Replicated State Machines Primary-Backup

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Primary-Backup Replication

- Widely used
- Reasonably simple to implement
- Hard to get desired consistency and performance
- Will revisit this and consider other approaches later in the class

Fault Tolerance

- we'd like a service that continues despite failures!
- available: still useable despite *some class of* failures
- strong consistency: act just like a single server to clients
- very useful!
- very hard!

Failure Model

- What do we want to cope with?
 - Independent fail-stop computer failure
 - Site-wide power failure (and eventual reboot)
 - Network partition
 - No bugs, no malice

Core Idea: replication

- Two servers (or more)
- Each replica keeps state needed for the service
- If one replica fails, others can continue

Key Questions

- What state to replicate?
- How does replica get state?
- When to cut over to backup?
- Are anomalies visible at cut-over?
- How to repair/re-integrate?

Two Main Approaches

- State transfer
 - "Primary" replica executes the service
 - Primary sends [new] state to backups
- Replicated state machine
 - All replicas execute all operations
 - If same start state, same operations, same order, deterministic → then same end state

• There are tradeoffs: complexity, costs, consistency

Design Space

- Active or passive replicas
- Symmetric replicas or primary-backup
- Replicate commands or low-level inputs

State Machines



- *c* is a Command
- *f* is a Transition Function

State Machine Replication (SMR)



- The State Machine Approach to a fault tolerant distributed system
- Keep around
 N copies of
 the state
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Great!













• Replicas need to handle requests in the same *order*



SMR

- All non faulty servers need:
 - Agreement
 - Every replica needs to accept the same set of requests
 - Order
 - All replicas process requests in the same relative order

Implementation

- Order
 - Assign unique ids to requests, process them in ascending order.
 - How do we assign unique ids in a distributed system?
 - How do we know when every replica has processed a given request?





Replica Generated IDs

- 2 Phase ID generation
 - Every Replica proposes a *candidate*
 - One candidate is chosen and agreed upon by all replicas



1) Propose Candidates



2) Accept r0



3) Accept *r1*

r1 is now stable

4) Apply *r1*

5) Apply *r0*

- Fault Tolerant Storage Service (Fail-Stop)
- Requests:
 - Update(x, y) => set object x to value y
 - Query(x) => read value of object **x**

- How does Chain Replication implement State Machine Replication?
- Agreement
 - Only *Update* modifies state, can ignore *Query*
 - Client always sends *update* to *Head*. *Head* propagates request down chain to *Tail*.
 - Everyone accepts the request!

- How does Chain Replication implement State Machine Replication?
- Order
 - Unique IDs generated implicitly by *Head*'s ordering
 - FIFO order preserved down the chain
 - Tail interleaves *Query* requests
 - How can clients tell when their *Updates* have been handled?

Fault Tolerance

- Trusted Master
 - Fault-tolerant state machine
 - Trusted by all replicas
 - Monitors all replicas & issues commands
- How can you rely on this trusted master?

Fault Tolerance

- Failure cases:
 - Head Fails
 - *Master* assigns 2nd node as Head
 - Tail Fails
 - *Master* assigns 2nd to last node as Tail
 - Intermediate Node Fails
 - *Master* coordinates chain link-up

Chain Replication Evaluation

- Compare to other primary/backup protocols
- Tradeoffs?
 - Latency
 - Consistency
- Trusted Master

VMware's FT Virtual Machines

- Whole-system replication
- Completely transparent to applications and clients
- High availability for any existing software
- Failure model:
 - independent hardware faults
 - site-wide power failure
- Limited to uniprocessor VMs

Overview

- two machines, primary and backup
- shared-disk for persistent storage
- back-up in "lock step" with primary
 - primary sends all inputs to backup
 - outputs of backup are dropped
- heart beats between primary and backup
 - if primary fails, start backup executing!

Challenges

- Making it look like a single reliable server
- How to avoid two primaries? ("split-brain syndrome")
- How to make backup an exact replica of primary
- What inputs must be sent to backup?
- How to deal with non-determinism?

Technique 1: Deterministic Replay

- Goal: make x86 platform deterministic
 - idea: use hypervisor to make virtual x86 platform deterministic
- Log all hardware events into a log
 - clock interrupts, network interrupts, i/o interrupts, etc.
 - for non-deterministic instructions, record additional info
 - e.g., log the value of the time stamp register
 - on replay: return the value from the log instead of the actual register

Deterministic Replay

- Replay: deliver inputs in the same order, at the same instructions
 - if during recording delivered clock interrupt at nth instr.
 - during replay also deliver the interrupt at the nth instr.
- Given an event log, deterministic replay recreates VM
 - hypervisor delivers first event
 - lets the machine execute to the next event
 - using special hardware registers to stop the processor at the right instruction
 - OS runs identical, applications runs identical
- Limitation: cannot handle multicore processors and interleaving

Applying Deterministic Replay to VM-FT

- Hypervisor at primary records
 - Sends log entries to backup over logging channel
- Hypervisor at backup replays log entries
 - We need to stop virtual x86 at instruction of next event
 - We need to know what is the next event
 - backup lags behind one event

Example

- Primary receives network interrupt
 - hypervisor forwards interrupt plus data to backup
 - hypervisor delivers network interrupt to OS kernel
 - OS kernel runs, kernel delivers packet to server
 - server/kernel write response to network card
 - hypervisor gets control and puts response on the wire
- Backup receives log entries
 - backup delivers network interrupt
 - ...
 - hypervisor does *not* put response on the wire
 - hypervisor ignores local clock interrupts

Technique 2: FT Protocol

- Primary delays any output until the backup acks
 - Log entry for each output operation
 - Primary sends output after backup acked receiving output operation
- Performance optimization:
 - primary keeps executing past output operations
 - buffers output until backup acknowledges

Questions

- Why send output events to backup and delay output until backup has acked?
- What happens when primary fails after receiving network input but before sending a corresponding log entry to backup?