

CSE599d: Advanced Query Processing

Lecture 7: Extensible Query Optimizers

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Motivation

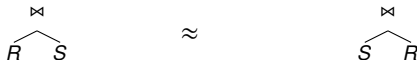
Dynamic programming is efficient, but handles only joins.

Difficult to add more complex operators (outer/anti joins, group-by).

Extensible Query Optimizer: based on a set of identities called **logical transformation rules**, which can be extended with new operators and new identities.

Examples of Identities¹

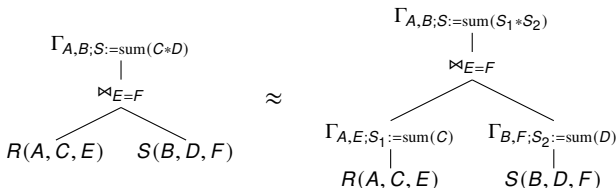
Commutativity:



Associativity:



Group-by:



¹Called Logical Transformation Rules in Volcano/Cascades.

Overview

- The optimization problem becomes an instance of the **word problem**
- There are two techniques for the word problem: TRS and E-graphs.
- Volcano and Cascades (an extension of Volcano) are essentially E-graphs on steroids.
- This lecture: review of the Word Problem, TRS, E-Graphs.

The Word Problem

Based on [Baader and Nipkow, 1999].

Σ -Algebras

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Examples:

- $\Sigma = \{f, g\}$ with arities 1, 2.

Algebra (\mathbb{N}, f^N, g^N) where $f^N(x) = x + 1$ and $g^N(x, y) = x \cdot y$.

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- $\Sigma = \{+, \times, 0, 1\}$

Algebra $\mathbb{N} = (\{0, 1, 2, \dots\}, +, \times, 0, 1)$

Another algebra $\mathbb{B} = (\{0, 1\}, \vee, \wedge, 0, 1)$

The Term Algebra

Fix an infinite set of variables $X = \{x_1, x_2, \dots\}$.

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$$f(g(x, f(g(x, y)))) =$$

The diagram shows a parse tree for the term $f(g(x, f(g(x, y))))$. The root node is f , which has a single child node g . This g node has two children: x and f . The f child of the g node has a single child node g . This g node has two children: x and y .

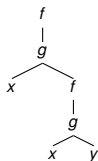
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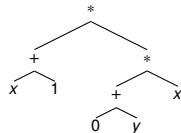
A Σ -term is an expression built from Σ and X .

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$$(x + 1) * ((0 + y) * x) =$$



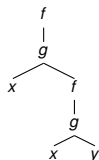
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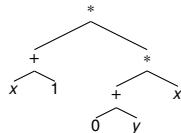
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$$f(g(x, f(g(x, y)))) =$$



$$(x + 1) * ((0 + y) * x) =$$



$T(\Sigma, X)$ is a Σ algebra

what are the operations f, g, \dots ??

Identities

An **identity** is a pair of terms (ℓ, r) . We write $\ell \approx r$.

ℓ = the **left-hand-side**

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What does $\ell \approx r$ mean? Fix an algebra **A**:

A **substitution** is a function $\sigma : X \rightarrow A$, where **A** is a Σ -algebra.

A **satisfies** the identity $\ell \approx r$ if $\sigma(\ell) = \sigma(r)$ for all σ . Notation: **A** $\models \ell \approx r$

Semantic Consequence

Fix a set of identities E .

An identity $s \approx t$ is a **semantic consequence** of E if:

For every Σ -algebra \mathbf{A} : $\text{if } \mathbf{A} \models E \text{ then } \mathbf{A} \models s \approx t$

We write \approx_E for the semantic consequences of E .

It turns out that we can describe \approx_E in terms of **reductions**.

The Reduction Relation

The **reduction relation** $s \rightarrow_E t$ holds if
 there exists $(\ell, r) \in E$, substitution $\sigma : X \rightarrow T(\Sigma, X)$, context ² $C[]$ s.t.:

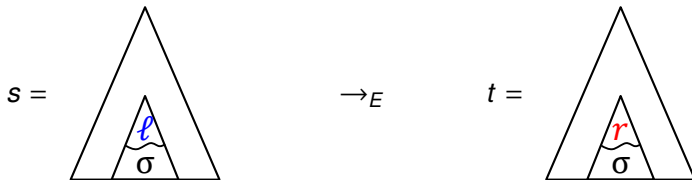
$$s = C[\sigma(\ell)] \text{ and } t = C[\sigma(r)]$$

²A context is a “term with a hole”.

