

Announcements



- Project proposal due next week: Tuesday 10/24
- Still looking for people to work on deep learning Phytolith project, join #phytolith slack channel



Gradient Descent

Machine Learning – CSE546

Kevin Jamieson

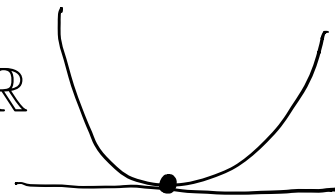
University of Washington

October ¹⁹~~18~~, 2016

Machine Learning Problems

- Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

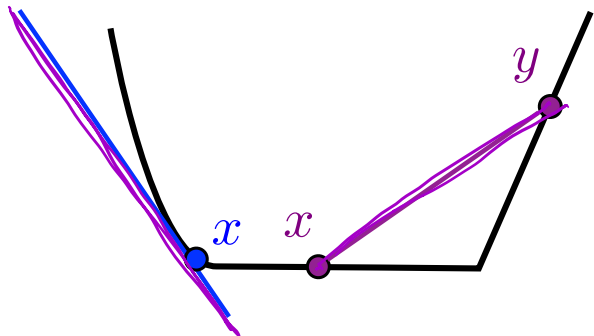


- Learning a model's parameters:

Each $\ell_i(w)$ is convex.

$$\sum_{i=1}^n \ell_i(w)$$

$f(x)$ is a minimum of f if g is a sub-gradient at x



f convex:

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

$$\forall x, y, \lambda \in [0, 1]$$

$$f(y) \geq f(x) + \nabla f(x)^T (y - x) \quad \forall x, y$$

g is a subgradient at x if

$$f(y) \geq f(x) + g^T (y - x)$$

Machine Learning Problems

- Have a bunch of iid data of the form:

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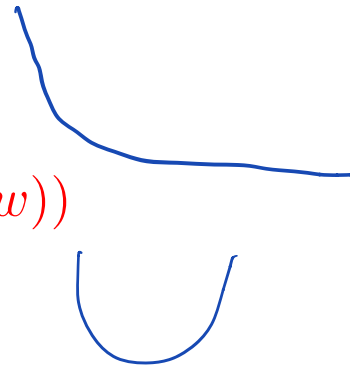
- Learning a model's parameters:

Each $\ell_i(w)$ is convex.

$$\sum_{i=1}^n \ell_i(w)$$

Logistic Loss: $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$

Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$



Taylor Series Approximation

$\eta > 0$

- Taylor series in one dimension:

