CSE544 Query Execution Thursday, February 2nd, 2011

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Outline

- Relational Algebra: Ch. 4.2
- Overview of query evaluation: Ch. 12
- Evaluating relational operators: Ch. 14
- Shapiro's paper

The WHAT and the HOW

- In SQL we write WHAT we want to get form the data
- The database system needs to figure out HOW to get the data we want
- The passage from WHAT to HOW goes
 through the Relational Algebra

Physical Data Independence

SQL = WHAT

Product(<u>pid</u>, name, price) Purchase(<u>pid</u>, <u>cid</u>, store) Customer(<u>cid</u>, name, city)

SELECT DISTINCT x.name, z.name FROM Product x, Purchase y, Customer z WHERE x.pid = y.pid and y.cid = y.cid and x.price > 100 and z.city = 'Seattle'

It's clear WHAT we want, unclear HOW to get it

Relational Algebra = HOW



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Relational Algebra = HOW

The order is now clearly specified:

Iterate over PRODUCT... ...join with PURCHASE... ...join with CUSTOMER... ...select tuples with Price>100 and City='Seattle'... ...eliminate duplicates... ...and that's the final answer !

Sets v.s. Bags

- Sets: {a,b,c}, {a,d,e,f}, { }, . . .
- Bags: {a, a, b, c}, {b, b, b, b}, . . .

Relational Algebra has two semantics:

- Set semantics
- Bag semantics

Extended Algebra Operators

- Union \cup , intersection \cap , difference -
- Selection o
- Projection Π
- Join 🖂
- Rename p
- Duplicate elimination δ
- Grouping and aggregation $\boldsymbol{\gamma}$
- Sorting τ

Relational Algebra (1/3) The Basic Five operators:

- Union: ∪
- Difference: -
- Selection: σ
- Projection: **Π**
- Join: 🖂

Relational Algebra (2/3)

Derived or auxiliary operators:

- Renaming: p
- Intersection, complement
- Variations of joins

-natural, equi-join, theta join, semi-join, cartesian product

Relational Algebra (3/3)

Extensions for bags:

- Duplicate elimination: δ
- Group by: γ
- Sorting: τ

Union and Difference

What do they mean over bags?

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What about Intersection ?

• Derived operator using minus

$$R1 \cap R2 = R1 - (R1 - R2)$$

• Derived using join (will explain later)

$$R1 \cap R2 = R1 \bowtie R2$$

Selection

 Returns all tuples which satisfy a condition



- Examples
 - $\sigma_{\text{Salary} > 40000}$ (Employee)
 - $\sigma_{\text{name = "Smith"}}$ (Employee)
- The condition c can be =, <, ≤, >, ≥, <>

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Employee

SSN	Name	Salary
1234545	John	200000
5423341	Smith	600000
4352342	Fred	500000

 $\sigma_{\text{Salary} > 40000}$ (Employee)

SSN	Name	Salary
5423341	Smith	600000
4352342	Fred	500000

Projection

Eliminates columns



- Example: project social-security number and names:
 - $\Pi_{SSN, Name}$ (Employee)
 - Answer(SSN, Name)

Semantics differs over set or over bags

Employee	SSN	Name	Salary
	1234545	John	20000
	5423341	John	60000
	4352342	John	20000

 $\Pi_{Name,Salary}$ (Employee)

Name	Salary	Name	Salary
John	20000	John	20000
John	60000	John	60000
John	20000		

Bag semantics

Set semantics

Which is more efficient to implement?¹⁷

Cartesian Product

• Each tuple in R1 with each tuple in R2



 Very rare in practice; mainly used to express joins

Employee

Dependent

Name	SSN
John	999999999
Tony	77777777

EmpSSN	DepName
999999999	Emily
77777777	Joe

Employee × **Dependent**

Name	SSN	EmpSSN	DepName
John	999999999	9999999999	Emily
John	999999999	77777777	Joe
Tony	77777777	999999999	Emily
Tony	777777777	777777777	Joe

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Renaming

• Changes the schema, not the instance



- Example:
 - $\rho_{N, S}$ (Employee) \rightarrow Answer(N, S)

Natural Join

R1 ⋈ R2

- Meaning: $R1 \bowtie R2 = \Pi_A(\sigma(R1 \times R2))$
- Where:
 - The selection σ checks equality of all common attributes
 - The projection eliminates the duplicate common attributes

