

## Case Study 4: Collaborative Filtering

### Probabilistic Models for Matrix Factorization

### Cold-Start Problem

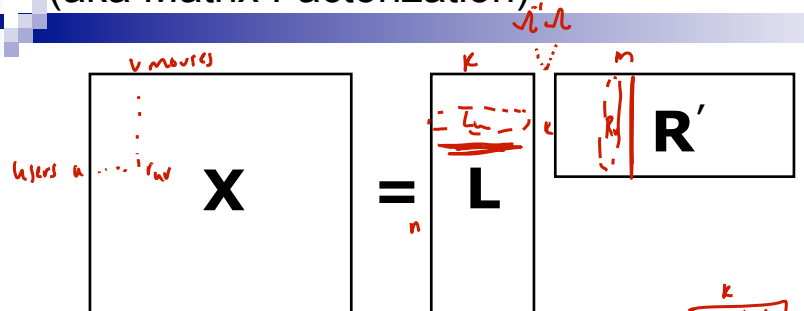
Machine Learning/Statistics for Big Data  
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## Interpreting Low-Rank Matrix Completion (aka Matrix Factorization)



$$r_{uv} \approx L_{u \cdot} \cdot R'_{\cdot v}$$

$$L_{u \cdot} = [l_{u1} \dots l_{uk}]$$

$$R'_{\cdot v} = [r_{1v} \dots r_{kv}]$$

movie topic  $i$  "action"  
↑  
how much user  $u$  likes movie topic  $i$

↑  
how much movie  $v$  is about topic  $i$

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# Stochastic Gradient Descent

$$\min_{L,R} F(L,R) = \frac{1}{2} \sum_{r_{uv}} (L_u \cdot R_v - r_{uv})^2 + \frac{\lambda_u}{2} \|L\|_F^2 + \frac{\lambda_v}{2} \|R\|_F^2$$

$\sum_u L_u \cdot L_u$

- Observe one rating at a time  $r_{uv}^t$   $\epsilon_t = L_u^{(t)} \cdot R_v^{(t)} - r_{uv}$

- Gradient observing  $r_{uv}$ :

$$\left. \begin{aligned} \frac{\partial F}{\partial L_u} &= \epsilon_t R_v + \lambda_u L_u \\ \frac{\partial F}{\partial R_v} &= \epsilon_t L_u + \lambda_v R_v \end{aligned} \right\} \nabla F_t = \begin{bmatrix} \epsilon_t R_v + \lambda_u L_u \\ \epsilon_t L_u + \lambda_v R_v \end{bmatrix}$$

- Updates:  $\text{step size } \eta_t, \begin{bmatrix} L \\ R \end{bmatrix} \leftarrow \begin{bmatrix} L \\ R \end{bmatrix} - \eta_t \nabla F_t$

$$\begin{bmatrix} L_u^{(t+1)} \\ R_v^{(t+1)} \end{bmatrix} \leftarrow \begin{bmatrix} (1 - \eta_t \lambda_u) L_u^{(t)} - \eta_t \epsilon_t R_v^{(t)} \\ (1 - \eta_t \lambda_v) R_v^{(t)} - \eta_t \epsilon_t L_u^{(t)} \end{bmatrix}$$

fast & easy to implement

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# What's Matrix Factorization Optimizing???

- A generative process:
  - Pick user factors
  - Pick movie factors
  - For each (user,movie) pair observed:
    - Pick rating as  $L_u R_v + \text{noise}$

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# Maximum A Posteriori for Matrix Completion

$$P(L, R|X) \propto P(L, R, X)$$

$$\propto e^{-\frac{1}{2\sigma_u^2} \sum_{u=1}^n \sum_{i=1}^k L_{ui}^2} e^{-\frac{1}{2\sigma_v^2} \sum_{v=1}^m \sum_{i=1}^k R_{vi}^2} e^{-\frac{1}{2\sigma_r^2} \sum_{r_{uv}} (L_u \cdot R_v - r_{uv})^2}$$