$$f(x + \delta) = f(x) + f'(x)\delta + \frac{1}{2}f''(x)\delta^2 + \dots$$

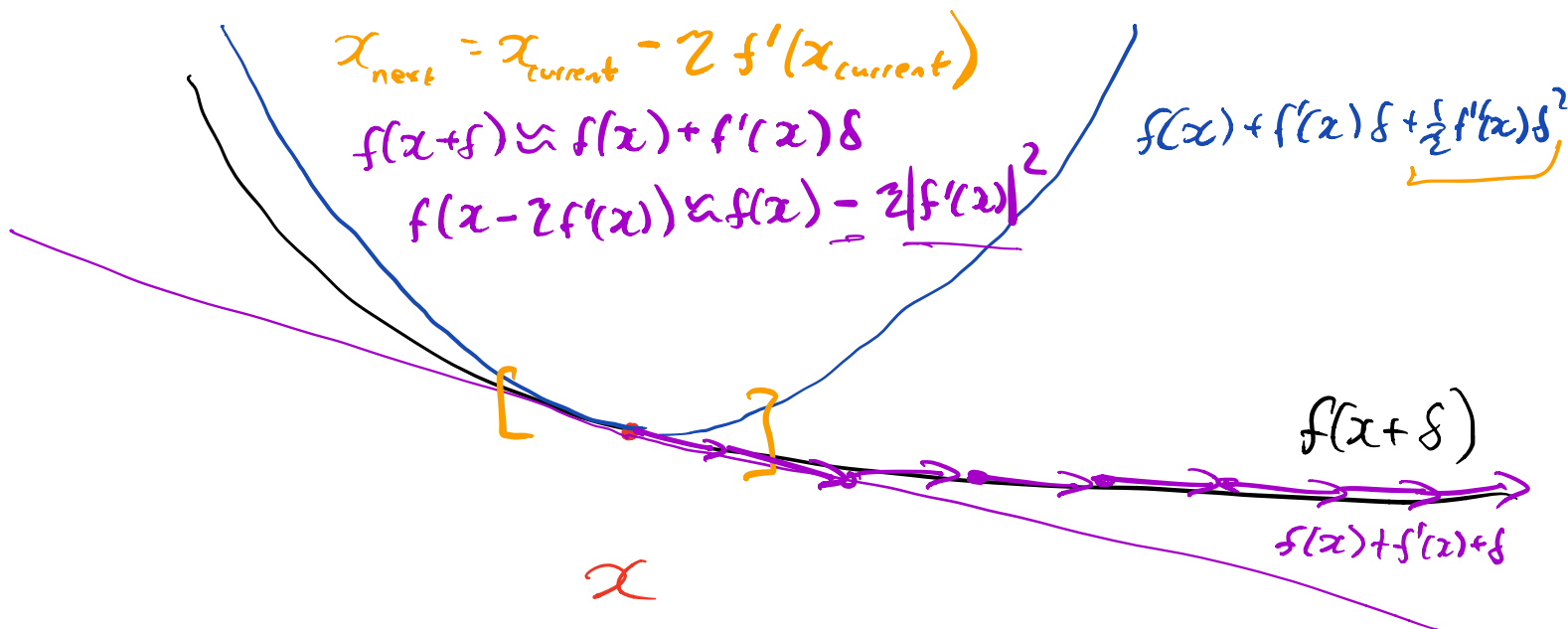
- Gradient descent:

$$x_{\text{next}} = x_{\text{current}} - \eta f'(x_{\text{current}})$$

$$f(x+\delta) \approx f(x) + f'(x)\delta$$

$$f(x - \eta f'(x)) \approx f(x) - \eta |f'(x)|^2$$

$$f(x) + f'(x)\delta + \frac{1}{2}f''(x)\delta^2$$



Taylor Series Approximation

f is convex $\Leftrightarrow \nabla^2 f(x) \succeq 0 \quad \forall x$ ^{PSD}

- Taylor series in d dimensions:

$$f(x + v) = f(x) + \nabla f(x)^T v + \frac{1}{2} v^T \nabla^2 f(x) v + \dots$$

- Gradient descent:

Hessian of f at x
 $\nabla^2 f(x) \in \mathbb{R}^{d \times d}$

$$f(x+v) \approx f(x) + \nabla f(x)^T v$$

$$f(x - \alpha \nabla f(x)) \approx f(x) - \alpha \|\nabla f(x)\|_2^2$$

$$\bullet f(x) + \nabla f(x)^T v$$

General case

$$w_0 = 0$$

$$w_{t+1} = w_t - \eta \nabla f(w_t)$$

$$w_{t+1} = w_t + \eta p_t$$

In general for Newton's method to achieve $f(w_t) - f(w_*) \leq \epsilon$:

$$t \approx O(\log(\log(1/\epsilon)))$$

So why are ML problems overwhelmingly solved by gradient methods?

Hint: v_t is solution to : $\nabla^2 f(w_t)v_t = -\nabla f(w_t)$

General Convex case

$$f(w_t) - f(w_*) \leq \epsilon$$

Newton's method:

$$t \approx \log(\log(1/\epsilon))$$

$$A \preceq B$$

$$B - A \succeq 0$$

B - A is PSD

Gradient descent:

- f is *smooth* and *strongly convex*: $aI \preceq \nabla^2 f(w) \preceq bI$

$$t \approx \frac{b}{a} \log(1/\epsilon)$$

- f is *smooth*: $\nabla^2 f(w) \preceq bI$

$$t \approx \frac{b}{\epsilon}$$

Newton's method $\sqrt{\frac{b}{\epsilon}}$

- f is potentially non-differentiable: $\|\nabla f(w)\|_2 \leq c$

$$\sqrt{\epsilon^2}$$

Other: BFGS, Heavy-ball, BCD, SVRG, ADAM, Adagrad,...