Natural Join

S

R

Α	В
Х	Y
Х	Z
Y	Z
Z	V

В	С
Z	U
V	W
Z	V

 $\mathbf{R} \bowtie \mathbf{S} =$ $\Pi_{ABC}(\sigma_{R.B=S.B}(\mathbf{R} \times \mathbf{S}))$

Α	В	С
Х	Z	U
Х	Z	V
Y	Z	U
Y	Z	V
Z	V	W

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Natural Join

- Given the schemas R(A, B, C, D), S(A, C, E), what is the schema of R ⋈ S ?
- Given R(A, B, C), S(D, E), what is $R \bowtie S$?
- Given R(A, B), S(A, B), what is $R \bowtie S$?

Theta Join

• A join that involves a predicate

$$R1 \bowtie_{\theta} R2 = \sigma_{\theta} (R1 \times R2)$$

• Here θ can be any condition

Eq-join

• A theta join where θ is an equality

$$R1 \bowtie_{A=B} R2 = \sigma_{A=B} (R1 \times R2)$$

This is by far the most used variant of join in practice

So Which Join Is It?

 When we write R ⋈ S we usually mean an eq-join, but we often omit the equality predicate when it is clear from the context

Semijoin

$$\mathsf{R} \ltimes_{\mathsf{C}} \mathsf{S} = \Pi_{\mathsf{A1},\ldots,\mathsf{An}} (\mathsf{R} \bowtie_{\mathsf{C}} \mathsf{S})$$

• Where A_1, \ldots, A_n are the attributes in R

Formally, $R \ltimes_C S$ means this: retain from R only those tuples that have some matching tuple in S

- Duplicates in R are preserved
- Duplicates in S don't matter



Employee $\bowtie_{SSN=EmpSSN}$ ($\sigma_{age>71}$ (Dependent))

Assumptions: Very few Employees have dependents. Very few dependents have age > 71. "Stuff" is big.

Task: compute the query with minimum amount of data transfer



Employee $\bowtie_{SSN=EmpSSN}$ ($\sigma_{age>71}$ (Dependent))

 $T(SSN) = \Pi_{SSN} \sigma_{age>71}$ (Dependents)





Joins R US

- The join operation in all its variants (eqjoin, natural join, semi-join, outer-join) is at the <u>heart</u> of relational database systems
- WHY ?

Operators on Bags

- Duplicate elimination δ $\delta(R)$ = select distinct * from R
- Grouping γ $\gamma_{A,sum(B)}$ (R) = select A,sum(B) from R group by A
- Sorting τ

Complex RA Expressions



RA = Dataflow Program

- Several operations, plus strictly specified order
- In RDBMS the dataflow graph is always a tree
- Novel applications (s.a. PIG), dataflow graph may be a DAG Dan Suciu -- 544, Winter 2011

Limitations of RA

• Cannot compute "transitive closure"

Name1	Name2	Relationship
Fred	Mary	Father
Mary	Joe	Cousin
Mary	Bill	Spouse
Nancy	Lou	Sister

- Find all direct and indirect relatives of Fred
- Cannot express in RA !!! Need to write Java program
- Remember the Bacon number ? Needs TC too !
Steps of the Query Processor



Example Database Schema

Supplier(sno,sname,scity,sstate) Part(pno,pname,psize,pcolor) Supply(sno,pno,price)

View: Suppliers in Seattle

CREATE VIEW NearbySupp AS SELECT sno, sname FROM Supplier WHERE scity='Seattle' AND sstate='WA'

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Example Query

Find the names of all suppliers in Seattle who supply part number 2

SELECT sname FROM NearbySupp WHERE sno IN (SELECT sno FROM Supplies WHERE pno = 2)

Steps in Query Evaluation

Step 0: Admission control

- User connects to the db with username, password
- User sends query in text format
- Step 1: Query parsing
 - Parses query into an internal format
 - Performs various checks using catalog
 - Correctness, authorization, integrity constraints
- Step 2: Query rewrite
 - View rewriting, flattening, etc.

