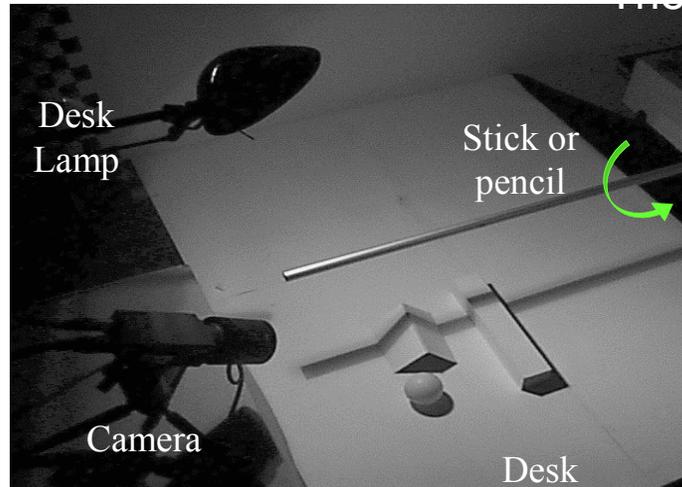
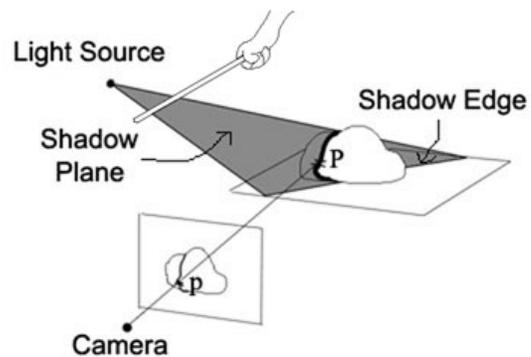


Shadow Scanning [Bouguet 1999]



J.-Y. Bouguet and P. Perona, "3D Photography on your desk", ICCV'98, pages 43-50, January 1998
available at: <http://www.vision.caltech.edu/bouguetj/ICCV98/>

Basic Idea

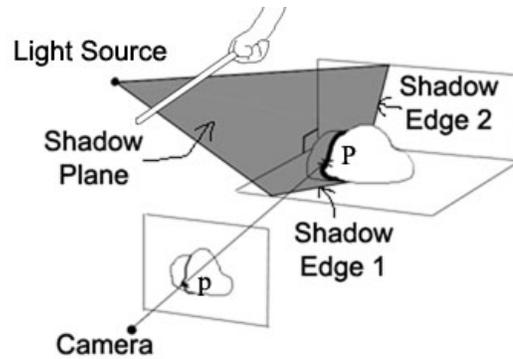


(from Jiwon Kim and Jia-chi Wu)

Calibration issues:

- where's the camera wrt. ground plane?
- where's the shadow plane?
 - depends on light source position, shadow edge

Two Plane Version

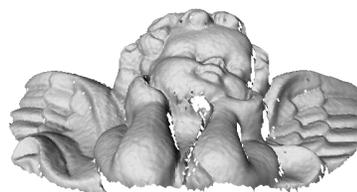


(from Jiwon Kim and Jia-chi Wu)

Advantage

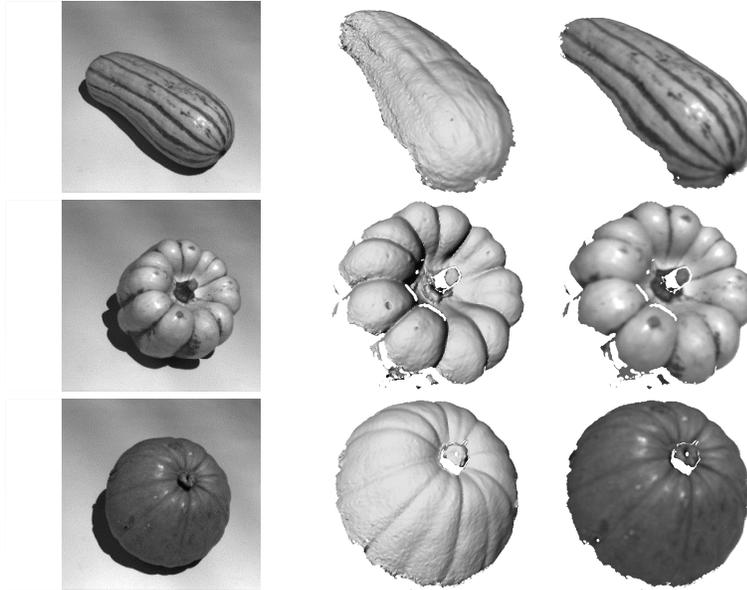
- don't need to pre-calibrate the light source
- shadow plane determined from two shadow edges

