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Approximation Theory

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Specific Setups

• "Average" approximation: given a distribution μ

$$\|f - g\|_{\mu} = \int_{x} |f(x) - g(x)| d\mu(x)$$

"Everywhere" approximation

$$||f - g||_{\infty} = \sup_{x} |f(x) - g(x)| \ge ||f - g||_{\mu}$$

Multivariate Approximation

Theorem: Let *g* be a continuous function that satisfies $||x - x'||_{\infty} \le \delta \Rightarrow |g(x) - g(x')| \le \epsilon$ (Lipschitzness). Then there exists a 3-layer ReLU neural network with $O(\frac{1}{\delta^d})$ nodes that satisfy $\int_{[0,1]^d} |f(x) - g(x)| dx = ||f - g||_1 \le \epsilon$





Definition: A class of functions \mathscr{F} is universal approximator over a compact set S (e.g., $[0,1]^d$), if for every continuous function g and a target accuracy $\epsilon > 0$, there exists $f \in \mathscr{F}$ such that

$$\sup_{x \in S} |f(x) - g(x)| \le \epsilon$$

Stone-Weierstrass Theorem

Theorem: If \mathcal{F} satisfies **1.** Each $f \in \mathcal{F}$ is continuous. check wiki fi-(ti EF cti EF **2.** $\forall x, \exists f \in \mathscr{F}, f(x) \neq 0$ **3.** $\forall x \neq x', \exists f \in \mathscr{F}, f(x) \neq f(x')$ 4. F is closed under multiplication and vector space operations, $t_1, t_2 \in F, t_1, t_2 \in F$ Then \mathcal{F} is a universal approximator: $\forall g: S \to R, \epsilon > 0, \exists f \in \mathscr{F}, \|f - g\|_{\infty} \le \epsilon.$

Example: cos activation $6 : \alpha (-t_i)/(\lambda t_i))$ $- F_{6,d,m} = \{ \chi \mapsto a^{T} 6(W \chi + b), u \in \mathbb{R}^{n}, W \in \mathbb{R}^{m \times d}, b \in \mathbb{R}^{m} \}$ - $F_{6,d} \stackrel{a}{=} O F_{6,d,m}$ $m_{7,0}$ $f(x) = \sum_{j=1}^{n} q_j \cdot (o) f(u, x + b_i)$ Pf: UVFEFcos,d is continuous $S(E) = \sum_{j=1}^{n} (j \circ o) (V_j^T X_j^T d_j)$ Frosid is universal $(2) \forall X, (0)(0^T X) = (0)(0) = ($ (3) f, g E Frond, =) f g E Fros,d Pe(all 2cos(4)(a)(2) = cos(4+2)+(o)(4-2) $2f(k) - 2 \begin{bmatrix} \frac{1}{2} & u_i(0) \\ u_i(k+b) \end{bmatrix} \begin{bmatrix} \frac{1}{2} & (i) \\ \frac{1}{2} & u_i(0) \end{bmatrix}$ $= \sum_{j=1}^{n} \mathcal{U}_{i}\left[\int_{1}^{1} \left[\cos\left(\left(w_{i}+v_{j}\right)^{T}X+b_{i}+d_{i}\right)+\left(\cos\left(\left(w_{i}-v_{j}\right)^{T}X+b_{i}+d_{i}\right)\right)\right]$

Example: cos activation

(4)
$$X \neq x', \exists f: f(r) \notin f(r')$$

 $def Me = f(2) = (0) \left(\frac{(z - x')^7 (x - x')}{\|x - x'\|_{2}^{2}} \right) \in \mathcal{F}$
 $f(r) = cos (1)$
 $f(x') = cos (0)$

 $\langle \rangle$

Other Examples

Exponential activation

Curse of Dimensionality

Unavoidable in the worse case





Barron's Theory time (-) frequency

- Can we avoid the curse of dimensionality for "nice" functions?
- What are nice functions?
 - Fast decay of the Fourier coefficients
- Fourier basis functions: $\{\overline{e_w(x) = e^{i\langle w, x \rangle}} = \cos(\langle w, x \rangle) + i\sin(\langle w, x \rangle) \mid w \in \mathbb{R}^d\}$ Fourier coefficient: $\hat{f}(w) = \int_{\mathbb{R}^d} f(x)e^{-i\langle w, x \rangle} dx$ Fourier integral / representation: $f(x) = \int_{\mathbb{R}^d} \hat{f}(w) e^{i\langle w, x \rangle} dw$ U= Z Ai Vi