Rewritten Version of Our Query

Original query:

SELECT sname FROM NearbySupp WHERE sno IN (SELECT sno FROM Supplies WHERE pno = 2)

Rewritten query:

SELECT S.sname FROM Supplier S, Supplies U WHERE S.scity='Seattle' AND S.sstate='WA' AND S.sno = U.sno AND U.pno = 2;

Continue with Query Evaluation

Step 3: Query optimization

- Find an efficient query plan for executing the query

- A query plan is
 - Logical query plan: an extended relational algebra tree
 - Physical query plan: with additional annotations at each node
 - Access method to use for each relation
 - Implementation to use for each relational operator

Extended Algebra Operators

- Union \cup , intersection \cap , difference -
- Selection o
- Projection π
- Join 🖂
- Duplicate elimination δ
- Grouping and aggregation
 γ
- Sorting τ
- Rename p



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Query Block

- Most optimizers operate on individual query blocks
- A query block is an SQL query with **no nesting**
 - Exactly one
 - SELECT clause
 - FROM clause
 - At most one
 - WHERE clause
 - GROUP BY clause
 - HAVING clause



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How about Subqueries?

```
SELECT Q.sno
FROM Supplier Q
WHERE Q.sstate = 'WA'
and not exists
SELECT *
FROM Supply P
WHERE P.sno = Q.sno
and P.price > 100
```

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How about Subqueries?



How about Subqueries?





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How about Subqueries?



How about Subqueries?



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Physical Query Plan

- Logical query plan with extra annotations
- Access path selection for each relation
 Use a file scan or use an index
- Implementation choice for each operator
- Scheduling decisions for operators

Physical Query Plan



Final Step in Query Processing

- Step 4: Query execution
 - How to synchronize operators?
 - How to pass data between operators?
- What techniques are possible?
 - One thread per query
 - Iterator interface
 - Pipelined execution
 - Intermediate result materialization

Iterator Interface

- Each operator implements this interface
- Interface has only three methods
- open()
 - Initializes operator state
 - Sets parameters such as selection condition
- get_next()
 - Operator invokes get_next() recursively on its inputs
 - Performs processing and produces an output tuple
- close(): cleans-up state

Pipelined Execution



Pipelined Execution

- Applies parent operator to tuples directly as they are produced by child operators
- Benefits
 - No operator synchronization issues
 - Saves cost of writing intermediate data to disk
 - Saves cost of reading intermediate data from disk
 - Good resource utilizations on single processor
- This approach is used whenever possible



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Intermediate Tuple Materialization

- Writes the results of an operator to an intermediate table on disk
- No direct benefit but
- Necessary data is larger than main memory
- Necessary when operator needs to examine the same tuples multiple times

Physical Operators

Each of the logical operators may have one or more implementations = physical operators

Will discuss several basic physical operators, with a focus on join

Question in Class

Logical operator: Supply(sno,pno,price) M_{pno=pno} Part(pno,pname,psize,pcolor)

Propose three physical operators for the join, assuming the tables are in main memory:

1.

2.

3.

Question in Class

Logical operator: Supply(sno,pno,price) M_{pno=pno} Part(pno,pname,psize,pcolor)

Propose three physical operators for the join, assuming the tables are in main memory:

- 1. Nested Loop Join
- 2. Merge join
- 3. Hash join

1. Nested Loop Join

```
for S in Supply do {
  for P in Part do {
     if (S.pno == P.pno) output(S,P);
  }
}
```

Supply = outer relation Part = inner relation Note: sometimes terminology is switched

Would it be more efficient to choose Part=inner, Supply=outer ? What if we had an index on Part.pno ?

It's more complicated...

- Each operator implements this interface
- open()
- get_next()
- close()

Supplier(sno, sname, scity, sstate) Part(pno, pname, psize, pcolor) Supply(sno, pno, price) Join Revisited

```
open ( ) {
   Supply.open( );
   Part.open( );
   S = Supply.get_next( );
}
```

```
close ( ) {
Supply.close ( );
Part.close ( );
}
```

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ALL operators need to be implemented this way !

BRIEF Review of Hash Tables Separate chaining:

A (naïve) hash function:

 $h(x) = x \mod 10$

Operations:



BRIEF Review of Hash Tables

- insert(k, v) = inserts a key k with value v
- Many values for one key
 Hence, duplicate k's are OK
- find(k) = returns the <u>list</u> of all values v associated to the key k



3. Merge Join (main memory)

```
Part1 = sort(Part, pno);
Supply1 = sort(Supply,pno);
P=Part1.get next(); S=Supply1.get_next();
While (P!=NULL and S!=NULL) {
  case:
    P.pno > S.pno: P = Part1.get_next();
    P.pno < S.pno: S = Supply1.get next();
    P.pno == S.pno { output(P,S);
                                                 Why ???
                     S = Supply1.get_next();
```

Main Memory Group By

Grouping: Product(name, department, quantity) γ_{department, sum(quantity)} (Product) → Answer(department, sum)

Main memory hash table Question: How ?

