

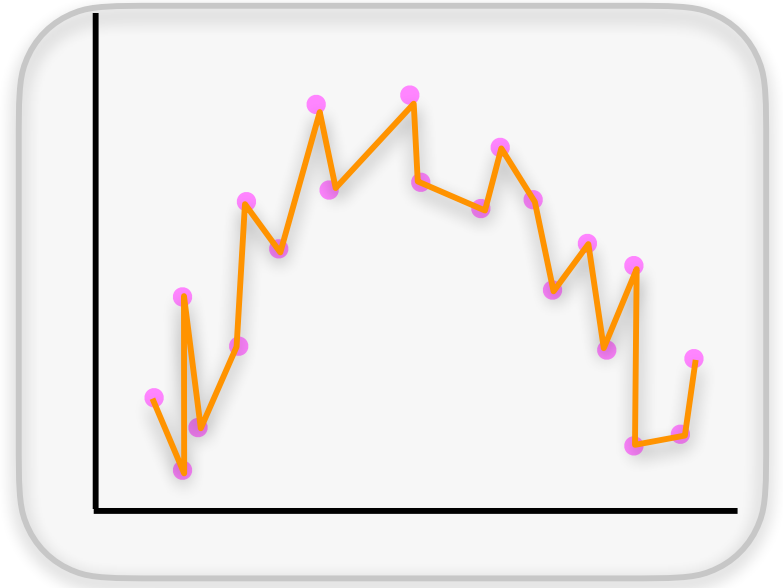
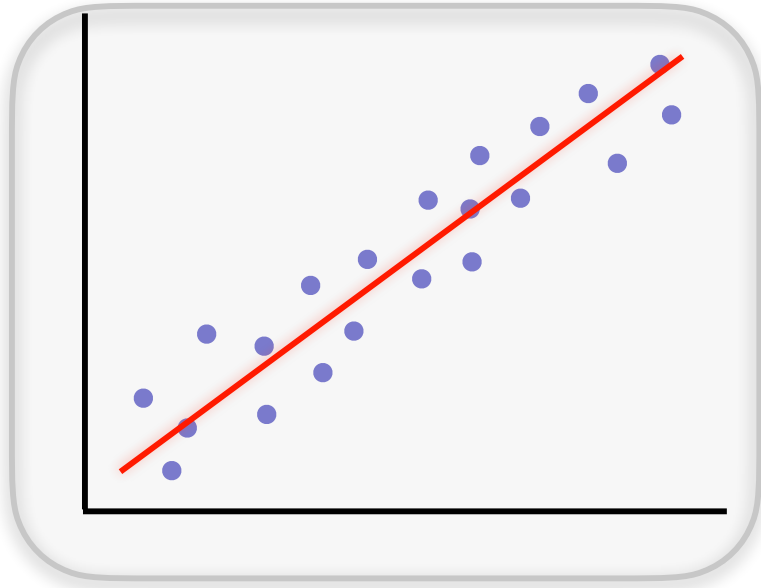
# Approximation Theory

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# Expressivity / Representation Power

