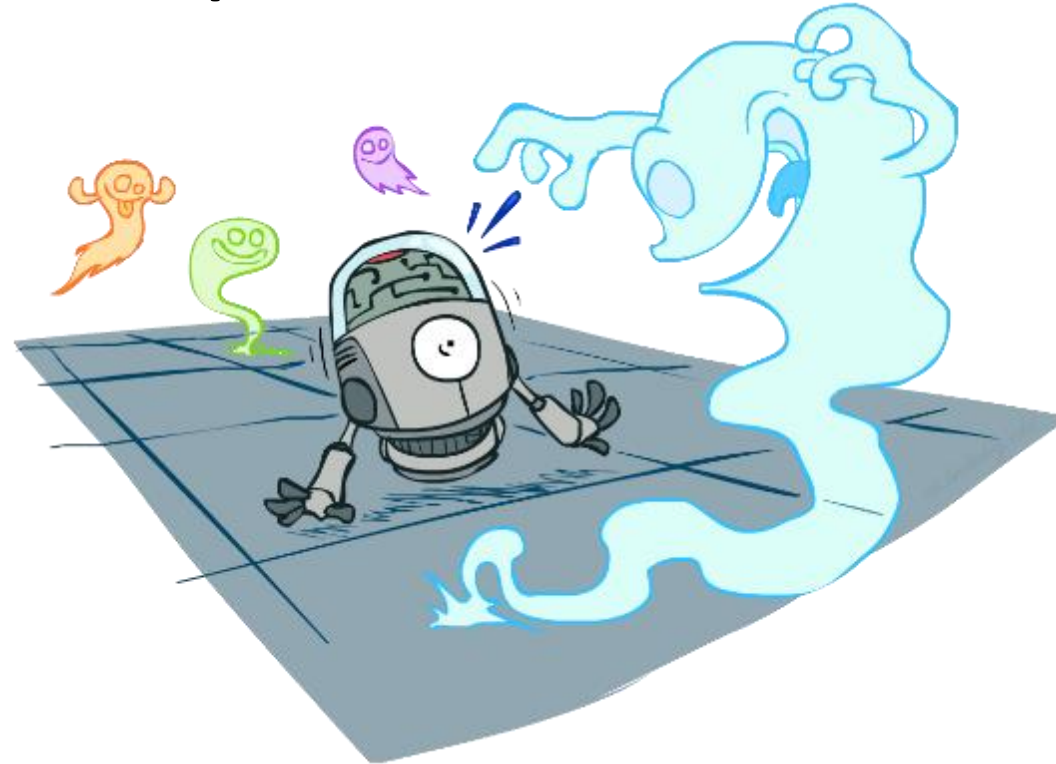


CSE 573: Artificial Intelligence

Graphical Models

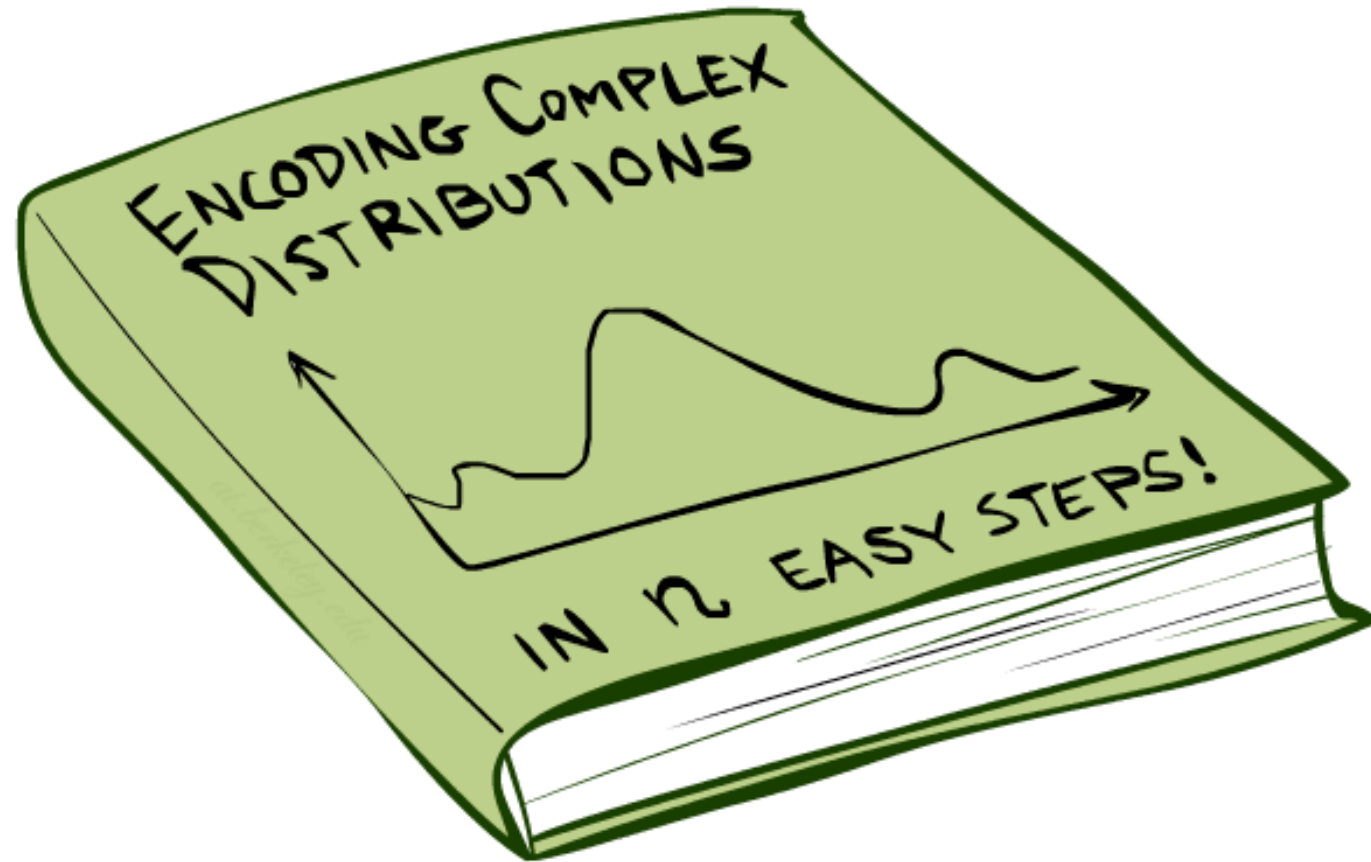


slides adapted from
Stuart Russel, Dan Klein, Pieter Abbeel from ai.berkeley.edu
And Hanna Hajishirzi, Dan Weld, Luke Zettlemoyer

Reminder: elementary probability

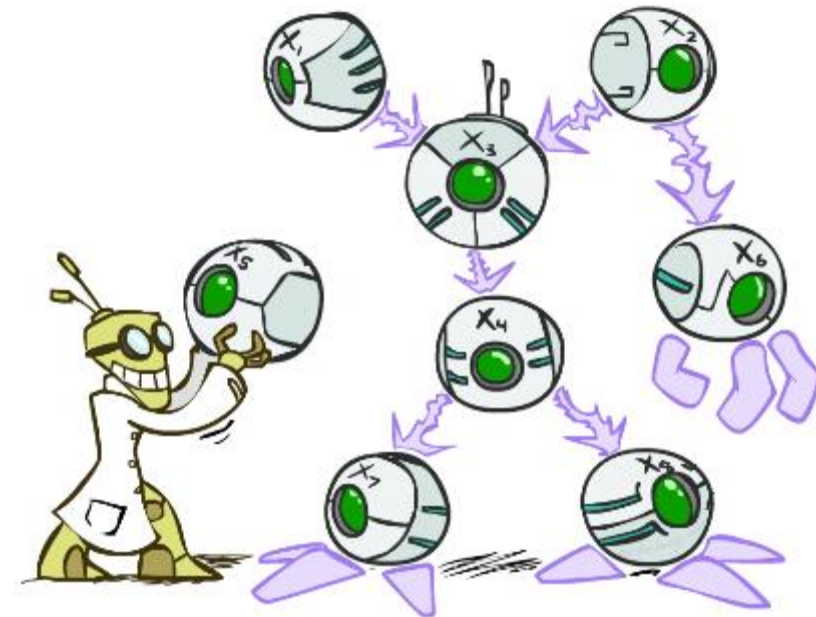
- Basic laws: $0 \leq P(\omega) \leq 1$ $\sum_{\omega \in \Omega} P(\omega) = 1$
- Events: subsets of Ω : $P(A) = \sum_{\omega \in A} P(\omega)$
- Random variable $X(\omega)$ has a value in each ω
 - Distribution $P(X)$ gives probability for each possible value x
 - Joint distribution $P(X, Y)$ gives total probability for each combination x, y
- Summing out/marginalization: $P(X=x) = \sum_y P(X=x, Y=y)$
- Conditional probability: $P(X|Y) = P(X, Y)/P(Y)$
- Product rule: $P(X|Y)P(Y) = P(X, Y) = P(Y|X)P(X)$
 - Generalize to chain rule: $P(X_1, \dots, X_n) = \prod_i P(X_i | X_1, \dots, X_{i-1})$

Bayes' Nets: Big Picture



Bayes Nets: Big Picture

- **Bayes nets:** a technique for describing complex joint distributions (models) using simple, conditional distributions
 - A subset of the general class of **graphical models**
 - Also called belief networks
- Use local causality/conditional independence:
 - the world is composed of many variables,
 - each interacting locally with a few others



Bayes Nets

Part I: Representation

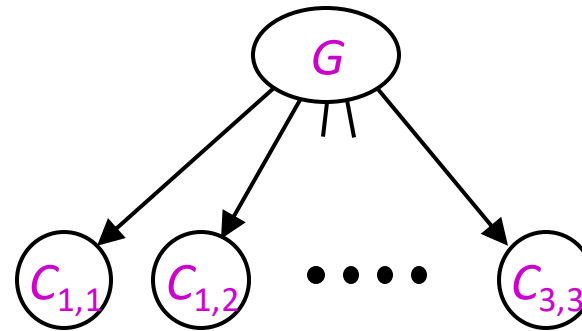
Part II: Independence


Part III: Exact inference

Part IV: Approximate Inference

Graphical Model Notation

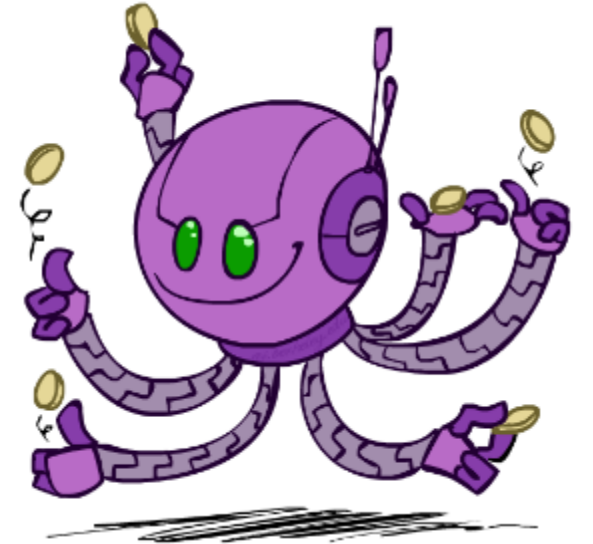
- **Nodes: variables (with domains)**
 - Can be assigned (observed) or unassigned (unobserved)
- **Arcs: interactions**
 - Indicate “direct influence” between variables
 - Formally: encode conditional independence (more on this later)



| | | |
|------|---|------|
| 0.11 |  | 0.11 |
| 0.11 | 0.11 | 0.11 |
| 0.11 | 0.11 | 0.11 |

