CSE P 501 – Compilers

Intermediate Representations

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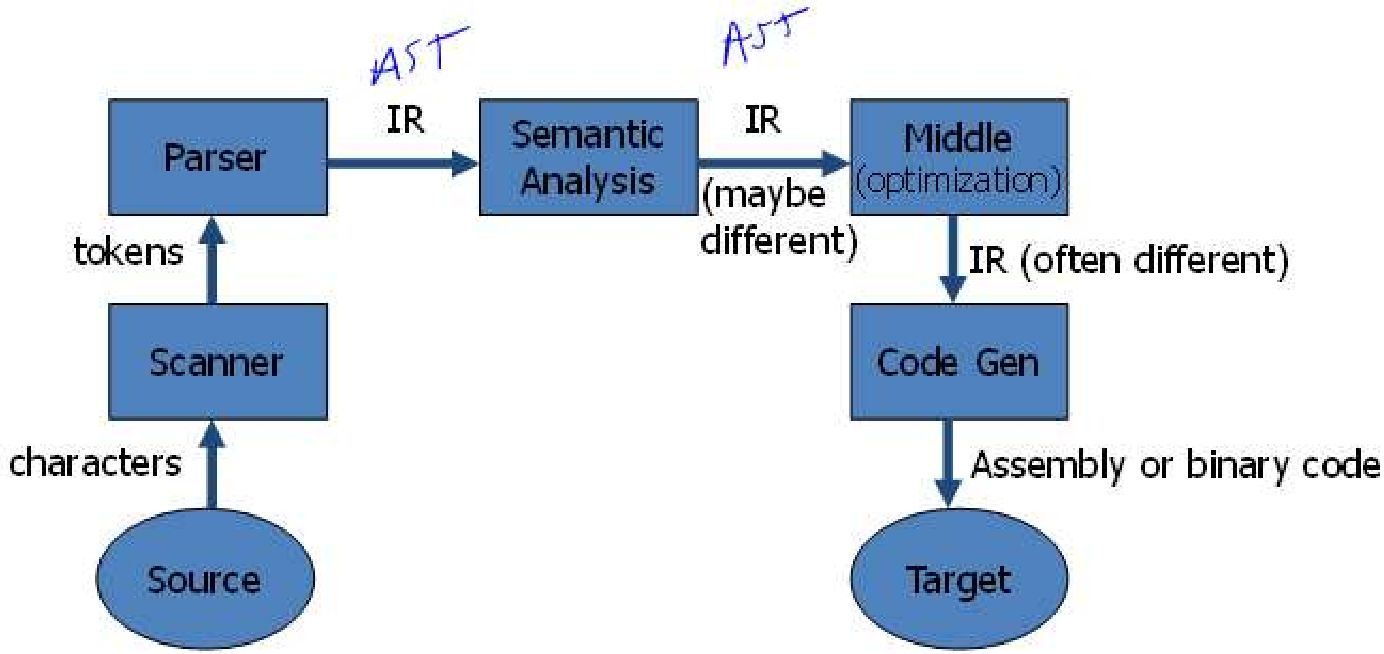
Administrivia

- Semantics/types/symbol table project due ~2 weeks – how goes it?
  - Should be caught up on grading and parser sanity checks late this week
- End-of-quarter probable schedule
  - Exam will be Thur. 3/3, 6:30-8:00 (both locations)
  - Compiler project final commit/push Sun. 3/13, 11pm
  - Compiler short report push by Mon. 3/14, 11pm
  - Project meetings: @Microsoft Tue. 3/15, @UW Wed. 3/16. What are good start times?

