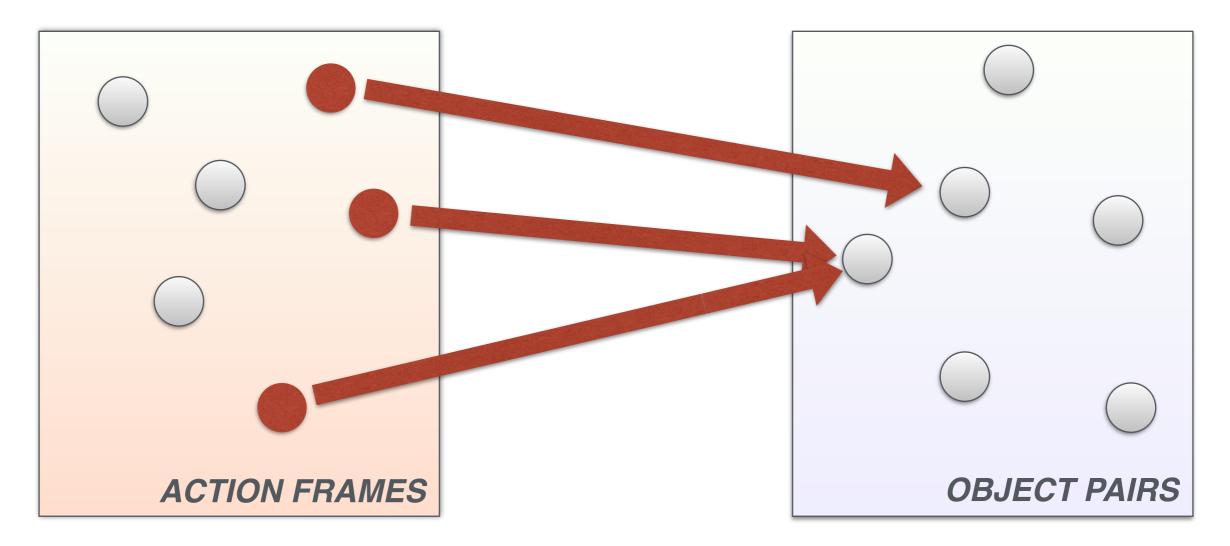
Loopy belief propagation



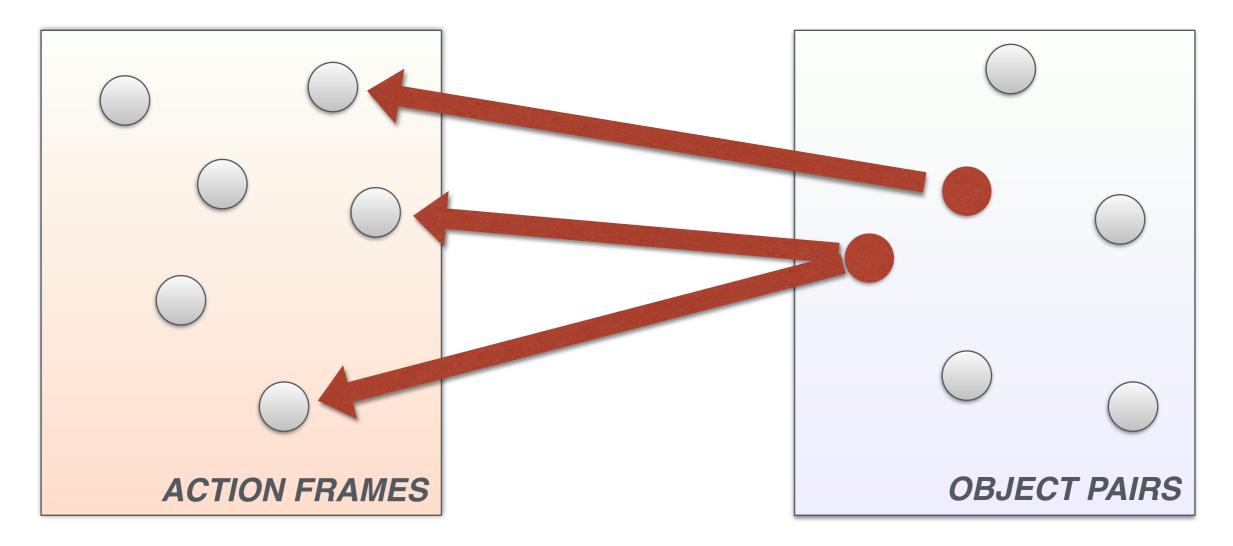


1. Introduction 2. Related work 3. Approach 4. Model 5. Data 6. Evaluation

Why collect data?



Why collect data?



