

Variational Autoencoders

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Discussion Board: Available on Ed

Zoom Link: Available on Canvas

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Course Webpage: <https://courses.cs.washington.edu/courses/cse599i/20au/>

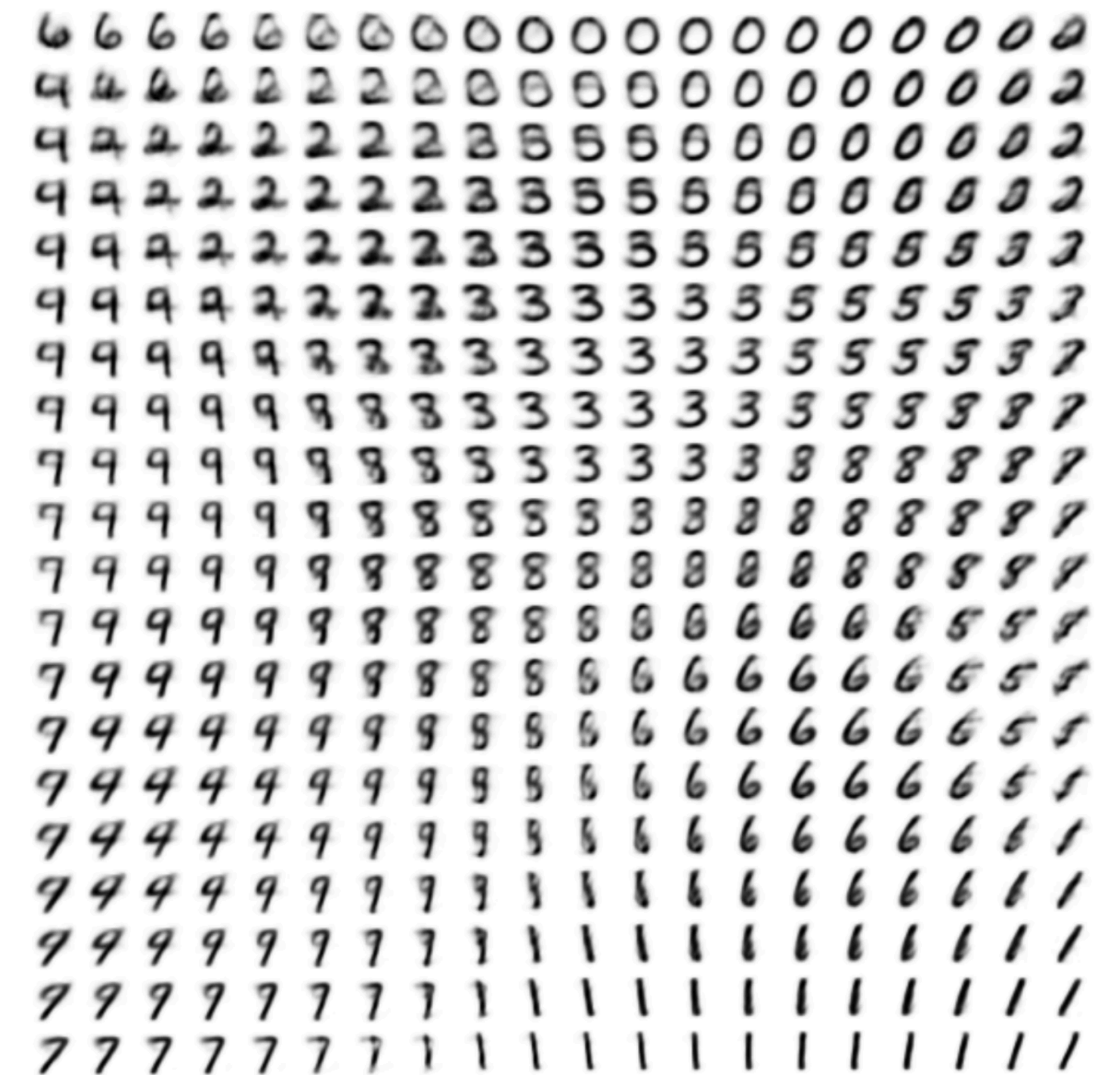
Latent Variable Models

- Given finite samples $x_1, \dots, x_n \sim p$, and unlimited samples $z \sim r$.
- Generative latent variable model:
 1. $z \sim r$,
 2. $x \sim p_\theta(\cdot|z)$
- Want to learn the marginal $p_\theta(x) \approx p(x)$ defined by

