

CSE P 501 – Compilers

Dataflow Analysis

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Autumn 2019

Agenda

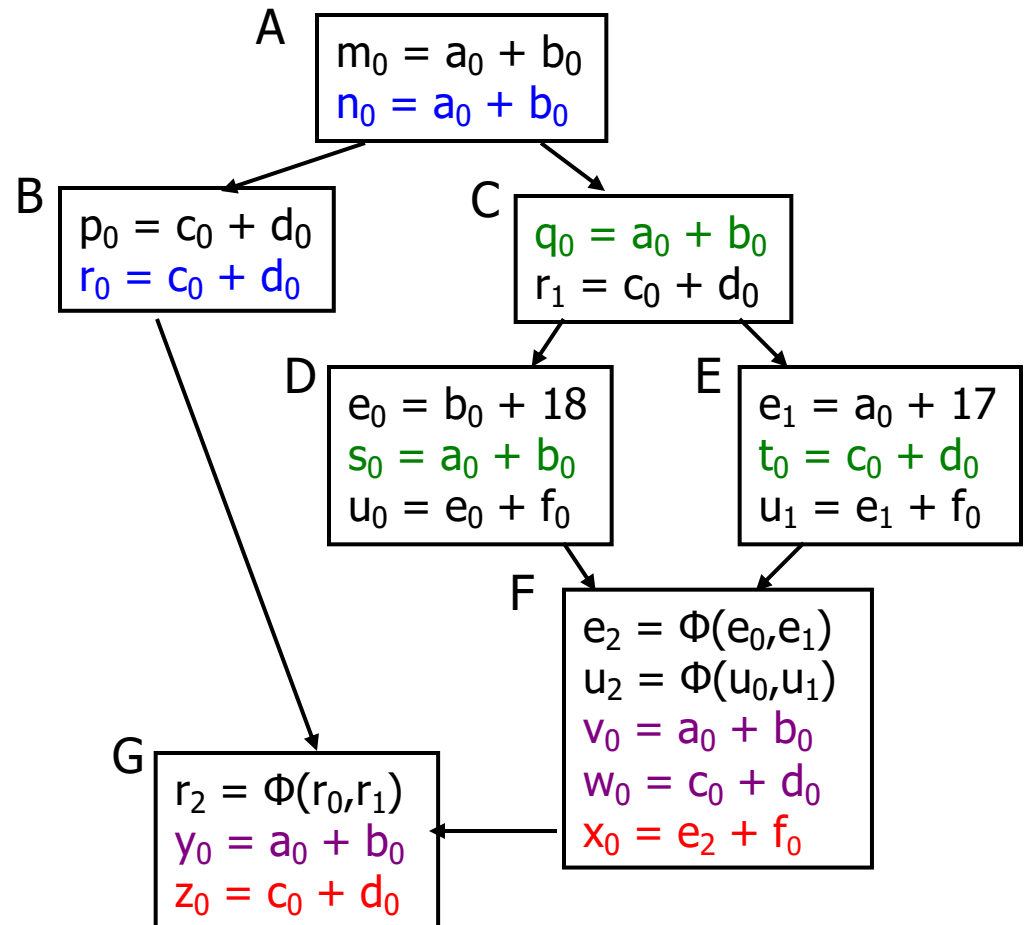
- Dataflow analysis: a framework and algorithm for many common compiler analyses
- Initial example: dataflow analysis for common subexpression elimination
- Other analysis problems that work in the same framework
- Some of these are optimizations we've seen, but now more formally and with details

The Story So Far...

- Redundant expression elimination
 - Local Value Numbering
 - Superlocal Value Numbering
 - Extends VN to EBBs
 - SSA-like namespace
 - Dominator VN Technique (DVNT)
- All of these propagate along forward edges
- None are global
 - In particular, can't handle back edges (loops)

Dominator Value Numbering

- Most sophisticated algorithm so far
- Still misses some opportunities
- Can't handle loops

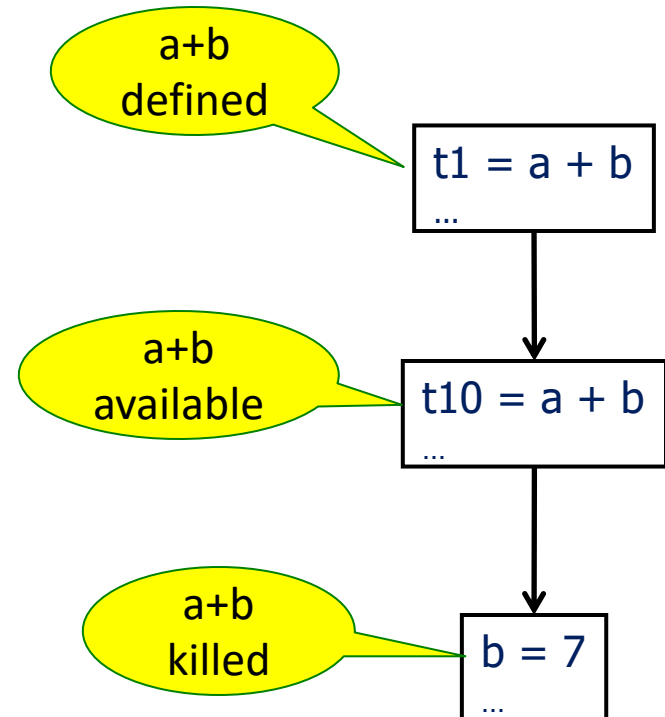


Available Expressions

- Goal: use dataflow analysis to find common subexpressions whose range spans basic blocks
- Idea: calculate *available expressions* at beginning of each basic block
- Avoid re-evaluation of an available expression
 - use a copy operation

“Available” and Other Terms

- An expression e is *defined* at point p in the CFG if its value is computed at p
 - Sometimes called *definition site*
- An expression e is *killed* at point p if one of its operands is defined at p
 - Sometimes called *kill site*
- An expression e is *available* at point p if every path leading to p contains a prior definition of e and e is not killed between that definition and p



Available Expression Sets

- To compute available expressions, for each block b , define
 - $AVAIL(b)$ – the set of expressions available on entry to b
 - $NKILL(b)$ – the set of expressions not killed in b
 - i.e., all expressions in the program *except* for those killed in b
 - $DEF(b)$ – the set of expressions defined in b and not subsequently killed in b

Computing Available Expressions

- $AVAIL(b)$ is the set
$$AVAIL(b) = \bigcap_{x \in \text{preds}(b)} (\text{DEF}(x) \cup (AVAIL(x) \cap \text{NKILL}(x)))$$
 - $\text{preds}(b)$ is the set of b 's predecessors in the CFG
 - The set of expressions available on entry to b is the set of expressions that were available at the end of *every* predecessor basic block x
 - The expressions available on exit from block b are those defined in b or available on entry to b and not killed in b
- This gives a system of simultaneous equations – a dataflow problem

Name Space Issues

- In previous value-numbering algorithms, we used a SSA-like renaming to keep track of versions
- In global dataflow problems, we use the original namespace
 - we require $a+b$ have the same value along *all* paths to its use
 - If a or b is updated along *any* path to its use, then $a+b$ has the “wrong” value
 - so original names are exactly what we want
- The KILL information captures when a value is no longer available

Computing Available Expressions

- Big Picture
 - Build control-flow graph
 - Calculate initial local data – $DEF(b)$ and $NKILL(b)$
 - This only needs to be done once for each block b and depends only on the statements in b
 - Iteratively calculate $AVAIL(b)$ by repeatedly evaluating equations until nothing changes
 - Another fixed-point algorithm

Computing DEF and NKILL (1)

- For each block b with operations o_1, o_2, \dots, o_k
 - KILLED = \emptyset // killed *variables*, not expressions
 - DEF(b) = \emptyset
 - for $i = k$ to 1 // note: working back to front
 - assume o_i is “ $x = y + z$ ”
 - add x to KILLED
 - if ($y \notin$ KILLED and $z \notin$ KILLED)
 - add “ $y + z$ ” to DEF(b) // i.e., neither y nor z killed
 - // after this point in b
 - ...

Computing DEF and NKILL (2)

- After computing DEF and KILLED for a block b , compute set of all expressions in the program not killed in b

