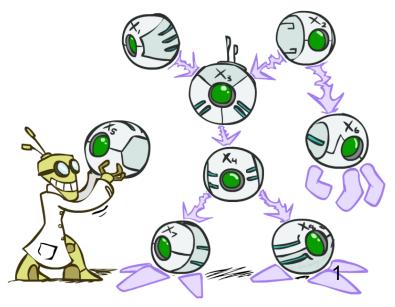
CSE 573: Artificial Intelligence

Hanna Hajishirzi Bayes Nets

slides adapted from Dan Klein, Pieter Abbeel ai.berkeley.edu And Dan Weld, Luke Zettelmoyer

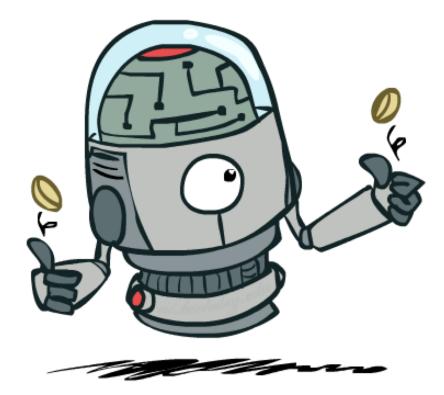


Probabilistic Models

- Models describe how (a portion of) the world works
- Models are always simplifications
 - May not account for every variable
 - May not account for all interactions between variables
 - "All models are wrong; but some are useful."
 George E. P. Box

- What do we do with probabilistic models?
 - We (or our agents) need to reason about unknown variables, given evidence
 - Example: explanation (diagnostic reasoning)
 - Example: prediction (causal reasoning)

Independence



Independence

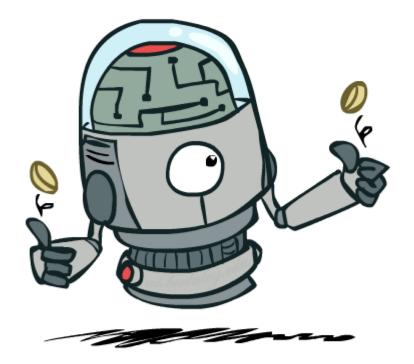
• Two variables are *independent* if:

$$\forall x, y \colon P(x, y) = P(x)P(y)$$

- This says that their joint distribution *factors* into a product two simpler distributions
- Another form:

 $\forall x, y : P(x|y) = P(x)$

- We write: $X \! \perp \!\!\!\perp Y$
- Independence is a simplifying modeling assumption
 - *Empirical* joint distributions: at best "close" to independent
 - What could we assume for {Weather, Traffic, Cavity, Toothache}?



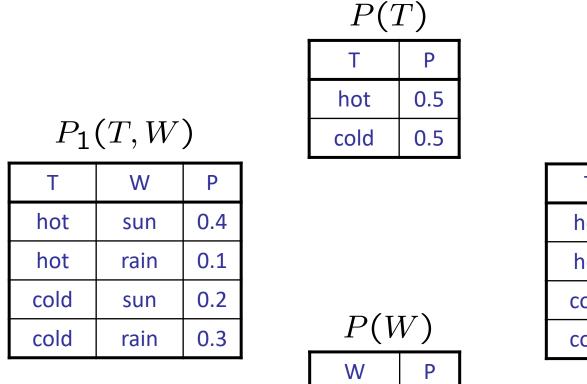
Example: Independence?