Angel experiment

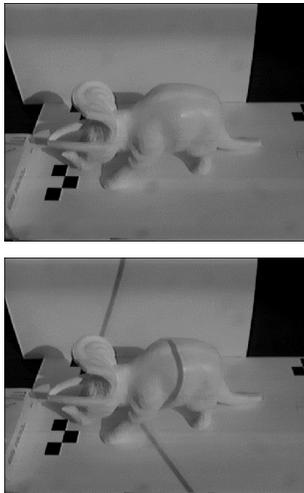


Accuracy: 0.1mm over 10cm → ~ 0.1% error

Textured objects

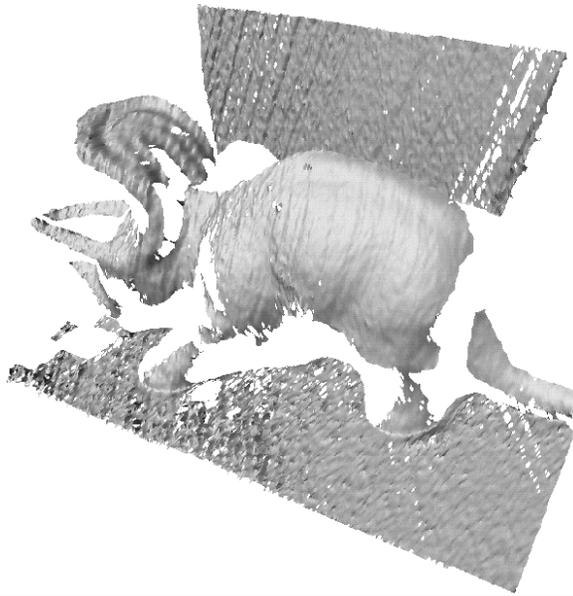


Scanning with the sun



Accuracy: 1mm over 50cm

 ~ 0.5% error

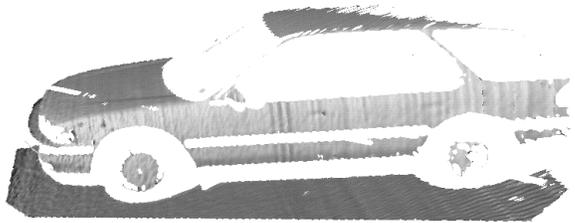
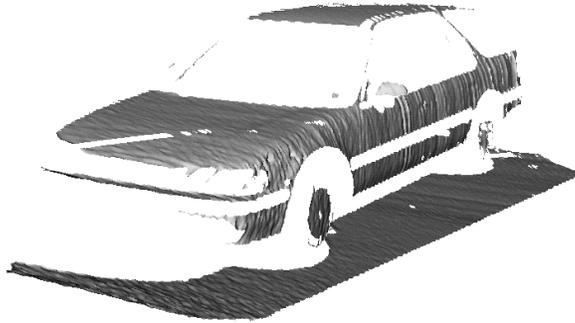


