

$$\max_{i=1, \dots, n} \sum_{t=1}^T x_{t,i} - x_{t, I_t} \leq \sqrt{nT}$$

$$\mathbb{E}[x_{t,i}] = \mu_i$$

Online-to-batch conversion.

$$\hat{i} \sim \text{uniform}(\{I_t\}_{t=1}^T)$$

$$\begin{aligned} \max_{j=1, \dots, n} \mathbb{E}[\mu_j - \mu_{\hat{i}}] &= \max_{j=1, \dots, n} \mathbb{E} \left[\frac{1}{T} \sum_{t=1}^T x_{t,j} - x_{t, I_t} \right] \\ &= \frac{\text{Regret}(T)}{T} \end{aligned}$$

Contextual Bandits (Stochastic)

Input: Π , $\pi_0 \in \Pi$, $\bar{c}: \mathcal{C} \rightarrow [n]$

for $t=1, 2, \dots, T$

Nature reveals $c_t \stackrel{iid}{\sim} \bar{c}$

Player chooses $\pi_t \in \Pi$, $a_t := \pi_t(c_t)$

Receives reward $r_t \in [0, 1]$: $\mathbb{E}[r_t | c_t] = r(c_t, a_t)$

Minimize regret $\max_{\pi \in \Pi} \sum_{t=1}^T r(c_t, \pi(c_t)) - r(c_t, a_t)$ $V(\pi) = \mathbb{E}_{c, a \sim \pi(c)} [r(c, a)]$
 $= \mathbb{E}_c [r(c, \pi(c))]$

Logging policy $\mu(\cdot | c_t) \in \Delta_n$, $p_t = \mu(a_t | c_t)$. Assume $\mu(a_t | c_t) > 0 \forall a, c$

Collect dataset $\{(c_t, a_t, r_t, p_t)\}_t$. Always log sampling probs p_t !

Forget context. Given $\{(a_t, r_t, p_t)\}_t$. Idea: learn some function

$f: f(a_t) \approx r_t$ (e.g. $\hat{f} = \underset{f \in \mathcal{F}}{\operatorname{argmin}} \sum_t (f(a_t) - r_t)^2$)

recommend $\underset{a}{\operatorname{argmax}} \hat{f}(a)$

Model the World Given $\{(c_t, a_t, r_t, p_t)\}_t$

learn $f: f(c_t, a_t) \approx r_t$ (e.g. $\hat{f} = \underset{f \in \mathcal{F}}{\operatorname{argmin}} \sum_t (f(c_t, a_t) - r_t)^2$)

recommend $\underset{a}{\operatorname{argmax}} \hat{f}(c_t, a)$

Model the Bias

$$\hat{r}(c_t, a) := r_t \frac{\mathbb{1}\{a_t = a\}}{P_t}$$

$$\begin{aligned} \mathbb{E}[\hat{r}(c_t, a)] &= \sum_{a'} \frac{P(a_t = a')}{\mu(a' | c_t)} r(c_t, a') \frac{\mathbb{1}\{a' = a\}}{\mu(a' | c_t)} \\ &= r(c_t, a) \end{aligned}$$

$$\hat{V}(\pi) = \frac{1}{T} \sum_{t=1}^T \hat{r}(c_t, \pi(c_t)), \quad \mathbb{E}[\hat{V}(\pi)] = V(\pi)$$

$$\mathbb{E}[(\hat{V}(\pi) - V(\pi))^2] = \frac{1}{T^2} \mathbb{E} \left[\sum_{t=1}^T (\hat{r}(c_t, \pi(c_t)) - r(c_t, \pi(c_t)))^2 \right]$$

$$\leq \frac{1}{T^2} \mathbb{E} \left[\sum_t \hat{r}(c_t, \pi(c_t))^2 \right]$$

$$= \frac{1}{T^2} \sum_t \mathbb{E}_{c_t} \left[r_t^2 \frac{\mathbb{1}\{a_t = \pi(c_t)\}}{P_t^2} \right]$$

$$\leq \frac{1}{T^2} \sum_t \mathbb{E}_{a_t, c_t} \left[\frac{\mathbb{1}\{a_t = \pi(c_t)\}}{\mu(a_t | c_t)^2} \right]$$

$$= \frac{1}{T} \mathbb{E}_{c \sim \nu} \left[\frac{1}{\mu(\pi(c) | c)} \right]$$

I want high prob bound on $|\hat{V}(\pi) - V(\pi)|$.