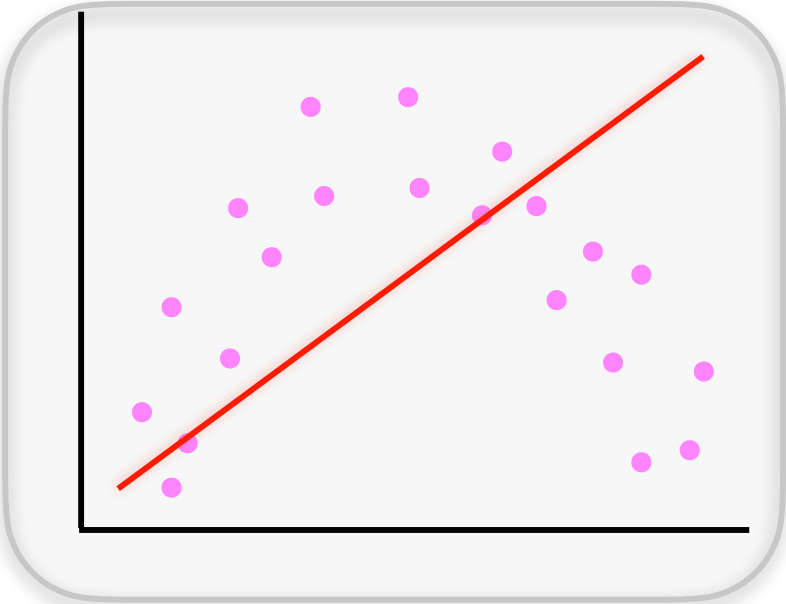
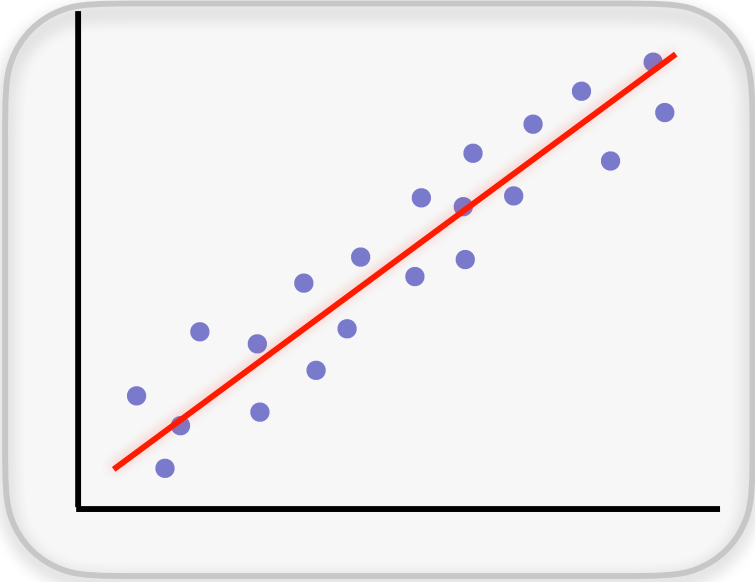
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Expressive: Functions in class can represent “complicated” functions.

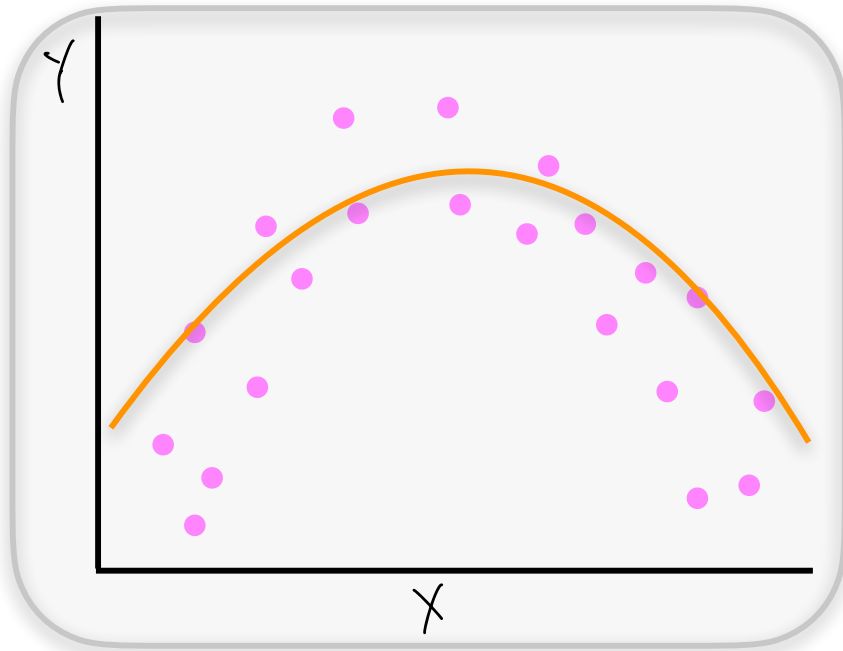
# Linear Function

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best linear fit

# Review: generalized linear regression



Transformed data:

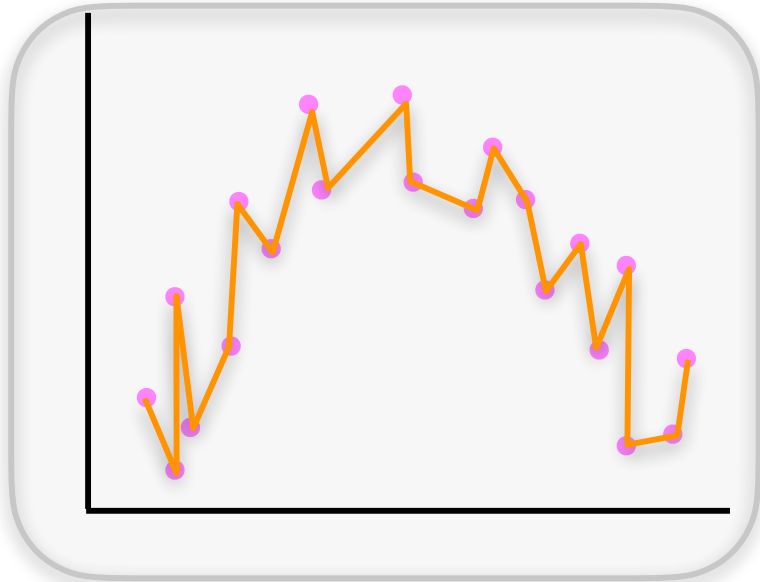
$$\begin{aligned}h_1(x) &= 1 \\h_2(x) &= x \\h_3(x) &= x^2\end{aligned}$$

$$h(x) = \begin{bmatrix} h_1(x) \\ h_2(x) \\ \vdots \\ h_p(x) \end{bmatrix}$$

Hypothesis: linear in  $h$

$$y_i \approx h(x_i)^T w$$

# Review: Polynomial Regression



$$h(x) = \begin{pmatrix} 1 \\ x \\ \vdots \\ x^p \end{pmatrix}$$

$$f(x) = \langle w, h(x) \rangle$$
$$w \in \mathbb{R}^{p+1}$$

Lagrange's Interpolation Theorem:  
Given a data set  $\{(x_i, y_i)\}_{i=1}^n$   
polynomial  $f$  of degree  $(n-1)$  s.t.  
 $\forall i, y_i = f(x_i)$

Assumption:  $\forall (x_i, y_i), (x_j, y_j)$   
if  $x_i = x_j, y_i = y_j$

# Approximation Theory Setup

Sanity check

- Goal: to show there exists a neural network that has small error on training / test set.

- Set up a natural baseline:  $\geq$

$$\inf_{f \in \mathcal{F}} L(f) \text{ v.s.}$$

$$\inf_{g \in \text{continuous functions}} L(g)$$

$$\mathcal{F} \subset \text{continuous function}$$

## Example

$$(1) \quad l(f(x), y) = l(yf(x)), \quad \rho\text{-Lipschitz } z$$

$$|l(z) - l(z')| \leq \rho |z - z'|$$

e.g. hinge loss

$$l(yf(x)) = \max\{0, 1 - yf(x)\}$$

$\rho$ -Lipschitz

$$L(f) = \int l(yf(x)) d\mu(x, y)$$

$\mu(x, y)$  distribution over  $(x, y)$

# Decomposition

$$\begin{aligned} & \mathcal{L}(f) - \mathcal{L}(g) \\ &= \int (\ell(yf(x)) - \ell(yg(x))) d\mu(x, y) \\ &\leq \int |\ell(yf(x)) - \ell(yg(x))| d\mu(x, y) \\ &\leq \int \rho |yf(x) - yg(x)| d\mu(x, y) \\ &\quad (\text{assume } |\ell| \leq \rho) \\ &\leq \rho \int |f(x) - g(x)| d\mu(x, y) \end{aligned}$$