Agenda

- Survey of Intermediate Representations
  - Graphical
    - Concrete/Abstract Syntax Trees (ASTs)
    - Control Flow Graph
    - Dependence Graph
  - Linear Representations
    - Stack Based
    - 3-Address
- Several of these will show up as we explore program analysis and optimization

Compiler Structure (review)



Intermediate Representations

- In most compilers, the parser builds an intermediate representation of the program
  - Typically an AST, as in the MiniJava project
- Rest of the compiler transforms the IR to improve ("optimize") it and eventually translate to final target code
  - Typically will transform initial IR to one or more different IRs along the way
- Some general examples now; more specifics later as needed

IR Design

- Decisions affect speed and efficiency of the rest of the compiler
  - General rule: compile time is important, but performance of generated code often more important
  - Typical case for production code: compile a few times, run many times
    - Although the reverse is true during development
  - So make choices that improve compile time as long as they don't compromise the result

IR Design

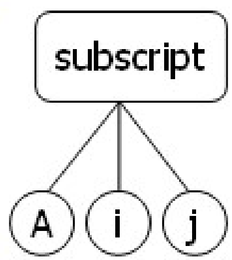
- Desirable properties
  - Easy to generate
  - Easy to manipulate
  - Expressive
  - Appropriate level of abstraction
- Different tradeoffs depending on compiler goals
- Different tradeoffs in different parts of the same compiler
  - So often different IRs in different parts

IR Design Taxonomy

- Structure
  - Graphical (trees, graphs, etc.)
  - Linear (code for some abstract machine)
  - Hybrids are common (e.g., control-flow graphs whose nodes are basic blocks of linear code)
- Abstraction Level
  - High-level, near to source language
  - Low-level, closer to machine (exposes more details to compiler)

Examples: Array Reference

source: A[i,j]



t1 ← A[i,j]

```
loadI  1   => r1
sub  rj,r1  => r2
loadI  10  => r3
mult r2,r3 => r4
sub  ri,r1  => r5
add  r4,r5 => r6
loadI @A  => r7
add  r7,r6 => r8
load r8    => r9
```

Levels of Abstraction

- Key design decision: how much detail to expose
  - Affects possibility and profitability of various optimizations
    - Depends on compiler phase: some semantic analysis & optimizations are easier with high-level IRs close to the source code. Low-level usually preferred for other optimizations, register allocation, code generation, etc.
  - ✓ Structural (graphical) IRs are typically fairly high-level – but are also used for low-level
  - ✓ Linear IRs are typically low-level
  - But these generalizations don't always hold

Graphical IRs

- IR represented as a graph (or tree)
- Nodes and edges typically reflect some structure of the program
  - E.g., source code, control flow, data dependence
- May be large (especially syntax trees)
- High-level examples: syntax trees, DAGs
  - Generally used in early phases of compilers
- Other examples: control flow graphs and data dependency graphs
  - Often used in optimization and code generation

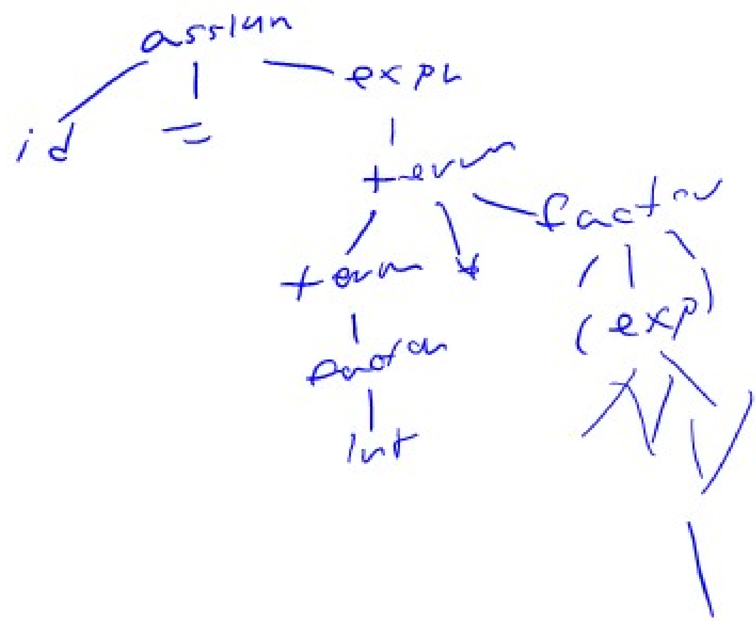
Concrete Syntax Trees

- The full grammar is needed to guide the parser, but contains many extraneous details
  - Chain productions
  - Rules that control precedence and associativity
- Typically the full syntax tree (parse tree) does not need to be used explicitly, but sometimes we want it (structured source code editors or transformations, …)

assign ::= *id* = *expr* ;
expr ::= *expr* + *term* | *expr* – *term* | *term*
term ::= *term* * *factor* | *term* / *factor* | *factor*
factor ::= *int* | *id* | (*expr*)

