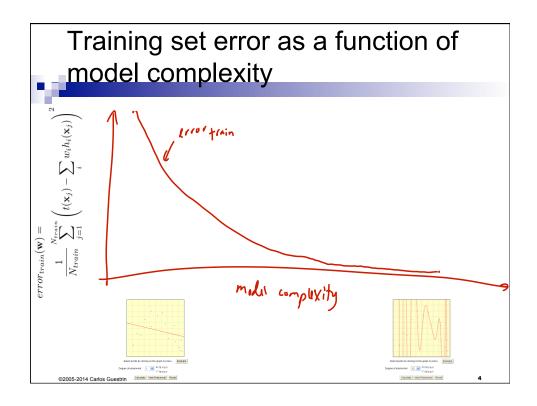


Training set error
$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_{j} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$



- Given a dataset (Training data)
- Choose a loss function
 - □ e.g., squared error (L₂) for regression
- Training set error: For a particular set of parameters, loss function on training data:

$$\underbrace{error_{train}}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$



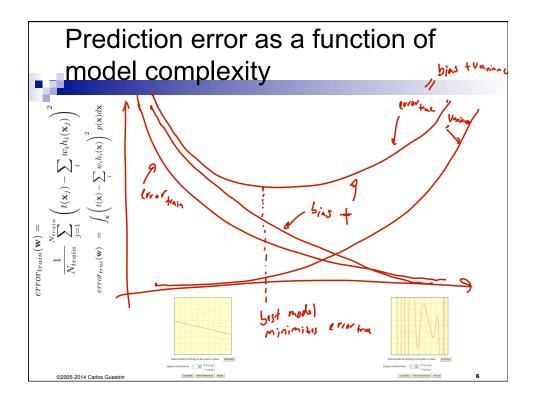
Prediction error



- - Training set error can be poor measure of "quality" of solution
 - **Prediction error:** We really care about error over all possible input points, not just training data:

$$error_{true}(\mathbf{w}) = E_{\mathbf{x}} \left[\left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} \right]$$
$$= \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} p(\mathbf{x}) d\mathbf{x}$$

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Computing prediction error



- Computing prediction
 - □ Hard integral
 - ☐ May not know t(x) for every x

$$error_{true}(\mathbf{w}) = \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} p(\mathbf{x}) d\mathbf{x}$$

- Monte Carlo integration (sampling approximation)



Why training set error doesn't approximate prediction error?



Sampling approximation of prediction error:

$$error_{true}(\mathbf{w}) \approx \frac{1}{M} \sum_{i=1}^{M} \left(t(\mathbf{x}_i) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

■ Training error :
$$error_{train}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

- Very similar equations!!!
 - □ Why is training set a bad measure of prediction error???

Why training set error doesn't approximate prediction error?

Because you cheated!!!

Training error good estimate for a single **w**,
But you optimized **w** with respect to the training error,
and found **w** that is good for this set of samples

Training error is a (optimistically) biased estimate of prediction error

- Very similar equations!!!
 - □ Why is training set a bad measure of prediction error???

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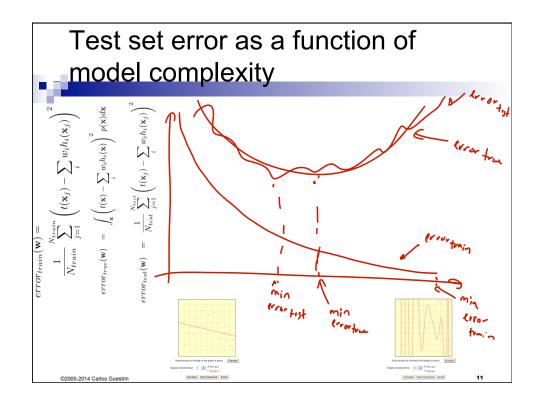
Test set error