# Specific Setups

- “Average” approximation: given a distribution  $\mu$

$$\|f - g\|_{\mu} = \int_x |f(x) - g(x)| d\mu(x)$$

- “Everywhere” approximation

$$\|f - g\|_{\infty} = \sup |f(x) - g(x)| \geq \|f - g\|_{\mu}$$

$$\begin{aligned} \|f - g\|_{\mu} &= \int_x |f(x) - g(x)| d\mu(x) \\ &\leq \int_x \sup_{\tilde{x}} |f(\tilde{x}) - g(\tilde{x})| d\mu(x) \\ &= \|f - g\|_{\infty} \cdot \int_x d\mu(x) \\ &= \|f - g\|_{\infty} \cdot 1 \end{aligned}$$

# Polynomial Approximation

(continuous)

**Theorem (Stone-Weierstrass):** for any function  $f$ , we can **approximate it** on any compact set  $\Omega$  by a sufficiently high degree polynomial: for any  $\epsilon > 0$ , there exists a polynomial  $p$  of sufficient high degree, s.t.,

$$\max_{x \in \Omega} |f(x) - p(x)| \leq \epsilon.$$

Intuition: **Taylor expansion!**

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2}(x-x_0)^2 + \dots$$

$$f(x) = \langle w, \phi(x) \rangle$$
$$\phi(x) = (1, x-x_0, (x-x_0)^2, \dots)$$

$$w = (f(x_0), f'(x_0), \frac{f''(x_0)}{2}, \dots)$$

# Kernel Method

$$x \mapsto \phi(x), \quad f(x) = \langle w, \phi(x) \rangle$$

$$f(x_{\text{test}}) = y^T K(x, x_{\text{test}}) \quad K(x, x') = \langle \phi(x), \phi(x') \rangle$$

## Polynomial kernel

$$\phi(x) = (1, x, x^2, \dots, x^p)$$

$$\text{or } \phi(x) = (1, x-x_0, (x-x_0)^2, \dots)$$

## Gaussian Kernel

$$K(x, x') = \exp\left(-\frac{|x-x'|^2}{2\sigma^2}\right)$$

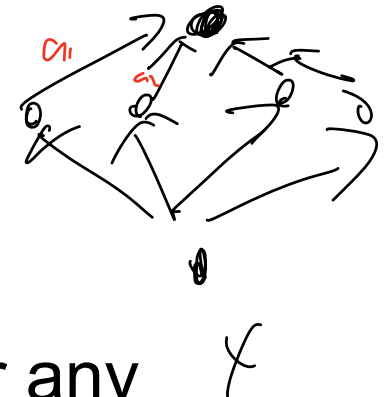
$$\Rightarrow \phi(x) = e^{-\frac{x^2}{2\sigma^2}} \left(1, \frac{x}{\sigma}, \sqrt{\frac{1}{2!}} \left(\frac{x}{\sigma}\right)^2, \dots\right)$$

# 1D Approximation

**Theorem:** Let  $g : [0,1] \rightarrow \mathbb{R}$ , and  $\rho$ -Lipschitz. For any  $\epsilon > 0$ ,  $\exists$  2-layer neural network  $f$  with  $\lceil \frac{\rho}{\epsilon} \rceil$  nodes,

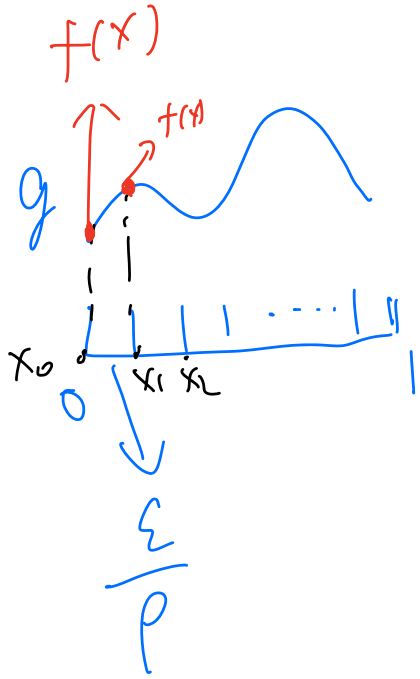
threshold activation:  $\sigma(z) : z \mapsto \mathbf{1}\{z \geq 0\}$  such that