Example

- Concrete syntax for x = 2*(n+m)



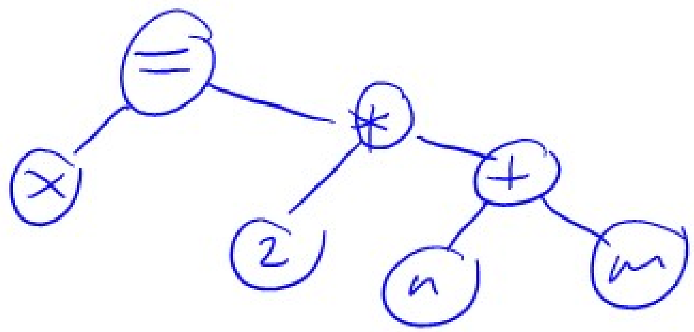
Abstract Syntax Trees

- Want only essential structural information
  - Omit extra junk
- Can be represented explicitly as a tree or in a linear form
  - Example: LISP/Scheme S-expressions are essentially ASTs
- Common output from parser; used for static semantics (type checking, etc.) and sometimes high-level optimizations

Example

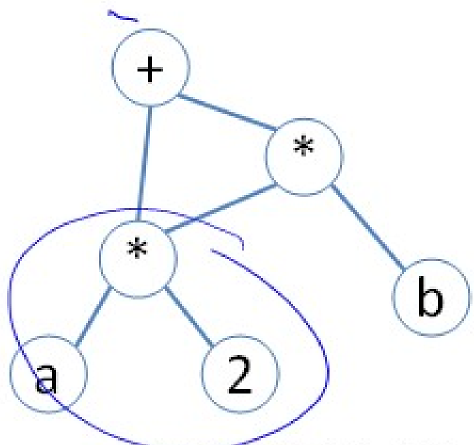
assign ::= *id* = *expr* ;
expr ::= *expr* + *term* | *expr* – *term* | *term*
term ::= *term* * *factor* | *term* / *factor* | *factor*
factor ::= *int* | *id* | (*expr*)

- Abstract syntax for x = 2*(n+m)



DAGs (Directed Acyclic Graphs)

- Variation on ASTs with shared substructures
- Pro: saves space, exposes redundant sub-expressions
- Con: less flexibility if part needs to be changed



(a*b) + (a*b) * b

Linear IRs

- Pseudo-code for some abstract machine
- Level of abstraction varies
- Simple, compact data structures
  - Commonly used: arrays, linked lists
- Examples: 3-address code, stack machine code

```
t1 ← 2
t2 ← b
t3 ← t1 * t2
t4 ← a
t5 ← t4 – t3
```

- Fairly compact
- Compiler can control reuse of names – clever choice can reveal optimizations
- ILOC & similar code

```
push 2
push b
multiply
push a
subtract
```

- Each instruction consumes top of stack & pushes result
- Very compact
- Easy to create and interpret
- Java bytecode, MSIL

Abstraction Levels in Linear IR

- Linear IRs can also be close to the source language, very low-level, or somewhere in between.
- Examples: Linear IRs for C array reference a[i][j+2]
  - High-level: $t1 \leftarrow a[i,j+2]$

More IRs for a[i][j+2]

- Medium-level

t1 ← j + 2

t2 ← i * 20

t3 ← t1 + t2

t4 ← 4 * t3

t5 ← addr a

t6 ← t5 + t4

t7 ← *t6

- Low-level

r1 ← [fp-4]

r2 ← r1 + 2

r3 ← [fp-8]

r4 ← r3 * 20

r5 ← r4 + r2

r6 ← 4 * r5

r7 ← fp – 216

f1 ← [r7+r6]

