

| (Squared) Bias of learner |
|---|
| |
| Given dataset <i>D</i> with <i>N</i> samples, learn function $h_D(x)$ |
| If you sample a different dataset D' with N samples, you will learn different h_D'(x) Expected hypothesis: E_D[h_D(x)] |
| ■ Expected hypothesis: E _D [h _D (x)] X |
| ■ Bias: difference between what you expect to learn and truth |
| ☐ Measures how well you expect to represent true solution |
| □ Decreases with more complex model □ Bias² at one point x: □ Average Bias²: |
| □ Average Bias²: |

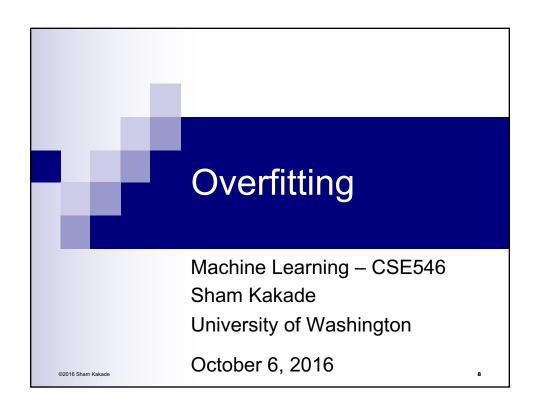
| Variance of learner |
|--|
| |
| ■ Given dataset <i>D</i> with <i>N</i> samples, learn function h _D (x) |
| If you sample a different dataset D' with N samples, you will learn different h_D'(x) |
| Variance: difference between what you expect to learn and what you learn from a particular dataset |
| ☐ Measures how sensitive learner is to specific dataset |
| □ Decreases with simpler model □ Variance at one point x: □ Chp(x) - 5n(x) → |
| Average variance: $E \times E_D \left(\left(h_v(x) - \overline{h_v(x)} \right)^3 \right)$. |
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Training set error
$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_{j} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$



- Given a dataset (Training data)
- Choose a loss function
 - □ e.g., squared error (L₂) for regression
- Training set error: For a particular set of parameters, loss function on training data:

$$error_{train}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$



Prediction error





- Training set error can be poor measure of "quality" of solution
- Prediction error: We really care about error over all possible input points, not just training data:

$$error_{true}(\mathbf{w}) = E_{\mathbf{x}} \left[\left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} \right]$$
$$= \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} p(\mathbf{x}) d\mathbf{x}$$

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Prediction error as a function of model complexity

$$error_{train}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

$$error_{true}(\mathbf{w}) = \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_i h_i(\mathbf{x}) \right)^2 p(\mathbf{x}) d\mathbf{x}$$

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Computing prediction error



- Computing prediction
 - □ Hard integral
 - □ May not know t(x) for every x

$$error_{true}(\mathbf{w}) = \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} p(\mathbf{x}) d\mathbf{x}$$

- Monte Carlo integration (sampling approximation)
 - □ Sample a set of i.i.d. points $\{x_1,...,x_M\}$ from p(x)
 - $\hfill \square$ Approximate integral with sample average

$$error_{true}(\mathbf{w}) \approx \frac{1}{M} \sum_{j=1}^{M} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

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Why training set error doesn't approximate prediction error?

Sampling approximation of prediction error:

$$error_{true}(\mathbf{w}) \approx \frac{1}{M} \sum_{i=1}^{M} \left(t(\mathbf{x}_i) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

■ Training error :

$$error_{train}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

- Very similar equations!!!
 - ☐ Why is training set a bad measure of prediction error???

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Why training set error doesn't approximate prediction error?

Because you cheated!!!

Training error good estimate for a single **w**,
But you optimized **w** with respect to the training error,
and found **w** that is good for this set of samples

Training error is a (optimistically) biased estimate of prediction error

- Very similar equations!!!
 - □ Why is training set a bad measure of prediction error???

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Test set error

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_{j} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$



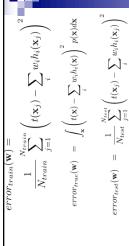
- Given a dataset, randomly split it into two parts:
 - □ Training data $\{x_1,..., x_{Ntrain}\}$
 - □ Test data {**x**₁,..., **x**_{Ntest}}
- Use training data to optimize parameters w
- Test set error: For the *final output* �, evaluate the error using:

$$error_{test}(\mathbf{w}) = \frac{1}{N_{test}} \sum_{j=1}^{N_{test}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

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Test set error as a function of model complexity







Catulate Vew Patronial Reset

Overfitting



■ Overfitting: a learning algorithm overfits the training data if it outputs a solution w when there exists another solution w' such that:

$$[error_{train}(\mathbf{w}) < error_{train}(\mathbf{w}')] \land [error_{true}(\mathbf{w}') < error_{true}(\mathbf{w})]$$

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How many points to I use for training/testing?