$NKILL(b) = \{ \text{all expressions} \}$

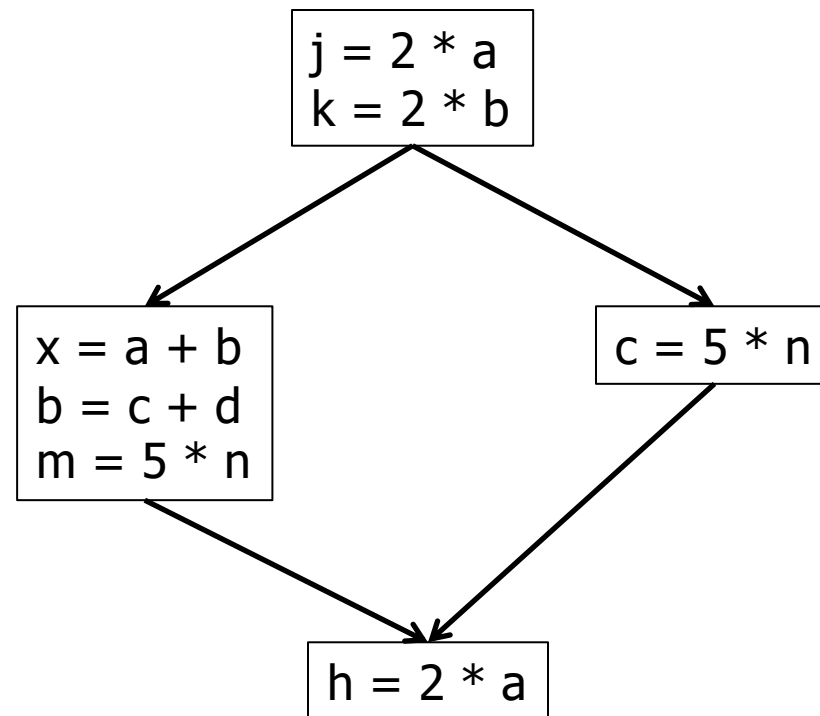
for each expression e

for each variable $v \in e$

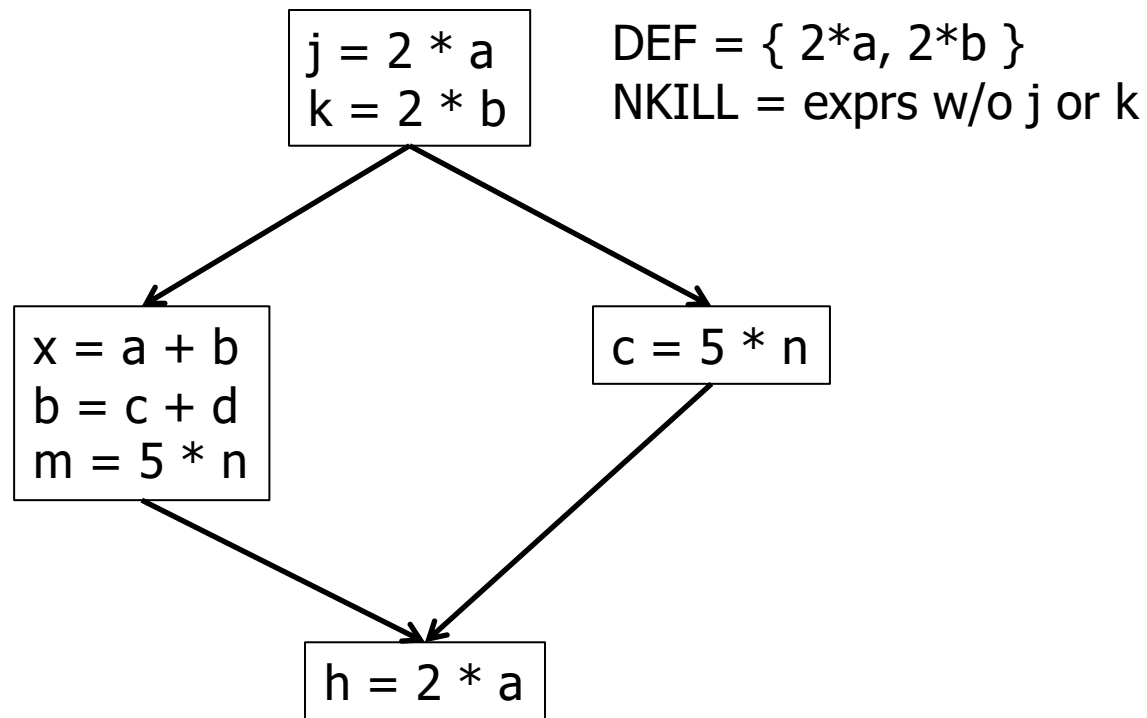
if $v \in KILLED$ then

$NKILL(b) = NKILL(b) - e$

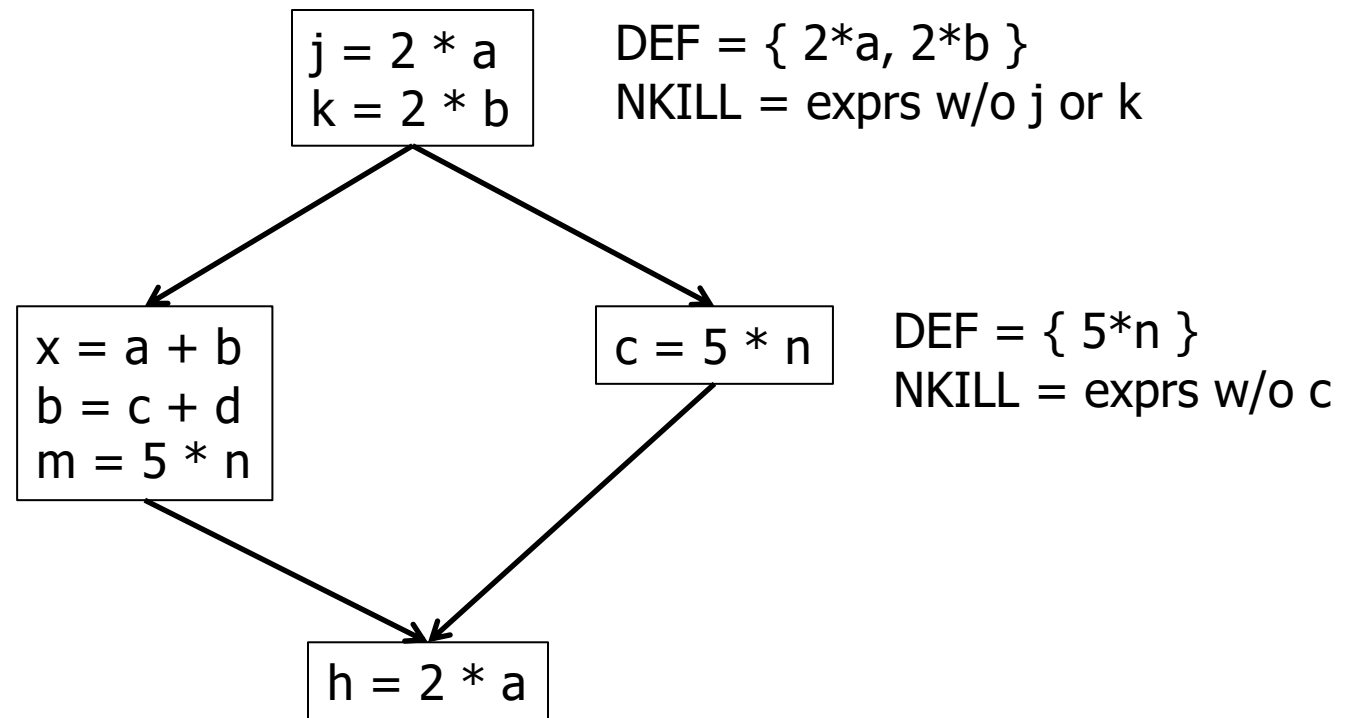
Example: Compute DEF and NKILL



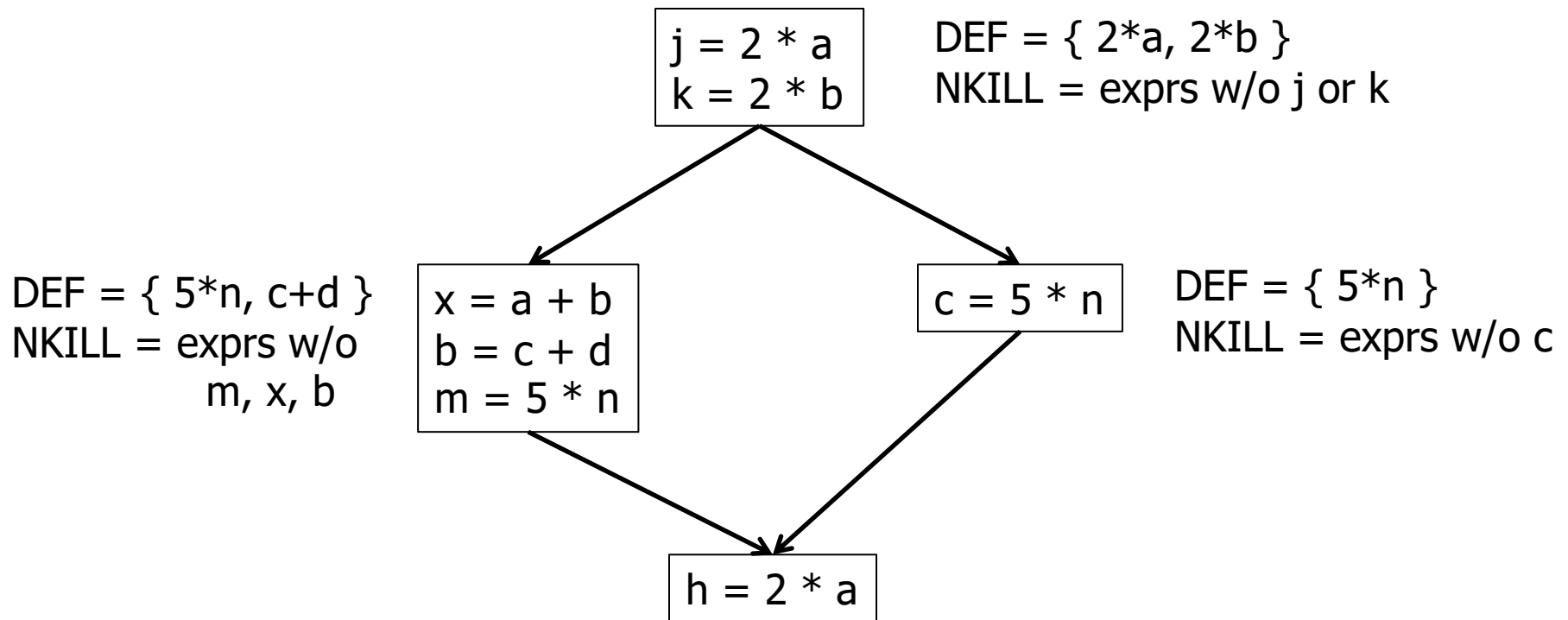
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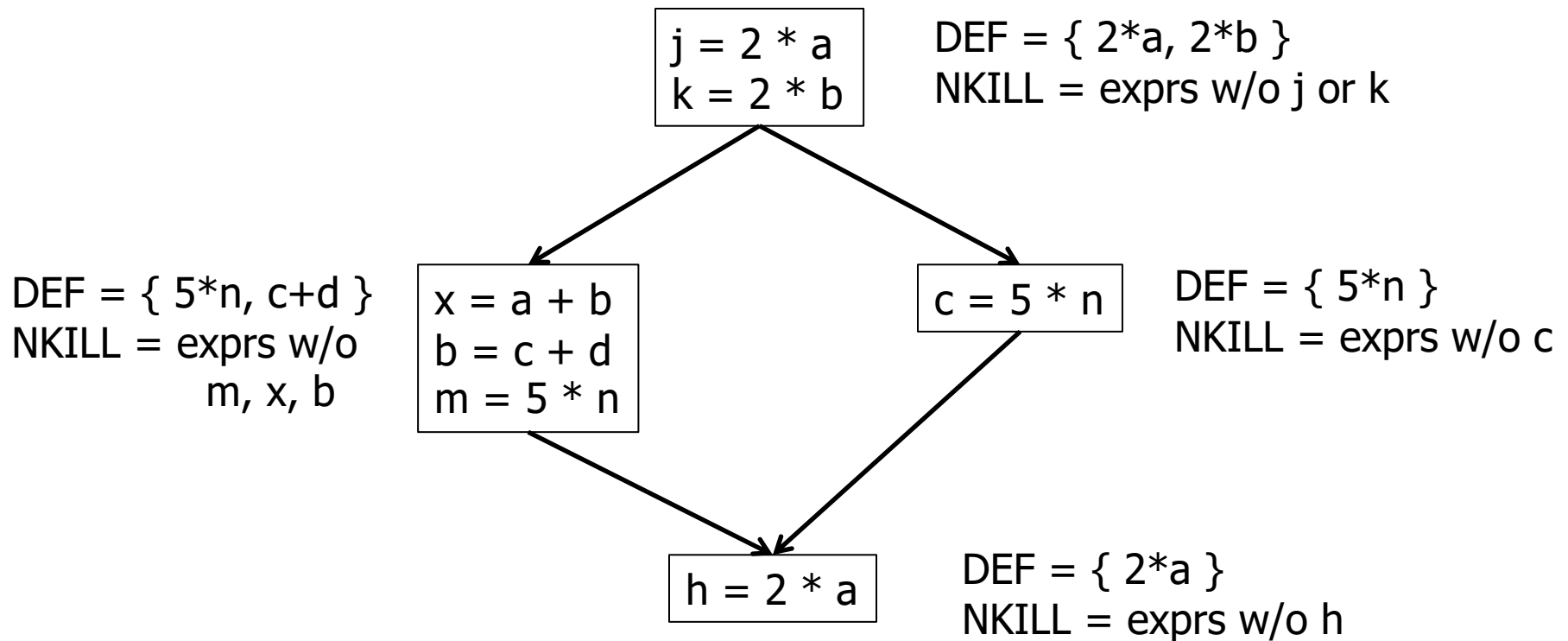
Example: Compute DEF and NKILL



