

CSE599d: Advanced Query Processing

Lecture 8: Extensible Query Optimizers

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Review

Σ -Algebras, $T(\Sigma, X)$

A **signature** is $\Sigma = \{f_1, f_2, \dots, f_m\}$
each function symbol f_i and has an **arity** $n_i \geq 0$.

A **Σ -algebra** is $\mathbf{A} = (A, f_1^A, f_2^A, \dots, f_m^A)$ where $f_i^A : A^{n_i} \rightarrow A$.

A **Σ -term** is an expression built from Σ and X .

The **term algebra** $T(\Sigma, X)$ is the Σ -algebra of all Σ terms.

The “free Σ -algebra” generated by X .

Identities

An **identity** is a pair of terms (ℓ, r) . We write $\ell \approx r$.

ℓ = the **left-hand-side**

r = the **right-hand-side**



Fix an algebra **A**. A **substitution** is $\sigma : X \rightarrow A$.

A **satisfies** the identity $\ell \approx r$ if $\sigma(\ell) = \sigma(r)$ for all σ

Notation: **A** $\models \ell \approx r$

$\sigma : (x, y, z) \mapsto (5, 2, 6)$, then

$$\sigma\left(\begin{array}{c} + \\ / \backslash \\ + \quad z \\ / \backslash \\ x \quad y \end{array}\right) = 13,$$

$$\sigma\left(\begin{array}{c} + \\ / \backslash \\ x \quad + \\ \quad / \backslash \\ \quad y \quad z \end{array}\right) = 13.$$

Semantic Consequence

Fix a set of identities E .

An identity $s \approx t$ is a **semantic consequence** of E if:

For every Σ -algebra $\mathbf{A}$: $\text{if } \mathbf{A} \models E \text{ then } \mathbf{A} \models s \approx t$

We write $\approx_E$ for the semantic consequences of E .

It turns out that we can describe $\approx_E$ in terms of **reductions**.

The Reduction Relation

Review in class the reduction $\rightarrow_E$.

$\xrightarrow{*}_E$ and $\leftrightarrow^*$ extend $\rightarrow_E$ and are:

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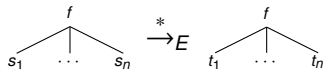
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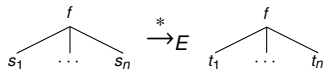
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Closed under substitutions¹ If $s \rightarrow t \in E$, then $\sigma(s) \xrightarrow{*}_E \sigma(t)$ for all σ

Theorem [Birkoff] $\approx_E$ is the same as $\leftrightarrow^*_E$

¹ σ is a substitution $\sigma : X \rightarrow T(\Sigma, X)$.

The Word Problem

Fix Σ, E .

The Word Problem: given s, t , decide whether $s \approx_E t$

Decidable cases: semigroup, monoids, groups, lattices

Undecidable cases: Matijasevič's strange identities; combinatory logic.

A Special Case

Theorem when all terms in E are grounded (i.e. no variables),
then the ground word problem (i.e. s, t are also grounded) is decidable.

Relational Algebra v.s. a Σ -algebra

$\Sigma = \{\sigma, \Pi, \bowtie, \cup, -\}$. However:

- Some operations are undefined: $R \cup S$ when R, S have different schemas.
- Some operations have parameters: $\sigma_p(R)$ where p is some predicate.
- Template identities: $R \bowtie_{A=B} S \approx S \bowtie_{B=A} R$ for every choice of A, B .

Could fix the theory. Volcano/Cascades just ignore these rough spots.

No Complete Identities for Relational Algebra!

Query equivalence, $Q \equiv Q'$, means: $Q(D) = Q'(D)$ for any database D .

Fact There is no r.e.² E for which $\approx_E$ coincides with $\equiv$.

Because:

- $Q \equiv Q'$ is undecidable
- $\approx_E$ is r.e.
- $\equiv$ is co-r.e.
- If $\approx_E$ coincides with $\equiv$, then they were decidable

²Recursively enumerable (e.g. templates).

E-Graphs

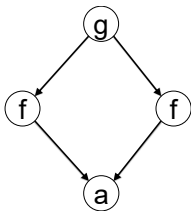
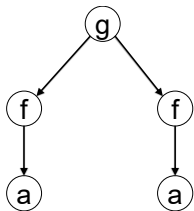
Overview

E-graphs are keeping all intermediate steps of a rewrite sequence $s \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$ in a compact data structure.

This part is based on the book [Baader and Nipkow, 1999] and the egg paper [Willsey et al., 2021].