Why collect data? **ACTION FRAMES OBJECT PAIRS**

- Small **seed set** (5%) breaks symmetry
- **Evaluate** generalizability (dev = 45%, test = 50%)

Selecting frames and objects

<u>Verbs</u>

- took
- grew
- washed
- trimmed
- squished
- got
- looked
- wrote
- entered
- kept
- lived
- played

"Action" verbs

```
[Levin, 1993]
```

Selecting frames and objects

Action frames

- took

Verbs

- grew
- washed
- trimmed
- squished
- got
- looked
- wrote
- entered
- kept
- lived

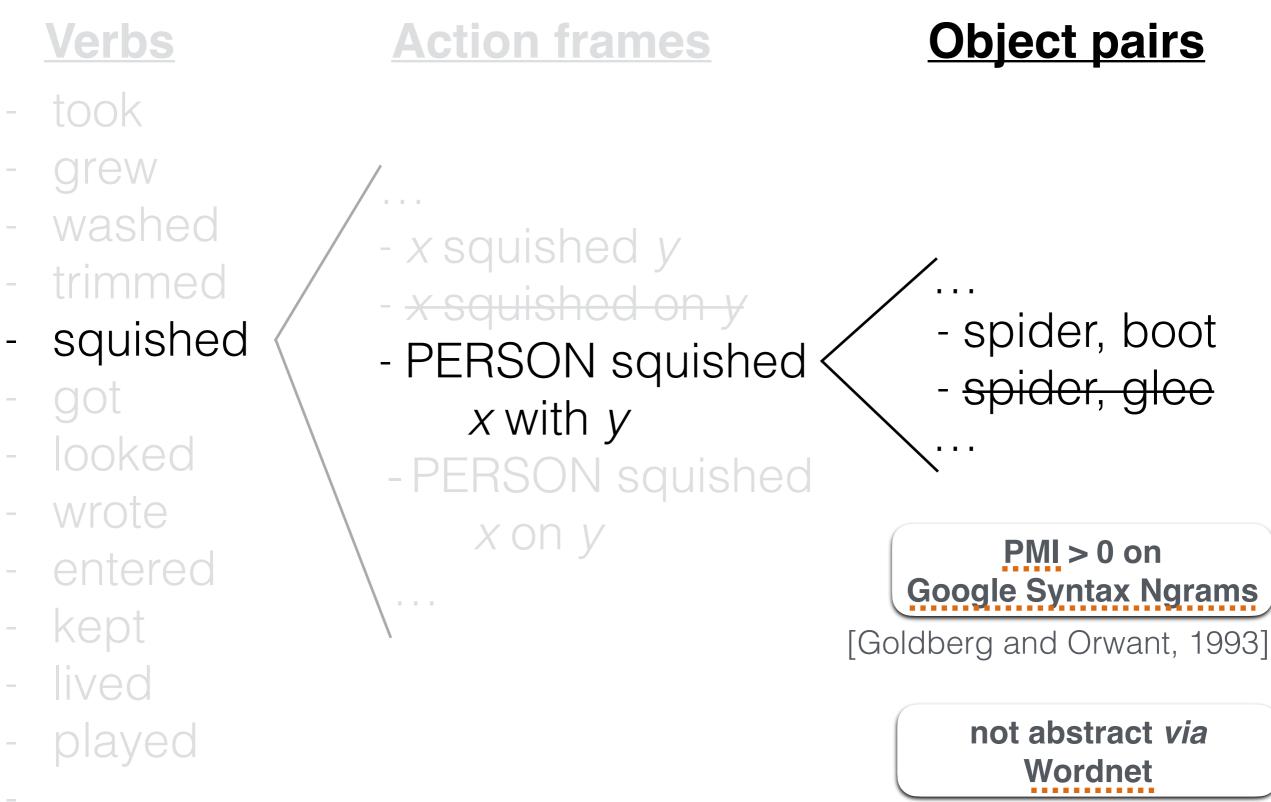
. . . .

- played

x squished *y x* squished on *y*PERSON squished *x* with *y*PERSON squished *x* on *y*...

Syntax + surface + crowdsourcing

Selecting frames and objects



. . .

[Miller, 1995]

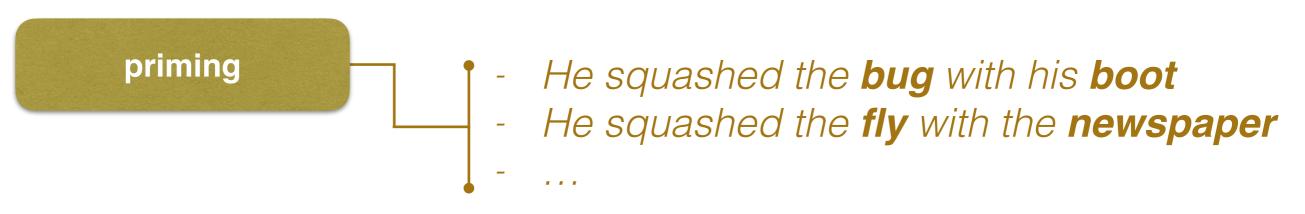
Given the sentence fragment

"He squished X with Y "

Given the sentence fragment

"He squished X with Y "

What are some (physical, non-abstract) examples of \mathbf{x} and \mathbf{y} ?