Example: Compute DEF and NKILL



Example: Compute DEF and NKILL



Computing Available Expressions

Once $DEF(b)$ and $NKILL(b)$ are computed for all blocks b

Worklist = { all blocks b_i }

while (Worklist $\neq \emptyset$)

 remove a block b from Worklist

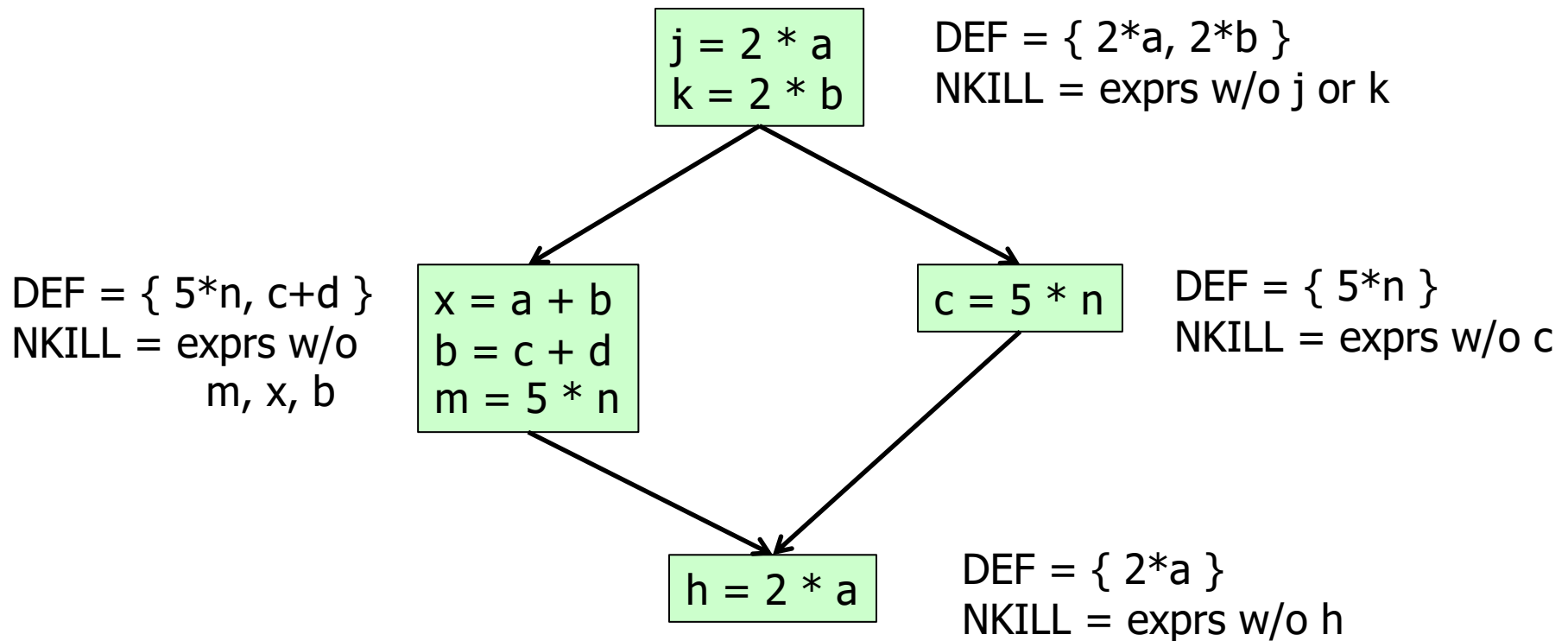
 recompute $AVAIL(b)$

 if $AVAIL(b)$ changed

 Worklist = Worklist \cup successors(b)

Example: Find Available Expressions

$$AVAIL(b) = \bigcap_{x \in \text{preds}(b)} (\text{DEF}(x) \cup (\text{AVAIL}(x) \cap \text{NKILL}(x)))$$

