# **Texture Mapping**

Brian Curless CSE 557 Fall 2014

### Reading

#### Required

• Shirley, 11.1-11.2, 11.4-11.6

#### **Recommended**

 Paul S. Heckbert. Survey of texture mapping. IEEE Computer Graphics and Applications 6(11): 56–67, November 1986.

#### **Optional**

- Woo, Neider, & Davis, Chapter 9
- James F. Blinn and Martin E. Newell. Texture and reflection in computer generated images. Communications of the ACM 19(10): 542–547, October 1976.

# **Texture mapping**



Texture mapping (Woo et al., fig. 9-1)

Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.

- Due to Ed Catmull, PhD thesis, 1974
- Refined by Blinn & Newell, 1976

A texture can modulate just about any parameter – diffuse color, specular color, specular exponent,

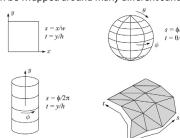
...

# Implementing texture mapping

A texture lives in it own abstract image coordinates paramaterized by (s,t) in the range ([0..1],[0..1]):



It can be wrapped around many different surfaces:



With a ray caster, we can do the sphere and cylinder mappings directly (as we will see later). For z-buffers, everything gets converted to a triangle mesh with associated (s,t) coordinates.

Note: if the surface moves/deforms, the texture goes with it.

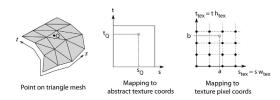
# Mapping to texture image coords

The texture is usually stored as an image. Thus, we need to convert from abstract texture coordinate:

(s,t) in the range ([0..1], [0..1])

to texture image coordinates:

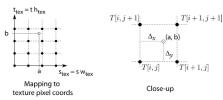
 $(s_{tex}t_{tex})$  in the range ([0..  $w_{tex}$ ], [0..  $h_{tex}$ ])



**Q**: What do you do when the texture sample you need lands between texture pixels?

## **Texture resampling**

We need to resample the texture:



Thus, we seek to solve for:  $T(a,b) = T(i + \Delta_x, j + \Delta_y)$ 

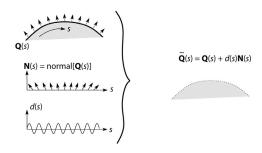
A common choice is bilinear interpolation:

$$\begin{split} \mathsf{T}\big(i+\Delta_{x},j\big) &= \underline{\hspace{1cm}} \mathsf{T}[i,j] &+ \underline{\hspace{1cm}} \mathsf{T}[i+1,j] \\ \mathsf{T}\big(i+\Delta_{x},j+1\big) &= \underline{\hspace{1cm}} \mathsf{T}[i,j+1] &+ \underline{\hspace{1cm}} \mathsf{T}[i+1,j+1] \\ \\ \mathsf{T}\big(i+\Delta_{x},j+\Delta_{y}\big) &= \underline{\hspace{1cm}} \mathsf{T}\big(i+\Delta_{x},j\big) &+ \underline{\hspace{1cm}} \mathsf{T}\big(i+\Delta_{x},j+1\big) \\ \\ &= \underline{\hspace{1cm}} \mathsf{T}[i,j] &+ \underline{\hspace{1cm}} \mathsf{T}[i+1,j] &+ \underline{\hspace{1cm}} \mathsf{T}[i+1,j+1] \end{split}$$

# Displacement mapping

Textures can be used for more than just color.

In **displacement mapping**, a texture is used to perturb the surface geometry itself. Here's the idea in 2D:



- These displacements "animate" with the surface
- In 3D, you would of course have (s,t) parameters instead of just s.

Suppose  $\mathbf{Q}$  is a simple surface, like a cube. Will it take more work to render the modified surface  $\mathbf{\tilde{Q}}$ ?

# **Bump mapping**

In **bump mapping**, a texture is used to perturb the normal:

- Use the original, simpler geometry, Q(s), for hidden surfaces
- Use the normal from the displacement map for shading:

$$\tilde{\mathbf{N}} = \text{normal}[\tilde{\mathbf{Q}}(s)]$$



What artifacts in the images would reveal that bump mapping is a fake?

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# Displacement vs. bump mapping

Input texture

Rendered as displacement map over a rectangular surface









# Displacement vs. bump mapping (cont'd)





Original rendering

Rendering with bump map wrapped around a cylinder

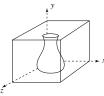
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Bump map and rendering by Wyvern Aldinger

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### **Solid textures**

**Q**: What kinds of artifacts might you see from using a marble veneer instead of real marble?



One solution is to use solid textures:

- Use model-space coordinates to index into a 3D texture
- Like "carving" the object from the material

One difficulty of solid texturing is coming up with the textures.

## Solid textures (cont'd)

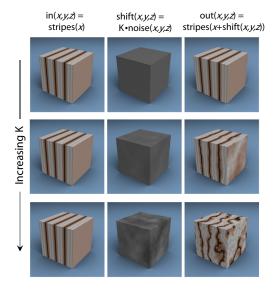
Here's an example for a vase cut from a solid marble texture:



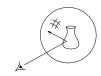
Solid marble texture by Ken Perlin, (Foley, IV-21)

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# Solid textures (cont'd)



# **Environment mapping**







In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:

- Rays are bounced off objects into environment
- Color of the environment used to determine color of the illumination
- Environment mapping works well when there is just a single object – or in conjunction with ray tracing

This can be readily implemented (without interreflection) using a fragment shader, where the texture is stored in a "cube map" instead of a sphere.

With a ray tracer, the concept is easily extended to handle refraction as well as reflection (and interreflection).

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