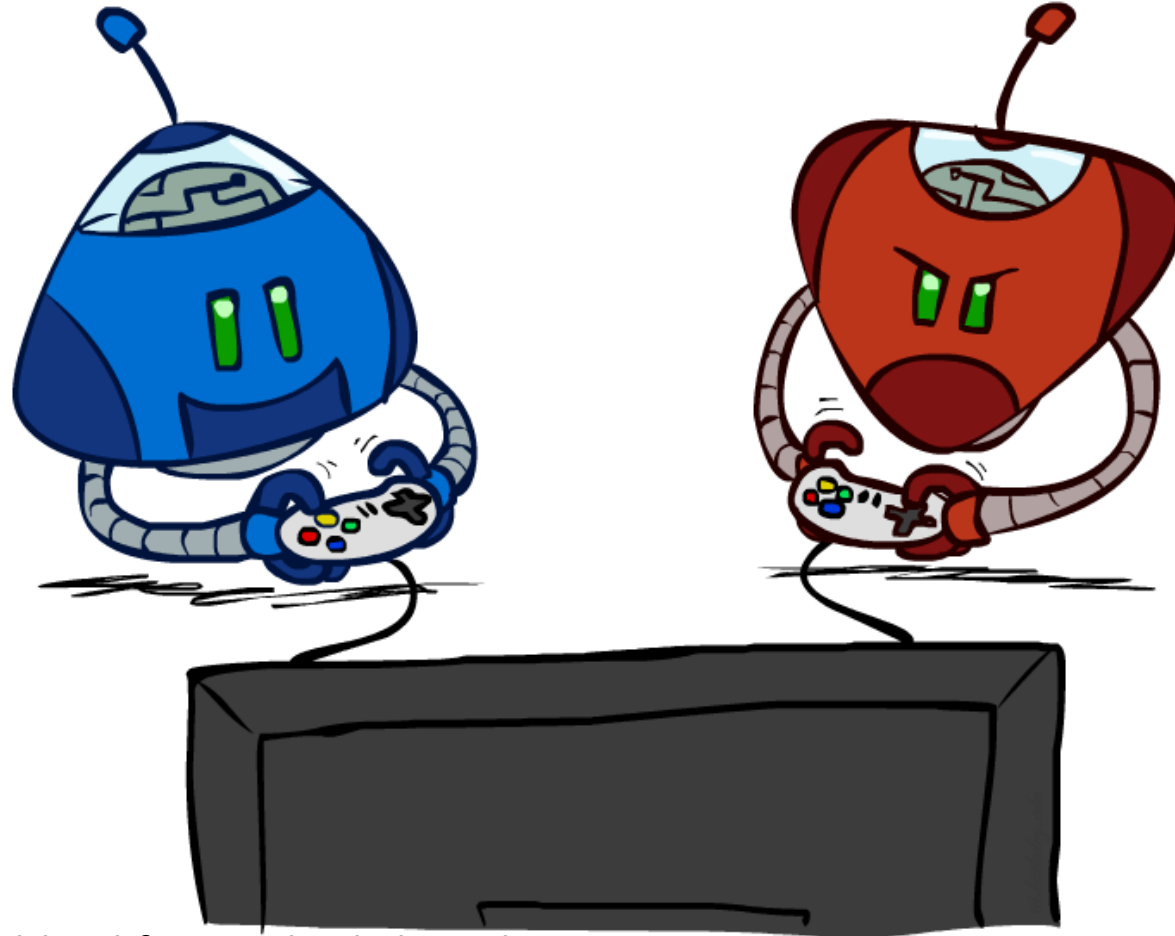


CSE 573: Artificial Intelligence

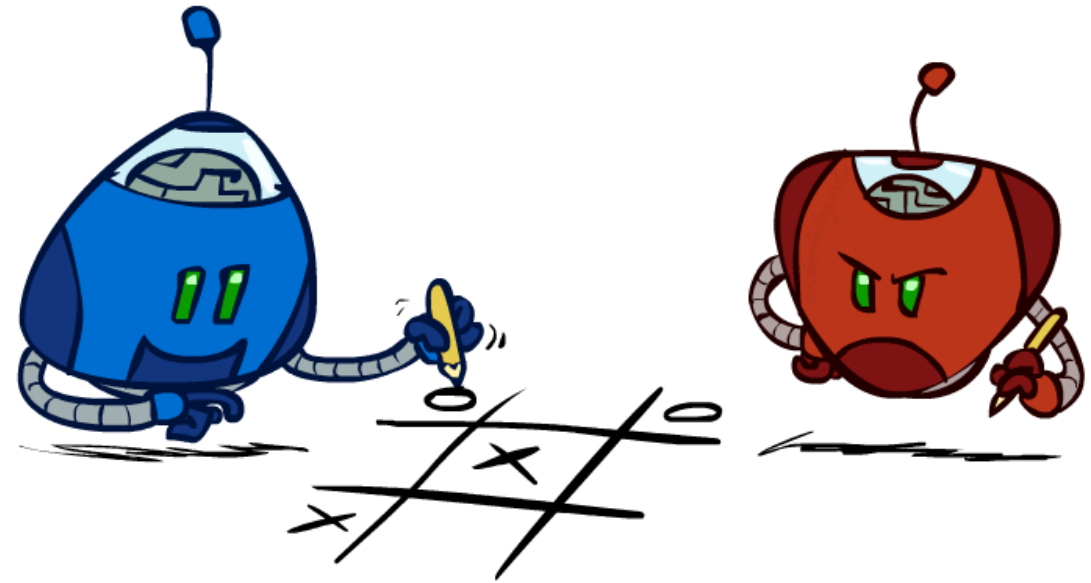
Adversarial Search



slides adapted from
Stuart Russel, Dan Klein, Pieter Abbeel from ai.berkeley.edu
And Hanna Hajishirzi, Jared Moore, Dan Weld

Outline

- History / Overview
- Minimax for Zero-Sum Games
- α - β Pruning
- Games with chance elements



A brief history

■ Checkers:

- 1950: First computer player.
- 1959: Samuel's self-taught program.
- 1994: First computer world champion: Chinook defeats Tinsley
- 2007: Checkers solved! Endgame database of 39 trillion states

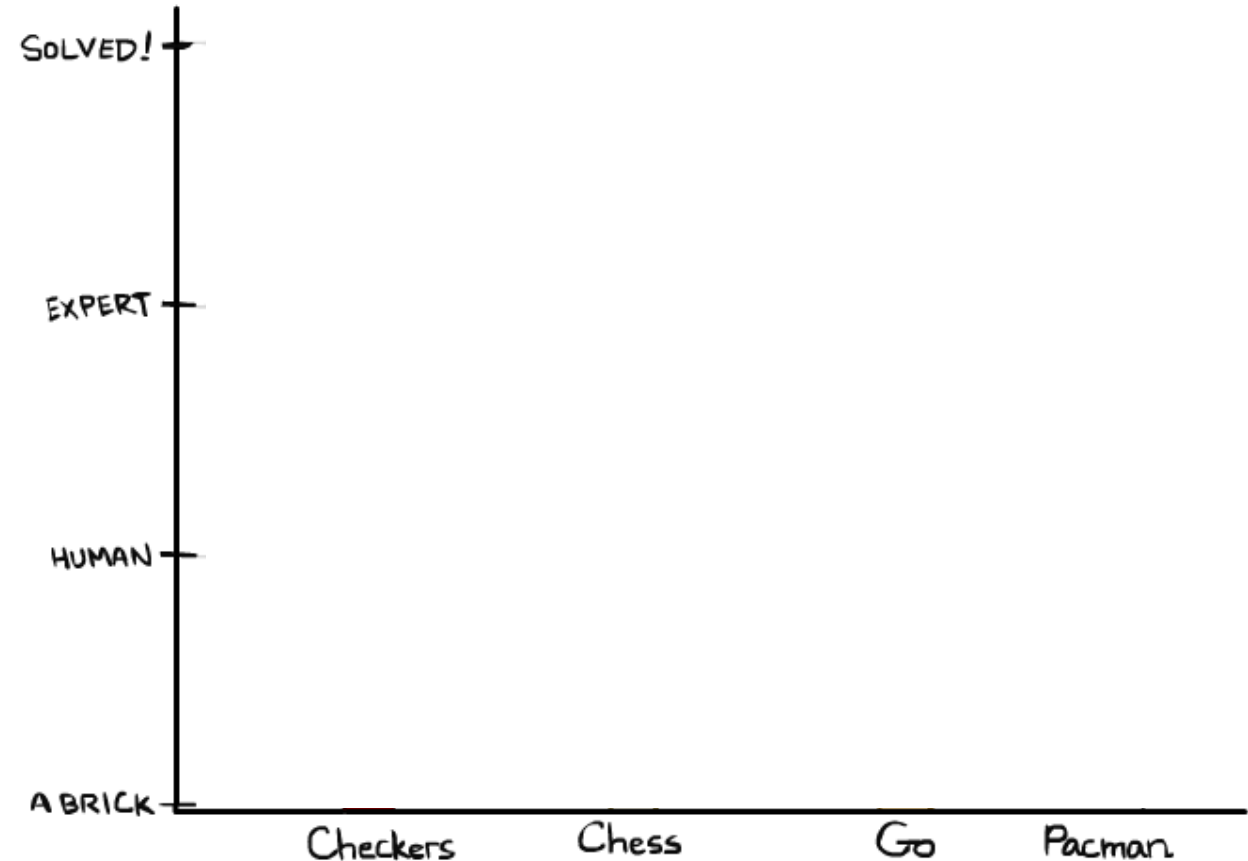
■ Chess:

- 1945-1960: Zuse, Wiener, Shannon, Turing, Newell & Simon, McCarthy.
- 1960s onward: gradual improvement under "standard model"
- 1997: Deep Blue defeats human champion Gary Kasparov
- 2021: Stockfish rating 3551 (vs 2870 for Magnus Carlsen).

■ Go:

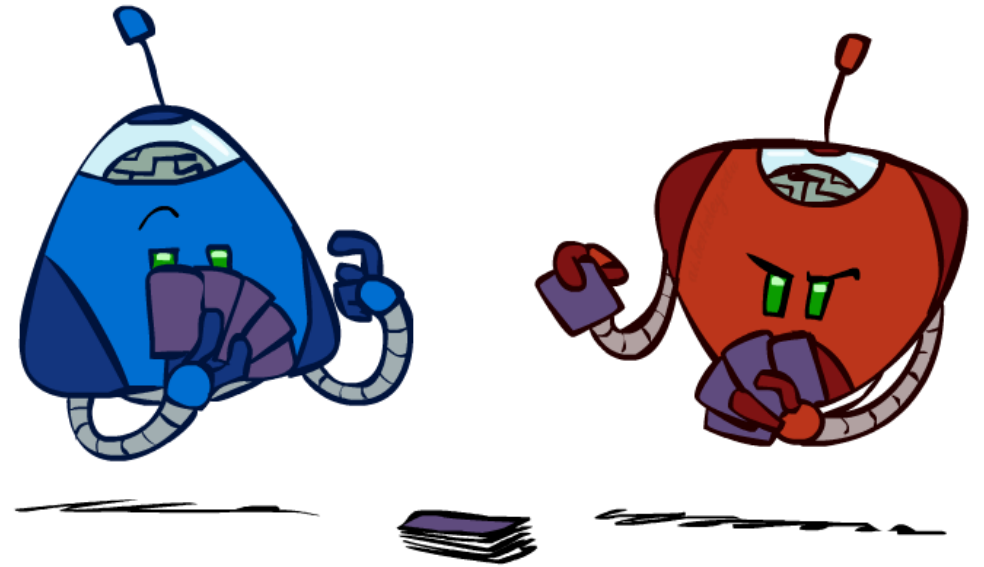
- 1968: Zobrist's program plays legal Go, barely ($b > 300!$)
- 1968-2005: various ad hoc approaches tried, novice level
- 2005-2014: Monte Carlo tree search -> strong amateur
- 2016-2017: AlphaGo defeats human world champions

■ Pacman



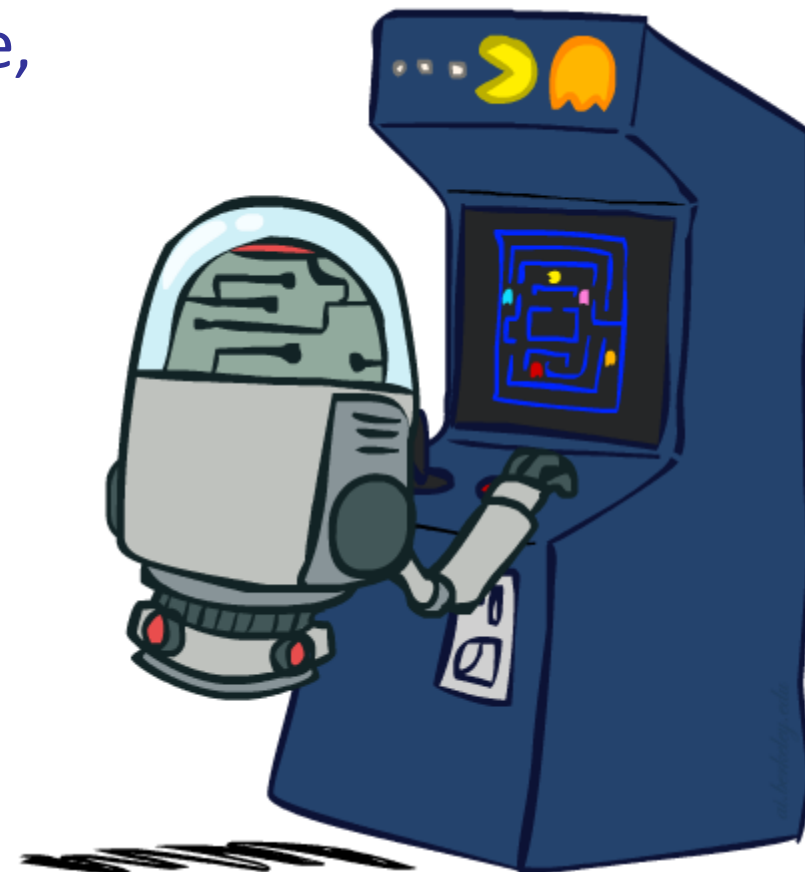
Types of Games

- Game = task environment with > 1 agent
- Axes:
 - Deterministic or stochastic?
 - Perfect information (fully observable)?
 - One, two, or more players?
 - Turn-taking or simultaneous?
 - Zero sum?
- Want algorithms for calculating a *contingent plan* (a.k.a. **strategy** or **policy**) which recommends a move for every possible eventuality

