

## Halving Algorithm

Input:  $\mathcal{H}$

Init:  $V = \mathcal{H}, Z = \emptyset$

while  $|V| > 1$

$b(x) = \text{Majority Vote} (h(x) : h \in V) \quad \forall x$

let  $S$  be a minimal specifying set for  $b \in \{0,1\}^m$

and request  $y = h^*(x) \quad \forall x \in S$ .  $Z = Z \cup \{(x_i, y_i)\}_{i \in S}$

Update  $V = \{h \in V : h(x) = y \quad \forall (x, y) \in Z\}$

Note:  $|S| < \text{EXT-TD}(\mathcal{H})$  at all rounds

Case 1:  $\exists h \in \mathcal{H} : y = h(x) \quad \forall x \in S$ , but by defn there is at most one of these, and it is equal to  $h^*$ . Thus, algorithm terminates w/  $V = \{h^*\}$

Case 2:  $\exists x \in S : y \neq b(x)$ . But by defn of Majority vote, at least half of hypotheses in  $V$  agreed that  $h(x)$  was  $b(x)$ . Thus, when proven wrong,  $|V| \rightarrow |V|/2$

$\Rightarrow$  At each round, either  $|V|$  is halved or terminates at most  $\text{EXT-TD}(\mathcal{H})$  queries per round

$\Rightarrow$  # labels  $\leq \lceil \log_2(\mathcal{H}) \rceil \cdot \text{EXT-TD}(\mathcal{H})$

$\square$

Another simpler algorithm...

### Generalized Binary Search (GBS)

Input:  $\mathcal{H}$ ,  $p \in \Delta_{\mathcal{H}}$  :  $\sum_{h \in \mathcal{H}} p(h) = 1$

Init:  $V = \mathcal{X}$  ( $h: \mathcal{X} \rightarrow \{0,1\}$ )

while  $|V| > 1$

$$x' \leftarrow \operatorname{argmin}_{x \in \mathcal{X}} \left| \frac{1}{2} - \sum_{h \in V} p(h) h(x) \right|$$

Request  $y' = h^*(x')$  update  $V = \{h \in \mathcal{H} : h(x') = y'\}$

Theorem) Fix any  $\mathcal{H}$  and  $p \in \Delta_{\mathcal{H}}$ . Let  $\text{OPT} =$

$\min_{\mathcal{A}} \mathbb{E}_{h^* \sim p} [\mathcal{S}(\mathcal{H}, \mathcal{H}, h^*, \mathcal{A})]$ . Then GBS

satisfies  $\mathbb{E}_{h^* \sim p} [\mathcal{S}(\mathcal{H}, \mathcal{H}, h^*, \mathcal{A}_{\text{GBS}})] \leq \text{OPT} \cdot 4 \log\left(\frac{1}{\min_h p(h)}\right)$

If  $p(h)$  is uniform  $\frac{1}{|\mathcal{H}|}$  then this is a  $\log(|\mathcal{H}|)$  approx ratio.

Separable, streaming setting

$X$  can be uncountable but I have access to an oracle  $\mathcal{D}_X$

s.t. I can request  $x \sim \mathcal{D}_X$ . Assume  $\exists h^* \in \mathcal{H}$

s.t.  $Y = h^*(x)$  for any  $x \sim \mathcal{D}_X$  and requested label  $Y$ .

$$\text{Risk}(h) = \mathbb{E}_{(x,Y) \sim \mathcal{D}} [\mathbb{1}\{h(x) \neq Y\}] \quad (Y = h^*(x), x \sim \mathcal{D}_X)$$

How many unlabeled examples and queried labels must I make to identify an  $\hat{h}$ :  $R(\hat{h}) \leq \epsilon$ ? (Note  $R(h^*) = 0$ )

Passive learning Review (Realizable / Separable  $\equiv h^*(x) = Y$ )

Suppose  $(x_i, y_i) \stackrel{\text{iid}}{\sim} \mathcal{D}$  for  $i = 1, 2, \dots, n$ .

and compute  $\hat{h}_n = \underset{h \in \mathcal{H}}{\text{argmin}} \underbrace{\frac{1}{n} \sum_{i=1}^n \mathbb{1}\{h(x_i) \neq y_i\}}_{\hat{R}_n(h)}$

What is  $R(\hat{h}_n)$ ? Rather, how large must

$n$  be to have  $R(\hat{h}_n) \leq \epsilon$  w.p.  $\geq 1 - \delta$ ?

Thm Assume  $\mathcal{H}$  is finite.  $R(\hat{h}_n) \leq \epsilon$  w.p.  $\geq 1 - \delta$  whenever  $n \geq \frac{1}{\epsilon} \log(|\mathcal{H}| / \delta)$ .

Proof  $\hat{R}_n(h^*) = \hat{R}_n(\hat{h}_n) = 0$ .

$$\mathbb{P}(R(\hat{h}_n) > \epsilon) \leq \mathbb{P}\left(\bigcup_{h \in \mathcal{H}} \{R(h) > \epsilon, \hat{R}_n(h) = 0\}\right)$$

$$\begin{aligned}
&\leq \sum_{h \in \mathcal{H}} P(R(h) > \varepsilon, \hat{R}_n(h) = 0) \\
&\leq \sum_{h \in \mathcal{H}} (1 - \varepsilon)^n \\
&\leq |\mathcal{H}| (1 - \varepsilon)^n \quad (\text{union bound}) \\
&\leq |\mathcal{H}| \exp(-n\varepsilon) \quad 1 - x \leq e^{-x} \\
&\leq \delta
\end{aligned}$$

when  $n \geq \frac{1}{\varepsilon} \log(|\mathcal{H}|/\delta)$ .  $\square$

(Empirical)