$$p_\theta(x) = \int_{\mathcal{Z}} p_\theta(x|z)r(z) dz.$$

Motivation for Latent Variables

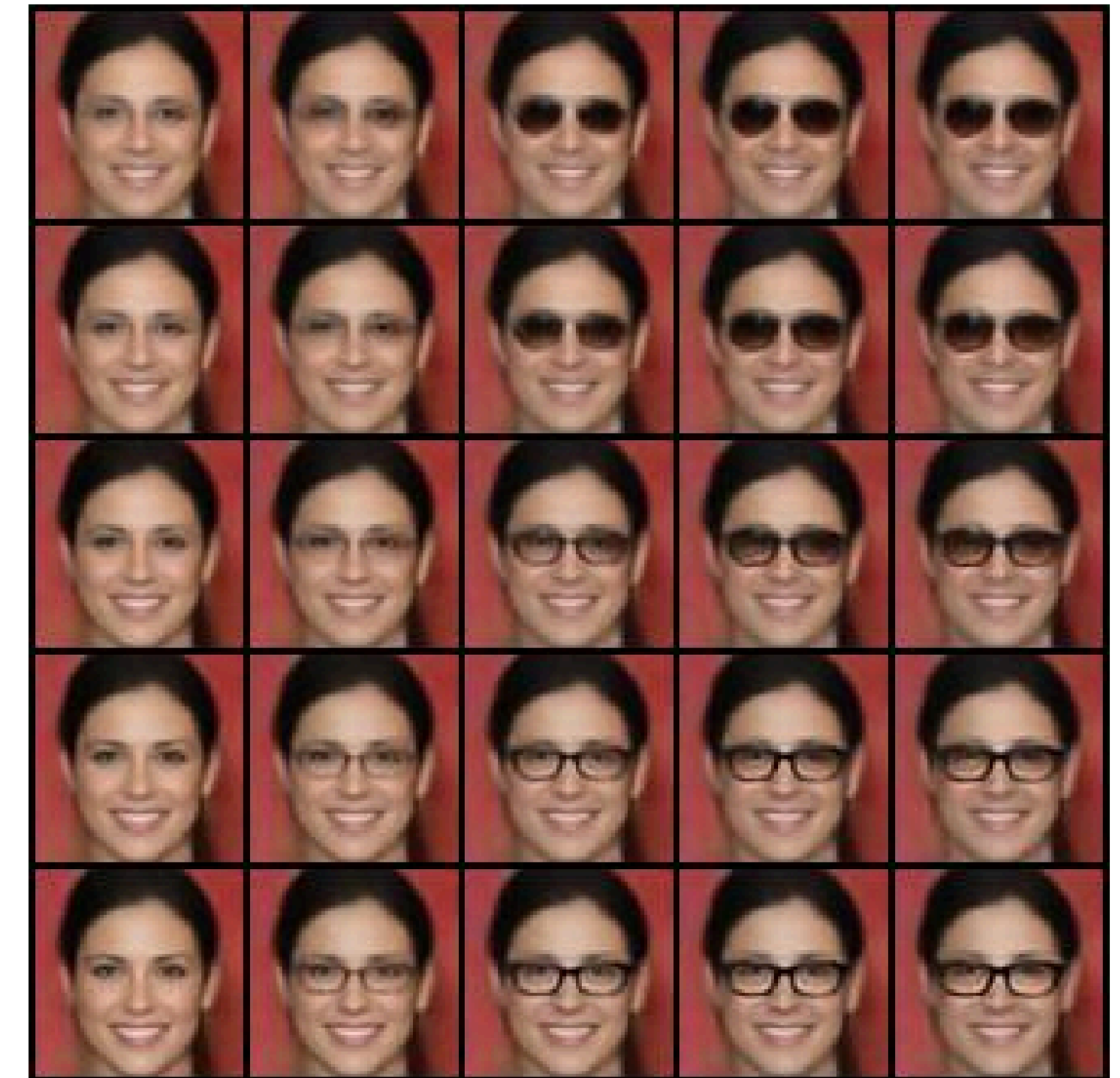
- Conditioning on a latent code z could give samples x more global coherence.
- Learned latent codes might reveal structure in the data distribution.
- The latent codes could be useful for downstream tasks or interpretability.