Term Graph

Term Graph is a DAG sharing common subexpressions:

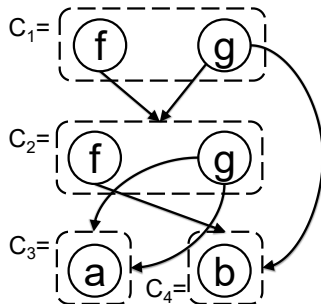


E-Graph

An E-graph G consists of:

- A set of **E-classes** $c_1, c_2, \dots$,
- ... where each E-class c is a set of **E-nodes** $c = \{v_1, v_2, \dots\}$,
- ... and each e-node is a pair $(f, (c_{i_1}, \dots, c_{i_k}))$ where $f \in \Sigma$, $c_{i_1}, \dots, c_{i_k}$ are E-classes, and k is the arity of f .

E-Graphs



Each class c represents a set of terms:

$$\text{terms}(c_3) = a,$$

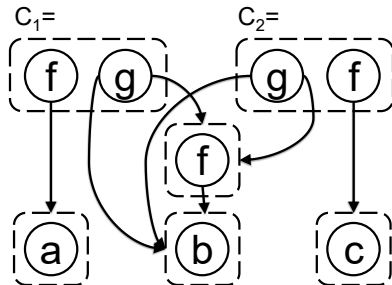
$$\text{terms}(c_4) = b$$

$$\text{terms}(c_2) = \{f(b), g(a, a)\}$$

$$\text{terms}(c_1) = \{f(f(b)), f(g(a, a)), g(f(b), b), g(g(a, a), b)\}$$

$\text{terms}(G)$ = the set of all terms represented by all E-classes.

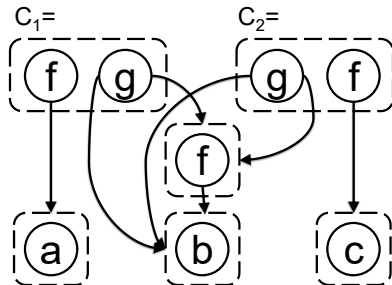
Congruence Closure



$\text{terms}(c_1) = \text{????}$

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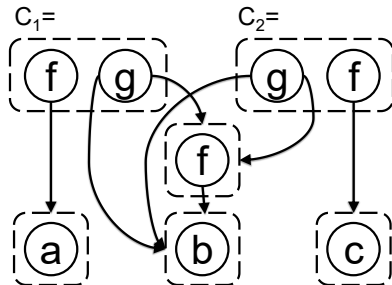
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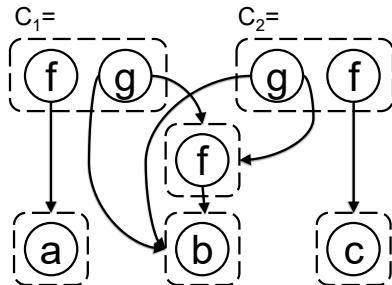
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$$\text{terms}(c_1) = \{f(a), g(b, f(b))\}$$

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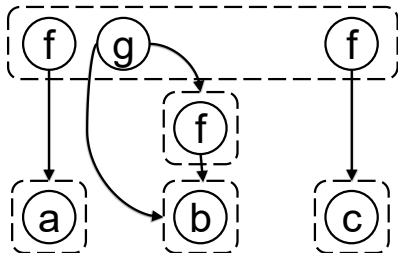
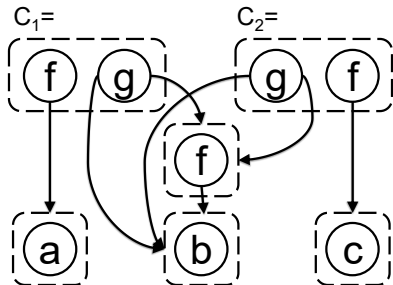


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Common term $g(b, f(b))$

Congruence Closure



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Congruence closure of the E-graph

$\text{terms}(c_2) = \{g(b, f(b)), f(c)\}$

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We say that G is **closed under congruence** if $\sim_G$ is a **congruence** on terms(G):

- $\sim_G$ is an equivalence relation, and
- if $f(s_1, \dots, s_n), f(t_1, \dots, t_n) \in \text{terms}(G)$
and $s_1 \sim_G t_1, s_2 \sim_G t_2, \dots$, then $f(s_1, \dots, s_n) \sim_G f(t_1, \dots, t_n)$.

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Congruence closure algorithm: modifies G to ensure that $\sim_G$ is a congruence.

