

CSE-571 Robotics

Gaussian Distributions

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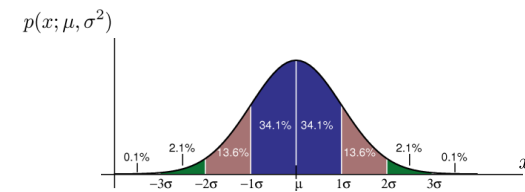
Gaussians (1D)

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- Gaussian with mean (μ) and standard deviation (σ)

$$X \sim \mathcal{N}(\mu, \sigma^2)$$

$$p(x; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$



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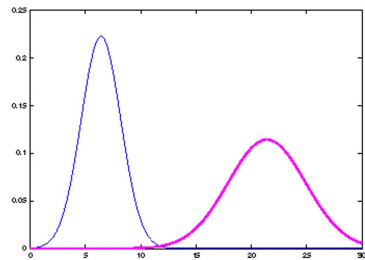
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Properties of Gaussians

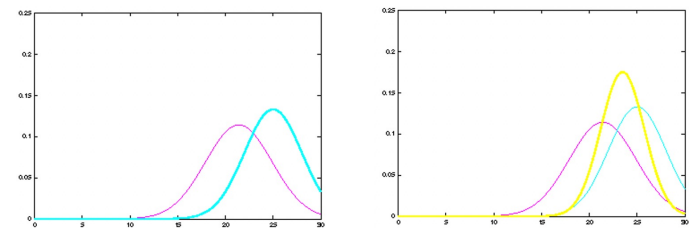
$$\left. \begin{array}{l} X \sim \mathcal{N}(\mu, \sigma^2) \\ Y = aX + b \end{array} \right\} \Rightarrow Y \sim \mathcal{N}(a\mu + b, a^2\sigma^2)$$



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Properties of Gaussians

$$\left. \begin{array}{l} X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2) \\ X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2) \end{array} \right\} \Rightarrow p(X_1) \cdot p(X_2) \sim \mathcal{N}\left(\frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2} \mu_1 + \frac{\sigma_1^2}{\sigma_1^2 + \sigma_2^2} \mu_2, \frac{1}{\sigma_1^{-2} + \sigma_2^{-2}}\right)$$



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Picture from [Bishop: Pattern Recognition and Machine Learning, 2006]

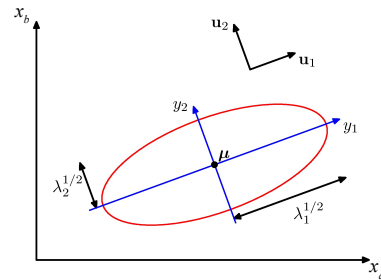
Gaussians (2D)

$$p(\mathbf{x}) = \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$\mathbf{x} = \begin{pmatrix} x_a \\ x_b \end{pmatrix}, \quad \boldsymbol{\mu} = \begin{pmatrix} \mu_a \\ \mu_b \end{pmatrix}$$

$$\boldsymbol{\Sigma} = \begin{pmatrix} \Sigma_{aa} & \Sigma_{ab} \\ \Sigma_{ba} & \Sigma_{bb} \end{pmatrix}$$

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})}$$



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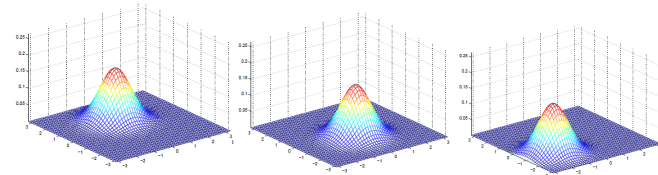
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2D examples



- $\boldsymbol{\mu} = [1; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

- $\boldsymbol{\mu} = [-.5; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

- $\boldsymbol{\mu} = [-1; -1.5]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

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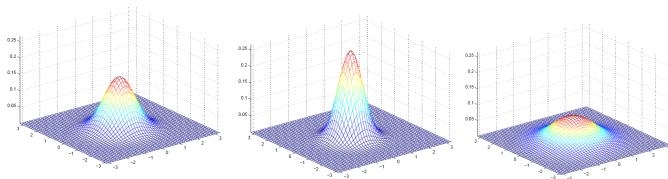
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2D examples



- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} .6 & 0 \\ 0 & .6 \end{bmatrix}$

- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$

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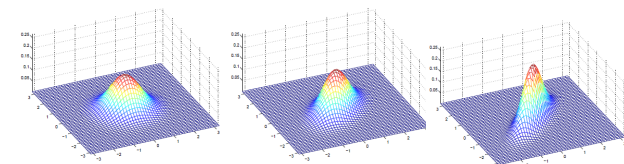
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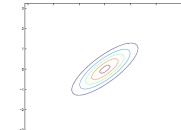
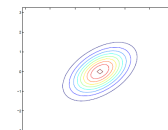
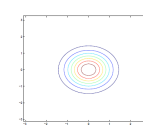
2D examples



- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$

- $\boldsymbol{\mu} = [0; 0]$
- $\boldsymbol{\Sigma} = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$



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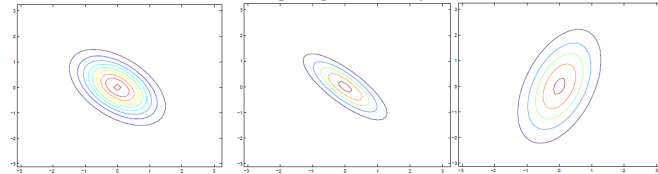
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2D examples

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- $\mu = [0; 0]$
 $\Sigma = [1 \ -0.5; -0.5 \ 1]$
- $\mu = [0; 0]$
 $\Sigma = [1 \ -0.8; -0.8 \ 1]$
- $\mu = [0; 0]$
 $\Sigma = [1 \ 0.8; 0.8 \ 3]$

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Marginalization / Conditioning

Pictures from [Bishop: PRML, 2006]

- Marginalizing joint distribution results in a Gaussian

$$p\left(\begin{bmatrix} x_a \\ x_b \end{bmatrix}\right) = \mathcal{N}\left(\begin{bmatrix} \mu_a \\ \mu_b \end{bmatrix}, \begin{bmatrix} \Sigma_{aa} & \Sigma_{ab} \\ \Sigma_{ba} & \Sigma_{bb} \end{bmatrix}\right) \quad p(x_a) = \int p(x_a, x_b) dx_b$$

$$p(x_a) = \mathcal{N}(\mu_a, \Sigma_{aa})$$

- Conditioning also leads to a Gaussian

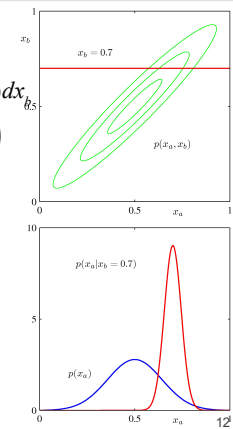
$$p(x_a | x_b) = \mathcal{N}(\mu_{a|b}, \Sigma_{a|b})$$

$$\mu_{a|b} = \mu_a + \Sigma_{ab} \Sigma_{bb}^{-1} (x_b - \mu_b)$$

$\Sigma_{a|b} = \Sigma_{aa} - \underbrace{\Sigma_{ab} \Sigma_{bb}^{-1} \Sigma_{ba}}_{\text{Shrink term } (>= 0)}$

Labels for the equation above:

- Σ_{ab} : Cross co-variance
- Σ_{bb}^{-1} : Prior Variance (b)
- $(x_b - \mu_b)$: Observed value
- μ_b : Prior mean (b)
- Σ_{aa} : Prior Variance (a)



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