Given the sentence fragment

"He squished X with Y "

What are some (physical, non-abstract) examples of \mathbf{x} and \mathbf{y} ?

In general, what does "He squished x with y" imply about the relative **size** of x and y?



- x is generally **bigger** than y
- x is generally **smaller** than y
- x is generally about the same size as y
- no general relation holds

For the two objects

person and shoe

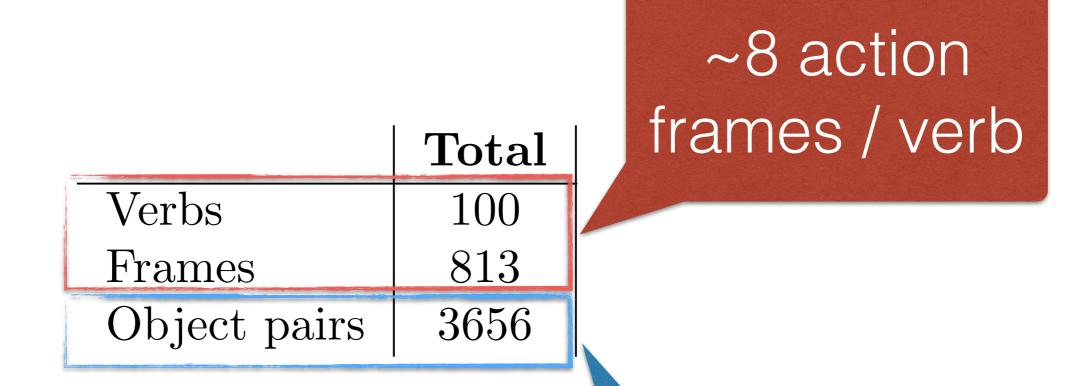
In general, what are their relative sizes ?

. . .

person is generally bigger than shoe
 person is generally smaller than shoe
 person is generally about the same size as shoe
 no general relation holds

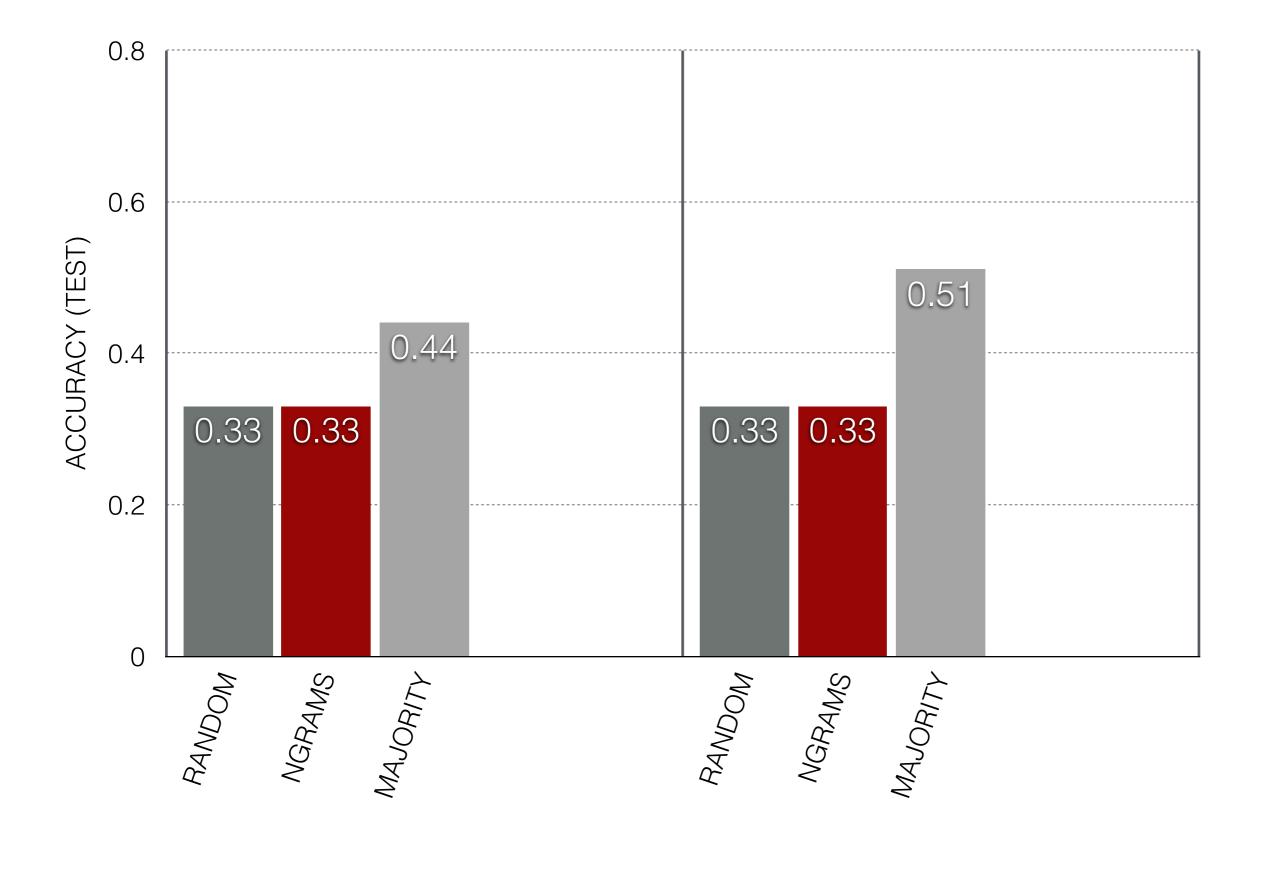
... relative weight ?
... relative rigidness ?