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TRS approach

$$\begin{array}{ccccccc} s & \rightarrow_E & s_1 & \rightarrow_E & s_2 & \rightarrow_E & \dots \\ t & \rightarrow_E & t_1 & \rightarrow_E & t_2 & \rightarrow_E & \dots \end{array}$$

Common term?

Then $s \approx_E t$.

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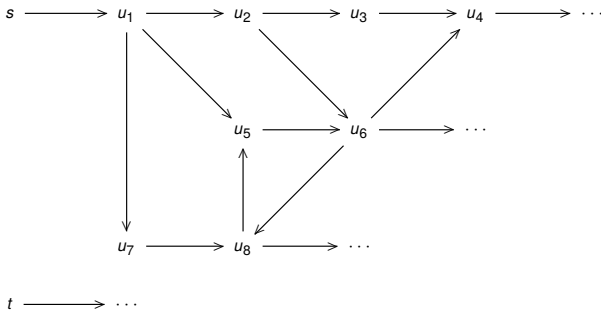
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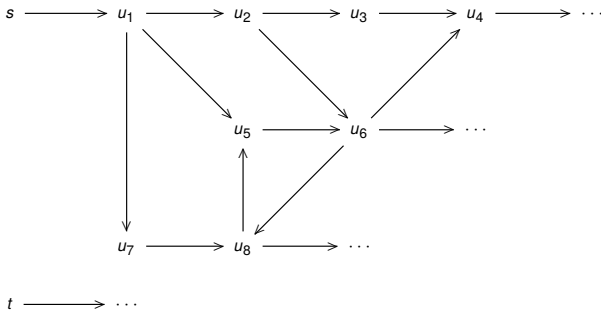
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Both approaches assume that E is directed.

Solving the Word Problem with E-graphs

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Initialize the E-graph with s, t .

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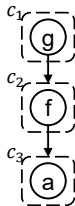
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When (and if!) it terminates, check $s \sim_G t$

Example from [Baader and Nipkow, 1999]

$$E = \boxed{g(x) \approx f(f(x))}$$

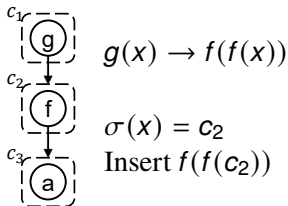
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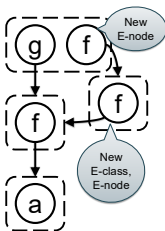
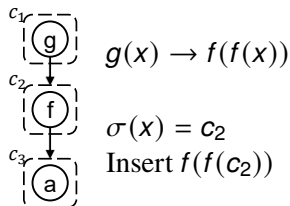
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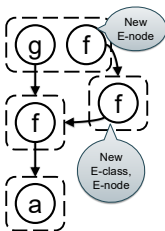
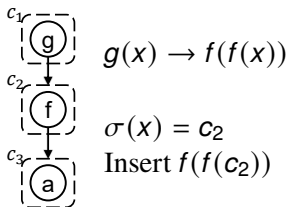
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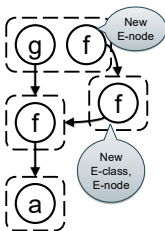
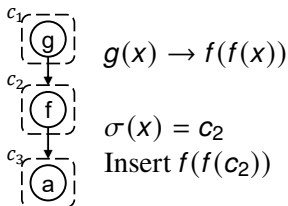
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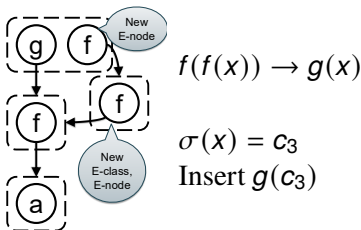
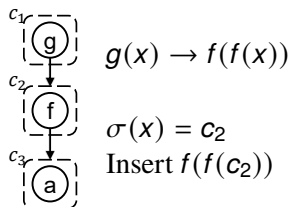
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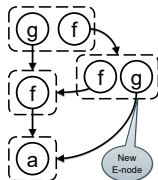
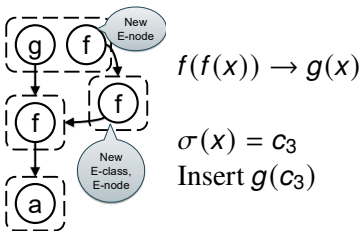
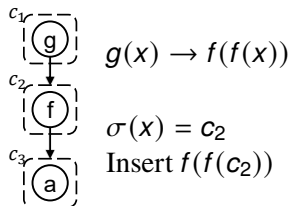
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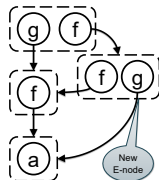
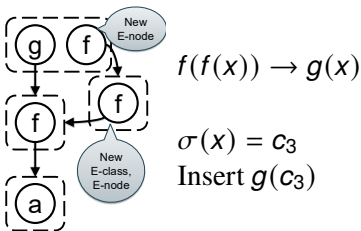
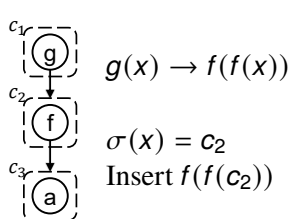
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Example from [Baader and Nipkow, 1999]

