

Best arm identification for Linear Bandits.

Input: $\mathcal{X} \subset \mathbb{R}^d$, $\delta \in (0, 1)$

for $t=1, 2, \dots$

Player chooses $x_t \in \mathcal{X}$

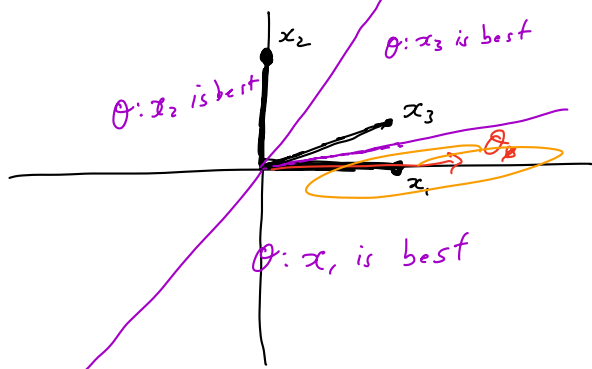
Nature reveals $y_t = \langle x_t, \theta_* \rangle + \zeta_t$

← 1-sub-Gaussian

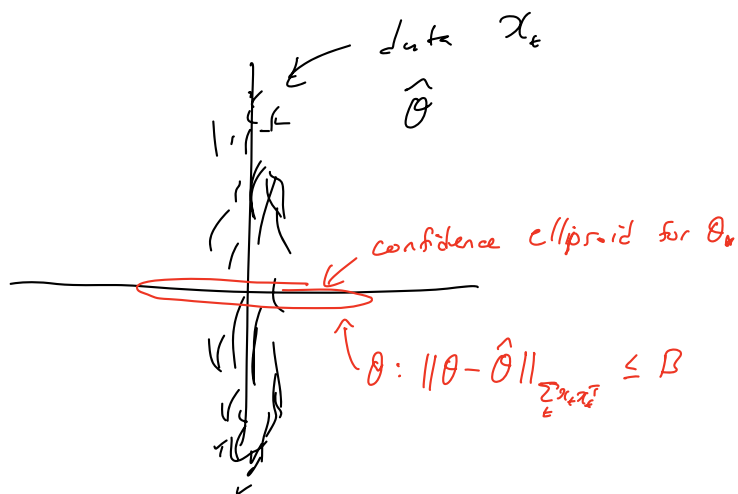
Player optimally stops and outputs $\hat{x} \in \mathcal{X}$.

Goal: With prob $\geq 1-\delta$ output $\hat{x} = x_*$ after as few samples as possible.

Soare et 2014 example:



$$x_3 = \begin{pmatrix} \cos \delta \\ \sin \delta \end{pmatrix}$$



Suppose we take samples x_1, \dots, x_T and observe $\{y_t\}_{t=1}^T$.

Compute $\hat{\theta} = (X^T X)^{-1} X^T y$.

$$x_* = \operatorname{argmax}_{x \in \mathcal{X}} \langle x, \theta_* \rangle$$

If $\hat{x} = \operatorname{argmax}_{x \in \mathcal{X}} \langle x, \hat{\theta} \rangle$ and $x_* = \hat{x}$

then $\langle x_* - x, \hat{\theta} \rangle > 0 \quad \forall x.$

$$\langle x_A - x, \hat{\theta} \rangle = \langle x_A - x, \hat{\theta} - \theta_A \rangle + \langle x_A - x, \theta_A \rangle$$

$$\geq \|x_A - x\|_{(X^T X)^{-1}} \sqrt{2 \log(1/\delta)} + \langle x_A - x, \theta_A \rangle$$

$$> 0 \quad \text{if}$$

$$\frac{\|x_A - x\|_{(X^T X)^{-1}} \sqrt{2 \log(1/\delta)}}{\langle x_A - x, \theta_A \rangle} < 1 \quad \forall x \neq x_A$$

$$\max_{x \neq x_A} \frac{\|x_A - x\|_{(X^T X)^{-1}}^2 \cdot 2 \log(1/\delta)}{\langle x_A - x, \theta_A \rangle^2} < 1$$

$$X^T X = \sum_{t=1}^T x_t x_t^T$$

$$\min_{T, x_1, \dots, x_T} T$$

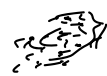
$$\text{s.t.} \quad \max_{x \neq x_A} \frac{\|x_A - x\|_{\left(\sum_{t=1}^T x_t x_t^T\right)^{-1}}^2 \cdot 2 \log(1/\delta)}{\langle x_A - x, \theta_A \rangle^2} < 1$$

