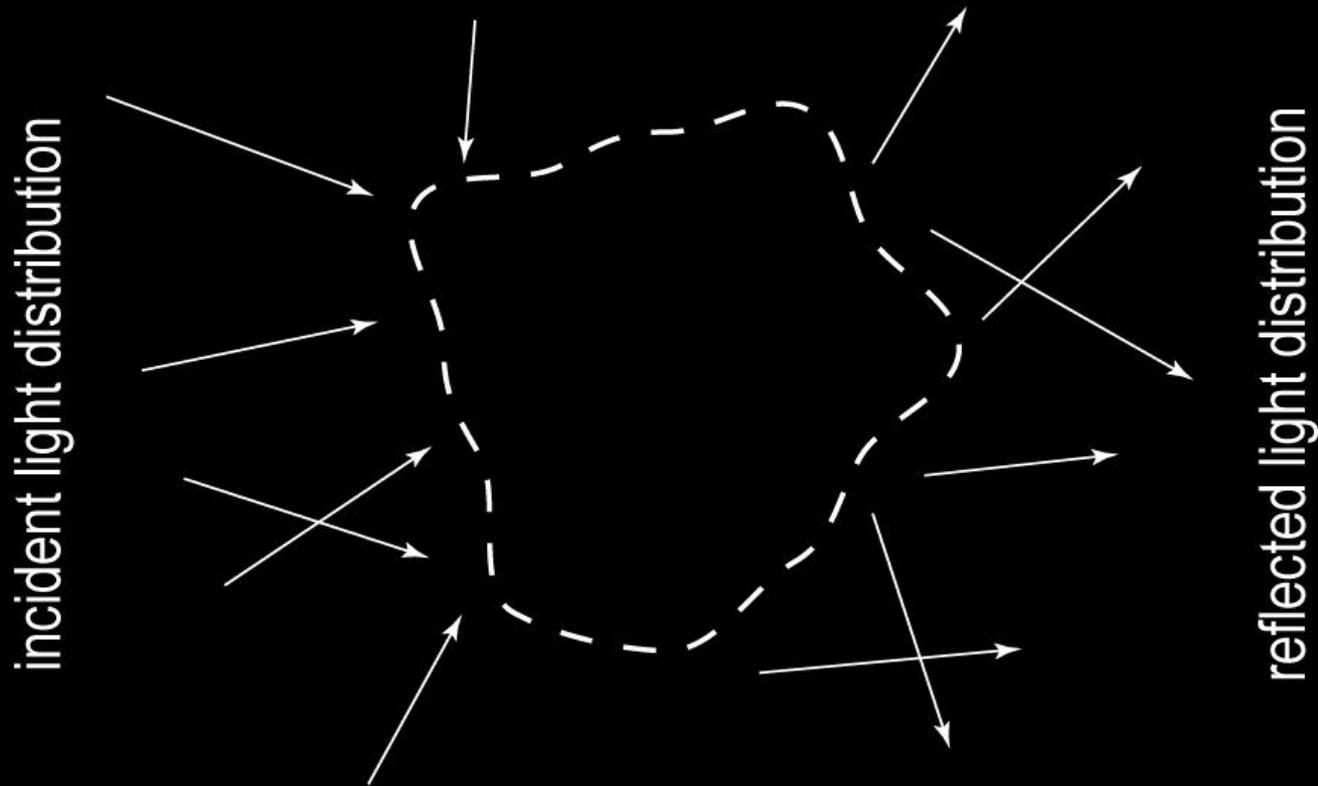


# Measuring and Modeling the Appearance of Objects and Materials

Steve Marschner  
Stanford University  
May 2001

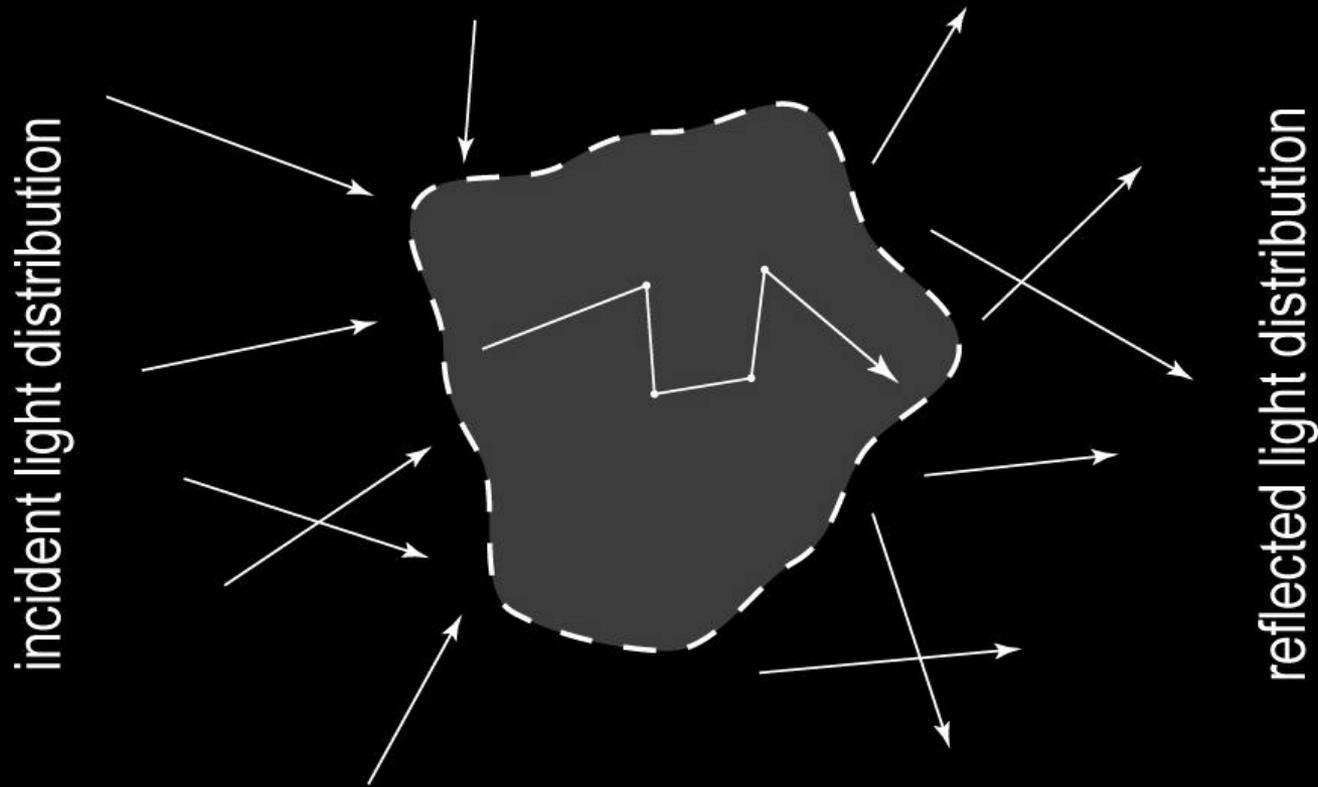
1. Appearance
2. Representing appearance  
(a scattering function taxonomy)  
– break –
3. Measuring appearance  
(three image-based methods)

# Appearance



You can model what's in the box  
or you can treat it as a general function

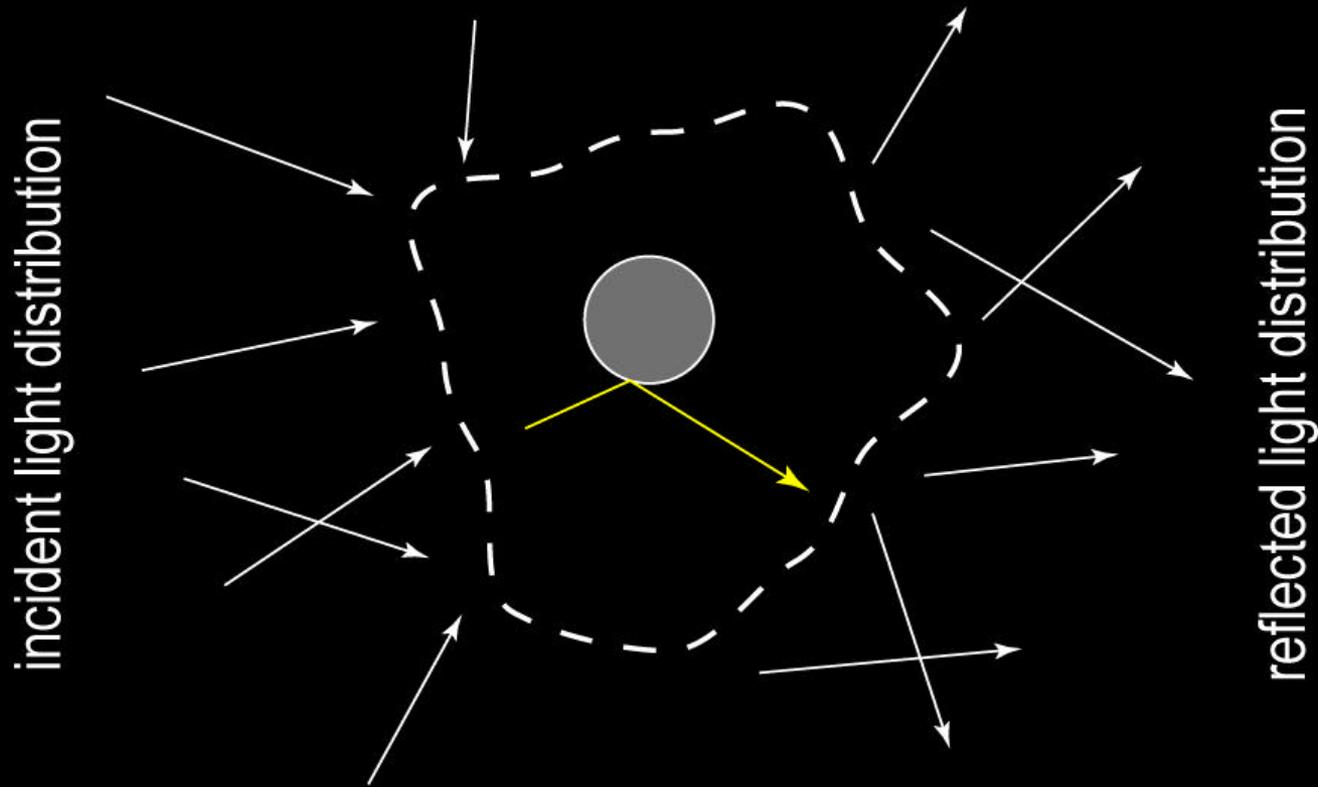
# Volume scattering



Most general form of model:

volume scattering as a function of position

# Geometry

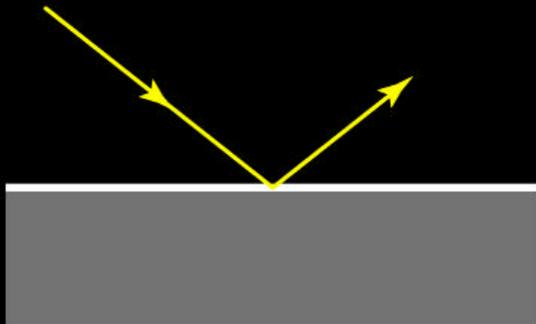


For opaque and transparent surfaces, you can model just the interfaces between materials

