DATA516/CSED516 Scalable Data Systems and Algorithms

Lecture 5

Parallel Query Execution

Announcements

Project proposals were due on Friday

Small review assignment was due today

HW3 is posted, due on Nov. 15

Outline

Basic notions

Distributed query processing algorithms

Skew (will continue next lecture)

Distributed/Parallel Query Processing

Parallel DBs since the 80s

Usually limited to small number of servers Why?

New trend: cloud databases.

E.g. Snowflake

Distributed/Parallel Query Processing

Parallel DBs since the 80s

Usually limited to small number of servers Why? Transactions!

New trend: cloud databases.

E.g. Snowflake

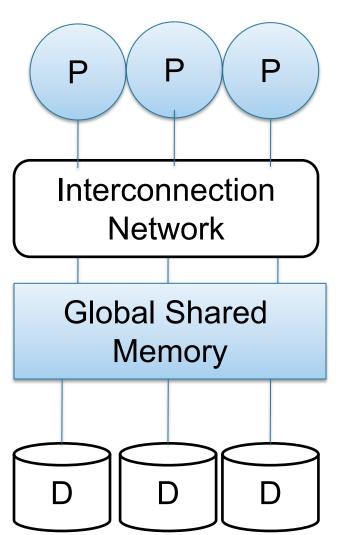
Architectures for Parallel Databases

Shared memory

Shared disk

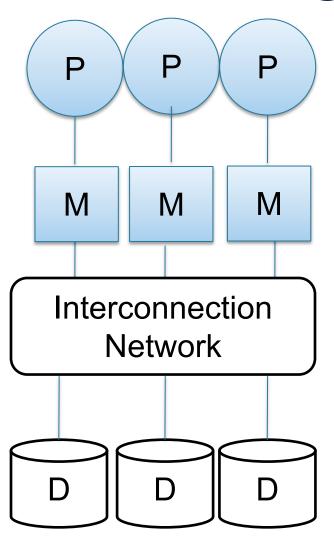
Shared nothing

Shared Memory



- SMP = symmetric multiprocessor
- Nodes share RAM and disk
- 10x ... 100x processors
- Example: SQL Server runs on a single machine and can leverage many threads to speed up a query
- Easy to use and program
- Expensive to scale

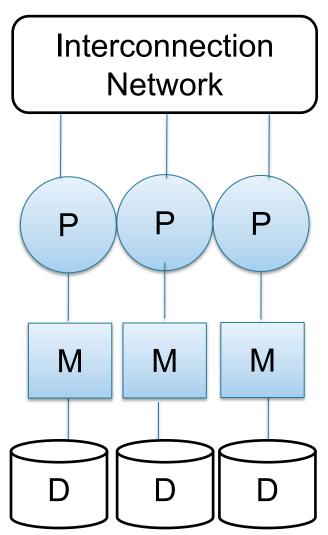
Shared Disk



- All nodes access same disks
- 10x processors
- Example: Oracle

- No more memory contention
- Harder to program
- Still hard to scale

Shared Nothing



- Cluster of commodity machines
- Called "clusters" or "blade servers"
- Each machine: own memory&disk
- Up to x1000-x10000 nodes
- Example: redshift, spark, snowflake

Because all machines today have many cores and many disks, shared-nothing systems typically run many "nodes" on a single physical machine.

- Easy to maintain and scale
- Most difficult to administer and tune.

Performance Metrics

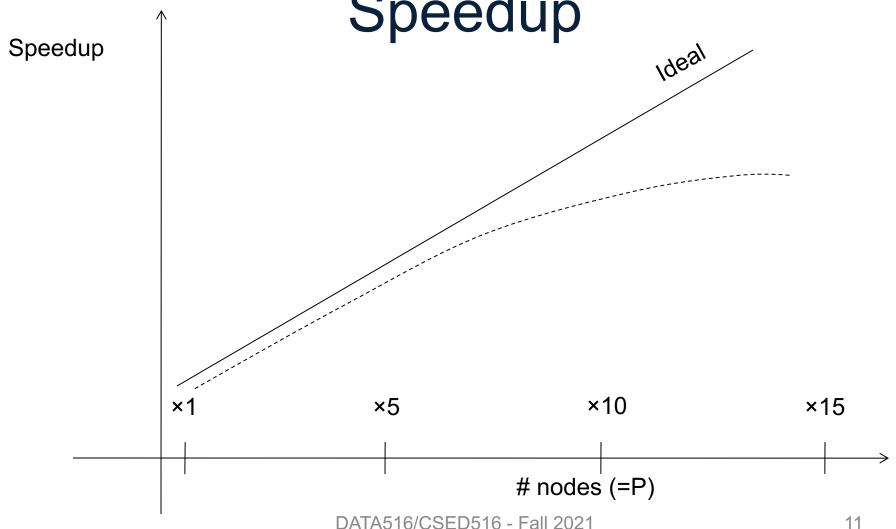
Nodes = processors = computers

- Speedup:
 - More nodes, same data → higher speed

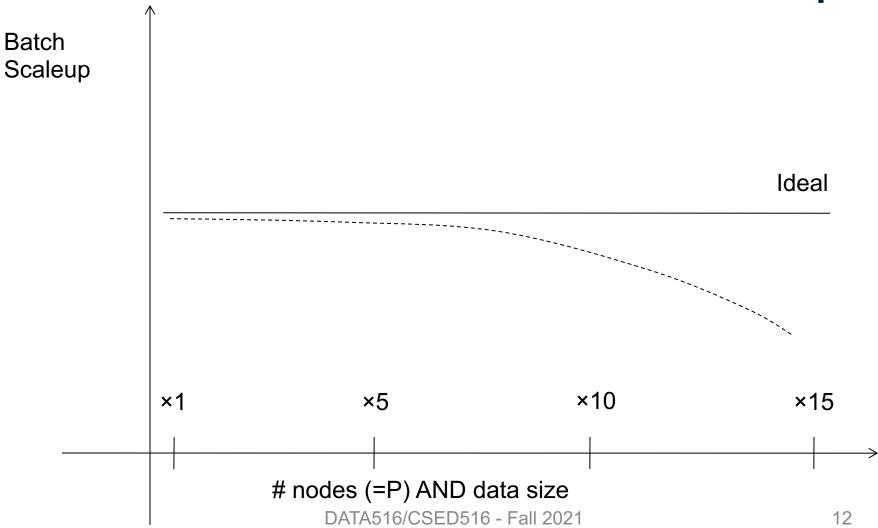
- Scaleup:
 - More nodes, more data → same speed