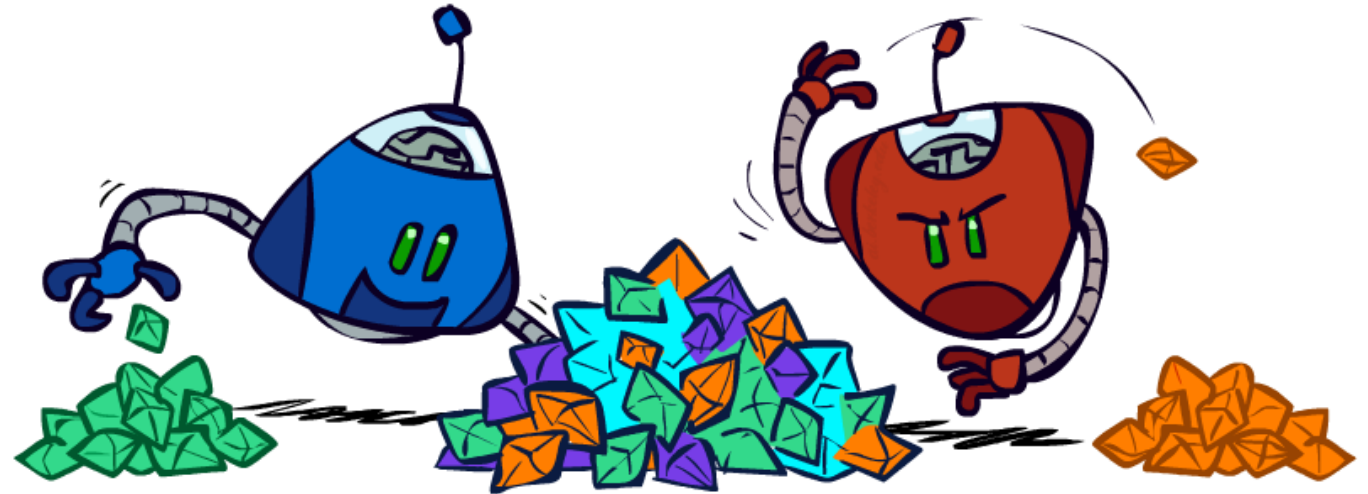
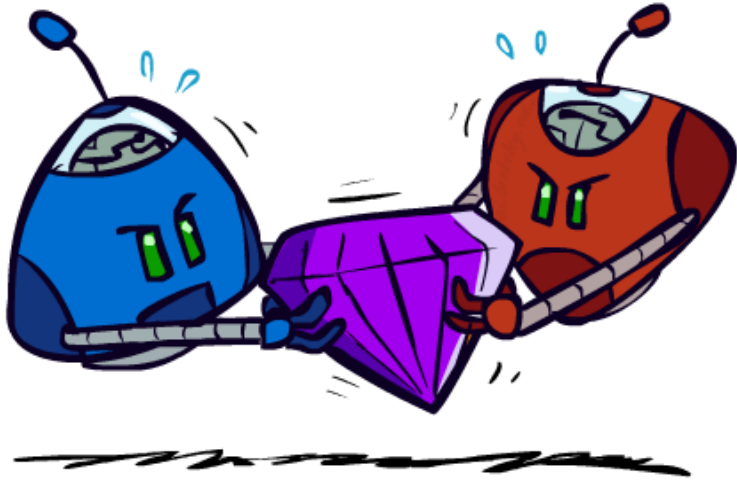


“Standard” Games

- Standard games are deterministic, observable, two-player, turn-taking, zero-sum
- Game formulation:
 - Initial state: s_0
 - Players: $\text{Player}(s)$ indicates whose move it is
 - Actions: $\text{Actions}(s)$ for player on move
 - Transition model: $\text{Result}(s,a)$
 - Terminal (goal) test: $\text{Terminal-Test}(s)$
 - Terminal values: $\text{Utility}(s,p)$ for player p
 - Or just $\text{Utility}(s)$ for player making the decision at root



Zero-Sum Games



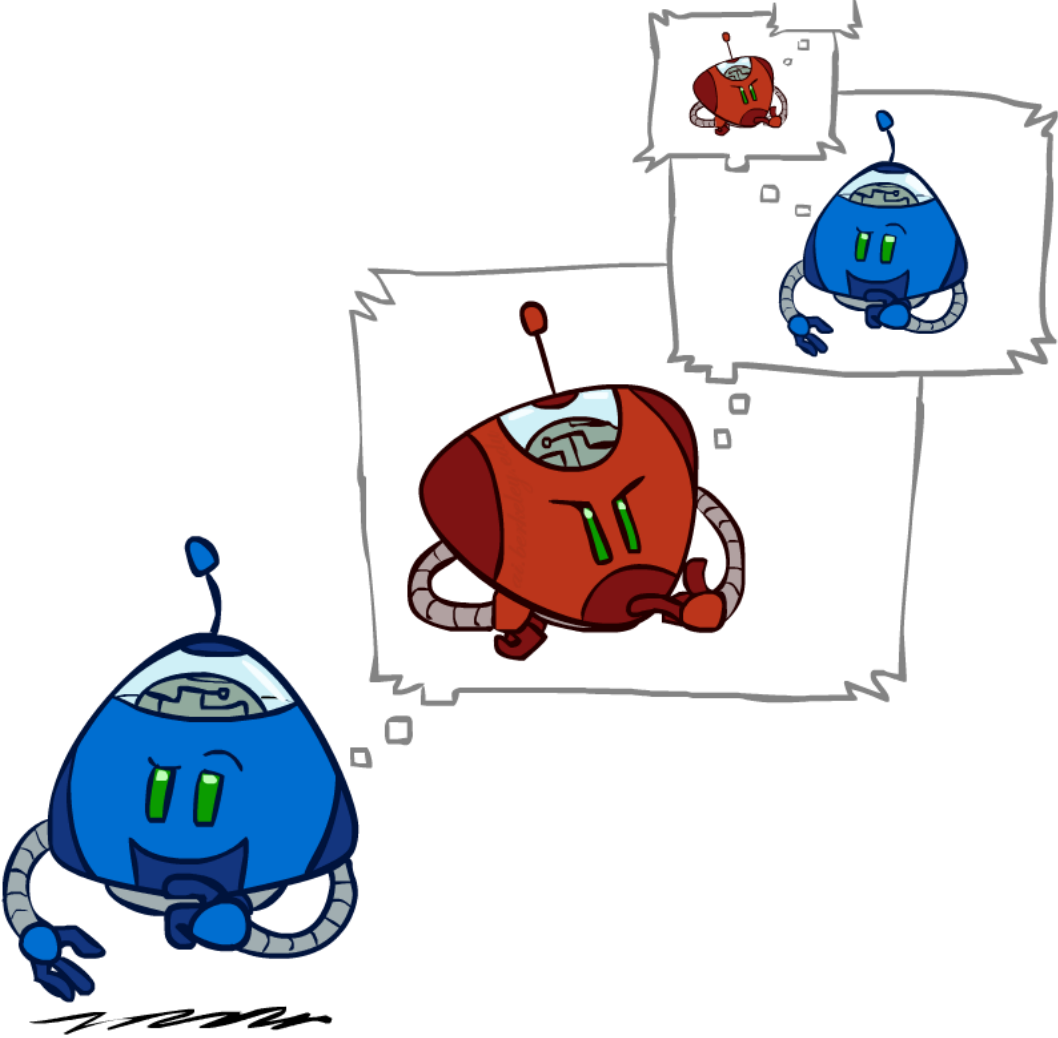
- Zero-Sum Games

- Agents have *opposite* utilities
- Pure competition: what is better for one player is worse for the other

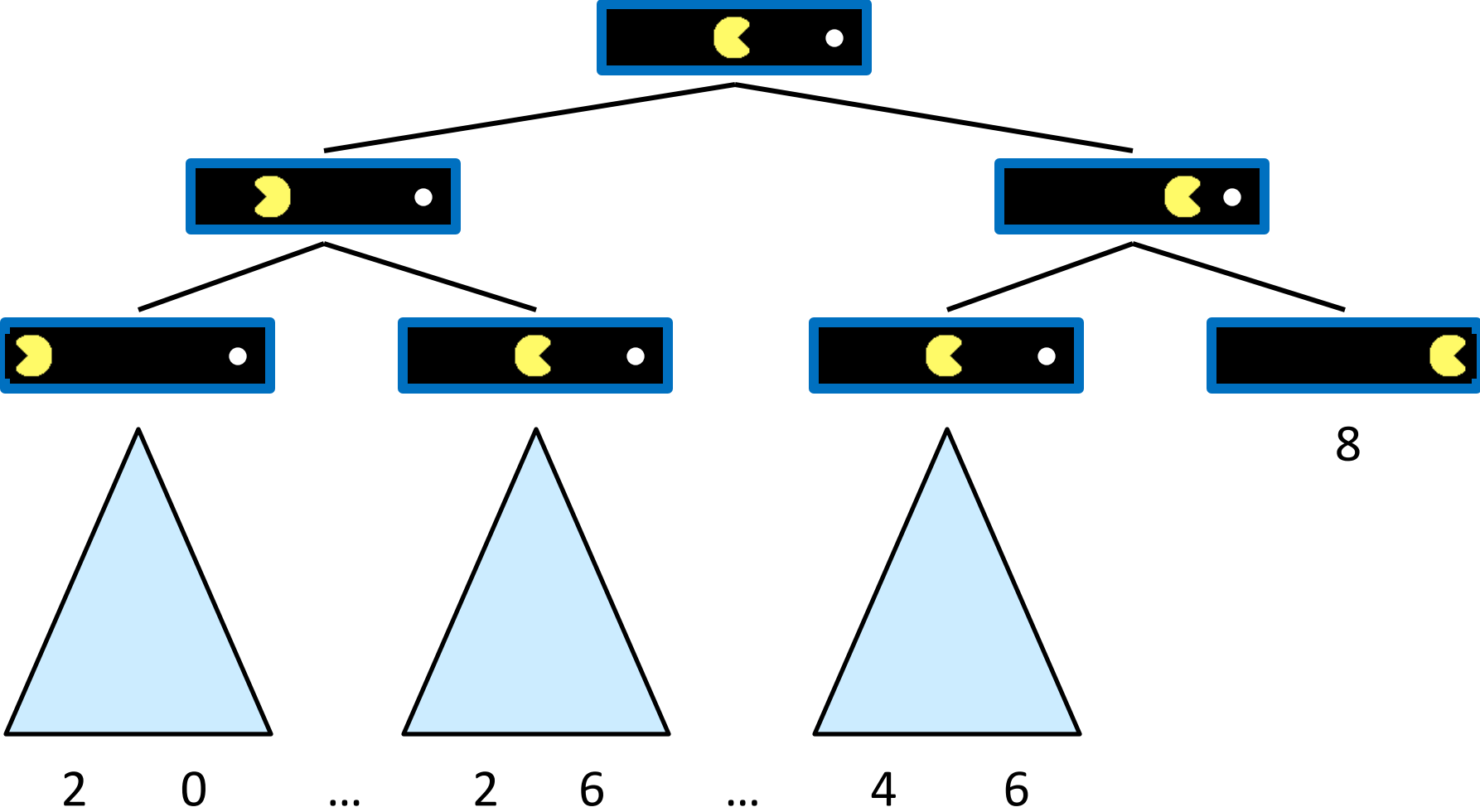
- General Games

- Agents have *independent* utilities
- Cooperation, indifference, competition, shifting alliances, and more are all possible