Abstraction Level Tradeoffs

- High-level: good for some source-level optimizations, semantic checking, but can't optimize things that are hidden – like address arithmetic for array subscripting
- Low-level: need for good code generation and resource utilization in back end but loses semantic knowledge (e.g., variables, data aggregates, source relationships are usually missing)
- Medium-level: more detail but keeps more higher-level semantic information – great for machine-independent optimizations. Many (all?) optimizing compilers work at this level
- Many compilers use all 3 in different phases

Three-Address Code (TAC)

- Usual form: $x \leftarrow y \text{ op } z$
  - One operator
  - Maximum of 3 names
  - (Copes with: nullary $x \leftarrow y$ and unary $x \leftarrow \text{op } y$)

- Eg: $x = 2 * (m + n)$ becomes
  - $t1 \leftarrow m + n; \quad t2 \leftarrow 2 * t1; \quad x \leftarrow t2$
  - You may prefer: add t1, m, n;   mul t2, 2, t1;   mov x, t2
  - Invent as many new temp names as needed. "expression temps" – don't correspond to any user variables; de-anonymize expressions

- Store in a quad(ruple)
  - <lhs, rhs1, op, rhs2>

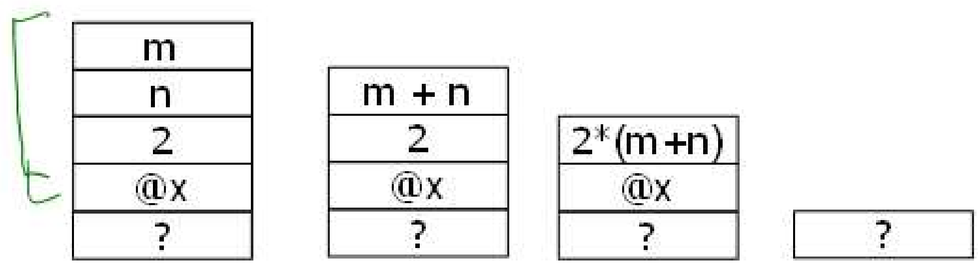
Three Address Code

- Advantages
  - Resembles code for actual machines
  - Explicitly names intermediate results
  - Compact
  - Often easy to rearrange
- Various representations
  - Quadruples, triples, SSA (Static Single Assignment)
  - We will see much more of this…

Stack Machine Code Example

Hypothetical code for x = 2 * (m + n)

```
pushaddr   x
pushconst  2
pushval    n
pushval    m
add
mult
store
```



Compact: common opcodes just 1 byte wide; instructions have 0 or 1 operand

Stack Machine Code

- Originally used for stack-based computers (famous example: B5000, ~1961)
- Also now used for virtual machines:
  - UCSD Pascal – pcode
  - Forth
  - Java bytecode in a .class files (generated by Java compiler)
  - MSIL in a .dll or .exe assembly (generated by C#/F#/VB compiler)
- Advantages
  - Compact; mostly 0-address opcodes (fast download over network)
  - Easy to generate; easy to write a FrontEnd compiler, leaving the 'heavy lifting' and optimizations to the JIT
  - Simple to interpret or compile to machine code
- Disadvantages
  - Inconvenient/difficult to optimize directly
  - Does not match up with modern chip architectures

Hybrid IRs

- Combination of structural and linear
- Level of abstraction varies
- Most common example: control-flow graph (CFG)

Control Flow Graph (CFG)