Warning: sometimes *Scaleup* is used to mean *Speedup*

Linear v.s. Non-linear Speedup



Linear v.s. Non-linear Scaleup

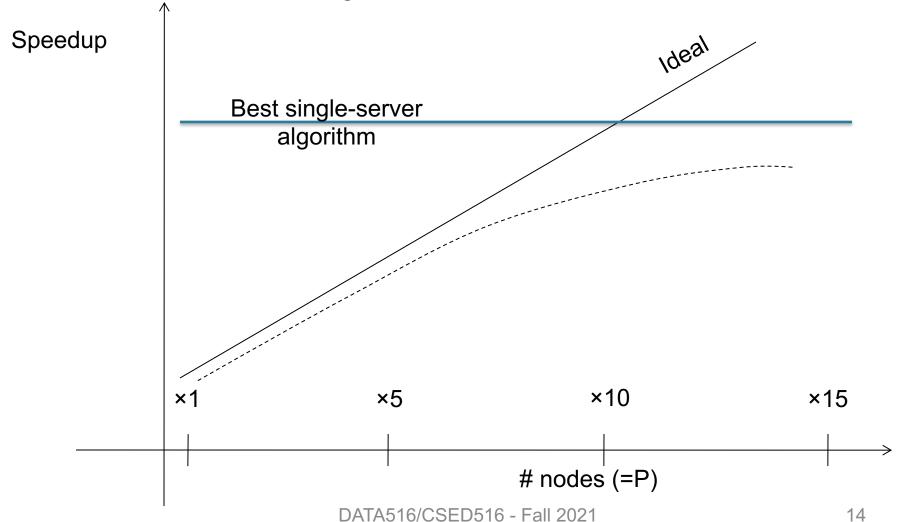


Why Sub-linear?

- Startup cost
 - Cost of starting an operation on many nodes
- Interference
 - Contention for resources between nodes

- Skew
 - Slowest node becomes the bottleneck

"Scalability but at what cost?"



Discussion

Parallel/distributed data processing:

- Scales up* to more data:
 - More servers can hold more data

- Speedup w/ number of nodes:
 - Harder to achieve
 - But can get there with very large p

More Discussion

New terminology:

Scale-up = speedup w/ shared memory

Scale-out = more data w/ more nodes

Acknowledges that speed comes from shared memory, capacity for large data comes from shared nothing

Outline

Basic notions

Distributed query processing algorithms

Skew (will continue next lecture)

Distributed Query Processing Algorithms

Table

sid name

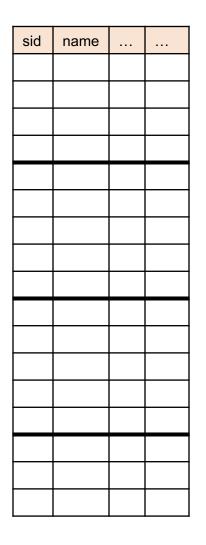
R

Table

sid name

Table

R









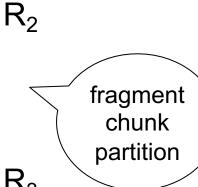


sid	name	

sid	name	

sid	name	

 R_1



113

- Block Partition, a.k.a. Round Robin:
 - Partition tuples arbitrarily s.t. size(R₁)≈ ... ≈ size(Rp)
- Hash partitioned on attribute A:
 - Tuple t goes to chunk i, where i = h(t.A) mod P + 1
- Range partitioned on attribute A:
 - Partition the range of A into $-\infty = v_0 < v_1 < ... < v_P = ∞$
 - Tuple t goes to chunk i, if $v_{i-1} < t.A < v_i$

Notations

p = number of servers (nodes) that hold the chunks

When a relation R is distributed to p servers, we draw the picture like this:

$$R_1$$
 R_2 R_P

Here R₁ is the fragment of R stored on server 1, etc

$$R = R_1 \cup R_2 \cup \cdots \cup R_P$$

Uniform Load and Skew

•
$$|R| = N$$
 tuples, then $|R_1| + |R_2| + ... + |R_p| = N$

We say the load is uniform when:
 |R₁| ≈ |R₂| ≈ ... ≈ |R_p| ≈ N/p

Skew means that some load is much larger:
 max_i |R_i| >> N/p

We design algorithms for uniform load, discuss skew later

Parallel Algorithm

Selection σ

Join ⋈

Group by \(\gamma\)

Data: $R(\underline{K}, A, B, C)$

Query: $\sigma_{A=v}(R)$, or $\sigma_{v1<A< v2}(R)$

- Block partitioned:
- Hash partitioned:

Range partitioned:

Data: $R(\underline{K}, A, B, C)$

Query: $\sigma_{A=v}(R)$, or $\sigma_{v1<A< v2}(R)$

- Block partitioned:
 - All servers need to scan
- Hash partitioned:

Range partitioned:

Data: $R(\underline{K}, A, B, C)$

Query: $\sigma_{A=v}(R)$, or $\sigma_{v1<A< v2}(R)$

- Block partitioned:
 - All servers need to scan
- Hash partitioned:
 - Point query: only one server needs to scan
 - Range query: all servers need to scan
- Range partitioned:

Data: $R(\underline{K}, A, B, C)$

Query: $\sigma_{A=v}(R)$, or $\sigma_{v1<A< v2}(R)$

- Block partitioned:
 - All servers need to scan
- Hash partitioned:
 - Point query: only one server needs to scan
 - Range query: all servers need to scan
- Range partitioned:
 - Only some servers need to scan

Parallel GroupBy

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

Discuss in class how to compute in each case:

- R is hash-partitioned on A
- R is block-partitioned or hash-partitioned on K

Parallel GroupBy

Data: $R(\underline{K}, A, B, C)$

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Discuss in class how to compute in each case:

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Parallel GroupBy

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

Discuss in class how to compute in each case:

- R is hash-partitioned on A
 - Each server i computes locally $\gamma_{A,sum(C)}(R_i)$
- R is block-partitioned or hash-partitioned on K
 - Need to reshuffle data on A first (next slide)
 - Then compute locally $\gamma_{A,sum(C)}(R_i)$

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

R is block-partitioned or hash-partitioned on K

R₁ R₂

. . .