Adversarial Search

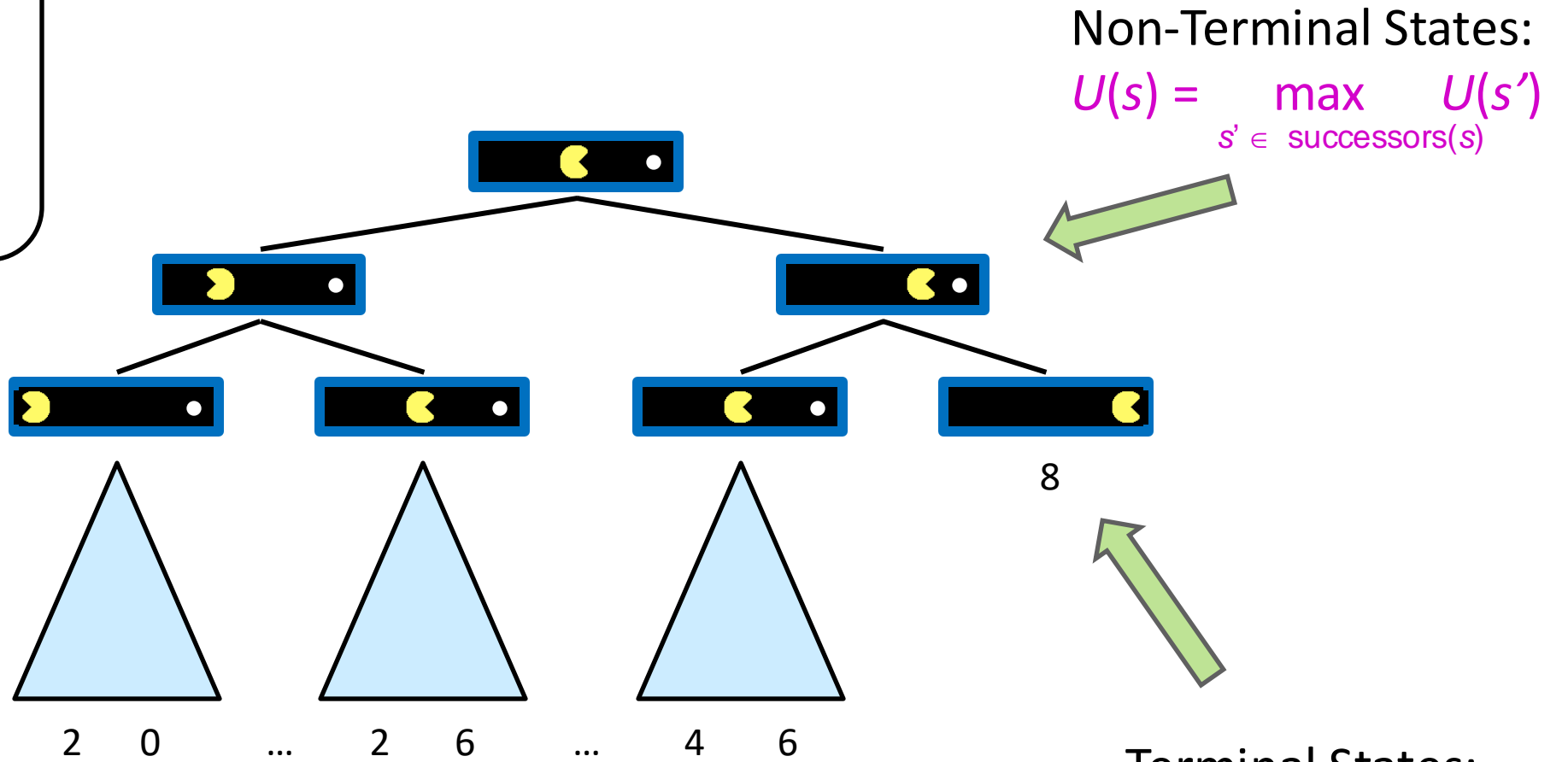


Single-Agent Trees



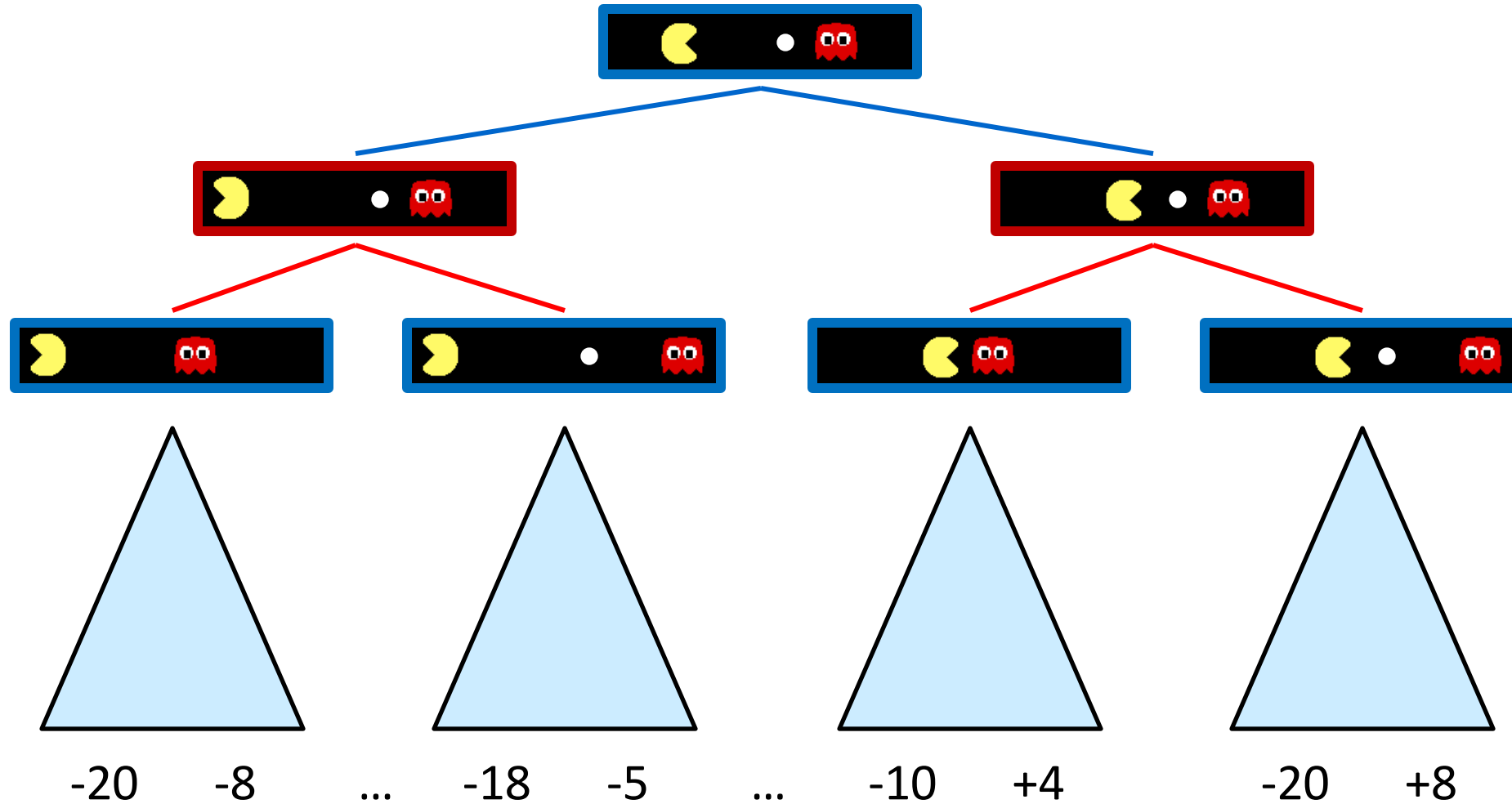
Utility (value) of a State

Utility of a state:
The best achievable
outcome (value)
from that state



Terminal States:
 $U(s) = \text{known}$

Adversarial Game Trees



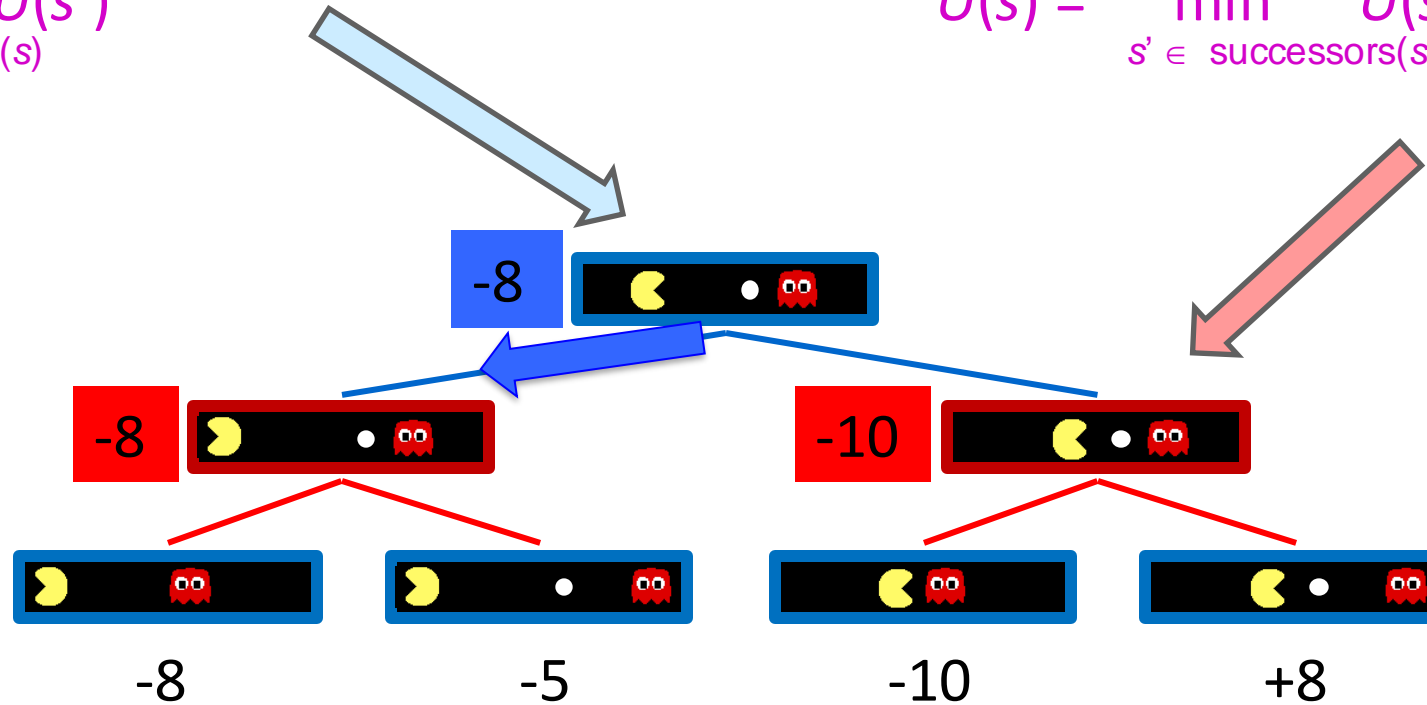
Minimax Values

MAX nodes: under Agent's control

$$U(s) = \max_{s' \in \text{successors}(s)} U(s')$$

MIN nodes: under Opponent's control

$$U(s) = \min_{s' \in \text{successors}(s)} U(s')$$



Tic-Tac-Toe Game Tree



MAX (X)



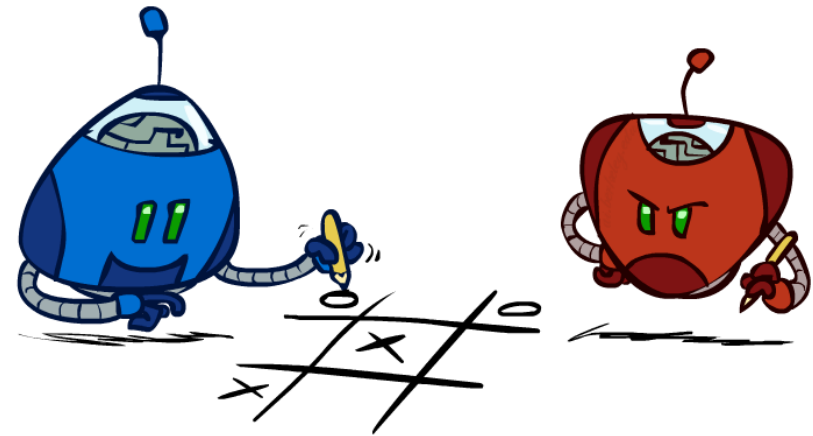
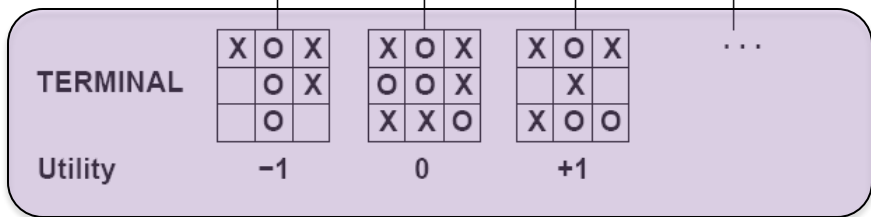
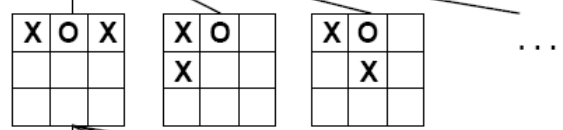
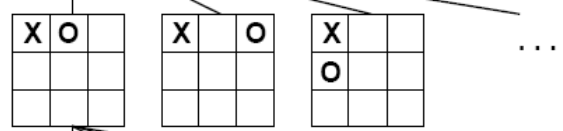
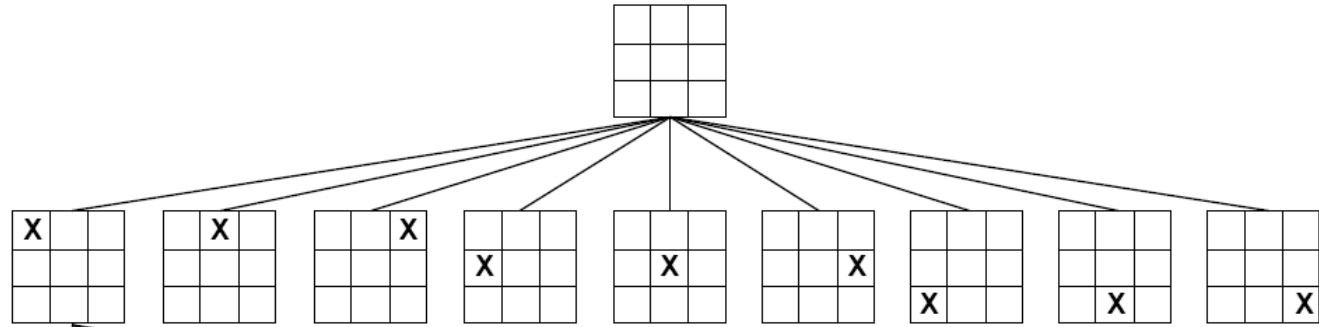
MIN (O)



MAX (X)

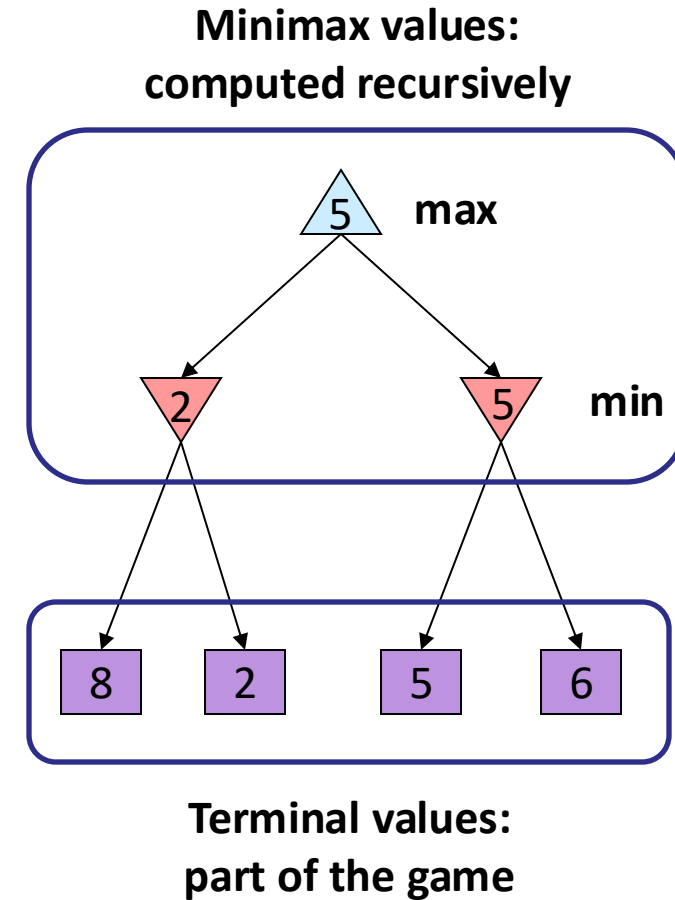


MIN (O)