$$\sup_{x \in [0,1]} |f(x) - g(x)| \leq \epsilon.$$



# Proof of 1D Approximation

Pf:



$$m \stackrel{\text{def}}{=} \left\lceil \frac{p}{\epsilon} \right\rceil, \quad x_i = \frac{(i-1)\epsilon}{p}$$

$$f(x) = \sum_{i=0}^m a_i \mathbb{1}_{\{x - x_i \geq 0\}}$$

$$a_0 = g(0), \quad a_i = g(x_i) - g(x_{i-1})$$

$$\bullet \text{ if } x < x_1, \quad \mathbb{1}_{\{x - x_i\}} = 0 \text{ for } i=1, \dots, m$$

$$f(x) = g(0)$$

$$\bullet \text{ if } x_1 \leq x < x_2, \quad \mathbb{1}_{\{x - x_i\}} = 0 \text{ for } i=2, \dots, m$$

$$f(x) = g(x_0) + g(x_1) - g(x_0) = g(x_1)$$

$$\begin{aligned} |g(x) - f(x)| &= |g(x) - f(x_i)|, \quad x_i \leq x, \text{ closest} \\ &= |g(x) - g(x_i)| + |g(x_i) - f(x_i)| \\ &\leq p|x - x_i| \\ &\leq p \cdot \frac{\epsilon}{p} = \epsilon \end{aligned}$$

□

# Multivariate Approximation

**Theorem:** Let  $g$  be a continuous function that satisfies  $\|x - x'\|_\infty \leq \delta \Rightarrow |g(x) - g(x')| \leq \epsilon$  (Lipschitzness). Then there exists a **3-layer ReLU neural network** with  $O(\frac{1}{\delta^d})$  nodes that satisfy

$$\int_{[0,1]^d} |f(x) - g(x)| \underbrace{dx}_{\text{uniform distribution}} = \|f - g\|_1 \leq \epsilon$$

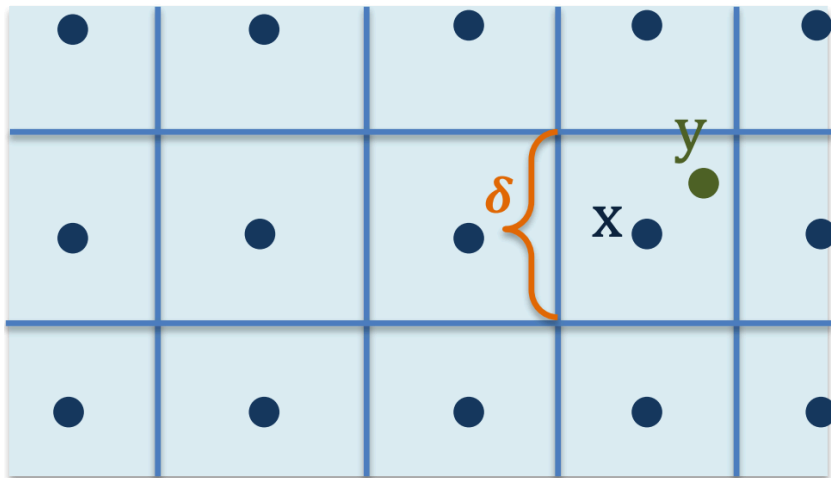
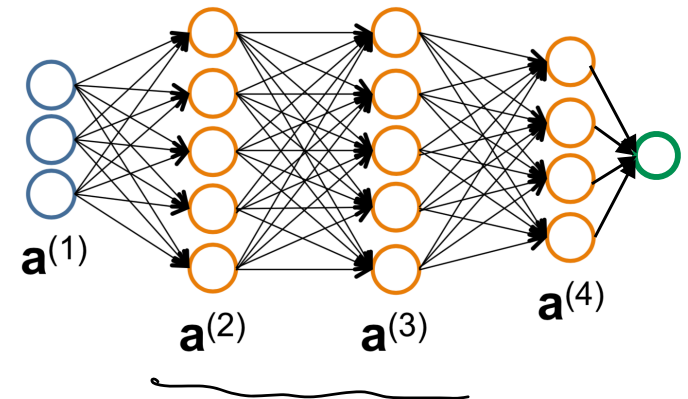
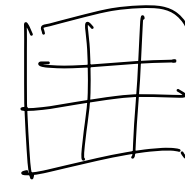