Hoeffding says that if $z_t \in [a, b]$ and

$$\mathbb{E}[z_t] = 0 \quad \text{then} \quad \mathbb{P}\left(\frac{1}{T} \sum_{t=1}^T z_t \geq |b-a| \sqrt{\frac{\log(1/\delta)}{2T}}\right) \leq \delta.$$

$$\hat{V}(c, \pi(c)) \in \left[0, \frac{1}{\min_{c,a} \mu(a|c)}\right]$$

Bernstein's inequality says that if $z_t \leq B$ and

$$\mathbb{E}[z_t] = 0, \quad \mathbb{E}[z_t^2] \leq \sigma^2 \quad \text{then}$$

$$\mathbb{P}\left(\frac{1}{T} \sum_{t=1}^T z_t \geq \sqrt{\frac{2\sigma^2 \log(1/\delta)}{T}} + \frac{2B \log(1/\delta)}{3T}\right) \leq \delta.$$

$$\Rightarrow \text{w.p.} \geq 1 - \delta$$

$$|\hat{V}(\pi) - V(\pi)| \leq \underbrace{\sqrt{\mathbb{E}_c \left[\frac{1}{\mu(\pi|c)} \right]} \cdot \frac{2 \log(2/\delta)}{T}}_{\leq \eta \text{ if union}} + \underbrace{\max_{c,a} \frac{1}{\mu(a|c)} \cdot \frac{2 \log(2/\delta)}{3T}}_{\leq \eta \text{ if union}}$$

Side note: There exists an estimator $\hat{\mu}: \mathbb{R}^T \rightarrow \mathbb{R}$

s.t. if $\mathbb{E}[z_t] = 0, \mathbb{E}[z_t^2] \leq \sigma^2$ then

$$\mathbb{P}\left(\hat{\mu}(\{z_t\}_{t=1}^T) \geq \sqrt{\frac{2\sigma^2 \log(1/\delta)}{T}}\right) \leq \delta.$$

See Catoni's estimator or median of means.

If $\mu(a|c) = \frac{1}{n}$ for c, a then for a $\pi \in \Pi$

$$|\hat{V}(\pi) - V(\pi)| \leq \sqrt{\frac{2n \log(2/d)}{T}} + \frac{2n \log(2/d)}{3T}$$

$$\leq \sqrt{\frac{4n \log(2/d)}{T}}$$

and $\forall \pi$ w.p. $\geq 1 - \delta$

$$|\hat{V}(\pi) - V(\pi)| \leq \sqrt{\frac{4n \log(2/\pi/d)}{T}} = C$$

You collected a data set computed $\hat{V}(\pi)$

for all $\pi \in \Pi$. Which one do you choose?

Natural to choose $\hat{\pi}_{MLE} = \arg \max_{\pi \in \Pi} \hat{V}(\pi)$

Define $C(\pi) = \sqrt{\mathbb{E}\left[\frac{1}{\mu(\pi(c)|c)}\right] - \frac{2 \log(2/\pi/d)}{T}} + 2 \frac{\max_{c \in \mathcal{C}} \frac{1}{\mu(\pi(c)|c)}}{3T}$

$$V(\hat{\pi}_{MLE}) \geq \hat{V}(\hat{\pi}_{MLE}) - C(\hat{\pi}_{MLE})$$

$$\geq \hat{V}(\pi_{\star}) - C(\hat{\pi}_{MLE})$$

$$\geq V(\pi_x) - C(\pi_x) - C(\hat{\pi})$$

$$\geq V(\pi_x) - 2 \max_{\pi \in \Pi} C(\pi)$$

Pessimism

Define $\hat{\pi}_{\text{pers}} = \underset{\pi \in \Pi}{\text{argmax}} \hat{V}(\pi) - C(\pi)$

$$V(\hat{\pi}_{\text{pers}}) \geq \hat{V}(\hat{\pi}_{\text{pers}}) - C(\hat{\pi}_{\text{pers}})$$

$$\geq \hat{V}(\pi_x) - C(\pi_x)$$

$$\geq V(\pi_x) - 2C(\pi_x)$$

Doubly Robust Estimator

$$\hat{r}_{\text{DR}}(l_t, a) = \hat{f}(l_t, a) + (r_t - \hat{f}(l_t, a)) \frac{\mathbb{1}\{a_t = a\}}{P_t}$$