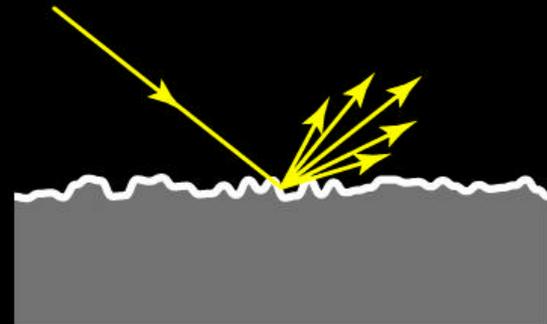
# Materials



conductor

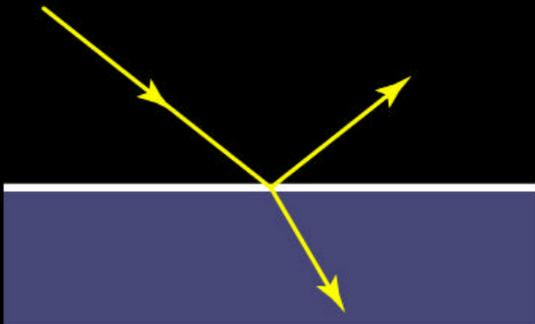


conductor plus  
microgeometry

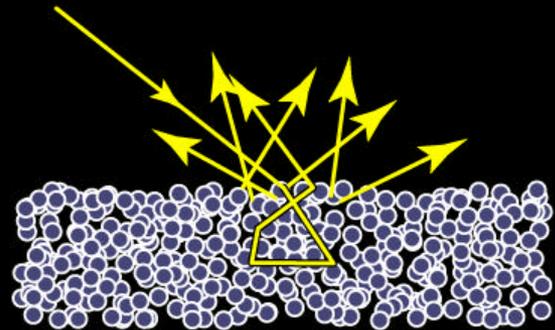




insulator

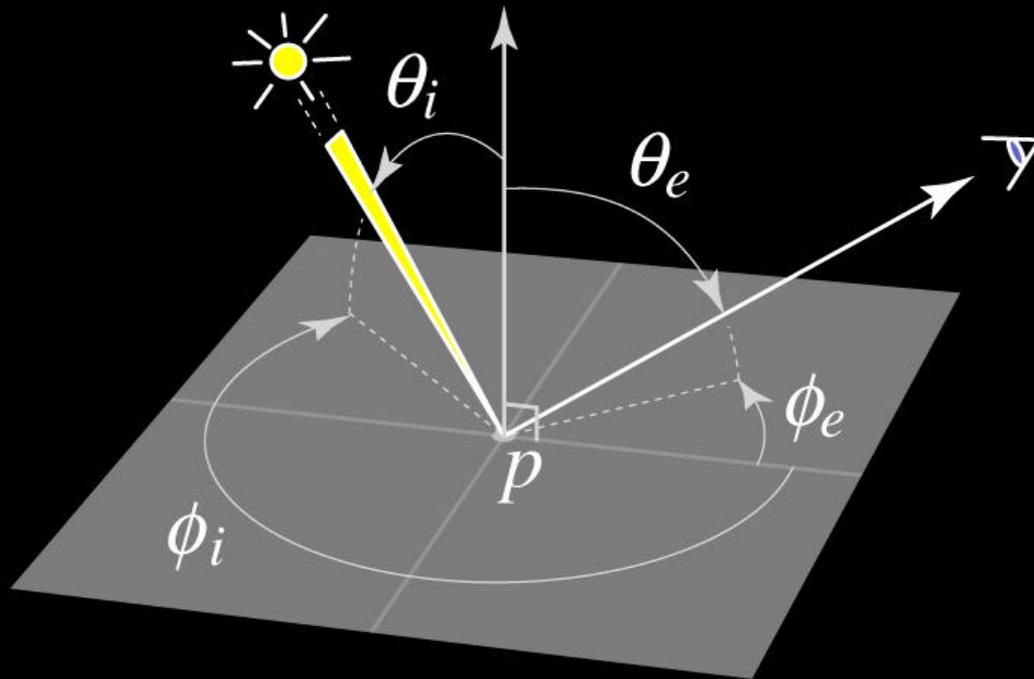


insulator plus  
microgeometry



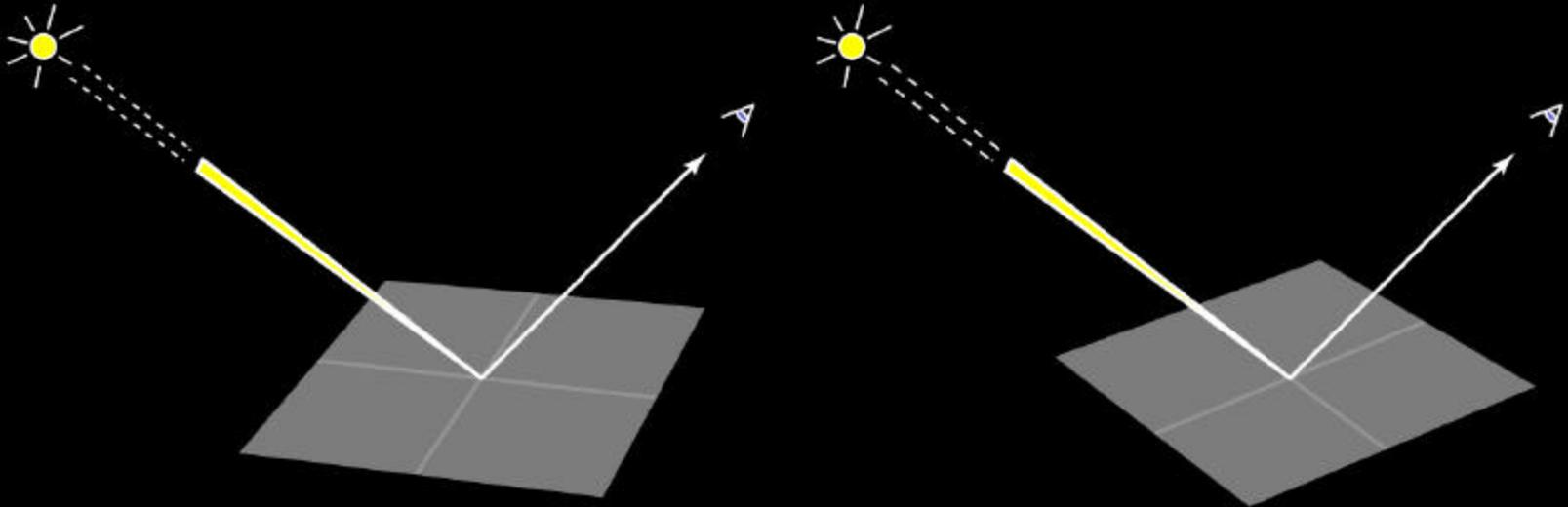
# BRDF

$$f_r(p, \theta_i, \phi_i, \theta_e, \phi_e)$$

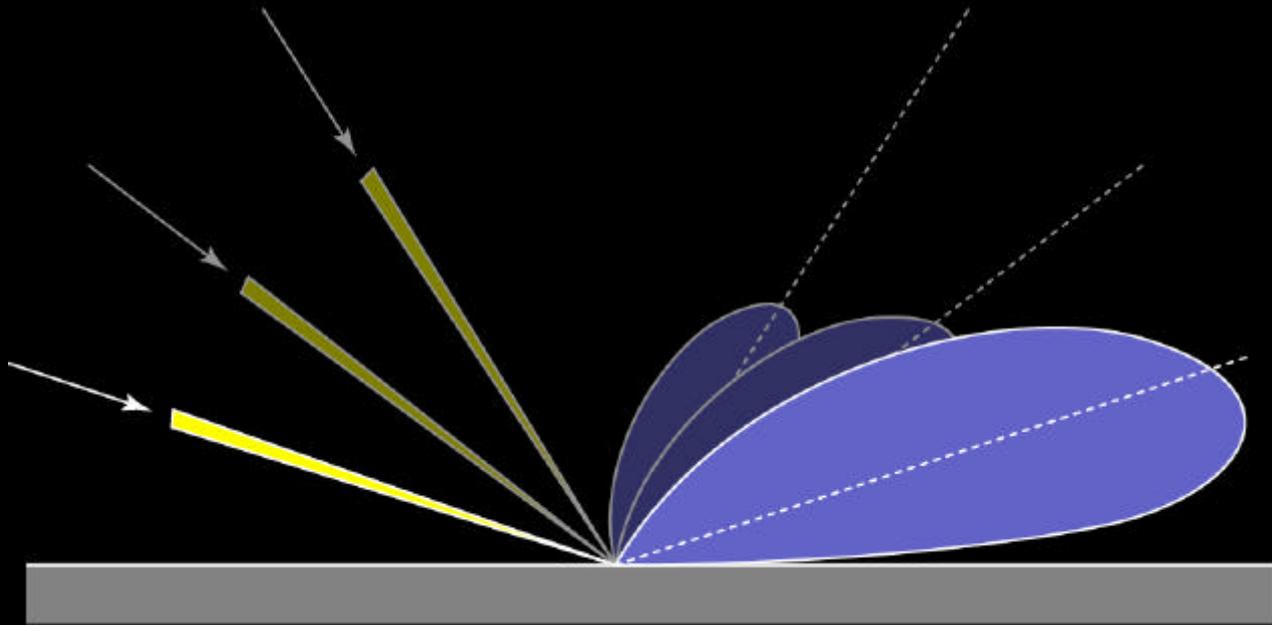


**Bidirectional Reflectance Distribution Function**  
Reciprocity; energy conservation

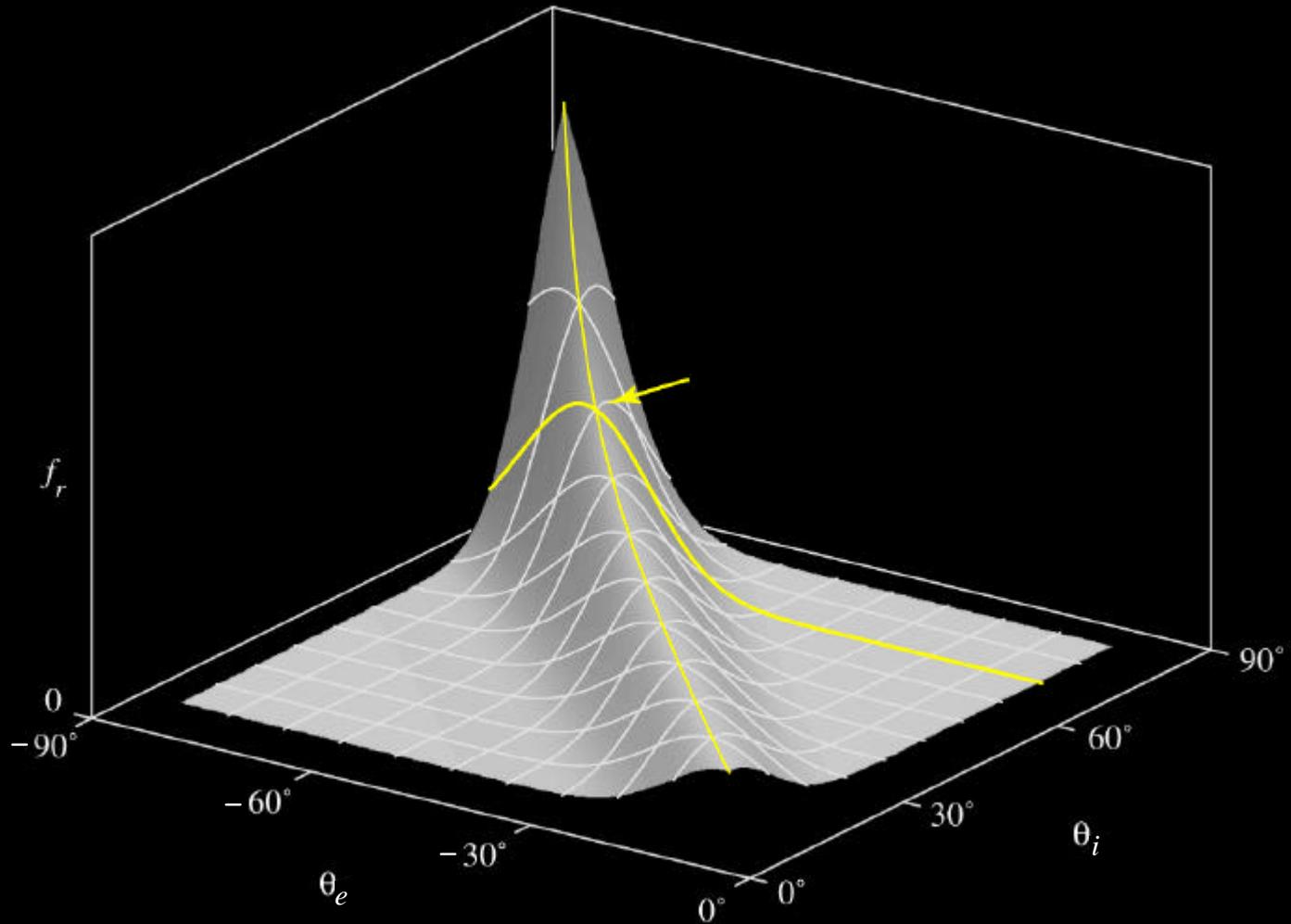
# Isotropy



# Off-specular Reflection

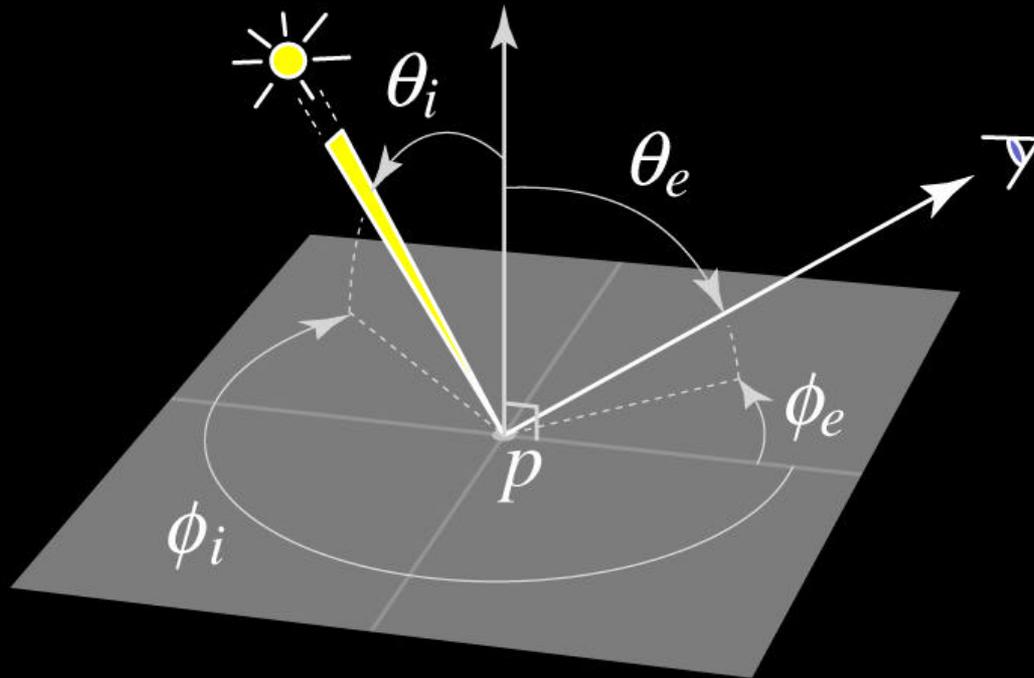


# Off-specular Reflection



# BRDF

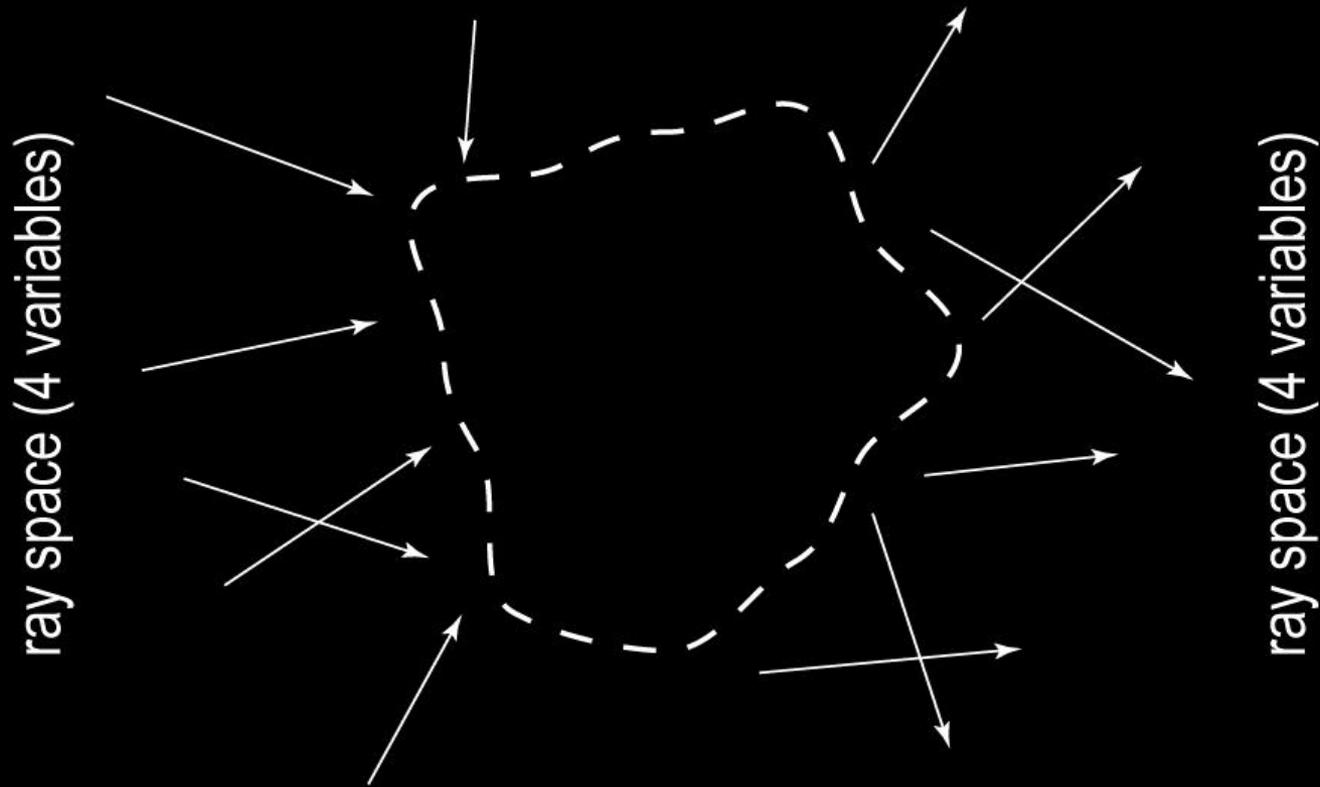
$$f_r(p, \theta_i, \phi_i, \theta_e, \phi_e)$$





# Representing Appearance

# Scattering Function



Operator transforms 4D function to 4D function  
Linear, so represent with 8D function

# Representing Scattering

8D is generally too much to treat generally

Two solutions:

- **Restrictions:** treat the function generally but constrain it to a lower-dimensional domain
- **Assumptions:** Keep the whole domain but use models to simplify the representation

# Restrict to 2D: Photograph

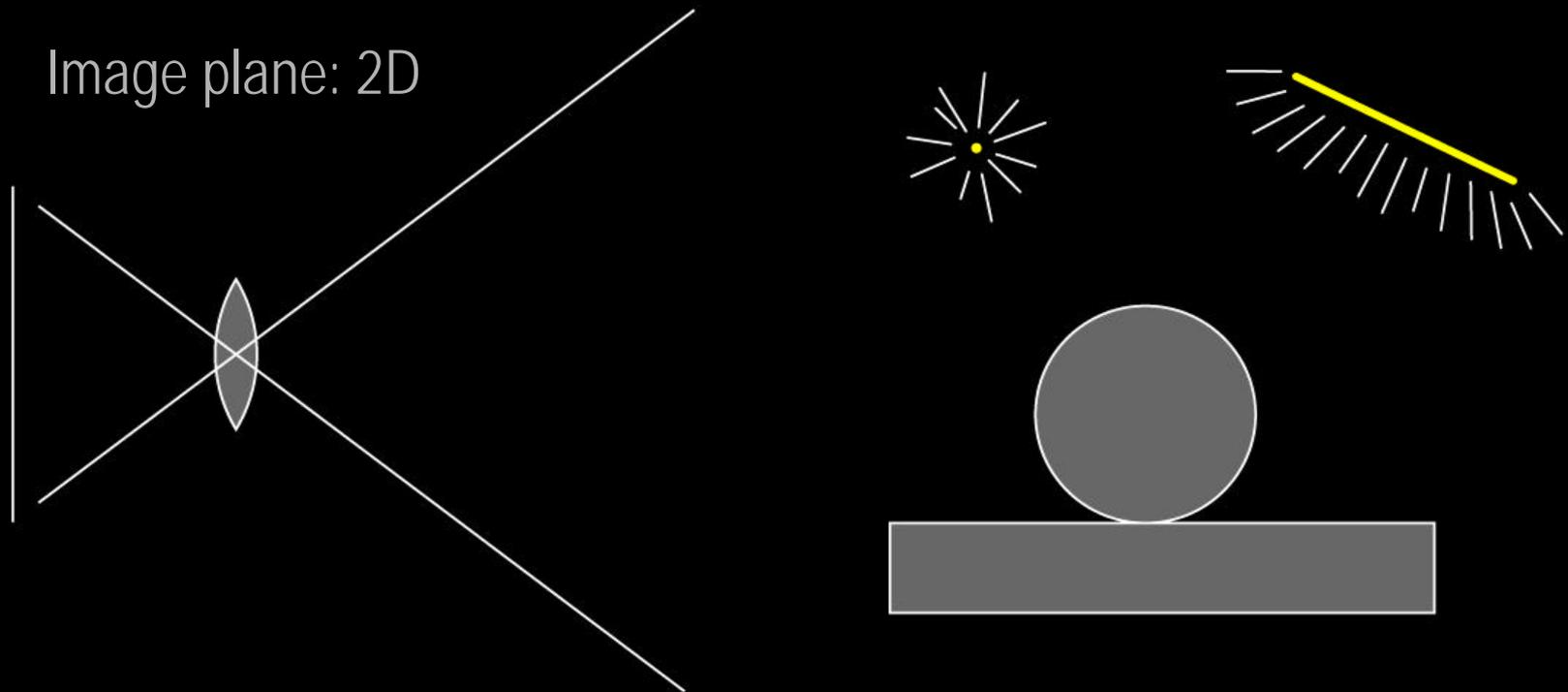


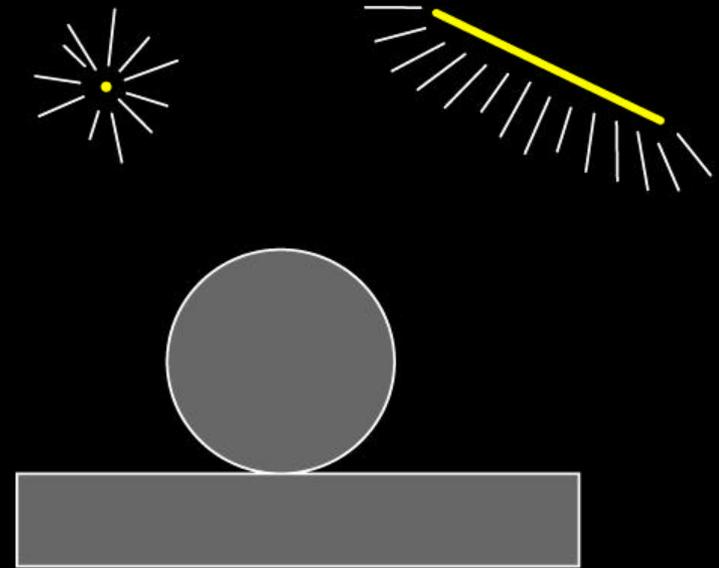
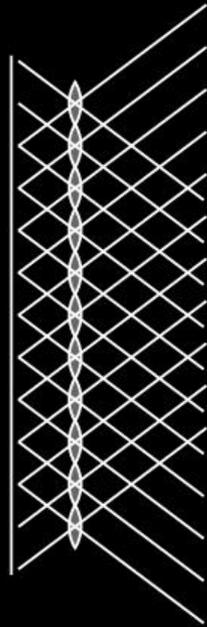
Image plane: 2D

Fixed viewpoint: -2D

Fixed incident distribution: -4D

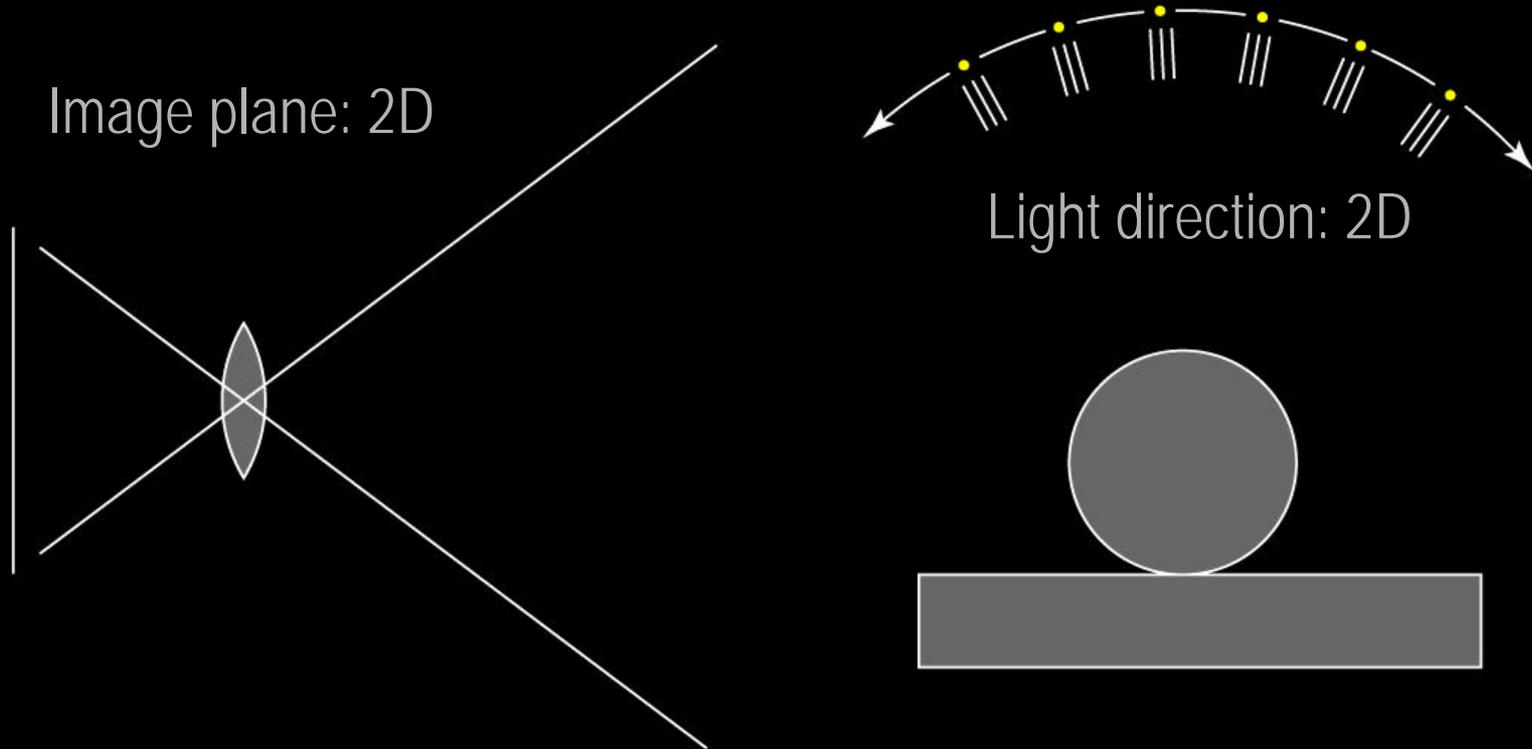
# Restrict to 4D: Light field

Image plane: 2D  
Viewpoint: 2D



Fixed incident distribution: -4D

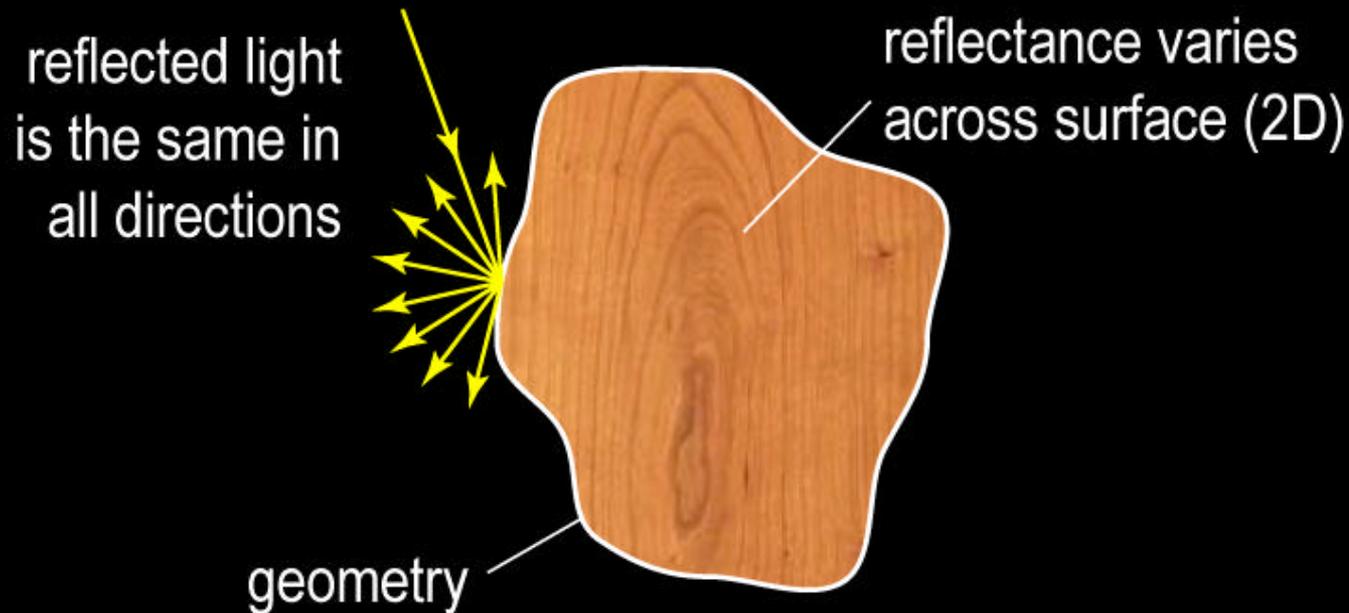
# Restrict to 4D: Light stage et al.