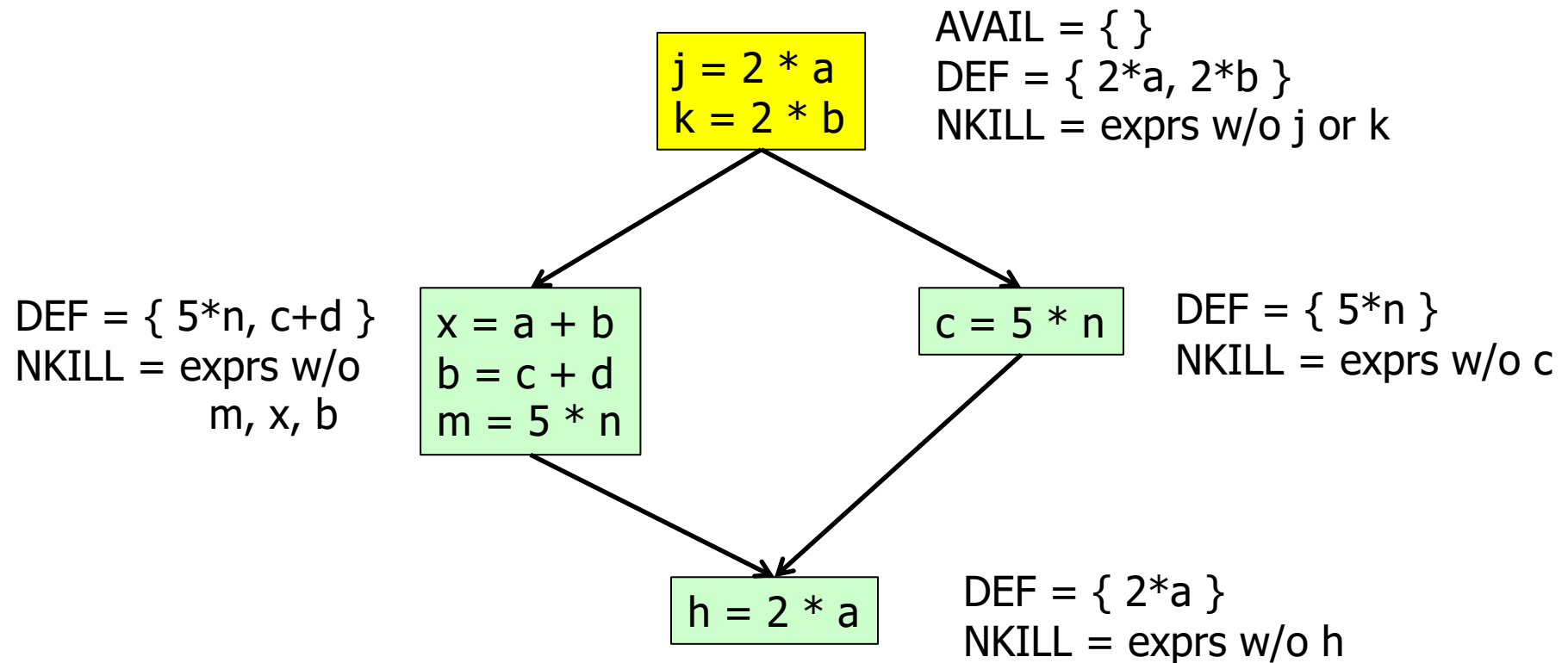


= in worklist

= processing

Example: Find Available Expressions

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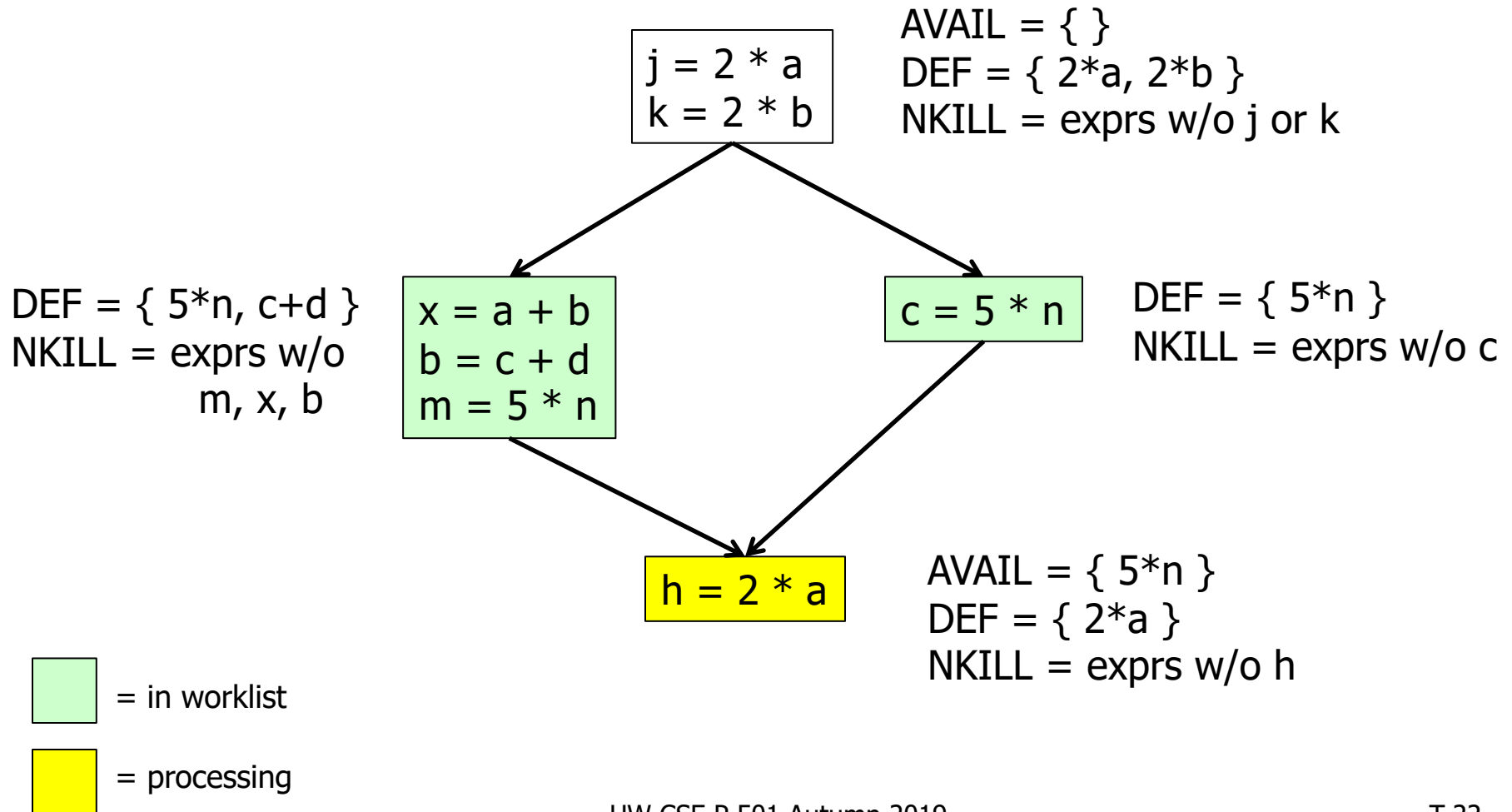


= in worklist

= processing

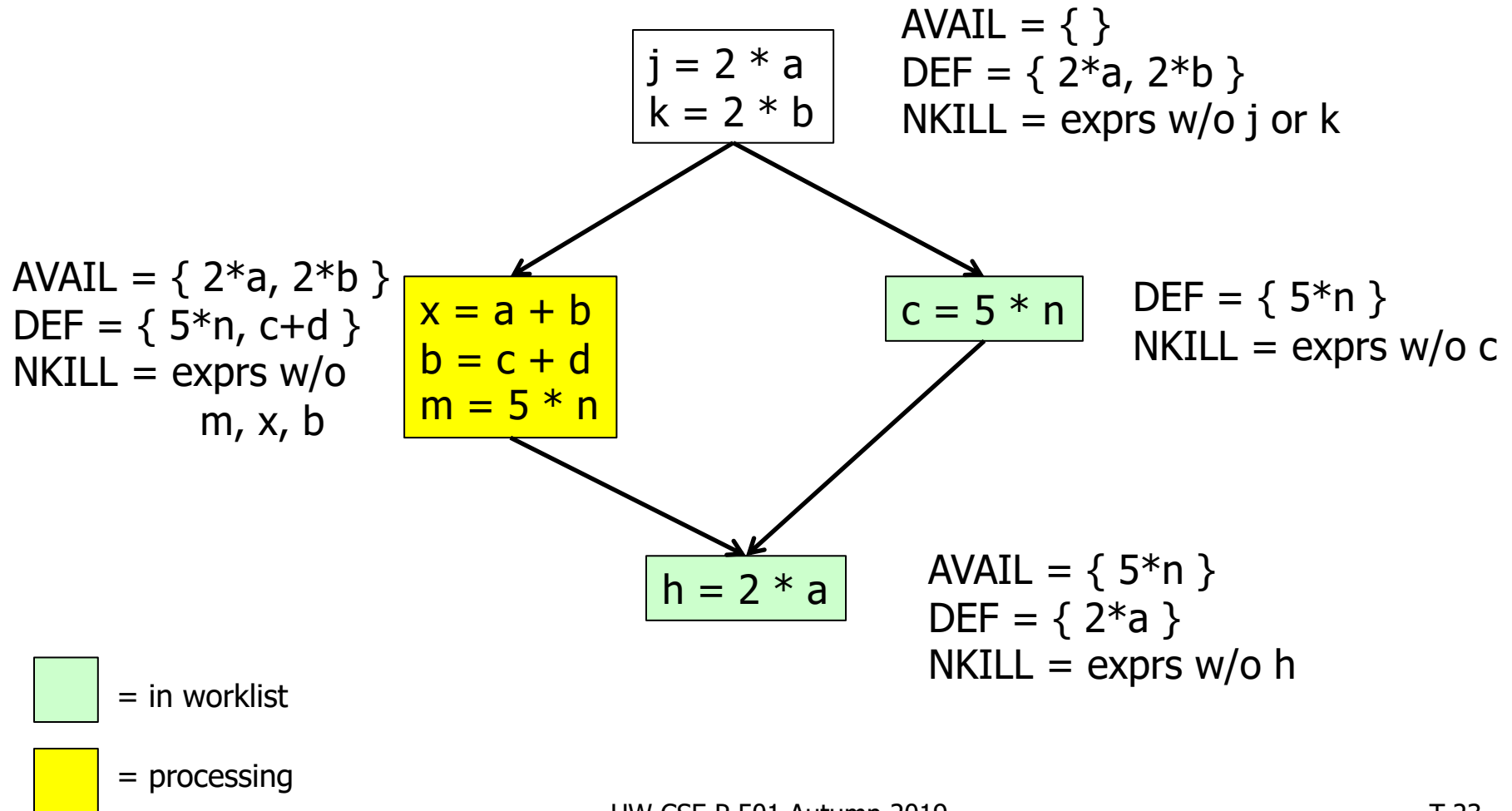
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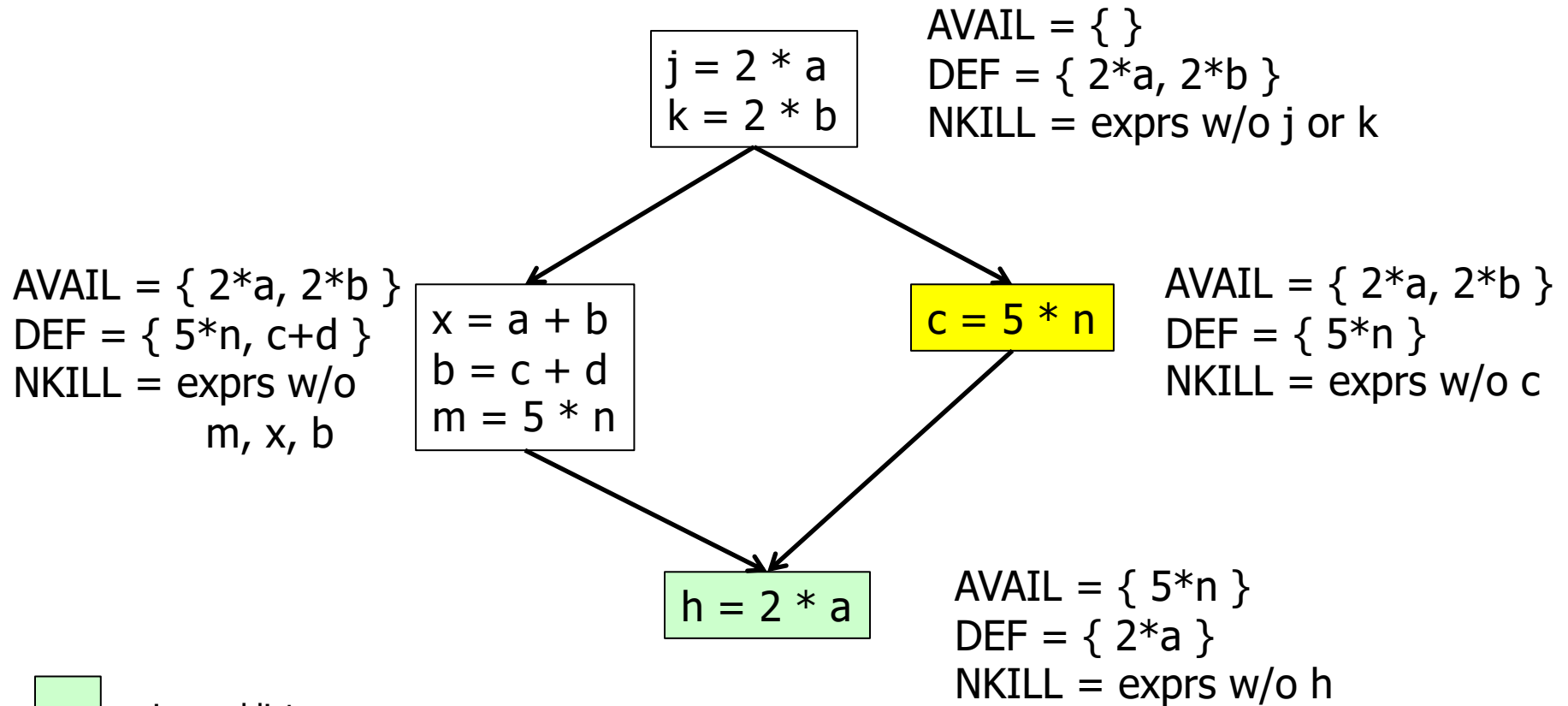
Example: Find Available Expressions