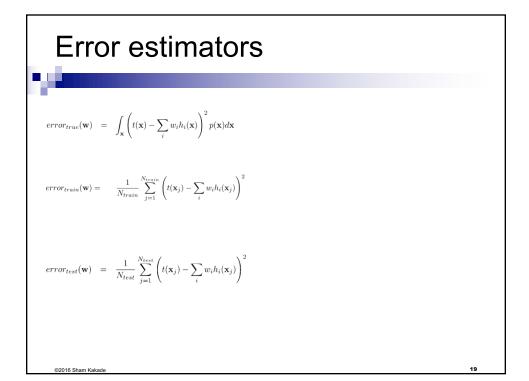


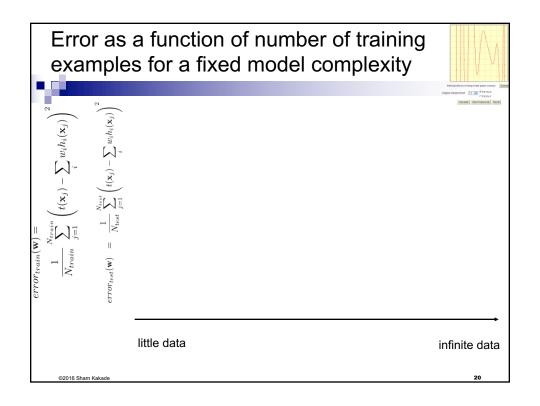
- Very hard question to answer!
 - □ Too few training points, learned w is bad
 - ☐ Too few test points, you never know if you reached a good solution
- Bounds, such as Hoeffding's inequality can help:

$$P(|\hat{\theta} - \theta^*| \ge \epsilon) \le 2e^{-2N\epsilon^2}$$

- More on this later this quarter, but still hard to answer
- Typically:
 - If you have a reasonable amount of data, pick test set "large enough" for a "reasonable" estimate of error, and use the rest for learning
 - ☐ If you have little data, then you need to pull out the big guns...
 - e.g., bootstrapping

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Error estimators



Be careful!!!

Test set only unbiased if you never never ever ever do any any any learning on the test data

For example, if you use the test set to select the degree of the polynomial... no longer unbiased!!! (We will address this problem later)

$$error_{test}(\mathbf{w}) = \frac{1}{N_{test}} \sum_{j=1}^{N_{test}} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

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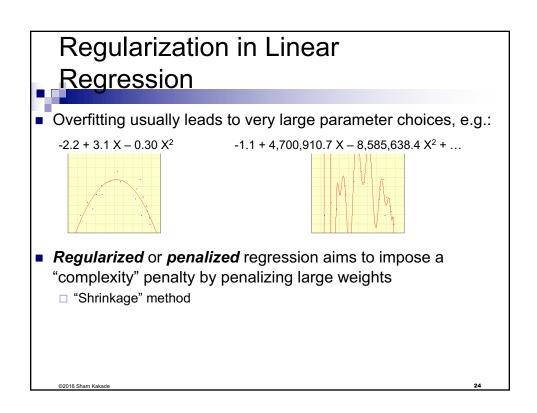
What you need to know



- True error, training error, test error
 - □ Never learn on the test data
 - Never learn on the test data
 - □ Never learn on the test data
 - □ Never learn on the test data
 - □ Never learn on the test data
- Overfitting

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Ridge Regression



- Aleviating issues with overfitting:
- New objective:

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Ridge Regression in Matrix Notation



$$\hat{\mathbf{w}}_{ridge} = \arg\min_{w} \sum_{j=1}^{N} \left(t(x_j) - (w_0 + \sum_{i=1}^{k} w_i h_i(x_j)) \right)^2 + \lambda \sum_{i=1}^{k} w_i^2$$

$$= \underset{\mathbf{w}}{\operatorname{arg} \min} \underbrace{(\mathbf{H}\mathbf{w} - \mathbf{t})^{T} (\mathbf{H}\mathbf{w} - \mathbf{t})}_{\text{residual error}} + \lambda \mathbf{w}^{T} I_{0+k} \mathbf{w}$$

$$\mathbf{H} = \underbrace{\left\{ \begin{array}{c} h_0 \dots h_k \\ \text{data points} \end{array} \right\}}_{\text{K+1 basis functions}} \underbrace{\left\{ \begin{array}{c} \mathbf{W} \\ \text{data points} \end{array} \right\}}_{\text{weights}} \underbrace{\left\{ \begin{array}{c} \mathbf{K} \\ \text{t} \\ \text{t} \\ \text{observations} \end{array} \right\}}_{\text{observations}} \underbrace{\left\{ \begin{array}{c} \mathbf{K} \\ \text{t} \\ \text{t} \\ \text{observations} \end{array} \right\}}_{\text{observations}} \underbrace{\left\{ \begin{array}{c} \mathbf{K} \\ \text{t} \\ \text{t} \\ \text{t} \\ \text{observations} \end{array} \right\}}_{\text{observations}} \underbrace{\left\{ \begin{array}{c} \mathbf{K} \\ \text{t} \\ \text$$