0.6

0.4

sun

rain

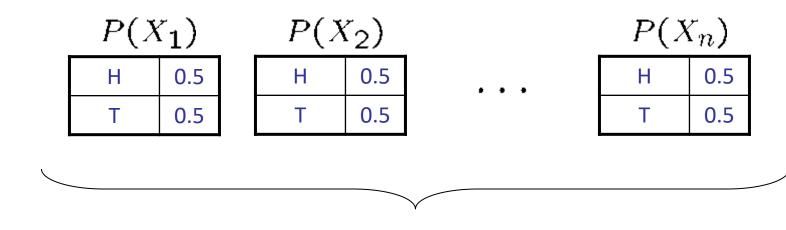


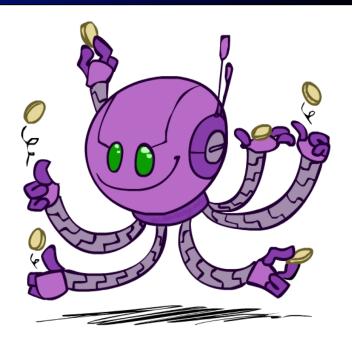
 $P_2(T,W)$

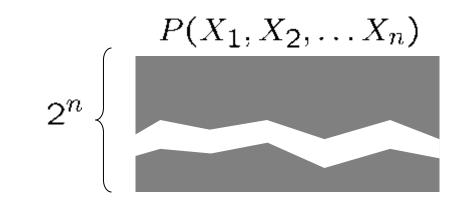
Т	W	Ρ
hot	sun	0.3
hot	rain	0.2
cold	sun	0.3
cold	rain	0.2

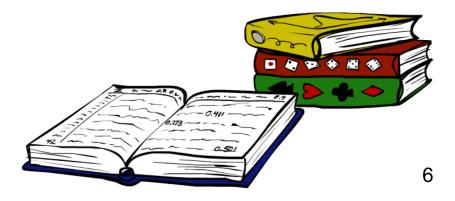
Example: Independence

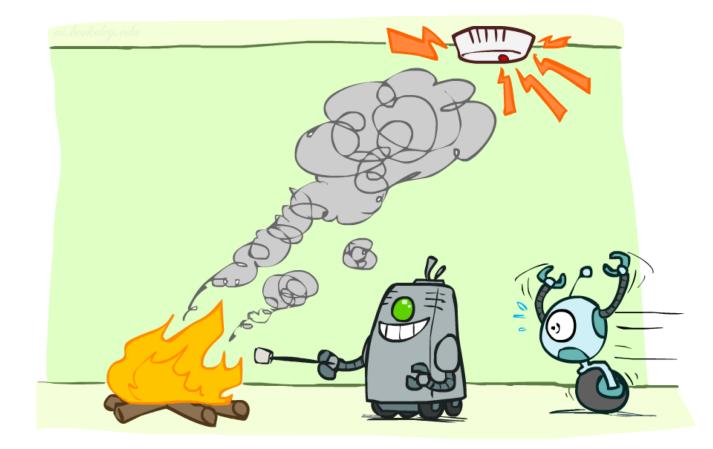
N fair, independent coin flips:



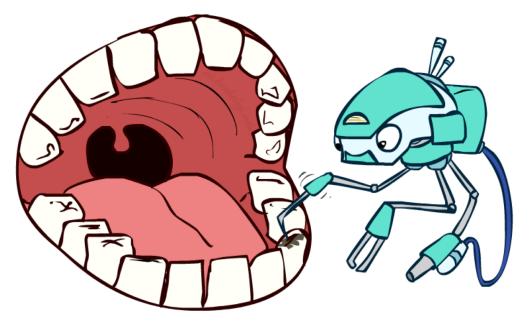








- P(Toothache, Cavity, Catch)
- If I have a cavity, the probability that the probe catches in it doesn't depend on whether I have a toothache:
 - P(+catch | +toothache, +cavity) = P(+catch | +cavity)
- The same independence holds if I don't have a cavity:
 - P(+catch | +toothache, -cavity) = P(+catch | -cavity)
- Catch is *conditionally independent* of Toothache given Cavity:
 - P(Catch | Toothache, Cavity) = P(Catch | Cavity)
- Equivalent statements:
 - P(Toothache | Catch , Cavity) = P(Toothache | Cavity)
 - P(Toothache, Catch | Cavity) = P(Toothache | Cavity) P(Catch | Cavity)
 - One can be derived from the other easily



- Unconditional (absolute) independence very rare (why?)
- Conditional independence is our most basic and robust form of knowledge about uncertain environments.
- X is conditionally independent of Y given Z

 $X \perp \!\!\!\perp Y | Z$

if and only if:

 $\forall x, y, z : P(x, y|z) = P(x|z)P(y|z)$

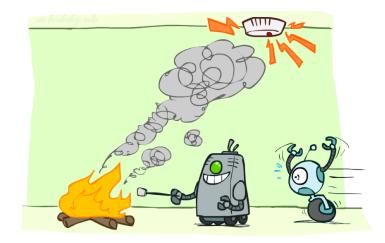
or, equivalently, if and only if

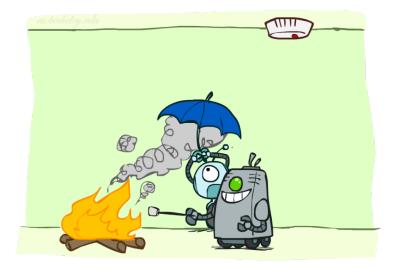
$$\forall x, y, z : P(x|z, y) = P(x|z)$$

- What about this domain:
 - Traffic
 - Umbrella
 - Raining



- What about this domain:
 - Fire
 - Smoke
 - Alarm





Conditional Independence and the Chain Rule

- Chain rule: $P(X_1, X_2, \dots, X_n) = P(X_1)P(X_2|X_1)P(X_3|X_1, X_2)\dots$
- Trivial decomposition:

P(Traffic, Rain, Umbrella) =P(Rain)P(Traffic|Rain)P(Umbrella|Rain, Traffic)

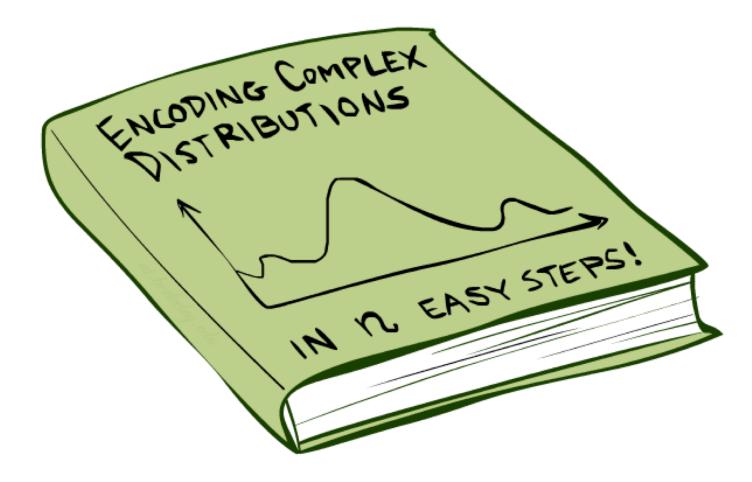
With assumption of conditional independence:

P(Traffic, Rain, Umbrella) =P(Rain)P(Traffic|Rain)P(Umbrella|Rain)

- We can represent joint distributions by multiplying these simpler local distributions.
- Bayes'nets / graphical models help us express conditional independence assumptions 13