Fixed viewpoint: -2D

Parallel incident distribution: -2D

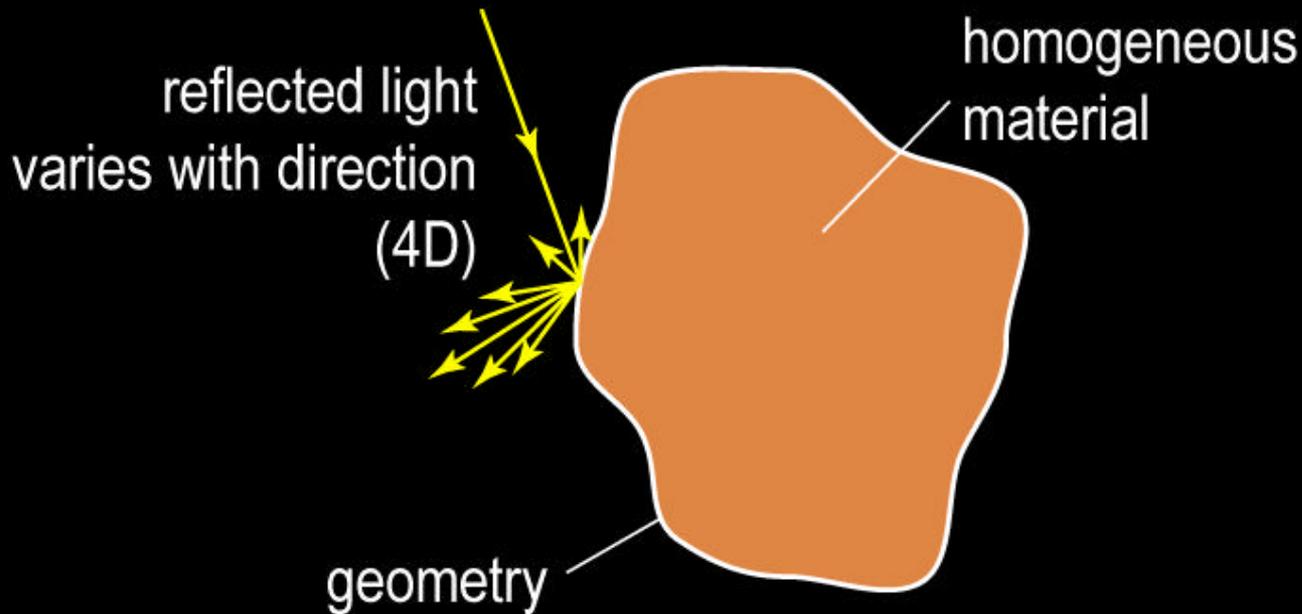
# 2D Assumption: Texture map



Single scattering: -1D; surface scattering: -1D

Diffuse reflection: -4D

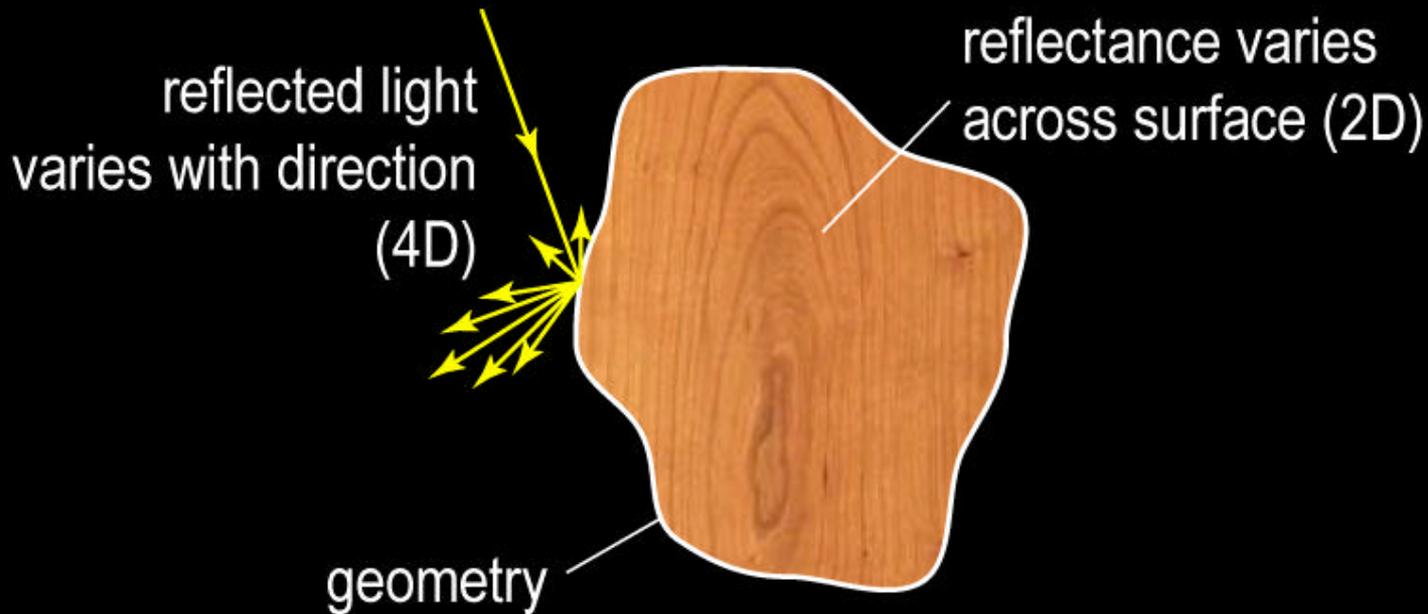
# 4D Assumption: BRDF



Single scattering: -1D; surface scattering: -1D

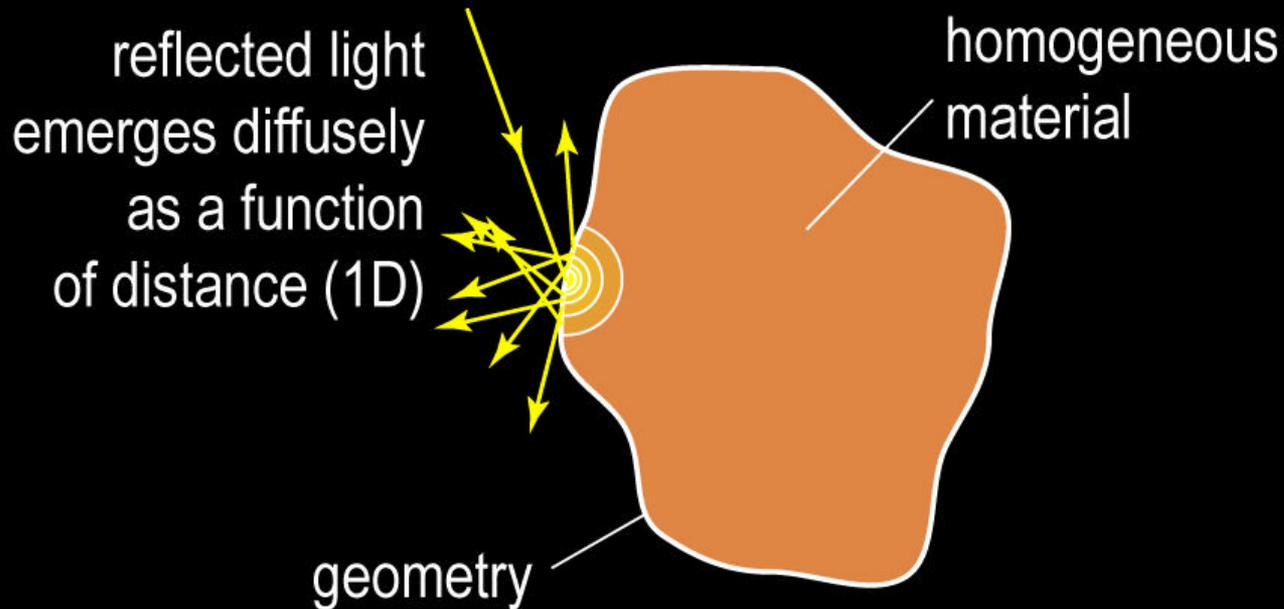
Homogeneous material: -2D

# 6D Assumption: Variable BRDF



Single scattering: -1D; surface scattering: -1D

# 1D Assumption: Translucent

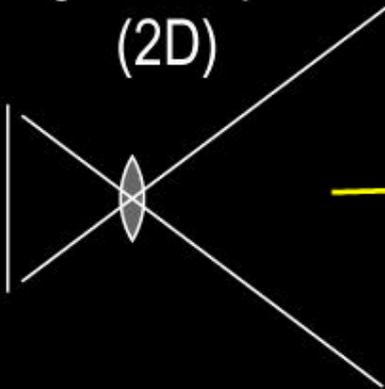


Homogeneous material: -2D

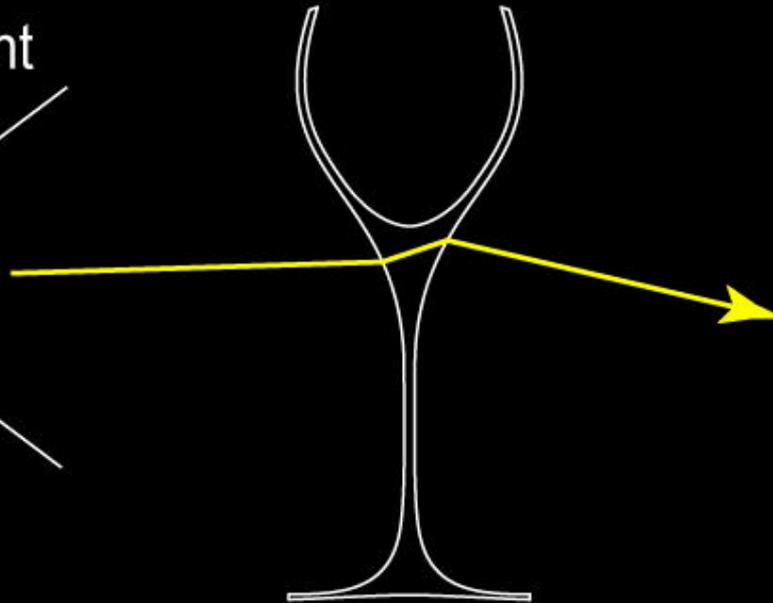
Diffuse reflection: -4D; isotropic material: -1D

# 2D: Environment matte

restriction:  
single viewpoint  
(2D)



assumption:  
single ray out  
per ray in  
(in essence)



Fixed viewpoint: -2D [restriction]

Single ray transport: -4D [assumption]

# Measuring Appearance

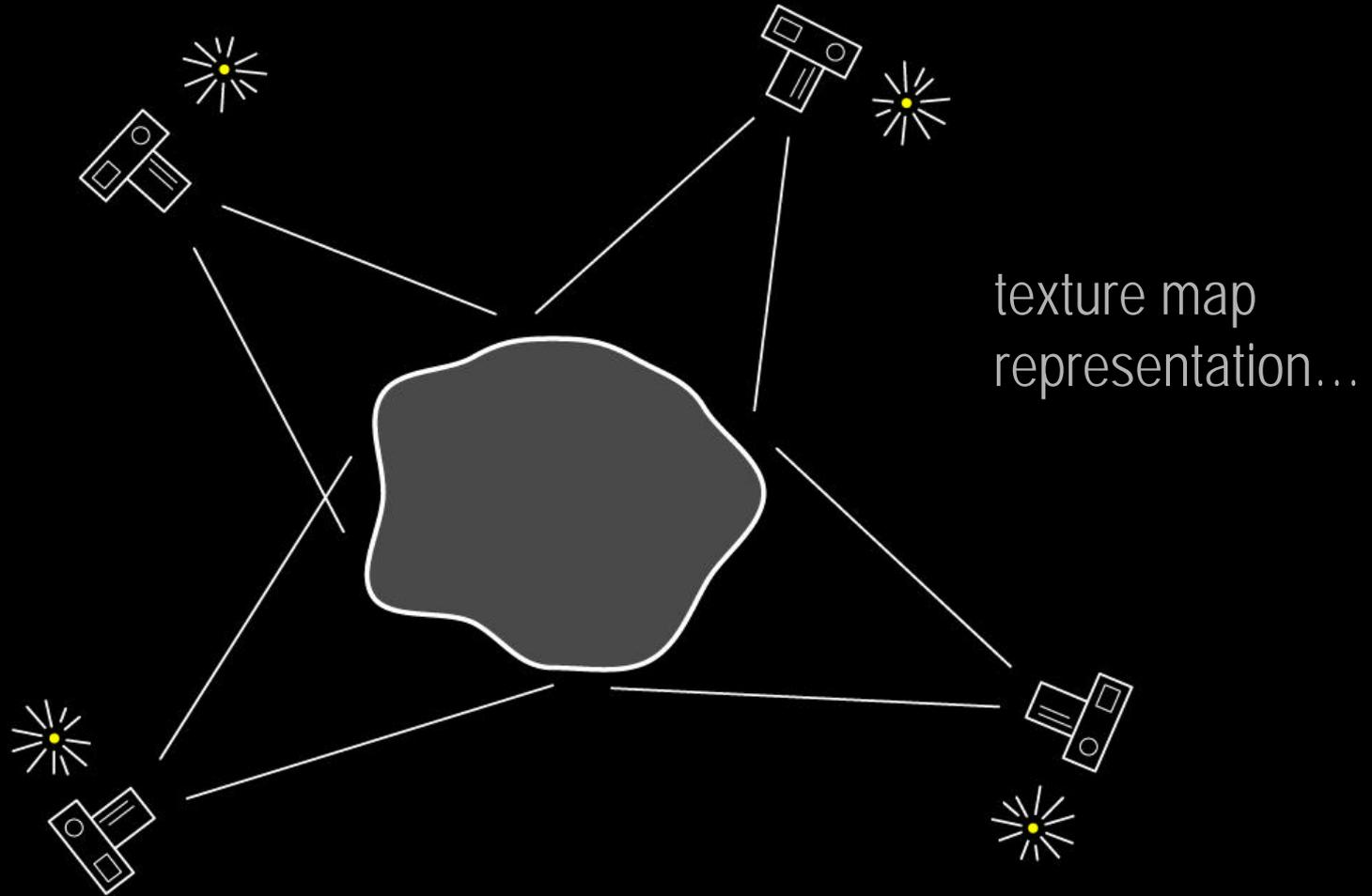
1. Diffuse texture maps
2. Homogeneous BRDFs
3. Translucent materials

# Measuring texture maps

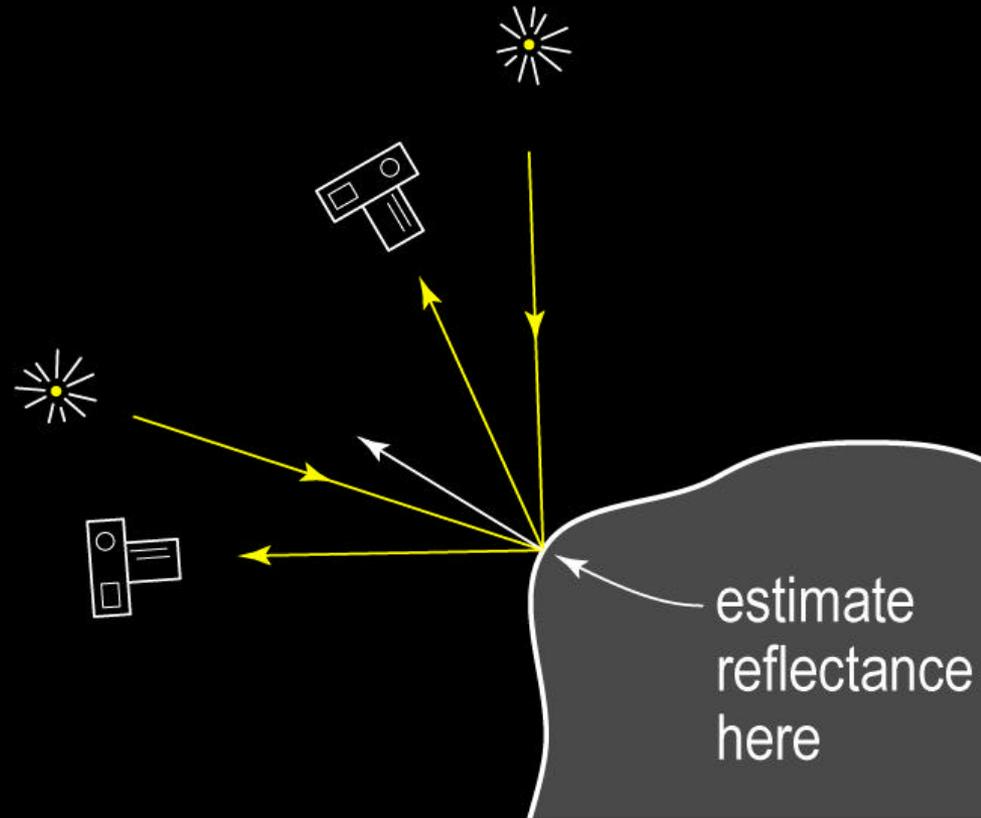
Techniques and results from:

Stephen R. Marschner. "Inverse Rendering for Computer Graphics." Ph.D. Thesis, Cornell University, August 1998.

# Measuring texture maps



# Measuring texture maps

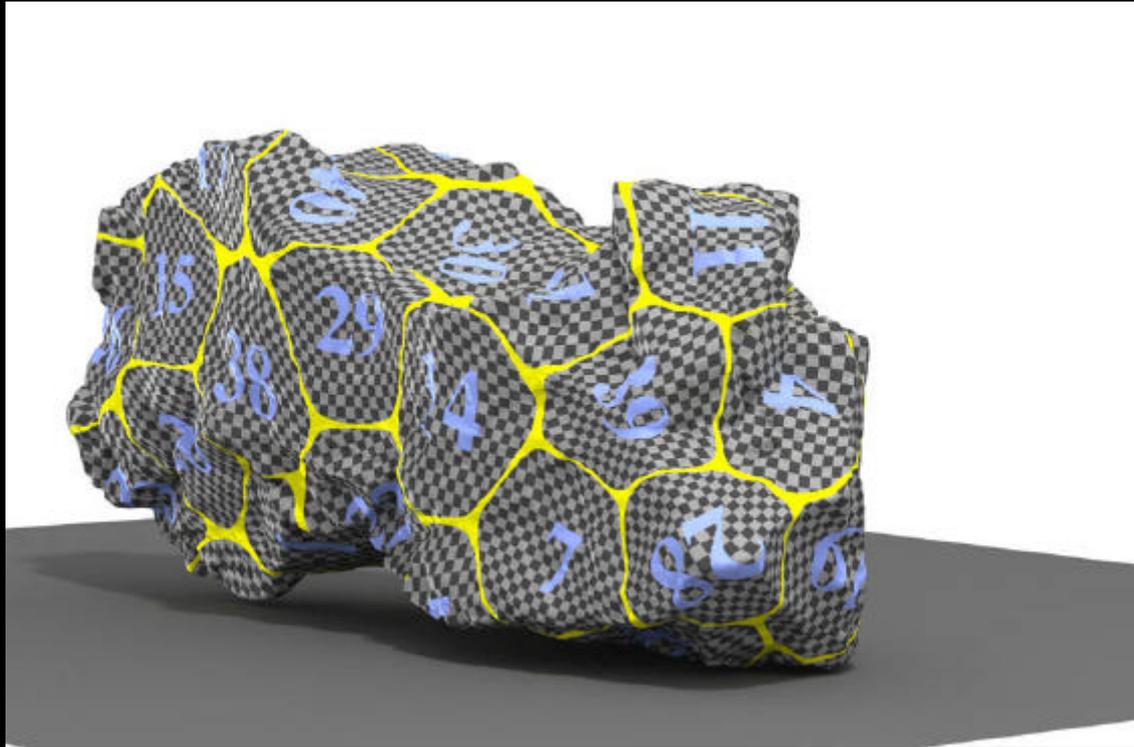


Each camera/source pair gives a BRDF estimate  
Combine by averaging to get diffuse albedo

# Rock: source photos



# Rock: Texture maps



# Rock: Textured model



# Rock: Photo comparison



# Measuring BRDFs

Techniques from:

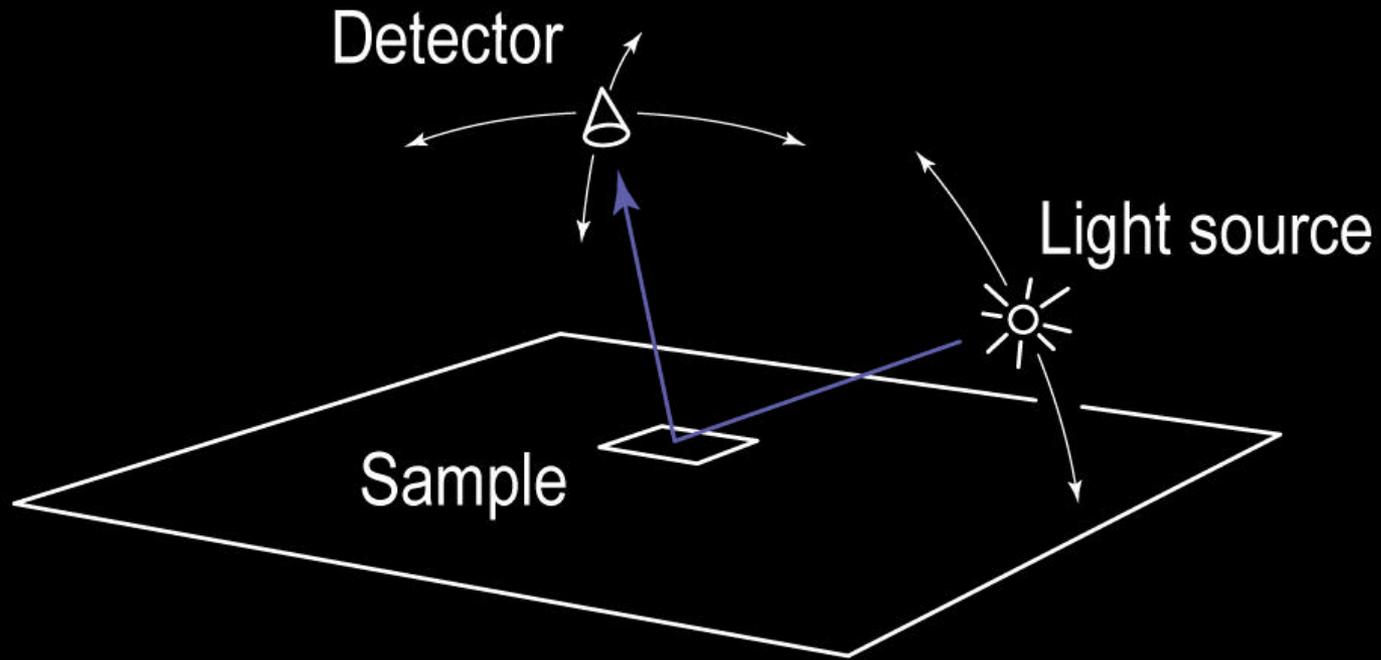
Stephen R. Marschner, Stephen H. Westin, Eric P. F. Lafortune, and Kenneth E. Torrance. "Image-based Measurement of the Bidirectional Reflectance Distribution Function." *Applied Optics*, vol. 39, no. 16 (2000).