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


Example: Find Available Expressions

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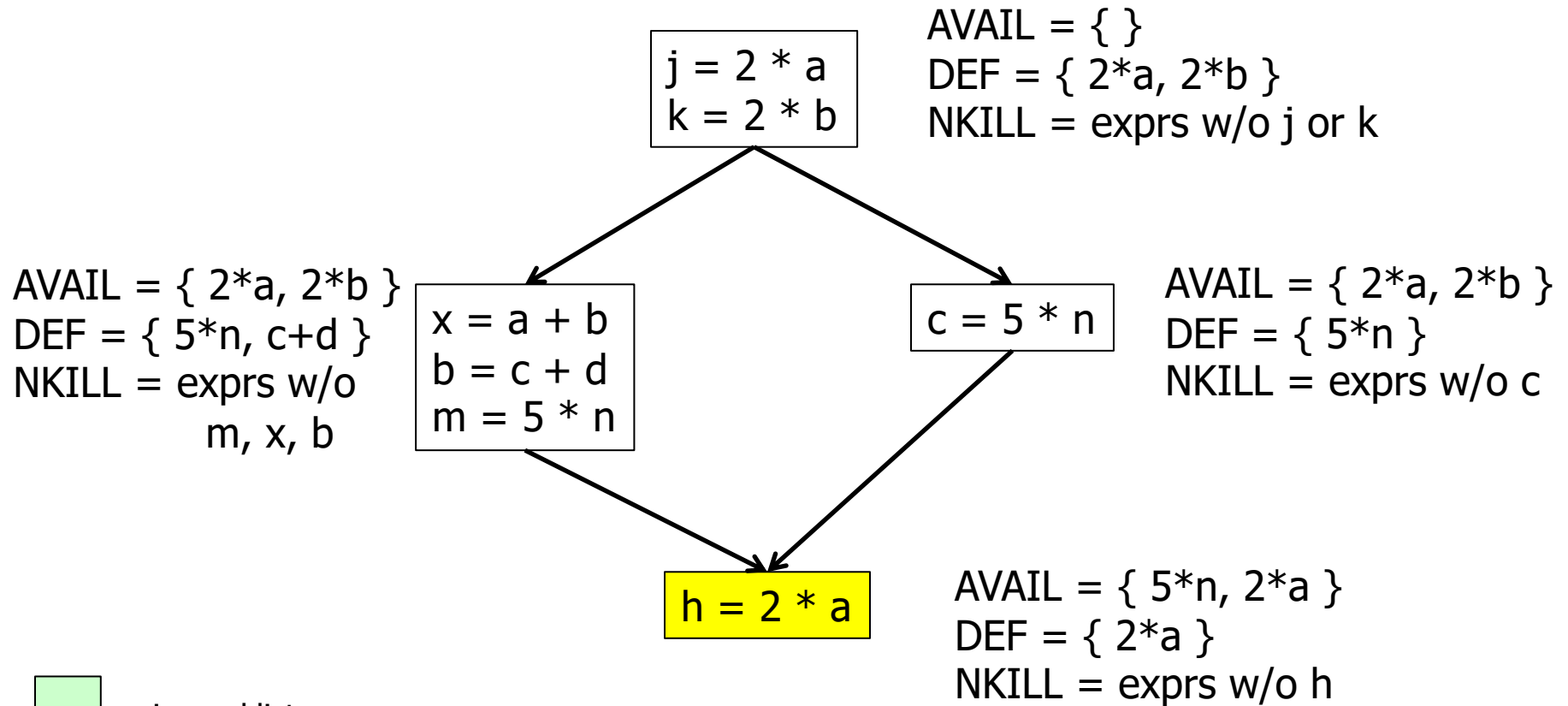


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Example: Find Available Expressions

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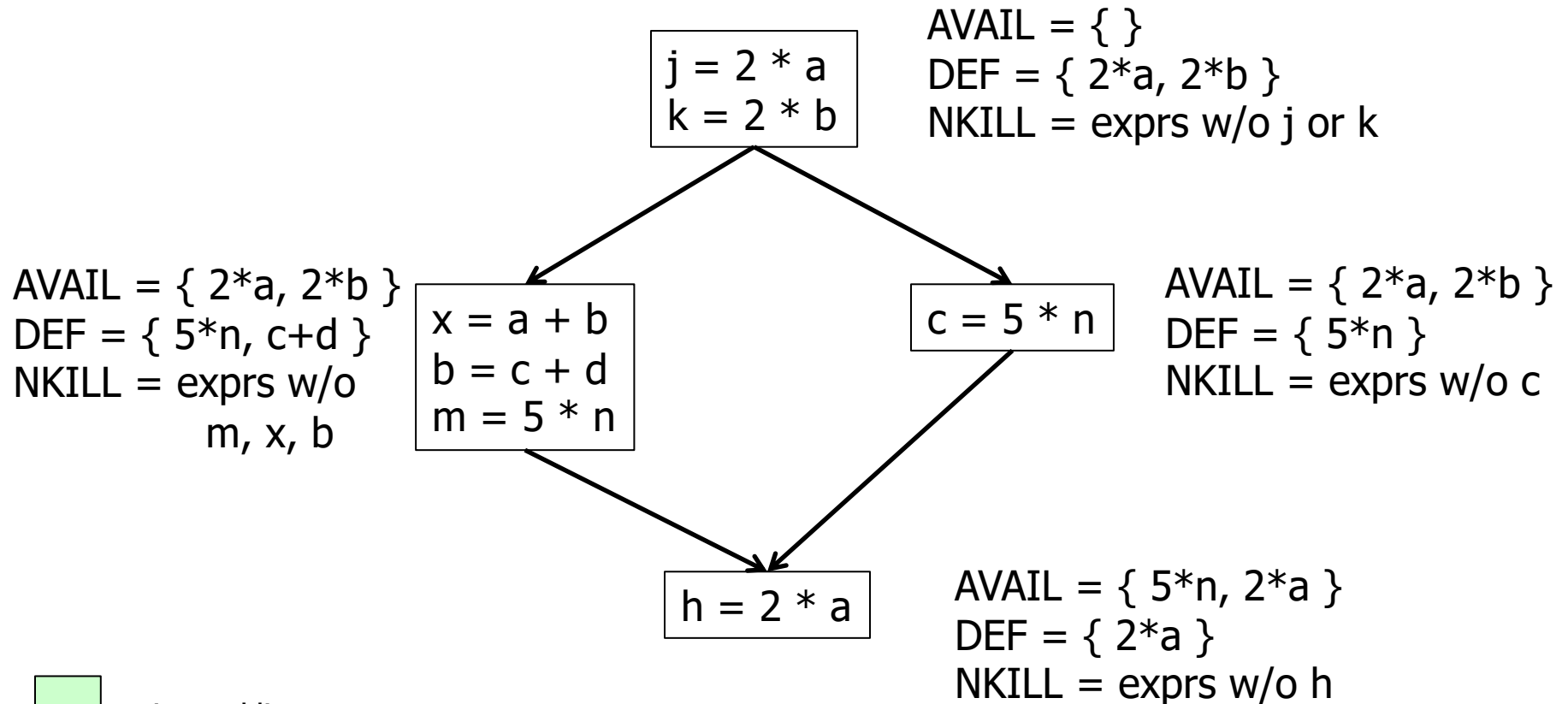


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Example: Find Available Expressions