Scanning with the sun

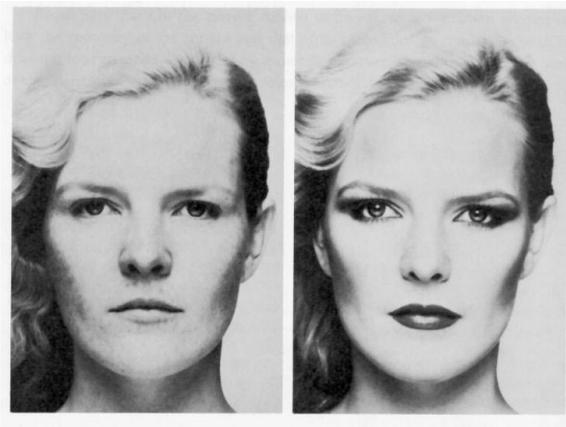


Accuracy: 1cm over 2m

→ ~ 0.5% error

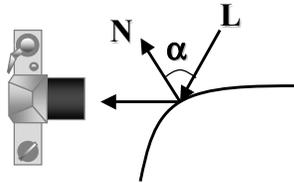


Shading as a 3D Cue



Merle Norman Cosmetics, Los Angeles

Shape from Shading [Horn, 1970]

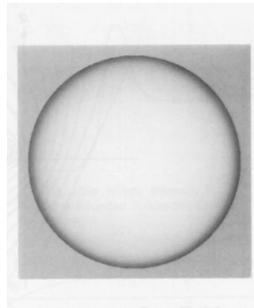
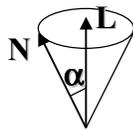


Classical Approach

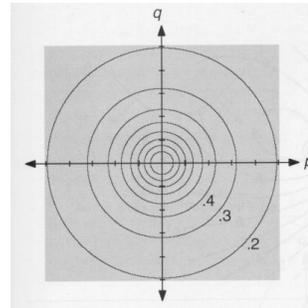
- Suppose reflected light depends only on α

$$\text{radiance} = k \cos \alpha$$

The Reflectance Map



Image



Reflectance Map:

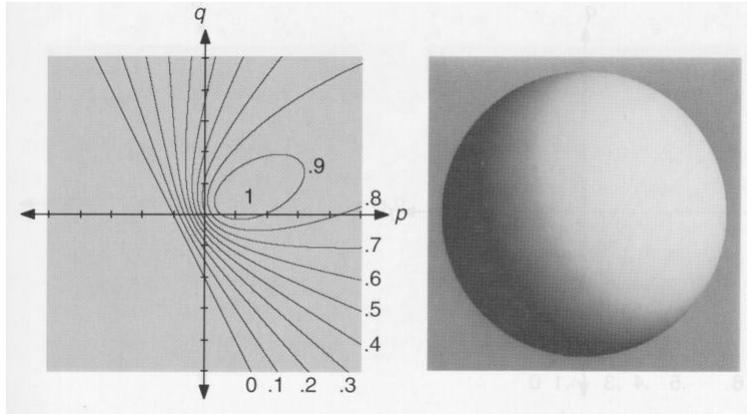
$$R(p,q) = \cos \alpha$$

Suppose

- image intensity = $\cos \alpha$
- L is known

$$\mathbf{N} = \begin{bmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} & -1 \end{bmatrix} = [p \quad q \quad -1]$$

The Reflectance Map



Reflectance Map

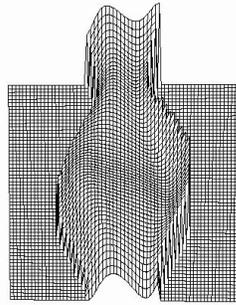
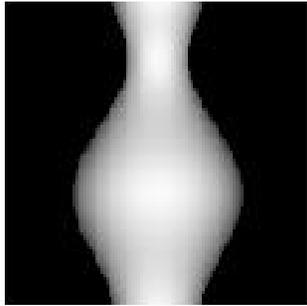
Image

Finding a Unique Solution

Three Approaches

- Characteristic Strip Method [Horn, 77]
 - select a few points where normal is known
 - grow solution by moving direction of ∇R
- Variational Method [Ikeuchi & Horn, 81]
 - start with an initial guess of surface shape
 - define energy function
 - refine to minimize energy function
- Photometric Stereo [Woodham 80]
 - use more images