Adversarial Search (Minimax)

- **Deterministic, zero-sum games:**
 - Tic-tac-toe, chess, checkers
 - One player maximizes result
 - The other minimizes result
- **Minimax search:**
 - A state-space search tree
 - Players alternate turns
 - Compute each node's **minimax value**: the best achievable utility against a rational (optimal) adversary



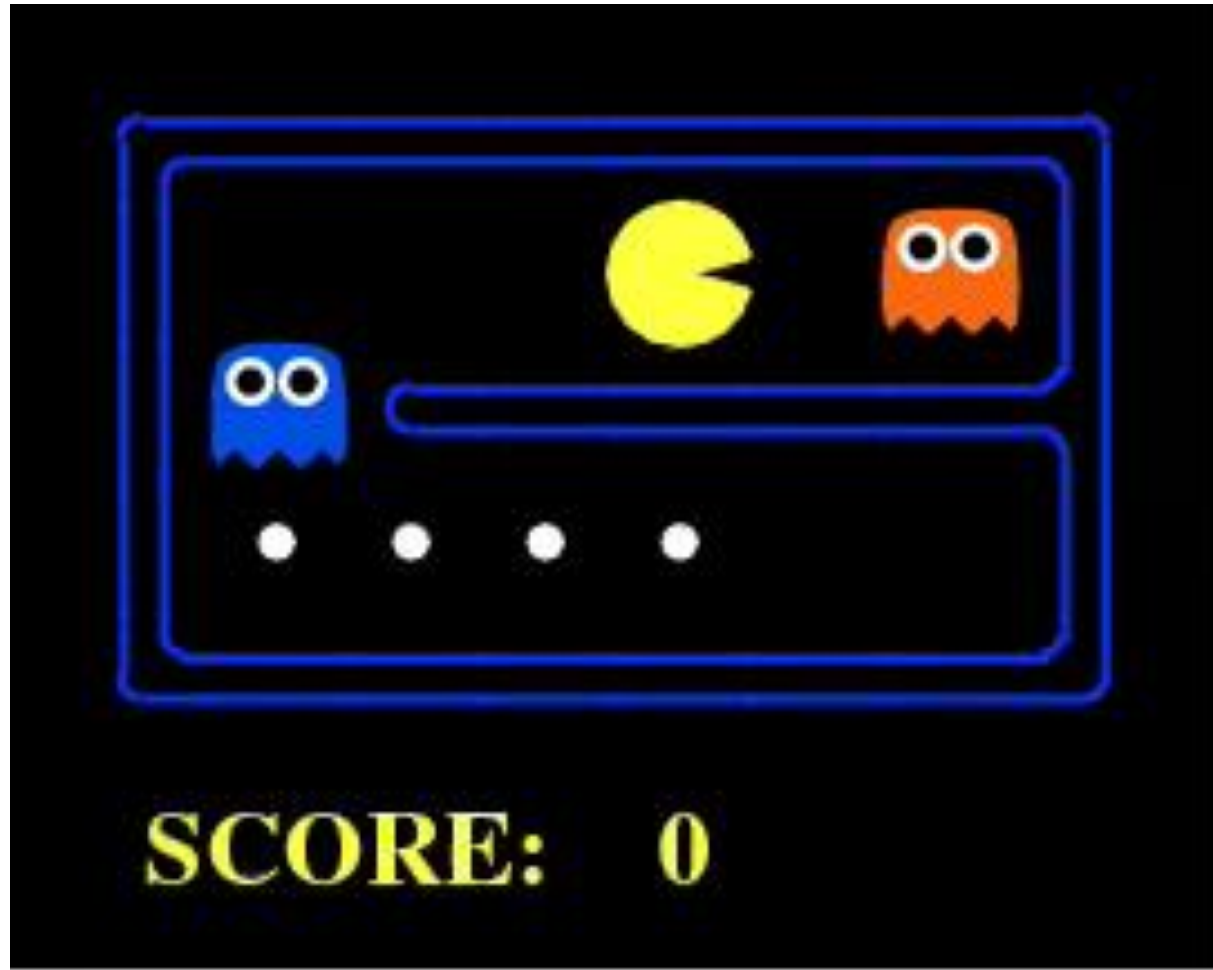
Implementation

```
function minimax-decision(s) returns an action
  return the action a in Actions(s) with the highest
  minimax_value(Result(s,a))
```

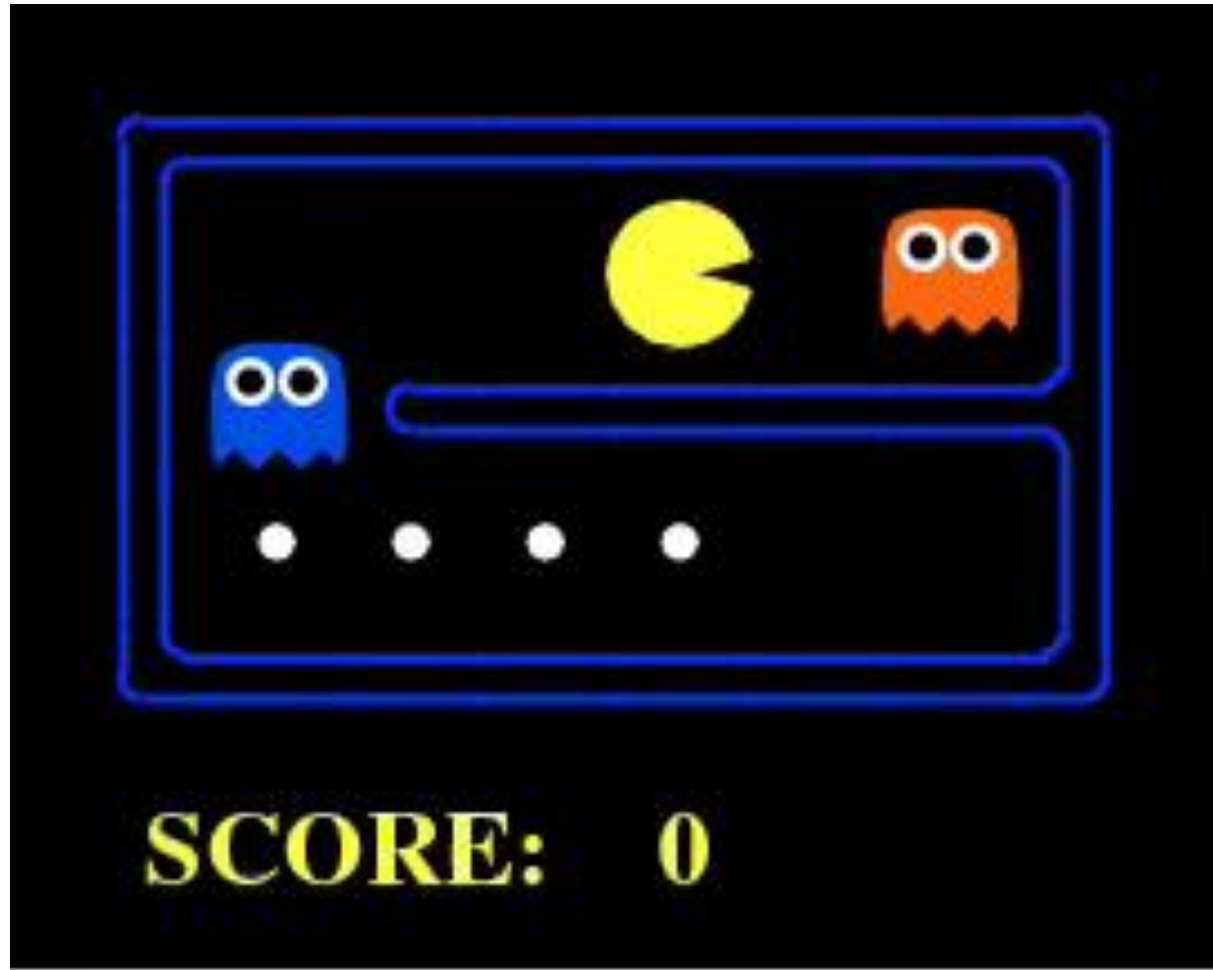


```
function minimax_value(s) returns a value
  if Terminal-Test(s) then return Utility(s)
  if Player(s) = MAX then return maxa in Actions(s) minimax_value(Result(s,a))
  if Player(s) = MIN then return mina in Actions(s) minimax_value(Result(s,a))
```

Video of Demo Min vs. Exp (Min)

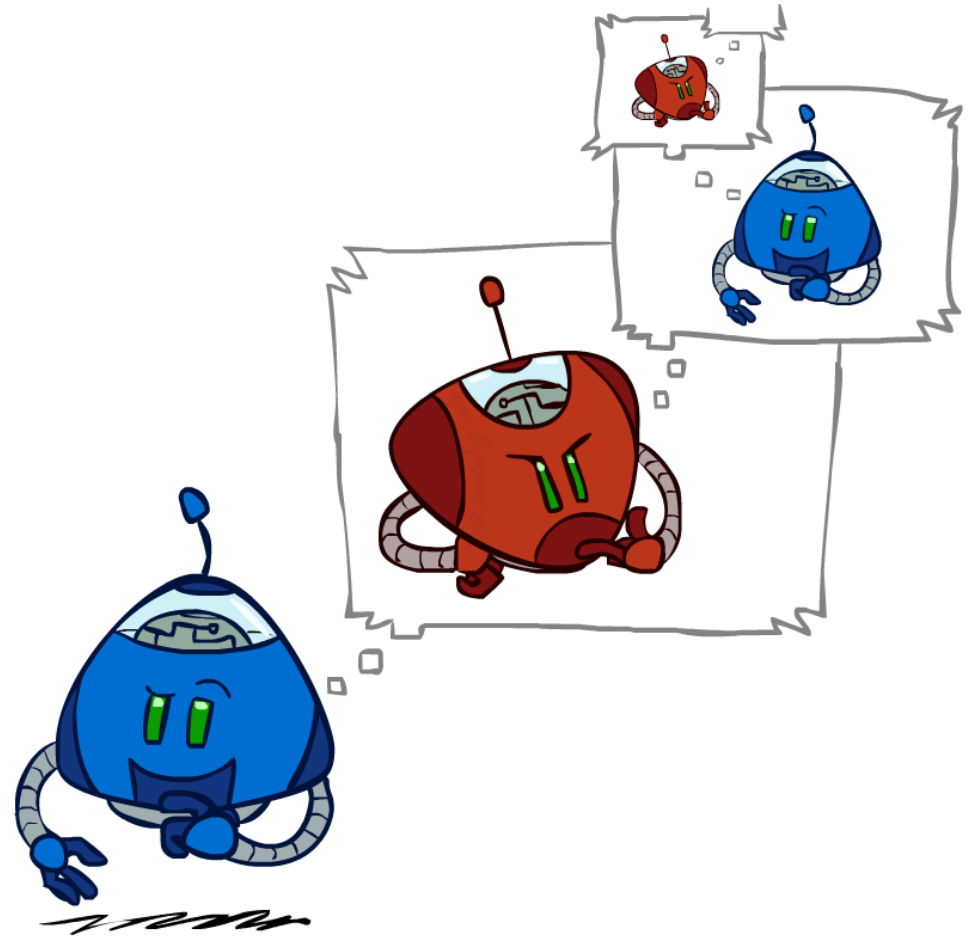


Video of Demo Min vs. Exp (Exp)