Minimizing the Ridge Regression Objective



$$\hat{\mathbf{w}}_{ridge} = \arg\min_{w} \sum_{j=1}^{N} \left(t(x_j) - (w_0 + \sum_{i=1}^{k} w_i h_i(x_j)) \right)^2 + \lambda \sum_{i=1}^{k} w_i^2$$
$$= (H\mathbf{w} - \mathbf{t})^T (H\mathbf{w} - \mathbf{t}) + \lambda \mathbf{w}^T I_{0+k} \mathbf{w}$$

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Shrinkage Properties



$$\hat{\mathbf{w}}_{ridge} = (H^T H + \lambda \ I_{0+k})^{-1} H^T \mathbf{t}$$

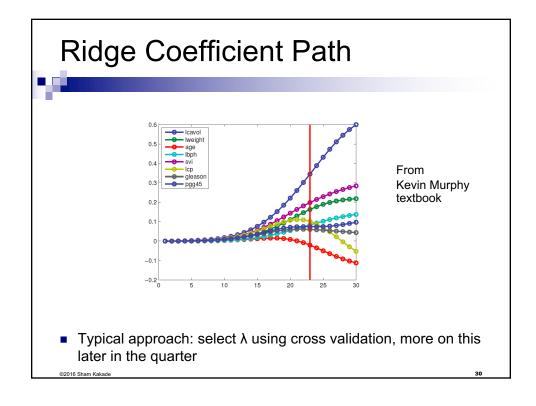
lacksquare If orthonormal features/basis: $H^T H = I$

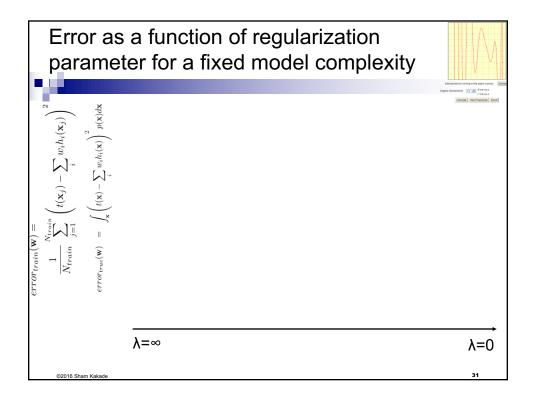
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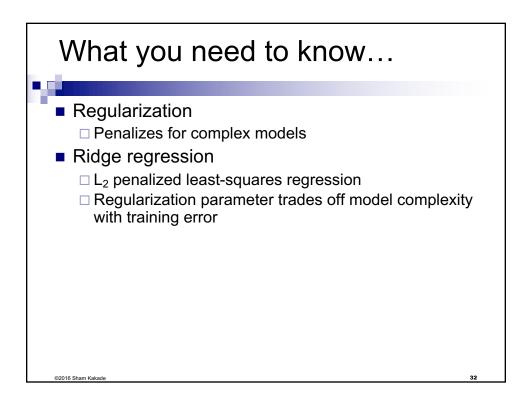
Ridge Regression: Effect of Regularization

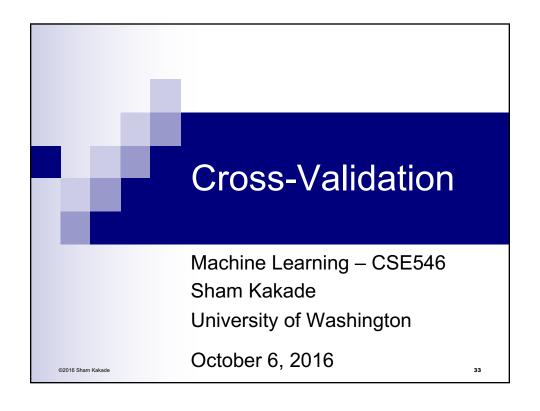
- $\hat{\mathbf{w}}_{ridge} = \arg\min_{w} \sum_{j=1}^{N} \left(t(x_j) (w_0 + \sum_{i=1}^{k} w_i h_i(x_j)) \right)^2 + \lambda \sum_{i=1}^{k} w_i^2$
 - Solution is indexed by the regularization parameter λ
 - Larger λ
 - Smaller λ
 - As $\lambda \rightarrow 0$
 - As λ →∞