$$E = \begin{cases} g(x) \approx f(f(x)) \\ f(f(x)) \approx g(x) \end{cases}$$

Check $g(f(a)) \approx_E f(g(a))$
Stuck! Need to close E under symmetry



$g(f(a)) \in \text{terms}(c_1)$ and also $f(g(a)) \in \text{terms}(c_1)$

Hence $g(f(a)) \sim_G f(g(a))$ which implies $g(f(a)) \approx_E f(g(a))$.

Discussion (1/2)

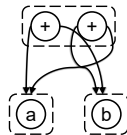
The Equality Saturation Algorithm ensures that $s \sim_G t$ implies $s \approx_E t$.

Converse fails for multiple reasons:

- E is treated as asymmetrically and may fail to trigger.
- $\sim_G$ is an equivalence relation only on terms(G).
Called **Partial Equivalence Relation**, PER; also partial **congruence**.

Discussion (2/2)

E-graphs can avoid some non-terminating reductions:
E.g. commutativity:



Non-termination can still happen, e.g. $g(x) \approx g(f(x))$:
Leads to $g(a) \approx g(f(a)) \approx g(f(f(a))) \approx \dots$

Direction of the identities in E may affect termination: e.g. $g(f(x)) \approx g(x)$.

No good theory exists for understanding termination.

Special Case: Grounded Identities

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Proof Initialize E-graph with s, t , and all sub-terms of terms E .

Make E symmetric: $\ell \rightarrow_E r$ and $r \rightarrow_E \ell$.

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Make E symmetric: $\ell \rightarrow_E r$ and $r \rightarrow_E \ell$.

Equality saturation never needs to insert new E-nodes in G

Hence the congruence closure algorithm terminates
and $\sim_G$ is the same as $\overset{*}{\leftrightarrow}_E$ on terms(G) (because E is symmetric).

Example from [Baader and Nipkow, 1999]

$$E = \begin{array}{l} f(f(a)) \approx a \\ f(f(f(a))) \approx a \end{array}$$

Check if $f(a) \approx_E a$

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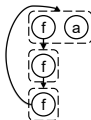
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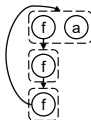
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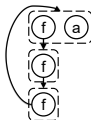
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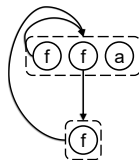
Check if $f(a) \approx_E a$



$$f(f(f(a))) \rightarrow a$$



$$f(f(a)) \rightarrow a$$



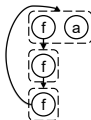
Example from [Baader and Nipkow, 1999]

$$E = \begin{cases} f(f(a)) \approx a \\ f(f(f(a))) \approx a \end{cases}$$

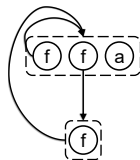
Check if $f(a) \approx_E a$



$$f(f(f(a))) \rightarrow a$$



$$f(f(a)) \rightarrow a$$



$$f(f(f(a))) \rightarrow a$$

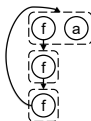
Example from [Baader and Nipkow, 1999]

$$E = \begin{array}{l} f(f(a)) \approx a \\ f(f(f(a))) \approx a \end{array}$$

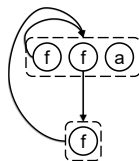
$$\text{Check if } f(a) \approx_E a$$



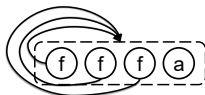
$$f(f(f(a))) \rightarrow a$$



$$f(f(a)) \rightarrow a$$



$$f(f(f(a))) \rightarrow a$$



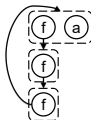
Example from [Baader and Nipkow, 1999]

$$E = \begin{cases} f(f(a)) \approx a \\ f(f(f(a))) \approx a \end{cases}$$

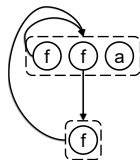
$$\text{Check if } f(a) \approx_E a$$



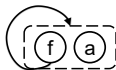
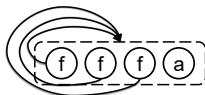
$$f(f(f(a))) \rightarrow a$$



$$f(f(a)) \rightarrow a$$



$$f(f(f(a))) \rightarrow a$$


$$\Leftarrow$$


Volcano/Cascades

Overview

Lecture mostly based on [Ding et al., 2024]

Volcano:

- Introduced in [Graefe, 1994]; more details [McKenna, 1993]
- Logical rules: equality saturation; physical rules: branch-and-bound.