Kingma and Welling, ICLR 2013

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Klys, Snell, and Zemel, Neurips 2018

The MLE with Latent Variables

- Want to learn the marginal $p_\theta(x) \approx p(x)$ defined by

$$p_\theta(x) = \int_{\mathcal{Z}} p_\theta(x|z)r(z) dz.$$

- Fit the maximum likelihood estimator?

$$\hat{\theta}_{\text{mle}} \equiv \arg \max_{\theta} \mathbb{E}_{x \sim p} \log p_\theta(x) = \arg \max_{\theta} \mathbb{E}_{x \sim p} \log \int_{\mathcal{Z}} p_\theta(x|z)r(z) dz.$$

- This doesn't look promising...

Gaussian Mixture Models

- Generative model:

1. $z \sim \text{Categorical}_{\pi}(K),$ $\pi \in \Delta^{K-1},$
2. $x \sim \mathcal{N}(\mu_z, \Sigma_z),$ $\mu \in \mathbb{R}^{K \times d}, \Sigma \in \mathbb{R}^{K \times d \times d}.$

- Likelihood:

$$p_{\theta}(x) = \int_{\mathcal{Z}} p_{\theta}(x|z)r(z) dz = \sum_{k=1}^K \pi_k \mathcal{N}(x; \mu_k, \Sigma_k).$$

- But what if $r(z)$ is a continuous distribution over, e.g. $z \in \mathbb{R}^k$?

The Evidence Lower Bound

- Fit the maximum likelihood estimator?

$$\hat{\theta}_{\text{mle}} \equiv \arg \max_{\theta} \mathbb{E}_{x \sim p} \log p_{\theta}(x) = \arg \max_{\theta} \mathbb{E}_{x \sim p} \log \int_{\mathbf{z}} p_{\theta}(x|\mathbf{z})r(\mathbf{z}) d\mathbf{z}.$$

- Use importance sampling to estimate the integral.
- Construct a lower-bound on the marginal log-likelihood (the ELBO):

$$\log p_{\theta}(x) = \log \mathbb{E}_{z \sim q(\cdot|x)} \left[\frac{p_{\theta}(x, z)}{q(z|x)} \right] \geq \mathbb{E}_{z \sim q(\cdot|x)} \left[\log \frac{p_{\theta}(x, z)}{q(z|x)} \right].$$

Monte Carlo ELBO Estimation

- Importance-sampling estimator: $\log p_\theta(x) = \log \mathbb{E}_{z \sim q(\cdot|x)} \left[\frac{p_\theta(x, z)}{q(z|x)} \right]$.
- Cannot directly estimate the log-likelihood with samples.
- Let $z_i \sim q(\cdot|x)$. Evidence lower-bound (often use $m = 1$; like “hard” EM):

$$\log p_\theta(x) \geq \mathbb{E}_{z \sim q(\cdot|x)} \left[\log \frac{p_\theta(x, z)}{q(z|x)} \right] \approx \frac{1}{m} \sum_{i=1}^m \left[\log \frac{p_\theta(x, z_i)}{q(z_i|x)} \right].$$

Joint Maximization

- Define the ELBO to be $\mathcal{L}(x, z; \theta, q) \equiv \log \frac{p_{\theta}(x, z)}{q(z|x)}$.
- Estimate the marginal log-likelihood with by $\log p_{\theta}(x) \geq \mathbb{E}_{z \sim q(\cdot|x)} \mathcal{L}(x, z; \theta, q)$.
- Equality holds when $q(z|x) = p_{\theta}(z|x) = \frac{p_{\theta}(x|z)r(z)}{p_{\theta}(x)}$.
- Jointly optimize over θ, q :

$$\hat{\theta}_{\text{mle}} \equiv \arg \max_{\theta} \mathbb{E}_{x \sim p} \log p_{\theta}(x) = \arg \max_{\theta} \sup_q \mathbb{E}_{\substack{x \sim p \\ z \sim q(\cdot|x)}} \mathcal{L}(x, z; \theta, q).$$

Posterior Inference

- How to estimate the posterior $q(z|x) \approx p_\theta(z|x)$?
- For GMM's this was easy. We can compute the posterior exactly:

$$q(z|x) = p_\theta(z|x) = \frac{p_\theta(x|z)p_\theta(z)}{p_\theta(x)} = \frac{\pi_z \mathcal{N}(x; \mu_z, \Sigma_z)}{\sum_{k=1}^K \pi_k \mathcal{N}(x; \mu_k, \Sigma_k)}.$$

- What if the model isn't so simple?
 - What if the likelihood $p_\theta(x|z)$ isn't just a Gaussian?
 - What if the prior $r(z)$ is a continuous distribution on $z \in \mathbb{R}^k$?