Example Bayes' Net: Coin Flips

- N independent coin flips



- No interactions between variables: absolute independence

Conditional Independence: Traffic

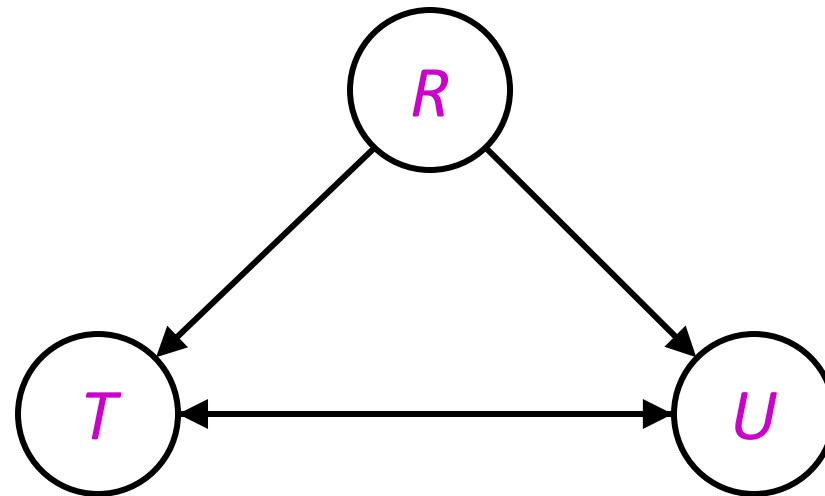
- What about this domain:
 - Traffic
 - Umbrella
 - Raining



Example Bayes' Net: Traffic

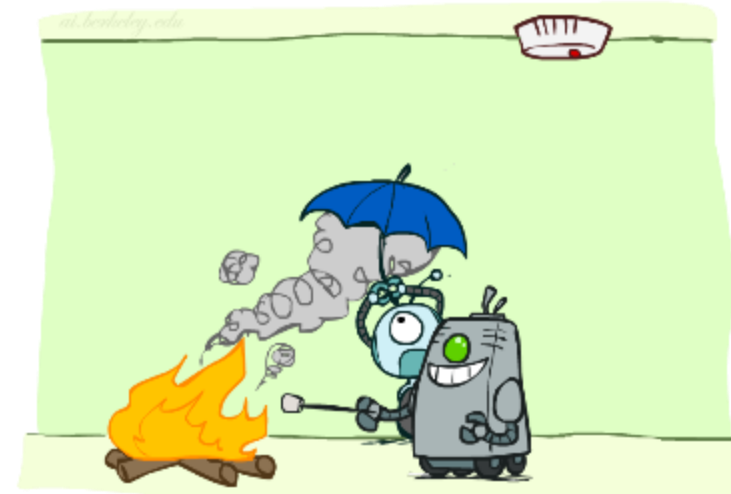
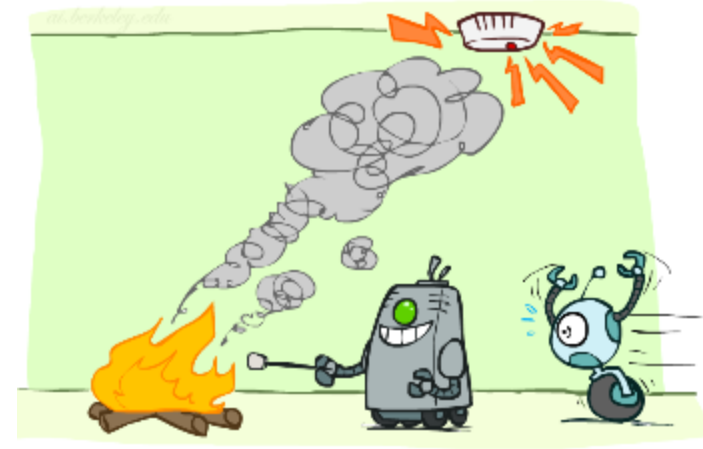
- Variables:

- T: There is traffic
- U: I'm holding my umbrella
- R: It rains



Conditional Independence: Fire

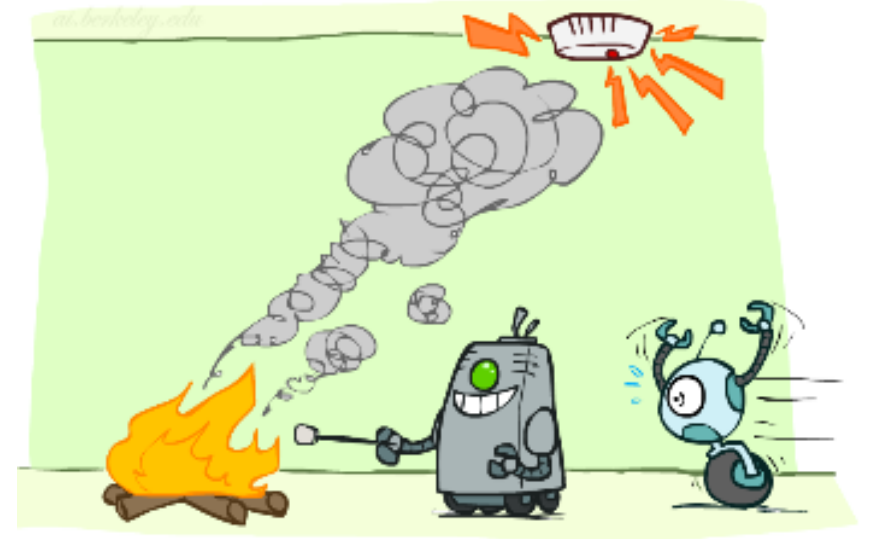
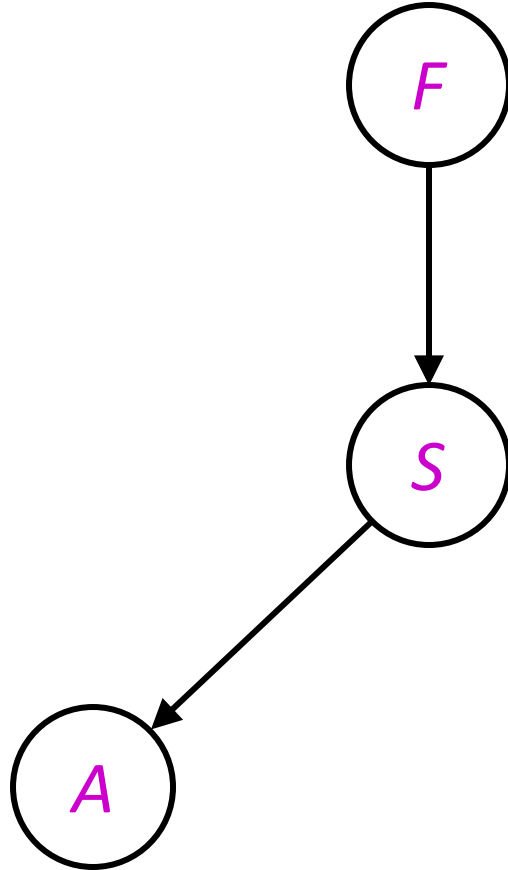
- What about this domain:
 - Fire
 - Smoke
 - Alarm



Example Bayes' Net: Smoke alarm

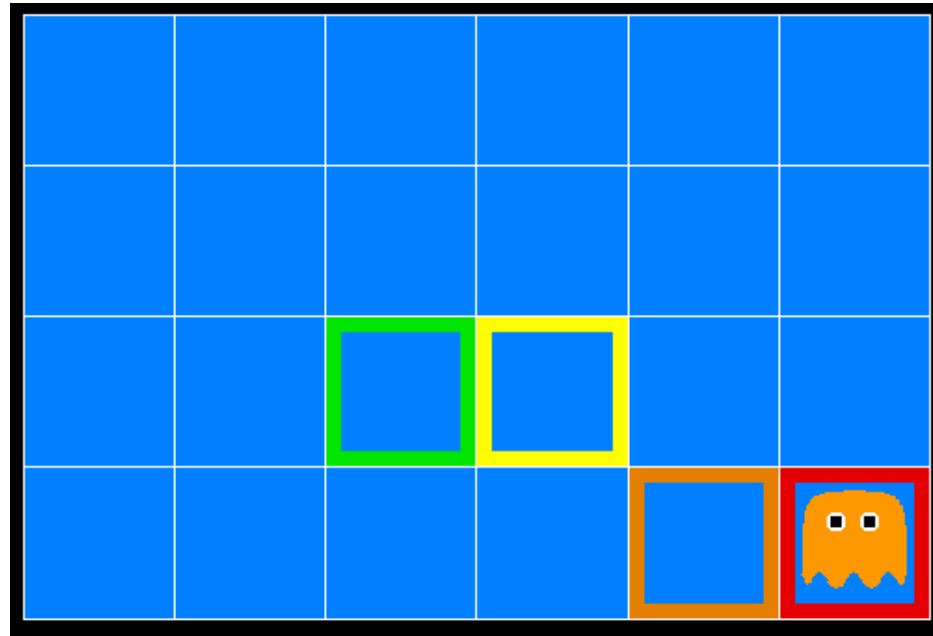
- Variables:

- F: There is fire
- S: There is smoke
- A: Alarm sounds

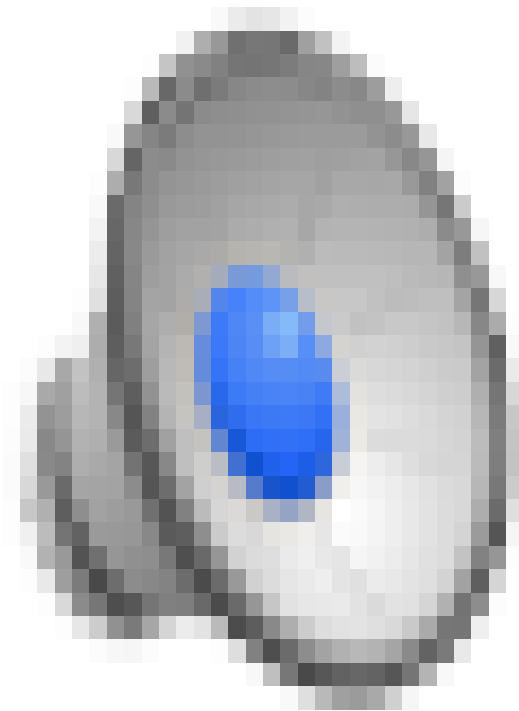


Why do conditional independence?-- Ghostbusters

- A ghost is in the grid somewhere
- Sensor readings tell how close a square is to the ghost
 - On the ghost: usually red
 - 1 or 2 away: mostly orange
 - 3 or 4 away: typically yellow
 - 5+ away: often green
- Click on squares until confident of location, then "*bust*"



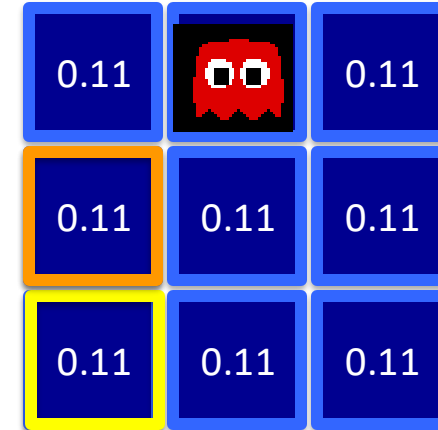
Video of Demo Ghostbusters with Probability



$P(\text{ghost is in this position given all of the evidence that we have seen so far})$

Ghostbusters model

- $P(G, C_{1,1}, \dots, C_{3,3})$ has ...
 - $9 \times 4^9 = 2,359,296$ entries!
 - $|G| = 9$, $|C_{i,j}| = 4$; Grid squares times size of each
- Ghostbuster independence:
 - Are $C_{1,1}$ and $C_{1,2}$ independent?
 - E.g., does $P(C_{1,1} = \text{yellow}) = P(C_{1,1} = \text{yellow} \mid C_{1,2} = \text{orange})$?
- Ghostbuster physics again:
 - $P(C_{x,y} \mid G)$ **depends only on distance to G**
 - So $P(C_{1,1} = \text{yellow} \mid \underline{G = (2,3)}) = P(C_{1,1} = \text{yellow} \mid \underline{G = (2,3)}, C_{1,2} = \text{orange})$
 - I.e., $C_{1,1}$ is **conditionally independent** of $C_{1,2}$ **given G**



Ghostbusters model, contd.