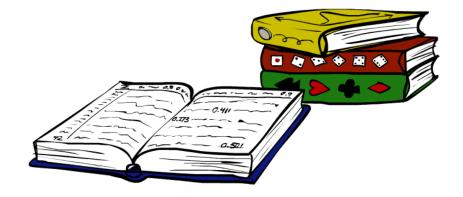


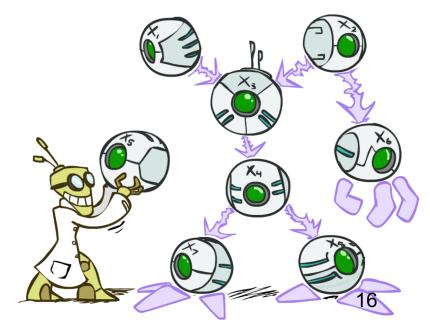
Bayes'Nets: Big Picture



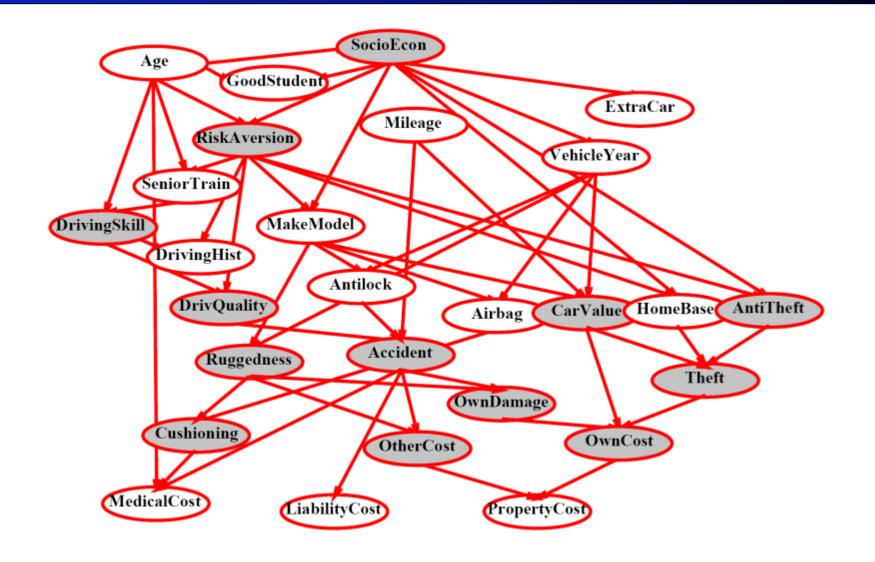
Bayes' Nets: Big Picture

- Two problems with using full joint distribution tables as our probabilistic models:
 - Unless there are only a few variables, the joint is WAY too big to represent explicitly
 - Hard to learn (estimate) anything empirically about more than a few variables at a time
- Bayes' nets: a technique for describing complex joint distributions (models) using simple, local distributions (conditional probabilities)
 - More properly called graphical models
 - We describe how variables locally interact
 - Local interactions chain together to give global, indirect interactions
 - For about 10 min, we'll be vague about how these interactions are specified