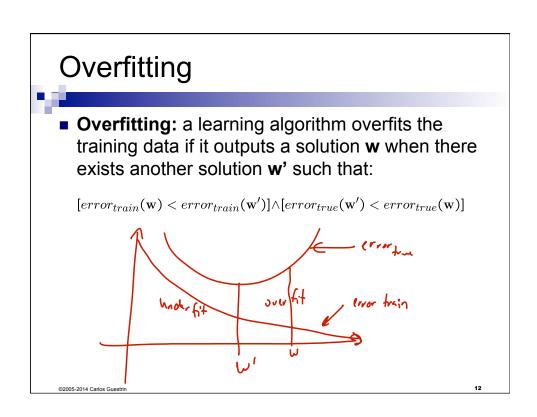
$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_{j} \left(t(\mathbf{x}_j) - \sum_{i} w_i h_i(\mathbf{x}_j) \right)^2$$

- Given a dataset, randomly split it into two parts:
 - \Box Training data $\{\mathbf{x}_1, ..., \mathbf{x}_{Ntrain}\}$
 - □ Test data {x₁,..., x_{Ntest}}
- Use training data to optimize parameters w
- **Test set error:** For the *final output* **ŵ**, evaluate the error using:

$$error_{test}(\mathbf{\hat{w}}) = \frac{1}{N_{test}} \sum_{j=1}^{N_{test}} \left(t(\mathbf{x}_j) - \sum_{i} \mathbf{\hat{w}}_i h_i(\mathbf{x}_j) \right)^2$$

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How many points to I use for training/testing?



- Very hard question to answer!
 - □ Too few training points, learned w is bad
 - ☐ Too few test points, you never know if you reached a good solution
- Bounds, such as Hoeffding's inequality can help:

$$P(|\hat{\theta} - \theta^*| \ge \epsilon) \le 2e^{-2N\epsilon^2}$$

- More on this later this quarter, but still hard to answer
- Typically:
 - ☐ If you have a reasonable amount of data, pick test set "large enough" for a "reasonable" estimate of error, and use the rest for learning
 - ☐ If you have little data, then you need to pull out the big guns...
 - e.g., bootstrapping

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Error estimators

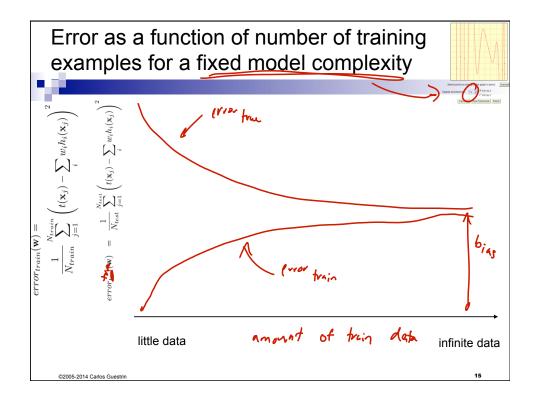


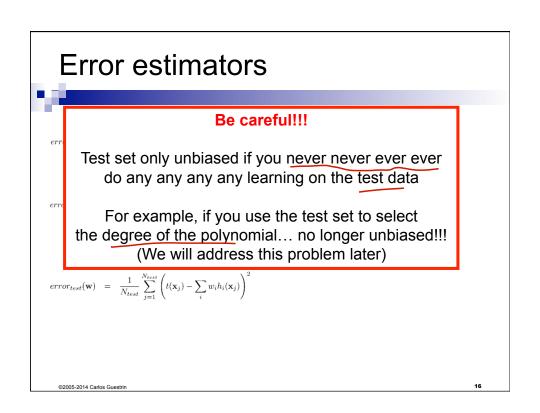
$$error_{true}(\mathbf{w}) = \int_{\mathbf{x}} \left(t(\mathbf{x}) - \sum_{i} w_{i} h_{i}(\mathbf{x}) \right)^{2} p(\mathbf{x}) d\mathbf{x}$$

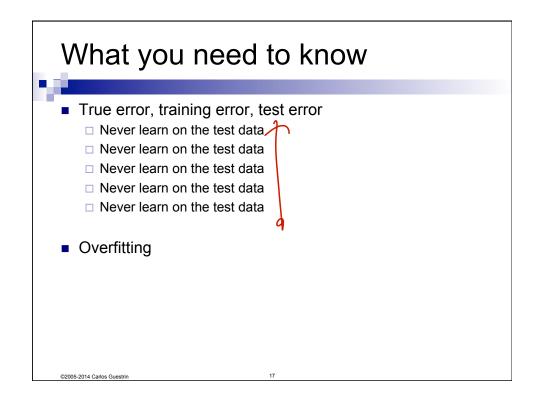
$$error_{train}(\mathbf{w}) = \frac{1}{N_{train}} \sum_{j=1}^{N_{train}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$
 optimistically blassed

$$error_{test}(\mathbf{w}) = \frac{1}{N_{test}} \sum_{j=1}^{N_{test}} \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$
 Framata fram model