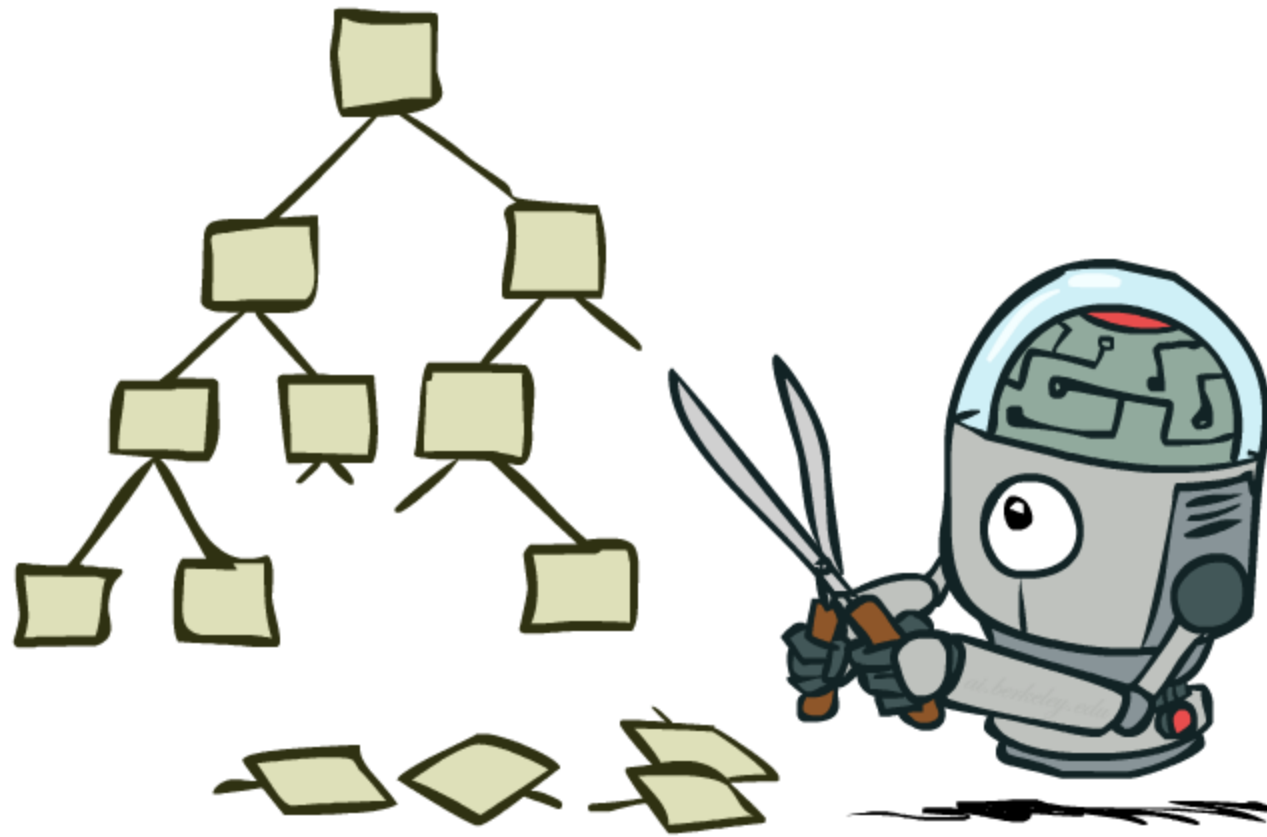


Minimax Efficiency

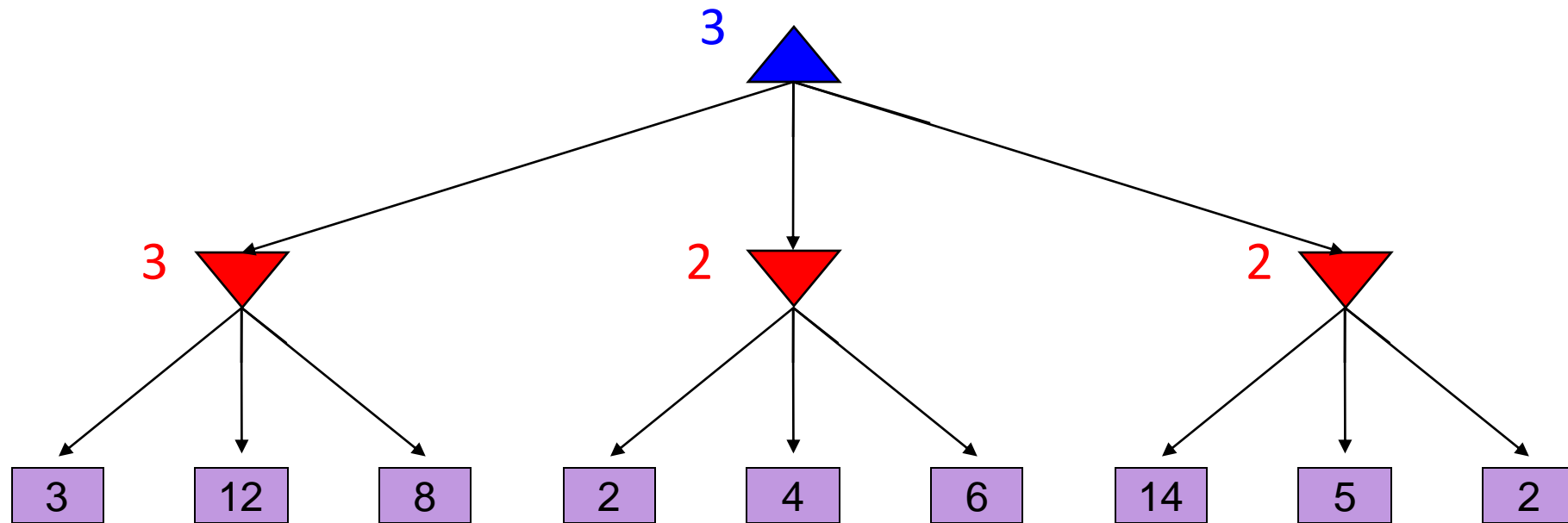
- How efficient is minimax?
 - Just like (exhaustive) DFS
 - Time: $O(b^m)$
 - Space: $O(bm)$
- Example: For chess, $b \approx 35$, $m \approx 100$
 - Exact solution is completely infeasible
 - Humans can't do this either, so how do we play chess?



Game Tree Pruning

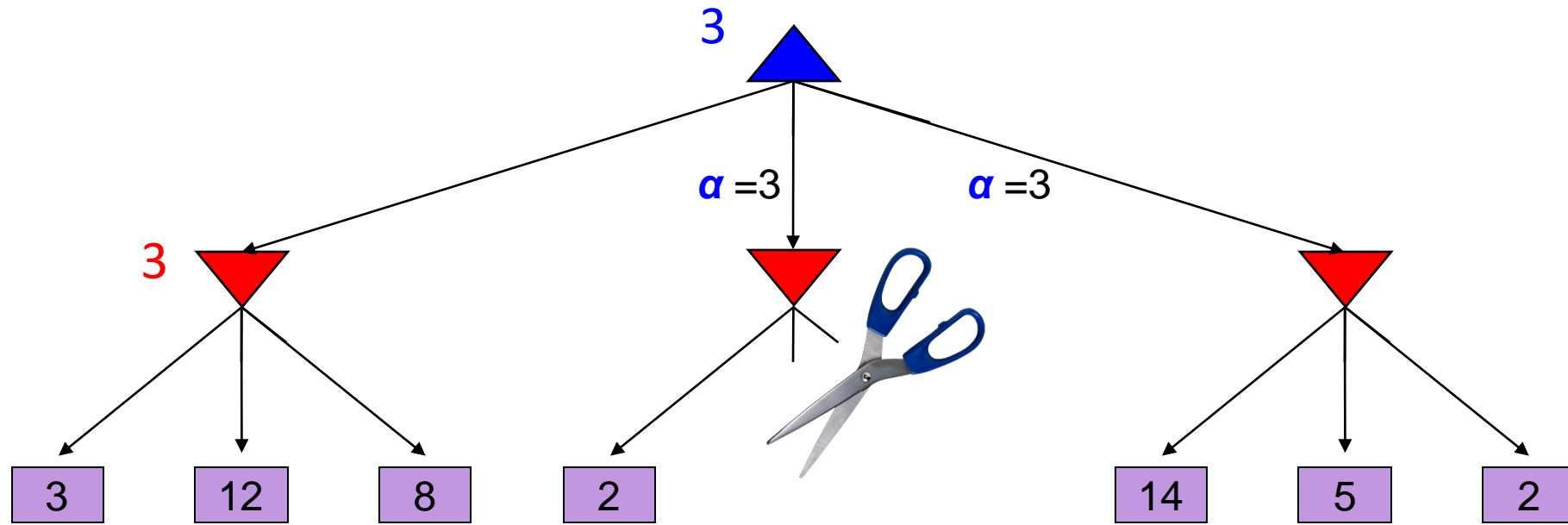


Minimax Example



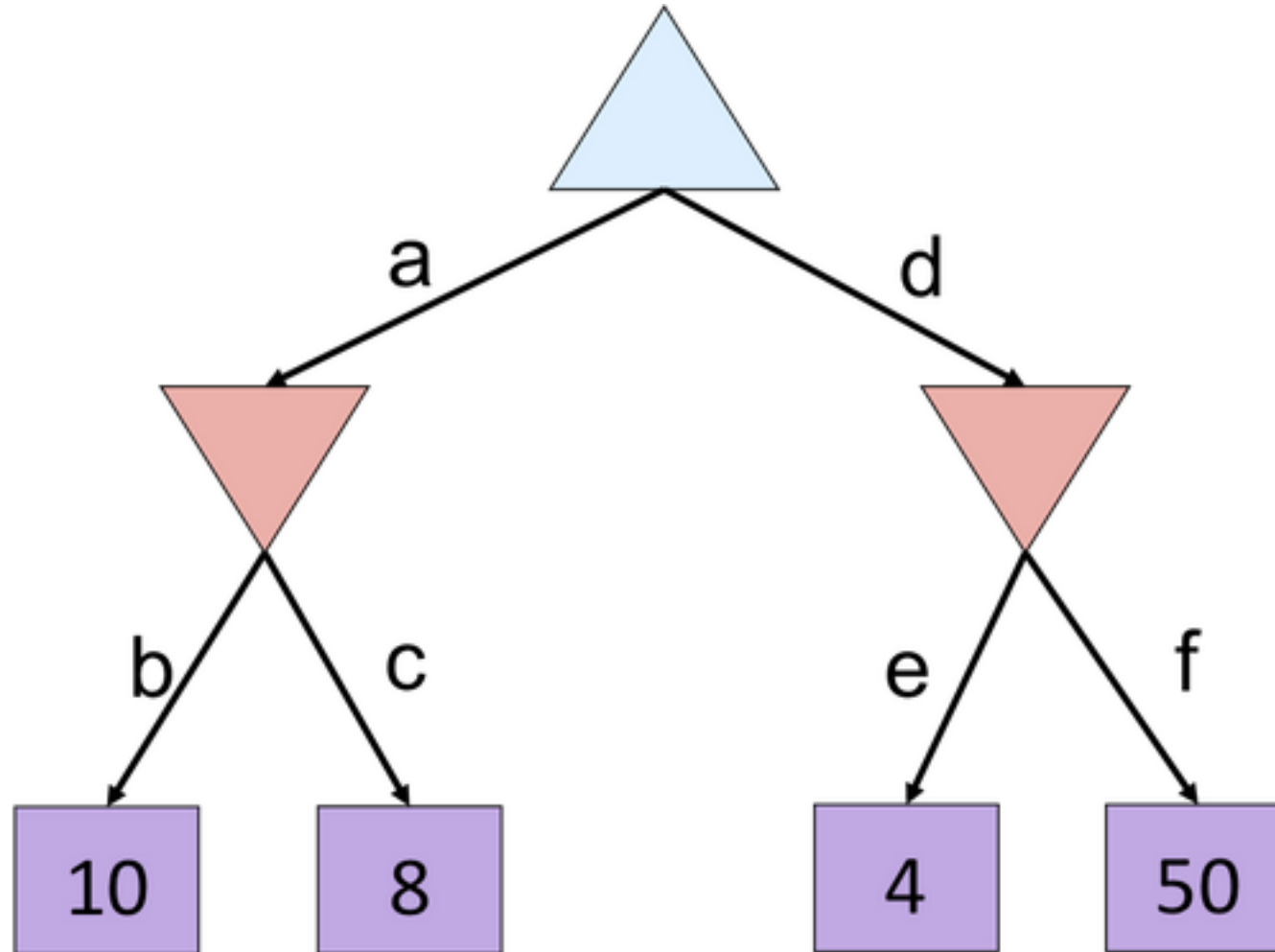
Alpha-Beta Example

α = best option so far from any MAX node on this path

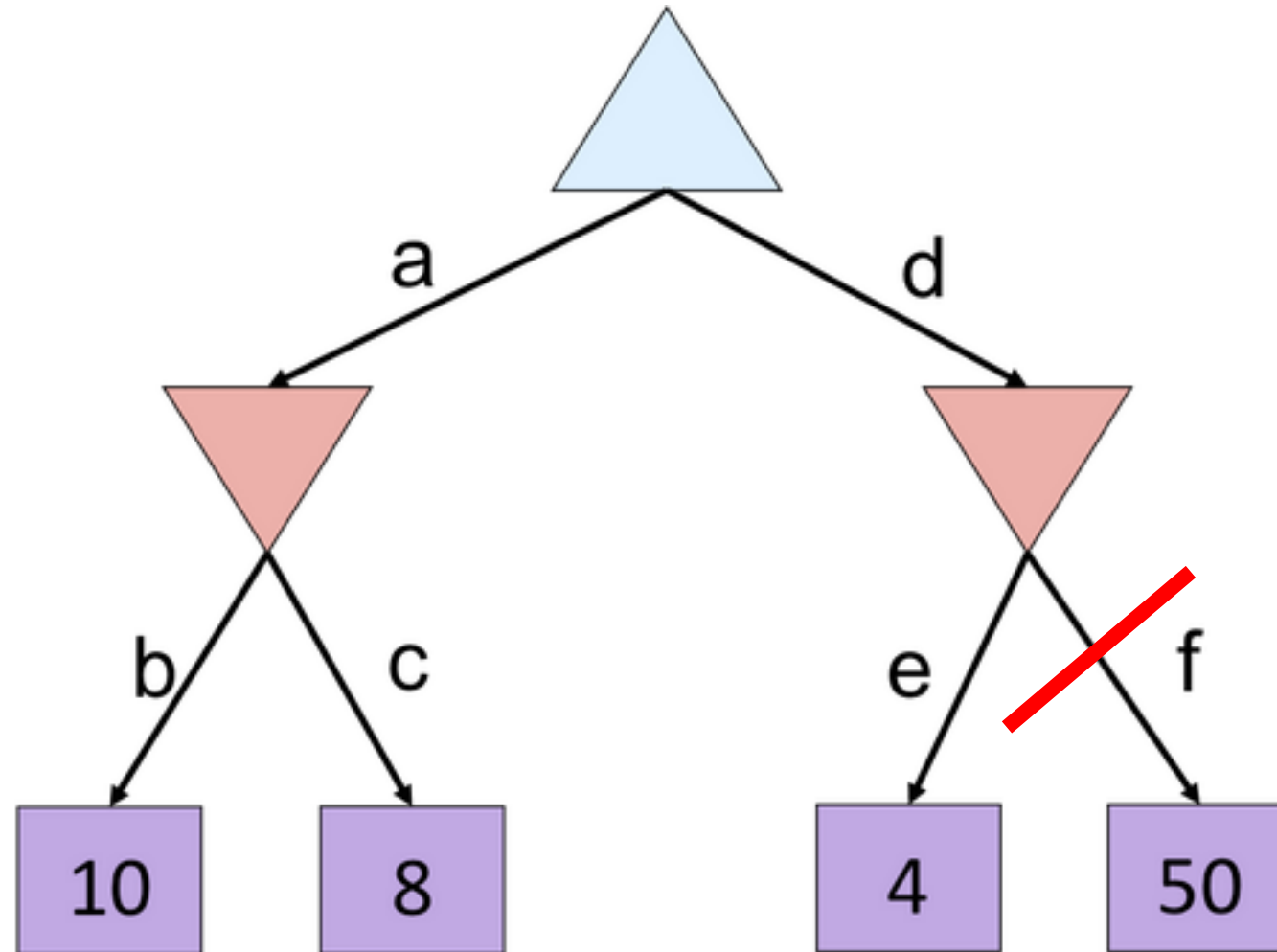


The order of generation matters: more pruning is possible if good moves come first