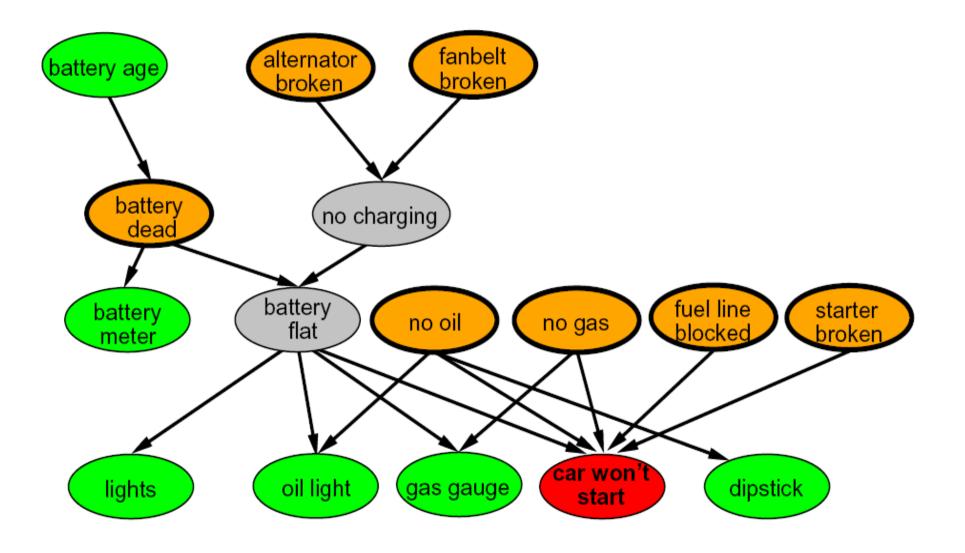




Example Bayes' Net: Insurance

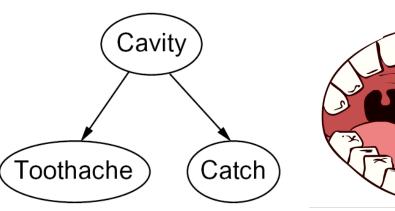


Example Bayes' Net: Car



Graphical Model Notation

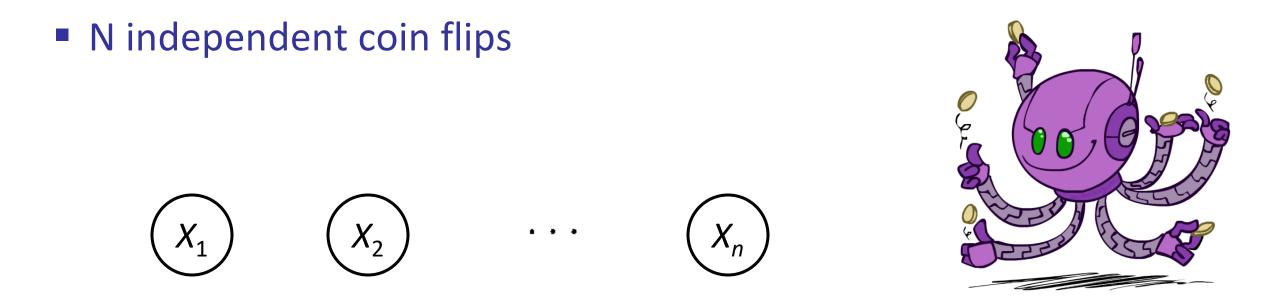
- Nodes: variables (with domains)
 - Can be assigned (observed) or unassigned (unobserved)
- Arcs: interactions
 - Indicate "direct influence" between variables
 - Formally: encode conditional independence (more later)
- For now: imagine that arrows mean direct causation (in general, they don't!)



Weather



Example: Coin Flips



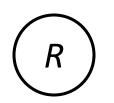
No interactions between variables: absolute independence

Example: Traffic

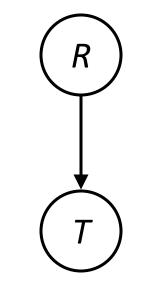
- Variables:
 - R: It rains
 - T: There is traffic



Model 1: independence



Model 2: rain causes traffic





Why is an agent using model 2 better?

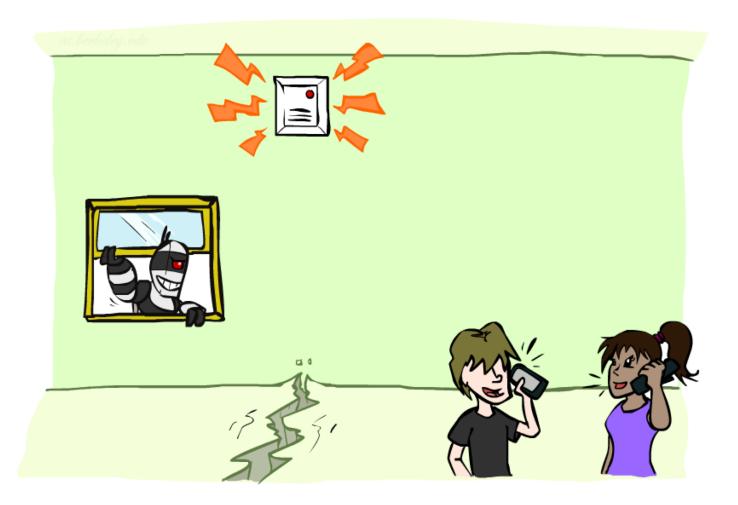
Example: Traffic II

- Variables
 - T: Traffic
 - R: It rains
 - L: Low pressure
 - D: Roof drips
 - B: Ballgame
 - C: Cavity



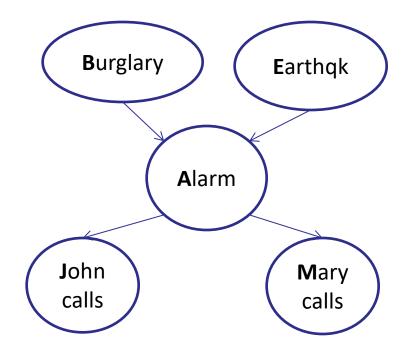
Example: Alarm Network

- Variables
 - B: Burglary
 - A: Alarm goes off
 - M: Mary calls
 - J: John calls
 - E: Earthquake!