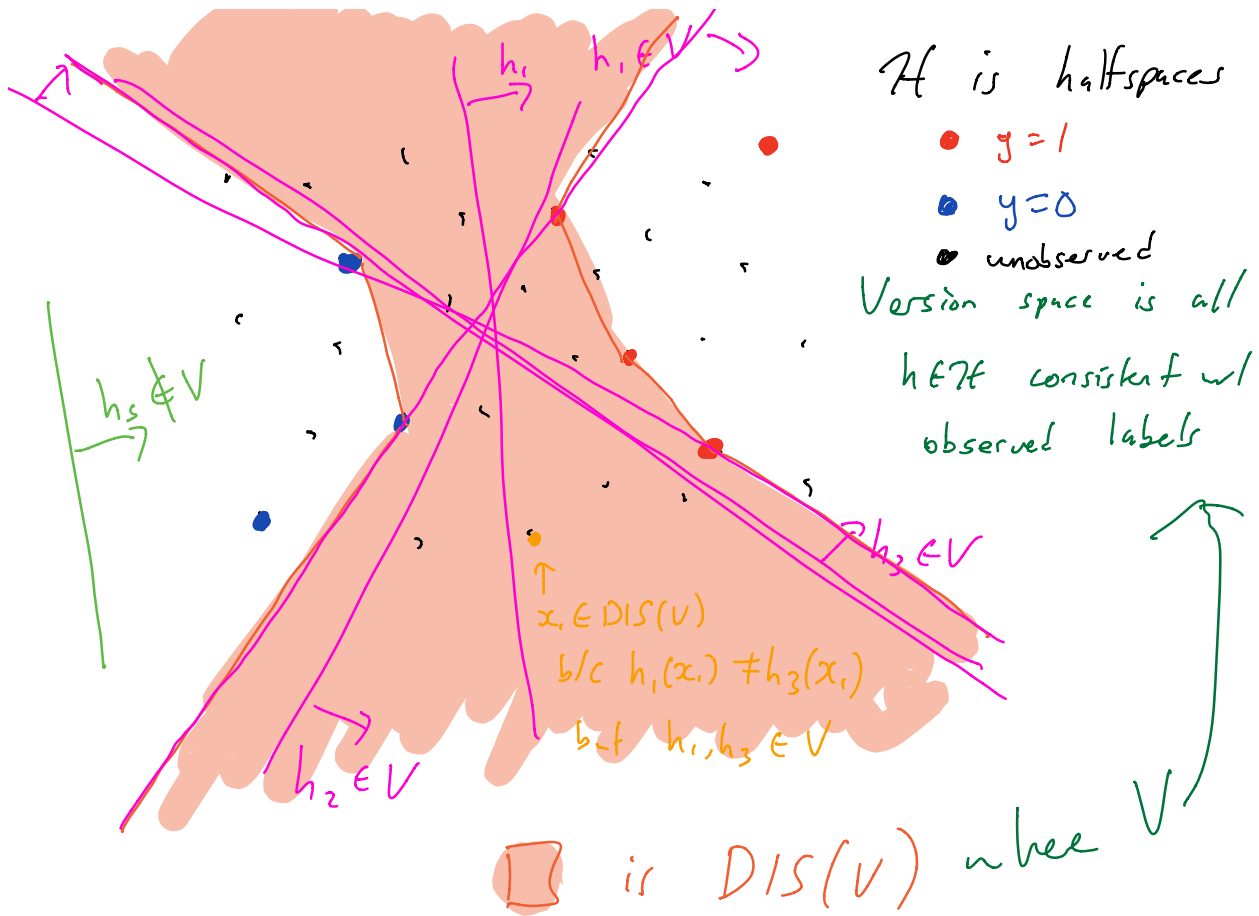
Aside: Bernstein says

$$|\hat{R}_n(h) - R(h)| \leq \sqrt{\frac{2\hat{R}_n(h) \log(|\mathcal{H}|/\delta)}{n}} + \frac{\log(|\mathcal{H}|/\delta)}{3n}$$

Active Learning / Disagreement-based learning.

Def] For any  $V \subset \mathcal{H}$  define region of disagreement of  $V$  as

$$DIS(V) = \{x : \exists h, h' \in V : h(x) \neq h'(x)\}$$



CAL (Cohn, Atlas, Ladner 1993)

Init  $Z_0 = \emptyset, V_0 = \mathcal{H}$

for  $t=1, 2, \dots$

Nature reveals  $x_t \cup D_x$

if  $x_t \in DIS(V_{t-1})$  then

query  $y_t = h^*(x_t), Z_t = Z_{t-1} \cup \{(x_t, y_t)\}$

else

$Z_t = Z_{t-1}$

$$V_t = \{h \in \mathcal{H} \mid h(x_s) = y_s \ \forall (x_s, y_s) \in Z_t\}$$

Hanneke in mid '00s analyzed it.

Dasgupta, Hsu, Monteleoni in '09 (?)

presented computational<sup>eff.</sup> version

Efficient CAL

Init  $Z_0 = \emptyset$

for  $t=1, 2, \dots$

Nature reveals  $x_t \in \mathcal{D}_x$

if for  $\hat{y} \in \{0, 1\}$   $\exists h_{\hat{y}} \in \mathcal{H}$  with

$$h_{\hat{y}}(x_s) = y_s \ \forall (x_s, y_s) \in Z_{t-1} \cup (x_t, \hat{y})$$

then request  $y_t$ ,  $Z_t = Z_{t-1} \cup (x_t, y_t)$

else

$$Z_t = Z_{t-1}.$$

If  $\mathcal{H}$  is halfspaces

linear program.