- Apply the chain rule to decompose the joint probability model:

$$P(G, C_{1,1}, \dots, C_{3,3}) = P(G) P(C_{1,1} | G) P(C_{1,2} | G, C_{1,1}) P(C_{1,3} | G, C_{1,1}, C_{1,2}) \dots P(C_{3,3} | G, C_{1,1}, \dots, C_{3,2})$$

- Now simplify using conditional independence:

$$P(G, C_{1,1}, \dots, C_{3,3}) = P(G) P(C_{1,1} | G) P(C_{1,2} | G) P(C_{1,3} | G) \dots P(C_{3,3} | G)$$

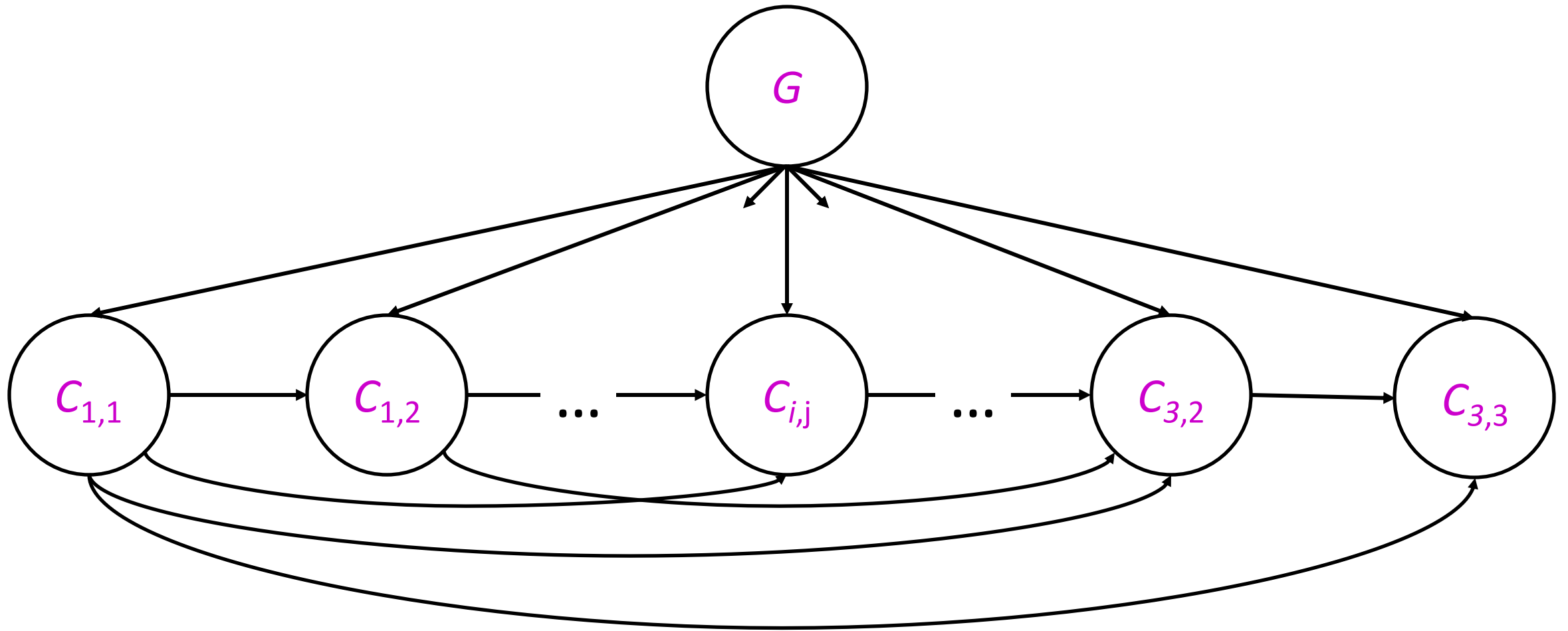
- I.e., conditional independence properties of ghostbuster physics simplify the probability model from **exponential** to **quadratic** in the number of squares

- $|P(C_{i,j} | G)| = 4 \times 9$ rather than $|P(C_{3,3} | G, C_{1,1}, \dots, C_{3,2})| = 4 \times 9 \times 4^8$
- In total: $9 + 9 \times (4 \times 9) = 333$ entries, before was $9 \times 4^9 = 2,359,296$ entries

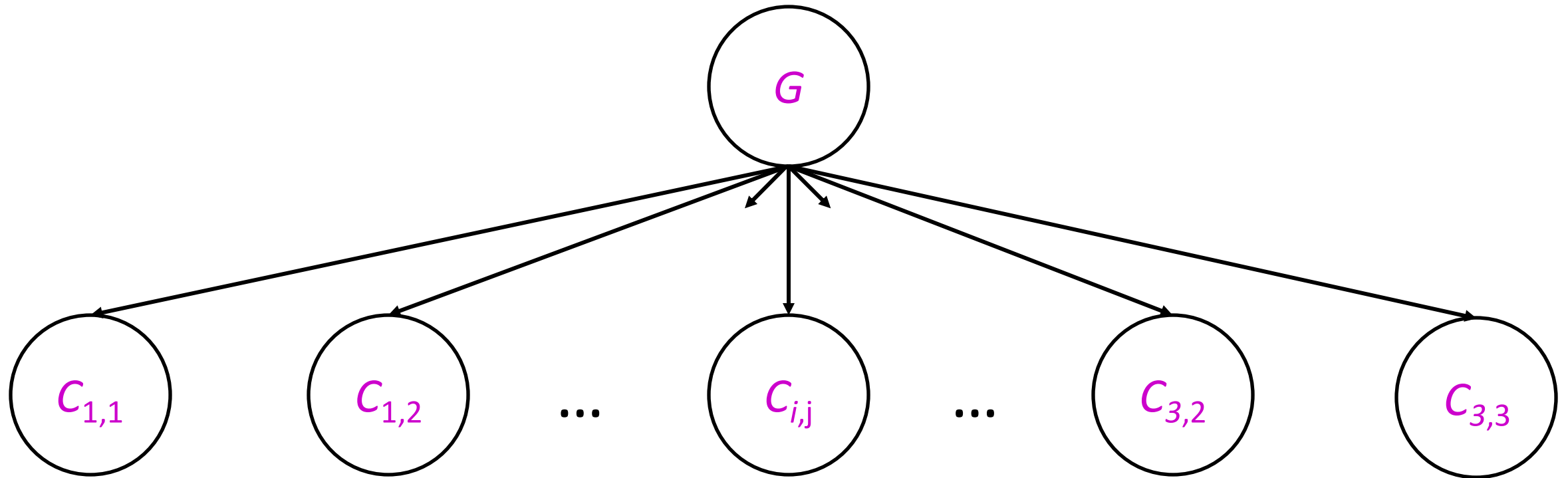
- This is called a **Naïve Bayes** model:

- One discrete query variable (often called the **class** or **category** variable)
- All other variables are (potentially) evidence variables
- Evidence variables are all conditionally independent given the query variable

Ghostbusters Full Joint



Ghostbusters Naïve Bayes



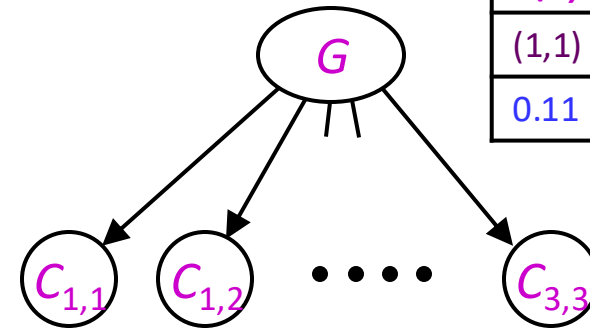
Bayes Net Syntax and Semantics



Bayes' Net Syntax



- A set of nodes, one per variable X_i
- A directed, acyclic graph
- A conditional distribution for each node given its **parent variables** in the graph
 - **CPT** (conditional probability table)
each row is a distribution for child given values of its parents