Example: Alarm Network

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Bayes' Net Semantics



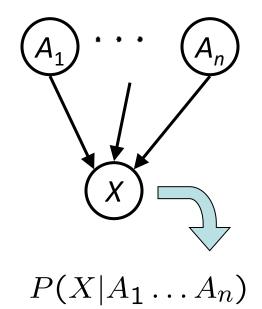
Bayes' Net Semantics



- A set of nodes, one per variable X
- A directed, acyclic graph
- A conditional distribution for each node
 - A collection of distributions over X, one for each combination of parents' values

 $P(X|a_1\ldots a_n)$

- CPT: conditional probability table
- Description of a noisy "causal" process



A Bayes net = Topology (graph) + Local Conditional Probabilities

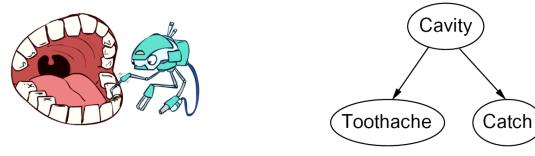
Probabilities in BNs



- Bayes' nets implicitly encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | parents(X_i))$$

• Example:



P(+cavity, +catch, -toothache)

=P(-toothache|+cavity)P(+catch|+cavity)P(+cavity)

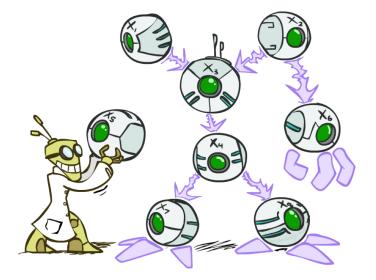
Bayes' Net Representation

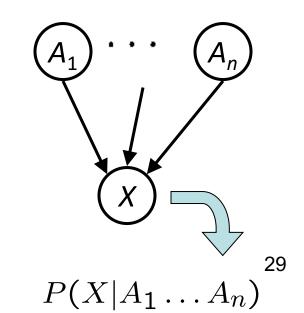
- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
 - A collection of distributions over X, one for each combination of parents' values

 $P(X|a_1\ldots a_n)$

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Probabilities in BNs



Why are we guaranteed that setting

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | parents(X_i))$$

results in a proper joint distribution?

• Chain rule (valid for all distributions):

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | x_1 \dots x_{i-1})$$

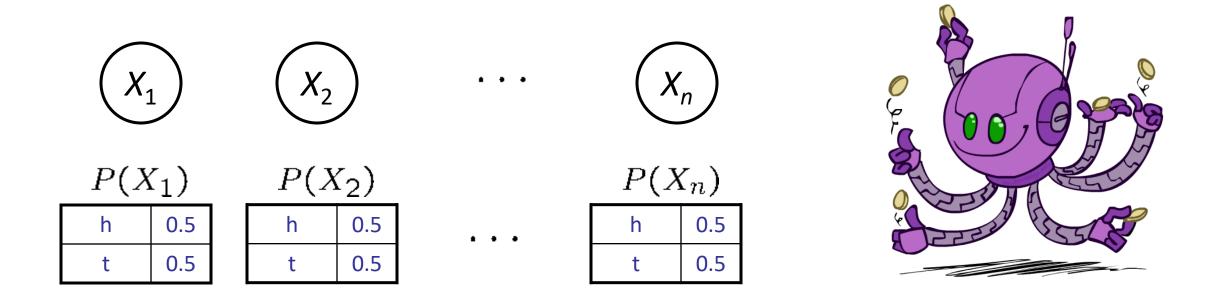
<u>Assume</u> conditional independences:

$$P(x_i|x_1,\ldots,x_{i-1}) = P(x_i|parents(X_i))$$

→ Consequence:
$$P(x_1, x_2, ..., x_n) = \prod_{i=1}^n P(x_i | parents(X_i))$$

- Not every BN can represent every joint distribution
 - The topology enforces certain conditional independencies

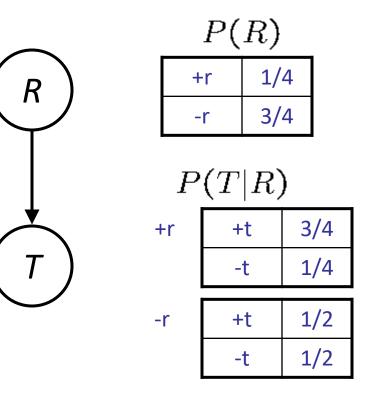
Example: Coin Flips



P(h, h, t, h) = P(h)P(h)P(t)P(h)

Only distributions whose variables are absolutely independent can be represented by a Bayes ' net with no arcs.