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The Reduction Relation

We extend \rightarrow_E as follows:

\rightarrow_E^* transitive and reflexive closure of \rightarrow_E

\leftarrow_E symmetric closure of \rightarrow_E

\leftrightarrow_E^* transitive, reflexive and symmetric closure of \rightarrow_E

We say that $s \leftrightarrow_E^* t$ is a **syntactic consequence** of E .

Theorem [Birkoff] \approx_E is the same as \leftrightarrow_E^*

The Word Problem

Fix Σ, E .

The Word Problem: given s, t , decide whether $s \approx_E t$

Decidability depends on Σ, E .

Examples of Decidable Word Problems

Semigroups $\Sigma = \{\cdot\}$

$$(xy)z \approx x(yz)$$

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Also:

- Commutative Semigroups

$$xy \approx yx$$

- Monoids $ex \approx xe \approx x$

- Groups $x^{-1}x \approx xx^{-1} \approx e$.

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Lattices $\Sigma = \{\vee, \wedge\}$

\wedge, \vee are associative, commutative, and:

$$x \vee (x \wedge y) \approx x$$

$$x \wedge (x \vee y) \approx x$$

Also:

- Distributive lattices
- Boolean algebras

Examples of Undecidable Word Problems

Semigroups [Matijasevič] $\Sigma = \{\cdot, a, b\}$

$$(xy)z \approx x(yz)$$

$$aba^2b^2 \approx b^2a^2ba$$

$$a^2bab^2a \approx b^2a^3ba$$

$$aba^3b^2 \approx ab^2aba^2$$

$$b^3a^2b^2a^2ba \approx b^3a^2b^2a^4$$

$$a^4b^2a^2ba \approx b^2a^4$$

Combinatory Logic $\Sigma = \{\cdot, S, K\}$

$$((S \cdot x) \cdot y) \cdot z \approx (x \cdot z) \cdot (y \cdot z)$$

$$(K \cdot x) \cdot y \approx x$$

A Special Case

Theorem when all terms in E are grounded (meaning: no variables), then the ground word problem³ for E is decidable.

³Meaning: s, t are also grounded.

QO v.s. the Word Problem

Query Optimization v.s. the Word Problem

Query optimization: given a set of logical transformations E (i.e. identities), and a query Q , find an “optimal” query Q' such that $Q \approx_E Q'$.

This is basically a word problem.

However, there are some rough spots in modeling QO as a word problem.

Relational Algebra v.s. a Σ -algebra

The relational algebra is a Σ -algebra, where $\Sigma = \{\sigma, \Pi, \bowtie, \cup, -\}$, however:

- Some operations are undefined: $R \cup S$ when R, S have different schemas.
- Some operations have parameters: $\sigma_p(R)$ where p is some predicate.
- Template identities: one $R \bowtie S \approx S \bowtie R$ for each schema of R, S .

Could fix with a multi-sorted algebra. In practice, just ignore these rough edges.

E is Always Incomplete!

Query equivalence, $Q \equiv Q'$, means: $Q(D) = Q'(D)$ for any database D .

Fact There is no r.e.⁴ E for which \approx_E coincides with \equiv .

⁴Recursively enumerable, e.g. templates.

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Proof Recall that checking $Q \equiv Q'$ is undecidable.

Assume \approx_E and \equiv are the same. Then we can check $Q \equiv Q'$:

- Enumerate all pairs (Q_1, Q_2) such that $Q_1 \approx_E Q_2$ how??
- Enumerate all pairs (Q_1, Q_2) such that $Q_1 \not\equiv Q_2$ how??
- Watch whether (Q, Q') appears in the first or second list.

⁴Recursively enumerable, e.g. templates.

Term Rewriting Systems

Two Approaches to the Word Problem

- Term Rewriting Systems (TRS)
- Equality Saturation Graphs (E-Graphs)

Term Rewriting Systems

A **Term Rewriting Systems (TRS)** is a set of oriented identities E , written $\ell \rightarrow r$.

Goal: study the properties of \rightarrow_E^* .

Note: TRS require $\text{Vars}(\ell) \supseteq \text{Vars}(r)$ and ℓ is not a variable

Solving the Word Problem via TRS

A Naive Approach to check $s \approx_E t$:

Perform reductions $s \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$

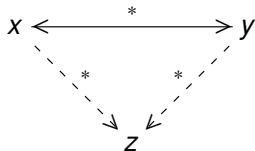
If t shows up, then $s \equiv_E t$.