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

R is block-partitioned or hash-partitioned on K

Reshuffle R on attribute A

 R_1

 R_2

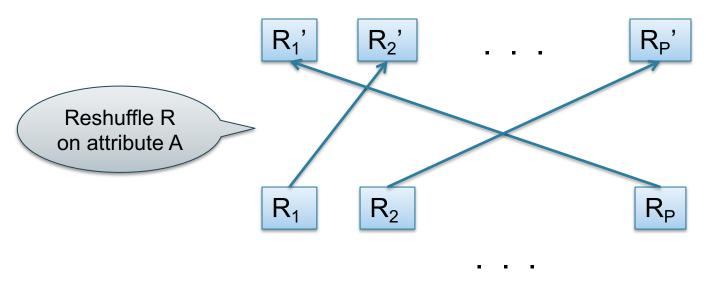
 R_{P}

. . .

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

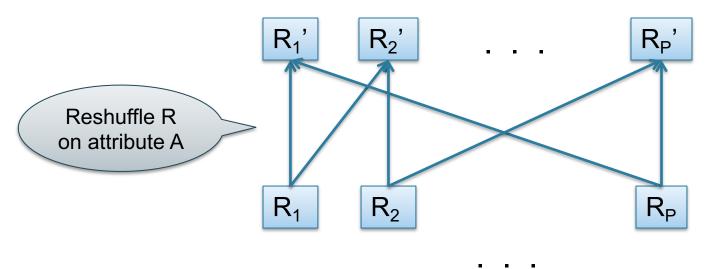
R is block-partitioned or hash-partitioned on K



Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

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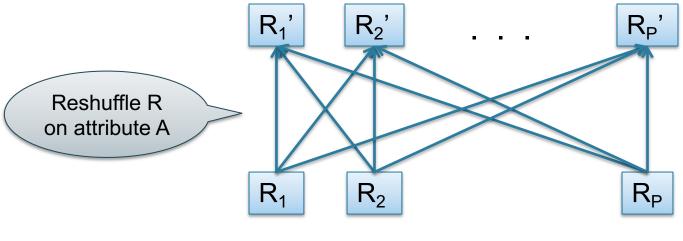


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Query: $\gamma_{A,sum(C)}(R)$

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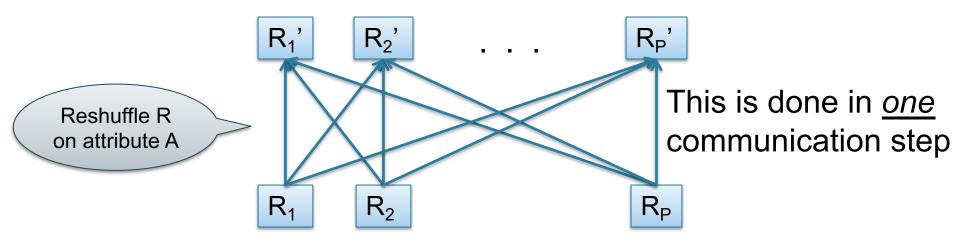


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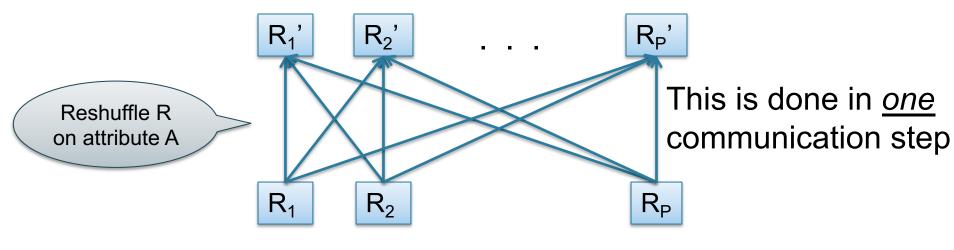


. . .

Data: $R(\underline{K}, A, B, C)$

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. . .

Reshuffling

Nodes send data over the network

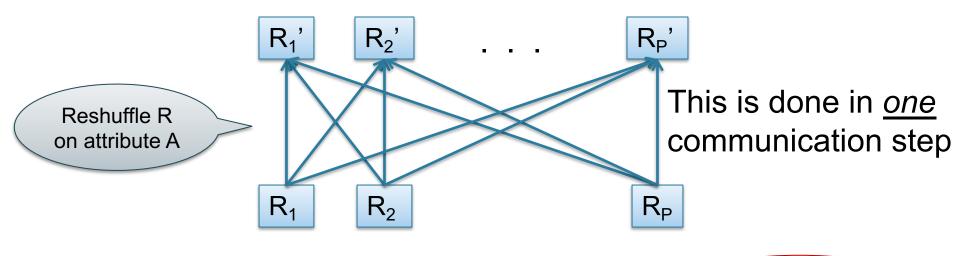
Many-many communications possible

- Throughput:
 - Better than disk
 - Worse than main memory

Data: $R(\underline{K}, A, B, C)$

Query: $\gamma_{A,sum(C)}(R)$

R is block-partitioned or hash-partitioned on K



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Can you think of an optimization?

city	 qant
Seattle	10
LA	20
Seattle	30
NY	40

city	 qant
LA	22
NY	33
LA	44
Austin	55

city	 qant
Seattle	66
LA	77
NY	88
LA	99

SELECT city, sum(quant)
FROM R
GROUP BY city

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Seattle	10
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Q: What is sum for Seattle?

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Q: What is sum for Seattle?
A: 106

SELECT city, sum(quant)
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Sum here = 40

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Sum here = 66

$$\gamma_{city,sum(q)}(R_1 \cup R_2 \cup R_3) =$$

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Sum here = 66

$$\gamma_{city,sum(q)}(R_1 \cup R_2 \cup R_3) =$$

$$= \gamma_{city,sum(q)} \left(\gamma_{city,sum(q)}(R_1) \cup \gamma_{city,sum(q)}(R_2) \cup \gamma_{city,sum(q)}(R_3) \right)$$

Data: R(<u>K</u>, A, B, C)

Query: $\gamma_{A,sum(C)}(R)$

Data: R(<u>K</u>, A, B, C)

Query: $\gamma_{A,sum(C)}(R)$

Step 0: [Optimization] each server i computes local group-by: $T_i = \gamma_{A,sum(C)}(R_i)$