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# MAP versus Regularized Least-Squares for Matrix Completion

- MAP under Gaussian Model:

$$P(L, R|X) \propto P(L, R, X)$$

$$\propto e^{-\frac{1}{2\sigma_u^2} \sum_{u=1}^n \sum_{i=1}^k L_{ui}^2} e^{-\frac{1}{2\sigma_v^2} \sum_{v=1}^m \sum_{i=1}^k R_{vi}^2} e^{-\frac{1}{2\sigma_r^2} \sum_{r_{uv}} (L_u \cdot R_v - r_{uv})^2}$$

- Least-squares matrix completion with  $L_2$  regularization:

$$\min_{L, R} \frac{1}{2} \sum_{r_{uv}} (L_u \cdot R_v - r_{uv})^2 + \frac{\lambda_u}{2} \|L\|_F^2 + \frac{\lambda_v}{2} \|R\|_F^2$$

- Understanding as a probabilistic models is very useful! E.g.,
  - Change priors
  - Incorporate other sources of information or dependencies

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# Cold-Start Problem

- **Challenge:** Cold-start problem (new movie or user)
- **Methods:** use features of movie/user

$\phi(\text{Skyfall}) = \begin{pmatrix} \text{action} \\ \text{romance} \\ \vdots \\ 7 \\ 2 \\ 0 \\ \vdots \end{pmatrix}$

$\phi(\text{FRWL}) = \begin{pmatrix} 8 \\ 1 \\ \vdots \end{pmatrix}$

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# Cold-Start More Formally

- No observations about a particular user:

$$\min_{L,R} \frac{1}{2} \sum_{r_{uv}} (L_u \cdot R_v - r_{uv})^2 + \frac{\lambda_u}{2} \|L\|_F^2 + \frac{\lambda_v}{2} \|R\|_F^2$$

- A simpler model for collaborative filtering:

- Observe ratings:
- Given features of a movie:
- Fit linear model:
- Minimize:

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# Personalization

- If we don't have any observations about a user, use wisdom of the crowd
  - Address cold-start problem
- But, as we gain more information about the user, forget the crowd:
- Graphically:

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# User Features...

- In addition to movie features, may have information user:
- Combine with features of movie:
- Unified linear model:

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## Feature-based Approach versus Matrix Factorization

- Feature-based approach:
  - Feature representation of user and movies fixed
  - Can address cold-start
  
- Matrix factorization approach:
  - Suffers from cold-start problem
  - User & movie features are learned from data
  
- Unified model:

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## MAP for Unified Collaborative Filtering via SGD

$$\min_{L, R, w, \{w_u\}_u} \frac{1}{2} \sum_{r_{uv}} (L_u \cdot R_v + (w + w_u) \cdot \phi(u, v) - r_{uv})^2 + \frac{\lambda_u}{2} \|L\|_F^2 + \frac{\lambda_v}{2} \|R\|_F^2 + \frac{\lambda_w}{2} \|w\|_2^2 + \frac{\lambda_{wu}}{2} \sum_u \|w_u\|_2^2$$

- Gradient step observing  $r_{uv}$ 
  - For L,R 
$$\begin{bmatrix} L_u^{(t+1)} \\ R_v^{(t+1)} \end{bmatrix} \leftarrow \begin{bmatrix} (1 - \eta_t \lambda_u) L_u^{(t)} - \eta_t \epsilon_t R_v^{(t)} \\ (1 - \eta_t \lambda_v) R_v^{(t)} - \eta_t \epsilon_t L_u^{(t)} \end{bmatrix}$$
  - For w and  $w_u$ :

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## What you need to know...

- Probabilistic model for collaborative filtering
  - Models, choice of priors
  - MAP equivalent to optimization for matrix completion
  
- Cold-start problem
  
- Feature-based methods for collaborative filtering
  - Help address cold-start problem
  
- Unified approach