Problems with the naive approach:

- Infinite reductions. E.g. commutativity $a + b \rightarrow b + a \rightarrow a + b \rightarrow \dots$
- We may need to go in both directions $s \rightarrow s_1 \leftarrow s_2 \leftarrow s_3 \rightarrow \dots$.

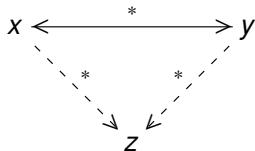
Desirable Properties of a TRS

Church-Rosser:

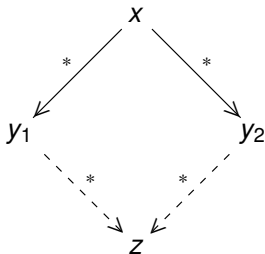


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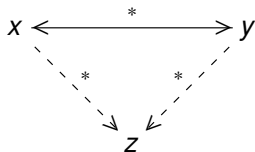


Confluent:

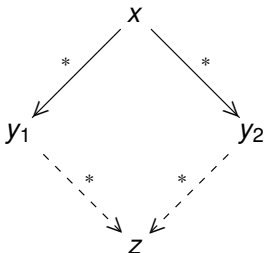


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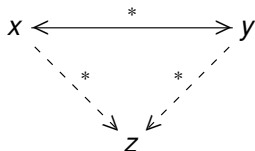
Terminating:

No infinite sequence:

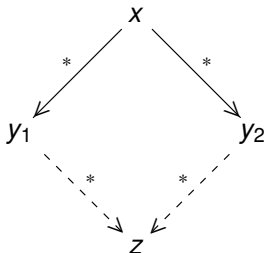
$$x_0 \rightarrow x_1 \rightarrow x_2 \rightarrow \dots$$

Desirable Properties of a TRS

Church-Rosser:



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Terminating:

No infinite sequence:

$$x_0 \rightarrow x_1 \rightarrow x_2 \rightarrow \dots$$

- \rightarrow is Church-Rosser iff it is confluent.
- If \rightarrow is confluent and terminating then \approx (which is $\overset{*}{\leftrightarrow}$) is decidable.
because each x has a unique **normal form** x_0 : $x \xrightarrow{*} x_0 \nrightarrow$

Discussion

Key assumption in TRS: identities are directional. $\ell \approx r$ not same as $r \approx \ell$.

Problems in TRS: non-terminating reductions.

Rich literature on sufficient conditions to ensure termination.
Still can't handle commutativity.

E-Graphs were introduced as a caching mechanism to avoid repeated terms.

E-Graphs

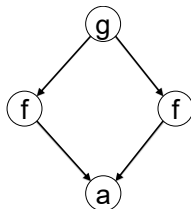
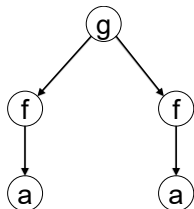
Overview

E-graphs are keeping all intermediate steps of a rewrite sequence
 $s \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$ in a compact data structure.

This part is based on the book [Baader and Nipkow, 1999] and the egg paper [Willsey et al., 2021].

Term Graph

Modify tree to a DAG by sharing common subexpressions: [Term Graph](#)



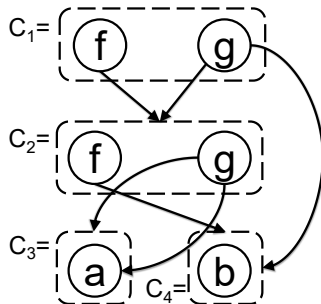
Each of these term graphs represent the term $g(f(a), f(a))$.

E-Graph

An E-graph G consists of:

- A set of **E-classes** c_1, c_2, \dots ,
- ... where each E-class c is a set of **E-nodes** $c = \{v_1, v_2, \dots\}$,
- ... and each e-node is a pair $(f, (c_{i_1}, \dots, c_{i_k}))$ where $f \in \Sigma$, c_{i_1}, \dots, c_{i_k} are E-classes, and k = the arity of f .

E-Graphs



Each class c represents a set of terms:

$$\text{terms}(c_3) = a,$$

$$\text{terms}(c_4) = b$$

$$\text{terms}(c_2) = \{f(b), g(a, a)\}$$

$$\text{terms}(c_1) = \{f(f(b)), f(g(a, a)), g(f(b), b), g(g(a, a), b)\}$$

$\text{terms}(G)$ = the set of all terms represented by all E-classes.