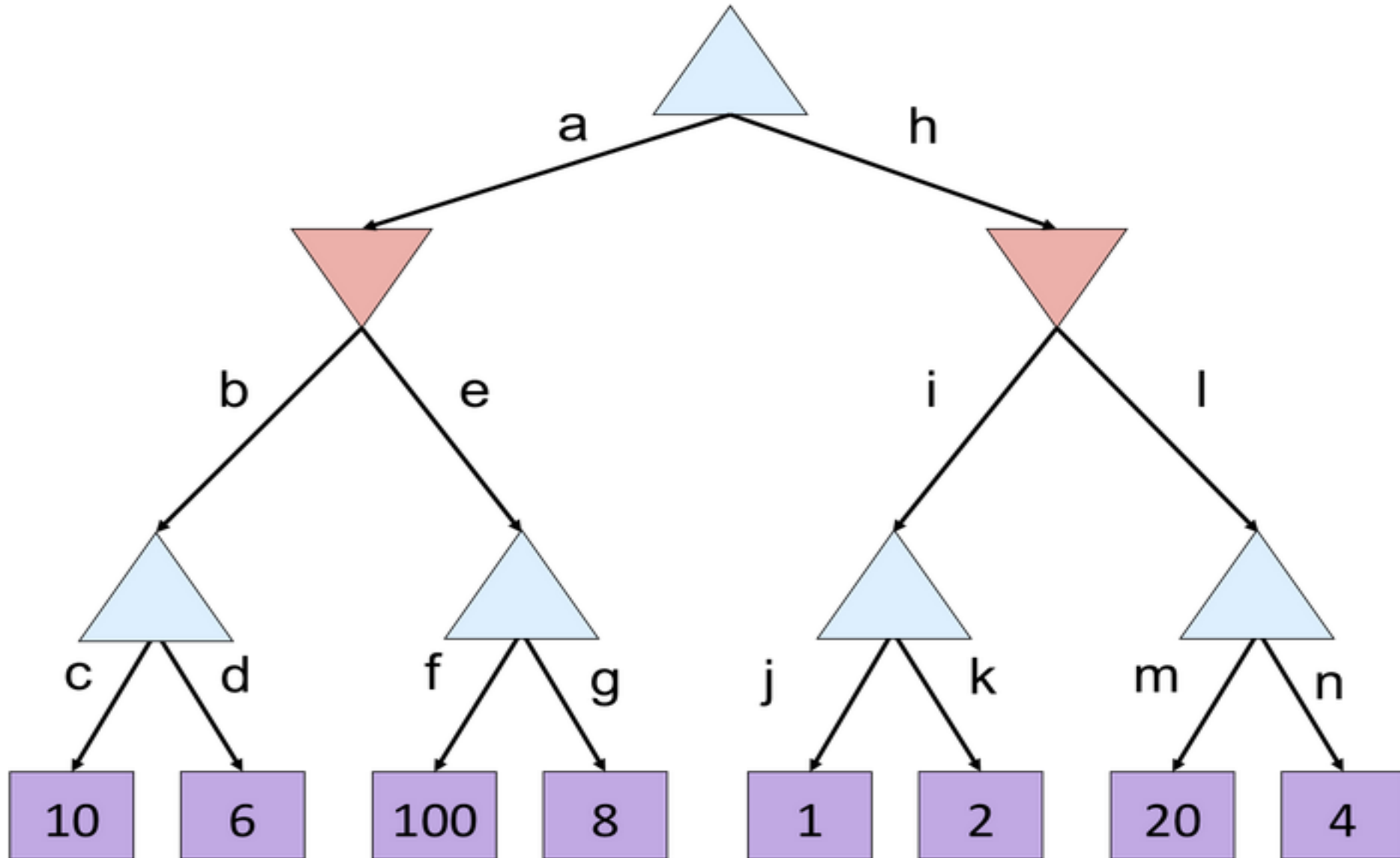
Alpha-Beta Quiz



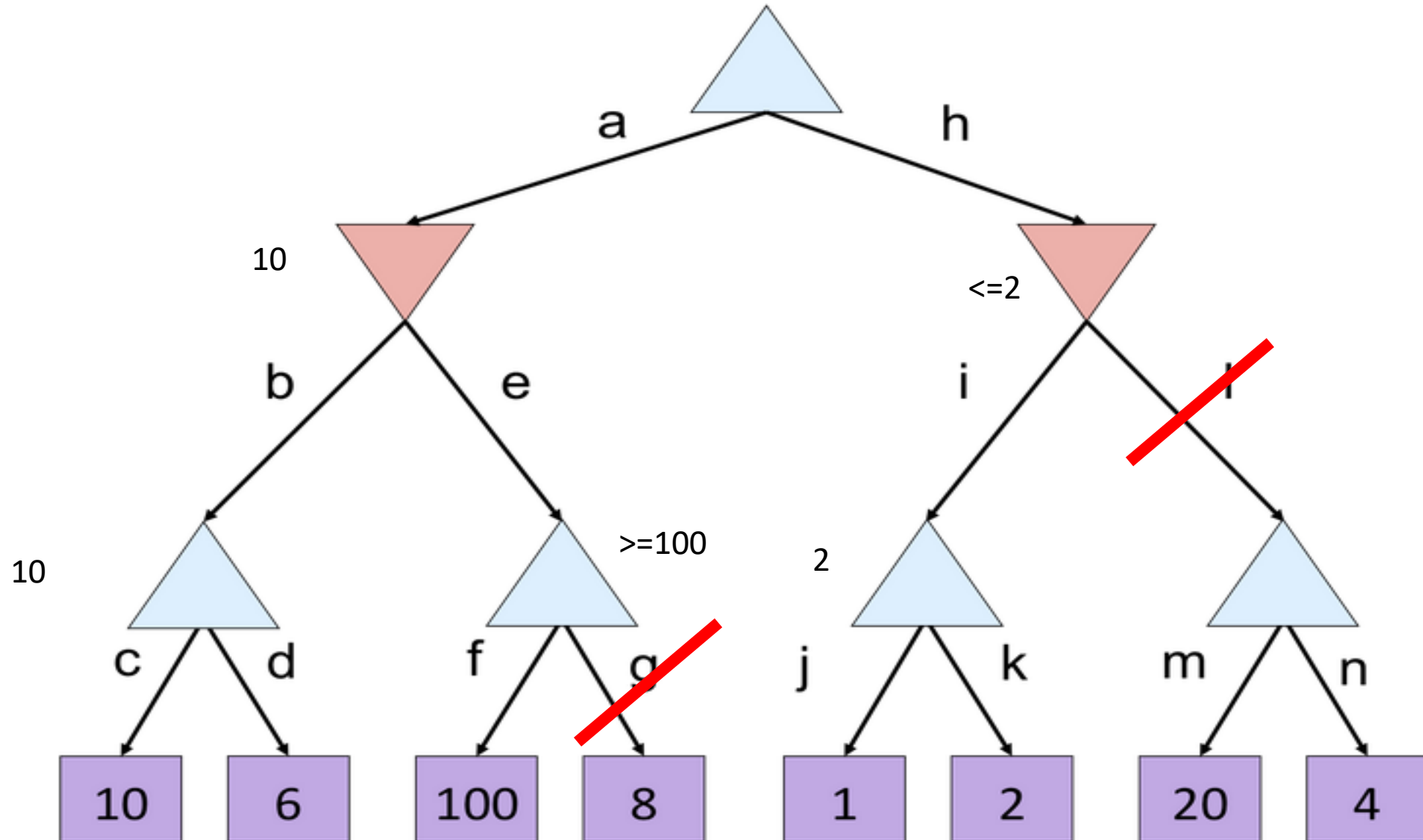
Alpha-Beta Quiz



Alpha-Beta Quiz 2

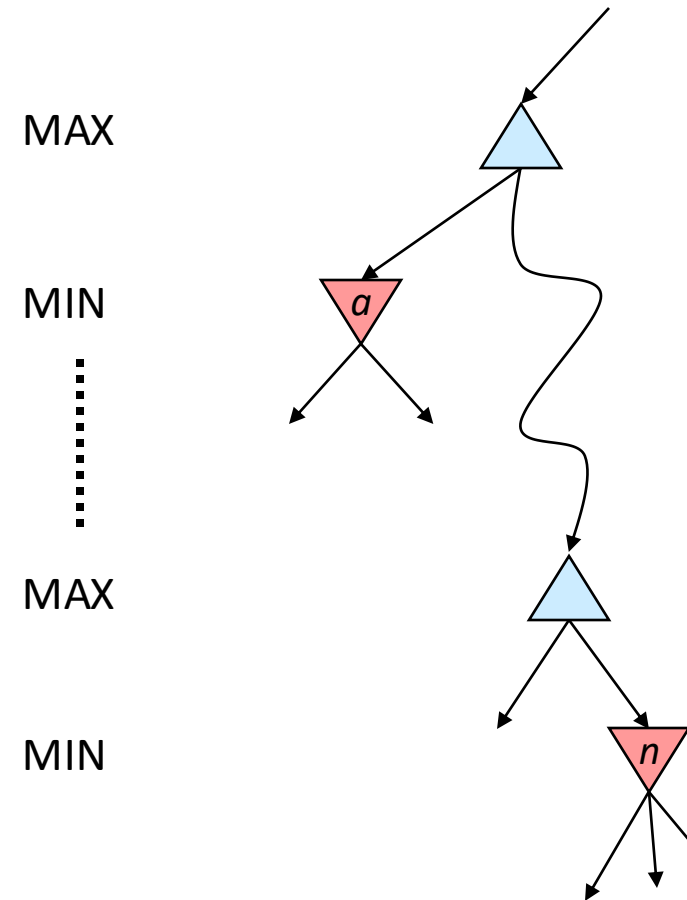


Alpha-Beta Quiz 2



Alpha-Beta Pruning

- General case (pruning children of MIN node)
 - We're computing the MIN-VALUE at some node n
 - We're looping over n 's children
 - n 's estimate of the childrens' min is dropping
 - Who cares about n 's value? MAX
 - Let α be the best value that MAX can get so far at any choice point along the current path from the root
 - If n becomes worse than α , MAX will avoid it, so we can prune n 's other children (it's already bad enough that it won't be played)
- Pruning children of MAX node is symmetric
 - Let β be the best value that MIN can get so far at any choice point along the current path from the root



Alpha-Beta Implementation

α : MAX's best option on path to root
 β : MIN's best option on path to root

```
def max-value(state,  $\alpha$ ,  $\beta$ ):  
    initialize  $v = -\infty$   
    for each successor of state:  
         $v = \max(v, \text{min-value}(\text{successor}, \alpha, \beta))$   
        if  $v \geq \beta$   
            return  $v$   
         $\alpha = \max(\alpha, v)$   
    return  $v$ 
```

```
def min-value(state,  $\alpha$ ,  $\beta$ ):  
    initialize  $v = +\infty$   
    for each successor of state:  
         $v = \min(v, \text{max-value}(\text{successor}, \alpha, \beta))$   
        if  $v \leq \alpha$   
            return  $v$   
         $\beta = \min(\beta, v)$   
    return  $v$ 
```

Alpha-Beta Implementation

function minimax-decision(s) returns an action

return the action a in $\text{Actions}(s)$ with the highest
 $\text{max-value}(\text{Result}(s,a), -\infty, +\infty)$

def max-value(state, α , β):

initialize $v = -\infty$

for each successor of state:

$v = \max(v, \text{min-value}(\text{successor}, \alpha, \beta))$

if $v \geq \beta$

return v

$\alpha = \max(\alpha, v)$

return v

def min-value(state, α , β):

initialize $v = +\infty$

for each successor of state:

$v = \min(v, \text{max-value}(\text{successor}, \alpha, \beta))$

if $v \leq \alpha$

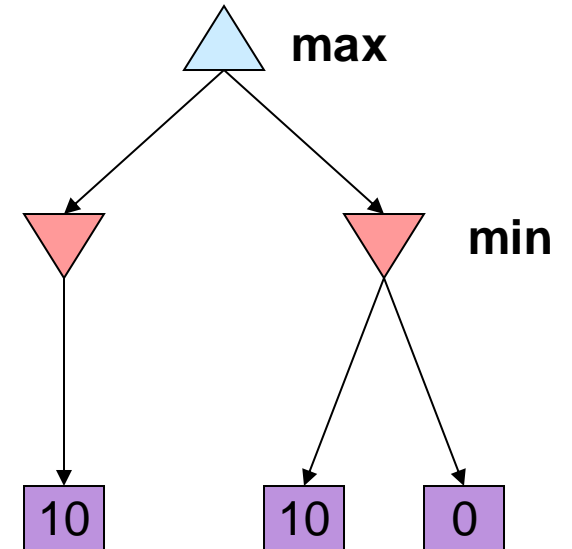
return v

$\beta = \min(\beta, v)$

return v

Alpha-Beta Pruning Properties

- Theorem: This pruning has **no effect** on minimax value computed for the root!
- Good child ordering improves effectiveness of pruning
 - Iterative deepening helps with this
- With “perfect ordering”:
 - Time complexity drops to $O(b^{m/2})$
 - Square root!
 - Doubles solvable depth!
- This is a simple example of **metareasoning** (reasoning about reasoning)
- For chess: only 35^{50} instead of 35^{100} ! Yay!