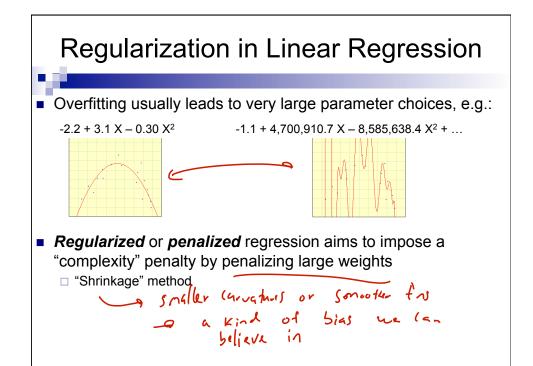
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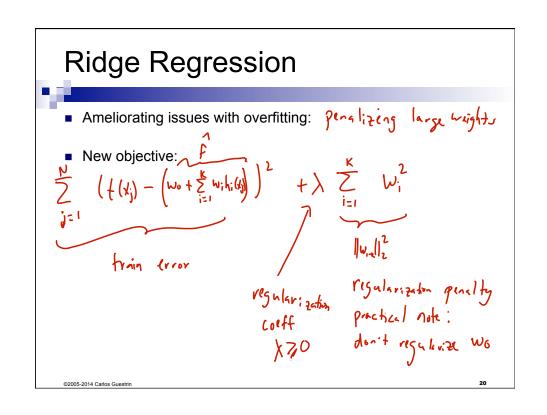










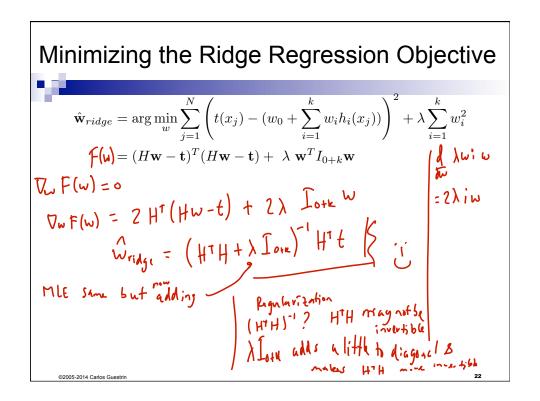


Ridge Regression in Matrix Notation
$$\hat{\mathbf{w}}_{ridge} = \arg\min_{\mathbf{w}} \sum_{j=1}^{N} \left(t(x_j) - (w_0 + \sum_{i=1}^{k} w_i h_i(x_j)) \right)^2 + \lambda \sum_{i=1}^{k} w_i^2$$

$$= \arg\min_{\mathbf{w}} \underbrace{\left(\mathbf{H} \mathbf{w} - \mathbf{t} \right)^T (\mathbf{H} \mathbf{w} - \mathbf{t})}_{\text{residual error}} + \lambda \mathbf{w}^T I_{0+k} \mathbf{w}$$

$$= \arg\min_{\mathbf{w}} \underbrace{\left(\mathbf{H} \mathbf{w} - \mathbf{t} \right)^T (\mathbf{H} \mathbf{w} - \mathbf{t})}_{\text{residual error}} + \lambda \mathbf{w}^T I_{0+k} \mathbf{w}$$

$$= \lim_{h_0 \dots h_k} \underbrace{\mathbf{v}_0 \dots h_k}_{\text{residual error}} \underbrace{\mathbf{v}_0 \dots h_k}_{\text{vols-50 HC earlies Guestin}} \underbrace{\mathbf{v}_0 \dots h_k}_{\text{weights}} \underbrace{\mathbf{v}_0 \dots h_k}_{\text{observations}}$$



Shrinkage Properties
$$\hat{\mathbf{w}}_{nige} = (H^T H + \lambda I_{0+k})^{-1} H^T \mathbf{t}$$