Cascades

- Introduced in [Graefe, 1995]; more details [Xu, 1998]
- Combines the two phases of Volcano.
- Adoption: SQLServer, Calcite, CockroachDB

Terminology (1/2)

Logical Property of an expression: e.g. estimated cardinality

Physical Property of an expression: interesting sort order, partition.

Logical Operators e.g. $\bowtie$, σ , Γ , $\bowtie$...

Physical Operators e.g. HashJoin, MergeJoin, IndexScan, ...

Enforcers e.g. Sort, Partition.

Terminology (2/2)

Rule = (CheckPattern, Transform):

- Transformation rule, e.g. $R \bowtie S \rightarrow S \bowtie R$
- Implementation rule, e.g. $R \bowtie S \rightarrow R \text{ HashJoin } S$

Memo = E-Graph

Group or Class = E-Class

Expression = E-Node

Volcano

1. **Generation Phase:** repeatedly applies transformation rules until saturation.
2. **Cost Analysis Phase:** applies implementation rules, using a cost **Limit**

R(A,B), S(B,C), T(C,D)

The Memo

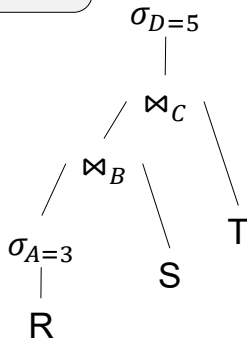
```
select *  
from R, S, T  
where R.B=S.B  
and S.C=T.C  
and R.A = 3  
and T.D = 5
```

R(A,B), S(B,C), T(C,D)

```
select *  
from R, S, T  
where R.B=S.B  
and S.C=T.C  
and R.A = 3  
and T.D = 5
```

The Memo

Initialize Memo
w/ one (naïve)
plan



R(A,B), S(B,C), T(C,D)

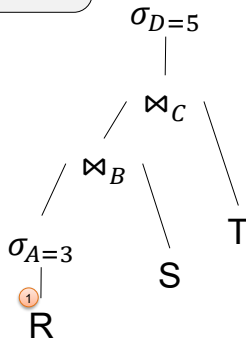
select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

The Memo

1

Scan R

Initialize Memo
w/ one (naïve)
plan

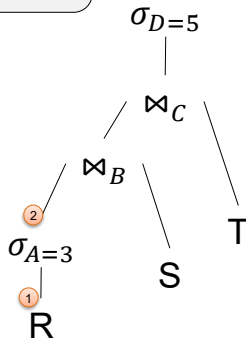
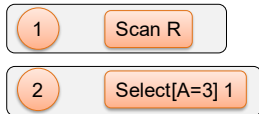


R(A,B), S(B,C), T(C,D)

select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

The Memo

Initialize Memo
w/ one (naïve)
plan

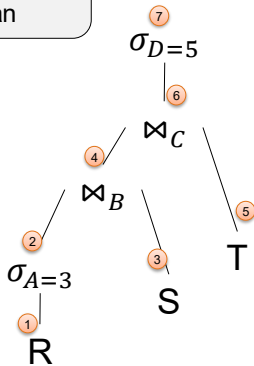
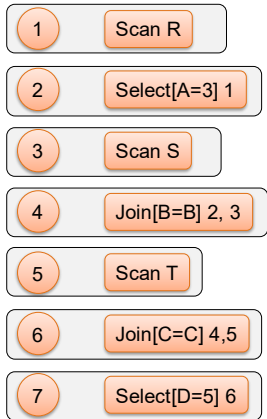


R(A,B), S(B,C), T(C,D)