Figure credit to Andrej Risteski



# Partition Lemma



**Lemma:** let  $g, \delta, \epsilon$  be given. For any partition  $P$  of  $[0,1]^d$ ,  $P = (R_1, \dots, R_N)$  with all side length smaller than  $\delta$ , there exists  $(\alpha_1, \dots, \alpha_N) \in \mathbb{R}^N$  such that

$$\sup_{x \in [0,1]^d} |g(x) - h(x)| \leq \epsilon \text{ with } h(x) := \sum_{i=1}^N \alpha_i \mathbf{1}_{R_i}(x).$$

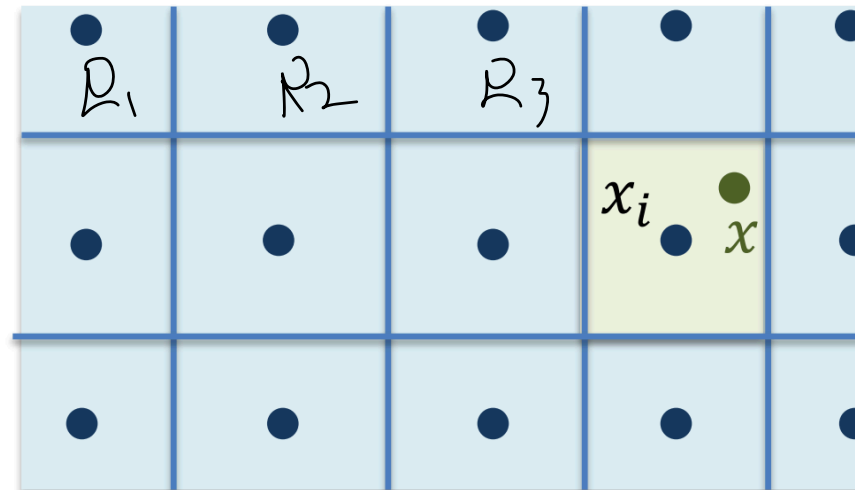


Figure credit to Andrej Risteski

# Proof of Partition Lemma

pf: For each  $R_i$ , pick  $x_i \in R_i$ , set  $\alpha_i \stackrel{\Delta}{=} g(x_i)$

$$\begin{aligned} \sup_{x \in [0,1]^d} |g(x) - h(x)| &= \sup_{i \in \{1, \dots, n\}} \sup_{x \in R_i} |g(x) - h(x)| \\ &\leq \sup_{i \in \{1, \dots, n\}} \sup_{x \in R_i} (|g(x) - g(x_i)| + \underbrace{|g(x_i) - h(x_i)|}_0) \\ &\leq \epsilon \end{aligned}$$