Definition: The Barron constant of a function f is:

$$C \triangleq \int_{\mathbb{R}^d} \|w\|_2 |\hat{f}(w)| \, dw.$$

Theorem (Barron '93): For any $g : \mathbb{B}_1 \to \mathbb{R}$ where $\mathbb{B}_1 = \{x \in \mathbb{R} : ||x||_2 \le 1\}$ is the unit ball, there exists a **3-layer neural network** f with $O(\frac{C^2}{\epsilon})$ neurons and sigmoid activation function such that g is a dual by $f(x) = g(x)^2 dx \le \epsilon$.



Gaussian function:
$$f(x) = (2\pi\sigma^2)^{d/2} \exp\left(-\frac{\|x\|_2^2}{2\sigma^2}\right)$$

$$\int (W) = \varrho \times \rho \left(-2\pi\delta^2 \|w\|_2^2\right)$$

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Function with bounded derivatives

Step 1: show any continuous function can be written as an infinite neural network with cosine-like activation functions. (Tool: Fourier representation.)

Step 2: Show that a function with small Barron constant can be approximated by a convex combination of a small number of cosine-like activation functions. (Tool: subsampling / probabilistic method.) *Combinativity*, (()

Step 3: Show that the cosine function can be approximated by sigmoid functions.

(Tool: classical approximation theory.)

Simple Infinite Neural Nets

Definition: An infinite-wide neural network is defined by a signed measure ν over neuron weights (w, b)

5 V(w, 5). 6(ux th)

$$f(x) = \int_{w \in \mathbb{R}^{d}, b \in \mathbb{R}} \underbrace{\sigma(w^{\top}x + b) d\nu(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \leq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \neq t \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_{f \neq v \neq v \quad da \gamma e_{t}} \underbrace{\sigma(w, b)}_$$

Step 1: Infinite Neural Nets



Step 1: Infinite Neural Nets Proof

The function can be written as

$$f(x) = f(0) + \int_{\mathbb{R}^d} |\hat{f}(w)| (\cos(b_w + \langle w, x \rangle) - \cos(b_w)) dw.$$

$$p_{\mathcal{R}^d} = \int_{\mathbb{R}^d} f(w) e^{i\zeta(w,x)} dw$$

$$= \int_{\mathbb{R}^d} f(w) dw + \int_{\mathbb{R}^d} f(w) (e^{i\zeta(w,x)} - 1) dw$$

$$f(w) = f(w) e^{i\omega} = f(0) + \int_{\mathbb{R}^d} d |f(w)| e^{i\omega} (e^{i\zeta(w,x)} - 1) dw$$

$$= f(0) + \int_{\mathbb{R}^d} d |f(w)| e^{i\omega} (e^{i\zeta(w,x)} - e^{i\omega}) dw$$

$$= f(0) + \int_{\mathbb{R}^d} d |f(w)| (c_0) (bw(c_w,x)) - c_0) (bw) dw$$

$$f(w) = f(0) + \int_{\mathbb{R}^d} d |f(w)| (c_0) (bw(c_w,x)) - c_0) (bw) dw$$

Step 2: Subsampling

 $f(x) = f(0) + \int_{\mathbb{R}^d} \frac{|\hat{f}(w)| ||w||_2}{C} \left(\frac{C}{||w||_2} (\cos(b_w + \langle w, x \rangle) - \cos(b_w)) \right) dw.$ $Iden: \quad (> u ftunct a distribution over u (bw))$ $Iden: \int_{\mathcal{D}^d} \int_{\mathcal{D}^d} \frac{|\hat{f}(w)| (|u|d_x)}{C} = 1 , \quad (z = \int_{\mathcal{D}^d} |\hat{f}(w)| ||w||_2)$ Writing the function as the expectation of a random variable: $f(x) = f(u) f H_{W/-D,w} \left[\frac{C}{Uwil} (COS(bwt(u,x))-(u) fw) \right]$