The Memo

Initialize Memo
w/ one (naïve)
plan

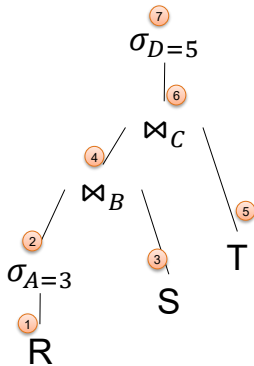
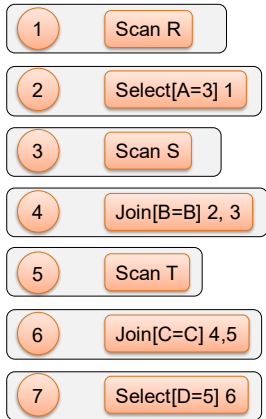
select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5



R(A,B), S(B,C), T(C,D)

The Memo

select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

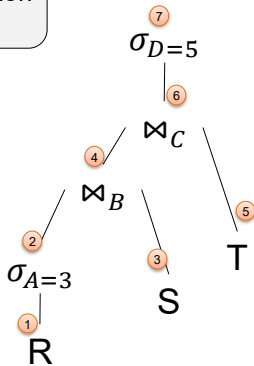
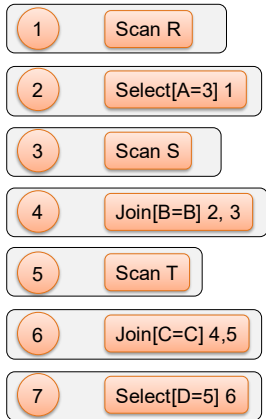


R(A,B), S(B,C), T(C,D)

The Memo

select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

Apply an
optimization
rule

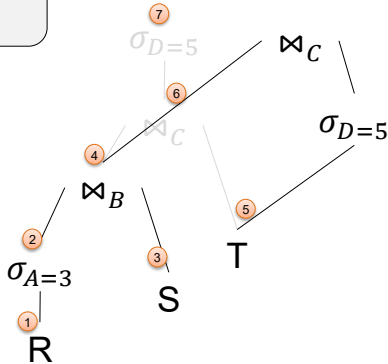
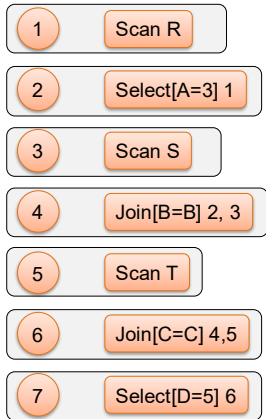


R(A,B), S(B,C), T(C,D)

The Memo

select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

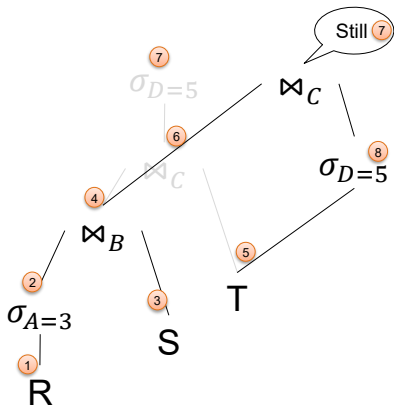
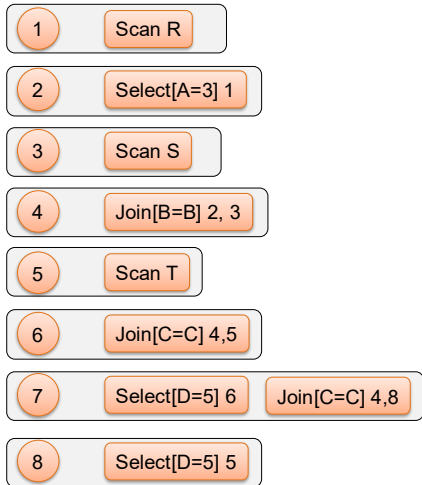
Apply an
optimization
rule



R(A,B), S(B,C), T(C,D)

The Memo

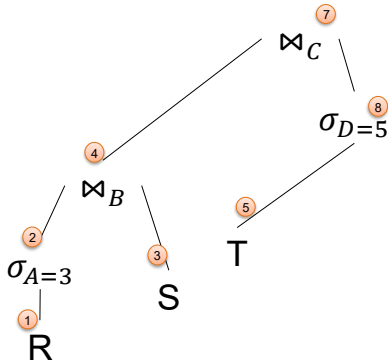
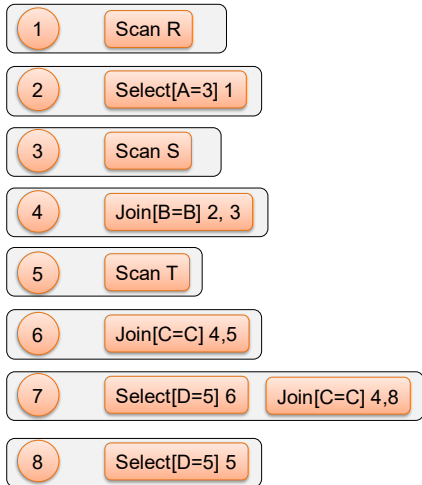
select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5