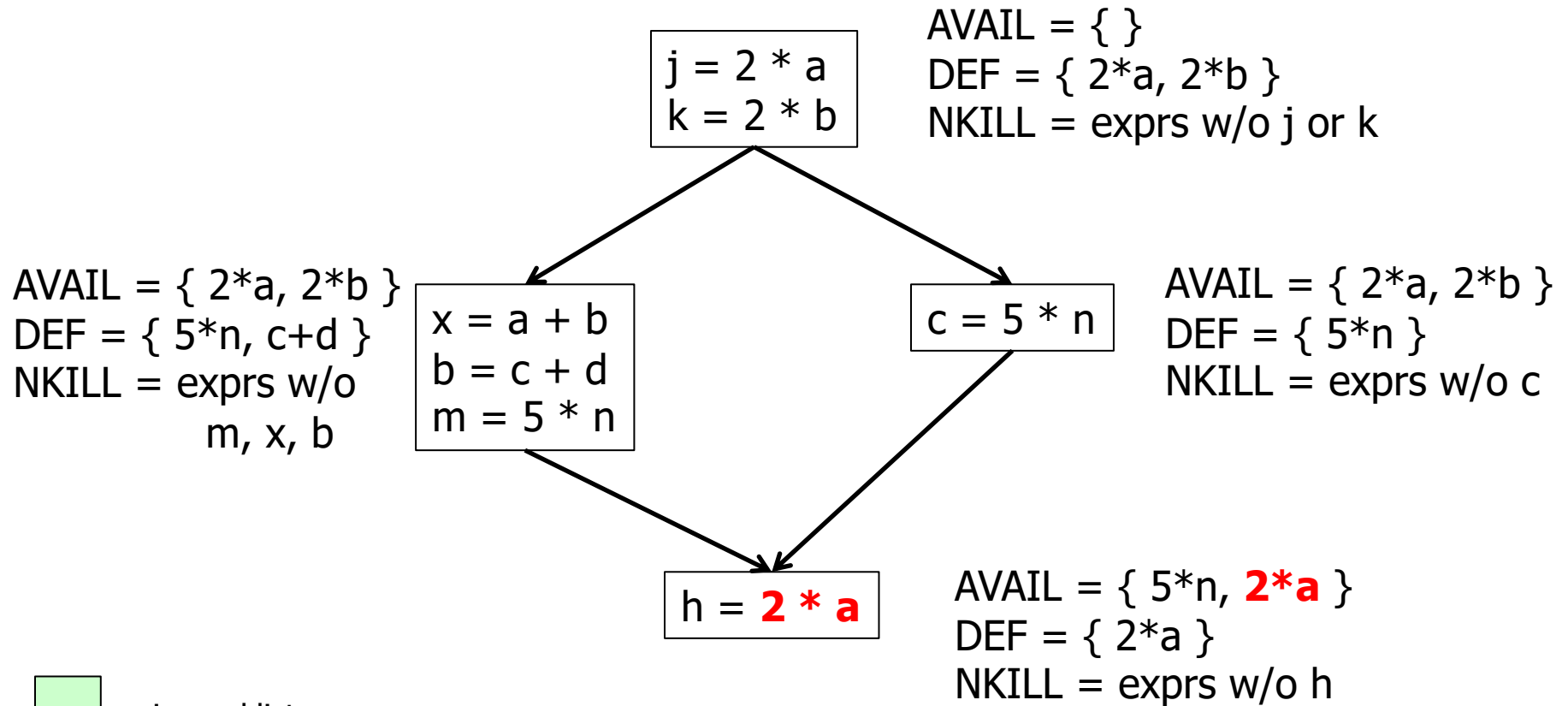
$$AVAIL(b) = \bigcap_{x \in \text{preds}(b)} (\text{DEF}(x) \cup (\text{AVAIL}(x) \cap \text{NKILL}(x)))$$



And the common subexpression is???

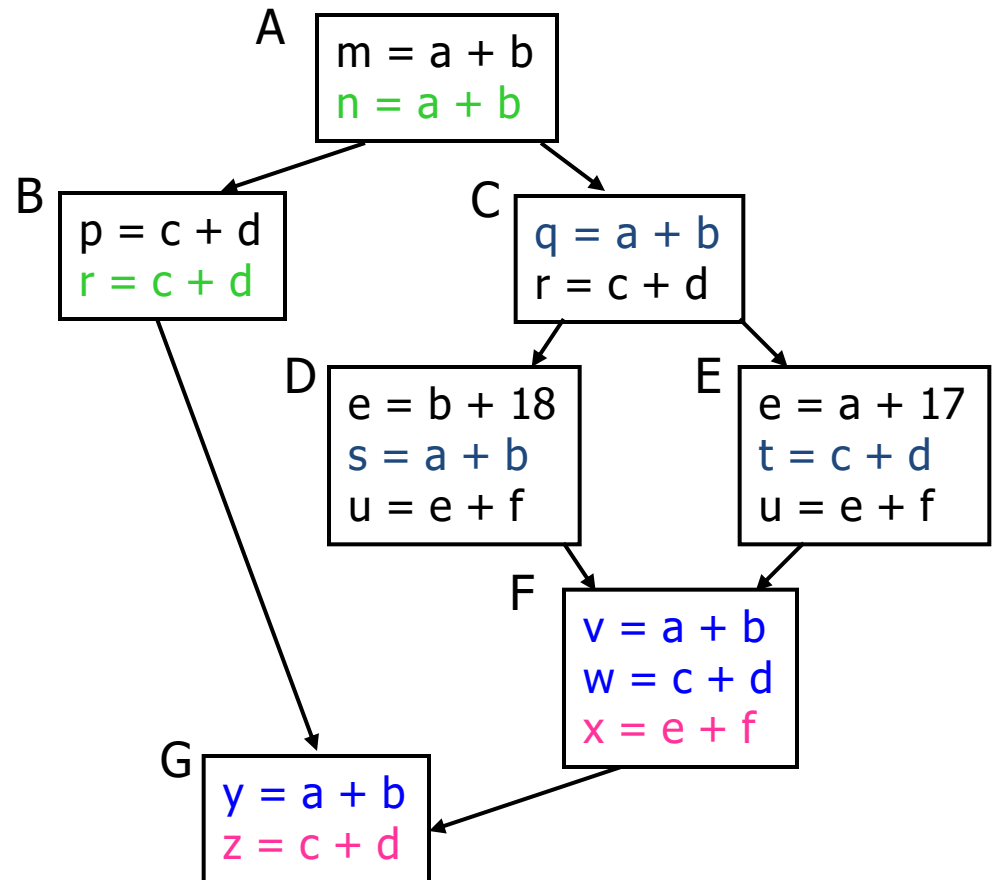
Example: Find Available Expressions

$$AVAIL(b) = \bigcap_{x \in \text{preds}(b)} (\text{DEF}(x) \cup (\text{AVAIL}(x) \cap \text{NKILL}(x)))$$



Comparing Algorithms

- LVN – Local Value Numbering
- SVN – Superlocal Value Numbering
- DVN – Dominator-based Value Numbering
- GRE – Global Redundancy Elimination



Comparing Algorithms (2)

- LVN \Rightarrow SVN \Rightarrow DVN form a strict hierarchy – later algorithms find a superset of previous information
- Global RE finds a somewhat different set
 - Discovers $e+f$ in F (computed in both D and E)
 - Misses identical values if they have different names (e.g., $a+b$ and $c+d$ when $a=c$ and $b=d$)
 - Value Numbering catches this

Scope of Analysis

- Larger context (EBBs, regions, global, interprocedural) sometimes helps
 - More opportunities for optimizations
- But not always
 - Introduces uncertainties about flow of control
 - Usually only allows weaker analysis
 - Sometimes has unwanted side effects
 - Can create additional pressure on registers, for example

Dataflow analysis

- Available expressions are an example of a *dataflow analysis* problem
- Many similar problems can be expressed in a similar framework
- Only the first part of the story – once we've discovered facts, we then need to use them to improve code

Characterizing Dataflow Analysis

- All of these algorithms involve sets of facts about each basic block b
 - IN(b) – facts true on entry to b
 - OUT(b) – facts true on exit from b
 - GEN(b) – facts created and not killed in b
 - KILL(b) – facts killed in b
- These are related by the equation
$$\text{OUT}(b) = \text{GEN}(b) \cup (\text{IN}(b) - \text{KILL}(b))$$
 - Solve this iteratively for all blocks
 - Sometimes information propagates forward; sometimes backward

Dataflow Analysis (1)

- A collection of techniques for compile-time reasoning about run-time values
- Almost always involves building a graph
 - Trivial for basic blocks
 - Control-flow graph or derivative for global problems
 - Call graph or derivative for whole-program problems

Dataflow Analysis (2)

- Usually formulated as a set of *simultaneous equations* (dataflow problem)
 - Sets attached to nodes and edges
 - Need a lattice (or semilattice) to describe values
 - In particular, has an appropriate operator to combine values and an appropriate “bottom” or minimal value

Dataflow Analysis (3)

- Desired solution is usually a *meet over all paths* (MOP) solution
 - “What is true on every path from entry”
 - “What can happen on any path from entry”
 - Usually relates to safety of optimization

Dataflow Analysis (4)

- Limitations
 - Precision – “up to symbolic execution”
 - Assumes all paths taken
 - Sometimes cannot afford to compute full solution
 - Arrays – classic analysis treats each array as a single fact
 - Pointers – difficult, expensive to analyze
 - Imprecision rapidly adds up
 - But gotta do it to effectively optimize things like C/C++
- For scalar values we can quickly solve simple problems

Example: Live Variable Analysis

- A variable v is *live* at point p iff there is *any* path from p to a use of v along which v is not redefined
- Some uses:
 - Register allocation – only live variables need a register
 - Eliminating useless stores – if variable not live at store, then stored variable will never be used
 - Detecting uses of uninitialized variables – if live at declaration (before initialization) then it might be used uninitialized
 - Improve SSA construction – only need Φ -function for variables that are live in a block (later)

Liveness Analysis Sets

- For each block b , define
 - $use[b]$ = variable used in b before any def
 - $def[b]$ = variable defined in b & not killed
 - $in[b]$ = variables live on entry to b
 - $out[b]$ = variables live on exit from b

Equations for Live Variables

- Given the preceding definitions, we have

$$\text{in}[b] = \text{use}[b] \cup (\text{out}[b] - \text{def}[b])$$

$$\text{out}[b] = \bigcup_{s \in \text{succ}[b]} \text{in}[s]$$

- Algorithm

- Set $\text{in}[b] = \text{out}[b] = \emptyset$

- Update in, out until no change

Example (1 stmt per block)