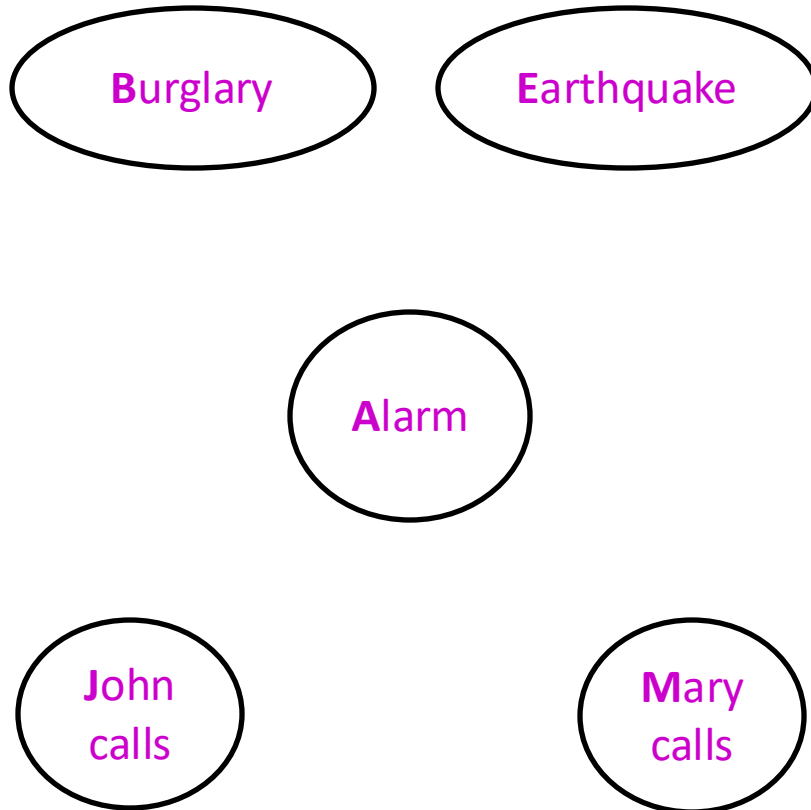


| P(G) | | | |
|-------|-------|-------|-----|
| (1,1) | (1,2) | (1,3) | ... |
| 0.11 | 0.11 | 0.11 | ... |

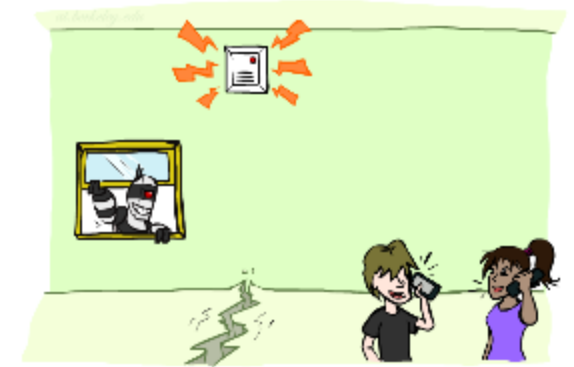
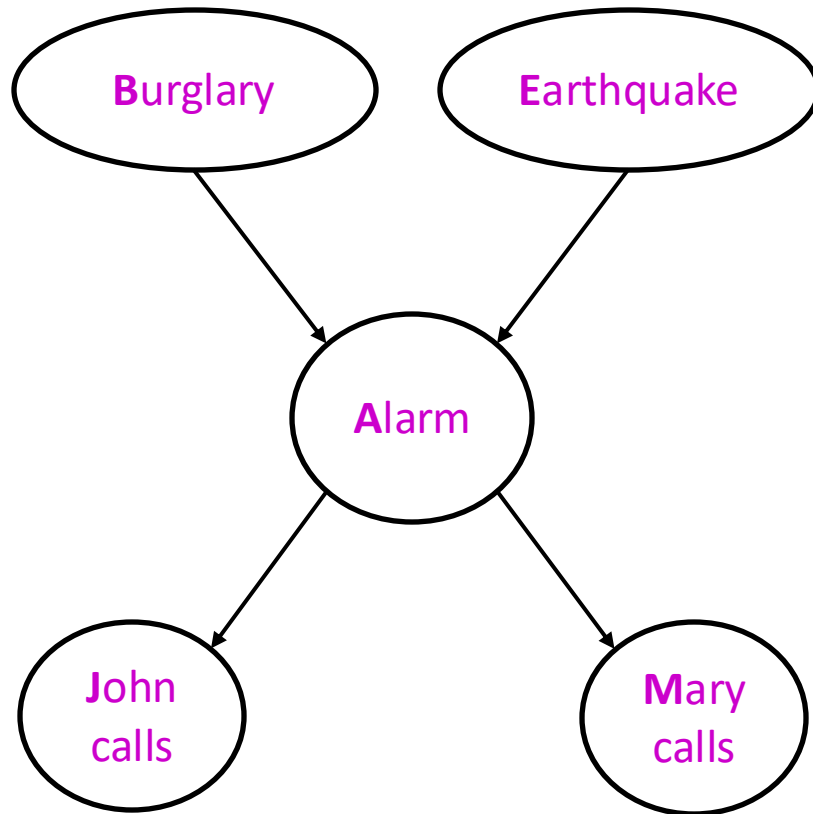
| G | P(C _{1,1} G) | | | |
|-------|-------------------------|-----|------|------|
| | g | y | o | r |
| (1,1) | 0.01 | 0.1 | 0.3 | 0.59 |
| (1,2) | 0.1 | 0.3 | 0.5 | 0.1 |
| (1,3) | 0.3 | 0.5 | 0.19 | 0.01 |
| ... | | | | |

Bayes net = Topology (graph) + Local Conditional Probabilities

Example: Alarm Network



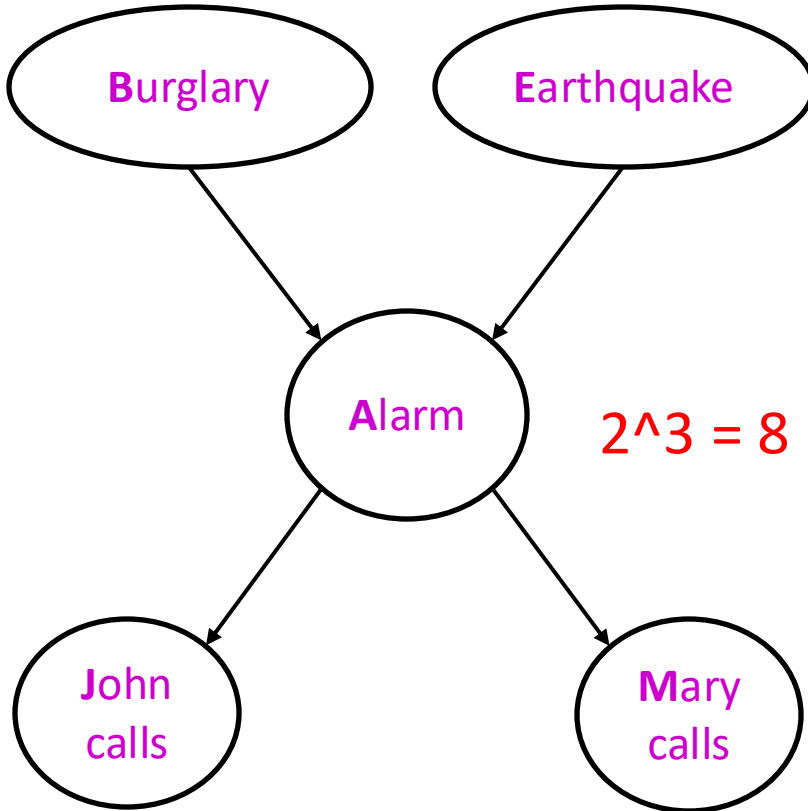
Example: Alarm Network



Example: Alarm Network

| P(B) | |
|-------|-------|
| true | false |
| 0.001 | 0.999 |

2



2

| P(E) | |
|-------|-------|
| true | false |
| 0.002 | 0.998 |

| B | E | P(A B,E) | |
|-------|-------|----------|-------|
| | | true | false |
| true | true | 0.95 | 0.05 |
| true | false | 0.94 | 0.06 |
| false | true | 0.29 | 0.71 |
| false | false | 0.001 | 0.999 |

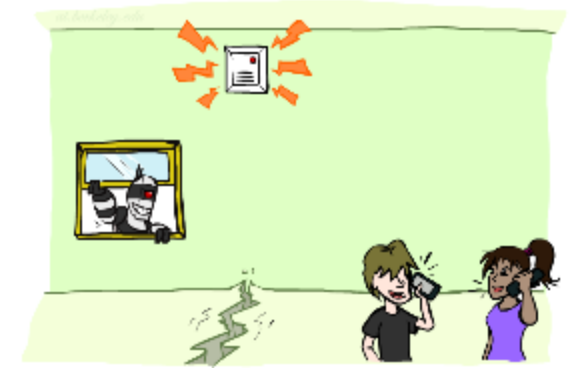
$2^3 = 8$

| A | P(J A) | |
|-------|--------|-------|
| | true | false |
| true | 0.9 | 0.1 |
| false | 0.05 | 0.95 |

$2^2 = 4$

| A | P(M A) | |
|-------|--------|-------|
| | true | false |
| true | 0.7 | 0.3 |
| false | 0.01 | 0.99 |

$2^2 = 4$



Factor size of each CPT:

$$d \prod d_i$$

Parent range sizes: d_1, \dots, d_k

Child range size: d

Each table row must sum to 1

General formula for sparse BNs

- Suppose
 - n variables
 - Maximum range size is d
 - Maximum number of parents is k
- Full joint distribution has size $O(d^n)$
- Bayes net has size $O(n \cdot d^k)$
 - Linear scaling with n as long as causal structure is local
- Often $O(n \cdot d^k) \ll O(d^n)$

Bayes net global semantics

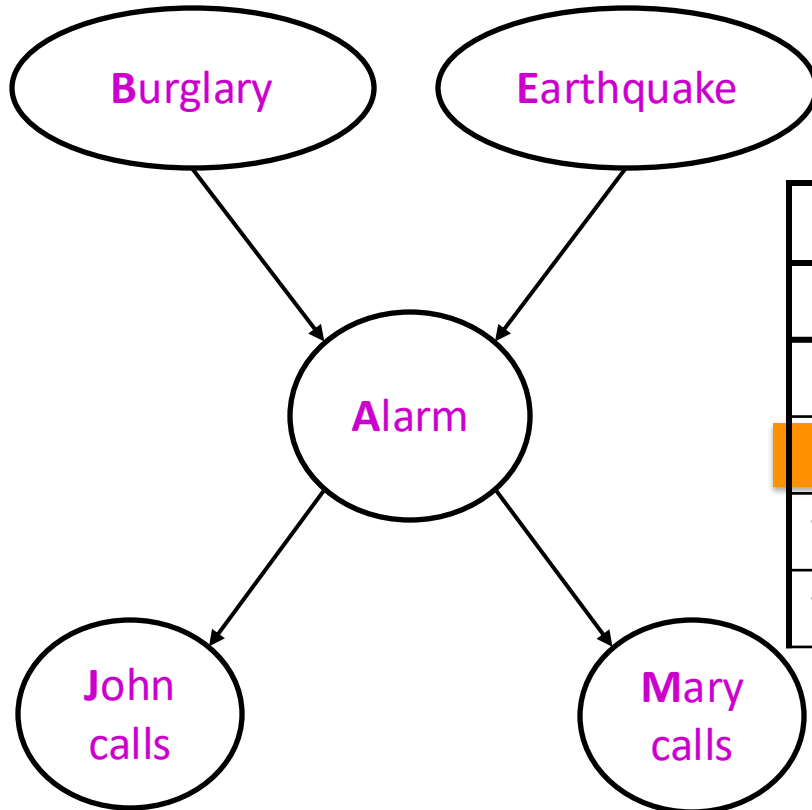


- Bayes nets encode joint distributions as product of conditional distributions on each variable:

$$P(X_1, \dots, X_n) = \prod_i P(X_i \mid \text{Parents}(X_i))$$

Example

| P(B) | |
|-------|-------|
| true | false |
| 0.001 | 0.999 |



| P(E) | |
|-------|-------|
| true | false |
| 0.002 | 0.998 |

| B | E | P(A B,E) | |
|-------|-------|----------|-------|
| | | true | false |
| true | true | 0.95 | 0.05 |
| true | false | 0.94 | 0.06 |
| false | true | 0.29 | 0.71 |
| false | false | 0.001 | 0.999 |

$$P(b, \neg e, a, \neg j, \neg m) =$$

$$P(b) P(\neg e) P(a|b, \neg e) P(\neg j|a) P(\neg m|a)$$

$$= .001 \times .998 \times .94 \times .1 \times .3$$

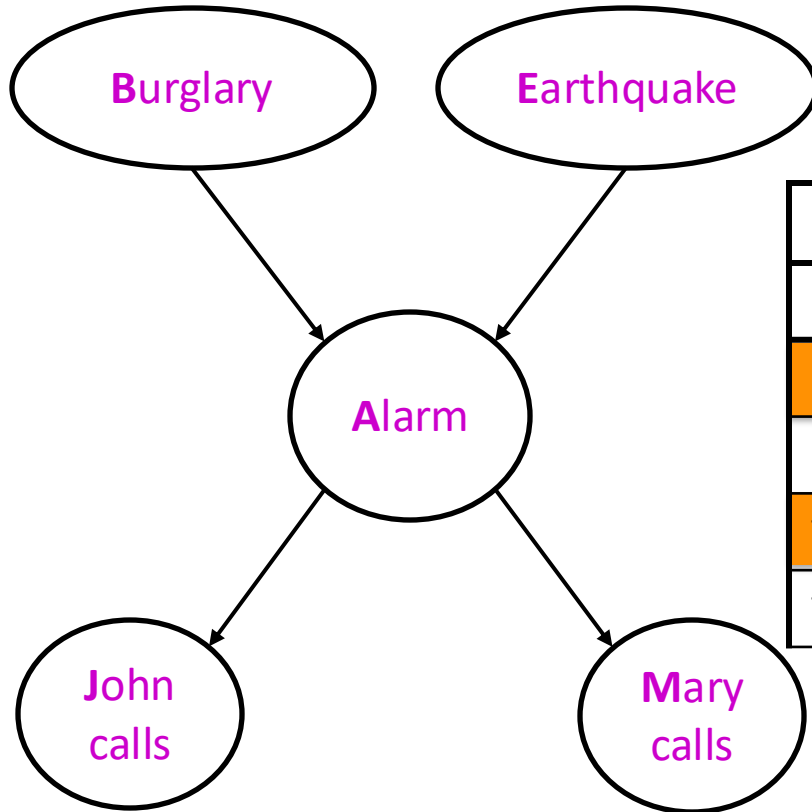
$$= .000028$$

| A | P(J A) | |
|-------|--------|-------|
| | true | false |
| true | 0.9 | 0.1 |
| false | 0.05 | 0.95 |

| A | P(M A) | |
|-------|--------|-------|
| | true | false |
| true | 0.7 | 0.3 |
| false | 0.01 | 0.99 |

Example: Your turn

| P(B) | |
|-------|-------|
| true | false |
| 0.001 | 0.999 |



| P(E) | |
|-------|-------|
| true | false |
| 0.002 | 0.998 |

| B | E | P(A B,E) | |
|-------|-------|----------|-------|
| | | true | false |
| true | true | 0.95 | 0.05 |
| true | false | 0.94 | 0.06 |
| false | true | 0.29 | 0.71 |
| false | false | 0.001 | 0.999 |

$$P(B, e, a, j, m) =$$

$$P(B) P(e) P(a|B,e) P(j|a) P(m|a)$$

$$=<.001, .999> \times .002 \times <.95, .29> \times .9 \times .7$$

$$=<.001 * .002 * .95 * .9 * .7, \\ .999 * .002 * .29 * .9 * .7>$$

$$=<.00000120, .000365>$$

| A | P(J A) | |
|-------|--------|-------|
| | true | false |
| true | 0.9 | 0.1 |
| false | 0.05 | 0.95 |