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Duplicate Elimination IS Group By

Duplicate elimination $\delta(R)$ is <u>the same</u> as group by $\gamma(R)$ WHY ???

- Hash table in main memory
- Cost: B(R)
- Assumption: $B(\delta(R)) \le M$
Selections, Projections

- Selection = easy, check condition on each tuple at a time
- Projection = easy (assuming no duplicate elimination), remove extraneous attributes from each tuple

Review (1/2)

- Each operator implements this interface
- open()
 - Initializes operator state
 - Sets parameters such as selection condition
- get_next()
 - Operator invokes get_next() recursively on its inputs
 - Performs processing and produces an output tuple
- close()
 - Cleans-up state

Review (2/2)

- Three algorithms for main memory join:
 - Nested loop join
 - Hash join
 - Merge join

If |R| = m and |S| = n, what is the asymptotic complexity for computing $R \bowtie S$?

Algorithms for selection, projection, group-by

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External Memory Algorithms

- Data is too large to fit in main memory
- Issue: disk access is 3-4 orders of magnitude slower than memory access
- Assumption: runtime dominated by # of disk I/O's; will ignore the main memory part of the runtime

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Cost Parameters

The *cost* of an operation = total number of I/Os Cost parameters:

- B(R) = number of blocks for relation R
- T(R) = number of tuples in relation R
- V(R, a) = number of distinct values of attribute a
- M = size of main memory buffer pool, in blocks

Facts: (1) B(R) << T(R): (2) When a is a key, V(R,a) = T(R) When a is not a key, V(R,a) << T(R)

Ad-hoc Convention

- We assume that the operator *reads* the data from disk
- We assume that the operator *does not* write the data back to disk (e.g.: pipelining)
- Thus:

Any main memory join algorithms for $R \bowtie S$: Cost = B(R)+B(S)

Any main memory grouping $\gamma(R)$: Cost = B(R)

Sequential Scan of a Table R

- When R is *clustered*
 - Blocks consists only of records from this table
 - B(R) << T(R)
 - Cost = B(R)

- When R is unclustered
 - Its records are placed on blocks with other tables
 - $B(R) \approx T(R)$
 - Cost = T(R)

Nested Loop Joins

• Tuple-based nested loop $R \bowtie S$

for each tuple r in R do for each tuple s in S do if r and s join then output (r,s)

R=outer relation S=inner relation

- Cost: T(R) B(S) when S is clustered
- Cost: T(R) T(S) when S is unclustered

Examples

M = 4; R, S are clustered

- Example 1:
 - B(R) = 1000, T(R) = 10000

$$- B(S) = 2, T(S) = 20$$

- Cost = ?

Can you do better ?

- Example 2:
 - -B(R) = 1000, T(R) = 10000
 - -B(S) = 4, T(S) = 40
 - Cost = ?

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Block-Based Nested-loop Join

Why not M?

for each (M-2) blocks bs of S do for each block br of R do for each tuple s in bs for each tuple r in br do if "r and s join" then output(r,s)

Terminology alert: book calls S the inner relation

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Block Nested-loop Join



Examples

M = 4; R, S are clustered

- Example 1:
 - B(R) = 1000, T(R) = 10000
 - B(S) = 2, T(S) = 20
 - Cost = B(S) + B(R) = 1002
- Example 2:
 - B(R) = 1000, T(R) = 10000
 - B(S) = 4, T(S) = 40
 - Cost = B(S) + 2B(R) = 2004

Note: T(R) and T(S) are irrelevant here.

Cost of Block Nested-loop Join

- Read S once: cost B(S)
- Outer loop runs B(S)/(M-2) times, and each time need to read R: costs B(S)B (R)/(M-2)

$$Cost = B(S) + B(S)B(R)/(M-2)$$

Index Based Selection

Recall IMDB; assume indexes on Movie.id, Movie.year

SELET *

FROM Movie

WHERE id = '12345'

SELET *

FROM Movie

WHERE year = '1995'

B(Movie) = 10kT(Movie) = 1M

What is your estimate of the I/O cost ?