Stephen R. Marschner, Stephen H. Westin, Eric P. F. Lafortune, Kenneth E. Torrance, and Donald P. Greenberg. "Image-based BRDF Measurement Including Human Skin." In proceedings of *10th Eurographics Workshop on Rendering*, pages 139-152, June 1999.

Face results from:

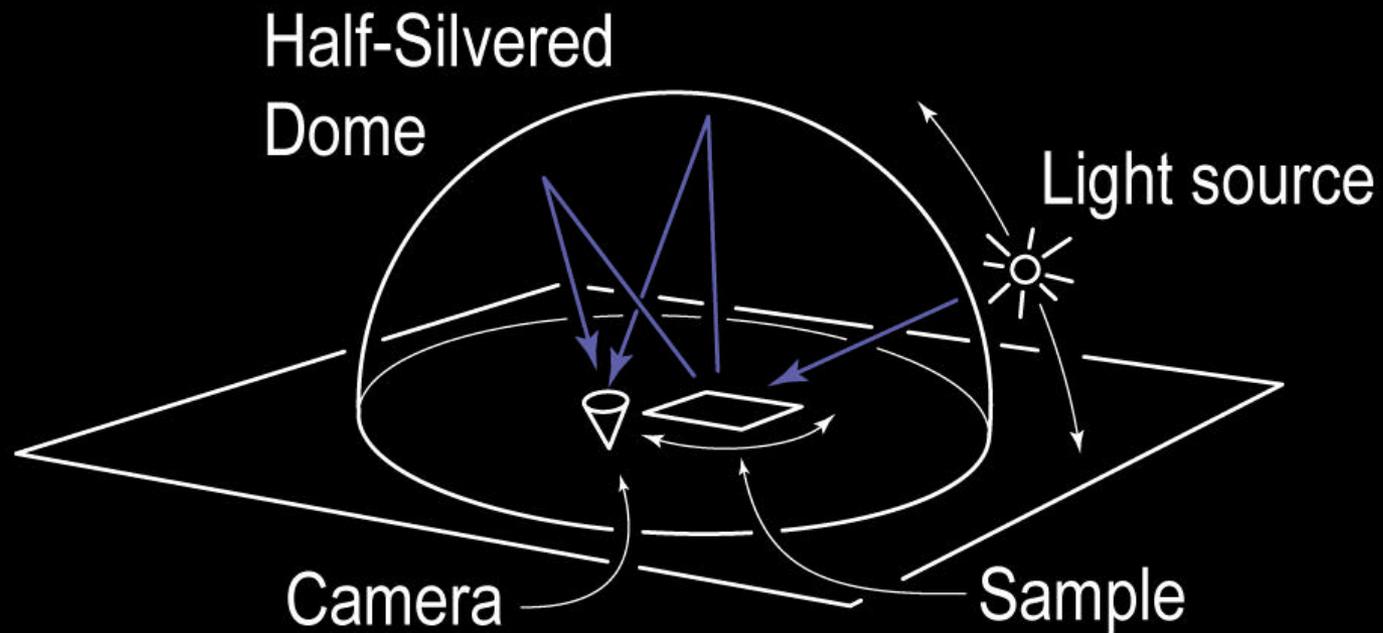
Stephen R. Marschner, Brian Guenter, and Sashi Raghupathy. "Modeling and Rendering for Realistic Facial Animation." In proceedings of *11th Eurographics Workshop on Rendering*, June 2000.

# Traditional



3 DOF: 2 detector, 1 source  
Samples arranged on any desired grid

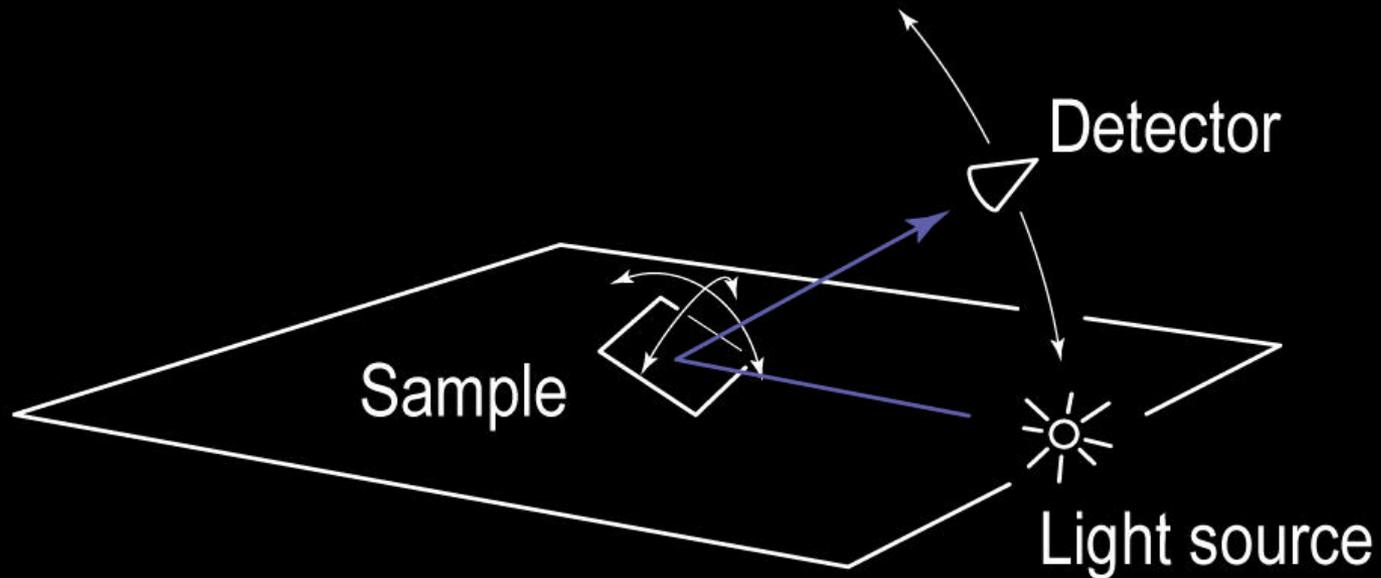
# Image-based: Ward



3 DOF: 2 detector, 1 source (+1 sample)

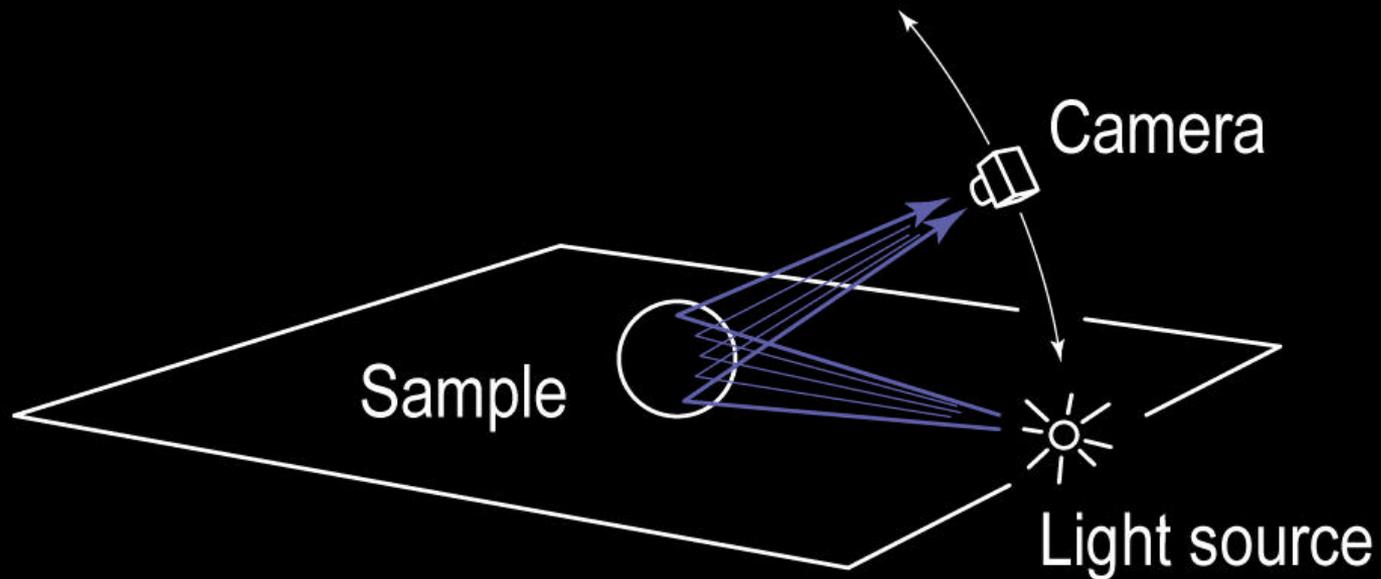
Exitant directions fixed by optics; incident directions chosen

# Traditional



3 DOF: 2 sample, 1 detector  
Samples arranged on any desired grid

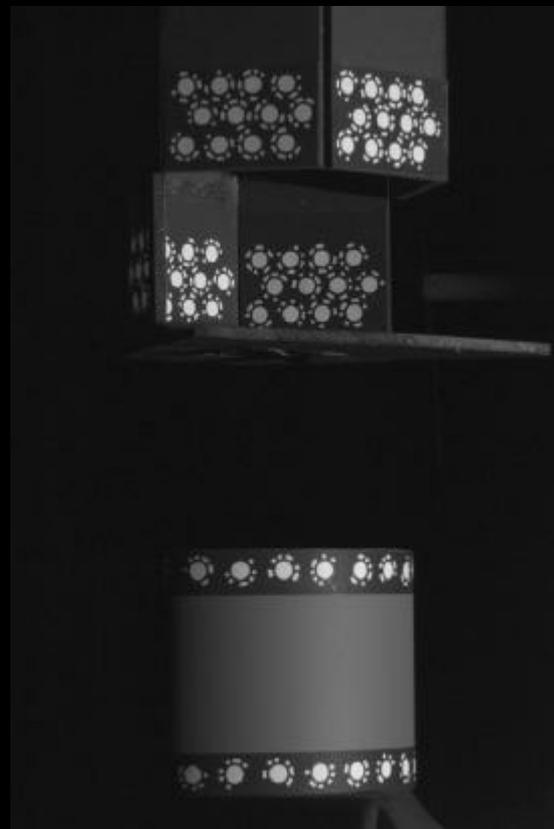
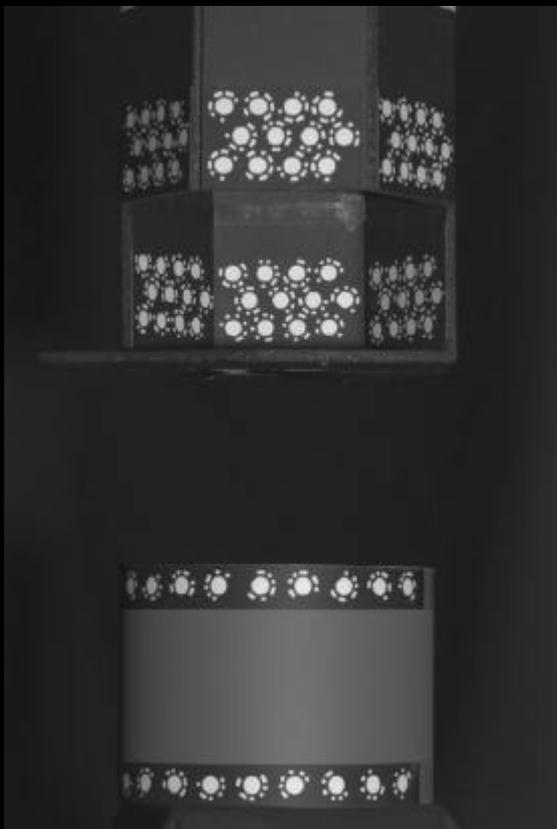
# Image-based



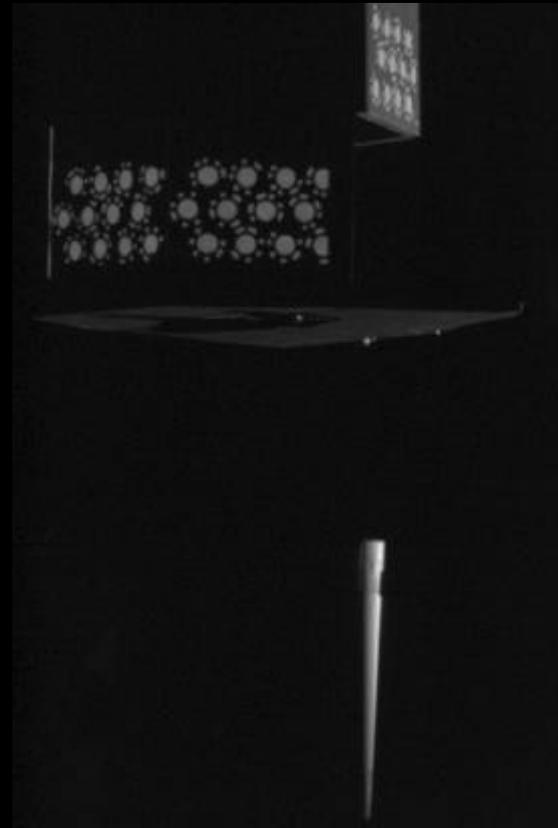
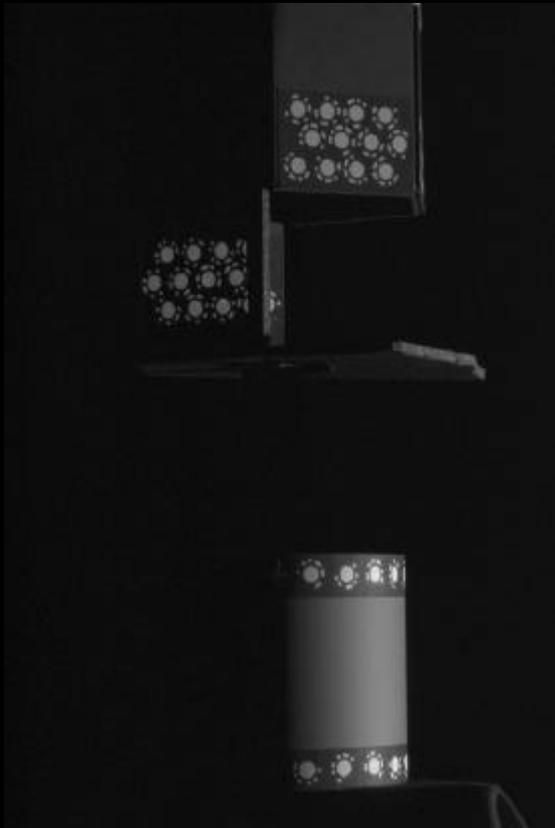
3 DOF: 2 image, 1 camera

Samples arranged on 2D sheets in 3D parameter space

# Results: paint

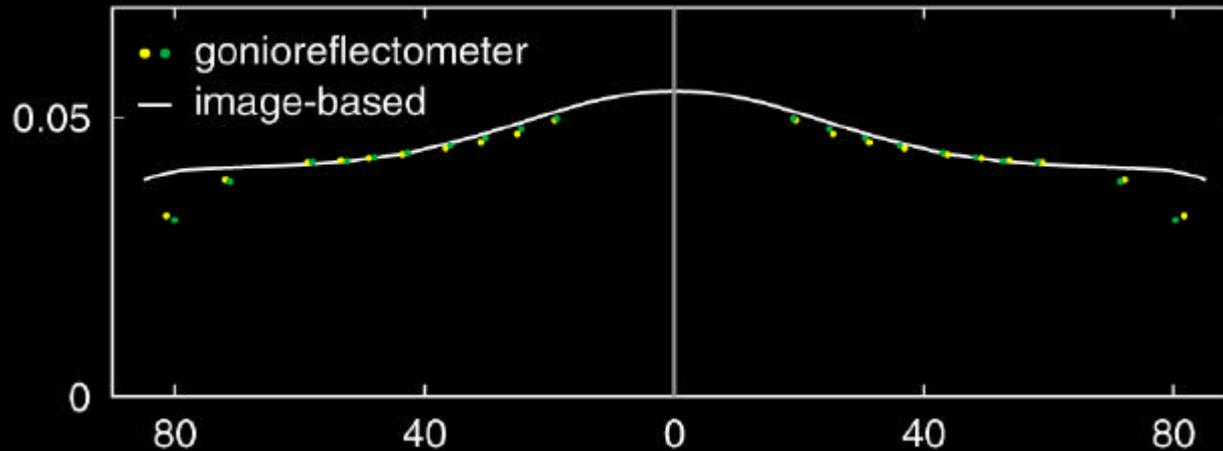
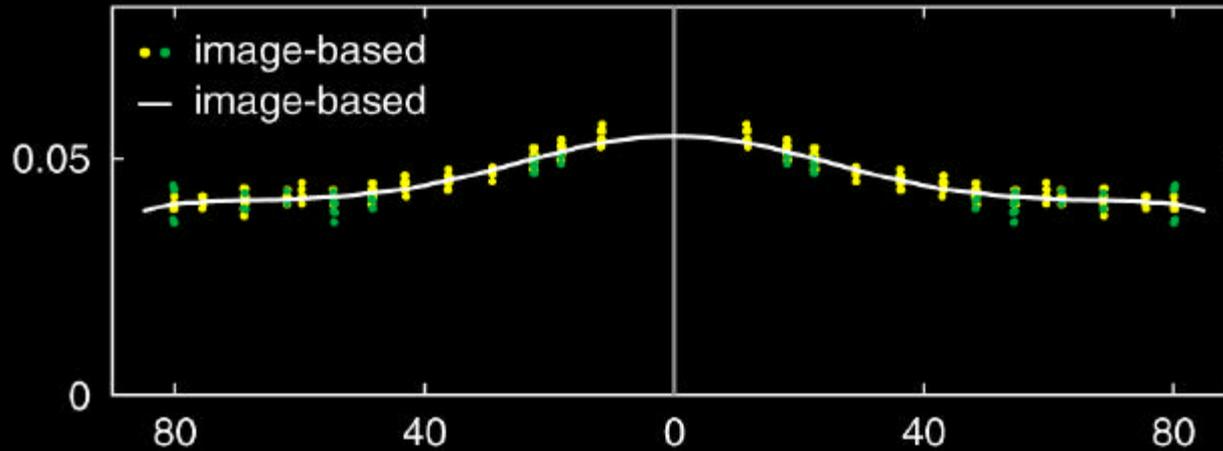