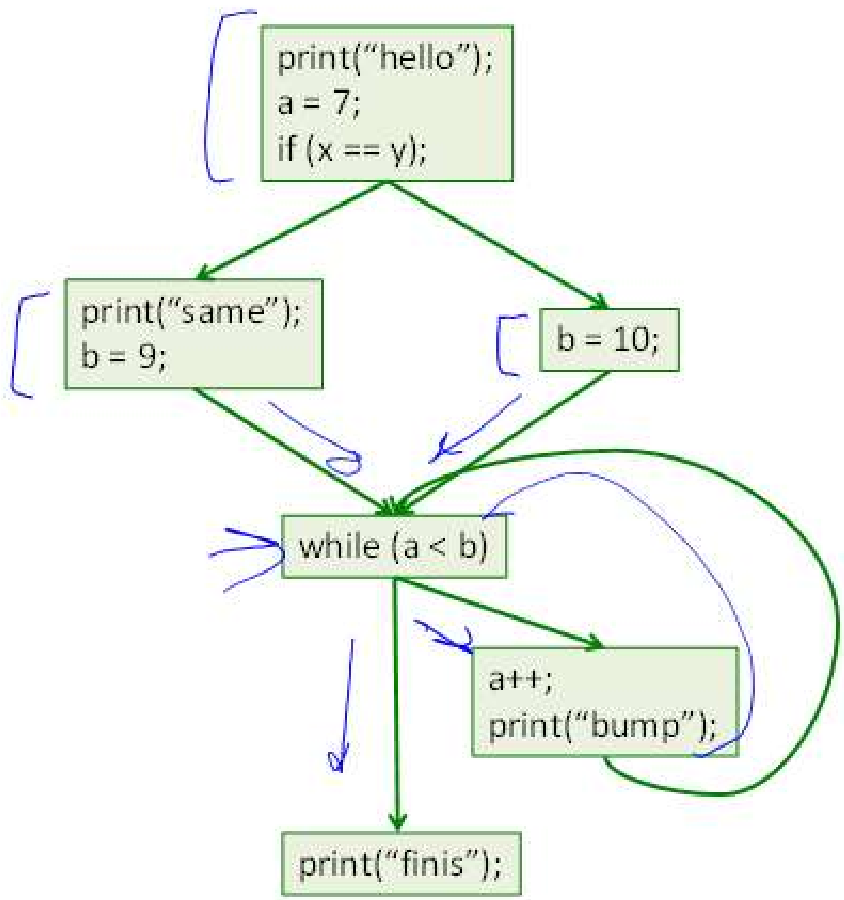
- Nodes: *basic blocks*
- Edges: represent possible flow of control from one block to another, i.e., possible execution orderings
  - Edge from A to B if B could execute immediately after A in some possible execution
- Required for much of the analysis done during optimization phases

Basic Blocks

- Fundamental concept in analysis/optimization
- A *basic block* is:
  - A sequence of code
  - One entry, one exit
  - Always executes as a single unit (“straightline code”) – so it can be treated as an indivisible block
    - We’ll ignore exceptions, at least for now
- Usually represented as some sort of a list although Trees/DAGs are possible

CFG Example

```
print("hello");
a=7;
if (x == y) {
  print("same");
  b = 9;
} else {
  b = 10;
}
while (a < b) {
  a++;
  print("bump");
}
print("finis");
```



Basic Blocks: Start with Tuples

```
1 i = 1
2 j = 1
3 t1 = 10 * i
4 t2 = t1 + j
5 t3 = 8 * t2
6 t4 = t3 - 88
7 a[t4] = 0
8 j = j + 1
9 if j <= 10 goto #3
10 i = i + 1
11 if i <= 10 goto #2
12 i = 1
13 t5 = i - 1
14 t6 = 88 * t5
15 a[t6] = 1
16 i = i + 1
17 if i <= 10 goto #13
```

Typical "tuple stew" - IR generated by traversing an AST

Partition into Basic Blocks:

- Sequence of consecutive instructions
- No jumps into the middle of a BB
- No jumps out of the middles of a BB
- "I've started, so I'll finish"
- (Ignore exceptions)