Clean
convergence
proofs:
Bubeck

Nocedal
+Wright,
Bubeck



Revisiting... Logistic Regression

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October ~~16~~¹⁹, 2016

Loss function: Conditional Likelihood

- Have a bunch of iid data of the form: $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d$, $y_i \in \{-1, 1\}$

$$\hat{w}_{MLE} = \arg \max_w \prod_{i=1}^n P(y_i | x_i, w) \quad P(Y = y | x, w) = \frac{1}{1 + \exp(-y w^T x)}$$

$$f(w) = \arg \min_w \sum_{i=1}^n \log(1 + \exp(-y_i x_i^T w))$$

$\frac{e^a}{1 + e^a} = 1 - \frac{1}{1 + e^a}$

$$\begin{aligned} \nabla f(w) &= \sum_{i=1}^n \frac{1}{1 + \exp(-y_i x_i^T w)} (-y_i x_i \exp(-y_i x_i^T w)) \\ &= \sum_{i=1}^n (1 - \sigma_i(w)) (-y_i x_i) \end{aligned}$$

$$w_0 = 0$$

$$w_{t+1} = w_t - \eta \nabla f(w_t)$$

$$\sigma_i(w) = \frac{1}{1 + \exp(-y_i x_i^T w)}$$



Online Learning

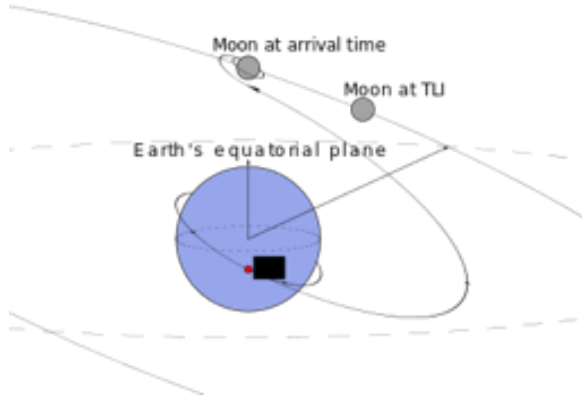
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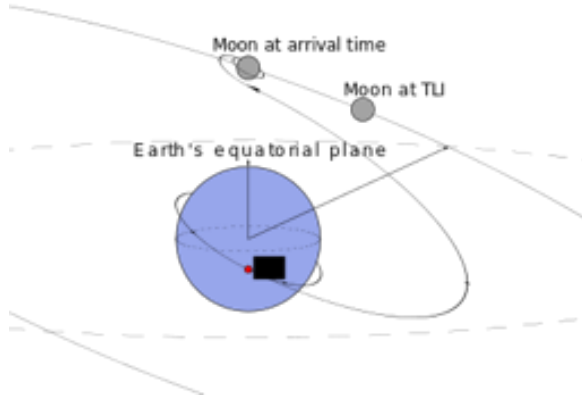
Going to the moon



Guidance computer predicts trajectories around moon and back with

- Noisy sensors
- Imperfect models
- Little computational power
- Big risk of failure

Going to the moon



Guidance computer predicts trajectories around moon and back with

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Why is Tom Hanks flying erratically?

Because they didn't have the power to turn on the Kalman Filter!