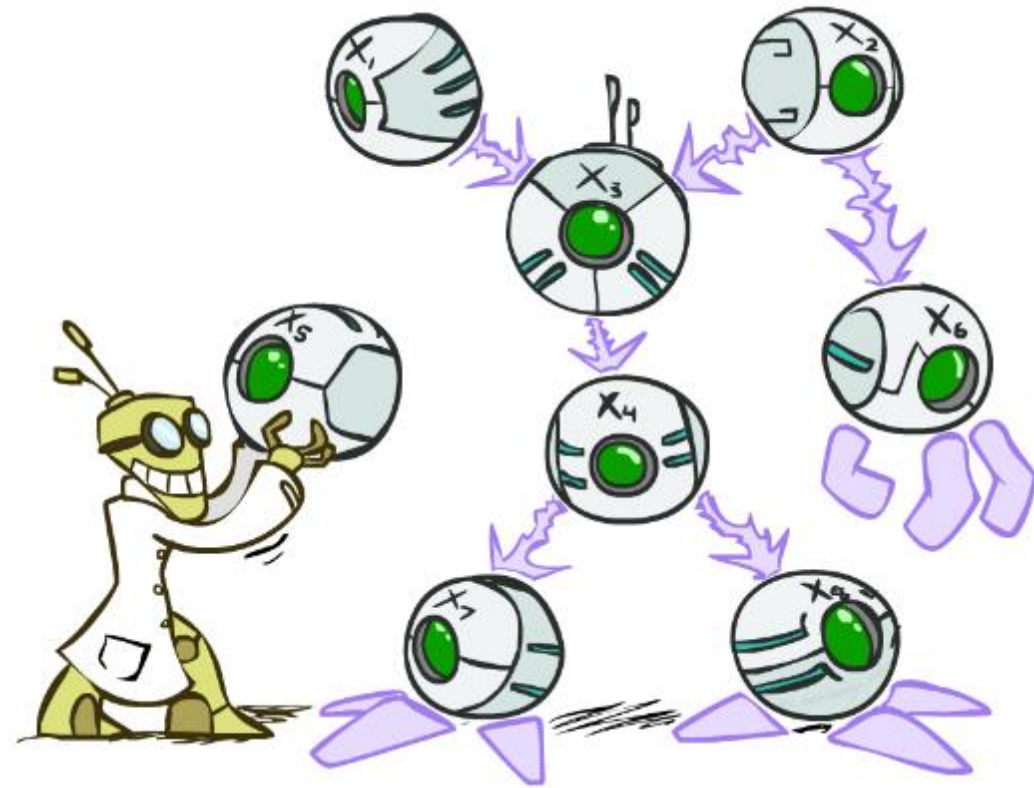
| A | P(M A) | |
|-------|--------|-------|
| | true | false |
| true | 0.7 | 0.3 |
| false | 0.01 | 0.99 |

Question

- Which of the following does a Bayes' net model explicitly?
 - The joint probability distribution?
 - The conditional probability distribution?
- Is one of the following more expressive than the other?
 - The joint probability distribution
 - The conditional probability distribution
- Why do we use Bayes' nets?

Summary

- Independence and conditional independence are important forms of probabilistic knowledge
- Bayes net encode joint distributions efficiently by taking advantage of conditional independence
 - Global joint probability = product of local conditionals
- Next: more on independence
- Then: how to answer queries, i.e., compute conditional probabilities of queries given evidence



Bayes Nets

✓ Part I: Representation

Part II: Independence

Part III: Exact inference

- Enumeration (always exponential complexity)
- Variable elimination (worst-case exponential complexity, often better)
- Inference is NP-hard in general

Part IV: Approximate Inference

Conditional independence in BNs



- Compare the Bayes net global semantics

$$P(X_1, \dots, X_n) = \prod_i P(X_i \mid \text{Parents}(X_i))$$

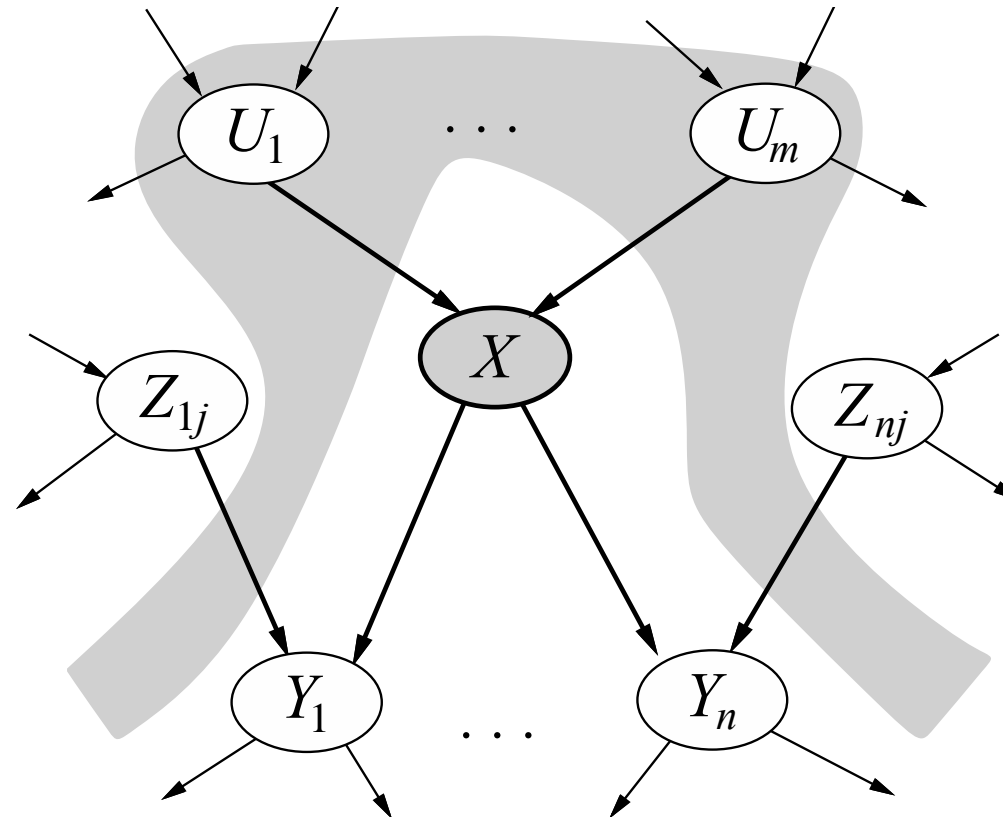
with the chain rule identity

$$P(X_1, \dots, X_n) = \prod_i P(X_i \mid X_1, \dots, X_{i-1})$$

- Assume (without loss of generality) that X_1, \dots, X_n sorted in topological order according to the graph (i.e., parents before children), so $\text{Parents}(X_i) \subseteq X_1, \dots, X_{i-1}$
- So the Bayes net asserts conditional independences $P(X_i \mid X_1, \dots, X_{i-1}) = P(X_i \mid \text{Parents}(X_i))$
 - To ensure these are valid, choose parents for node X_i that “shield” it from other predecessors

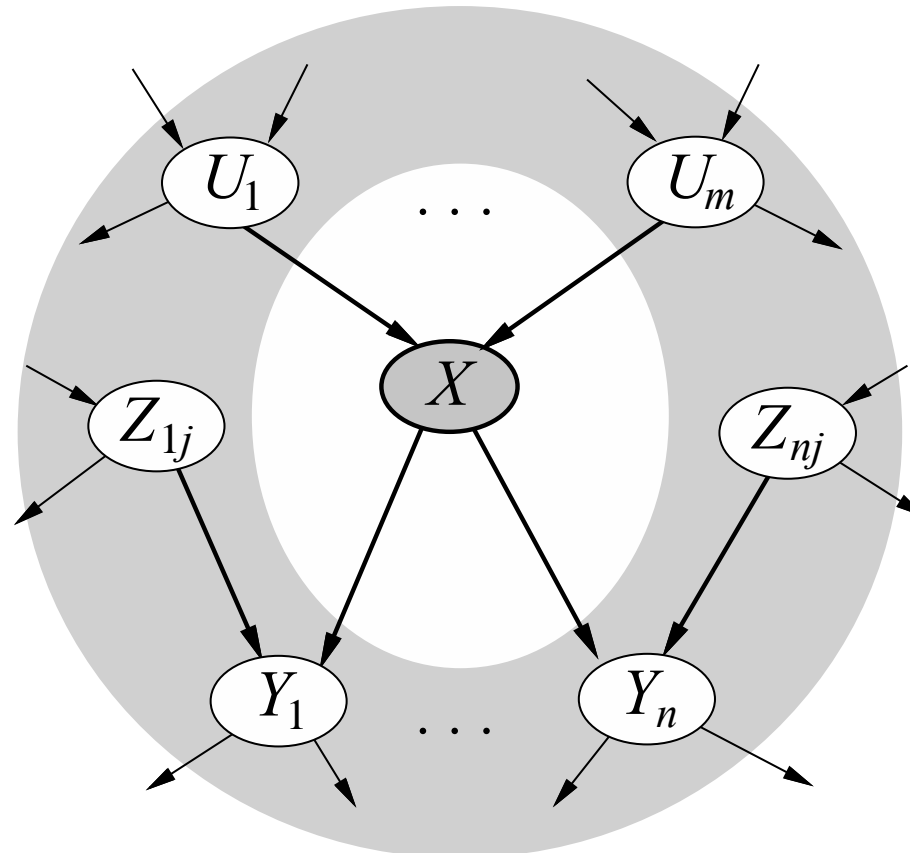
Conditional independence semantics

- *Every variable is conditionally independent of its non-descendants given its parents*
- Conditional independence semantics \Leftrightarrow global semantics



Markov blanket

- A variable's Markov blanket consists of parents, children, children's other parents
- ***Every variable is conditionally independent of all other variables given its Markov blanket***



Reminder: Conditional Independence

- X and Y are **independent** if

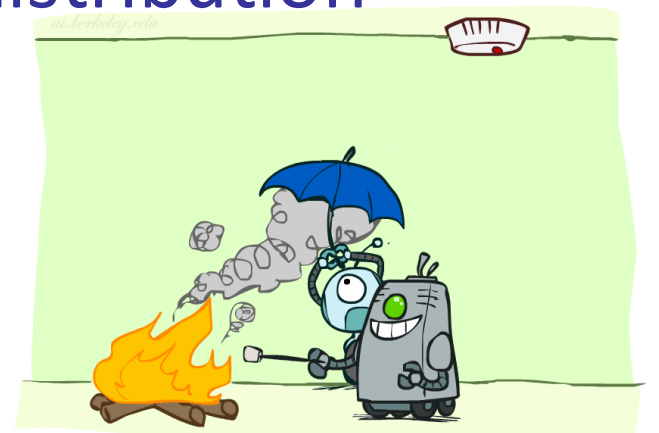
$$\forall x, y \quad P(x, y) = P(x)P(y) \quad \text{---} \rightarrow \quad X \perp Y$$

- X and Y are **conditionally independent** given Z

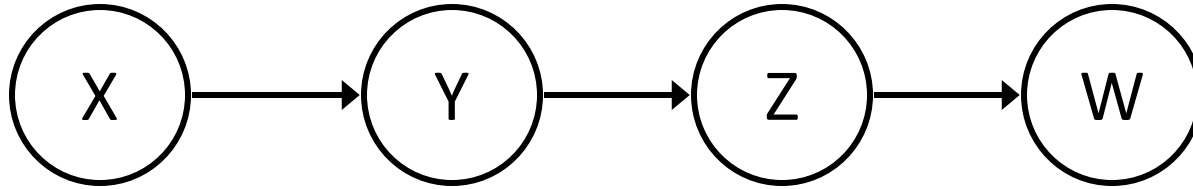
$$\forall x, y, z \quad P(x, y|z) = P(x|z)P(y|z) \quad \text{---} \rightarrow \quad X \perp Y|Z$$

- (Conditional) independence is a property of a distribution

- Example: $Alarm \perp Fire|Smoke$



Example



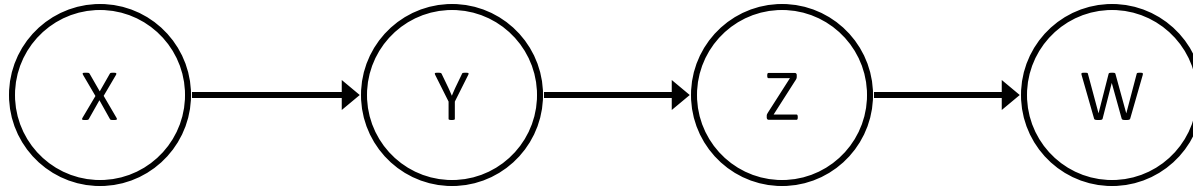
- Conditional independence assumptions directly from simplifications in chain rule:

$$P(x, y, z, w) = P(x)P(y|x)P(z|x, y)P(w|x, y, z)$$

$$P(x, y, z, w) = P(x)P(y|x)P(z|y)P(w|z)$$

- Additional implied conditional independence assumptions?