$$\mathbb{E}[\hat{r}_{\text{DR}}(l_t, a)] = r(l_t, a)$$

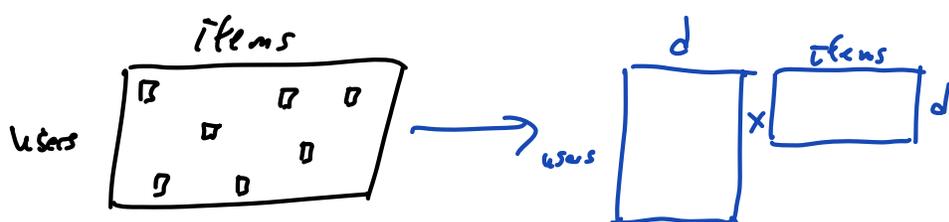
$$\begin{aligned}
\hat{\pi}_{MLE} &= \operatorname{argmax}_{\pi \in \Pi} \hat{V}(\pi) \\
&= \operatorname{argmax}_{\pi \in \Pi} \frac{1}{T} \sum_{t=1}^T \frac{\mathbb{1}\{a_t = \pi(c_t)\}}{P_t} r_t \\
&= \operatorname{argmax}_{\pi} \frac{1}{T} \sum_{t=1}^T \frac{(1 - \mathbb{1}\{a_t \neq \pi(c_t)\})}{P_t} r_t \\
&= \operatorname{argmax}_{\pi} \frac{1}{T} \sum_{t=1}^T - \frac{\mathbb{1}\{a_t \neq \pi(c_t)\}}{P_t} r_t \\
&= \operatorname{argmin}_{\pi} \frac{1}{T} \sum_{t=1}^T \frac{r_t}{P_t} \mathbb{1}\{a_t \neq \pi(c_t)\}
\end{aligned}$$

Example Let $\phi: \mathcal{C} \times [n] \rightarrow \mathbb{R}^d$, for each $\theta \in \mathbb{R}^d$, there exists

$$\pi_{\theta} \in \Pi : \pi_{\theta}(c_t) = \operatorname{argmax}_{i=1, \dots, n} \langle \phi(c_t, i), \theta \rangle$$

$$\hat{\theta} = \operatorname{argmin}_{\theta} \sum_t \frac{r_t}{P_t} - \log \left(\frac{\exp(\langle \phi(c_t, a_t), \theta \rangle)}{\sum_i \exp(\langle \phi(c_t, i), \theta \rangle)} \right)$$

$$\theta_{k+1} = \theta_k + \eta_k \sum_{t=1}^T \frac{r_t}{P_t} \nabla_{\theta} \log \left(\frac{\exp(\langle \phi(c_t, a_t), \theta \rangle)}{\sum_i \exp(\langle \phi(c_t, i), \theta \rangle)} \right)$$



Policy Gradient (REINFORCE)

$$V(\pi) = \mathbb{E}_{\substack{c \sim \nu \\ a \sim \pi(\cdot|c)}} [r(c, a)]$$

Parameterize our policies: $\Pi = \{\pi_\theta : \theta \in \mathbb{R}^d\}$

$$\begin{aligned} \nabla_\theta V(\pi_\theta) &= \nabla_\theta \sum_c \gamma_c \sum_a \pi_\theta(a|c) r_{c,a} \\ &= \sum_c \gamma_c \sum_a r_{c,a} \nabla_\theta \pi_\theta(a|c) \\ &= \sum_c \gamma_c \sum_a r_{c,a} \pi_\theta(a|c) \cdot \underbrace{\frac{\nabla_\theta \pi_\theta(a|c)}{\pi_\theta(a|c)}}_{\nabla_\theta \log(\pi_\theta(a|c))} \\ &= \sum_c \sum_a \gamma_c \pi_\theta(a|c) r_{c,a} \cdot \nabla_\theta \log(\pi_\theta(a|c)) \\ &= \mathbb{E} \left[r_t \cdot \nabla_\theta \log(\pi_\theta(a_t|c_t)) \right] \end{aligned}$$

At time t , $a_t \sim \pi_{\theta_t}(c_t)$

$$\theta_{t+1} = \theta_t + \eta_t \nabla_\theta \log(\pi_{\theta_t}(a_t|c_t))$$

n arms (no context)

$$[\pi_\theta]_i = \frac{\exp(\theta_i)}{\sum_j \exp(\theta_j)}$$

$$\begin{aligned} \left[\nabla_{\theta_i} \log(\pi_\theta(i)) \right]_k &= \nabla_{\theta_i} (\theta_i - \log \sum_j e^{\theta_j}) \\ &= \mathbb{1}\{k=i\} - \frac{e^{\theta_k}}{\sum_j e^{\theta_j}} \end{aligned}$$

$$\theta_0 = 0 \quad \therefore \mathbb{1}\{k=i\} - \pi_\theta(k)$$

for $t=1, 2, \dots$

$$\text{Player draws } I_t \sim \frac{e^{\theta_{t,i}}}{\sum_j e^{\theta_{t,j}}}$$

Nature reveals r_t , $\mathbb{E}[r_t] = \mu_{I_t}$

$$\theta_{t+1} = \theta_t + \eta (e_{I_t} - \pi_\theta(\cdot)) r_t$$