State Estimation

- Predict current state given past state and current control input

$$\tilde{w}_n = f(w_{n-1}) + g(u_n)$$

- Given current context, x_n compare your prediction to noisy measurement y_n

$$\ell_n(\tilde{w}_n) = (y_n - h(x_n, \tilde{w}_n))^2$$

- Update current state to include measurement

$$w_n = \tilde{w}_n - K_n \nabla_w \ell_n(w) \Big|_{w=\tilde{w}_n}$$

Kalman filter does optimal least squares state estimation if f, g, h are linear!

Recursive Least Squares (RLS)

Least squares = special case of Kalman Filter: no dynamics, no control

$$\begin{aligned}\tilde{w}_n &= f(w_{n-1}) + g(u_n) \\ &= w_{n-1}\end{aligned}$$

$$\begin{aligned}\ell_n(\tilde{w}_n) &= (y_n - h(x_n, \tilde{w}_n))^2 & h(x, s) &:= x^T s \\ &= (y_n - x_n^T \tilde{w}_n)^2 \\ &= (y_n - x_n^T w_{n-1})^2\end{aligned}$$

$$\begin{aligned}w_n &= \tilde{w}_n - K_n \nabla_w \ell_n(w) \Big|_{w=\tilde{w}_n} \\ &= w_{n-1} + 2(y_n - x_n^T w_{n-1}) K_n x_n\end{aligned}$$

Recursive Least Squares (RLS)

Least squares = special case of Kalman Filter: no dynamics, no control

$$\begin{aligned}\tilde{w}_n &= f(w_{n-1}) + g(u_n) \\ &= w_{n-1}\end{aligned}$$

$$\begin{aligned}\ell_n(\tilde{w}_n) &= (y_n - h(x_n, \tilde{w}_n))^2 \\ &= (y_n - x_n^T \tilde{w}_n)^2 \\ &= (y_n - x_n^T w_{n-1})^2\end{aligned}$$

Ideally:

$$w_n = \arg \min_w \sum_{i=1}^n (y_i - x_i^T w)^2$$

$$\begin{aligned}w_n &= \tilde{w}_n - K_n \nabla_w \ell_n(w) \Big|_{w=\tilde{w}_n} \\ &= w_{n-1} + 2(y_n - x_n^T w_{n-1}) K_n x_n\end{aligned}$$

Recursive Least Squares (RLS)

Sherman–Morrison: $(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1}uv^T A^{-1}}{1 + v^T A^{-1}u}$.

$$w_n = \left(\sum_{i=1}^n x_i x_i^T \right)^{-1} \sum_{i=1}^n x_i y_i \quad b_n$$

Ideally:

$$w_n = \arg \min_w \sum_{i=1}^n (y_i - x_i^T w)^2$$

$$= \left(\sum_{i=1}^{n-1} x_i x_i^T + x_n x_n^T \right)^{-1} \left(\sum_{i=1}^{n-1} x_i y_i + x_n y_n \right)$$

$X \in \mathbb{R}^{n \times n}$

$$= \left((XX^T)^{-1} - \frac{(XX^T)^{-1} x_n x_n^T (XX^T)^{-1}}{1 + x_n^T (XX^T)^{-1} x_n} \right) (X^T y + x_n y_n)$$

$$= \left(S_{n-1} - \frac{S_{n-1} x_n x_n^T S_{n-1}}{1 + x_n^T S_{n-1} x_n} \right) (b_{n-1} + x_n y_n)$$

$$= S_n b_n$$

$$S_n = \left(\sum_{i=1}^n x_i x_i^T \right)^{-1} = S_{n-1} - \frac{S_{n-1} x_n x_n^T S_{n-1}}{1 + x_n^T S_{n-1} x_n}$$

$$b_n = \sum_{i=1}^n x_i y_i = b_{n-1} + x_n y_n$$

Recursive Least Squares (RLS)

$$w_n = \left(\sum_{i=1}^n x_i x_i^T \right)^{-1} \sum_{i=1}^n x_i y_i$$

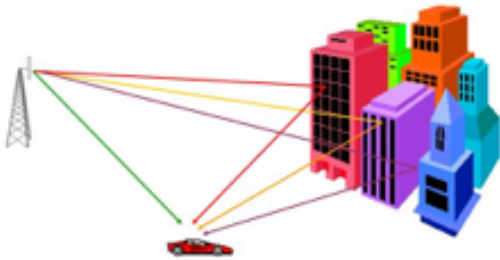
Great, what's the time-complexity of this?