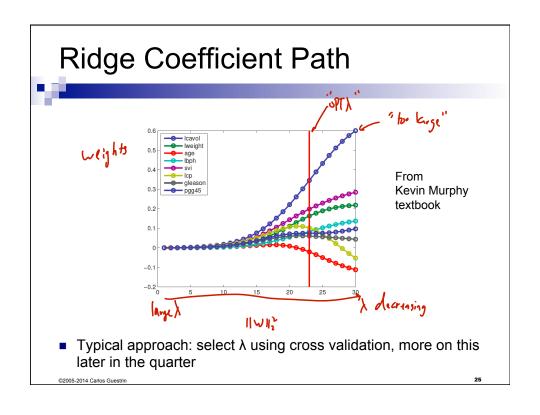
lacksquare If orthonormal features/basis: $H^T H = I$

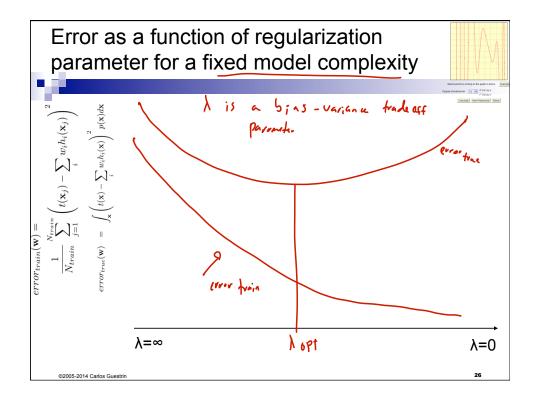
$$\hat{w}_{r;\lambda} g_{\epsilon} = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ = \left(\begin{array}{c} 1 + \lambda \hat{1}_{0+\kappa} \right)^{-1} H^{\tau t} \\ =$$

Ridge Regression: Effect of Regularization

$$\hat{\mathbf{w}}_{ridge} = \arg\min_{w} \sum_{j=1}^{N} \left(t(x_j) - (w_0 + \sum_{i=1}^{k} w_i h_i(x_j)) \right)^2 + \lambda \sum_{i=1}^{k} w_i^2$$

- Solution is indexed by the regularization parameter λ
- higher regularization Larger λ
- Smaller A lower rijularization



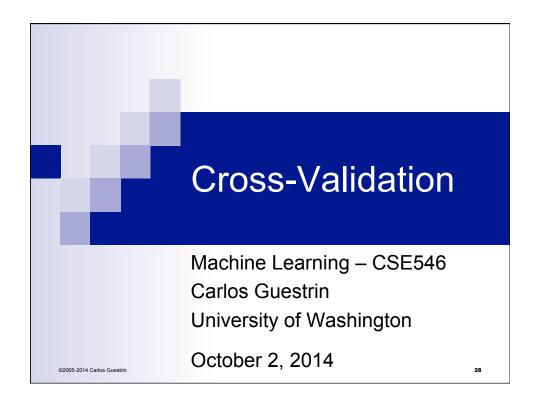


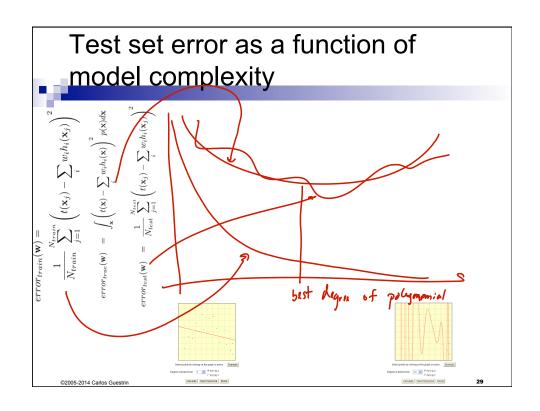
What you need to know...



- Regularization
 - □ Penalizes for complex models
- Ridge regression
 - □ L₂ penalized least-squares regression
 - □ Regularization parameter trades off model complexity with training error

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How... How???????