- Code

a := 0

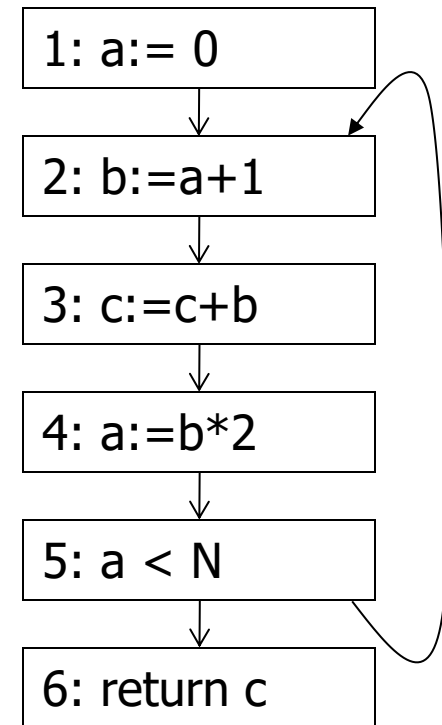
L: b := a+1

c := c+b

a := b*2

if a < N goto L

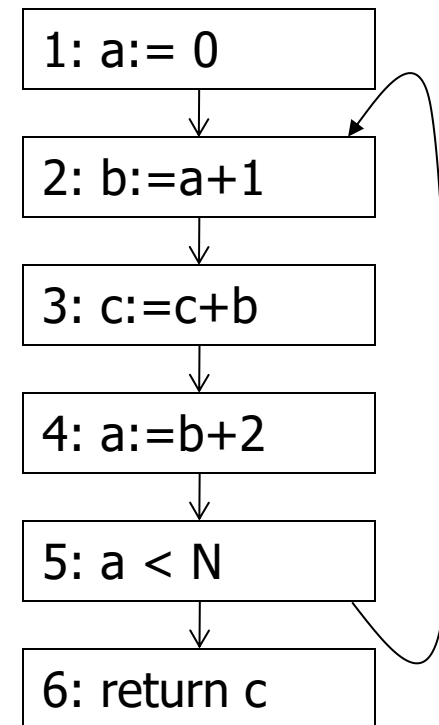
return c



$$\text{in}[b] = \text{use}[b] \cup (\text{out}[b] - \text{def}[b])$$
$$\text{out}[b] = \bigcup_{s \in \text{succ}[b]} \text{in}[s]$$

Calculation

block	use	def	I		II		III	
			out	in	out	in	out	in
6								
5								
4								
3								
2								
1								

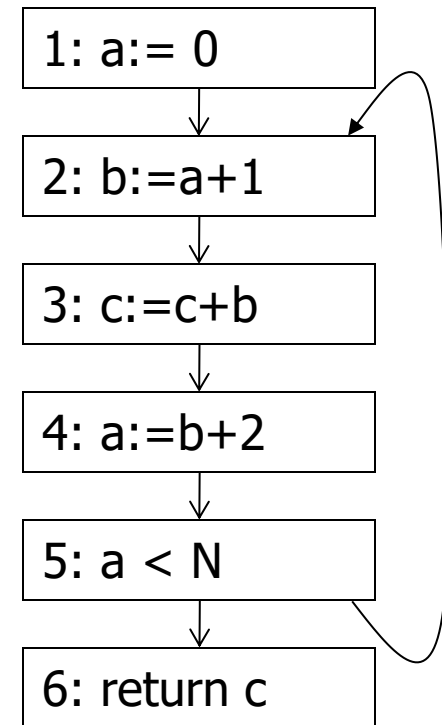


$$\text{in}[b] = \text{use}[b] \cup (\text{out}[b] - \text{def}[b])$$

$$\text{out}[b] = \bigcup_{s \in \text{succ}[b]} \text{in}[s]$$

Calculation

			I	II	III			
block	use	def	out	in	out	in	out	in
6	c	--	--	c	--	c		
5	a	--	c	a,c	a,c	a,c		
4	b	a	a,c	b,c	a,c	b,c		
3	b,c	c	b,c	b,c	b,c	b,c		
2	a	b	b,c	a,c	b,c	a,c		
1	--	a	a,c	c	a,c	c		



$$\text{in}[b] = \text{use}[b] \cup (\text{out}[b] - \text{def}[b])$$

$$\text{out}[b] = \bigcup_{s \in \text{succ}[b]} \text{in}[s]$$

Equations for Live Variables v2

- Many problems have more than one formulation. For example, Live Variables...
- Sets
 - USED(b) – variables used in b before being defined in b
 - NOTDEF(b) – variables not defined in b
 - LIVE(b) – variables live on *exit* from b
- Equation

$$\text{LIVE}(b) = \bigcup_{s \in \text{succ}(b)} \text{USED}(s) \cup (\text{LIVE}(s) \cap \text{NOTDEF}(s))$$

Efficiency of Dataflow Analysis

- The algorithms eventually terminate, but the expected time needed can be reduced by picking a good order to visit nodes in the CFG
 - Forward problems – reverse postorder
 - Backward problems – postorder

Example: Reaching Definitions

- A definition d of some variable v *reaches* operation i iff i reads the value of v and there is a path from d to i that does not define v
- Uses
 - Find all of the possible definition points for a variable in an expression

Equations for Reaching Definitions

- Sets
 - DEFOUT(b) – set of definitions in b that reach the end of b (i.e., not subsequently redefined in b)
 - SURVIVED(b) – set of all definitions not obscured by a definition in b
 - REACHES(b) – set of definitions that reach b

- Equation

$$\text{REACHES}(b) = \bigcup_{p \in \text{preds}(b)} \text{DEFOUT}(p) \cup (\text{REACHES}(p) \cap \text{SURVIVED}(p))$$

Example: Very Busy Expressions

- An expression e is considered *very busy* at some point p if e is evaluated and used along every path that leaves p , and evaluating e at p would produce the same result as evaluating it at the original locations
- Uses
 - Code hoisting – move e to p (reduces code size; no effect on execution time)

Equations for Very Busy Expressions

- Sets
 - USED(b) – expressions used in b before they are killed
 - KILLED(b) – expressions redefined in b before they are used
 - VERYBUSY(b) – expressions very busy on exit from b

- Equation

$$\text{VERYBUSY}(b) = \bigcap_{s \in \text{succ}(b)} \text{USED}(s) \cup (\text{VERYBUSY}(s) - \text{KILLED}(s))$$

Using Dataflow Information

- A few examples of possible transformations...

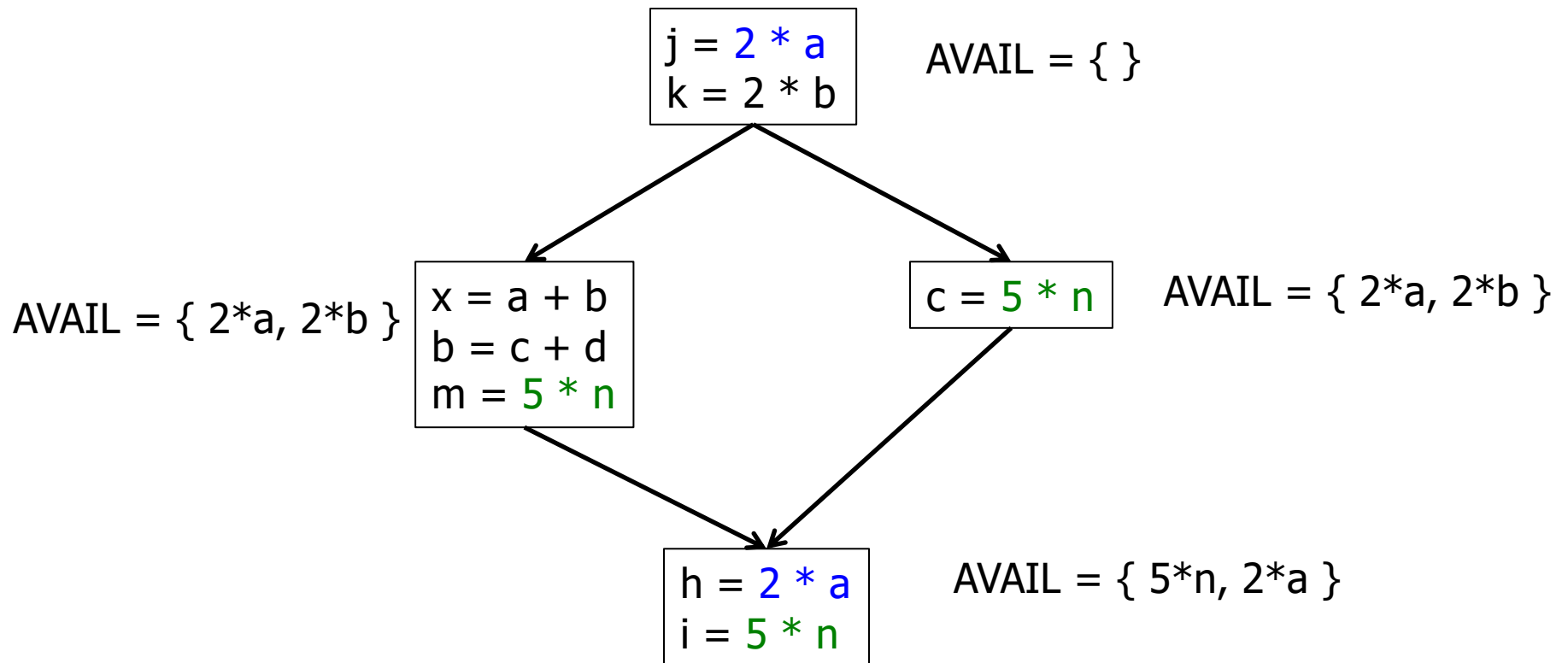
Classic Common-Subexpression Elimination (CSE)

- In a statement $s: t := x \text{ op } y$, if $x \text{ op } y$ is *available* at s then it need not be recomputed
- Analysis: compute *reaching expressions* i.e., statements $n: v := x \text{ op } y$ such that the path from n to s does not compute $x \text{ op } y$ or define x or y