$O(n^3)$ (matrix-vector multiply)

It is 2017. Not the 60's... is limited computation still really a problem?

Digital Signal Processing

The original “Big Data”



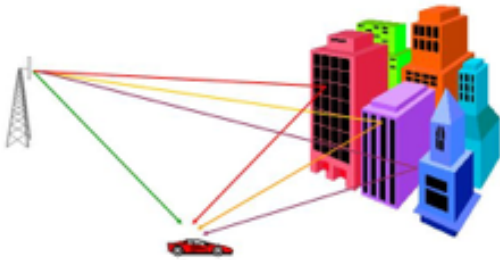
Wifi/cell-phones are *constantly* solving least squares to invert out multipath



Low power devices, high data rates

Digital Signal Processing

The original “Big Data”



Wifi/cell-phones are *constantly* solving least squares to invert out multipath



Low power devices, high data rates



Gigabytes of data per second

YouTube Uploads: > 300 Hours of Video per Minute



Incremental Gradient Descent

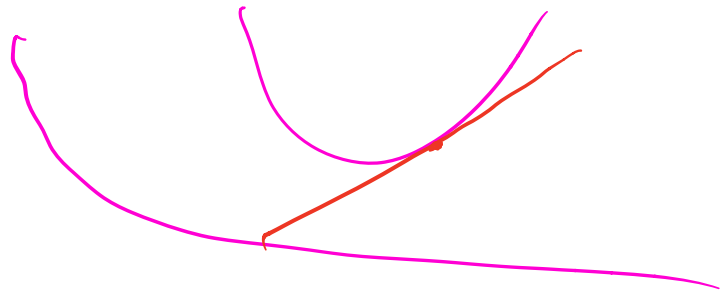
(x_t, y_t) arrive:

Note: no matrix multiply

$$w_{t+1} = w_t - \eta \left[\nabla_w (y_t - x_t^T w)^2 \Big|_{w=w_t} \right]$$

We know RLS is exact. How much worse is this?

In general convex $\ell_t(w)$ arrives:



$$\ell(\cdot) \text{ is convex} \iff \ell(y) \geq \ell(x) + \nabla \ell(x)^T (y - x) \quad \forall x, y$$

$$w_{t+1} = w_t - \eta \nabla \ell(w_t)$$

Incremental Gradient Descent

$$\|w_{t+1} - w_*\|_2^2 = \|w_t - \eta \nabla \ell_t(w_t) - w_*\|_2^2$$

$$= \|w_t - w_*\|_2^2 - 2\eta \nabla \ell_t(w_t)^\top (w_t - w_*) + \eta^2 \|\nabla \ell_t(w_t)\|_2^2$$

$$\ell_t(w_t) - \ell_t(w_*) \leq \nabla \ell_t(w_t)^\top (w_t - w_*) = \frac{\|w_t - w_*\|_2^2 - \|w_{t+1} - w_*\|_2^2 + \eta^2 \|\nabla \ell_t(w_t)\|_2^2}{2\eta}$$

$$\frac{1}{t} \sum_{s=0}^t \ell_s(w_s) - \ell_t(w_*) \leq \frac{\sum_{s=0}^{t-1} (\|w_s - w_*\|_2^2 - \|w_{s+1} - w_*\|_2^2) + \eta^2 \sum_{s=0}^{t-1} \|\nabla \ell_s(w_s)\|_2^2}{2\eta}$$

$$\leq \frac{\|w_0 - w_*\|_2^2 - \|w_t - w_*\|_2^2 + t\eta^2 \max_{1 \leq s \leq t} \|\nabla \ell_s(w_s)\|_2^2}{2\eta t}$$

$$\stackrel{\eta = \frac{1}{\sqrt{t}}}{\leq} \frac{\|w_0 - w_*\|_2^2 + \max_s \|\nabla \ell_s(w_s)\|_2^2}{2\sqrt{t}}$$