Example



- Conditional independence assumptions directly from simplifications in chain rule:

$$X \perp\!\!\!\perp Z | Y$$

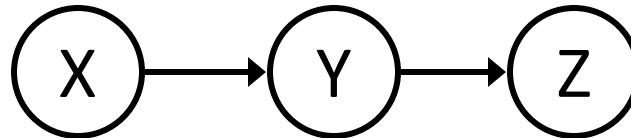
$$W \perp\!\!\!\perp \{X, Y\} | Z$$

- Additional implied conditional independence assumptions?

$$W \perp\!\!\!\perp X | Y$$

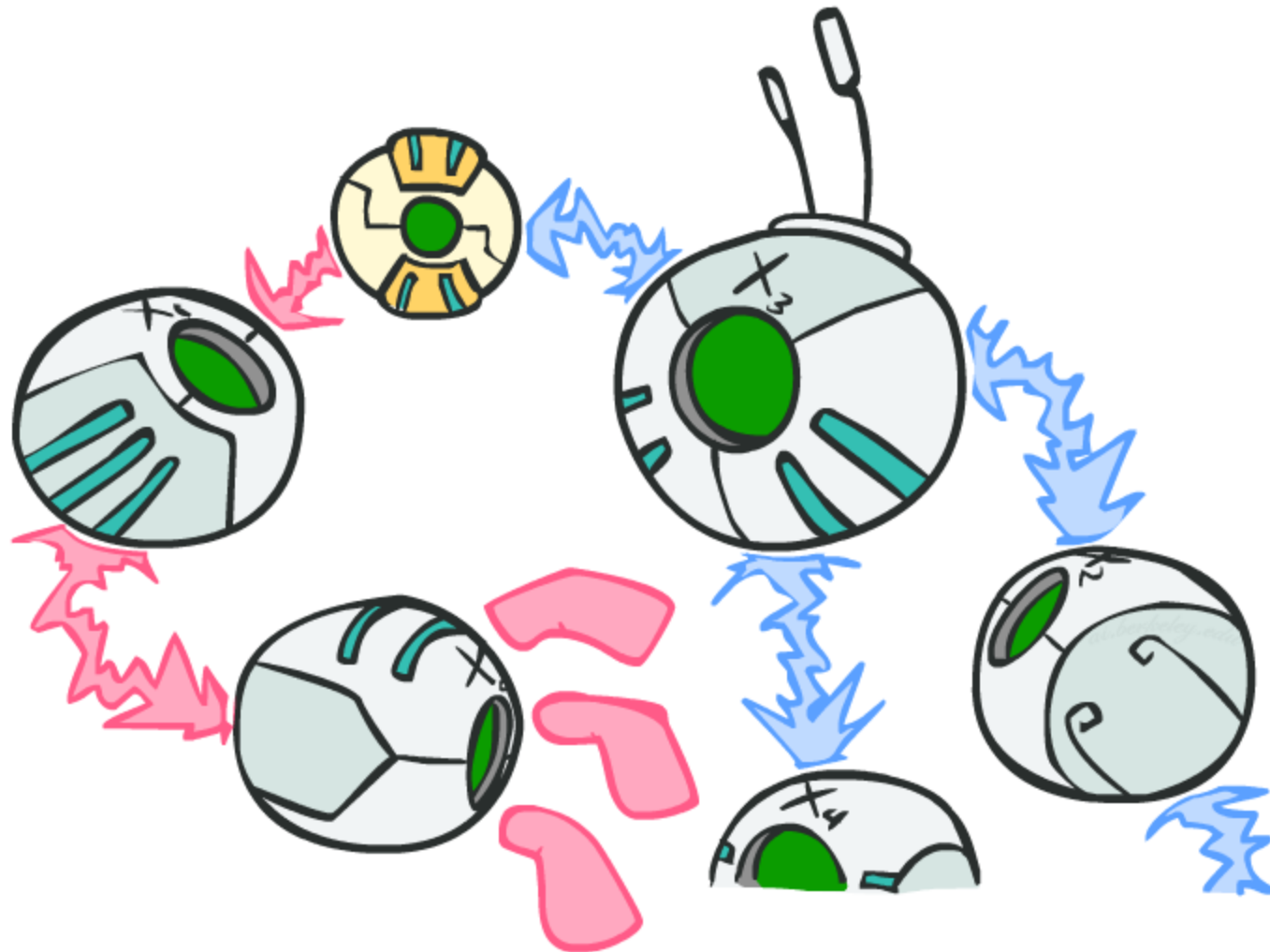
Independence in a Bayes' Net

- Important question about a Bayes' Net:
 - Are two nodes independent given certain evidence?
 - If yes, can prove using algebra (tedious in general)
 - If no, can prove with a counter-example
 - Example:



- Question: are X and Z necessarily independent?
 - Answer: no. Example: low pressure causes rain, which causes traffic.
 - X can influence Z, Z can influence X (via Y)
 - Addendum: they *could* be independent: how?

D-separation: Outline

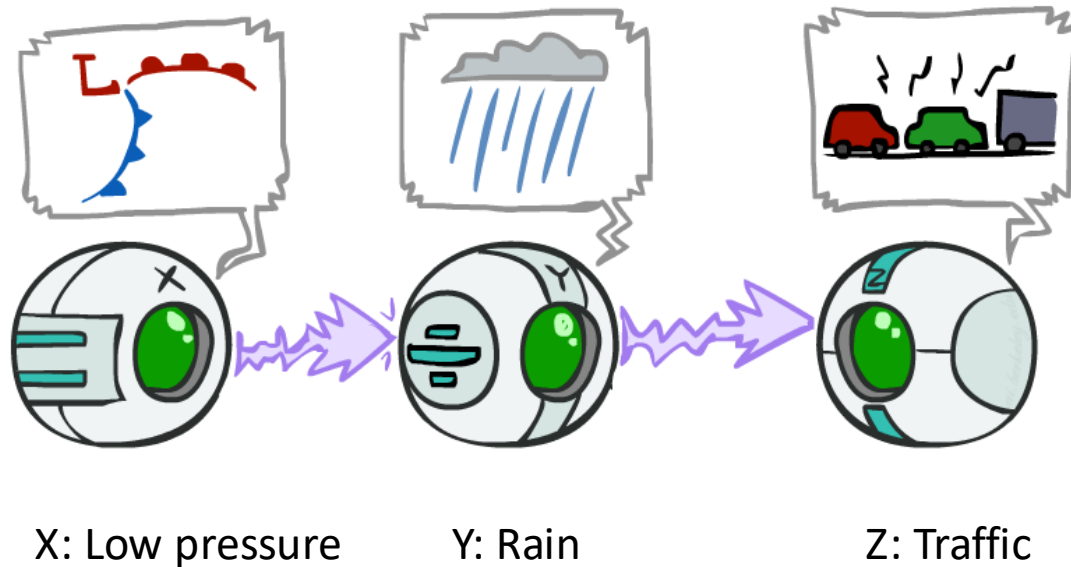


D-separation: Outline

- Study independence properties for triples
 - Why triples?
- Analyze complex cases in terms of member triples
- D-separation: a condition / algorithm for answering such queries

Causal Chains

- This configuration is a “causal chain”



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

- Guaranteed X independent of Z ?
- *No!*

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.

- Example:

- Low pressure causes rain causes traffic, high pressure causes no rain causes no traffic

- In numbers:

$$P(+y \mid +x) = 1, P(-y \mid -x) = 1,$$
$$P(+z \mid +y) = 1, P(-z \mid -y) = 1$$

Causal Chains

- This configuration is a “causal chain”



X: Low pressure

Y: Rain

Z: Traffic

$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

- Guaranteed X independent of Z given Y?

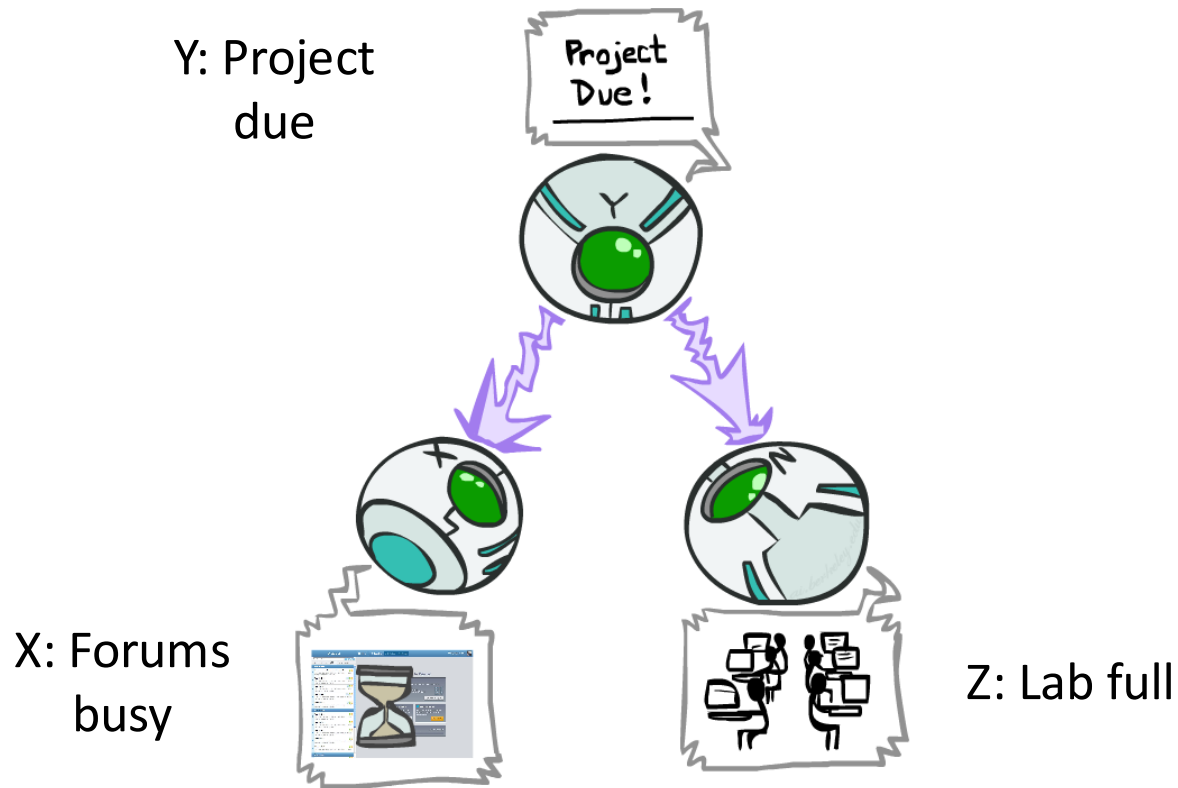
$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(x)P(y|x)P(z|y)}{P(x)P(y|x)} \\ &= P(z|y) \end{aligned}$$

Yes!