Data: $R(\underline{K}, A, B, C)$ Query: $\gamma_{A.sum(C)}(R)$

Step 0: [Optimization] each server i computes local group-by: $T_i = \gamma_{A,sum(C)}(R_i)$

Step 1: partitions tuples in T_i using hash function h(A): $T_{i,1}, T_{i,2}, ..., T_{i,p}$ then send fragment $T_{i,j}$ to server j

Data: R(<u>K</u>, A, B, C)

Query: $\gamma_{A,sum(C)}(R)$

Step 0: [Optimization] each server i computes local group-by: $T_i = \gamma_{A,sum(C)}(R_i)$

Step 1: partitions tuples in T_i using hash function h(A): $T_{i,1}, T_{i,2}, ..., T_{i,p}$ then send fragment $T_{i,j}$ to server j

Step 2: receive fragments, union them, then group-by $R_j' = T_{1,j} \cup ... \cup T_{p,j}$ Answer_j = $\gamma_{A, sum(C)}(R_j')$

Pushing Aggregates Past Union

Which other rules can we push past union?

- Sum?
- Count?
- Avg?
- Max?
- Median?

Pushing Aggregates Past Union

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Count?

•	Avg	?

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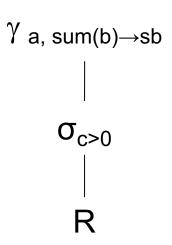
Distributive	Algebraic	Holistic
sum($a_1+a_2++a_9$)= sum(sum($a_1+a_2+a_3$)+ sum($a_4+a_5+a_6$)+ sum($a_7+a_8+a_9$))	avg(B) = sum(B)/count(B)	median(B)

