

Challenge 1: Complexity of Computing Gradients



$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 \mid \mathbf{x}^j, \mathbf{w}^{(t)})] \right\}$$

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Challenge 2: Data is streaming

- Assumption thus far: Batch data
- But, e.g., in click prediction for ads is a streaming data task:
 - ☐ User enters query, and ad must be selected:
 - Observe **x**^j, and must predict y^j
 - □ User either clicks or doesn't click on ad:
 - Label y^j is revealed afterwards
 - Google gets a reward if user clicks on ad
 - □ Weights must be updated for next time:

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Online Learning Problem



- At each time step t:
 - □ Observe features of data point:
 - Note: many assumptions are possible, e.g., data is iid, data is adversarially chosen... details beyond scope of course
 - Make a prediction:
 - Note: many models are possible, we focus on linear models
 For simplicity, use vector notation
 - □ Observe true label:
 - Note: other observation models are possible, e.g., we don't observe the label directly, but only a noisy version... Details beyond scope of course
 - □ Update model:



The Perceptron Algorithm [Rosenblatt '58, '62]

- Classification setting: y in {-1,+1}
- Linear model
 - □ Prediction:
- Training:
 - □ Initialize weight vector:
 - ☐ At each time step:
 - Observe features:
 - Make prediction:
 - Observe true class:
 - Update model:
 - $\hfill\Box$ If prediction is not equal to truth

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Fundamental Practical Problem for All Online Learning Methods: Which weight vector to report?

- - Perceptron prediction:
 - Suppose you run online learning method and want to sell your learned weight vector... Which one do you sell???
 - Last one?

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Choice can make a huge difference!!

Trandom (unnorm)

last (unnorm)

avg (unnorm)

vote

[Freund & Schapire '99]

Mistake Bounds



Algorithm "pays" every time it makes a mistake:

How many mistakes is it going to make?

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Linear Separability: More formally, Using Margin



- Data linearly separable, if there exists
 - □ a vector
 - □ a margin
- Such that

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Perceptron Analysis: Linearly Separable Case



- Theorem [Block, Novikoff]:
 - ☐ Given a sequence of labeled examples:
 - □ Each feature vector has bounded norm:
 - □ If dataset is linearly separable:
- Then the number of mistakes made by the online perceptron on any such sequence is bounded by

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Perceptron Proof for Linearly Separable case



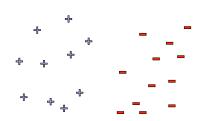
- Every time we make a mistake, we get gamma closer to w*:
 - □ Mistake at time t: $w^{(t+1)} = w^{(t)} + y^{(t)} x^{(t)}$
 - □ Taking dot product with w*:
 - □ Thus after m mistakes:
- Similarly, norm of w^(t+1) doesn't grow too fast:
 - $||\mathbf{w}^{(t+1)}||^2 = ||\mathbf{w}^{(t)}||^2 + 2y^{(t)}(\mathbf{w}^{(t)} \cdot \mathbf{x}^{(t)}) + ||\mathbf{x}^{(t)}||^2$
 - □ Thus, after m mistakes:
- Putting all together:

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Beyond Linearly Separable Case



- Perceptron algorithm is super cool!
 - □ No assumption about data distribution!
 - Could be generated by an oblivious adversary, no need to be iid
 - Makes a fixed number of mistakes, and it's done for ever!
 - Even if you see infinite data
- However, real world not linearly separable
 - □ Can't expect never to make mistakes again
 - Analysis extends to non-linearly separable case
 - □ Very similar bound, see Freund & Schapire
 - Converges, but ultimately may not give good accuracy (make many many many mistakes)



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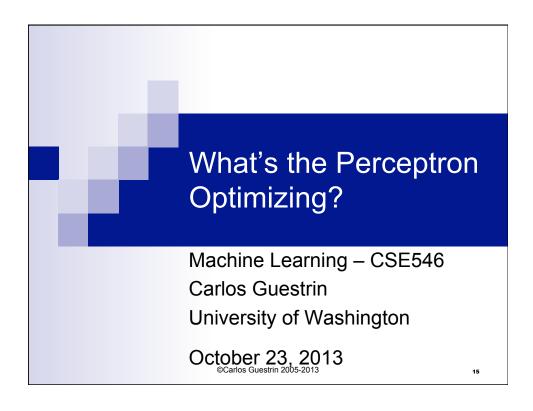
What you need to know



- Notion of online learning
- Perceptron algorithm
- Mistake bounds and proof
- In online learning, report averaged weights at the end

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What is the Perceptron Doing???

- - When we discussed logistic regression:
 - □ Started from maximizing conditional log-likelihood
 - When we discussed the Perceptron:
 - $\hfill\Box$ Started from description of an algorithm
 - What is the Perceptron optimizing????

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Perceptron Prediction: Margin of Confidence

Hinge Loss

- - Perceptron prediction:
 - Makes a mistake when:
 - Hinge loss (same as maximizing the margin used by SVMs)

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Minimizing hinge loss in Batch Setting



- Given a dataset:
- Minimize average hinge loss:
- How do we compute the gradient?

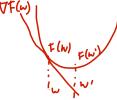
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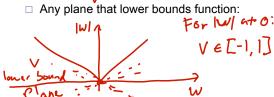
Subgradients of Convex Functions

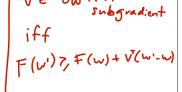


Gradients lower bound convex functions:



- Gradients are unique at **w** iff function differentiable at **w**
- Subgradients: Generalize gradients to non-differentiable points:





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Subgradient of Hinge ■ Hinge loss: ■ Subgradient of hinge loss: □ If y(t) (w.x(t)) > 0: □ If y(t) (w.x(t)) < 0: □ If y(t) (w.x(t)) = 0: □ In one line:

Subgradient Descent for Hinge Minimization Given data: Want to minimize: Subgradient descent works the same as gradient descent: But if there are multiple subgradients at a point, just pick (any) one:

Perceptron Revisited



Perceptron update

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} + \mathbb{1} \left[y^{(t)} (\mathbf{w}^{(t)} \cdot \mathbf{x}^{(t)}) \le 0 \right] y^{(t)} \mathbf{x}^{(t)}$$

■ Batch hinge minimization update:

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} + \eta \frac{1}{N} \sum_{i=1}^{N} \left\{ \mathbb{1} \left[y^{(i)} (\mathbf{w}^{(t)} \cdot \mathbf{x}^{(i)}) \le 0 \right] y^{(i)} \mathbf{x}^{(i)} \right\}$$

■ Difference?

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What you need to know



- Perceptron is optimizing hinge loss
- Subgradients and hinge loss
- (Sub)gradient decent for hinge objective

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