Example: Traffic

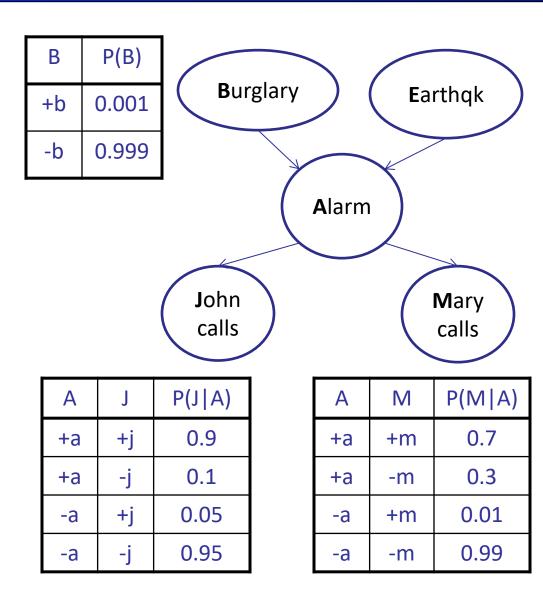


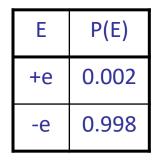
$$P(+r, -t) = P(+r)P(-t|+r) = \frac{1}{4} + \frac{1}{4}$$

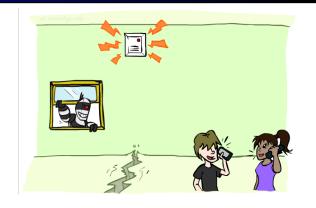




Example: Alarm Network







В	Ε	Α	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-е	+a	0.94
+b	-е	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-е	+a	0.001
-b	-е	-a	0.999

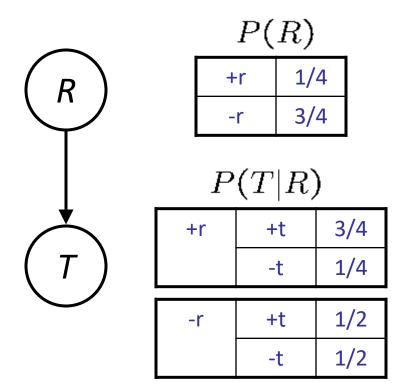
P(M|A)P(J|A)P(A|B,E)

Example: Traffic

Causal direction







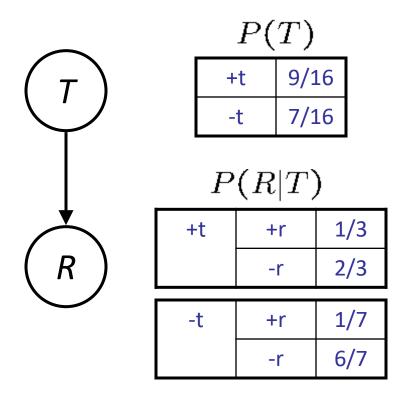
P(T,R)

+r	+t	3/16
+r	-t	1/16
-r	+t	6/16
-r	-t	6/16

Example: Reverse Traffic

Reverse causality?





P(T,R)

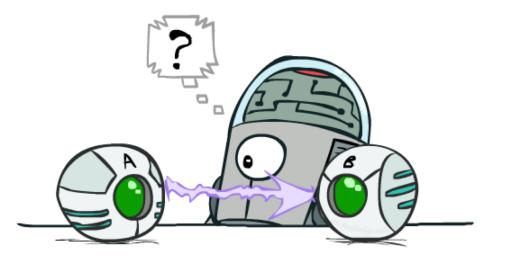
+r	+t	3/16
+r	-t	1/16
-r	+t	6/16
-r	-t	6/16

Causality?

• When Bayes' nets reflect the true causal patterns:

- Often simpler (nodes have fewer parents)
- Often easier to think about
- Often easier to elicit from experts
- BNs need not actually be causal
 - Sometimes no causal net exists over the domain (especially if variables are missing)
 - E.g. consider the variables *Traffic* and *Drips*
 - End up with arrows that reflect correlation, not causation
- What do the arrows really mean?
 - Topology may happen to encode causal structure
 - Topology really encodes conditional independence

 $P(x_i|x_1,\ldots,x_{i-1}) = P(x_i|parents(X_i))$



Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
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 $P(X|a_1\ldots a_n)$

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