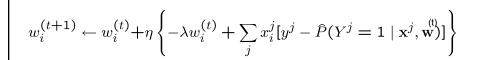


Machine Learning – CSE546 Sham Kakade University of Washington October 20, 2016

©Sham Kakade 2016

Challenge 1: Complexity of Computing Gradients



©Sham Kakade 2016

Challenge 2: Data is streaming

- Assumption thus far: Batch data
- But, e.g., in click prediction for ads is a streaming data task:
 - ☐ User enters query, and ad must be selected:
 - Observe xi, and must predict yi
 - □ User either clicks or doesn't click on ad:
 - Label yi is revealed afterwards
 - □ Google gets a reward if user clicks on ad
 - □ Weights must be updated for next time:

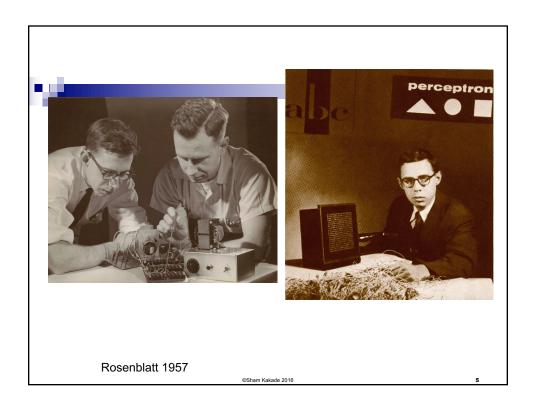
©Sham Kakade 2016

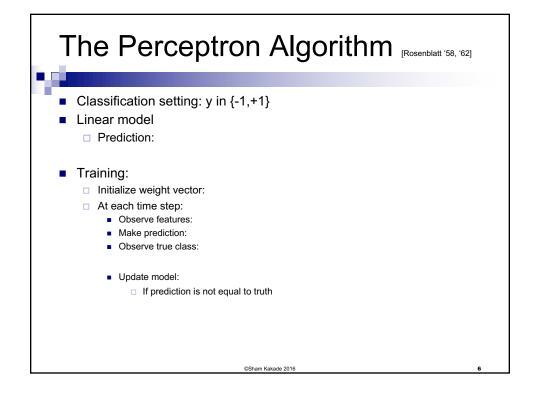
Online Learning Problem



- At each time step t:
 - □ Observe features of data point:
 - Note: many assumptions are possible, e.g., data is iid, data is adversarially chosen... details beyond scope of course
 - Make a prediction:
 - Note: many models are possible, we focus on linear models
 - For simplicity, use vector notation
 - □ Observe true label:
 - Note: other observation models are possible, e.g., we don't observe the label directly, but only a noisy version... Details beyond scope of course
 - □ Update model:

©Sham Kakade 201





Fundamental Practical Problem for All Online Learning Methods: Which weight vector to report?

- - Perceptron prediction:
 - Suppose you run online learning method and want to sell your learned weight vector... Which one do you sell???
 - Last one?

©Sham Kakade 2016

Choice can make a huge difference!! Trandom (unnorm) last (unnorm) avg (unnorm) vote [Freund & Schapire '99]

Mistake Bounds

Algorithm "pays" every time it makes a mistake:

■ How many mistakes is it going to make?

©Sham Kakade 2016

Perceptron Analysis: Linearly Separable Case



- Theorem [Block, Novikoff]:
 - ☐ Given a sequence of labeled examples:
 - □ Each feature vector has bounded norm:
 - □ If dataset is linearly separable:
- Then the number of mistakes made by the online perceptron on any such sequence is bounded by