- Evidence along the chain “blocks” the influence

Common Causes

- This configuration is a “common cause”



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

- Guaranteed X independent of Z ?
- **No!**

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.

- Example:

- Project due causes both forums busy and lab full

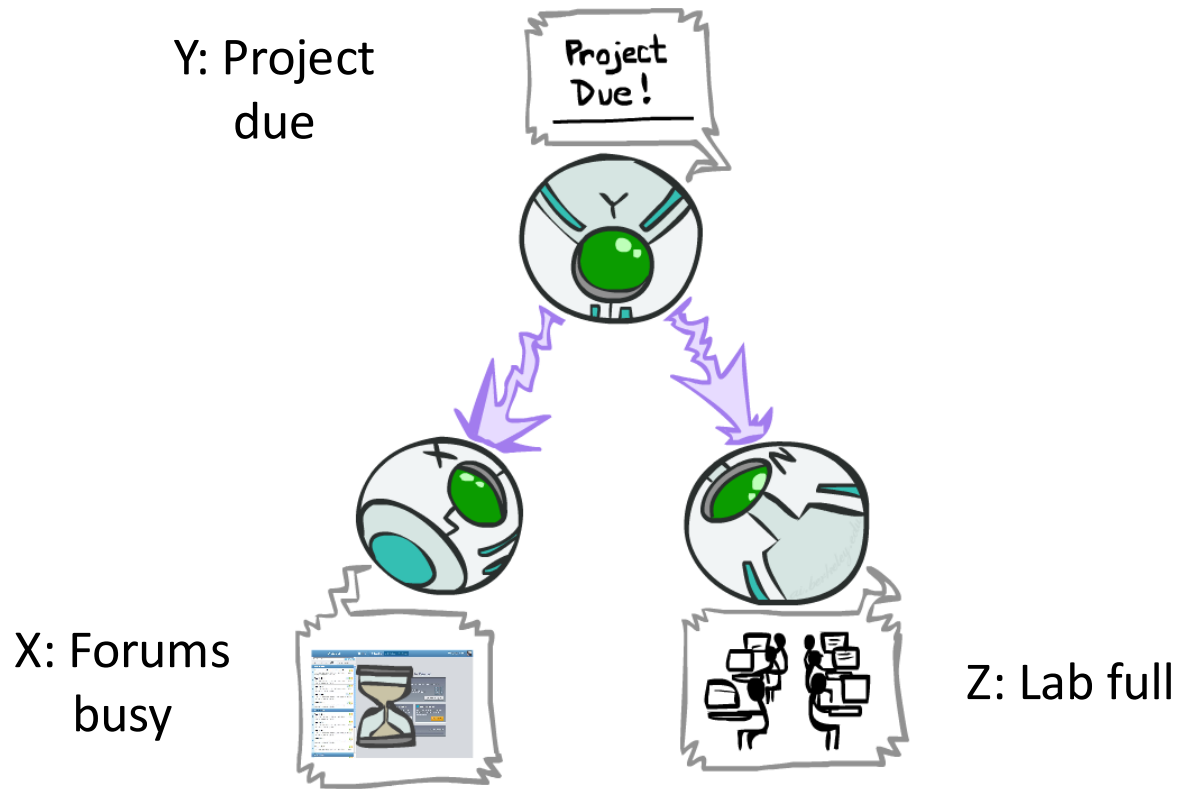
- In numbers:

$$P(+x | +y) = 1, P(-x | -y) = 1, \\ P(+z | +y) = 1, P(-z | -y) = 1$$

Common Cause

- This configuration is a “common cause”

- Guaranteed X and Z independent given Y?



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

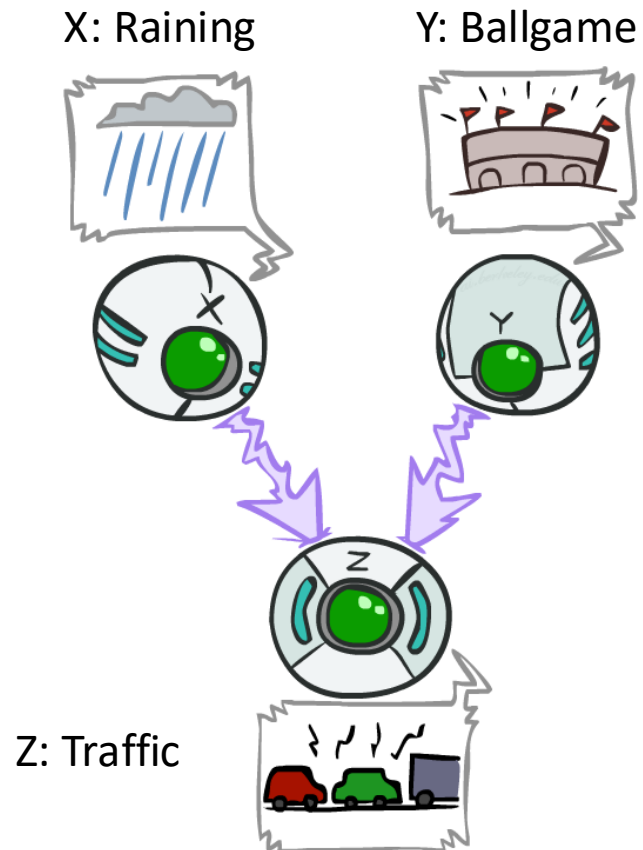
$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(y)P(x|y)P(z|y)}{P(y)P(x|y)} \\ &= P(z|y) \end{aligned}$$

Yes!

- Observing the cause blocks influence between effects.

Common Effect

- Last configuration: two causes of one effect (v-structures)



- Are X and Y independent?

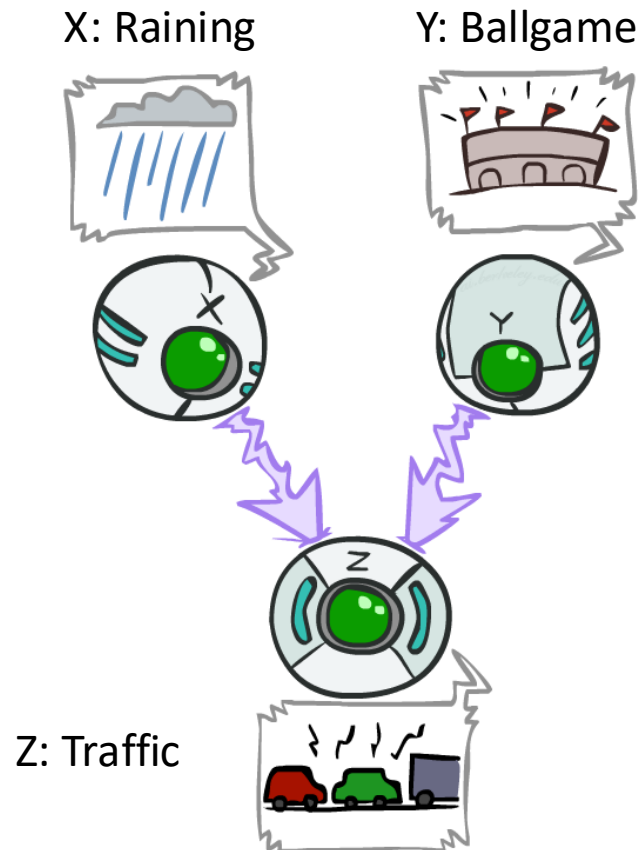
- **Yes:** the ballgame and the rain cause traffic, but they are not correlated

- **Proof:**

$$P(x, y) = \sum P(x, y, z)$$

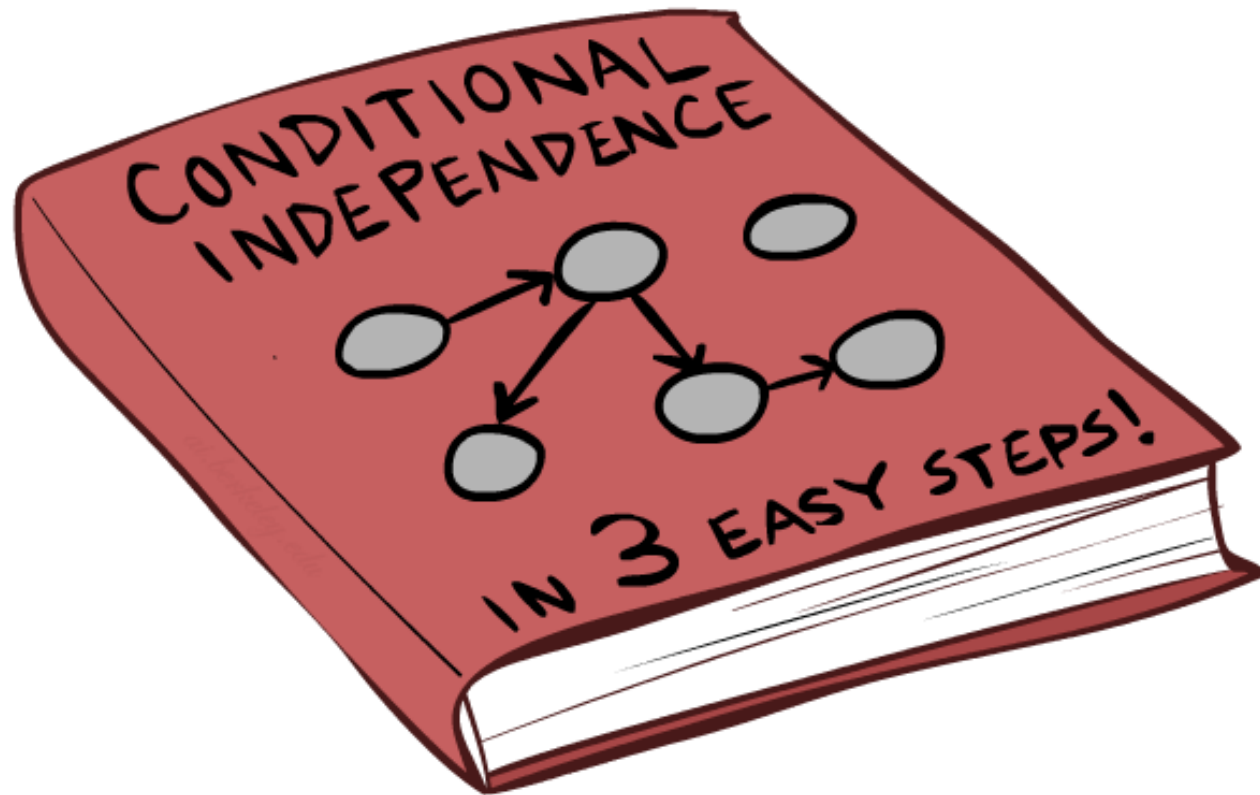
Common Effect

- Last configuration: two causes of one effect (v-structures)



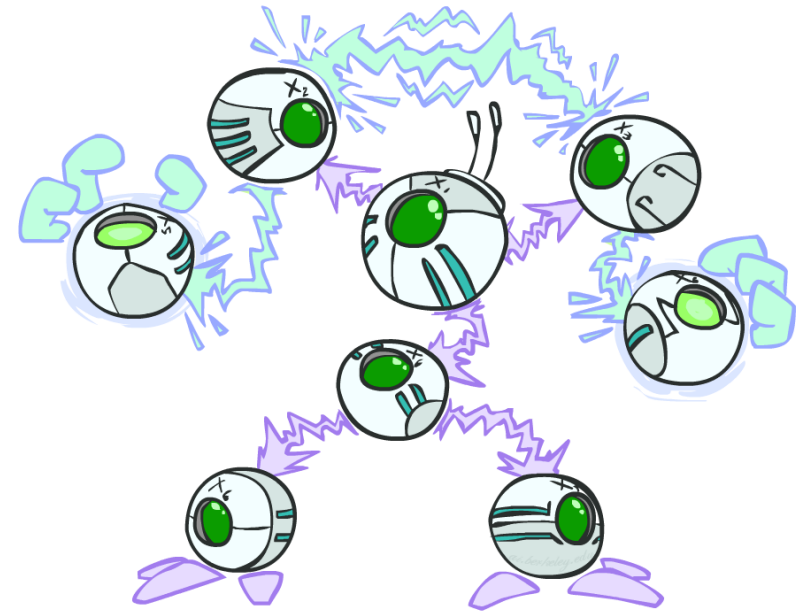
- Are X and Y independent?
 - **Yes**: the ballgame and the rain cause traffic, but they are not correlated
 - (Proved previously)
- Are X and Y independent given Z?
 - **No**: seeing traffic puts the rain and the ballgame in competition as explanation.
- **This is backwards from the other cases**
 - Observing an effect **activates** influence between possible causes.