Example Query with Group By

SELECT a, sum(b) as sb FROM R WHERE c > 0 GROUP BY a

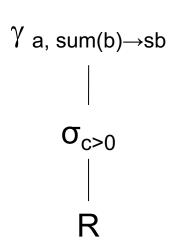
Example Query with Group By

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Example Query with Group By

SELECT a, sum(b) as sb FROM R WHERE c > 0 GROUP BY a



Machine 1

1/3 of R

Machine 2

1/3 of R

Machine 3

1/3 of R

SELECT a, sum(b) as sb FROM R WHERE c > 0 GROUP BY a

Machine 1

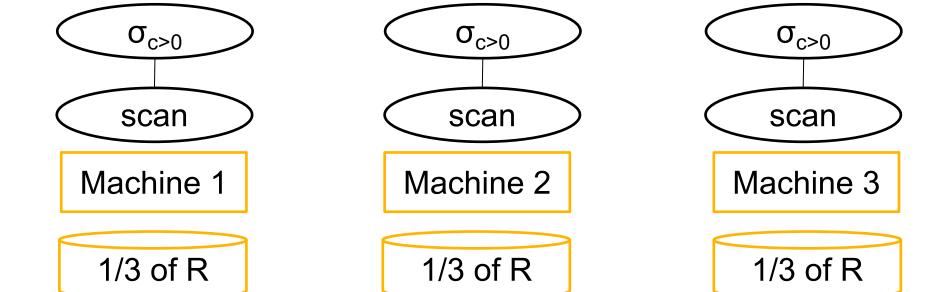
Machine 2

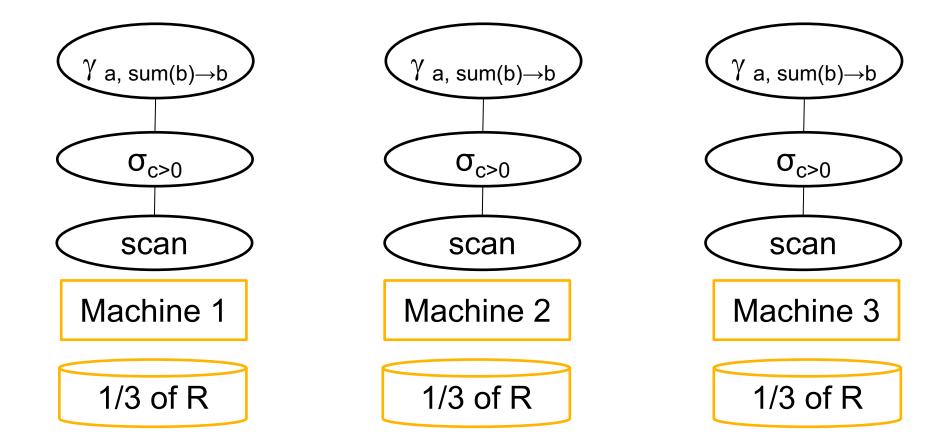
Machine 3

1/3 of R

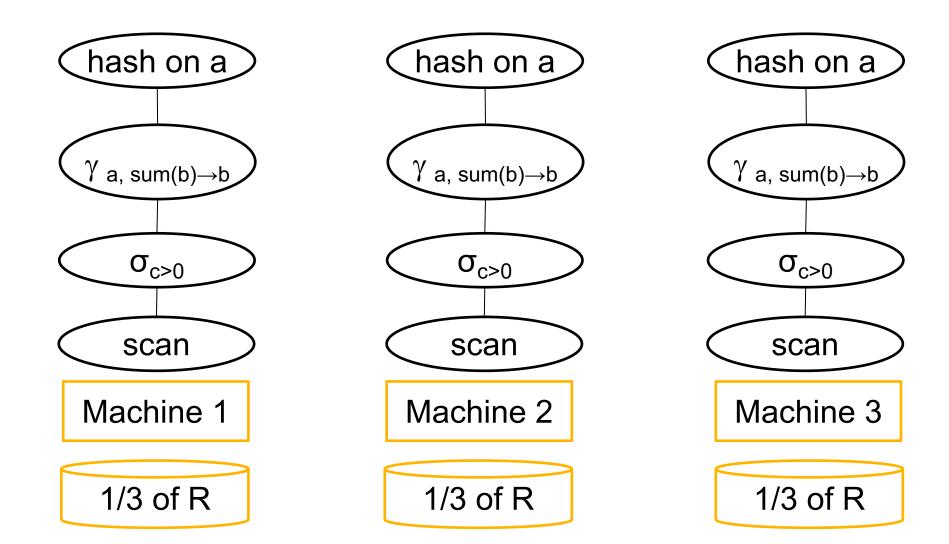
1/3 of R

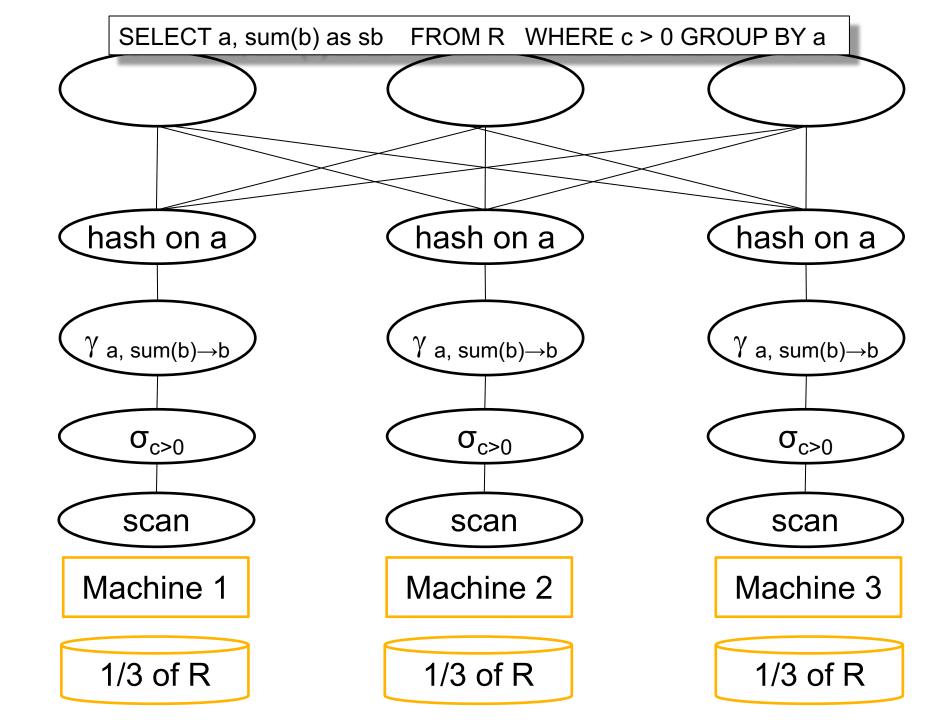
1/3 of R

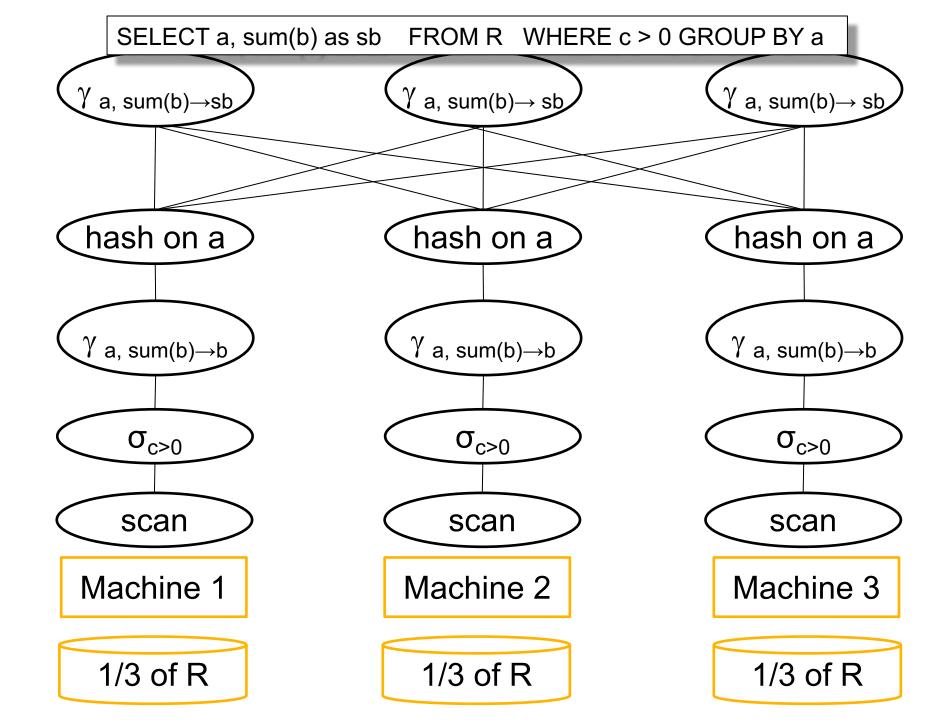




SELECT a, sum(b) as sb FROM R WHERE c > 0 GROUP BY a







Speedup and Scaleup

Consider the query $\gamma_{A,sum(C)}(R)$ Assume the local runtime for group-by is linear O(|R|)

If we double number of nodes P, what is the runtime?

If we double both P and size of R, what is the runtime?

Speedup and Scaleup

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Half (chunk sizes become ½)

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Same (chunk sizes remain the same)

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Same (chunk sizes remain the same)

Parallel/Distributed Join

Three "algorithms":

Hash-partitioned

Broadcast

Combined: "skew-join" or other names

Distributed Hash-Join

Data: R(A, C), S(B, D)

Query: $R \bowtie_{A=B} S$

 R_1, S_1

 R_2, S_2

R_P, S_P

Initially, R and S are block partitioned.
Notice: they may be stored in DFS (recall MapReduce)
Some servers hold R-chunks, some hold S-chunks, some hold both

Data: R(A, C), S(B, D)

Query: $R \bowtie_{A=B} S$

Reshuffle R on R.A and S on S.B

 R_1, S_1

 R_2, S_2

R_P, S_P

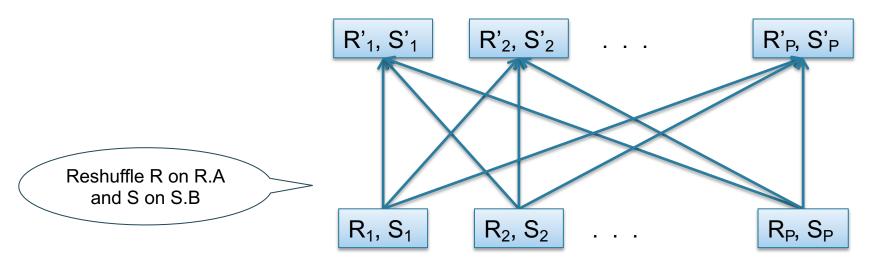
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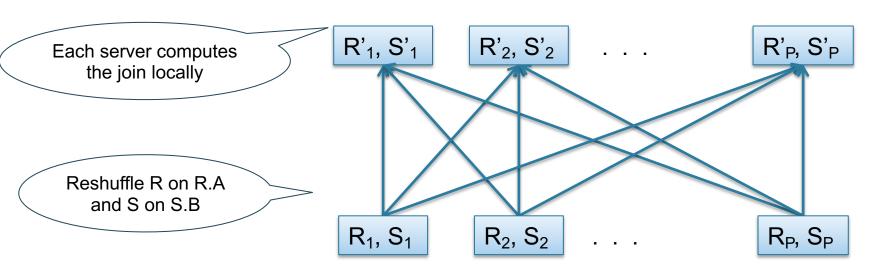
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Initially, R and S are block partitioned.