Congruence Closure

An E-graph defines the following relation on terms(G):

$s \sim_G t$ if exists E-class c such that $s, t \in \text{terms}(c)$

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We say that G is **closed under congruence** if \sim_G is a congruence relation on terms(G), meaning:

- \sim_G is an equivalence relation, and
- if $f(s_1, \dots, s_n), f(t_1, \dots, t_n) \in \text{terms}(G)$ and $s_1 \sim_G t_1, s_2 \sim_G t_2, \dots$ then $f(s_1, \dots, s_n) \sim_G f(t_1, \dots, t_n)$.

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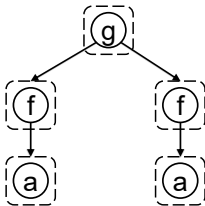
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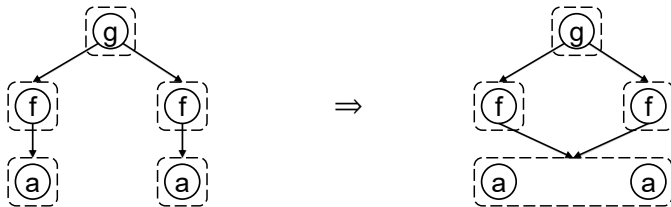
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Congruence closure algorithm: modifies G to ensure that \sim_G is a congruence.

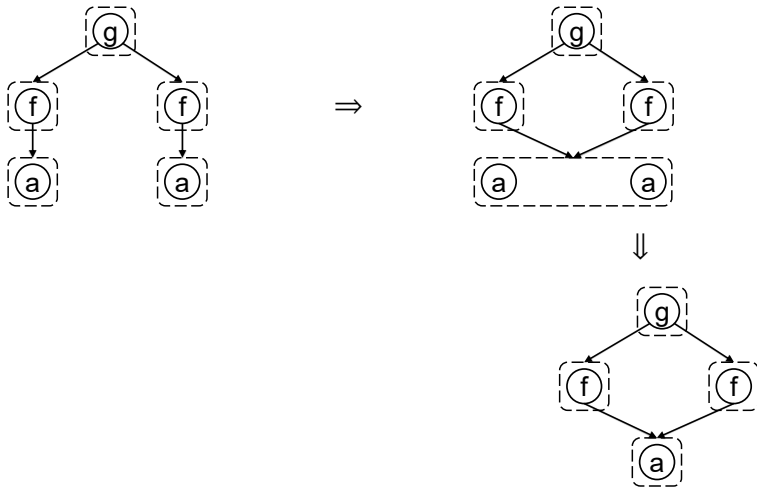
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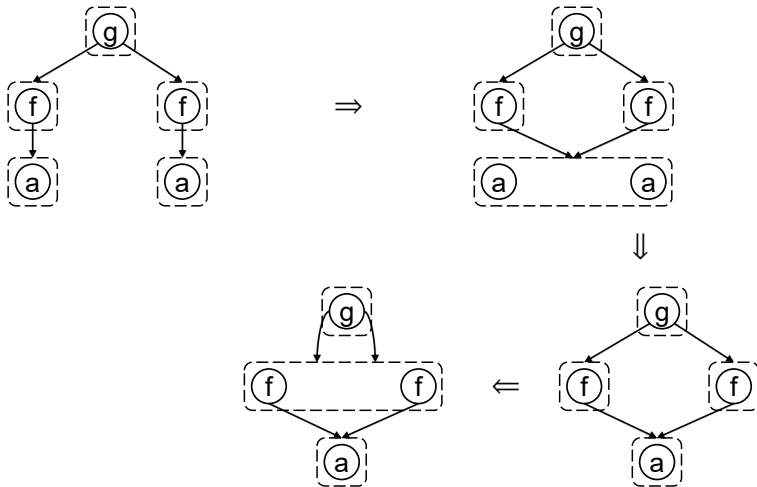


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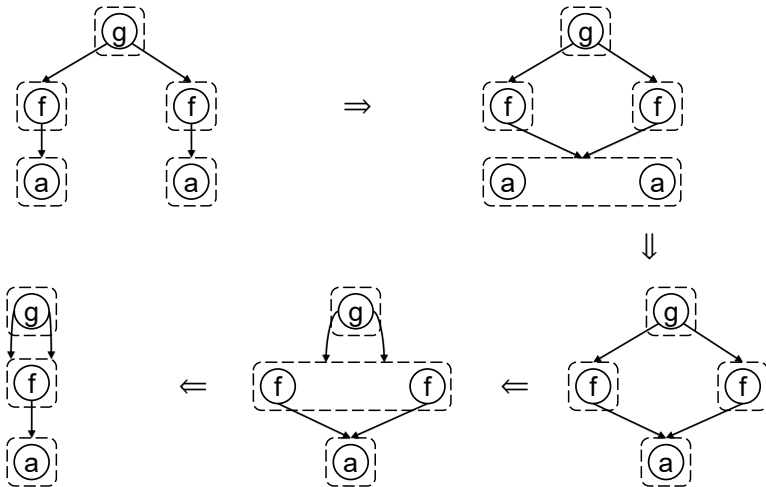
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The Equality Saturation Algorithm for the Word Problem

To check $s \approx_E t$, start with the E-graph encoding s and t .