Data statistics



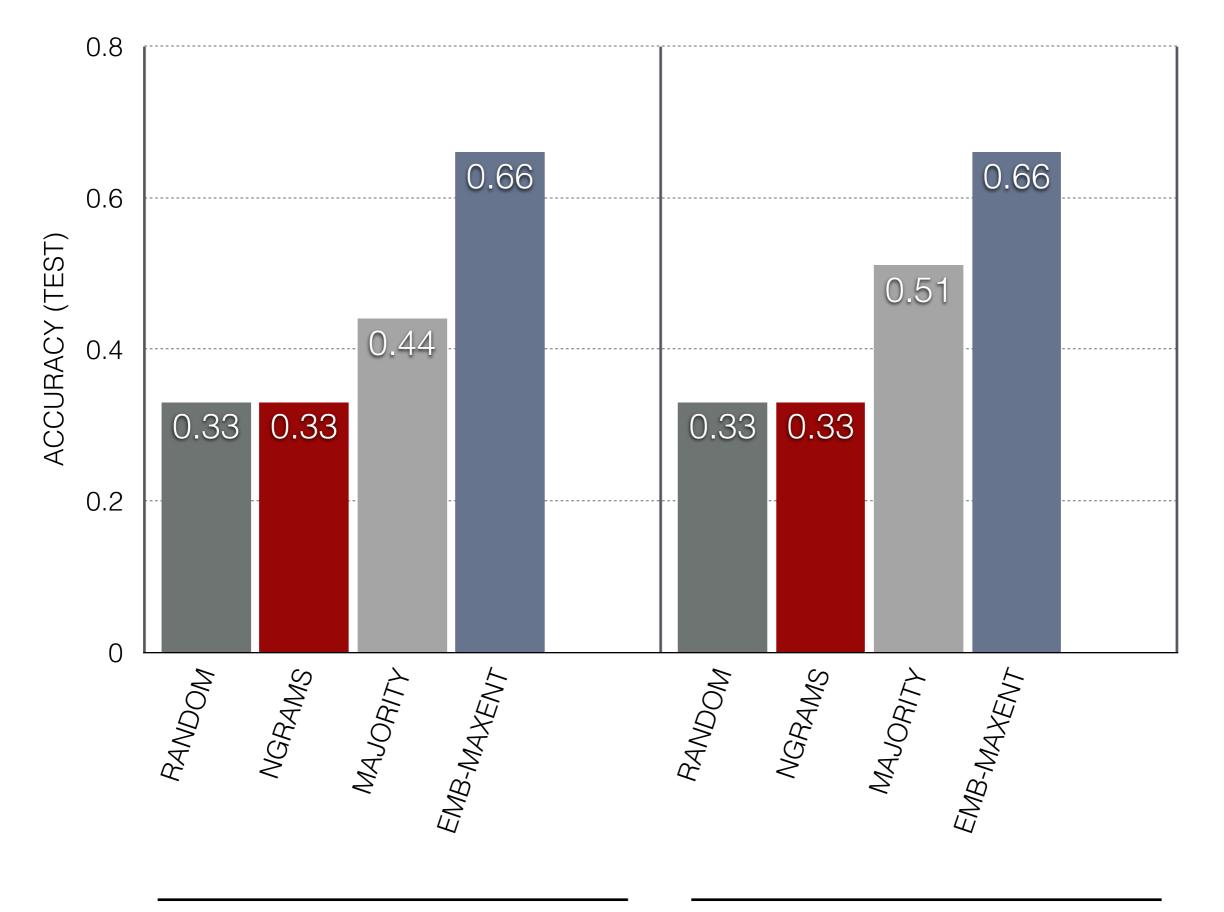
~200 distinct objects

1. Introduction 2. Related work 3. Approach 4. Model 5. Data 6. Evaluation



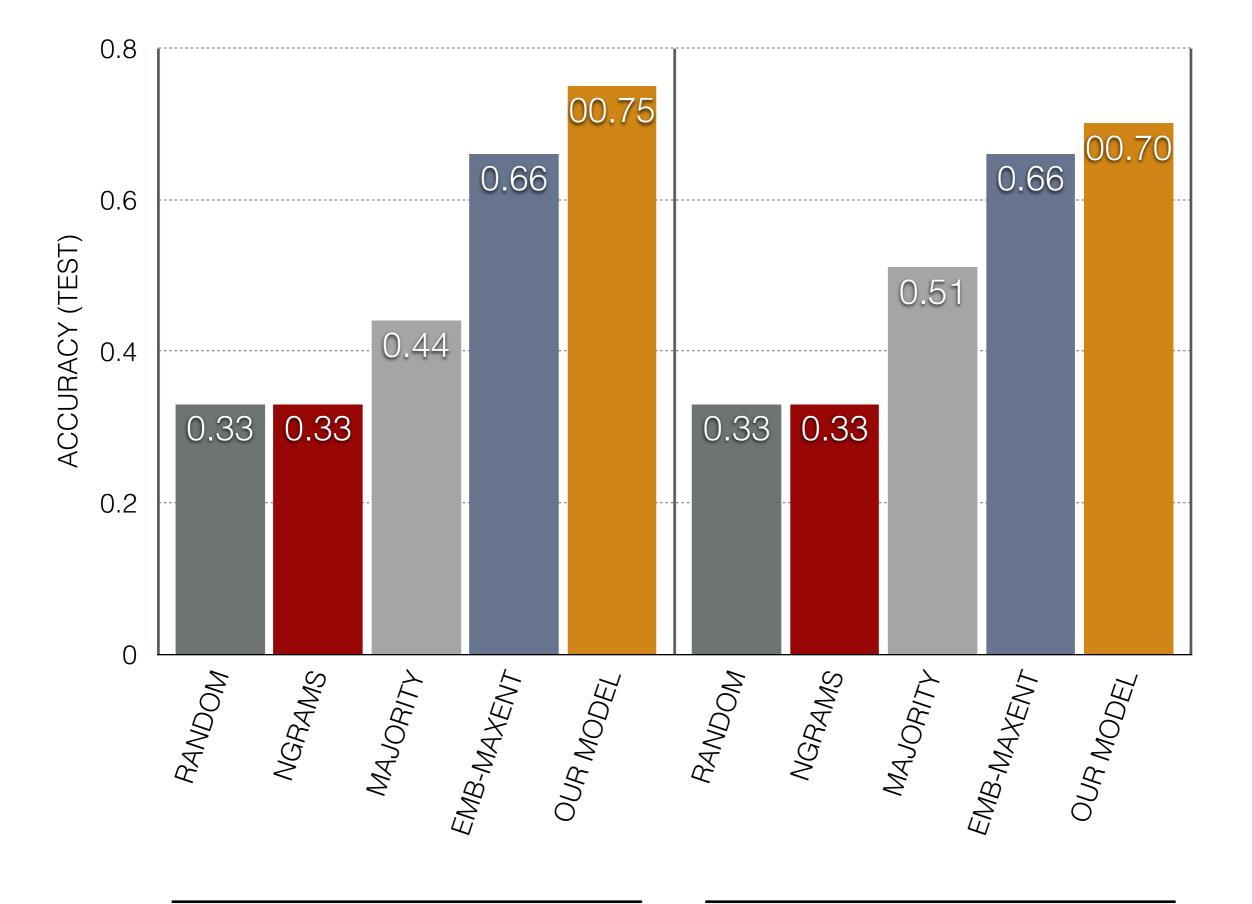
ACTION FRAMES

OBJECTS



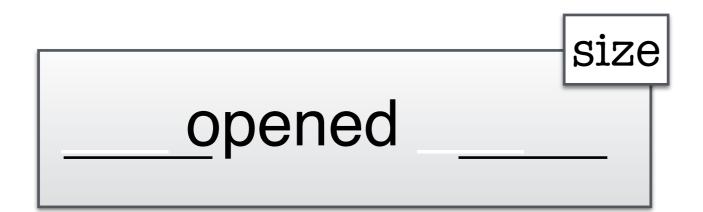
ACTION FRAMES

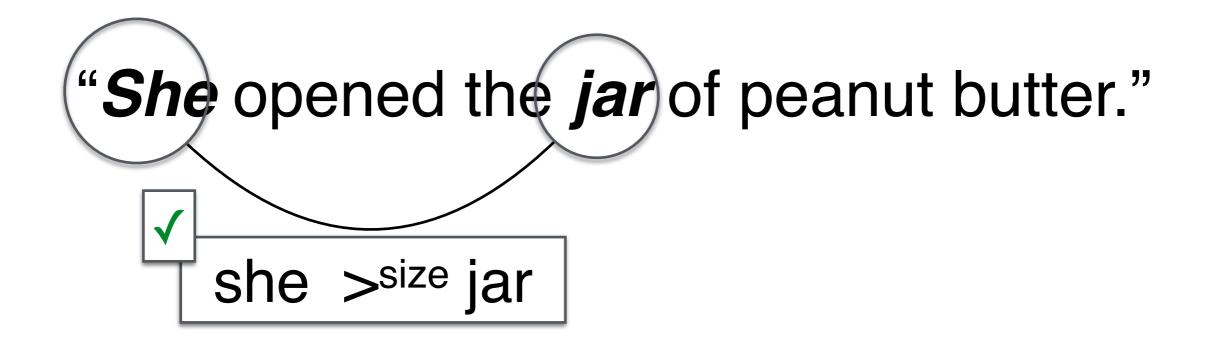
OBJECTS



ACTION FRAMES

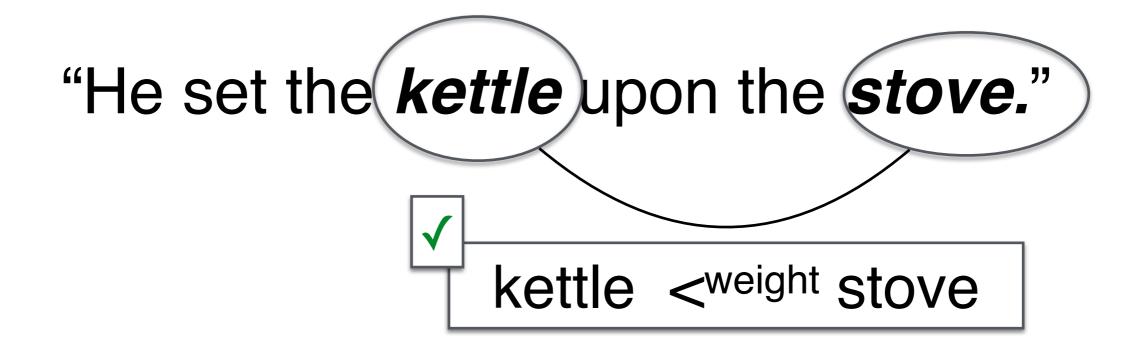
OBJECTS



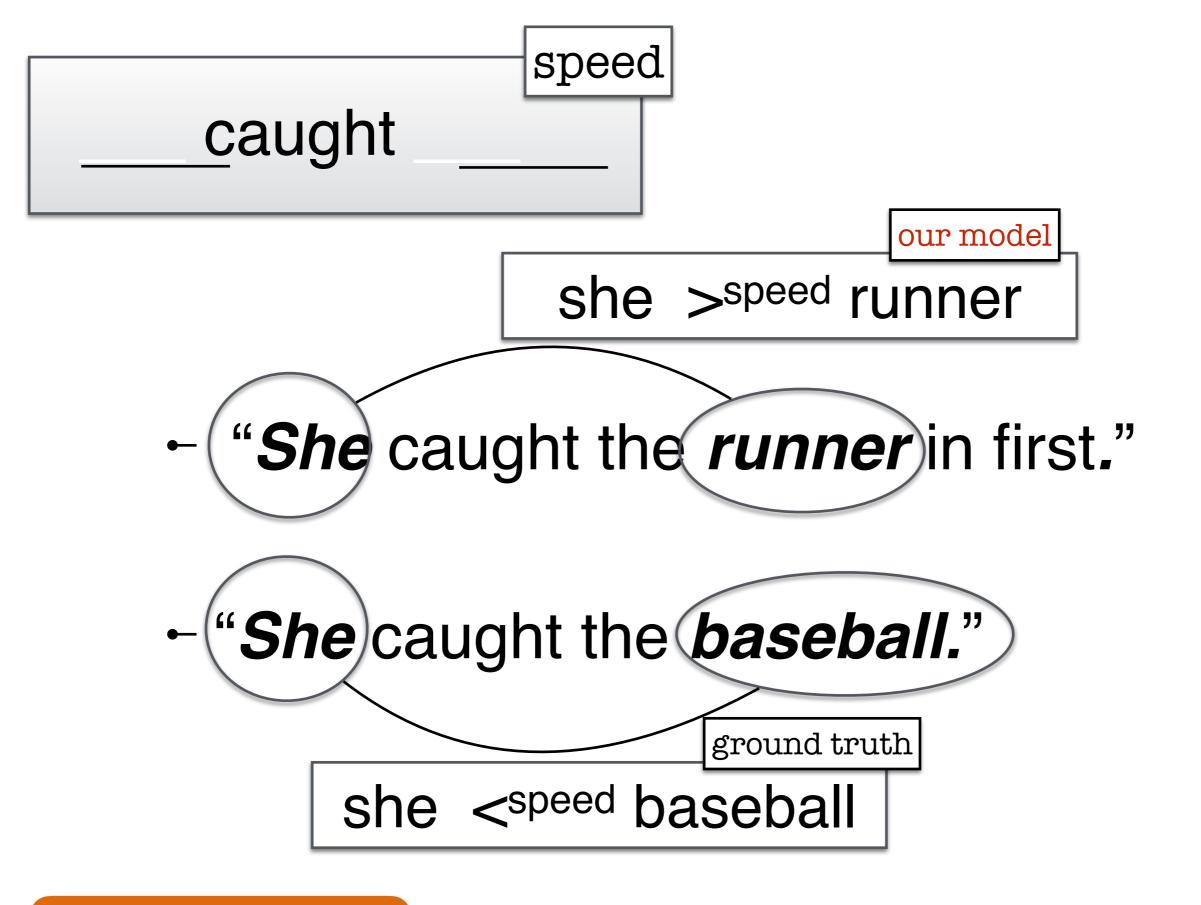


Correct dev set examples



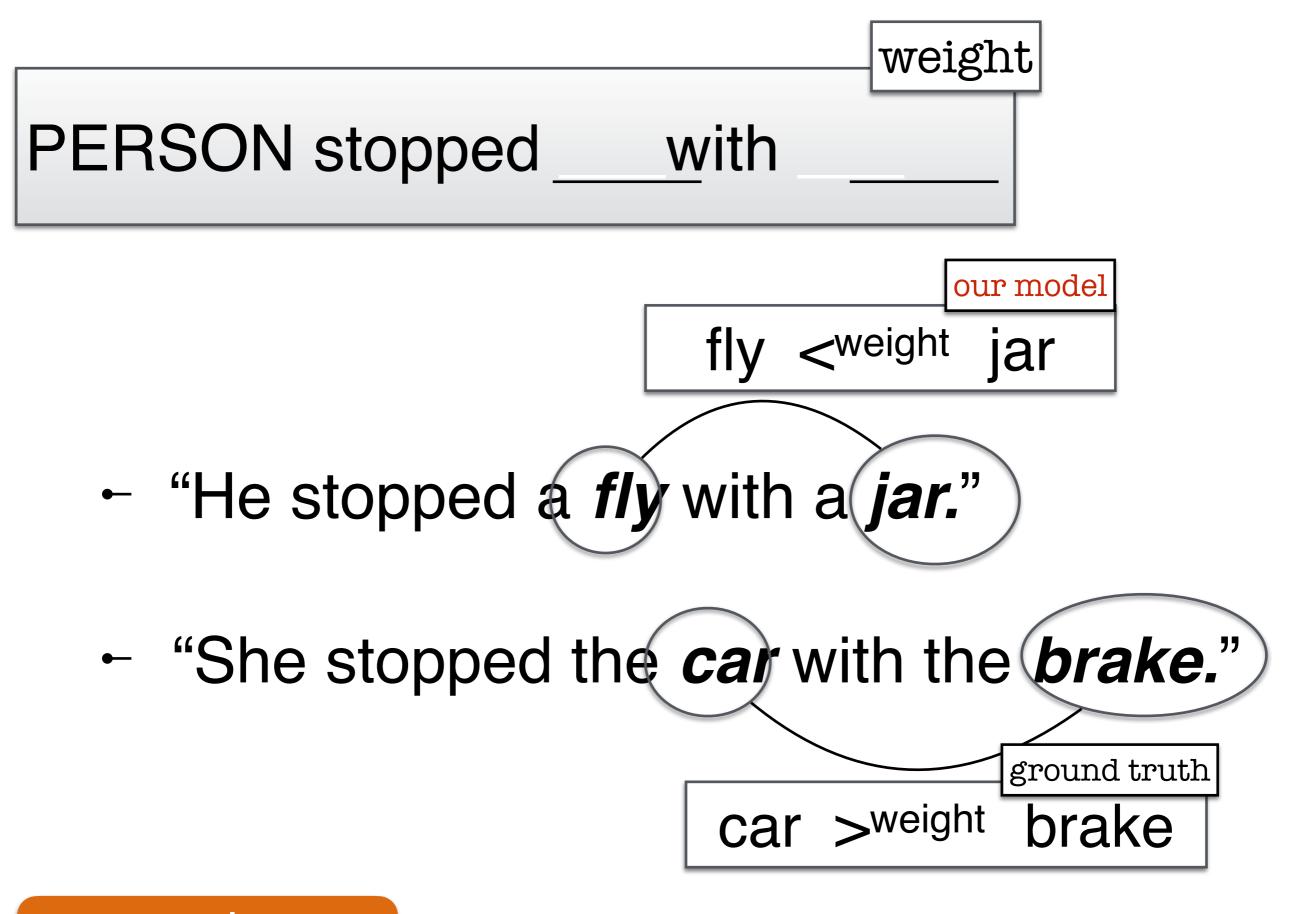