# Results: paint



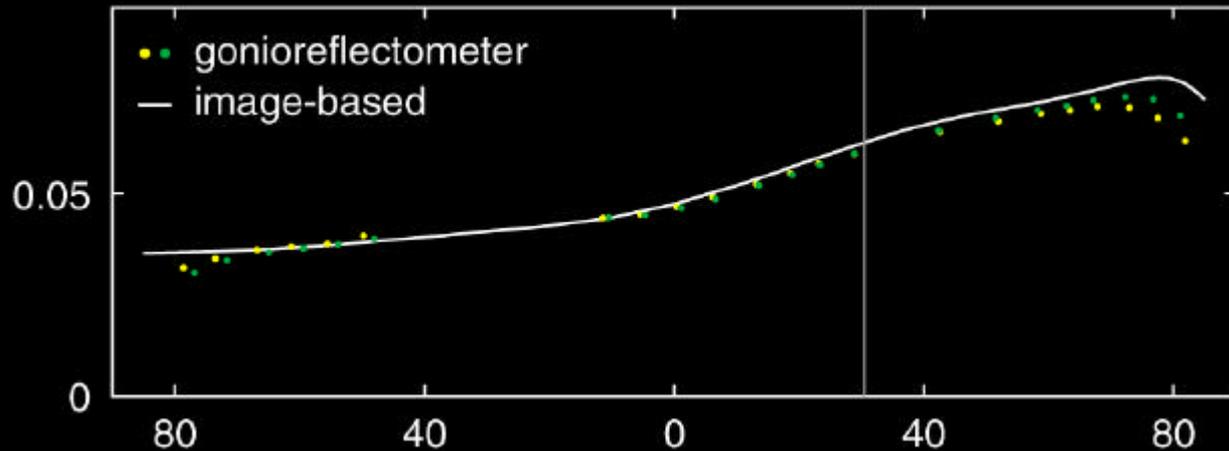
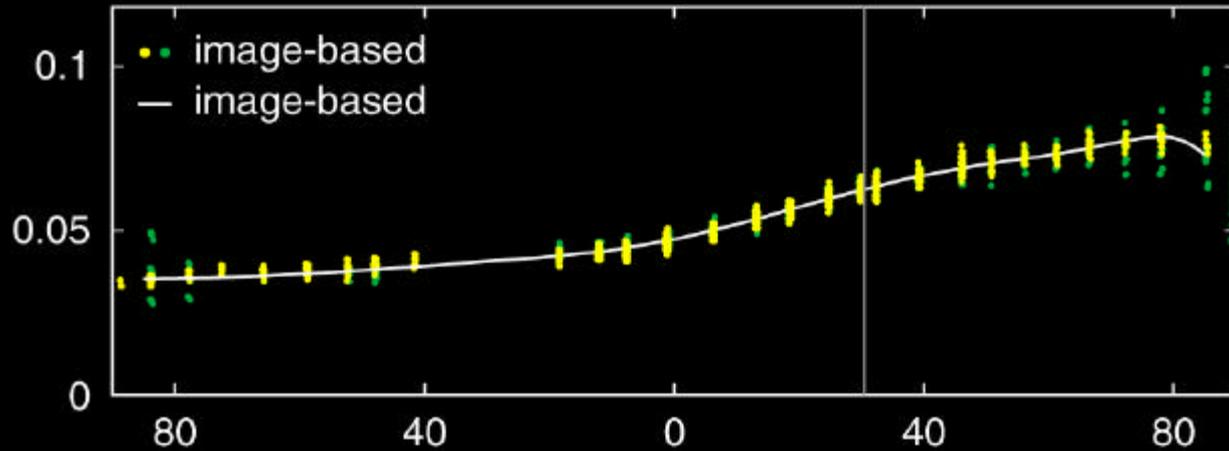
# Results: paint

0°



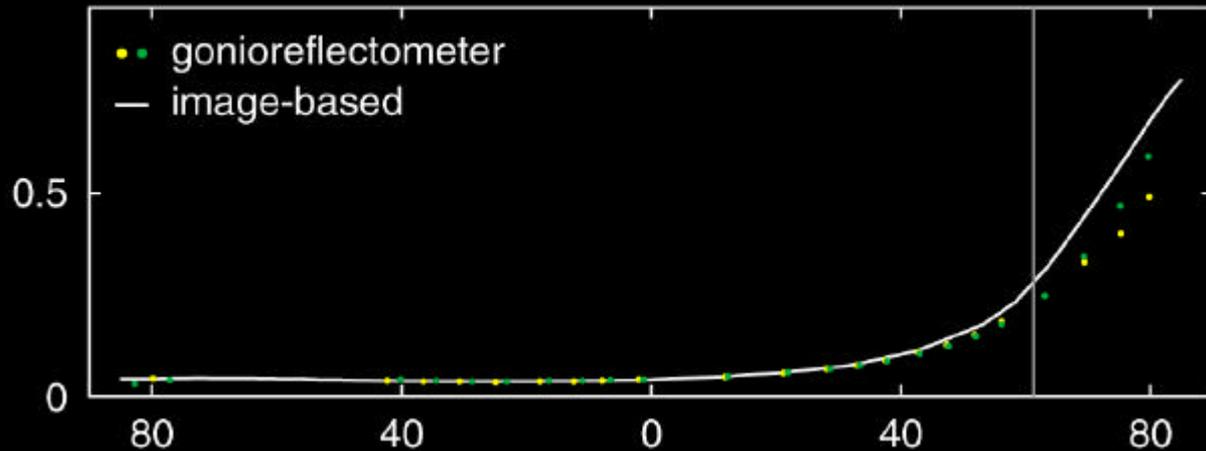
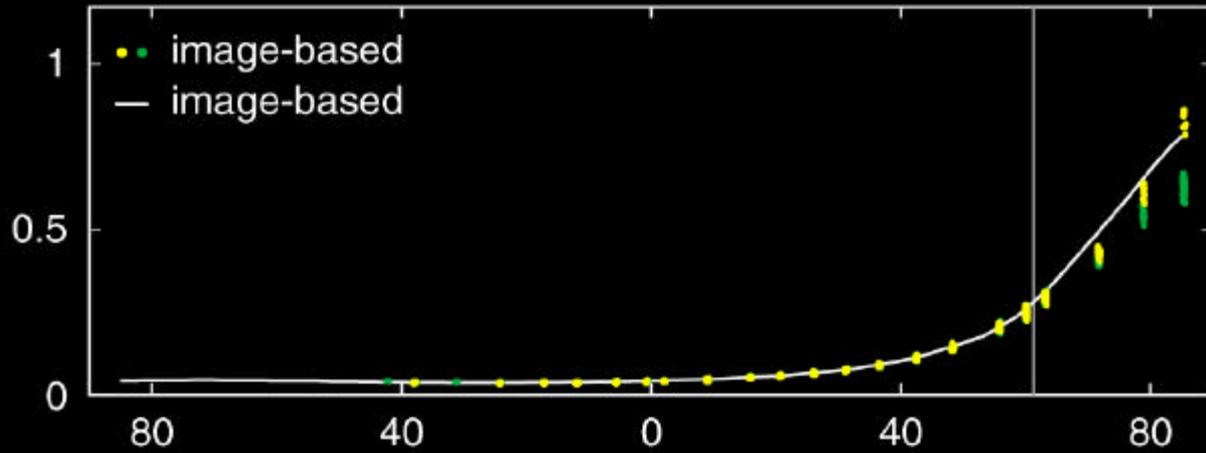
# Results: paint

30°



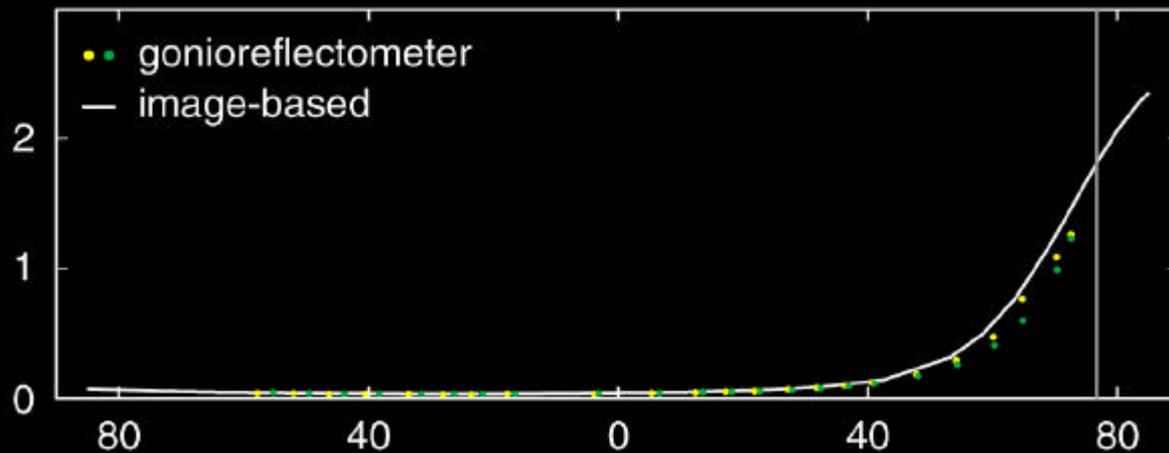
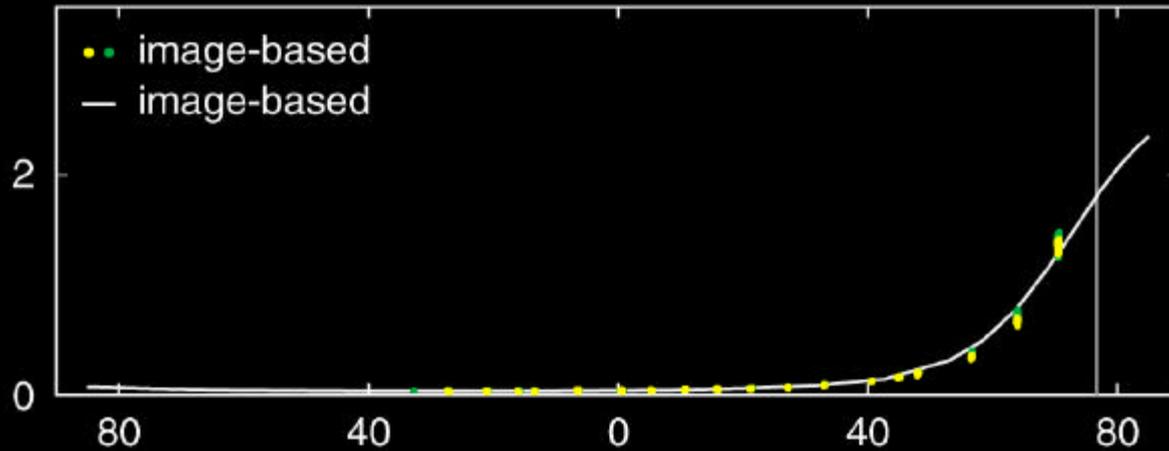
# Results: paint

60°

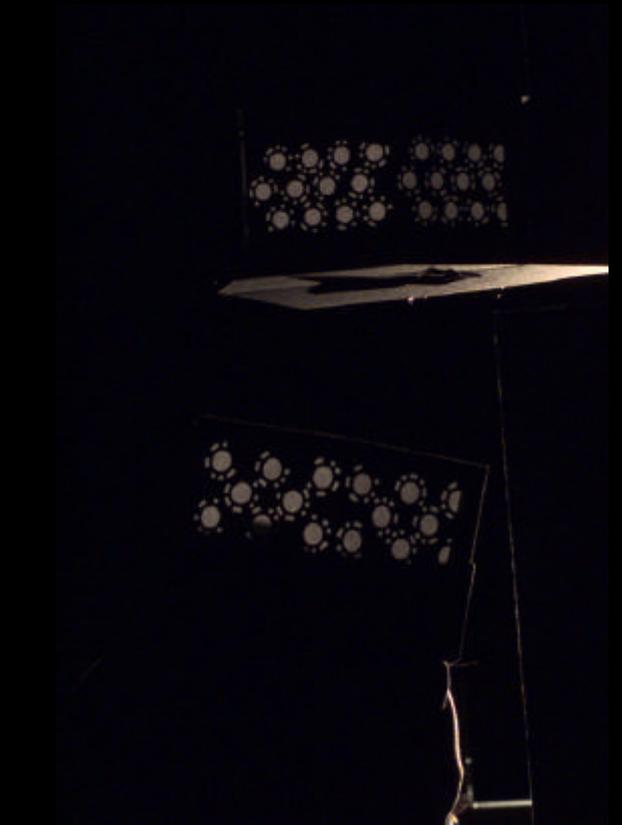


# Results: paint

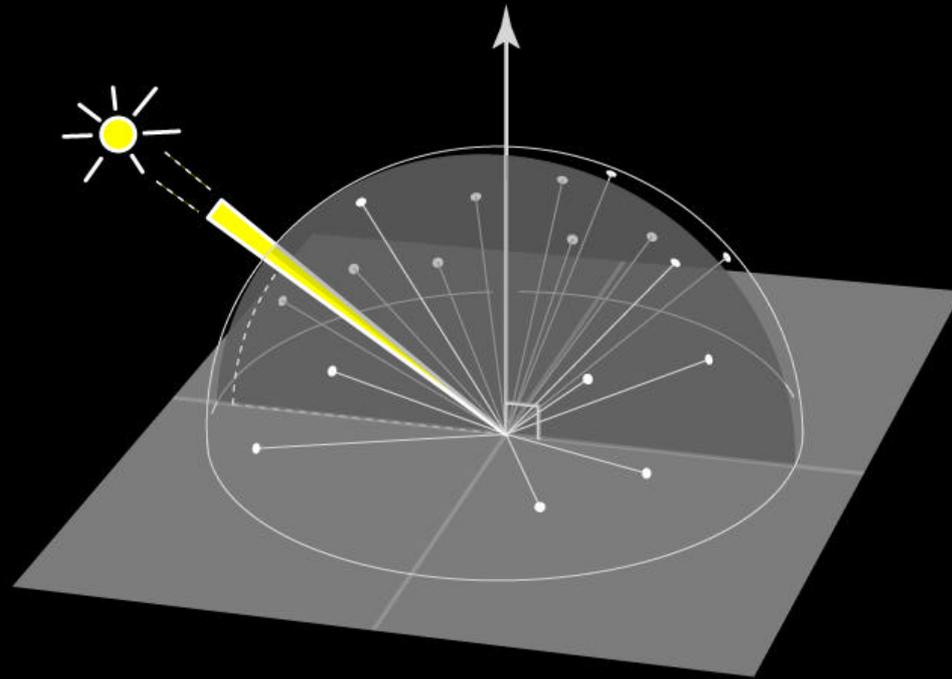
75°



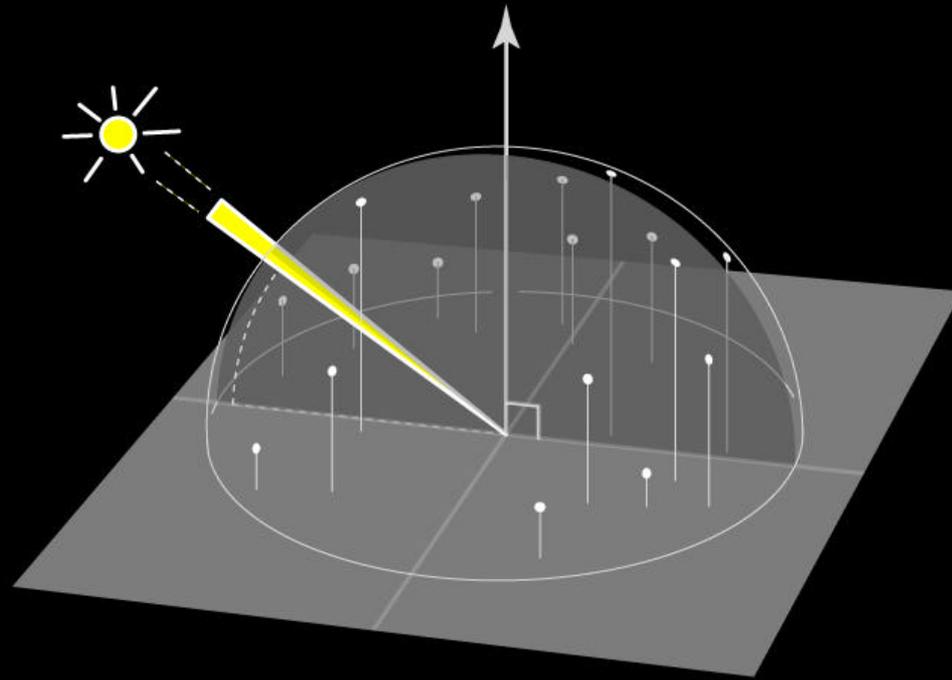
# Results: skin



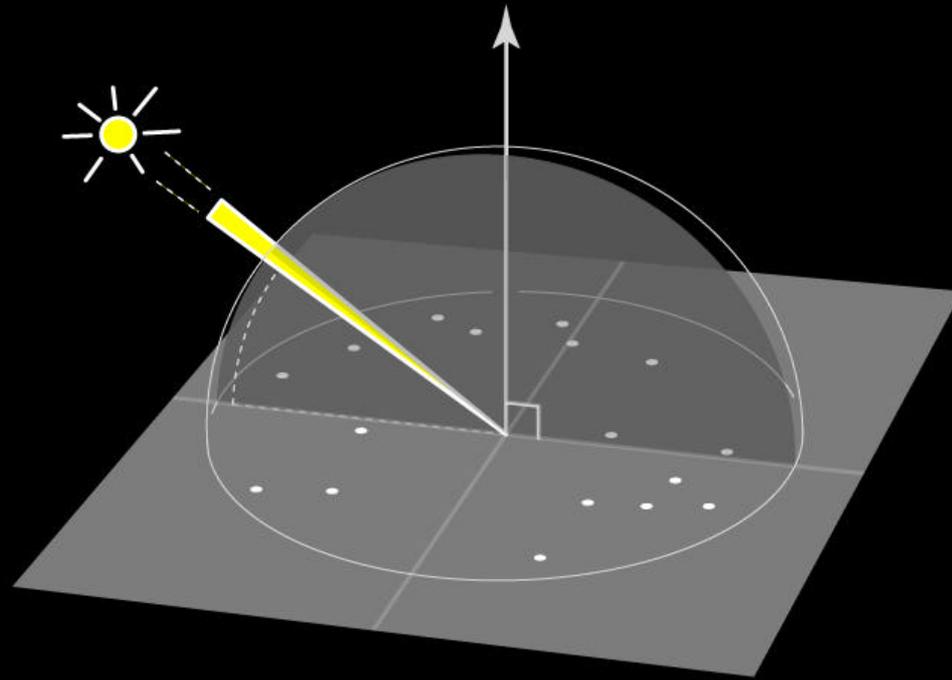
# Domain Coverage



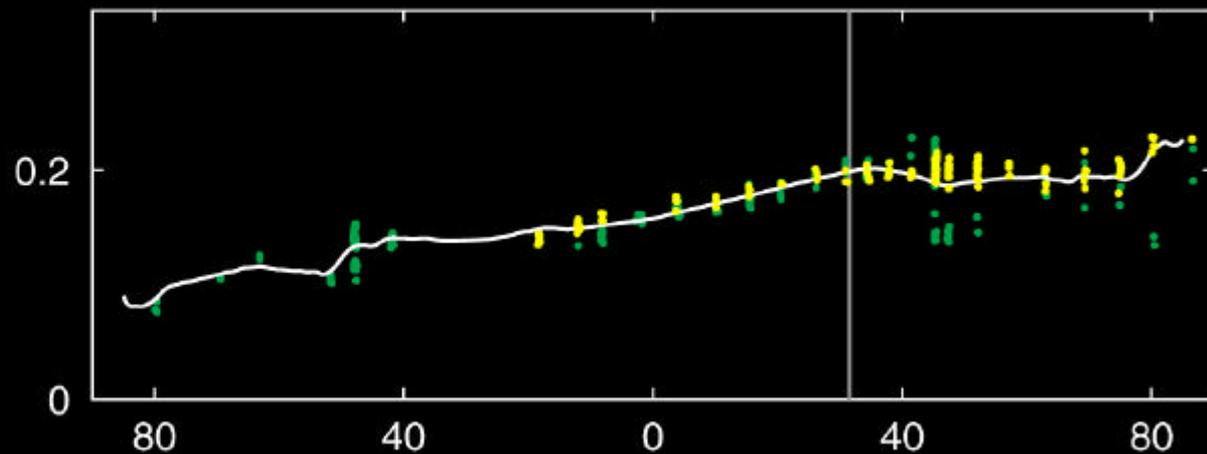
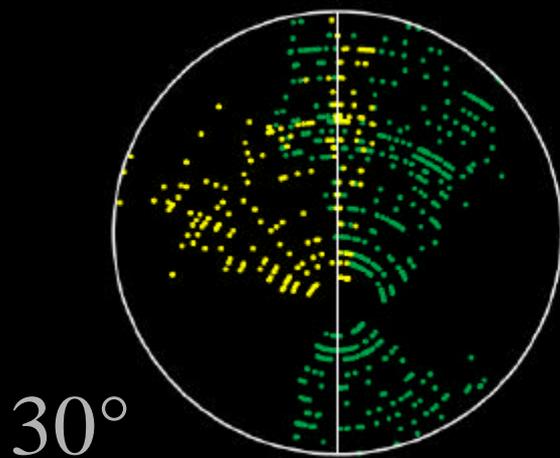
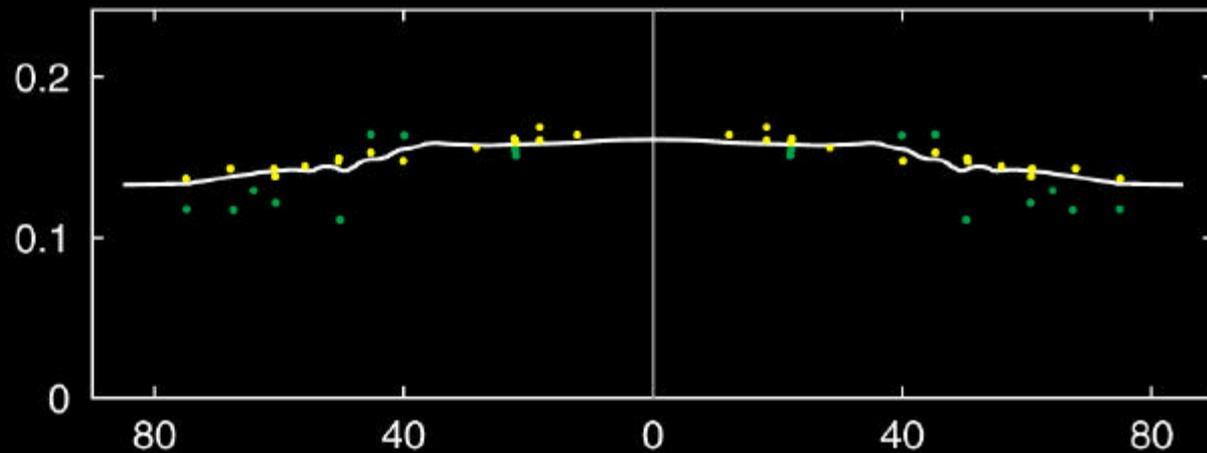
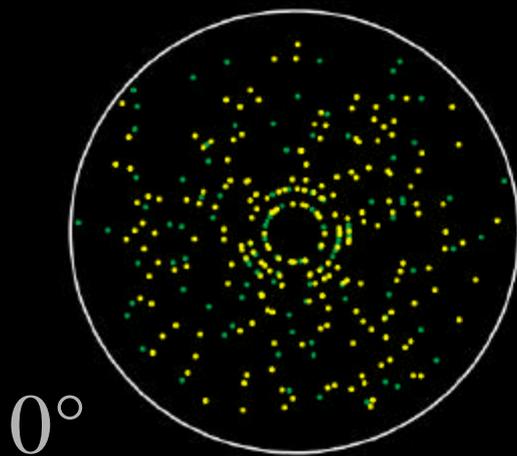
# Domain Coverage



