

# Direct cortical control of 3D neuroprosthetic devices

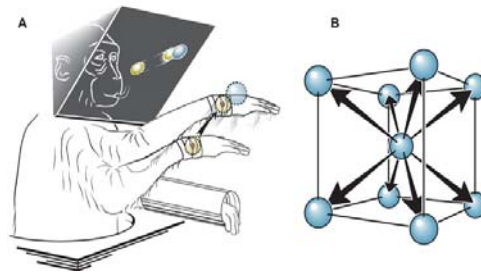
Taylor, Tillery & Schwartz  
*Science* 2002, 296

## Background

- Prediction of intended movement by cortical activity: 2 approaches
  - “open-loop”: offline trajectory recreation based on cortical activity, no feedback of neuronal activity
  - “closed-loop”: online trajectory recreation, subject receives feedback of neuronal activity
- Authors compared the two approaches when only small numbers of neurons were sampled

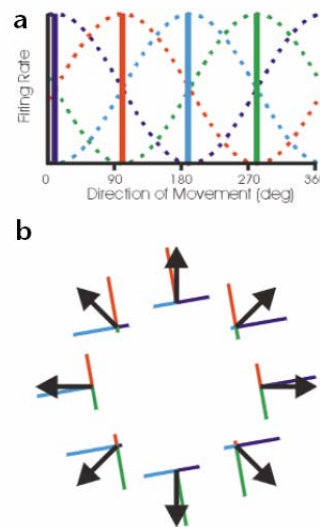
## Methods (I)

- Task
  - reach targets in a 3-D virtual environment
- Recording
  - chronic electrode array
  - L motor, premotor
- Decoding
  - population vector
  - approx. 18 cells



## Population vector

- Preferred direction
- Single neurons 'vote' using their firing rates
- 'Final vote' calculated by vectorial summation of individual preferred directions weighted by individual firing rate
- Each cell's contribution scaled by:
  - its quality of tuning
  - expected magnitude of movements



## Hand-control (open loop trajectories)

- Beginning of each day, new baseline data
- Slightly-different brain-to-cursor movement relation each day
- Fairly stable waveforms across days
- Encoded trajectories were calculated offline

## Brain-control (closed loop trajectories)

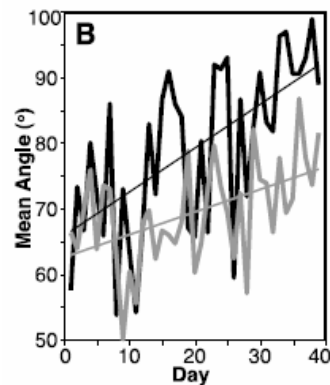
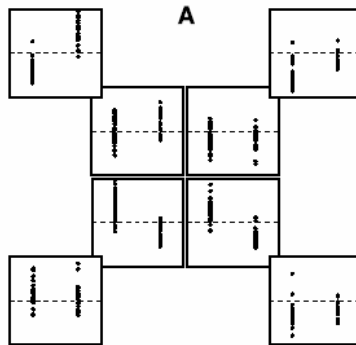
- Subjects used visual feedback to make online error correction
- More accurate than open-loop trajectories
- Subjects learned the new day-to-day relations
- Brain control was tested in both slow and rapid movements with comparable results

Closed-loop brain-controlled trajectories	M1	M2	both
% Targets hit	52 ± 14	46 ± 18	49 ± 17
% Time in correct octant	36 ± 9	34 ± 11	35 ± 11
Open-loop brain-predicted trajectories	M1	M2	both
% Targets hit	32 ± 11	23 ± 5	27 ± 9
% Time in correct octant	23 ± 9	23 ± 9	23 ± 9

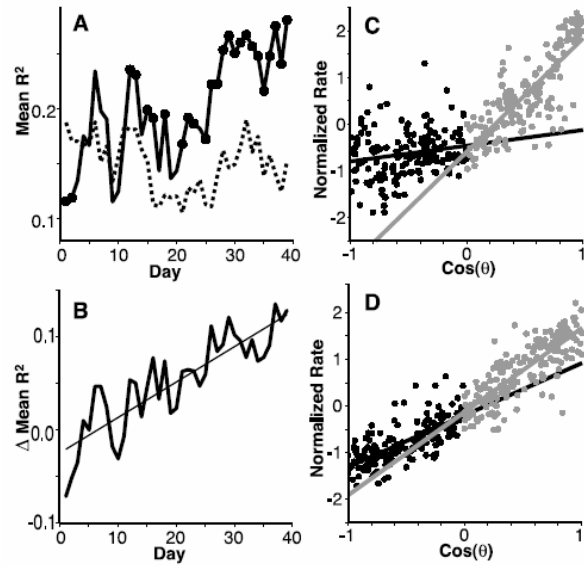
## Co-adaptive algorithm

- In the clinical setting, initial tuning properties will not be available
- Start with random initial preferred directions
- Iteratively refine “preferred direction” of each cell, based on difference between calculated cursor position (in 3D space) and desired cursor position

## Gradual change in cells' tuning properties



## Gradual change in cells' tuning quality & performance



## Testing novel targets