R(A,B), S(B,C), T(C,D)

The Memo

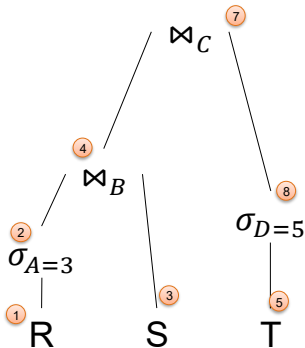
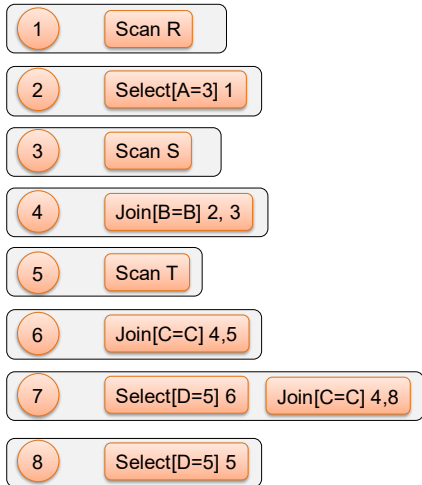
```
select *  
from R, S, T  
where R.B=S.B  
and S.C=T.C  
and R.A = 3  
and T.D = 5
```



R(A,B), S(B,C), T(C,D)

The Memo

select *
from R, S, T
where R.B=S.B
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and R.A = 3
and T.D = 5

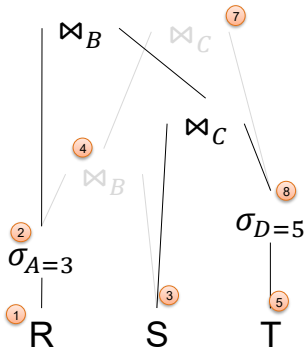
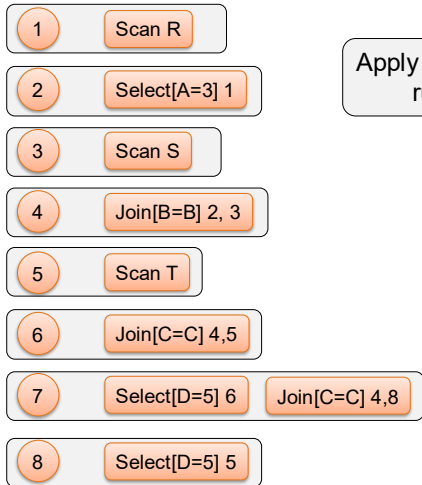


R(A,B), S(B,C), T(C,D)

The Memo

select *
from R, S, T
where R.B=S.B
and S.C=T.C
and R.A = 3
and T.D = 5

Apply another
rule



Volcano: Generation Phase

[Ding et al., 2024] **Top Down** equality saturation:

```
1: function GENERATELOGICALEXPR(LogExpr, Rules)           ▷ Generation phase
2:   for Child in inputs of LogExpr do
3:     if Group(Child)  $\notin$  Memo then
4:       GenerateLogicalExpr(Child)                       ▷ Update memo
5:     MatchTransRule(LogExpr, Rules)
6: function MATCHTRANSRULE(LogExpr, Rules)           ▷ Apply transformation rules
7:   for rule in Rules do
8:     if rule matches LogExpr then
9:       NewLogExpr  $\leftarrow$  Transform(LogExpr, rule)   ▷ Update memo and
       record the neighbors
10:      GenerateLogicalExpr(NewLogExpr)                 ▷ Only invoke if
       NewLogExpr is not previously in memo
```

Small bug: `GenerateLogicalExpr` should have `Rules` as parameter.