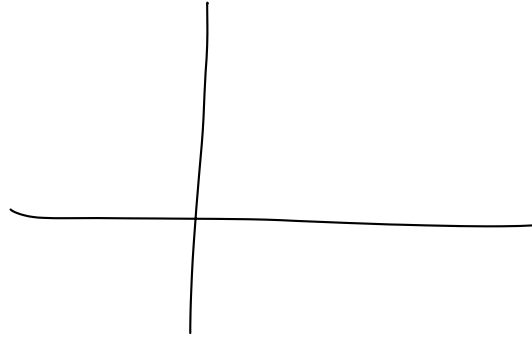
$$A(\lambda) = \sum_{x \in X} \lambda_x x x^T \quad \lambda \in \Delta_X, \quad T A(\lambda) \preceq \sum_{t=1}^T x_t x_t^T$$

$$\min_{\lambda \in \Delta_X, T} T$$

$$\text{s.t.} \quad \max_{x \neq x_A} \frac{\|x_A - x\|_{A(\lambda)^{-1}}^2 \cdot 2 \log(1/\delta)}{\langle x_A - x, \theta_A \rangle^2} < T$$

$$\Rightarrow T \geq \underbrace{\min_{\lambda \in \Delta_{\mathcal{X}}} \max_{x \neq x_{\lambda}} \frac{\|x_{\lambda} - x_{\theta}\|_{A(\lambda)^{-1}}^2}{\langle x_{\lambda} - x, \theta_{\lambda} \rangle^2}}_{:= \mathcal{P}_{\theta}} \cdot 2 \log(1/\delta).$$

Claim There exists an algorithm that identifies x_{θ} w.p. $> 1 - \delta$ and takes fewer than $\mathcal{P}_{\theta} \log(1/\delta)$ total pulls. 



Input: Finite set $\mathcal{X} \subset \mathbb{R}^d$, confidence level $\delta \in (0, 1)$.

Let $\mathcal{X}_1 \leftarrow \mathcal{X}, t \leftarrow 1$

while $|\mathcal{X}_t| > 1$ **do**

Let $\hat{\lambda}_t \in \Delta_{\mathcal{X}}$ be a $\frac{d(d+1)}{2}$ -sparse minimizer of $f(\lambda; \mathcal{X}_t)$ where

$$f(\mathcal{V}) = \inf_{\lambda \in \mathcal{X}} f(\lambda; \mathcal{V}) = \inf_{\lambda \in \mathcal{X}} \max_{x, x' \in \mathcal{V}} \|x - x'\|_{(\sum_{x \in \mathcal{X}} \lambda_x x x^T)^{-1}}^2$$

Set $\epsilon_t = 2^{-t}, \tau_t = 2\epsilon_t^{-2} f(\hat{\lambda}_t; \mathcal{X}_t) \log(4t^2 |\mathcal{X}| / \delta)$

Pull arm $x \in \mathcal{X}$ exactly $\lceil \tau_t \hat{\lambda}_{t,x} \rceil$ times and construct $\hat{\theta}_t$

$\mathcal{X}_{t+1} \leftarrow \mathcal{X}_t \setminus \{x \in \mathcal{X}_t : \max_{x' \in \mathcal{X}_t} \langle x' - x, \hat{\theta}_t \rangle > \epsilon_t\}$