Basic Blocks: Leaders

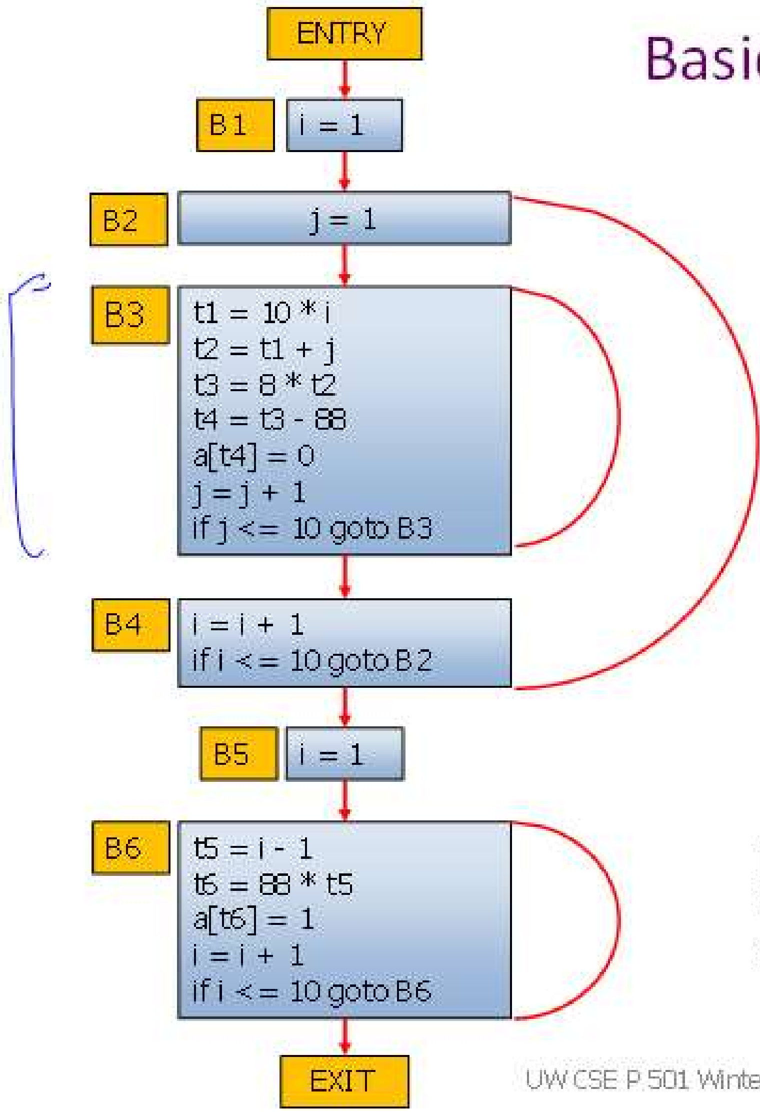
```
1 i = 1                      10 i = i + 1
2 j = 1                      11 if i <= 10 goto #2
3 t1 = 10 * i                12 i = 1
4 t2 = t1 + j                13 t5 = i - 1
5 t3 = 8 * t2                14 t6 = 88 * t5
6 t4 = t3 - 88               15 a[t6] = 1
7 a[t4] = 0                  16 i = i + 1
8 j = j + 1                  17 if i <= 10 goto #13
9 if j <= 10 goto #3
```

Identify Leaders (first instruction in a basic block):

- First instruction is a leader
- Any target of a branch/jump/goto
- Any instruction immediately after a branch/jump/goto

Leaders in red. Why is each leader a leader?

Basic Blocks: Flowgraph



Control Flow Graph ("CFG", again!)

- 3 loops total
- 2 of the loops are nested

Most of the executions likely spent in loop bodies; that's where to focus efforts at optimization

Identifying Basic Blocks: Recap

- Perform linear scan of instruction stream
- A basic blocks begins at each instruction that is:
  - The beginning of a method
  - The target of a branch
  - Immediately follows a branch or return

Dependency Graphs

- Often used in conjunction with another IR
- Data dependency: edges between nodes that reference common data
- Examples
  - Block A defines x then B reads it (RAW – read after write)
  - Block A reads x then B writes it (WAR – "anti-dependence)
  - Blocks A and B both write x (WAW) – order of blocks must reflect original program semantics
- These restrict reorderings the compiler can do

What IR to Use?

- Common choice: all(!)
  - AST used in early stages of the compiler
    - Closer to source code
    - Good for semantic analysis
    - Facilitates some higher-level optimizations
  - Lower to linear IR for optimization and codegen
    - Closer to machine code
    - Use to build control-flow graph
    - Exposes machine-related optimizations
  - Hybrid (graph + linear IR = CFG) for dataflow & opt

Coming Attractions

- Survey of compiler “optimizations”
- Analysis and transformation algorithms for optimizations (including SSA IR)
- Back-end organization in production compilers
  - Instruction selection and scheduling, register allocation
- Other topics depending on time
  - Dynamic languages? JVM? Memory management (garbage collection)? Any preferences?