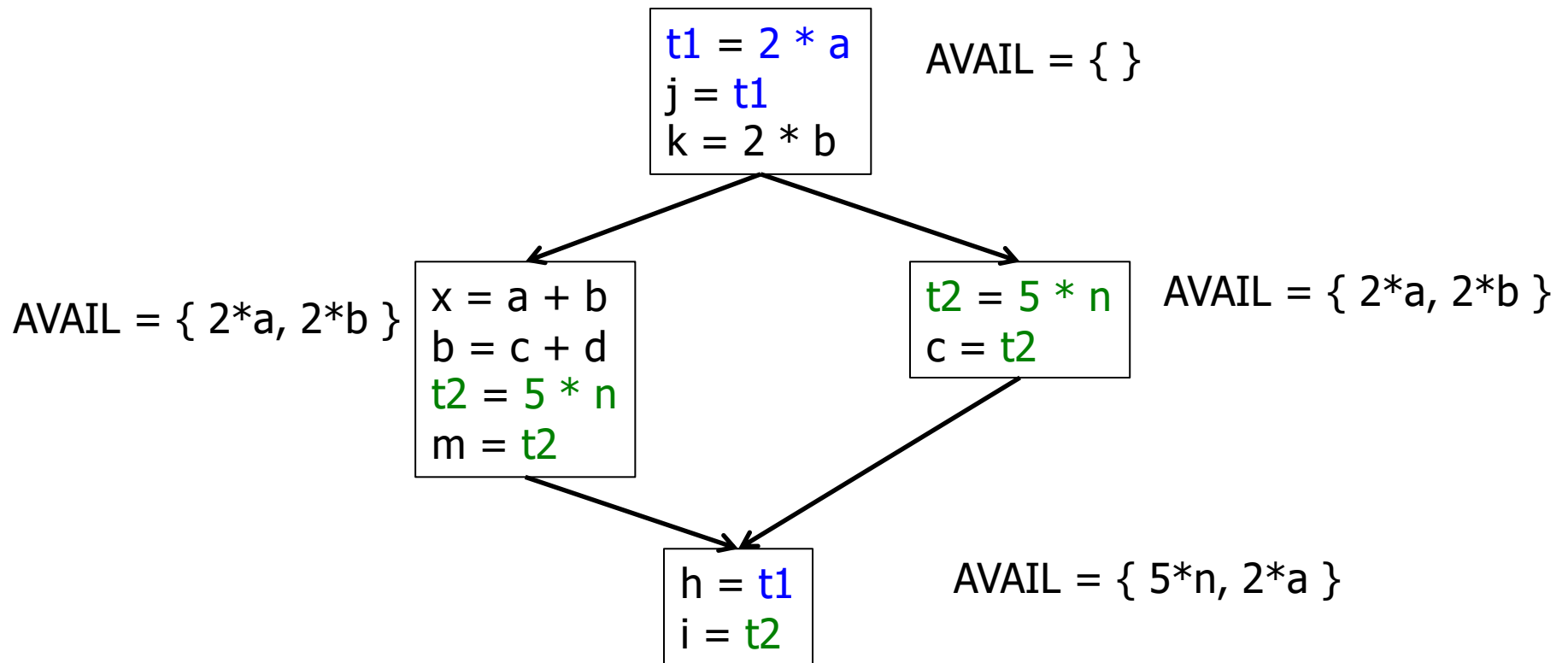
Classic CSE Transformation

- If $x \text{ op } y$ is defined at n and reaches s
 - Create new temporary w
 - Rewrite $n: v := x \text{ op } y$ as
 - $n: w := x \text{ op } y$
 - $n': v := w$
 - Modify statement s to be
 - $s: t := w$
 - (Rely on copy propagation to remove extra assignments that are not really needed)

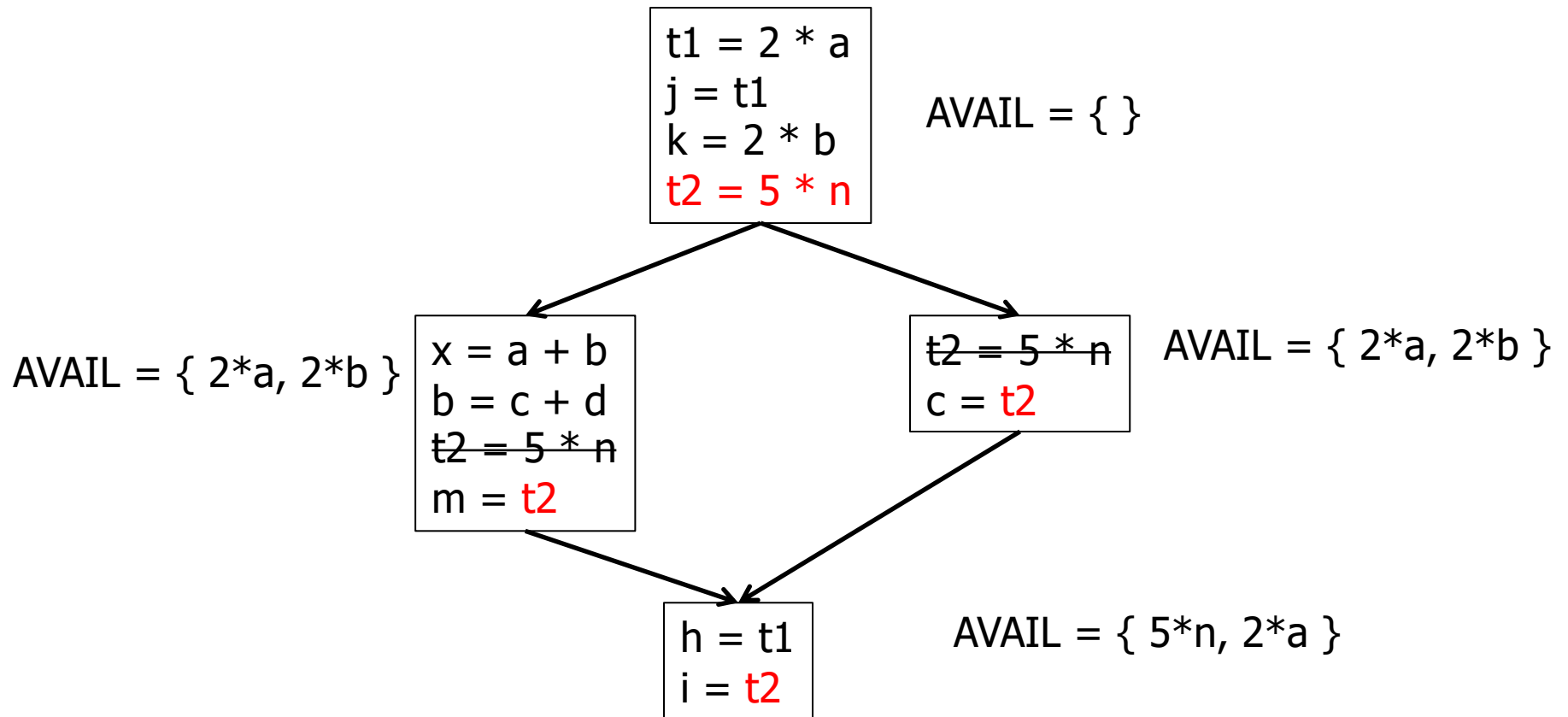
Revisiting Example (w/small change)



Revisiting Example (w/small change)



Then Apply Very Busy...



Constant Propagation

- Suppose we have
 - Statement d : $t := c$, where c is constant
 - Statement n that uses t
- If d reaches n and no other definitions of t reach n , then rewrite n to use c instead of t

Copy Propagation

- Similar to constant propagation
- Setup:
 - Statement d: $t := z$
 - Statement n uses t
- If d reaches n and no other definition of t reaches n, and there is no definition of z on any path from d to n, then rewrite n to use z instead of t
 - Recall that this can help remove dead assignments

Copy Propagation Tradeoffs

- Downside is that this can increase the lifetime of variable z and increase need for registers or memory traffic
- But it can expose other optimizations, e.g.,
 - $a := y + z$
 - $u := y$
 - $c := u + z$ // copy propagation makes this $y + z$
- After copy propagation we can recognize the common subexpression

Dead Code Elimination

- If we have an instruction

$s: a := b \text{ op } c$

and a is not live-out after s , then s can be eliminated

- Provided it has no implicit side effects that are visible (output, exceptions, etc.)
 - If b or c are function calls, they have to be assumed to have unknown side effects unless the compiler can prove otherwise

Aliases

- A variable or memory location may have multiple names or *aliases*
 - Call-by-reference parameters
 - Variables whose address is taken (&x)
 - Expressions that dereference pointers (p.x, *p)
 - Expressions involving subscripts (a[i])
 - Variables in nested scopes

Aliases vs Optimizations

- Example:

`p.x := 5; q.x := 7; a := p.x;`

- Does reaching definition analysis show that the definition of `p.x` reaches `a`?
- (Or: do `p` and `q` refer to the same variable/object?)
- (Or: *can* `p` and `q` refer to the same thing?)

Aliases vs Optimizations

- Example

```
int f(int *p, int *q) {  
    *p = 1; *q = 2;  
    return *p;  
}
```

- How do we account for the possibility that p and q might refer to the same thing?
- Safe approximation: since it's possible, assume it is true (but rules out a lot)
 - C programmers can use “restrict” to indicate no other pointer is an alias for this one

Types and Aliases (1)

- In Java, ML, MiniJava, and others, if two variables have incompatible types they cannot be names for the same location
 - Also helps that programmer cannot create arbitrary pointers to storage in these languages

Types and Aliases (2)

- Strategy: Divide memory locations into *alias classes* based on type information (every type, array, record field is a class)
- Implication: need to propagate type information from the semantics pass to optimizer
 - Not normally true of a minimally typed IR
- Items in different alias classes cannot refer to each other

Aliases and Flow Analysis

- Idea: Base alias classes on points where a value is created
 - Every new/malloc and each local or global variable whose address is taken is an alias class
 - Pointers can refer to values in multiple alias classes (so each memory reference is to a set of alias classes)
 - Use to calculate “may alias” information (e.g., p “may alias” q at program point s)

Using “may-alias” information

- Treat each alias class as a “variable” in dataflow analysis problems
- Example: framework for available expressions
 - Given statement $s: M[a]:=b$,
 $gen[s] = \{ \}$
 $kill[s] = \{ M[x] \mid a \text{ may alias } x \text{ at } s \}$

May-Alias Analysis

- Without alias analysis, #2 kills $M[t]$ since x and t might be related
- If analysis determines that “ x may-alias t ” is false, $M[t]$ is still available at #3; can eliminate the common subexpression and use copy propagation
- Code
 - 1: $u := M[t]$
 - 2: $M[x] := r$
 - 3: $w := M[t]$
 - 4: $b := u+w$

Where are we now?

- Dataflow analysis is the core of classical optimizations
 - Although not the only possible story
- Still to explore:
 - Discovering and optimizing loops
 - SSA – Static Single Assignment form