Correct dev set examples



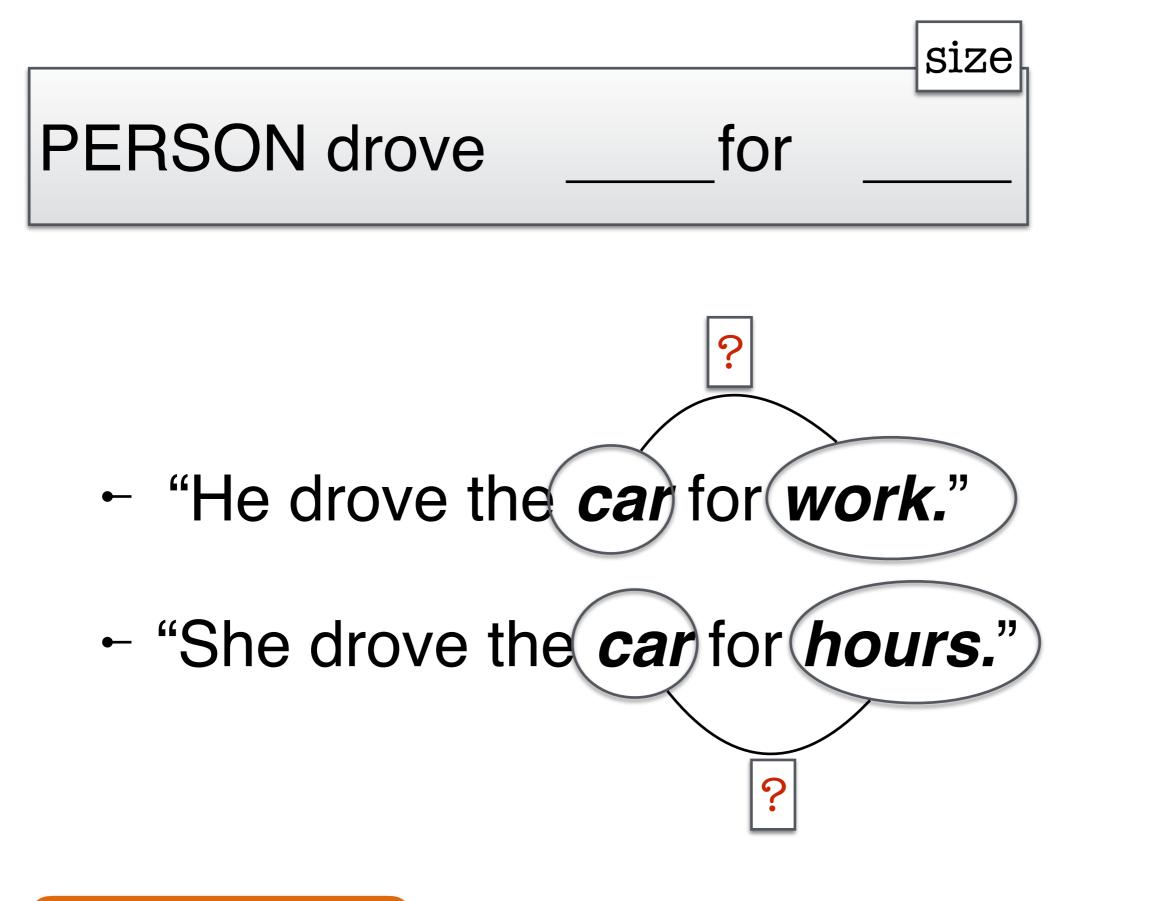
Incorrect dev set examples

polysemy



Incorrect dev set examples

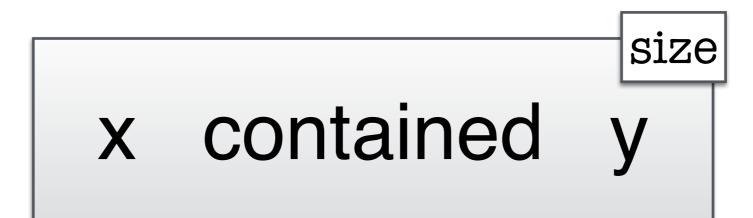
complex physics



Incorrect dev set examples

nonsensical comparison

Metaphorical language?



 $\implies x >^{size} y$



Physical

Metaphorical

X Y bag book taco tomato cup coffee x y dictator revolution firefighters forest fire

VerbPhysics Summary

Reverse engineer
 commonsense
 physical knowledge

