We progress in rounds and 
$$e$$
 time  $s$ , an admissing  
picks  $Ls \in \mathbb{R}^{k}$ , learner pick  $I_{s} \in [k]$ , learner  
observes  $l_{s,I_{s}}$ .  
 $R_{t} = \sum_{s=1}^{t} l_{s,I_{s}} - \min \sum_{i \in [k]}^{t} L_{s,i}$   
Two types of adversaries  
· adoptive adversary: loss  $e$  the t is dependent on  
· the physers actions up to time t  
· oblinious adversory: Fixes all of it's losses ahead  
of time.  
Gool  $ER_{s} \rightarrow expectation being taken over the
randomness in learner and adversary.
Pseudo-Regret:
 $PR_{t} = E \begin{bmatrix} \sum_{s=1}^{t} l_{s,I_{s}} - \min \\ i \in [k] \end{bmatrix} E \begin{bmatrix} \sum_{s=1}^{t} l_{s,i} \end{bmatrix}$   
 $= \max \\ i \in [k] \end{bmatrix} E \begin{bmatrix} \sum_{s=1}^{t} l_{s,I_{s}} - l_{s,i} \end{bmatrix}$   
In general:  $PR_{t} \leq ER_{t}$   
Stochastic Setting  $\rightarrow PR_{t}$   
For oblivious adversaries:  $\min \\ i \in [k] \end{bmatrix} E \begin{bmatrix} \sum_{s=1}^{t} l_{s,i} \end{bmatrix} = \min \\ i \in [k] \frac{1}{s_{s+1}} \end{bmatrix}$$ 

-> 
$$PR_t = ER_t$$
  
Remark Any deterministic learner will incur linear  
regret against some adversary.  
-> at time t the learner has to choose a  
distribution  $g_t \in \Delta_{1k} = \mathcal{I}(x_{1,1-1}, x_k) : \sum_{i=1}^{k} x_i \ge 0$ ?  
and then  $ploy \quad I_t = \mathcal{I}_t$ .  
 $e \quad time \quad s \quad you \quad see \quad loss \quad l_{s,1s}$   
 $\forall j \in [k] \quad \widehat{I}_{s,j} = \underbrace{\Pi(I_t = j) l_{s,1s}}_{q_{s,j}}, \underbrace{2g_{s,j} \notin 0}_{q_{s,j}}$ 

$$\mathbb{E}\left[\hat{\mathcal{L}}_{s,j}\right] = \mathbb{E}\left[\mathbb{E}\left[\hat{\mathcal{L}}_{s,j} \mid I_{s}, \mathcal{L}_{s}, I_{s}, \dots, I_{s+1}, \mathcal{L}_{s+1}\right]\right]$$

$$= \mathbb{E}\left[q_{s,j} \cdot \frac{\mathcal{L}_{s,j}}{q_{j}} + (1 - q_{s,j}) \cdot 0\right]$$

$$= \mathbb{E}\left[\mathcal{L}_{s,j}\right] \rightarrow \mathbb{IPS} \text{ estimator}$$

$$\Rightarrow \text{Estimator for the reward of total reward}$$

$$\text{for each arms} \quad \hat{\mathcal{S}}_{t,j} = \sum_{s=1}^{t} \hat{\mathcal{L}}_{s,j}$$

Algorithm 7 EXP3
 Imput: 
$$\gamma \in [0, 1], \eta > 0, k$$

 1: Initialize  $\lambda = (\frac{1}{k}, \dots, \frac{1}{k})$ .

2: for  $s = 1, \dots, t$  do

- 3:
- 4:
- Let  $q_s = (1 \gamma)p_s + \gamma\lambda$ Draw  $I_s \sim q_s$  and observe loss  $\ell_{s,I_s}$ Calculate the estimated total rewards for each  $i \in [k]$ 5:

$$\hat{S}_{si} = \sum_{r=1}^{s} \frac{\mathbf{1}(I_r = i)\ell_{r,I_r}}{q_{ri}}$$

Calculate the sampling distribution 6:

$$p_{s+1,i} = \frac{\exp(-\eta \hat{S}_{si})}{\sum_{j=1}^{k} \exp(-\eta \hat{S}_{sj})} \text{ for } i \in [k].$$

7: **end for** 

**Theorem 6.** Assume  $\gamma \in [0, 1]$ ,  $\eta > 0$  and for all  $i \in [k]$  and  $s \le t$ , we have  $|\ell_{si}| \le 1$ . Then for all  $i \in [k]$ 

$$\mathbb{E}\left[\sum_{s=1}^{t} \ell_{\boldsymbol{\ell}, I_{\boldsymbol{\ell}}} - \ell_{\boldsymbol{\ell}, i}\right] \leq \frac{\log(k)}{\eta} + 2\gamma \mathbf{t} + \mathfrak{P} \mathbb{E}\left[\sum_{s=1}^{t} \sum_{j=1}^{k} q_{s, j} \psi(-\eta \hat{\ell}_{s, j})\right]$$
where  $\psi(x) = e^{x} - 1 - x \leq \mathbf{x}^{2}, \mathbf{x} \in ($ 

$$q_{j, j} \cdot \eta^{2} \ell_{s, j}^{2}$$

Example 
$$\mathcal{Y} = \eta \mathcal{K}, \eta = \sqrt{\frac{3 \mathcal{K} \log |\mathcal{K}|}{t}} | \mathcal{Q}_{s} = (1 - \mathcal{Y}) \mathcal{P}_{s} + \mathcal{J} \mathcal{A}$$
  
 $| \eta \hat{\mathcal{I}}_{s,j} | \leq | 2 \frac{\ell_{s,j}}{2_{s,j}} | \leq \eta \frac{\mathcal{K}}{s} \leq 1$   
We also have  $\mathscr{O}(\mathbf{x}) \leq \mathbf{x}^{2}, \mathbf{x} \leq 1$   
 $| \log \mathcal{K} + 2\eta \mathcal{K} t + \frac{1}{\eta} |\mathbf{F} \left[ \sum_{s=r}^{t} \sum_{s=r}^{K} \mathcal{Q}_{s,j} \eta^{2} \mathcal{L}_{s,j}^{2} \right]$ 

$$\frac{P_{roof}}{S_{t}} = \sum_{s=1}^{t} \sum_{j=1}^{k} 2_{sj} \hat{I}_{sj}, \quad W_{t} = \sum_{j=1}^{k} \exp(-\eta \hat{S}_{tj})$$

$$\rightarrow \hat{S}_{t} = \sum_{s=1}^{t} 2_{s, I_{s}}$$

$$() = \exp(-\eta \hat{S}_{ti}) + \sum_{s=1}^{k} \exp(-\eta \hat{S}_{ti})$$

$$\frac{\partial U_{s}}{\partial s_{s+1}} = \frac{\partial U_{s}}{\partial s_{s+1}} + \frac{\partial$$

$$= \sum_{j=1}^{n} \sum_$$

$$\frac{|E| - \langle Y \rangle_{t,i} + \langle Y \rangle_{s=i}}{s_{s=i}} \frac{1}{s_{s=i}} \frac{1}{s_{s=i}$$