Volcano: Cost Analysis Phase

FindBestPlan: Logical Expression $\mapsto$ Physical plan

FindBestPlan(Group, Limit) by example:

Volcano: Cost Analysis Phase

FindBestPlan: Logical Expression $\mapsto$ Physical plan

FindBestPlan(Group, Limit) by example:

- For each Expr $\in$ Group



Volcano: Cost Analysis Phase

FindBestPlan: **Logical Expression** $\mapsto$ **Physical plan**

FindBestPlan(Group, Limit) by example:

- For each Expr $\in$ Group



- Apply an implementation rule



Cost = 100

Volcano: Cost Analysis Phase

FindBestPlan: Logical Expression $\mapsto$ Physical plan

FindBestPlan(Group, Limit) by example:

- For each Expr $\in$ Group



- Apply an implementation rule



Cost = 100

- FindBestPlan(g_1 , Limit - 100)



Cost = 2100

Volcano: Cost Analysis Phase

FindBestPlan: Logical Expression $\mapsto$ Physical plan

FindBestPlan(Group, Limit) by example:

- For each Expr $\in$ Group



- Apply an implementation rule



Cost = 100

- FindBestPlan(g_1 , Limit - 100)



Cost = 2100

- FindBestPlan(g_2 , Limit - 2100)



Cost = ...

Volcano: Cost Analysis Phase

FindBestPlan: Logical Expression $\mapsto$ Physical plan

FindBestPlan(Group, Limit) by example:

- For each Expr $\in$ Group



- Apply an implementation rule



Cost = 100

- FindBestPlan(g_1 , Limit - 100)



Cost = 2100

- FindBestPlan(g_2 , Limit - 2100)



Cost = ...

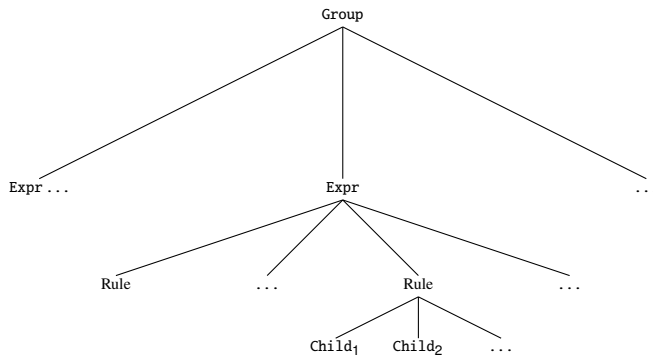
- Whenever Cost > Limit stop and return NULL

Volcano: Cost Analysis Phase (Very Simplified)

Function FindBestPlan(**Group**, **Limit**)

if **Limit** $\leq$ 0 **then return** Null;**Plan**, **Cost** := LookUpMemo(**Group**)**if** **Cost** $\neq$ Null **then** **if** **Cost** $\leq$ **Limit** **then return** **Plan**, **Cost** ; **else return** NULL;**Cost** := ∞ ;**for** **Expr** $\in$ **Group**, **r** $\in$ ImplementationRules(**Expr**) **do** **Pln**, **Cst** := **r.Op**, **r.Cost** ; // Start new plan with **r.Op** **for** **Grp** $\in$ Children(**Expr**) **do** **Pln**, **Cst** += FindBestPlan(**Grp**, **Limit** - **Cst**) **if** Success all children? **then** **Plan**, **Cost**, **Limit** := **Pln**, **Cst**, **Cst**;;**InsertMemo**(**Group**, **Plan**, **Cost**)**return** (**Plan**, **Cost**)

Volcano: Cost Analysis Phase (Visual Representation)



$$\text{Limit}_1 \geq \text{Limit}_2 \geq \text{Limit}_3 \geq \dots$$

When $\text{Cost} > \text{Limit}$, prune the search.

Discussion

- Generation phase is straightforward: saturate the whole E-Graph.
- Cost-analysis phase: prunes the search based on cost. In addition:
 - ▶ Store applicable implementation rules in a set of Moves
 - ▶ Sort Moves by “promise”, to find better plans first.
 - ▶ Early stopping is possible, e.g. timeout.
- A physical expression may have multiple version, with different properties.

Cascades

Will discuss only at a very high level.

Cascades makes the following changes to Volcano:

- Handles transformation and implementation rules in the same phase.
- Replaces recursive call with stack-based processing: allows control over the order of operations.
- Breaks down each rule application into smaller steps, each becomes a separate task, to be placed on the stack.

This allows for a more aggressive cost-based pruning.

Discussion

- Volcano/Cascades: complex, but clean foundation in E-Graphs
- Lots of additional heuristics:
 - ▶ Simplification rules: apply $E_1 \rightarrow E_2$, then delete E_1
 - ▶ Macro rules: e.g. $\text{StarJoin}(R_1, \dots, R_n) \rightarrow \text{DPccp}$
- Systems implementing Cascades: SQLServer, Orca (Greenplum), Calcite.
- Other systems: Postgres (DP), Catalyst/Spark (greedy).



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