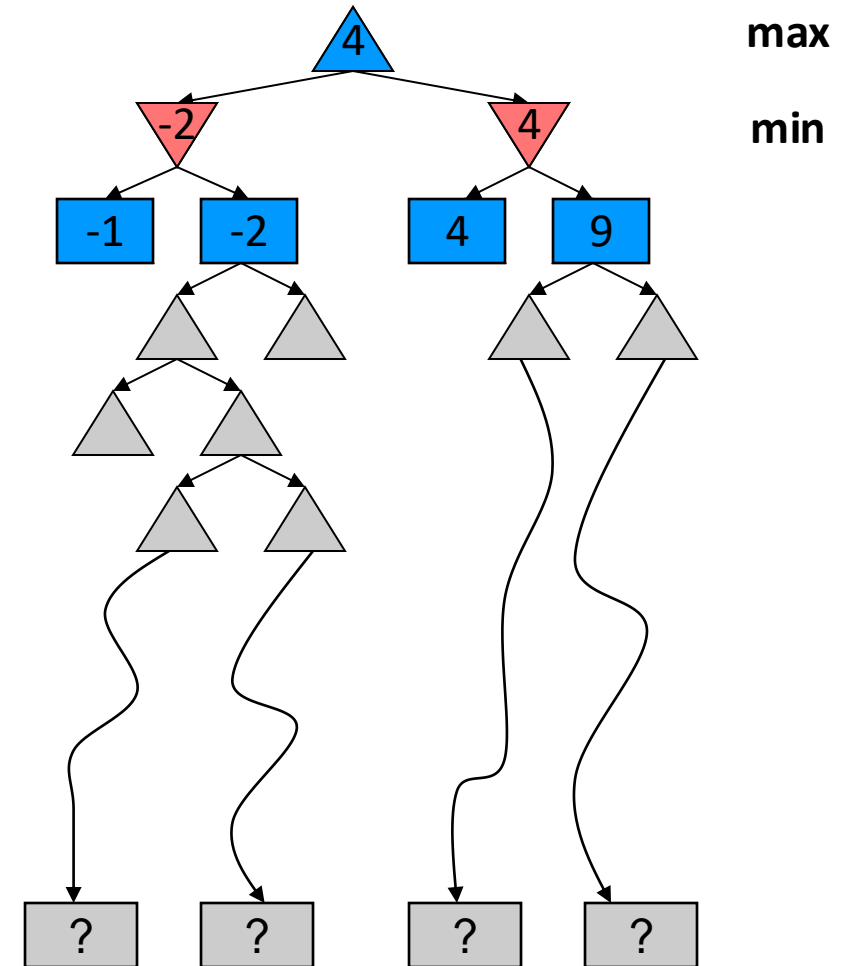


Resource Limits

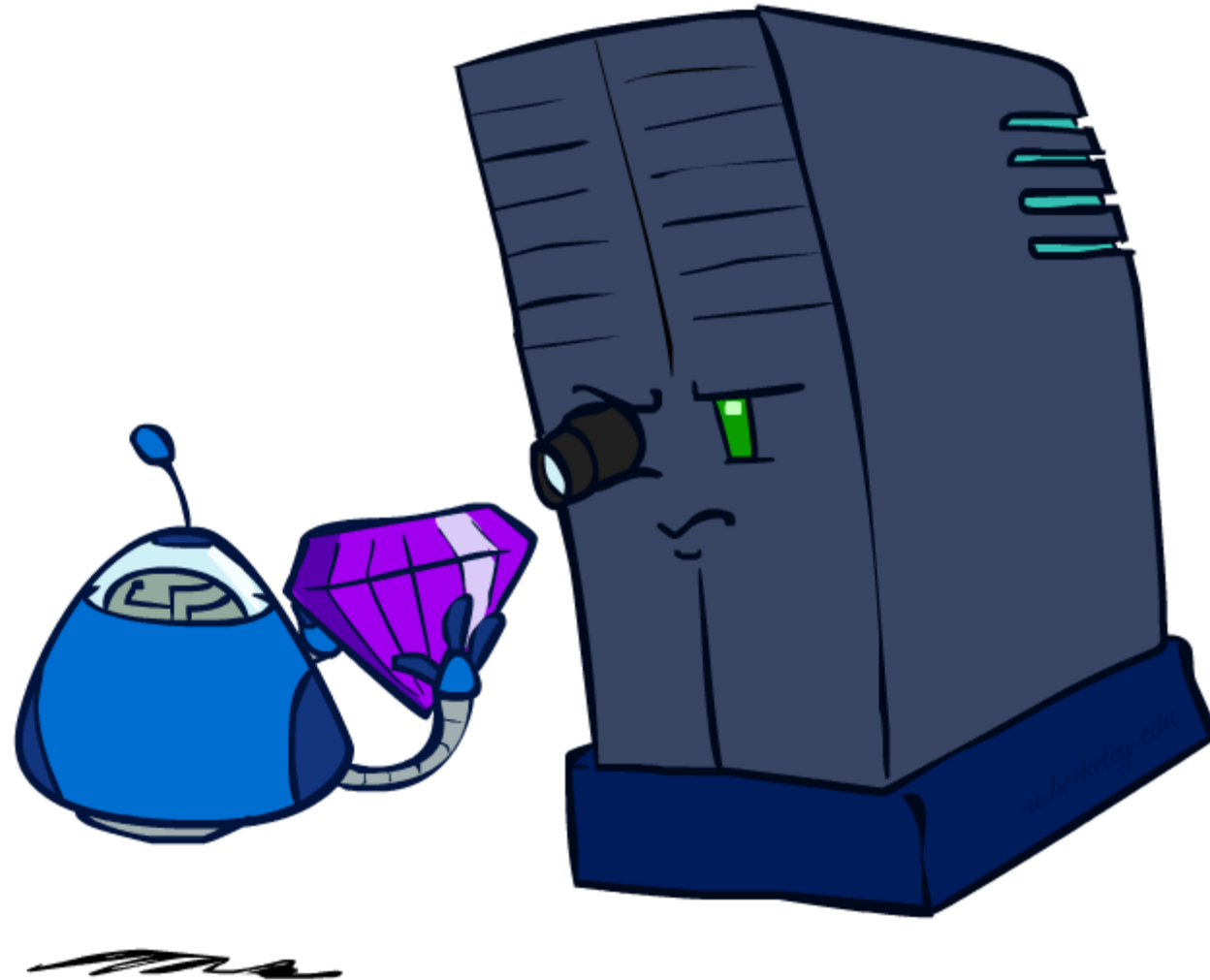


Resource Limits

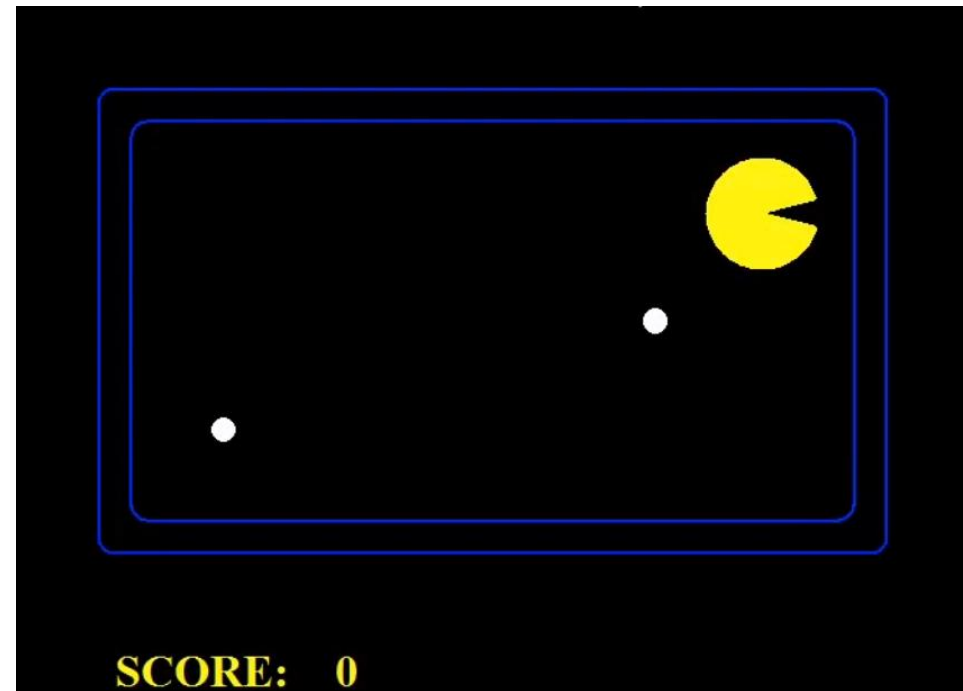
- Problem: In realistic games, cannot search to leaves!
- Solution: Depth-limited search
 - Instead, search only to a limited depth in the tree
 - Replace terminal utilities with **an evaluation function** for non-terminal positions
- Example:
 - Suppose we have 100 seconds, can explore 10K nodes / sec
 - So can check 1M nodes per move
 - α - β reaches about depth 8 – decent chess program
- Guarantee of optimal play is gone
- More plies makes a BIG difference
- Use iterative deepening for an anytime algorithm



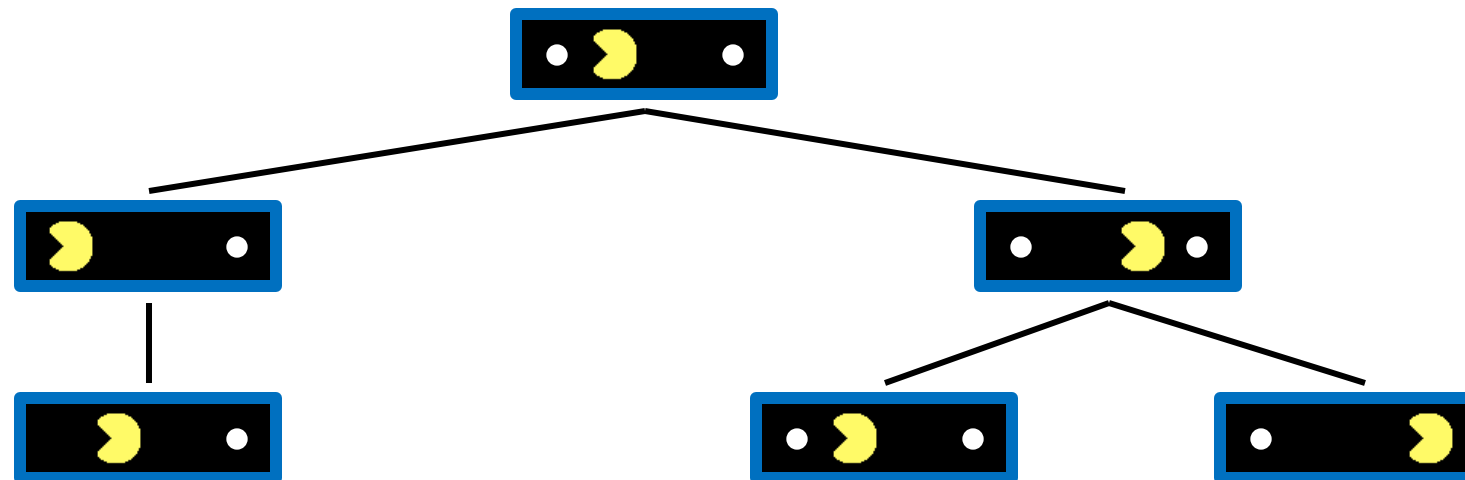
Evaluation Functions



Video of Demo Thrashing (d=2)



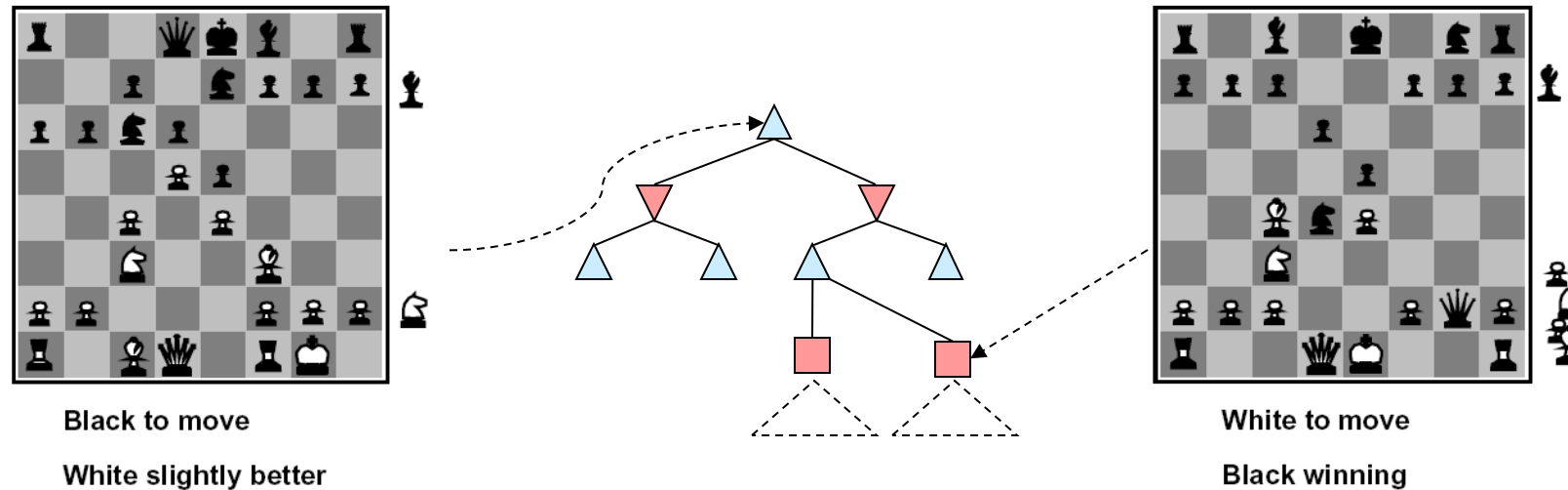
Why Pacman Starves



- A danger of replanning agents!
 - He knows his score will go up by eating the dot now (west, east)
 - He knows his score will go up just as much by eating the dot later (east, west)
 - There are no point-scoring opportunities after eating the dot (within the horizon, two here)
 - Therefore, waiting seems just as good as eating: he may go east, then back west in the next round of replanning!

Evaluation Functions

- Evaluation functions score non-terminals in depth-limited search

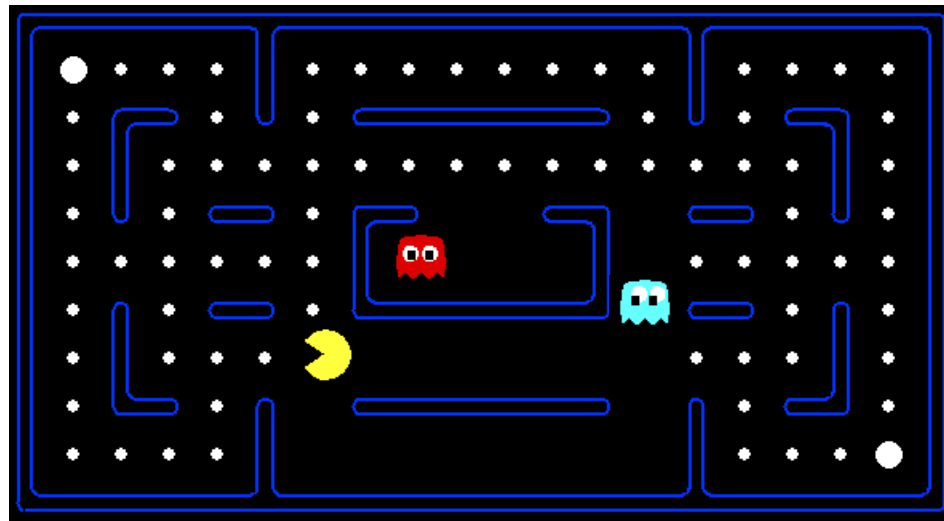


- Ideal function: returns the actual minimax value of the position
- In practice: typically weighted linear sum of features:

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \dots + w_n f_n(s)$$

- e.g. $f_1(s) = (\text{num white queens} - \text{num black queens})$, etc.