- - How do we pick the regularization constant λ...
 - □ And all other constants in ML, 'cause one thing ML doesn't lack is constants to tune… ⊗
 - We could use the test data, but...
 - I don't learn on test date
 - 2. don't lan on test date
 - 3. may not be enough date for a good train first Split

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Consider a validation set with 1 example: D - training data with jth data point moved to validation set

- □ $D\setminus j$ training data with j th data point moved to validation set

 Learn classifier $h_{D\setminus j}$ with $D\setminus j$ dataset $(-1)^{N-1}$ data $(-1)^{N-1}$ data $(-1)^{N-1}$ dataset $(-1)^{N-1}$
- Estimate true error as squared error on predicting t(x_j):

Unbiased estimate of error
$$h_{D/j}(x_j)^2$$
 = $(rror frac (h_{D/j}))$

- □ Seems really bad estimator, but wait!
- LOO cross validation: Average over all data points j:
 □ For each data point you leave out, learn a new classifier h_{DN}
 - Estimate error as: $error_{LOO} = \frac{1}{N} \sum_{j=1}^{N} \left(t(\mathbf{x}_j) h_{\mathcal{D} \backslash j}(\mathbf{x}_j) \right)^2$

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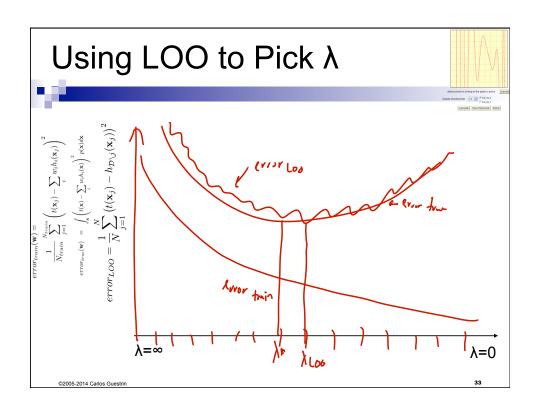
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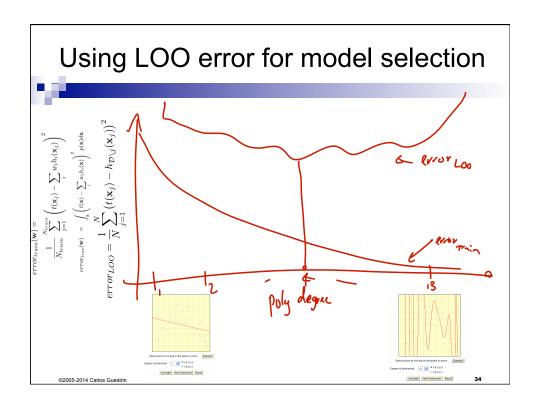
LOO cross validation is (almost) unbiased estimate of true error of h_D !

- When computing LOOCV error, we only use N-1 data points
 - □ So it's not estimate of true error of learning with *N* data points!
 - □ Usually pessimistic, though learning with less data typically gives worse answer
- LOO is almost unbiased!

- Great news!
 - ☐ Use LOO error for model selection!!!
 - E.g., picking λ

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Computational cost of LOO



- Suppose you have 100,000 data points
- You implemented a great version of your learning algorithm
 - □ Learns in only 1 second
- Computing LOO will take about 1 day!!!
 - ☐ If you have to do for each choice of basis functions, it will take fooooooreeeve'!!!
- Solution 1: Preferred, but not usually possible
 - ☐ Find a cool trick to compute LOO (e.g., see homework)

Solution 2 to complexity of computing LOO:

(More typical) Use k-fold cross validation



 Randomly divide training data into k equal parts $\square D_1,...,D_k$



- For each i
 - □ Learn classifier $h_{D \setminus D_i}$ using data point not in D_i

• k-fold cross validation error is average over data splits:

$$error_{k-fold} = \frac{1}{k} \sum_{i=1}^{k} error_{\mathcal{D}_i}$$

- k-fold cross validation properties:
 - Much faster to compute than LOO
 - □ More (pessimistically) biased using much less data, only M(k-1)/k
 - □ Usually, k = 10 ②

What you need to know...



- Use cross-validation to choose magic parameters such as λ
- Leave-one-out is the best you can do, but sometimes too slow
 - ☐ In that case, use k-fold cross-validation

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