The General Case



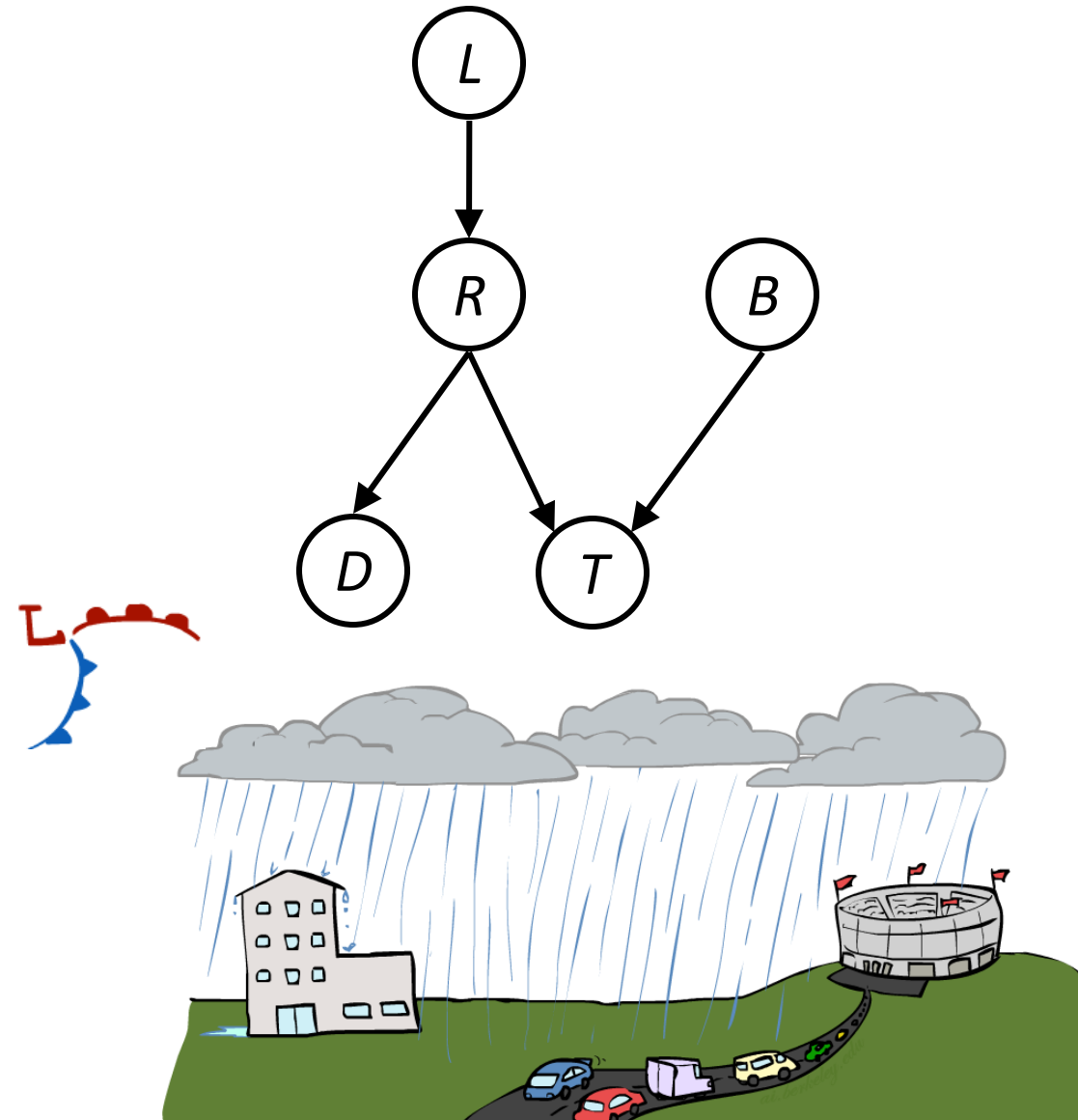
The General Case

- General question: in a given BN, are two variables independent (given evidence)?
- Solution: analyze the graph
- Any complex example can be broken into repetitions of the three canonical cases



Reachability

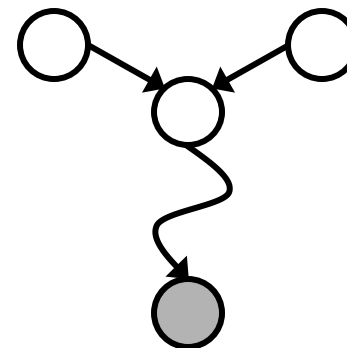
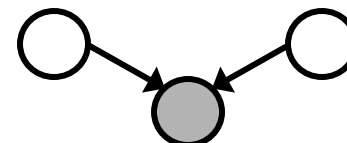
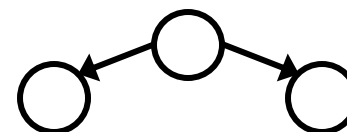
- Recipe: shade evidence nodes, look for paths in the resulting graph
- Attempt 1: if two nodes are **not connected*** they are conditionally independent
 - *There does not exist an undirected path between them, excluding those blocked by a shaded node.
- Almost works, but not quite
 - Where does it break?
 - Answer: the v-structure at T doesn't count as a link in a path unless "active"



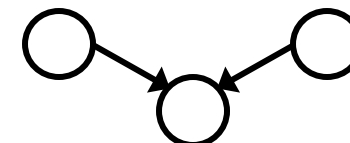
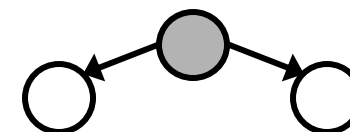
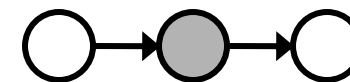
Active / Inactive Paths

- Question: Are X and Y conditionally independent given evidence variables {Z}?
 - Yes, if X and Y “d-separated” by Z
 - Consider all (undirected) paths from X to Y
 - No active paths = independence!
- A path is active if each triple is active:
 - **Causal chain:** $A \rightarrow B \rightarrow C$ where B is unobserved (either direction)
 - **Common cause:** $A \leftarrow B \rightarrow C$ where B is unobserved
 - **Common effect:** (aka v-structure)
 $A \rightarrow B \leftarrow C$ where B or one of its descendants is observed
- All it takes to block a path is a single inactive segment

Active Triples



Inactive Triples



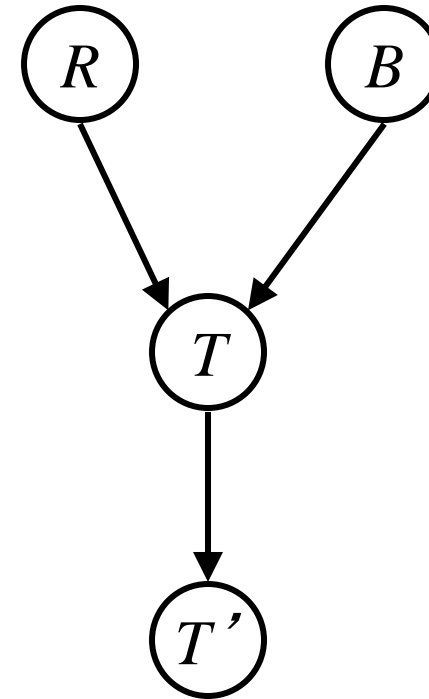
```
def d-separated(first, second):
    for path in paths(first, second):
        path_active = True
        for triple in path:
            if not active(triple):
                path_active = False
                break
        if path_active:
            return False
    return True
```

Example: which assumptions apply?

$R \perp\!\!\!\perp B$ *Yes*

$R \perp\!\!\!\perp B | T$

$R \perp\!\!\!\perp B | T'$



Example: which assumptions apply?

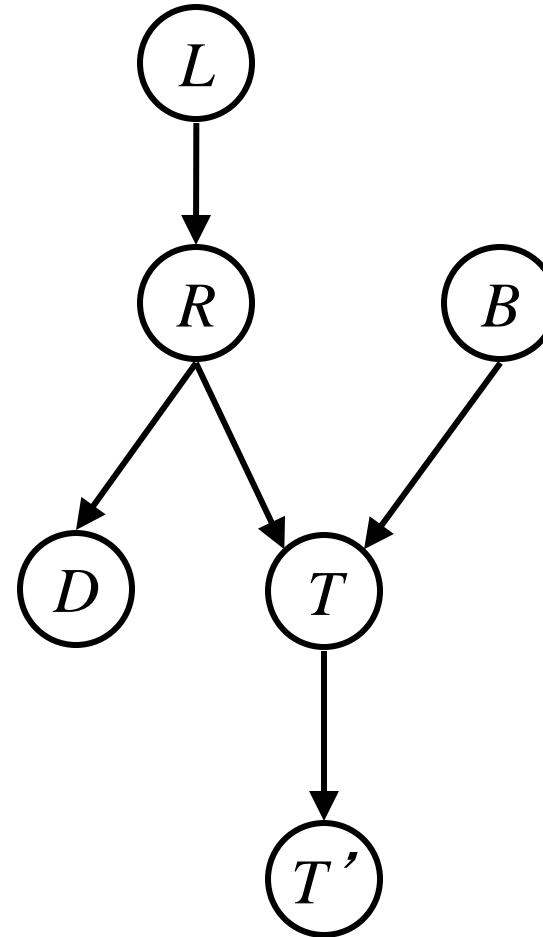
$L \perp\!\!\!\perp T' | T$ *Yes*

$L \perp\!\!\!\perp B$ *Yes*

$L \perp\!\!\!\perp B | T$

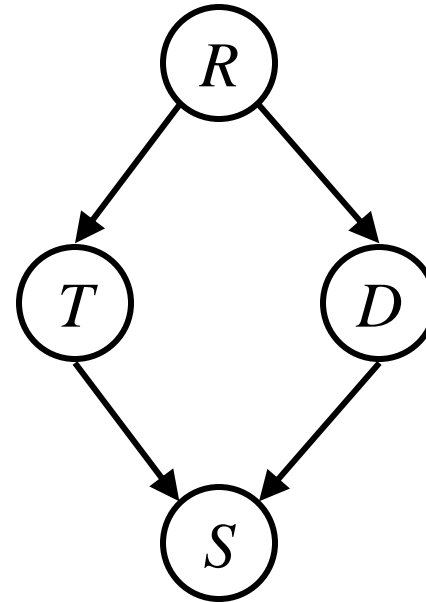
$L \perp\!\!\!\perp B | T'$

$L \perp\!\!\!\perp B | T, R$ *Yes*



Example: which assumptions apply?

- Variables:
 - R: Raining
 - T: Traffic
 - D: Roof drips
 - S: I'm sad



- Questions:

$$T \perp\!\!\!\perp D$$

$$T \perp\!\!\!\perp D | R \quad \text{Yes}$$

$$T \perp\!\!\!\perp D | R, S$$