$t \leftarrow t + 1$

Output: \mathcal{X}_{t+1}

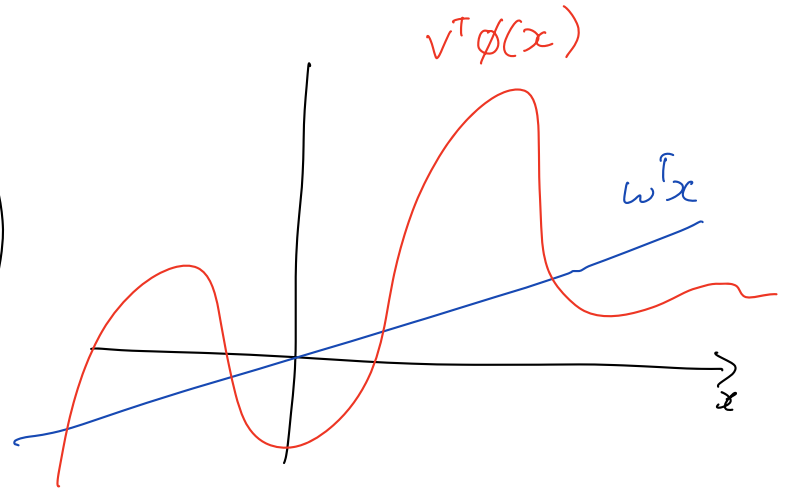
$$\begin{aligned} \max_x \|x - x_{\theta}\| &\leq \max_{x, x'} \|x - x'\| = \max_{x, x'} \| (x - x_{\theta}) - (x' - x_{\theta}) \| \\ &\leq \max_{x, x'} \|x - x_{\theta}\| + \|x' - x_{\theta}\| \\ &= \max_x 2 \|x - x_{\theta}\| \end{aligned}$$

$$x \mapsto \phi(x) \in \mathbb{R}^p \quad \forall x \in \mathcal{X} \subset \mathbb{R}^d$$

$$x \in \mathbb{R} \\ \phi(x) \in \mathbb{R}^{20}$$

$$p \gg d$$

$$\phi\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = \begin{pmatrix} x_1^2 \\ x_2^2 \\ x_1 x_2 \\ x_1 \\ x_2 \\ 1 \end{pmatrix}$$



For any $\phi: \mathbb{R}^d \rightarrow \mathbb{R}^p$ define $k(x, x') := \langle \phi(x), \phi(x') \rangle$.

$$\text{RBF kernel } k(x, x') = e^{-\|x - x'\|^2 / 2\sigma^2}$$

$$\langle w, x \rangle \equiv \sum_i \alpha_i k(x, x_i)$$

UCB $\hat{\theta} = (X^T X + \lambda I)^{-1} X^T y$ ← from data up to time T

$$= V_t^{-1} \sum_{s=1}^t x_s y_s$$

$$\operatorname{argmax}_{x \in \mathcal{X}} \langle \hat{\theta}, x \rangle + \|x\|_{V_t^{-1}} \cdot \sqrt{\beta_t}$$

$$\langle \hat{\theta}, x \rangle = x^T (X^T X + \lambda I)^{-1} X^T y$$

Claim $(X^T X + \lambda I)^{-1} X^T = X^T (X X^T + \lambda I)^{-1}$

$$\langle \hat{\theta}, x \rangle = x^T X^T (XX^T + \lambda I)^{-1} y$$

$$= k_t(x)^T (K_t + \lambda I)^{-1} y$$

$$k_t(x) = \begin{bmatrix} k(x, x_1) \\ \vdots \\ k(x, x_t) \end{bmatrix}$$

$$[K_t]_{i,j} = k(x_i, x_j)$$

$$\|x\|_{V_t}^2 = x^T V_t^{-1} x = x^T (X^T X + \lambda I)^{-1} x$$

$$= \frac{1}{\lambda} k(x, x) - \frac{1}{\lambda} k_t(x)^T (K_t + \lambda I)^{-1} k_t(x)$$

$$(X^T X + \lambda I) b = X^T X b + \lambda b$$

$$b = (X^T X + \lambda I)^{-1} X^T X b + \lambda (X^T X + \lambda I)^{-1} b$$

$$= X^T (X X^T + \lambda I)^{-1} X b + \lambda (X^T X + \lambda I)^{-1} b$$

$$\Rightarrow a^T (X^T X + \lambda I)^{-1} b = \frac{1}{\lambda} a^T b - \frac{1}{\lambda} a^T X^T (X X^T + \lambda I)^{-1} X b$$