Evaluation for Pacman

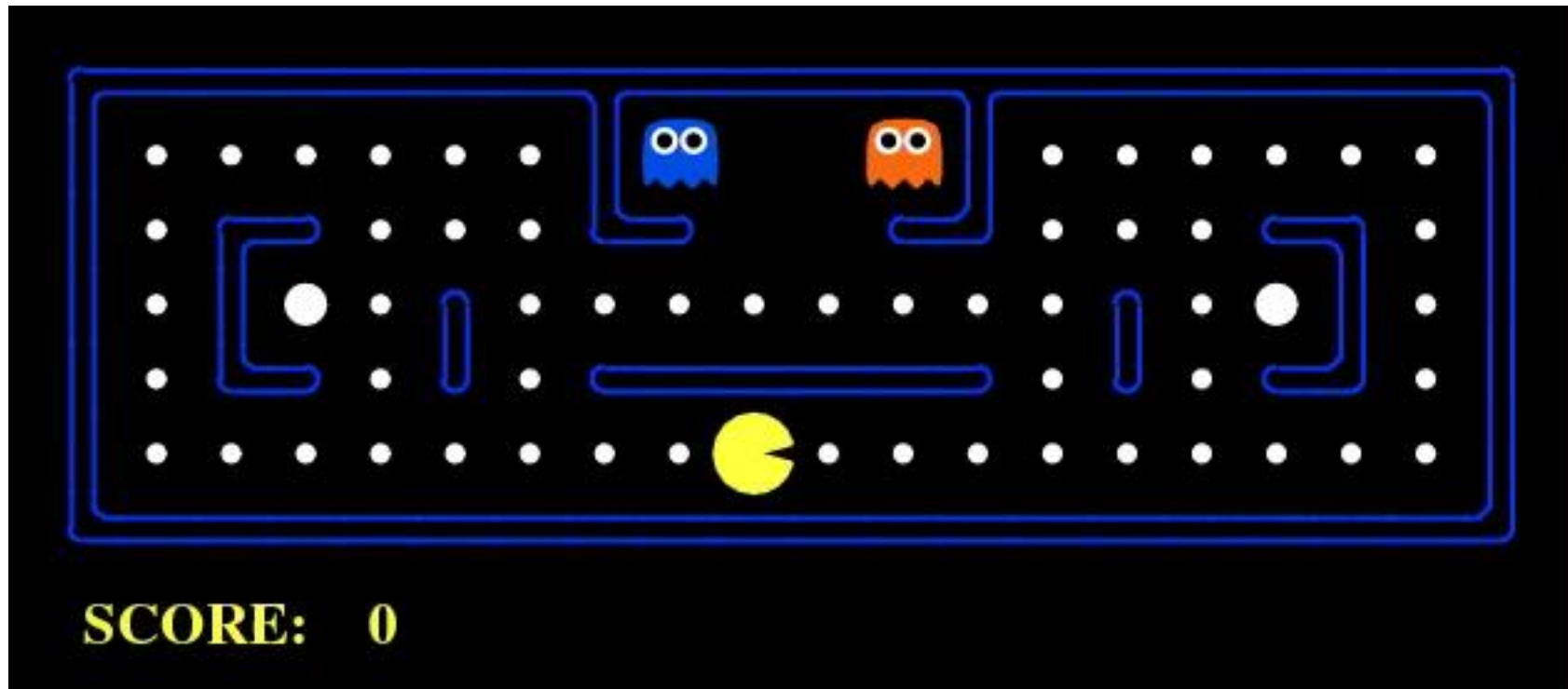


What features would be good for Pacman?

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \dots + w_n f_n(s)$$

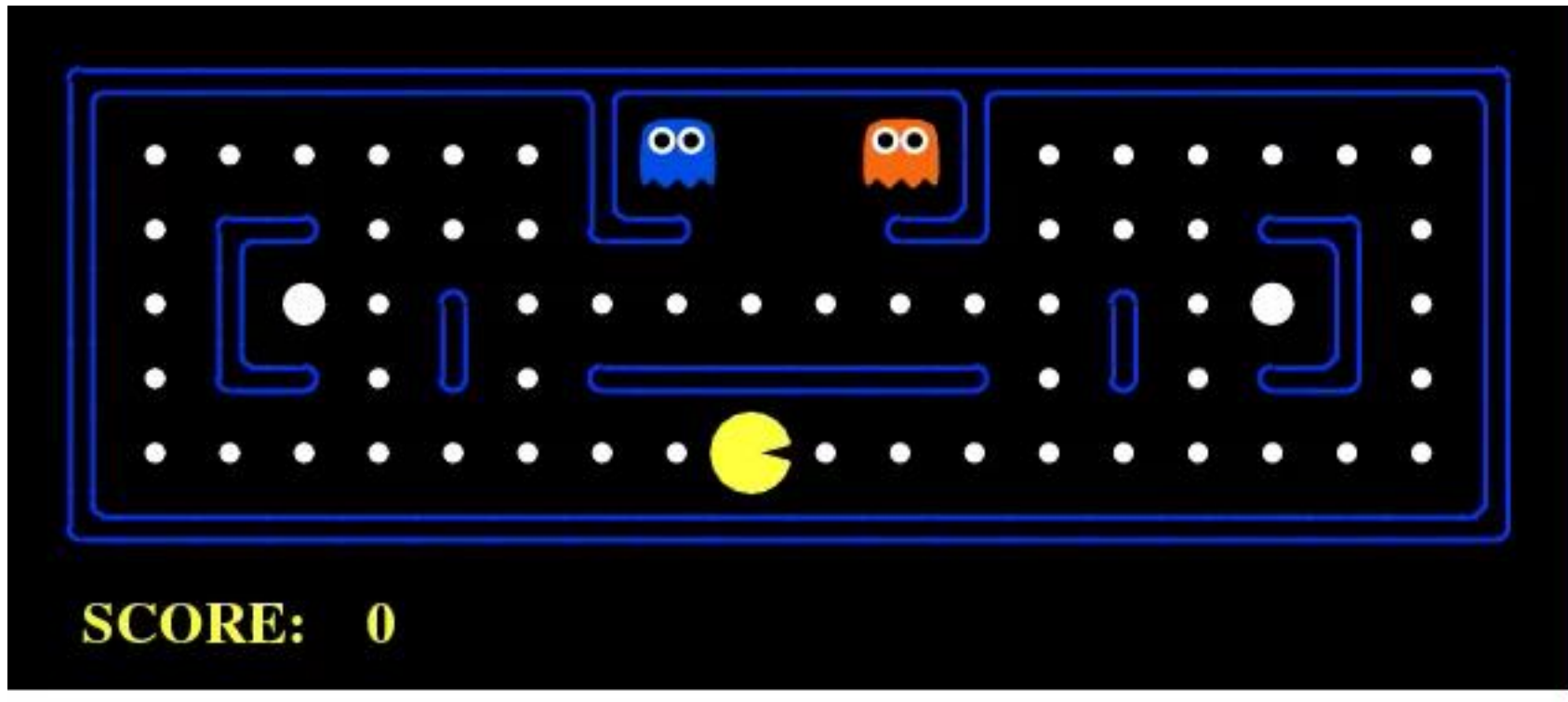
Which algorithm?

$\langle - \textcircled{R} \rangle$, depth 4, simple eval fun



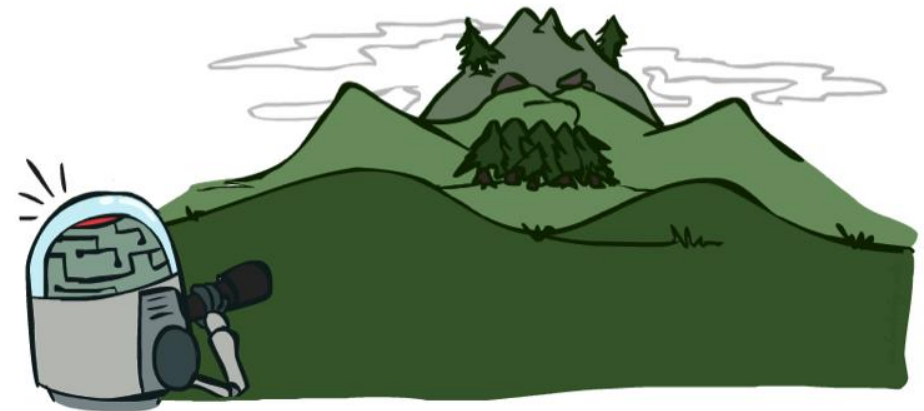
Which algorithm?

$\langle -^{\circledR}$, depth 4, better eval fun

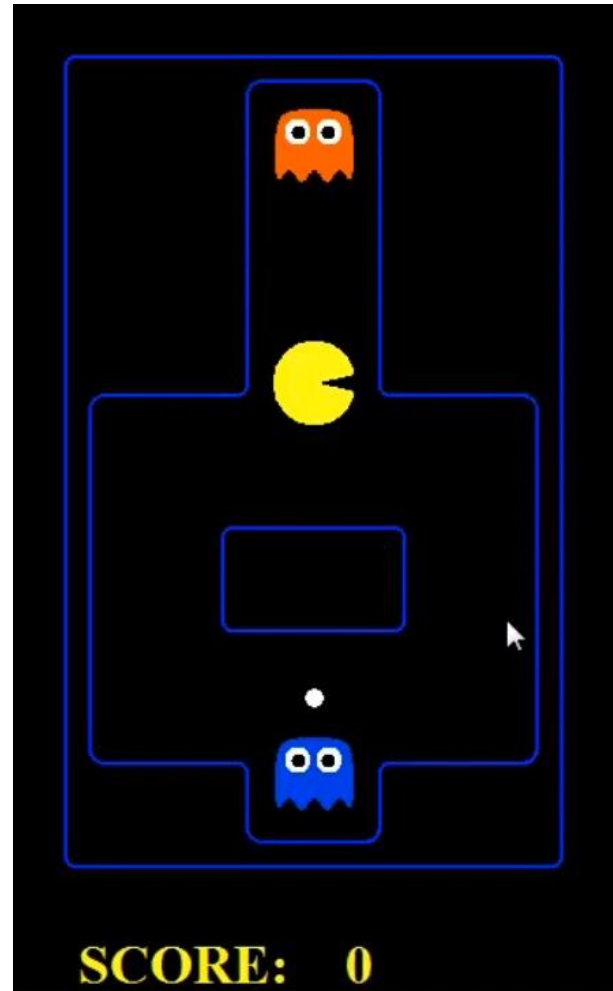


Depth Matters

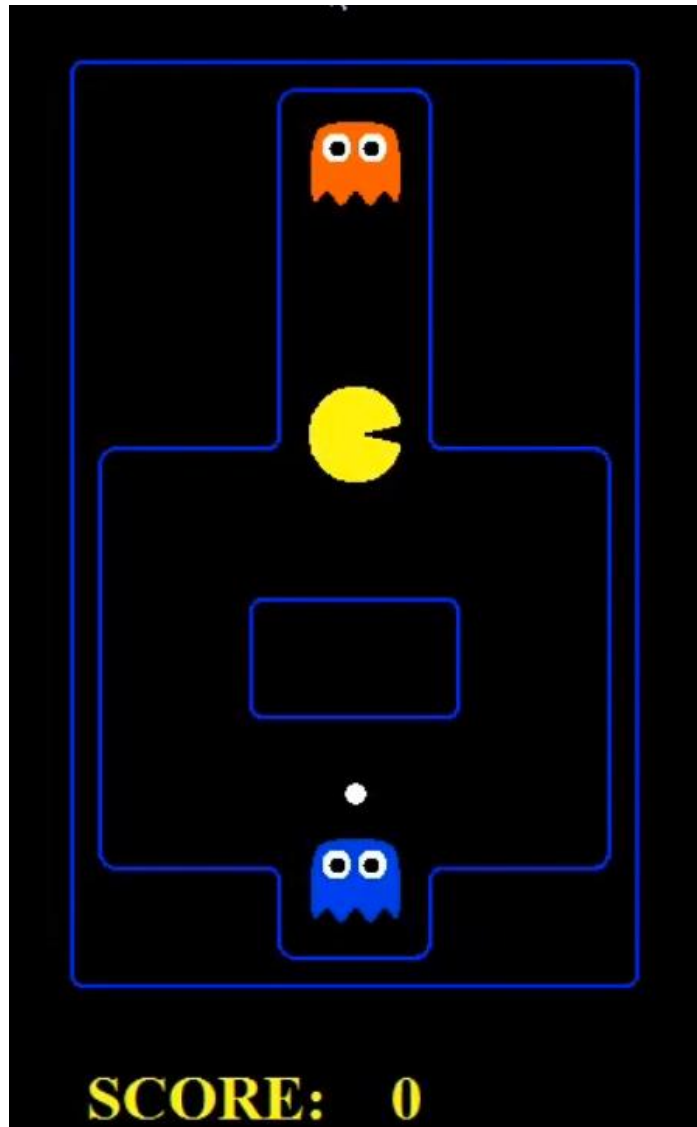
- Evaluation functions are always imperfect
- The deeper in the tree the evaluation function is buried, the less the quality of the evaluation function matters
- An important example of the tradeoff between complexity of features and complexity of computation



Video of Demo Limited Depth (2)



Video of Demo Limited Depth (10)



Synergies between Alpha-Beta and Evaluation Function

- Alpha-Beta: amount of pruning depends on expansion ordering
 - Evaluation function can provide guidance to expand most promising nodes first
- Alpha-beta:
 - Value at a min-node will only keep going down
 - Once value of min-node lower than better option for max along path to root, can prune
 - Hence, IF evaluation function provides upper-bound on value at min-node, and upper-bound already lower than better option for max along path to root THEN can prune