- Find $(\ell, r) \in E$ such that ℓ “matches” the E-graph.
Meaning: there exists substitution σ , s.t. $\sigma(\ell) \in \text{terms}(G)$.
Notice: identities are directional.

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When (and if!) it terminates, check $s \sim_G t$.

Example from [Baader and Nipkow, 1999]

$$E = \boxed{g(x) \approx f(f(x))}$$

$$\text{Check if } \boxed{g(f(a)) \approx f(g(a))}$$

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$$E = \begin{array}{l} g(x) \approx f(f(x)) \\ f(f(x)) \approx g(x) \end{array}$$

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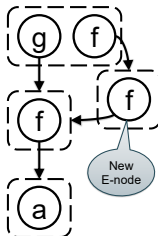
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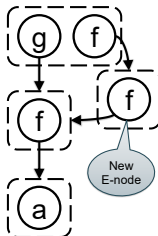
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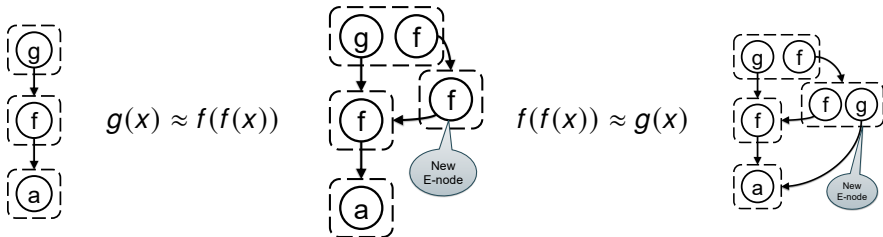


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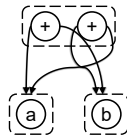
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Discussion

E-graphs can avoid some non-terminating reductions:
E.g. commutativity:



Non-termination can still happen, e.g. $g(x) \approx g(f(x))$:
Leads to $g(a) \approx g(f(a)) \approx g(f(f(a))) \approx \dots$

Direction of the identities in E may affect termination: e.g. $g(f(x)) \approx g(x)$.

No good theory exists for understanding termination.

Special Case: Grounded Identities

Theorem if all identities in E are grounded, then equality saturation terminates, and the ground word problem is decidable.

Proof: start with the E-graph consisting of s , t , and all terms in E .

Then we never need to insert a new nodes in G , hence the congruence closure algorithm terminates.

Example from [Baader and Nipkow, 1999]

$$E = \begin{cases} f(f(a)) \approx a \\ f(f(f(a))) \approx a \end{cases}$$

Check if $f(a) \approx_E a$

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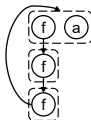
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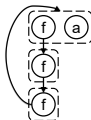
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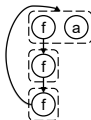
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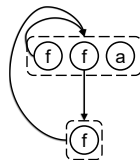
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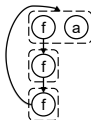
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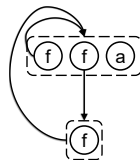
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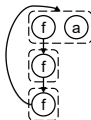
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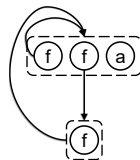
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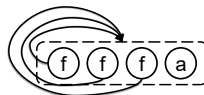
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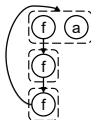
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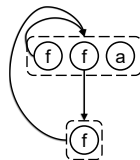
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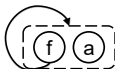
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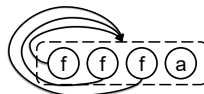


$$f(f(a)) \approx a$$



$$f(f(f(a))) \approx a$$



$$\Leftarrow$$


Discussion

The extensible query optimizers Volcano and Cascades are essentially E-graphs on steroids.

However, they come with their specialized terminology, and with heavy engineering.

Will discuss them in the next lecture(s), and refer to TRS and E-graphs.



Baader, F. and Nipkow, T. (1999).

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