□



# Proof of Multivariate Approximation Theorem

Idea:  $h(x) = \sum_i \alpha_i \mathbb{1}_{Q_i}(x)$

1) use 2-layer N/V to approximate  
 $x \mapsto \mathbb{1}_{Q_i}(x)$

2) find a linear combination to represent  $h$

$$\Rightarrow \|f - g\|_1 \leq \|f - h\|_1 + \|h - g\|_1$$

$$\text{Let } f = \sum_{i=1}^N \alpha_i f_i, \quad f_i \approx \mathbb{1}_{Q_i}(x)$$

$$\alpha_i \stackrel{\text{def}}{=} g(x_i)$$

$$\|f - h\|_1 = \left\| \sum_i \alpha_i (\mathbb{1}_{Q_i} - f_i) \right\|_1$$

$$\leq \sum_i |\alpha_i| \|\mathbb{1}_{Q_i} - f_i\|_1$$

$$\text{say } \|\mathbb{1}_{Q_i} - f_i\|_1 \leq \frac{\varepsilon}{\sum_{i=1}^N |\alpha_i|}$$

$$\Rightarrow \|f - h\|_1 \leq \varepsilon$$

$$\text{if } \sum_{i=1}^N |\alpha_i| = 0 \Rightarrow g(x_i) = 0$$

$$\Rightarrow |g(x)| \leq \varepsilon$$

use 0-network

# Proof of Multivariate Approximation Theorem

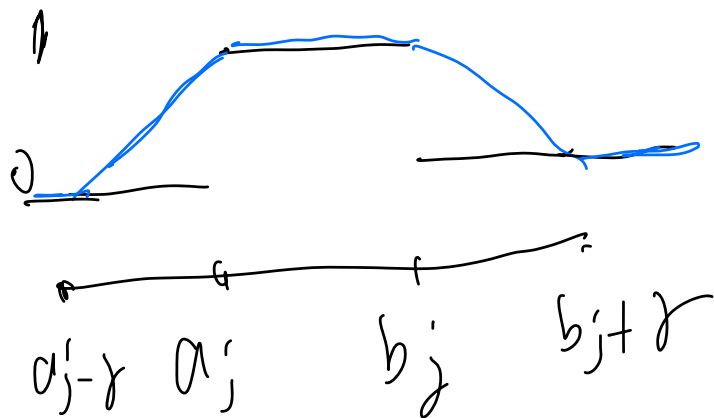
① bump function / smoothly approximating  
 $\mathbb{R}^n = \mathbb{D} [a_1, b_1] \times [a_2, b_2] \cdots \times [a_d, b_d]$

Given  $r > 0$ , define  $\phi: \mathbb{R} \rightarrow [0, 1]$   

$$g_{r, j}(z) = \phi\left(\frac{z - (a_j - r)}{r}\right) - \phi\left(\frac{z - a_j}{r}\right)$$

$$- \phi\left(\frac{z - b_j}{r}\right) + \phi\left(\frac{z - (b_j + r)}{r}\right)$$

$\left\{ \begin{array}{l} \text{if } z \in [a_j, b_j] \Rightarrow g_{r, j}(z) = 1 \\ z \notin [a_j - r, b_j + r] \Rightarrow g_{r, j}(z) = 0 \end{array} \right.$   
 $r \rightarrow 0, g_{r, j} \rightarrow \mathbb{1}_{[a_j, b_j]}$



# Proof of Multivariate Approximation Theorem

Define  $g_r(x) = 6 \left( \sum_{j=1}^d g_{r,j}(x^j) - (d-1) \right)$

$$g_{r,j}(x) = \begin{cases} 1 & \text{if } x \in \mathcal{P}_i \\ 0 & \text{if } x \notin \left[ \bar{a}_i - r, \bar{b}_i + r \right] \\ & \text{d.w. } x \in \left[ \bar{a}_i - r, \bar{b}_i + r \right] \dots \end{cases}$$

$x = \begin{pmatrix} x^1 \\ x^2 \\ \vdots \\ x^d \end{pmatrix}$

Since  $r \rightarrow 0$ ,  $g_{r,j} \rightarrow \mathbb{1}_{\mathcal{P}_i}$

$\Rightarrow g_r \rightarrow \mathbb{1}_{\mathcal{P}_i}$

choose

$$f_i = g_r$$

$$f \stackrel{\Delta}{=} \sum_{i=1}^N \alpha_i f_i$$

□