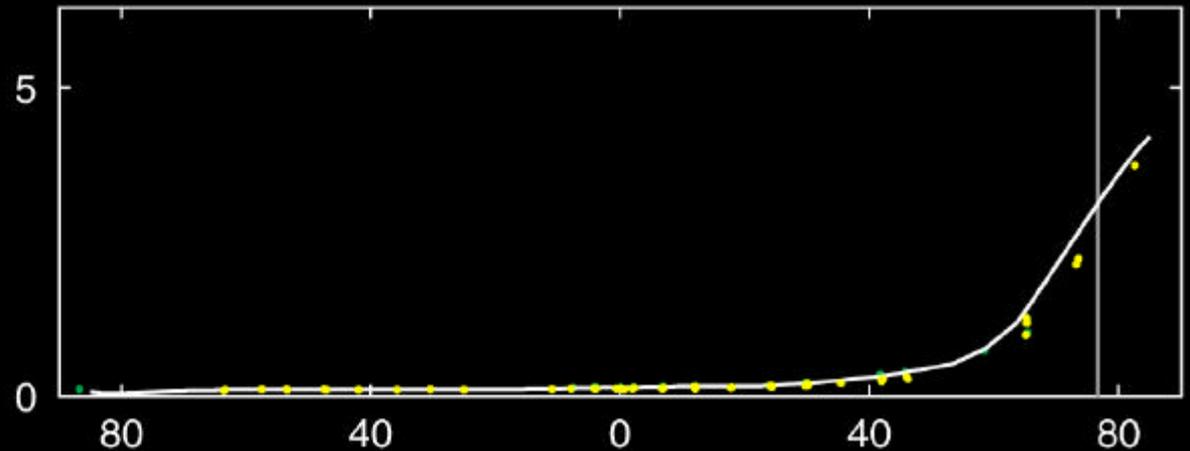
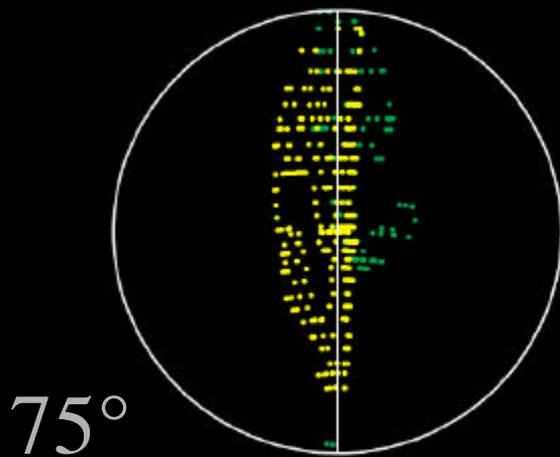
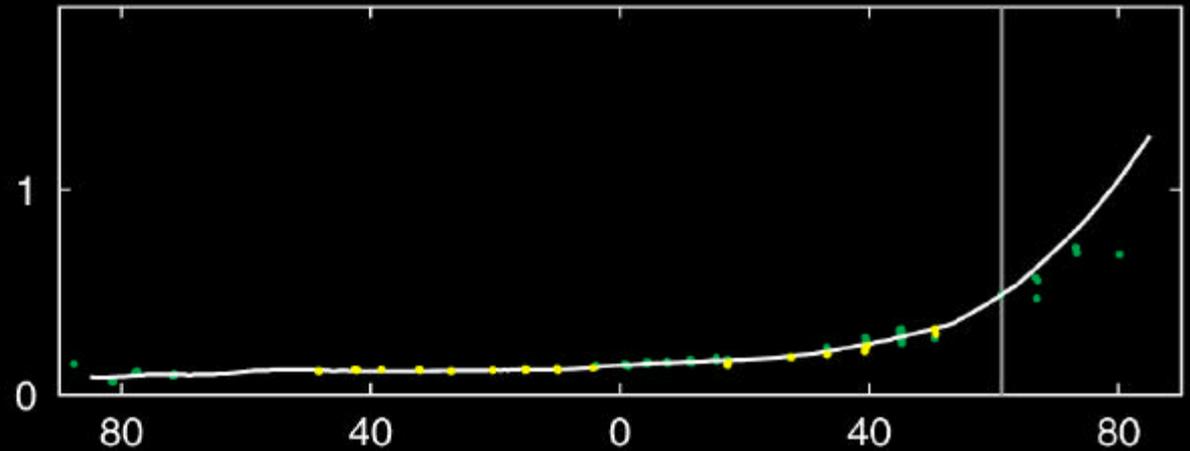
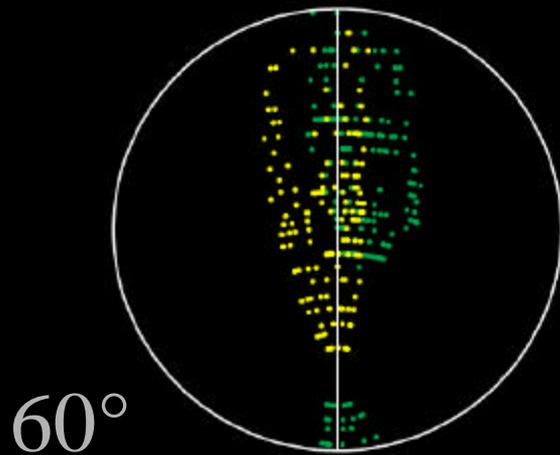
# Domain Coverage



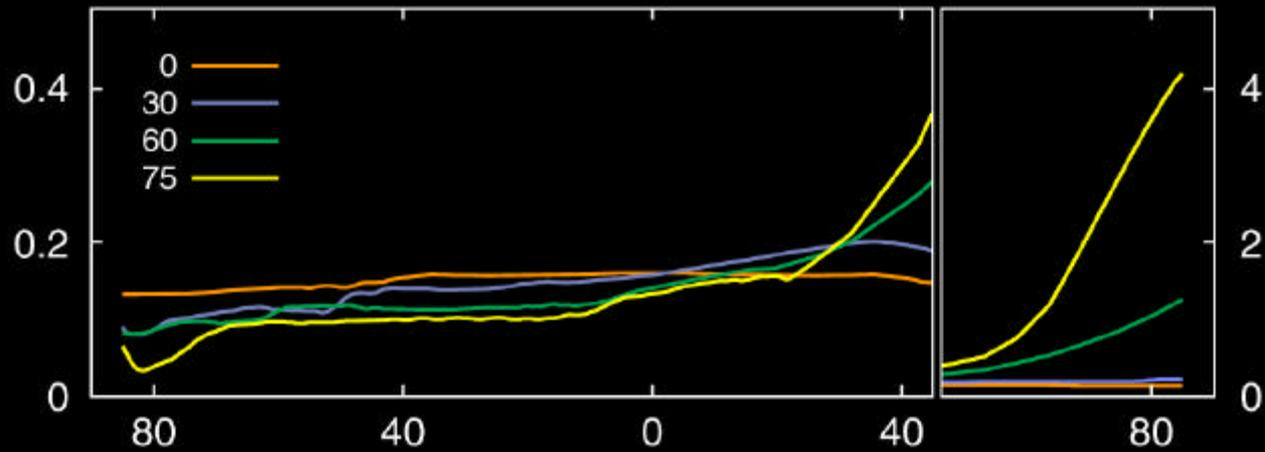
# Results: skin



# Results: skin



# Results: skin



# Face model

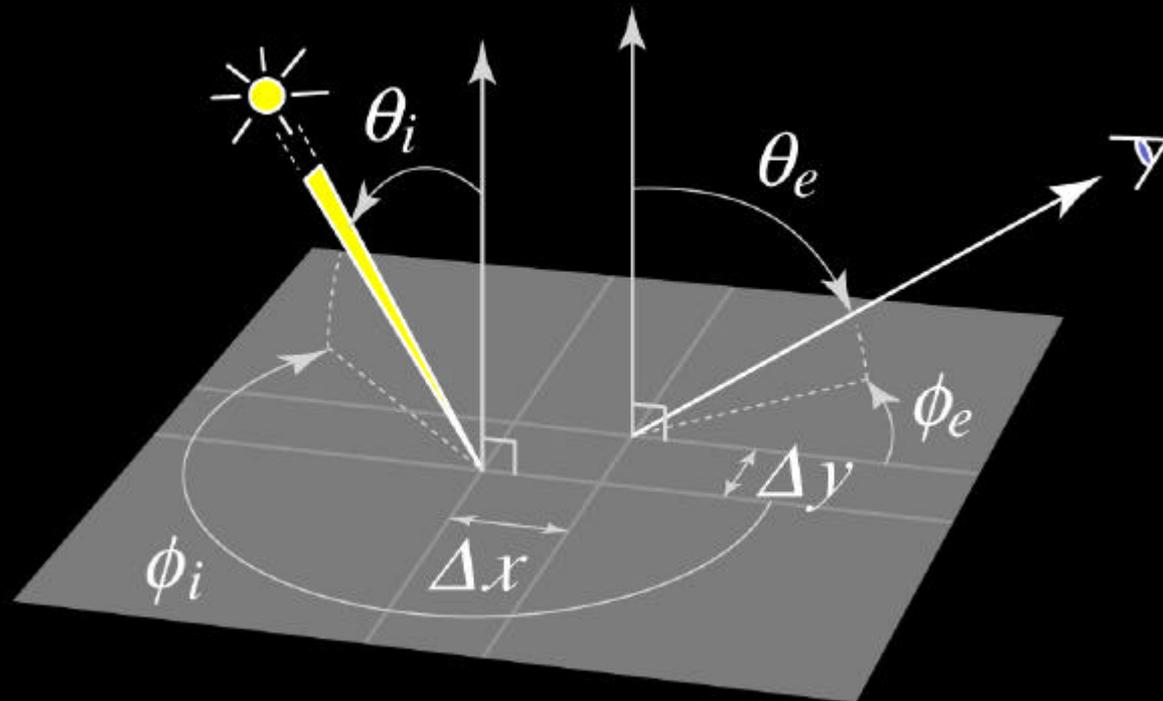


# Measuring Translucency

Techniques and results from:

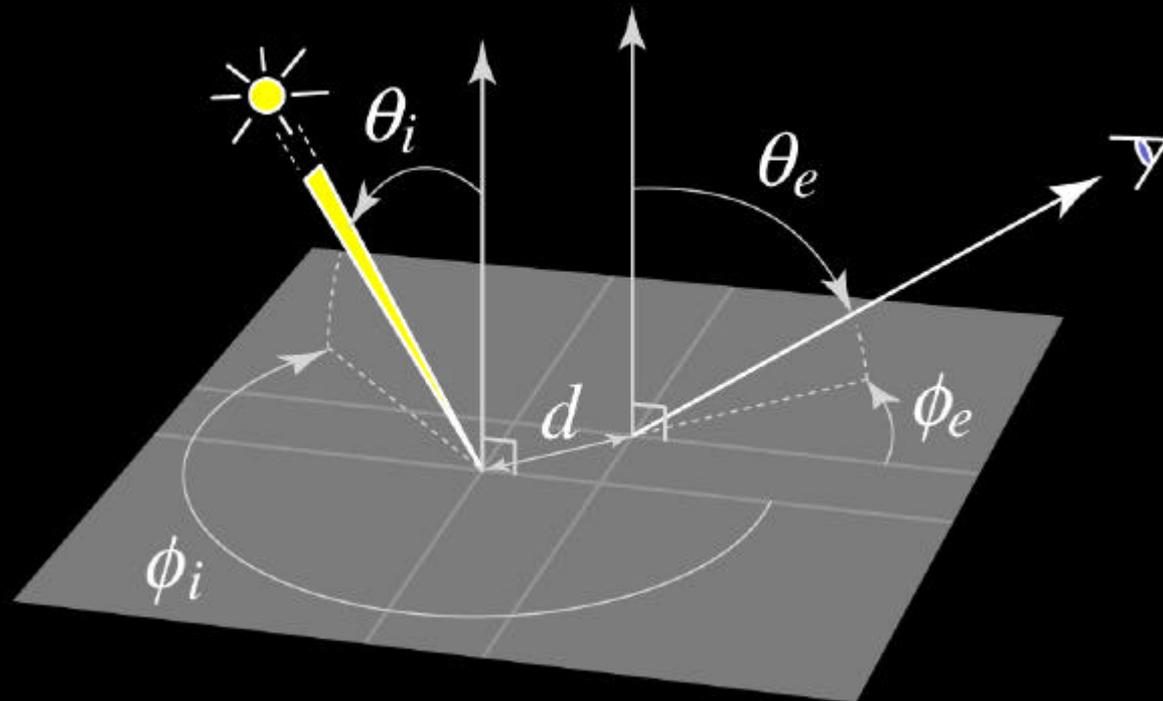
Henrik Wann Jensen, Stephen R. Marschner, Marc Levoy, and Pat Hanrahan. "A Practical Model for Subsurface Light Transport." In proceedings of *SIGGRAPH 2001*, August 2001.

# BSSRDF



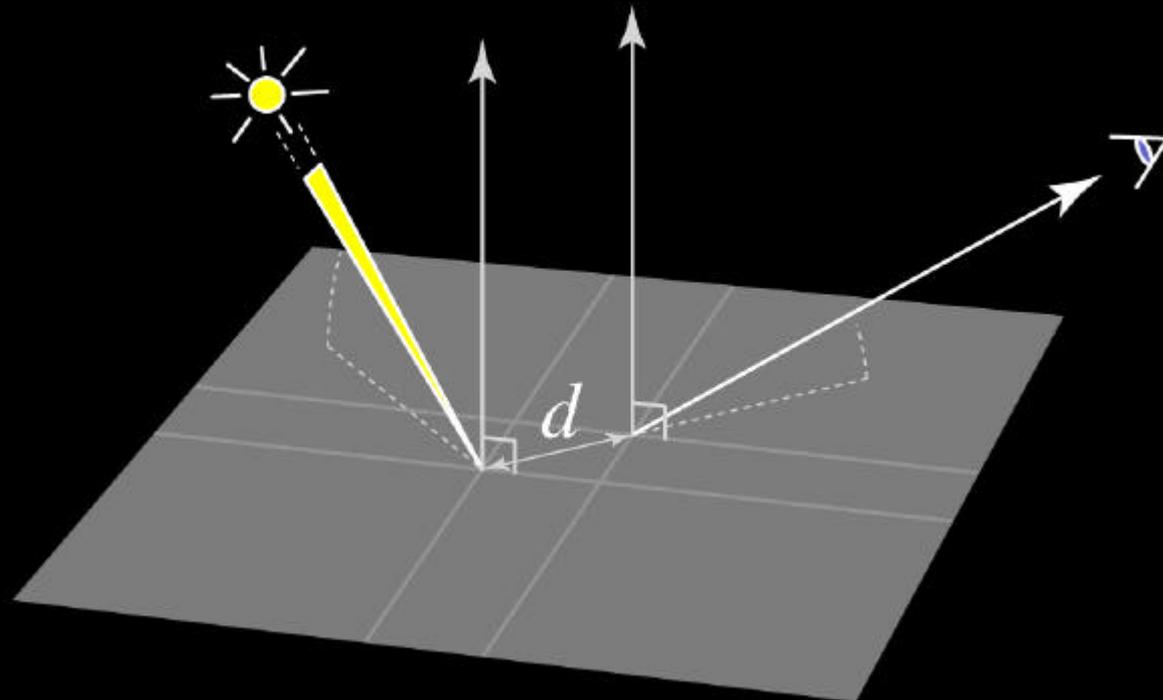
$$S(\theta_i, \phi_i, \theta_e, \phi_e, \Delta x, \Delta y)$$

# BSSRDF: isotropic



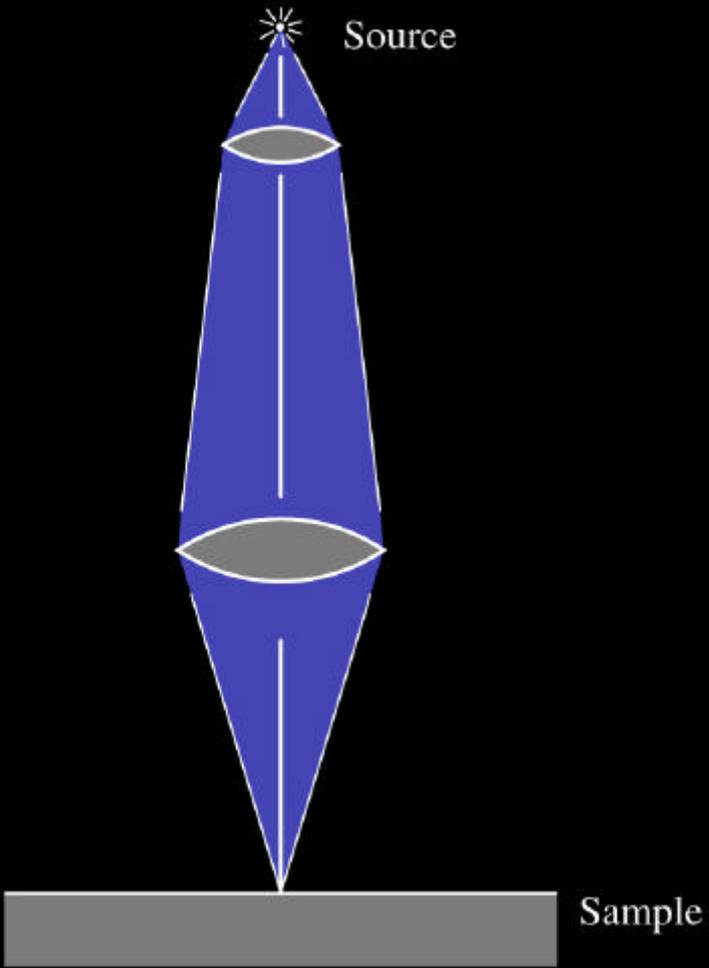
$$S(\theta_i, \phi_i, \theta_e, \phi_e, d)$$