Notice: they may be stored in DFS (recall MapReduce)

Some servers hold R-chunks, some hold S-chunks, some hold both

Step 1

- Every server holding any chunk of R partitions its chunk using a hash function h(t.A)
- Every server holding any chunk of S partitions its chunk using a hash function h(t.B)

• Step 2:

 Each server computes the join of its local fragment of R with its local fragment of S

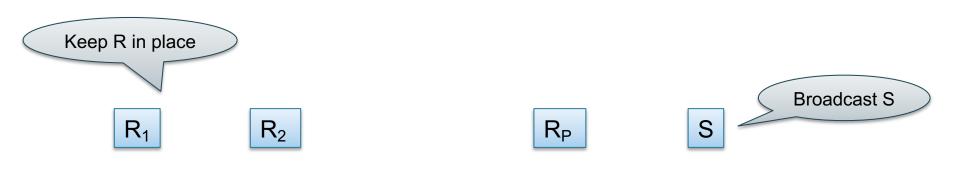
Broadcast Join A.k.a. "Small Join"

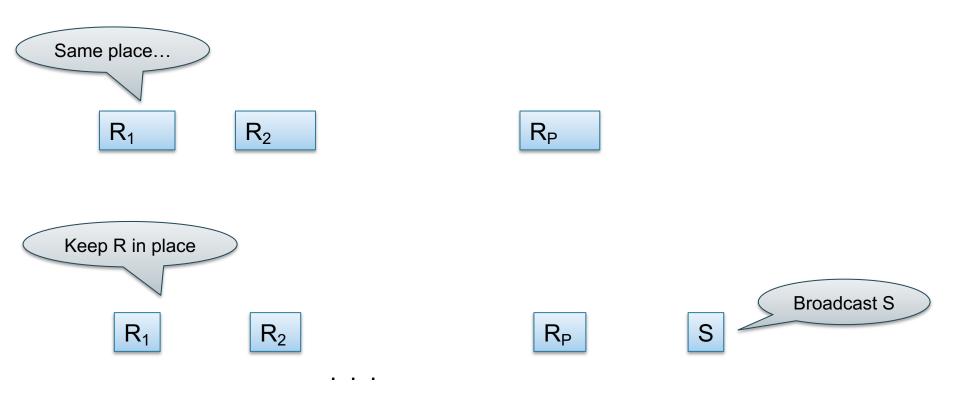
- When joining R and S
- If |R| >> |S|
 - Leave R where it is
 - Replicate entire S relation across R-nodes
- Called a small join or a broadcast join

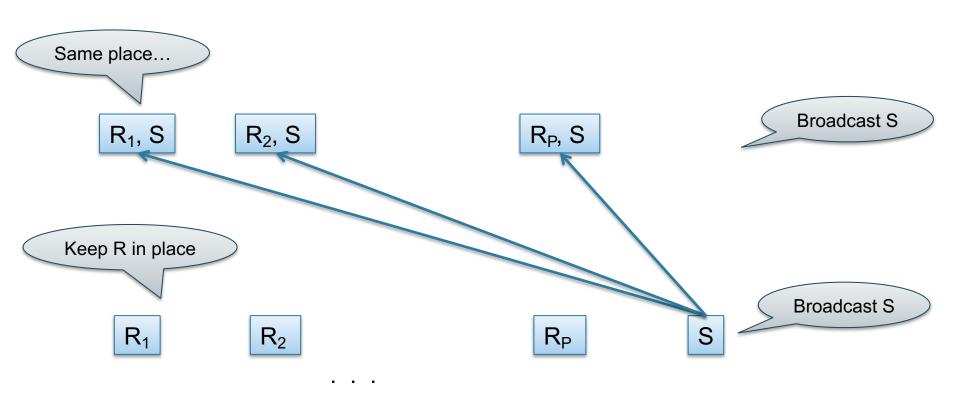
Broadcast Join

 R_1 R_2 R_P S

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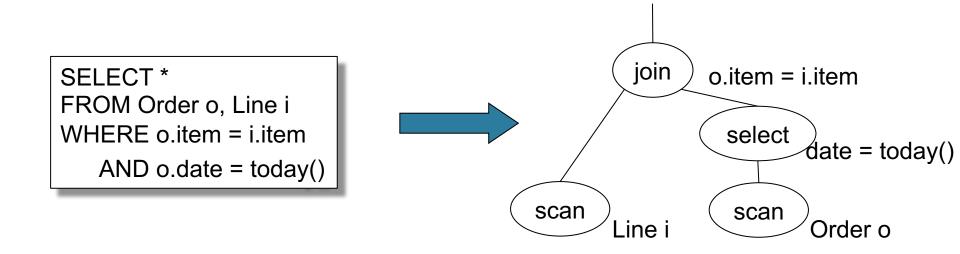