Overcome **reporting bias** by modeling frames and objects

-

VerbPhysics Summary

Reverse engineer commonsense physical knowledge

Overcome **reporting bias** by modeling frames and objects

-

New dataset VERBPHYSICS uwnlp.github.io/verbphysics/

random variables: 5	
factors: 5 focus: threw_d	
locus. thew_u	
	seed [emb]
[size] turned_d	
	erb_sim
●[size] got_d _{verb_si}	[size] threw_d
	erb_sim
[size] swung_d	
V	erb sim
[size] drove_d	
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/pe below to select an	action frame to visualize. All action frames names start with one of the fi ht," "strength," "rigidness," or "speed."
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ype below to select an ttributes: "size," "weig ompletions (live) (cli	ht," "strength," "rigidness," or "speed." Load ckable): -accepted_dp_for size-accepted_dp_in size-accepted_od

Today's takeaways

1. NLP needs commonsense PART I

2. We can learn (some) commonsense from text! **PART II**

Factor graphs PART II — INTERLUDE

References

Verb Physics

https://arxiv.org/abs/1706.03799 (contains actual citations for all references in Part II)

Factor Graphs and Loopy Belief Propagation Tutorial

https://www.cs.cmu.edu/~mgormley/bp-tutorial/

Noah Smith's factor graph slides

https://courses.cs.washington.edu/courses/cse517/16wi/slides/angm-slides.pdf

my Verb Physics code (python) https://github.com/uwnlp/verbphysics

my factor graph code (python) https://github.com/mbforbes/py-factorgraph