# BSSRDF: Lambertian

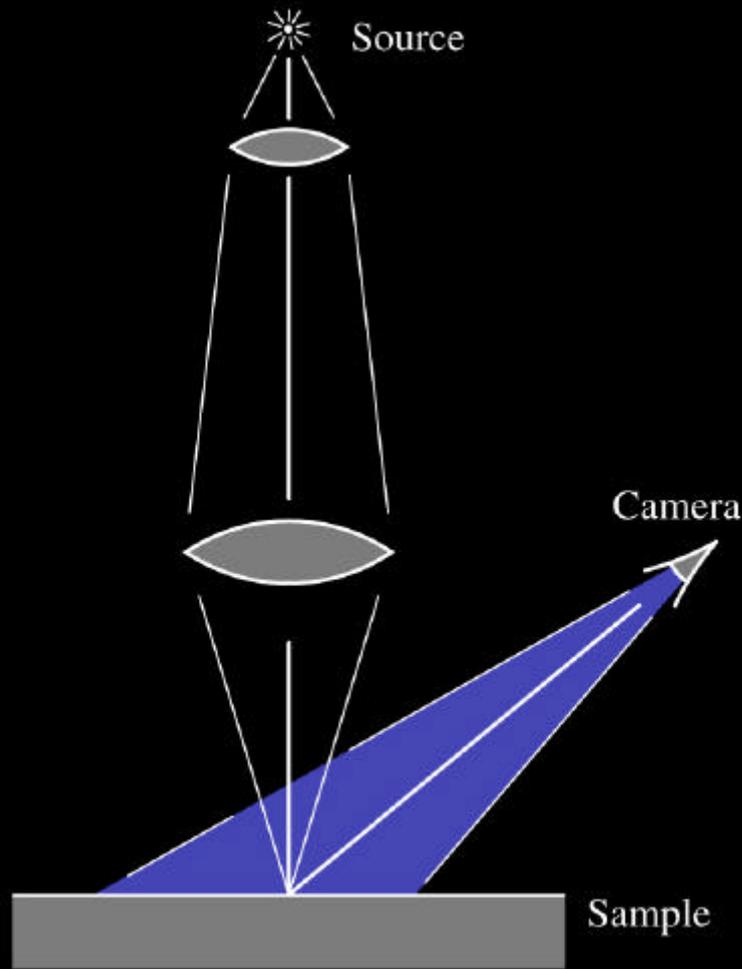


$$R_d(d)$$

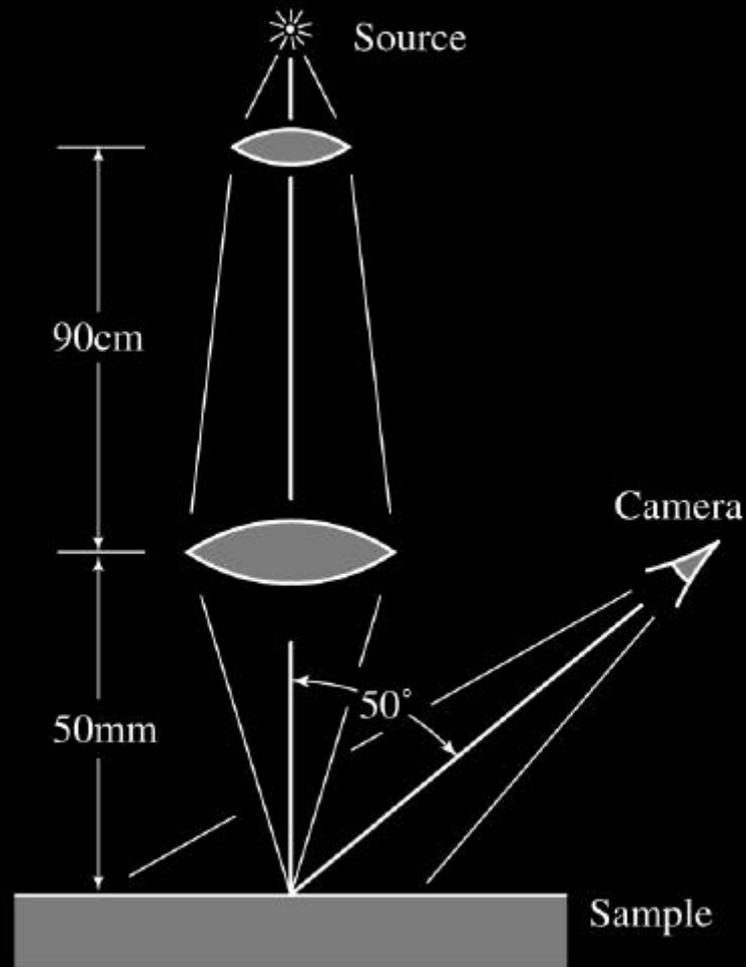
# Scattering measurement



# Scattering measurement



# Scattering measurement



# Marble sample

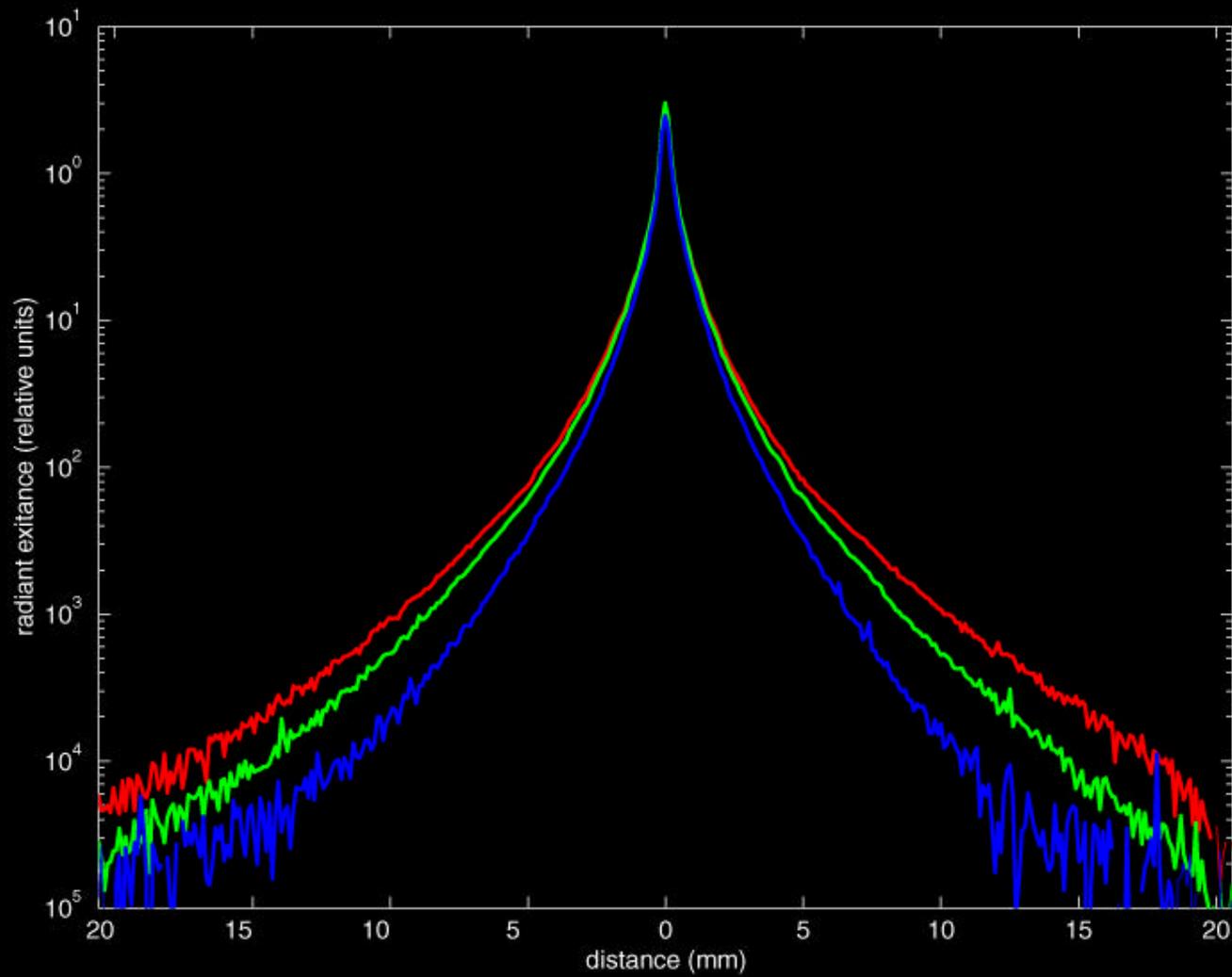


# HDR photograph

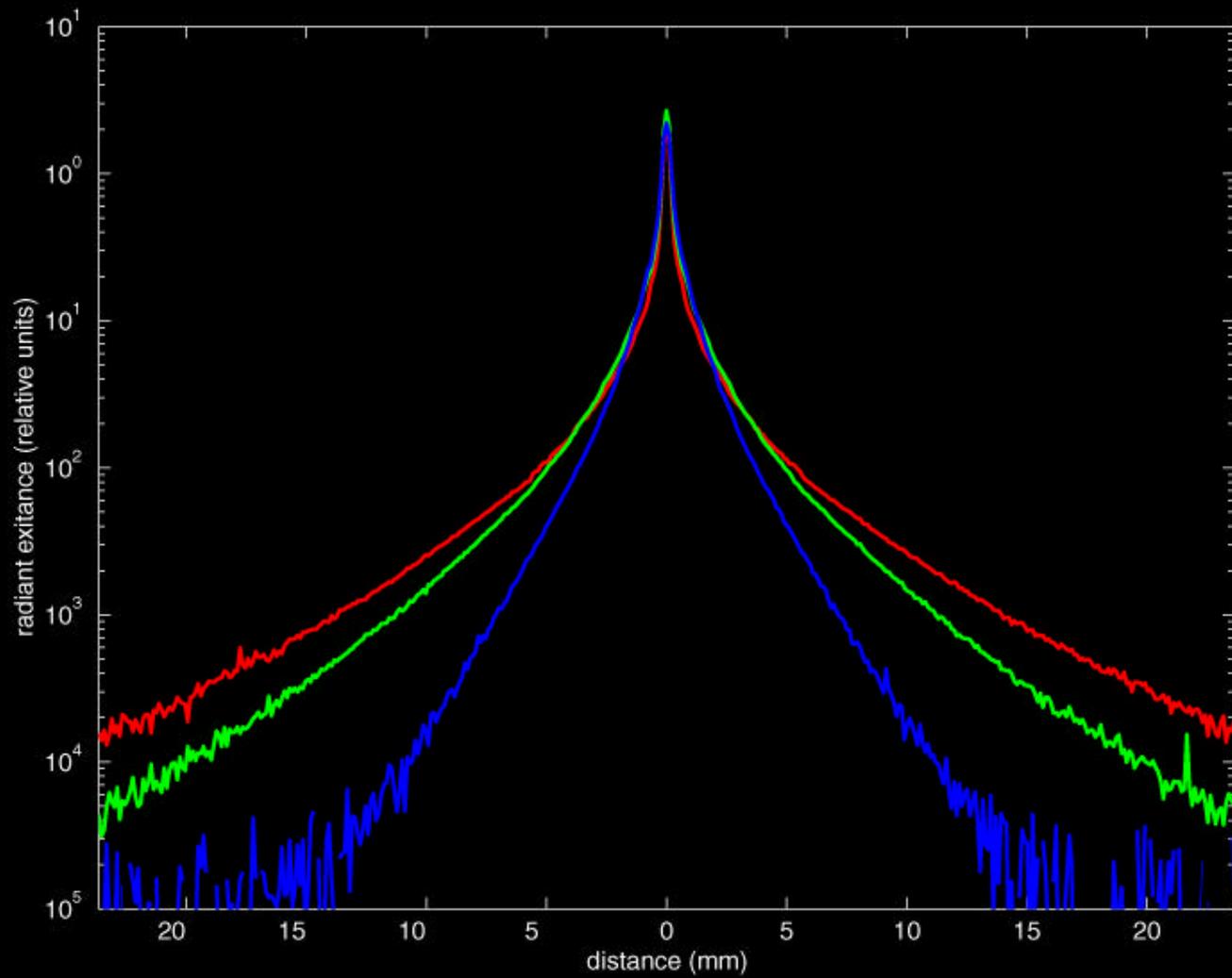


(log scaled image)