Step 2: Subsampling

Writing the function as the expectation of a random variable: $f(x) = f(0) + \left[\frac{\|f(w)\| \|w\|}{C} \left(\frac{C}{\|w\|} (\cos(b_w + \langle w, x \rangle) - \cos(b_w)) \right) dw.$ Sample one $w \in \mathbb{R}^{d}$ with probability $\frac{|\hat{f}(w)| ||w||_{2}}{C}$ for r times. $\begin{cases} w_{1,...,w_{V}} \end{cases}$ with $(m_{1}m_{1}w_{1}w_{1})^{2} + \frac{1}{2} \int_{1}^{V} \int_{1}^{C} \int_{1}^{C} \int_{1}^{V} \int_{1}^{C} \int_{1}^{C} \int_{1}^{V} \int_{1}^{C} \int_{1}^{V} \int_{1}^{C} \int_{1}^{V} \int_{1}^{C} \int_{1}^{V} \int_{1}^{V} \int_{1}^{C} \int_{1}^{V} \int_{$ ~-) w, -> f(x) $\xi - e_{k} k r = O\left(\frac{c}{2}\right)$

Step 3: Approximating the Cosines

Lemma: Given
$$g_w(x) = \frac{C}{\|w\|_2} (\cos(b_w + \langle w, x \rangle) - \cos(b_w))$$
,
there exists a 2-layer neural network f_0 of size $O(1/\epsilon)$ with sigmoid activations, such that $\sup_{x \in [-1,1]} |f_0(y) - h_w(y)| \le \epsilon$.

So far we only talk about 2-layer or 3-layer neural networks.

Why we need **Deep** learning?

Can we show deep neural networks are **strictly** better than shallow neural networks?

A brief history of depth separation

Early results from theoretical computer science

Boolean circuits: a directed acyclic graph model for computation over binary inputs; each node ("gate") performs an operation (e.g. OR, AND, NOT) on the inputs from its predecessors.



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Depth separation: the difference of the computation power: shallow vs deep Boolean circuits.

Håstad ('86): parity function cannot be approximated by a small constant-depth circuit with OR and AND gates.

Modern depth-separation in neural networks

- Related architectures / models of computation
 - Sum-product networks [Bengio, Delalleau '11]
- Heuristic measures of complexity
 - Bound of number of linear regions for ReLU networks [Montufar, Pascanu, Cho, Bengio '14]
- Approximation error
 - A small deep network cannot be approximated by a small shallow network [Telgarsky '15]

Theorem (Telgarsky '15): For every $L \in \mathbb{N}$, there exists a function $f: [0,1] \to [0,1]$ representable as a network of depth $O(L^2)$, with $O(L^2)$ nodes, and ReLU activation such that, for every network $g: [0,1] \to \mathbb{R}$ of depth Land $\leq 2^L$ nodes, and ReLU activation, we have $\int_{[0,1]} |f(x) - g(x)| \, dx \geq \frac{1}{32}.$ (infant)

Intuition

A ReLU network *f* is piecewise linear, we can subdivide domain into a finite number of polyhedral pieces (P_1, P_2, \ldots, P_N) such that in each piece, *f* is linear: $\forall x \in P_i, f(x) = A_i x + b_i$.



Deeper neural networks can make exponentially more regions than shallow neural networks.

Make each region has different values, so shallow neural networks cannot approximate.

Theorem (Yarotsky '15): Suppose $f : [0,1]^d \to \mathbb{R}$ has all partial derivatives of order r with coordinate-wise bound in [-1,1], and let $\epsilon > 0$ be given. Then there exists a $O(\ln \frac{1}{\epsilon})$ - depth and $\left(\frac{1}{\epsilon}\right)^{O(\frac{d}{r})}$ -size network so that $\sup_{x \in [0,1]^d} |f(x) - g(x)| \le \epsilon$. $\gamma = J$



- All results discussed are existential: they prove that a good approximator exists. Finding one efficiently (e.g., using gradient descent) is the next topic (optimization).
- The choices of non-linearity are usually very flexible: most results we saw can be re-proven using different non-linearities.
- There are other approximation error results: e.g., deep and narrow networks are universal approximators.
 GMM
- Depth separation for optimization and generalization is widely open.