Index Based Selection

Selection on equality: $\sigma_{a=v}(R)$

- Clustered index on a: cost B(R)/V(R,a)
- Unclustered index : cost T(R)/V(R,a)

Index Based Selection

• Example:

B(R) = 10kT(R) = 1M V(R, a) = 100

cost of
$$\sigma_{a=v}(R) = ?$$

- Table scan (assuming R is clustered):
 - B(R) = 10k I/Os
- Index based selection:
 - If index is clustered: B(R)/V(R,a) = 100 I/Os
 - If index is unclustered: T(R)/V(R,a) = 10000 I/Os

Rule of thumb: don't build unclustered indexes when V(R,a) is small ! 88

Index Based Join

- R 🛛 S
- Assume S has an index on the join attribute

\underline{for} each tuple r in R \underline{do}

lookup the tuple(s) s in S using the index output (r,s)

Index Based Join

Cost (Assuming R is clustered):

- If index is clustered: B(R) + T(R)B(S)/V(S,a)
- If unclustered: B(R) + T(R)T(S)/V(S,a)

Operations on Very Large Tables

- Compute R ⋈ S when each is larger than main memory
- Two methods:
 - Partitioned hash join (many variants)
 - Merge-join
- Similar for grouping Dan Suciu -- 544, Winter 2011

Partitioned Hash-based Algorithms

Idea:

- If B(R) > M, then partition it into smaller files: R1, R2, R3, ..., Rk
- Assuming B(R1)=B(R2)=...= B(Rk), we have B(Ri) = B(R)/k
- Goal: each Ri should fit in main memory: B(Ri) ≤ M How big can k be ?

Partitioned Hash Algorithms

- Idea: partition a relation R into M-1 buckets, on disk
- Each bucket has size approx. B(R)/(M-1) ≈ B(R)/M



Assumption: $B(R)/M \le M$, i.e. $B(R) \le M^2$

Grouping

- $\gamma(R)$ = grouping and aggregation
- Step 1. Partition R into buckets
- Step 2. Apply γ to each bucket (may read in main memory)
- Cost: 3B(R)
- Assumption: $B(R) \le M^2$

Partitioned Hash Join GRACE Join

 $\mathsf{R} \bowtie \mathsf{S}$

- Step 1:
 - Hash S into M buckets
 - send all buckets to disk
- Step 2
 - Hash R into M buckets
 - Send all buckets to disk
- Step 3
 - Join every pair of buckets

Grace-Join

 Partition both relations using hash fn h: R tuples in partition i will only match S tuples in partition i.

 Read in a partition of R, hash it using h2 (<> h!). Scan matching partition of S, search for matches.



Grace Join

- Cost: 3B(R) + 3B(S)
- Assumption: min(B(R), B(S)) <= M²

External Sorting

- Problem:
- Sort a file of size B with memory M
- Where we need this:
 - ORDER BY in SQL queries
 - Several physical operators
 - Bulk loading of B+-tree indexes.
- Will discuss only 2-pass sorting, when $B < M^2$

External Merge-Sort: Step 1

• Phase one: load M bytes in memory, sort



External Merge-Sort: Step 2

- Merge M 1 runs into a new run
- Result: runs of length M (M 1) \approx M²



Cost of External Merge Sort

• Read+write+read = 3B(R)

• Assumption: B(R) <= M²

Grouping

Grouping: γ_{a, sum(b)} (R)

- Idea: do a two step merge sort, but change one of the steps
- Question in class: which step needs to be changed and how ?

```
Cost = 3B(R)
Assumption: B(\delta(R)) \le M^2
```

Merge-Join

Join R ⋈ S

- Step 1a: initial runs for R
- Step 1b: initial runs for S
- Step 2: merge and join

Merge-Join



Two-Pass Algorithms Based on Sorting

 $\mathsf{Join} \ \mathsf{R} \bowtie \mathsf{S}$

- If the number of tuples in R matching those in S is small (or vice versa) we can compute the join during the merge phase
- Total cost: 3B(R)+3B(S)
- Assumption: $B(R) + B(S) \le M^2$

Summary of External Join Algorithms

- Block Nested Loop: B(S) + B(R)*B(S)/M
- Index Join: B(R) + T(R)B(S)/V(S,a)
- Partitioned Hash: 3B(R)+3B(S);
 min(B(R),B(S)) <= M²
- Merge Join: 3B(R)+3B(S)
 B(R)+B(S) <= M² Dan Suciu - 544, Winter 2011