@Sham Kakada 2016

44

Perceptron Proof for Linearly Separable case



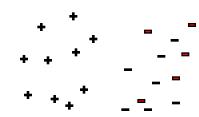
- Every time we make a mistake, we get gamma closer to w*:
 - \square Mistake at time t: $w^{(t+1)} = w^{(t)} + y^{(t)} x^{(t)}$
 - ☐ Taking dot product with w*:
 - □ Thus after m mistakes:
- Similarly, norm of w^(t+1) doesn't grow too fast:
 - $||\mathbf{w}^{(t+1)}||^2 = ||\mathbf{w}^{(t)}||^2 + 2y^{(t)}(\mathbf{w}^{(t)} \cdot \mathbf{x}^{(t)}) + ||\mathbf{x}^{(t)}||^2$
 - □ Thus, after m mistakes:
- Putting all together:

©Sham Kakade 2016

Beyond Linearly Separable Case



- Perceptron algorithm is super cool!
 - □ No assumption about data distribution!
 - Could be generated by an oblivious adversary, no need to be iid
 - Makes a fixed number of mistakes, and it's done for ever!
 - Even if you see infinite data
- However, real world not linearly separable
 - □ Can't expect never to make mistakes again
 - Analysis extends to non-linearly separable case
 - □ Very similar bound, see Freund & Schapire
 - Converges, but ultimately may not give good accuracy (make many many many mistakes)



©Sham Kakade 2016

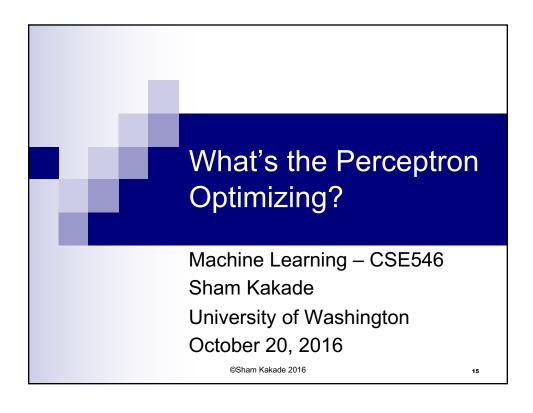
13

What you need to know



- Notion of online learning
- Perceptron algorithm
- Mistake bounds and proof
- In online learning, report averaged weights at the end

©Sham Kakade 2016



What is the Perceptron Doing???

- - When we discussed logistic regression:
 - □ Started from maximizing conditional log-likelihood
 - When we discussed the Perceptron:
 - □ Started from description of an algorithm
 - What is the Perceptron optimizing????

©Sham Kakade 2016

Perceptron Prediction: Margin of Confidence

Hinge Loss

- - Perceptron prediction:
 - Makes a mistake when:
 - Hinge loss (same as maximizing the margin used by SVMs)

©Sham Kakade 2016

Minimizing hinge loss in Batch Setting



- Given a dataset:
- Minimize average hinge loss:
- How do we compute the gradient?

©Sham Kakade 2016

19

Subgradients of Convex Functions



- Gradients lower bound convex functions:
- Gradients are unique at w iff function differentiable at w
- Subgradients: Generalize gradients to non-differentiable points:
 - ☐ Any plane that lower bounds function:

©Sham Kakade 2016

Subgradient of Hinge Hinge loss: Subgradient of hinge loss: If y(t) (w.x(t)) > 0: If y(t) (w.x(t)) < 0: If y(t) (w.x(t)) = 0: If one line:



Perceptron Revisited



Perceptron update:

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} + \mathbb{1} \left[y^{(t)} (\mathbf{w}^{(t)} \cdot \mathbf{x}^{(t)}) \le 0 \right] y^{(t)} \mathbf{x}^{(t)}$$

■ Batch hinge minimization update:

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} + \eta \frac{1}{N} \sum_{i=1}^{N} \left\{ \mathbb{1} \left[y^{(i)} (\mathbf{w}^{(t)} \cdot \mathbf{x}^{(i)}) \le 0 \right] y^{(i)} \mathbf{x}^{(i)} \right\}$$

■ Difference?

©Sham Kakade 2016

23

What you need to know



- Perceptron is optimizing hinge loss
- Subgradients and hinge loss
- (Sub)gradient decent for hinge objective

©Sham Kakade 2016