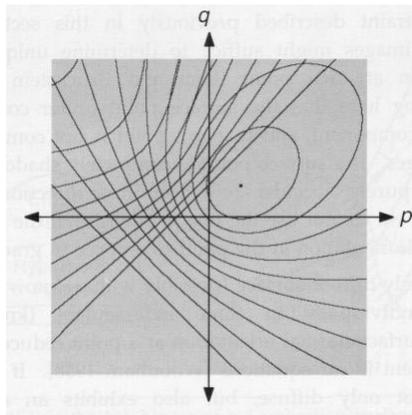
Shape from Shading



Lee & Kau 91 (from survey by Zhang et al., 1999)

Photometric Stereo

Two Images Under Different Lighting



Need Three Images for Unique Solution

Photometric Stereo: Matrix Formulation

Write Equations in Matrix Form

$$\begin{array}{l}
 \begin{array}{l} I_1 \\ I_2 \\ I_3 \end{array} = \begin{array}{l} \hat{\mathbf{L}}_1^T \\ \hat{\mathbf{L}}_2^T \\ \hat{\mathbf{L}}_3^T \end{array} \bullet \begin{array}{l} k\hat{\mathbf{N}} \\ k\hat{\mathbf{N}} \\ k\hat{\mathbf{N}} \end{array} \\
 \mathbf{I}_{3 \times 1} \quad \mathbf{L}_{3 \times 3} \quad \tilde{\mathbf{N}}_{3 \times 1}
 \end{array}
 \quad \longrightarrow \quad
 \begin{array}{l}
 \tilde{\mathbf{N}} = \mathbf{L}_1^{-1} \mathbf{I} \\
 k = \|\tilde{\mathbf{N}}\|
 \end{array}$$

Advantage:

- Can solve for reflectance k that varies over the surface

Depth from Normals

- Solve for $z(i,j)$ from (p,q)
- This is an integration problem—can be solved by minimizing an energy function:

$$\begin{aligned}
 E &= E_{data} + E_{smooth} + E_{constraint} \\
 &= \sum_{i,j} w_{data} * \left[\left(\frac{\partial z(i,j)}{\partial x} - p_{ij} \right)^2 + \left(\frac{\partial z(i,j)}{\partial y} - q_{ij} \right)^2 \right] \\
 &\quad + \sum_{i,j} w_{smooth} * \left[\left(\frac{\partial^2 z(i,j)}{\partial x^2} \right)^2 + 2 \left(\frac{\partial^2 z(i,j)}{\partial x \partial y} \right)^2 + \left(\frac{\partial^2 z(i,j)}{\partial y^2} \right)^2 \right] \\
 &\quad + \sum_{(i,j) \in \text{Constraints}} w_{constraint} * (z(i,j) - c_{ij})^2
 \end{aligned}$$

(from Yung-Yu Chung and David Ely)

Issues

Limitations?

- Lambertian assumption
- No interreflections
 - work by Shree Nayar & colleagues addresses this issue
- No transparency
- No discontinuities
- Requires known light source

Strengths (compared to stereo)?

- No correspondence problem
- Recovers reflectance parameter
- Easier to implement

Bibliography

Shape from Shading/Photometric Stereo

- B. Horn and M. Brooks, “Shape from Shading”, 1989, MIT Press.
- L. Wolff, S. Shafer, and G. E. Healey, “Physics-Based Vision: Shape Recovery”, 1992, Jones and Bartlett.
- R. J. Woodham, “Photometric Method for Determining Surface Orientation from Multiple Images”, Optical Engineering, 1980, pp. 139-144.

Shadow Scanning

- J.-Y. Bouguet and P. Perona, “3D Photography on your desk”, ICCV’98, pages 43-50, January 1998.
- J.-Y. Bouguet and P. Perona, “3D photography using shadows in dual-space geometry”, to appear in the International Journal of Computer Vision.
- For papers, images, models, talks, and more, see:
<http://www.vision.caltech.edu/bouguetj/ICCV98/>