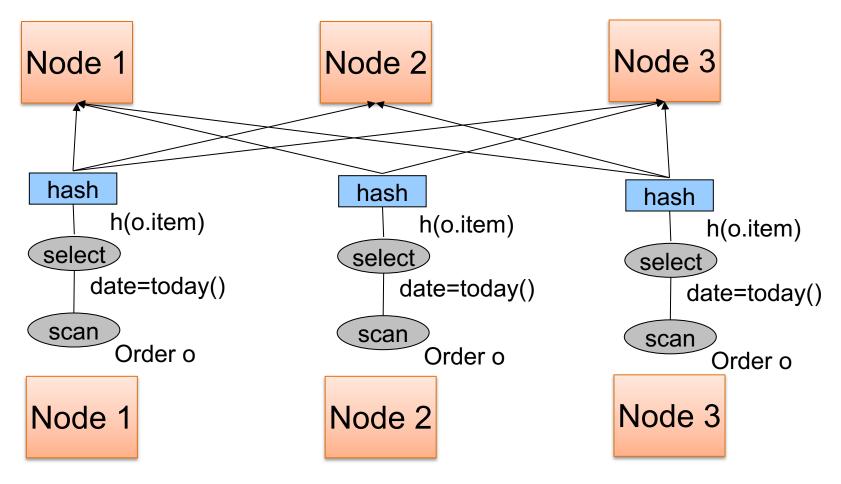


Example Query Execution

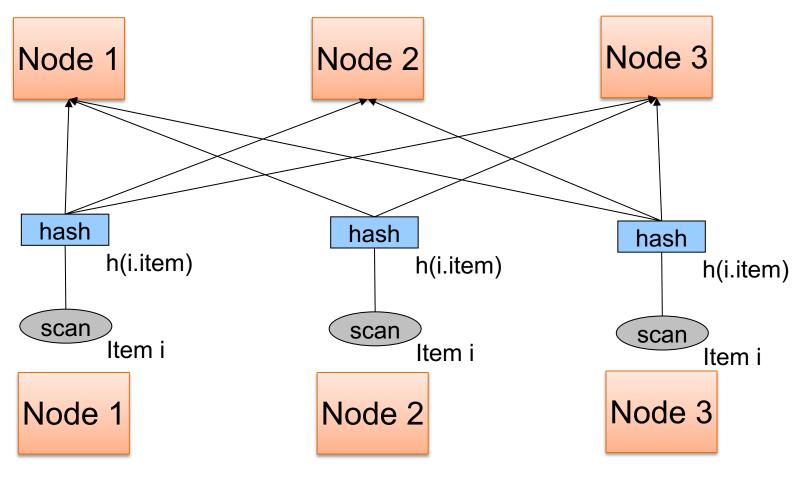
Find all orders from today, along with the items ordered