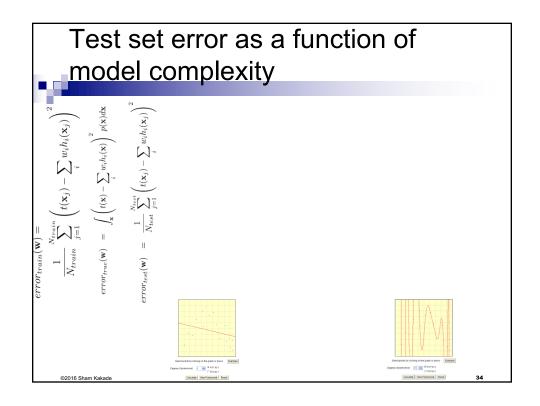
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How... How... How???????



- How do we pick the regularization constant λ...
 - ☐ And all other constants in ML, 'cause one thing ML doesn't lack is constants to tune... 🕾
- We could use the test data, but...

(LOO) Leave-one-out cross validation



- Consider a validation set with 1 example:
 - □ D training data
 - \Box D\j training data with j th data point moved to validation set
- Learn classifier h_{D\i} with D\i dataset
- Estimate true error as squared error on predicting t(x_i):
 - □ Unbiased estimate of error_{true}(*h_{D\i}*)!
 - □ Seems really bad estimator, but wait!
- LOO cross validation: Average over all data points *j*:
 - \Box For each data point you leave out, learn a new classifier h_{Dij}

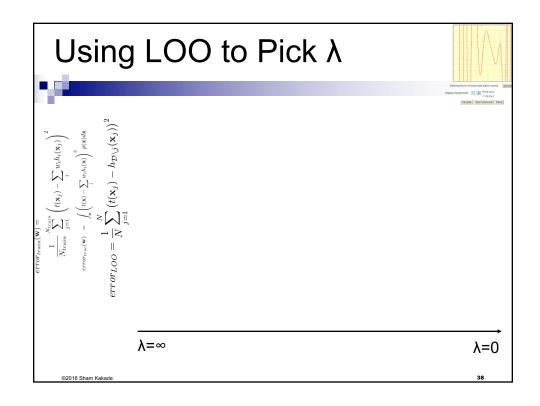
Estimate error as:
$$error_{LOO} = rac{1}{N} \sum_{j=1}^{N} ig(t(\mathbf{x}_j) - h_{\mathcal{D}\setminus j}(\mathbf{x}_j)ig)^2$$

LOO cross validation is (almost) unbiased estimate of true error of h_D !

- When computing LOOCV error, we only use N-1 data points
 - $\ \square$ So it's not estimate of true error of learning with N data points!
 - □ Usually pessimistic, though learning with less data typically gives worse answer
- LOO is almost unbiased!

- Great news!
 - □ Use LOO error for model selection!!!
 - \square E.g., picking λ

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Using LOO error for model selection

$$\frac{1}{2^{N_{\text{leam}}}} \sum_{j=1}^{N_{\text{leam}}} (x_{j})^{j} \times \sum_{j$$

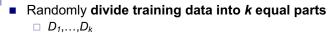
Computational cost of LOO

- Suppose you have 100,000 data points
- You implemented a great version of your learning algorithm
 - □ Learns in only 1 second
- Computing LOO will take about 1 day!!!
 - ☐ If you have to do for each choice of basis functions, it will take foooooreeeve'!!!
- Solution 1: Preferred, but not usually possible
 - ☐ Find a cool trick to compute LOO (e.g., see homework)

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Solution 2 to complexity of computing LOO:

(More typical) Use k-fold cross validation



- For each i
 - □ Learn classifier $h_{D\setminus Di}$ using data point not in D_i
 - □ Estimate error of $h_{D \setminus Di}$ on validation set D_i :

$$error_{\mathcal{D}_i} = \frac{1}{N} \sum_{\mathbf{x}_j \in \mathcal{D}_i} (t(\mathbf{x}_j) - h_{\mathcal{D} \setminus \mathcal{D}_i}(\mathbf{x}_j))^2$$

• k-fold cross validation error is average over data splits:

$$error_{k-fold} = \frac{1}{k} \sum_{i=1}^{k} error_{\mathcal{D}_i}$$

- k-fold cross validation properties:
 - Much faster to compute than LOO
 - □ More (pessimistically) biased using much less data, only m(k-1)/k
 - ☐ Usually, **k = 10** ③

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What you need to know...



- Use cross-validation to choose magic parameters such as λ
- Leave-one-out is the best you can do, but sometimes too slow
 - ☐ In that case, use k-fold cross-validation

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