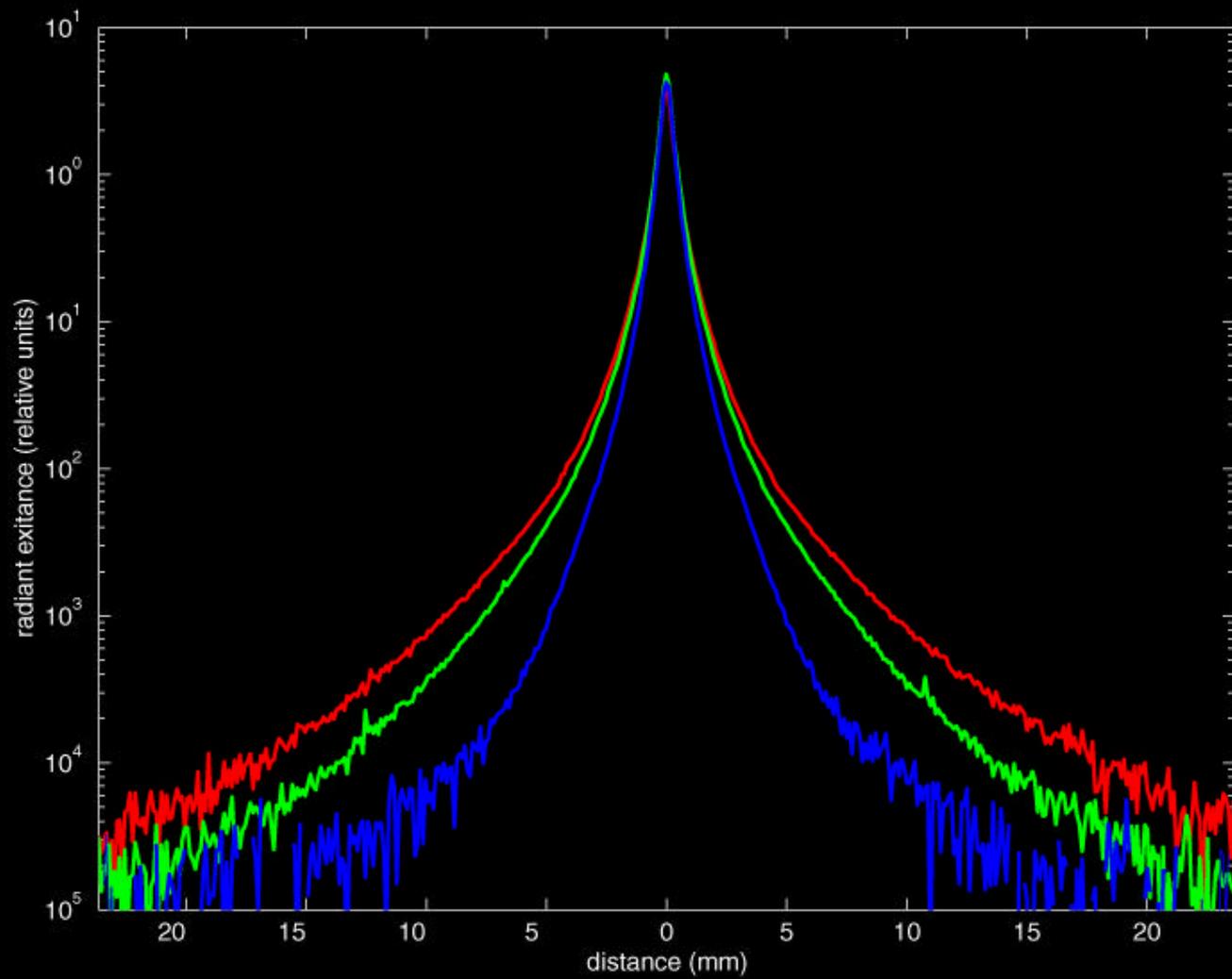
# Marble



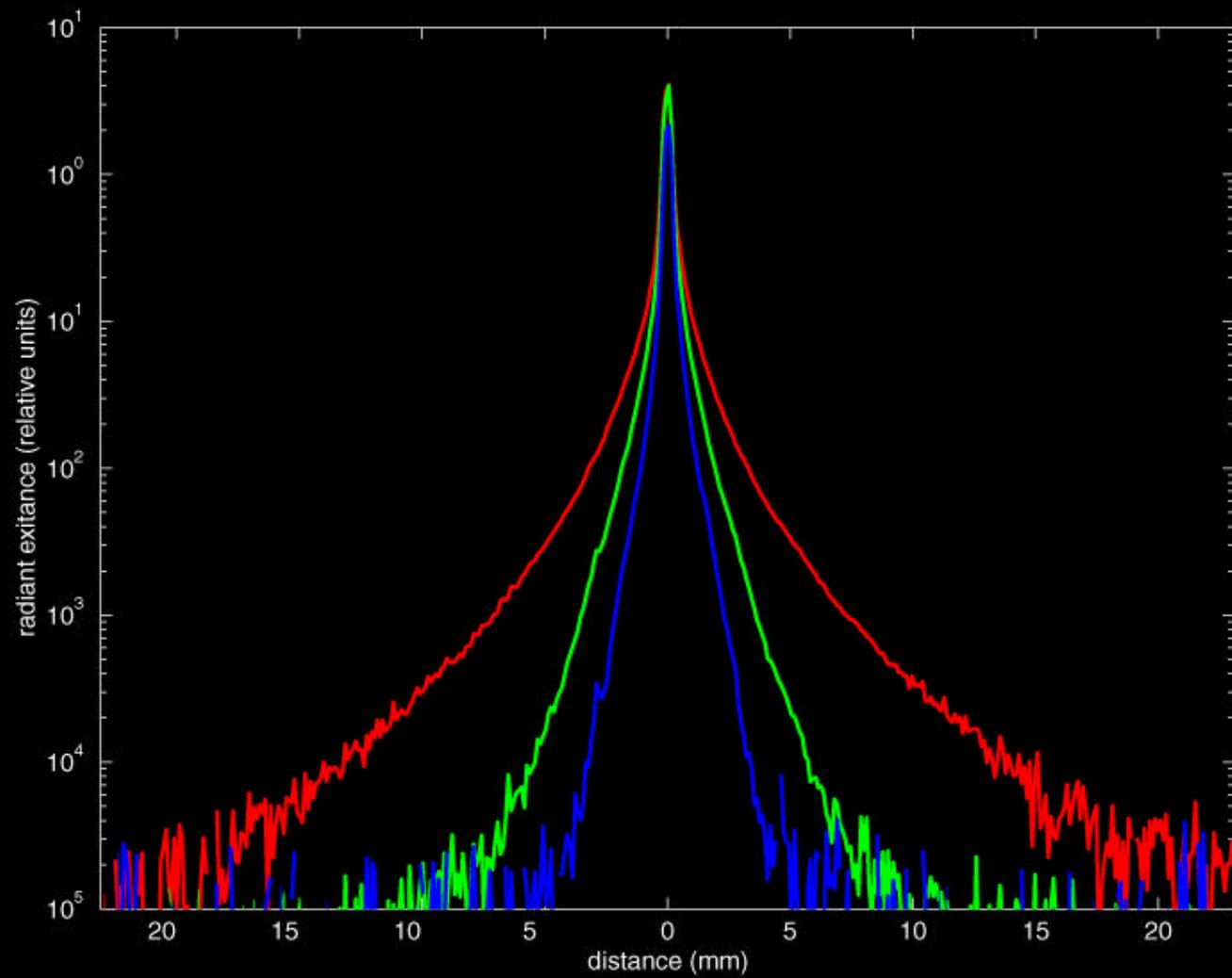
# Skim milk



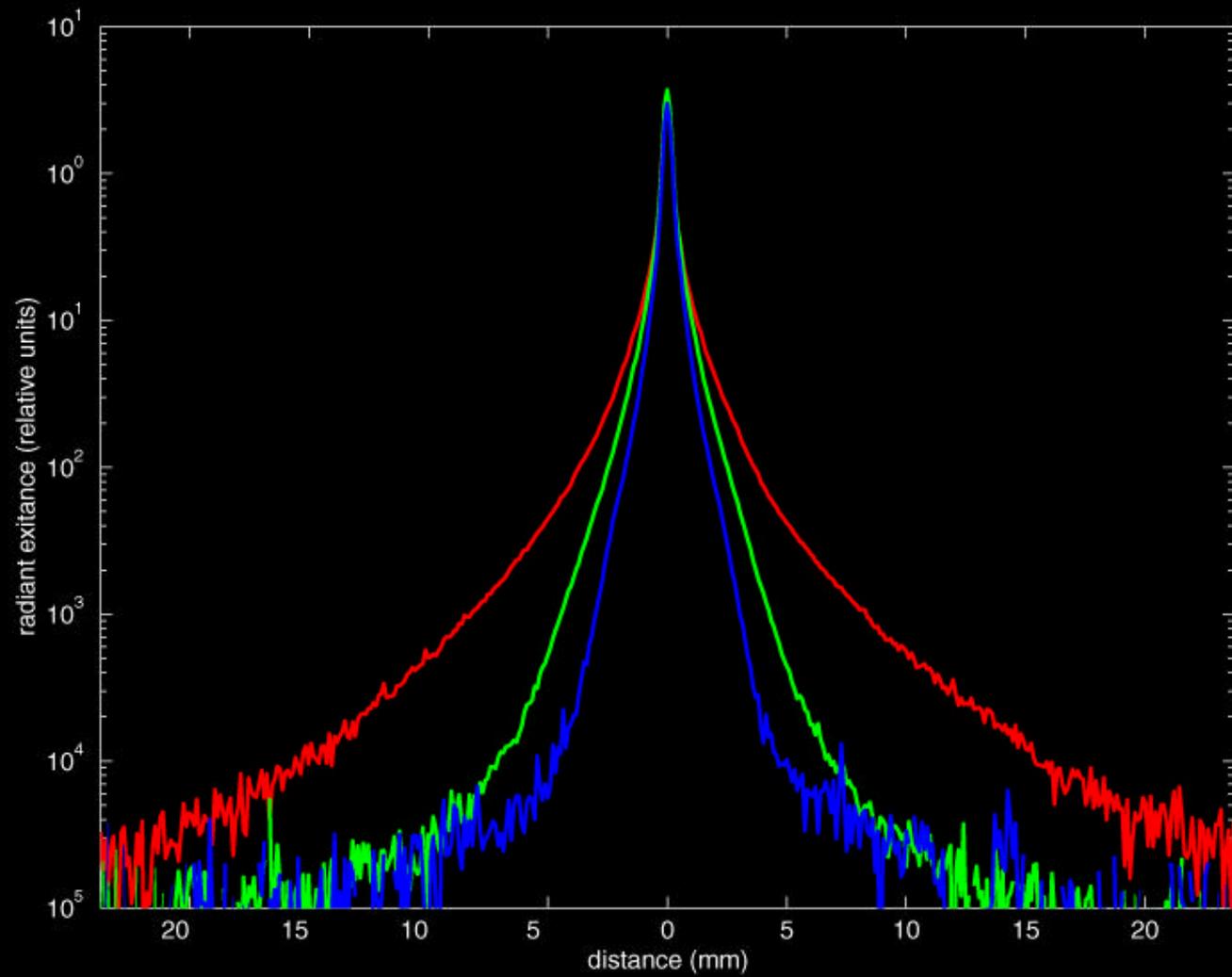
# Whole milk



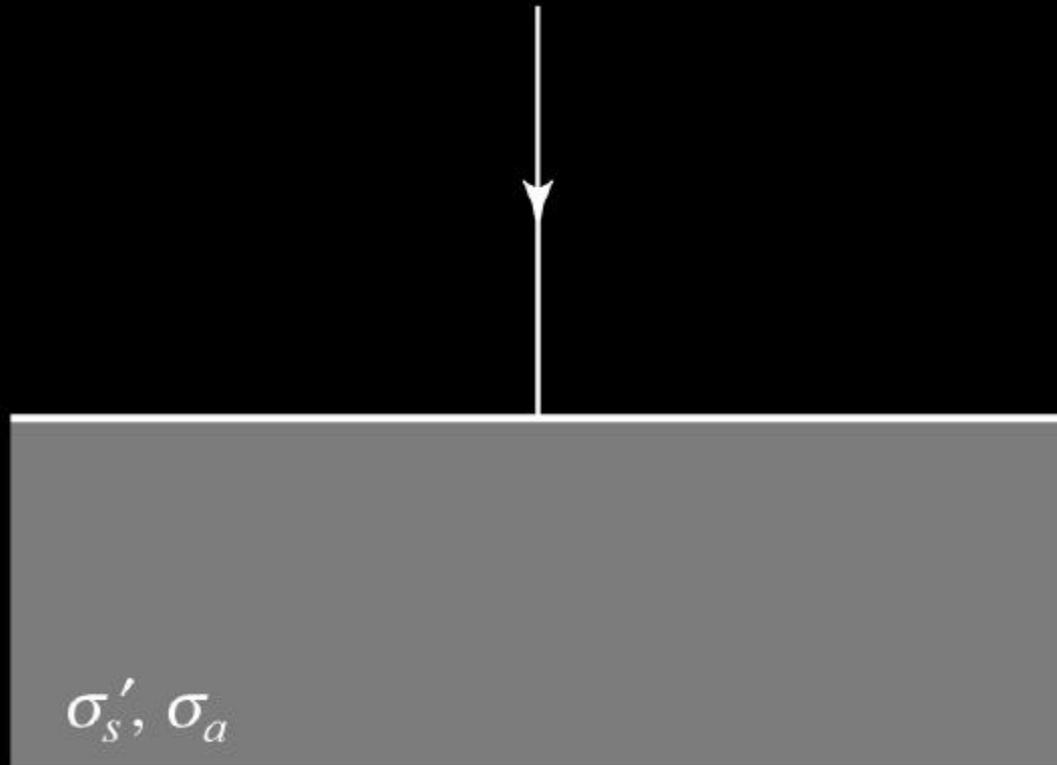
# Skin #1



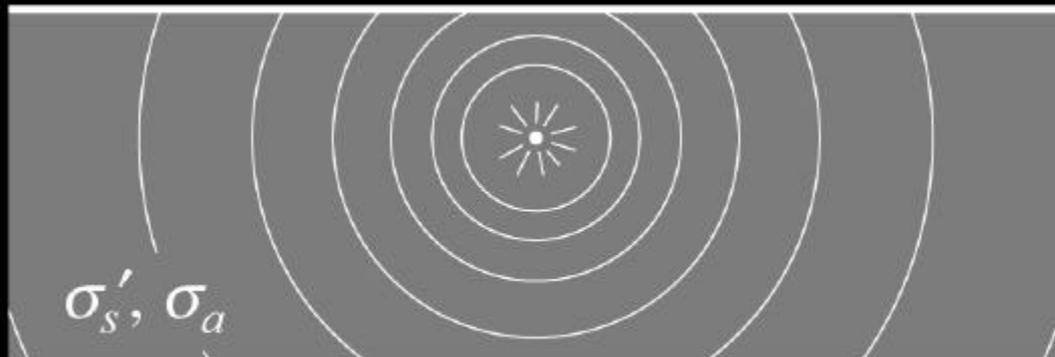
# Skin #2



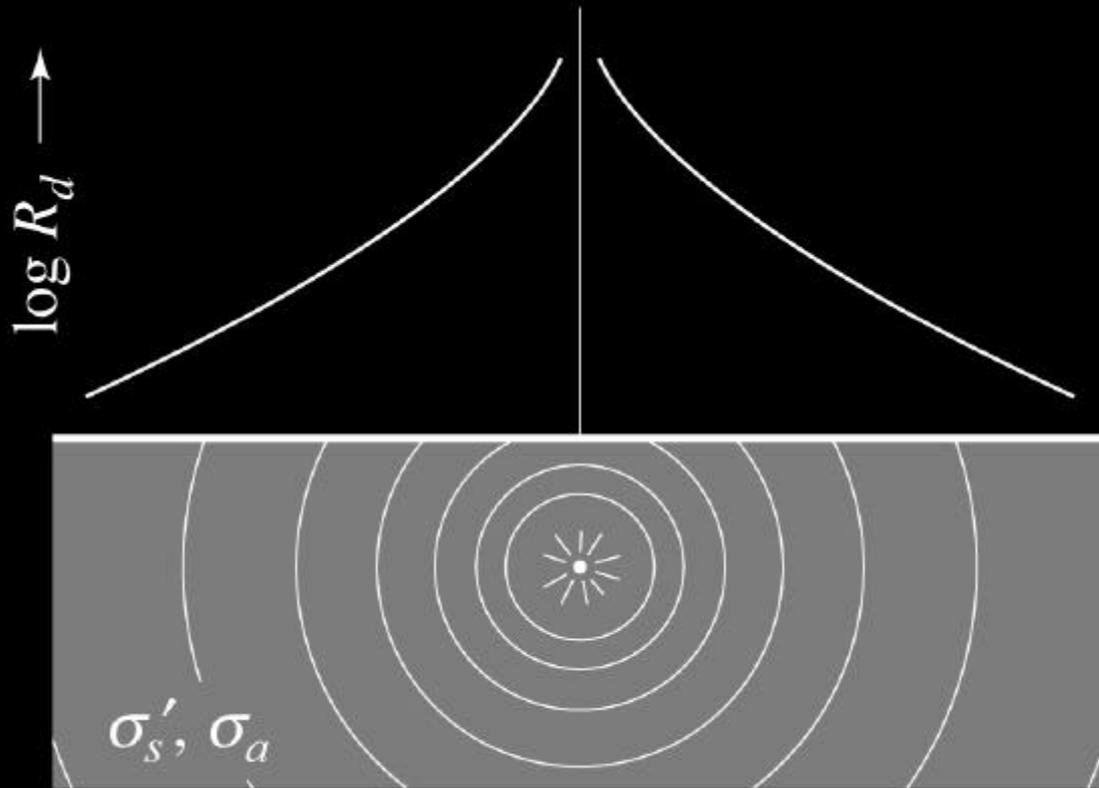
# Diffusion approximation



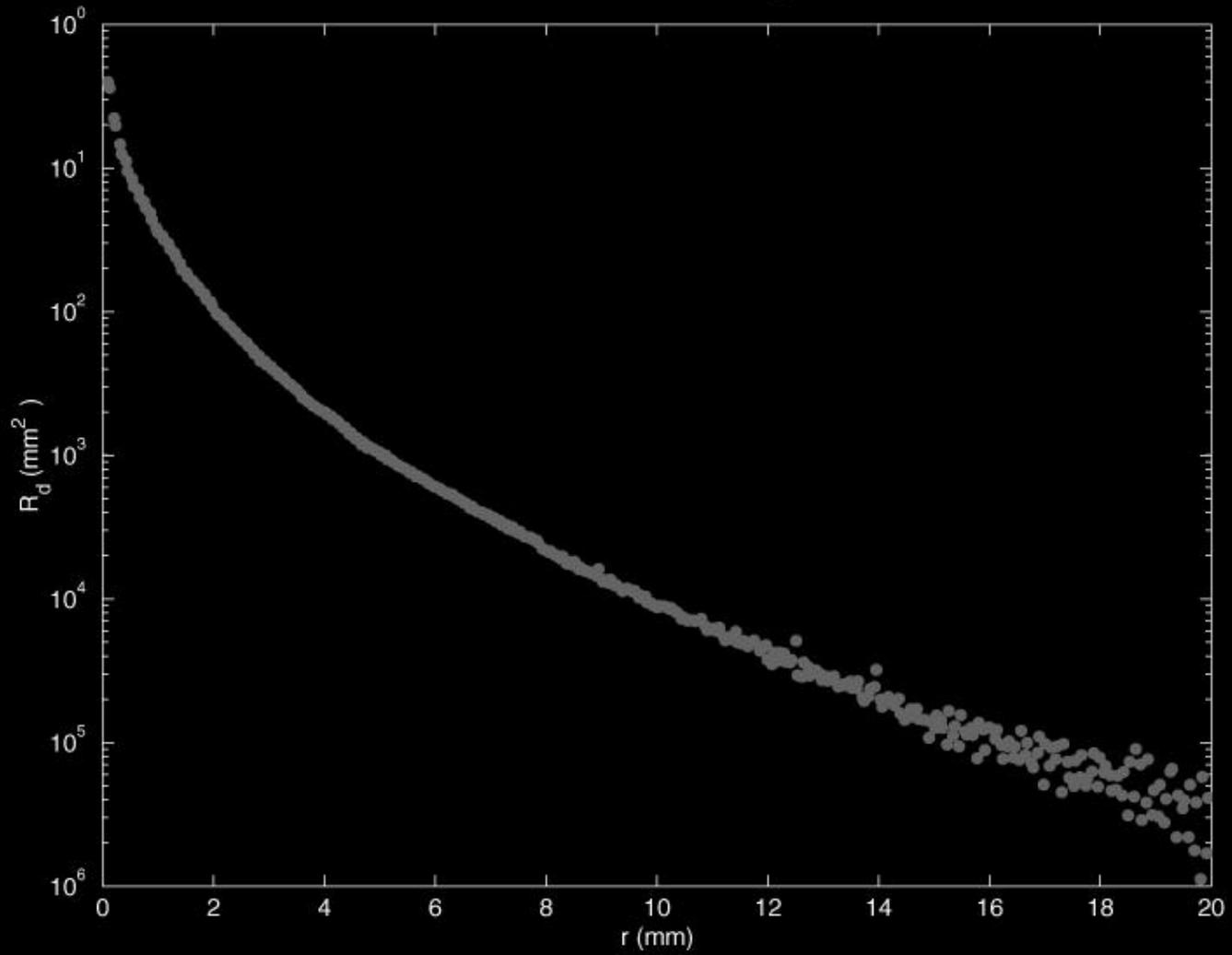
# Diffusion approximation



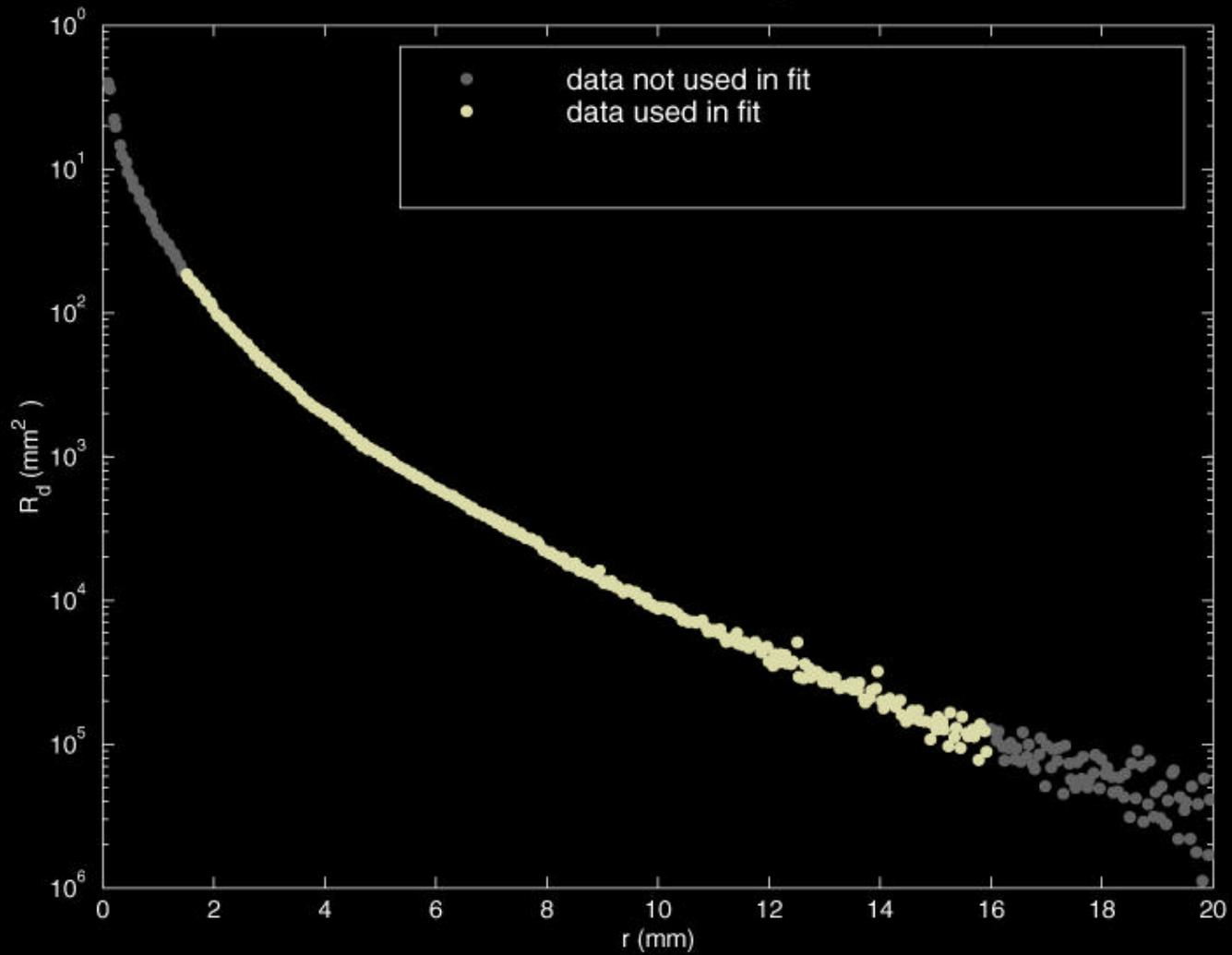
# Diffusion approximation



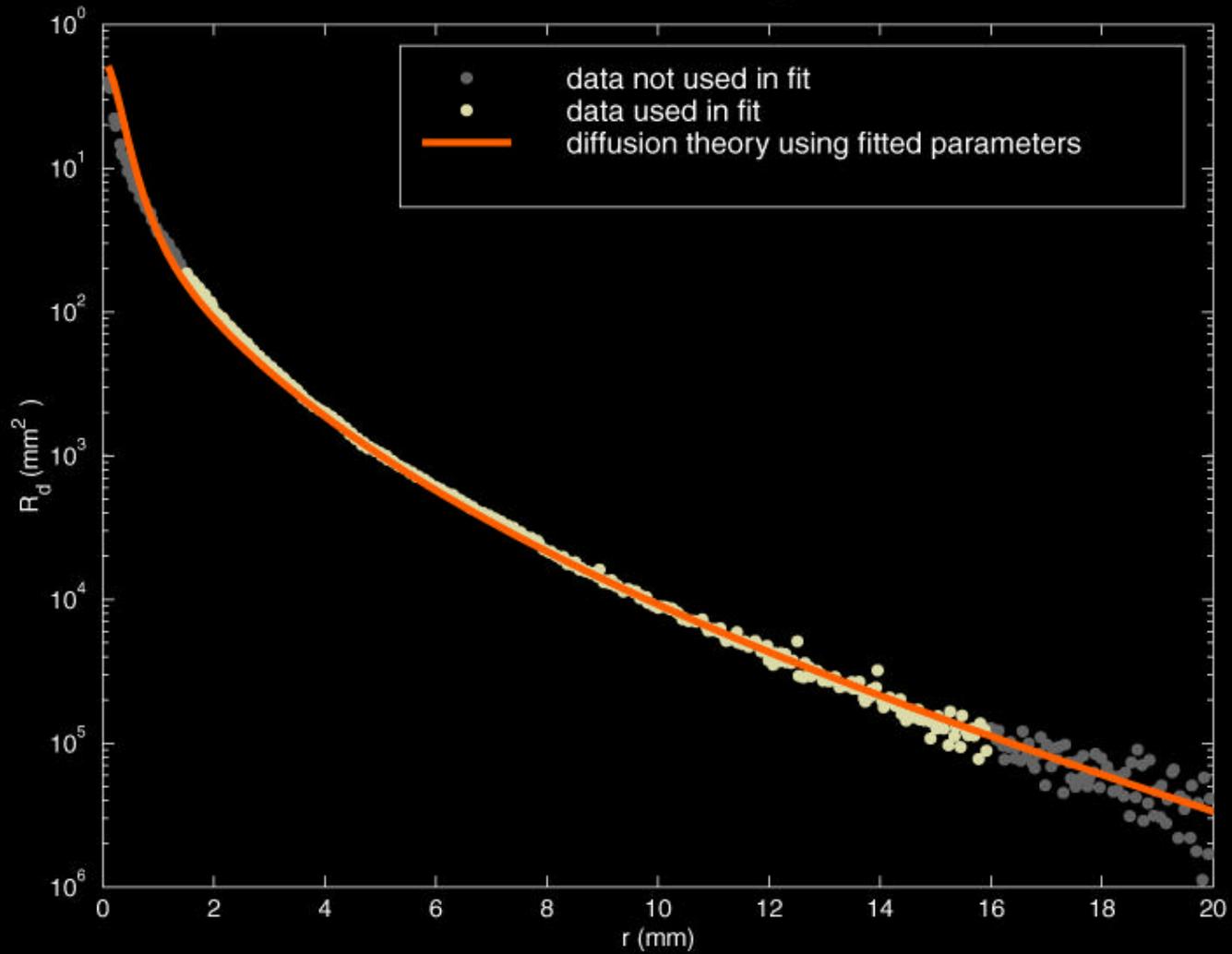
# Marble data fitting



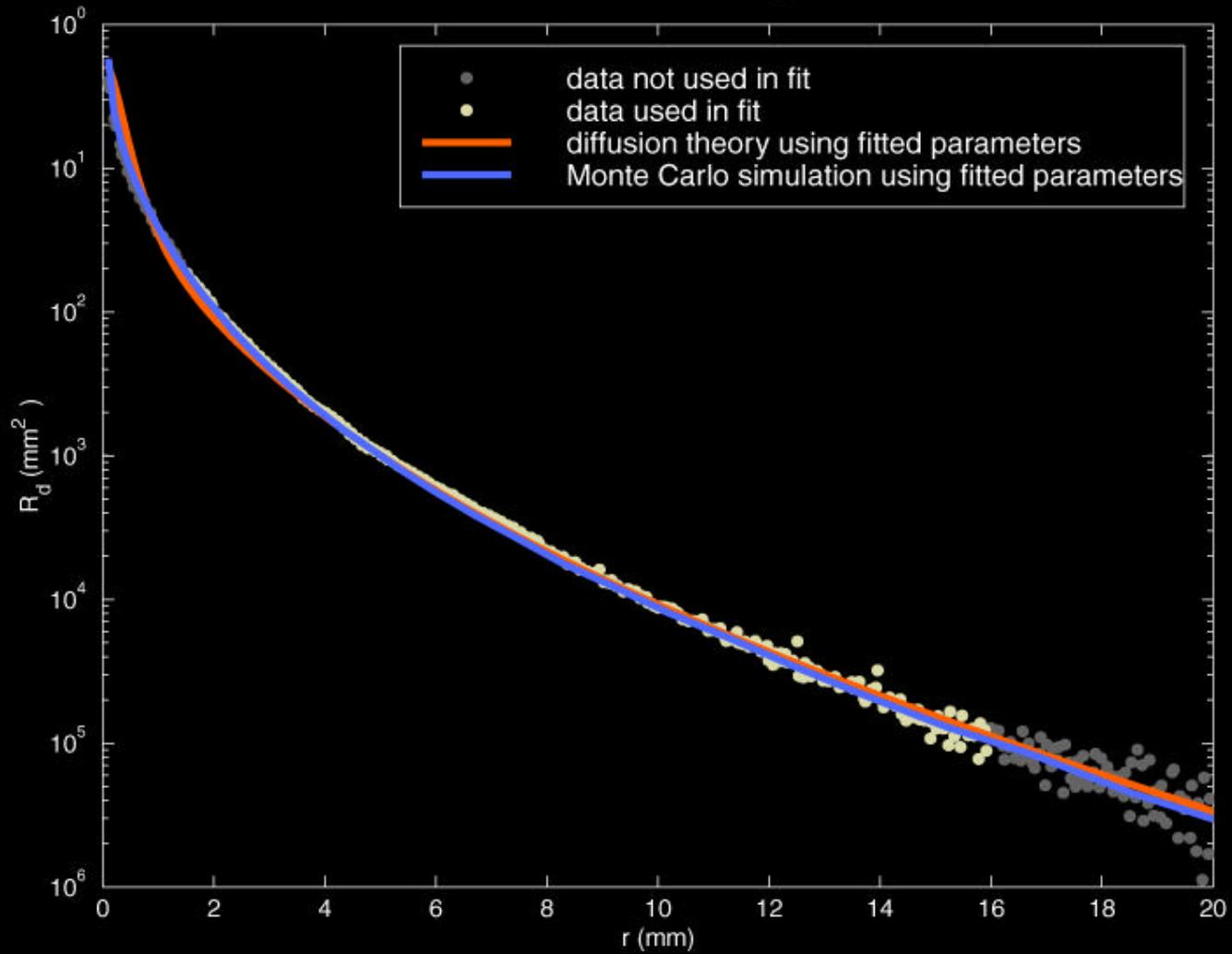
# Marble data fitting



## Marble data fitting



## Marble data fitting





Diffuse "milk"



Skim milk



Whole milk



Opaque face



Translucent face