Approximate Posterior Inference

- How to estimate the posterior $q(z|x) \approx p_\theta(z|x)$?
- Learn a model that approximates the posterior!
- Let $q_\phi(z|x)$ be a family of density estimators with parameters ϕ .
- People sometimes call this amortized inference.
- Wait a minute... are we begging the question here?

5-Minute Break

Stochastic Backpropagation

- Jointly optimize over θ, ϕ :

$$\hat{\theta}_{\text{mle}} \equiv \arg \max_{\theta} \mathbb{E}_{x \sim p} \log p_{\theta}(x) = \arg \max_{\theta} \sup_{\phi} \mathbb{E}_{\substack{x \sim p \\ z \sim q_{\phi}(\cdot|x)}} \mathcal{L}(x, z; \theta, \phi).$$

- Let's use SGD, given a sample $x_i \sim p, z_i \sim q_{\phi}(\cdot|x_i)$.

- Estimate the gradient w.r.t θ : $\nabla_{\theta} \mathbb{E}_{\substack{x \sim p \\ z \sim q_{\phi}(\cdot|x)}} \mathcal{L}(x, z; \theta, \phi) \approx \nabla_{\theta} \log \frac{p_{\theta}(x_i, z_i)}{q_{\phi}(z_i|x_i)}$.

- But we're in trouble computing $\nabla_{\phi} \mathbb{E}_{\substack{x \sim p \\ z \sim q_{\phi}(\cdot|x)}} \mathcal{L}(x, z; \theta, \phi)$.

The Reparameterization Trick

- Need to construct a Monte Carlo estimate of $\nabla_{\phi} \mathbb{E}_{\substack{x \sim p \\ z \sim q_{\phi}(\cdot|x)}} \mathcal{L}(x, z; \theta, \phi)$.
- Suppose $q_{\phi}(z|x)$ is defined by a pushforward distribution, e.g.

$$z = f_{\phi}(x, \varepsilon), \text{ where } \varepsilon \sim \mathcal{N}(0, I).$$

- Then $\nabla_{\phi} \mathbb{E}_{\substack{x \sim p \\ z \sim q_{\phi}(\cdot|x)}} \mathcal{L}(x, z; \theta, \phi) = \mathbb{E}_{\substack{x \sim p \\ \varepsilon \sim \mathcal{N}(0, I)}} \nabla_{\phi} \mathcal{L}(x, f_{\phi}(x, \varepsilon); \theta, \phi)$.
- This is an example of Monte Carlo gradient estimation.

The Gaussian VAE

- Use a prior $r(z) = \mathcal{N}(0, I)$ where $z \in \mathbb{R}^k$ (k is a hyper-parameter).
- With a Gaussian likelihood $p_\theta(x|z) = \mathcal{N}(x; g_\theta(z), \sigma_\theta^2(z)I)$.
- Where $g_\theta : \mathcal{Z} \rightarrow \mathcal{X}$ (the “decoder”) and $\sigma_\theta^2 : \mathcal{Z} \rightarrow \mathbb{R}$ are neural nets.
- Use a posterior approximation $q_\phi(z|x) = \mathcal{N}(z; f_\phi(x), \Sigma_\phi(x))$
- Where $f_\phi : \mathcal{X} \rightarrow \mathcal{Z}$ (the “encoder”) and $\Sigma_\phi : \mathcal{X} \rightarrow \mathcal{Z} \otimes \mathcal{Z}$ are neural nets.
- Think of it like a Gaussian mixture model with infinitely many components!

Reconstruction and Divergence

- The ELBO of the Gaussian VAE is:

$$-\frac{\dim(\mathcal{X})}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} \mathbb{E}_{z \sim q_\phi(\cdot|x)} \|x - g_\theta(z)\|^2 - D(q_\phi(z|x) \parallel r(z)).$$

- If σ^2 is held constant, then

$$\hat{\theta}_{\text{MLE}} = \arg \min_{\theta} \inf_{\varphi} \mathbb{E}_{\substack{x \sim p \\ z \sim q_\varphi(\cdot|x)}} \left[\frac{1}{2\sigma^2} \|x - g_\theta(z)\|^2 + D(q_\varphi(z|x) \parallel r(z)) \right].$$

- People refer to these terms as “reconstruction” and “divergence.”