Incremental Gradient Descent



Stochastic Gradient Descent

- Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

- Learning a model's parameters:

Each $\ell_i(w)$ is convex.

$$\frac{1}{n} \sum_{i=1}^n \ell_i(w)$$

Stochastic Gradient Descent

- Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

- Learning a model's parameters:

Each $\ell_i(w)$ is convex.

$$\frac{1}{n} \sum_{i=1}^n \ell_i(w)$$

Gradient Descent:

$$w_{t+1} = w_t - \eta \nabla_w \left(\frac{1}{n} \sum_{i=1}^n \ell_i(w) \right) \Big|_{w=w_t} = w_t - \eta \sum_{i=1}^n \nabla_w \ell_i(w)$$

Stochastic Gradient Descent

- Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

- Learning a model's parameters:

Each $\ell_i(w)$ is convex.

$$\frac{1}{n} \sum_{i=1}^n \ell_i(w)$$

Gradient Descent:

$$w_{t+1} = w_t - \eta \nabla_w \left(\frac{1}{n} \sum_{i=1}^n \ell_i(w) \right) \Big|_{w=w_t}$$

Stochastic Gradient Descent:

$$w_{t+1} = w_t - \eta \nabla_w \ell_{I_t}(w) \Big|_{w=w_t}$$

I_t drawn uniform at random from $\{1, \dots, n\}$

$$\mathbb{E}[\nabla \ell_{I_t}(w)] = \frac{1}{n} \sum_{i=1}^n \nabla \ell_i(w)$$

Stochastic Gradient Descent

Gradient Descent:

$$w_{t+1} = w_t - \eta \nabla_w \left(\frac{1}{n} \sum_{i=1}^n \ell_i(w) \right) \Big|_{w=w_t}$$

Stochastic Gradient Descent: $\ell(w)$

$$w_{t+1} = w_t - \eta \nabla_w \ell_{I_t}(w) \Big|_{w=w_t}$$

I_t drawn uniform at random from $\{1, \dots, n\}$

$$\mathbb{E} \left[\frac{1}{T} \sum_{t=1}^T \ell_t(w_t) - \ell(w_*) \right] \leq \mathbb{E} \left[\frac{\|w_0 - w_*\|_2^2 + \max_s \|\nabla \ell_s(w_s)\|_2^2}{2\sqrt{T}} \right]$$

$$\frac{1}{T} \sum_{t=1}^T \mathbb{E}[\ell(w_t)] - \ell(w_*) = \bar{w} = \frac{1}{T} \sum_{t=1}^T w_t$$

$$\ell(\bar{w}_T) - \ell(w_*) \leq \frac{\|w_0 - w_*\|_2^2 + \max_s \mathbb{E} \|\nabla \ell_s(w_s)\|_2^2}{2\sqrt{T}}$$

Stochastic Gradient Ascent for Logistic Regression

- Logistic loss as a stochastic function:

$$E_{\mathbf{x}} [\ell(\mathbf{w}, \mathbf{x})] = E_{\mathbf{x}} [\ln P(y|\mathbf{x}, \mathbf{w}) - \lambda \|\mathbf{w}\|_2^2]$$

- Batch gradient ascent updates:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \frac{1}{N} \sum_{j=1}^N x_i^{(j)} [y^{(j)} - P(Y = 1 | \mathbf{x}^{(j)}, \mathbf{w}^{(t)})] \right\}$$

- Stochastic gradient ascent updates:

- Online setting:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta_t \left\{ -\lambda w_i^{(t)} + x_i^{(t)} [y^{(t)} - P(Y = 1 | \mathbf{x}^{(t)}, \mathbf{w}^{(t)})] \right\}$$