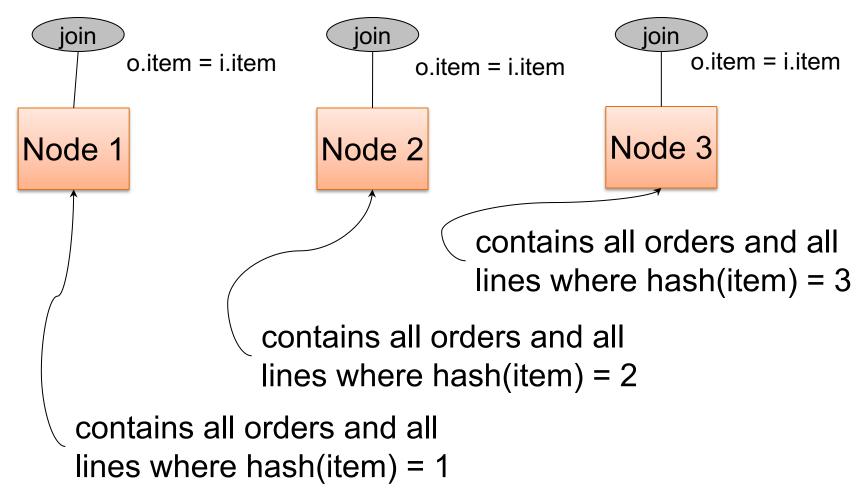








Query Execution



Example 2

SELECT *

FROM R, S, T

WHERE R.b = S.c AND S.d = T.e AND (R.a - T.f) > 100

Machine 1

Machine 2

Machine 3

1/3 of R, S, T

1/3 of R, S, T

1/3 of R,⁸\$, T

... WHERE R.b = S.c AND S.d = T.e AND (R.a - T.f) > 100

Machine 1

1/3 of R, S, T

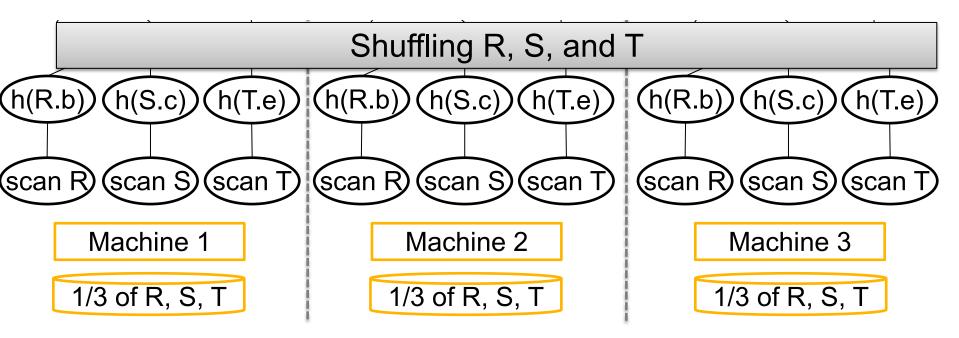
Machine 2

1/3 of R, S, T

Machine 3

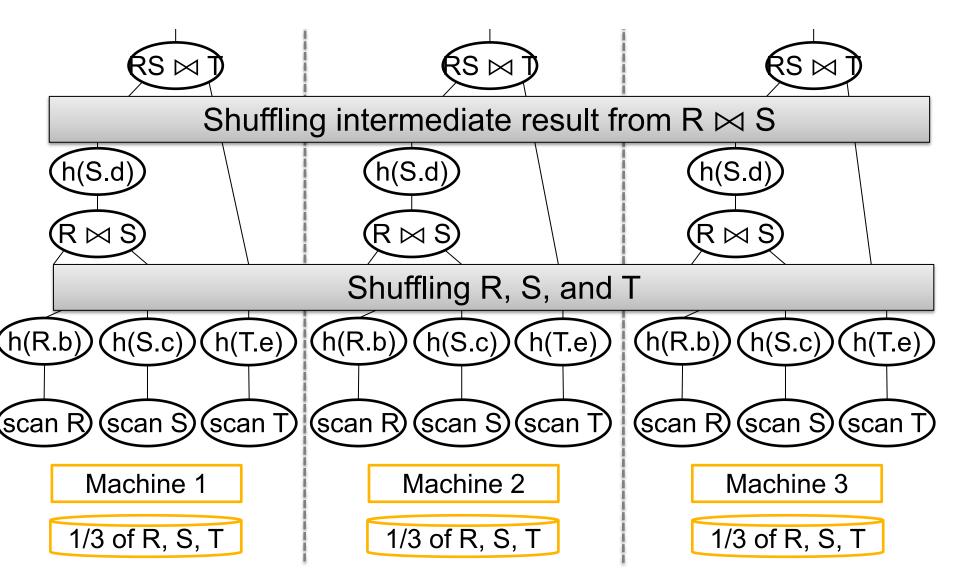
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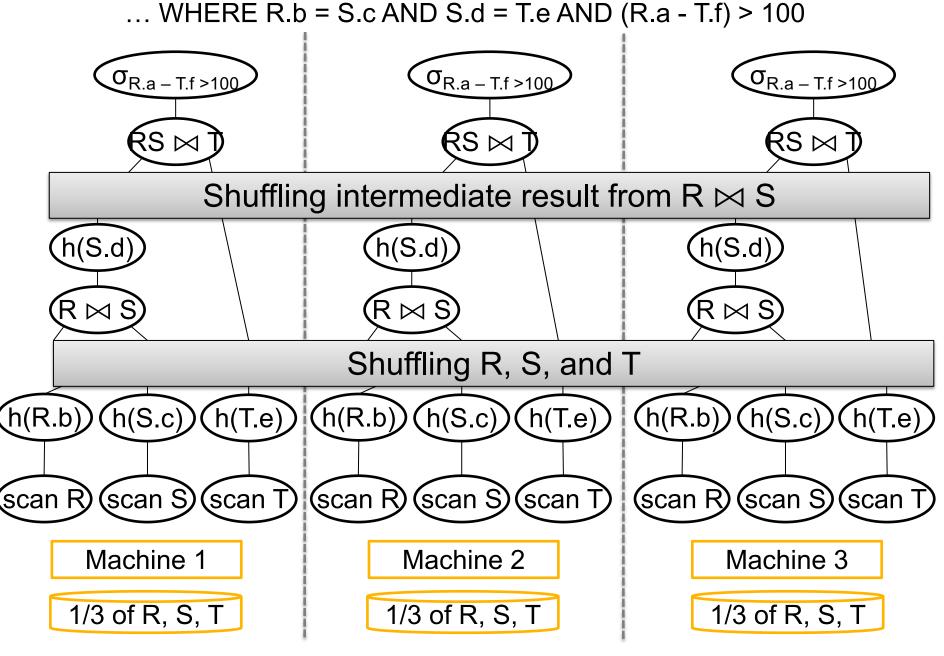


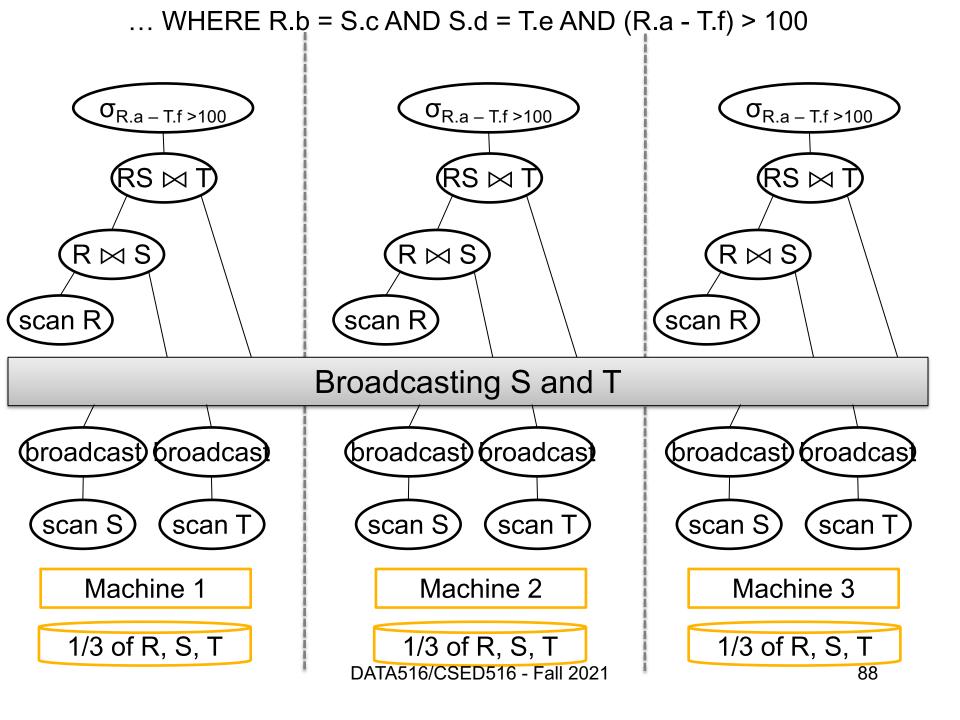
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... WHERE R.b = S.c AND S.d = T.e AND (R.a - T.f) > 100



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Discussion

- Hash-join:
 - Both relations are partitioned (good)
 - May have skew (bad)

Discussion

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- Broadcast join
 - One relation must be broadcast (bad)
 - No worry about skew (good)

Discussion

- Hash-join:
 - Both relations are partitioned (good)
 - May have skew (bad)
- Broadcast join
 - One relation must be broadcast (bad)
 - No worry about skew (good)
- Skew join (has other names):
 - Combine both: in class

Outline

Basic notions

Distributed query processing algorithms

Skew (will continue next lecture)

Skew

Skew

 Skew means that one server runs much longer than the other servers

- Reasons:
 - Computation skew
 - Data skew

Computation Skew

- All workers receive the same amount of input data, but some need to run much longer than others
- E.g. perform some image processing whose runtimes depends on the image
- Solution: use virtual servers

Virtual Servers

Main idea:

- If we send the data uniformly to the P servers, and one of them is stuck with the complicated image, then we have skew
- Solution: pretend we have many "virtual" servers. (Next slide.)

Virtual Servers

Large number P_v of "virtual servers"

- Design algorithm for P_v virtual servers
- Scale down to P << P_v physical servers, by simulating them round-robin

E.g. MapReduce: P=workers, P_v=map tasks

Data Skew

- We fail to distribute the data uniformly to the servers
- Question: why can this happen?

Data Skew

- We fail to distribute the data uniformly to the servers
- Question: why can this happen?
- Answer:
 - Range partition may have many more tuples in one bucket than another
 - Hash partition may suffer from heavy hitters

Next Lecture

Analyze skew: notice hw3 question

New topic: scalable graph processing