Thompson Sampling for Linear Bandits

In MAB we played am
$$I_{\epsilon}: P(I_{\tau=i})=P(i=i|(x_{s},y_{s})_{s=i}^{t-1})$$

Equivalently, maintain a posterior over the parameter $O_{\mathbf{x},i}$
 $suy \equiv \mathcal{N}(\hat{\theta}_{\epsilon,i},\frac{1}{\tau_{i}})$ and $draw \quad O_{\epsilon,i}' \sim \mathcal{N}(\hat{\theta}_{\epsilon,i},\frac{1}{\tau_{i}})$ the
 $I_{\epsilon} = \arg_{i}^{max} O_{\epsilon,i}'$

$$\begin{array}{c} \text{Toput: i arm set } \chi c R^{d} \\ F_{n}: f. prior \quad P_{e} = \mathcal{N}(0, 1) \\ \text{br} \quad f^{e}(2, 2, ---) \\ \text{Draw} \quad O'_{t} \sim P_{e-1} \\ \text{full arm} \quad \chi_{t} = \frac{\arg\max}{\chi e \chi} \left\{ \chi, O'_{t} \right\}, \text{ observe } y_{t} = \left\{ \chi_{t}, O_{t} \right\} + \frac{1}{2e} \\ \text{Update posterior} \quad P_{t-1} \rightarrow P_{t}, \quad \left(\text{More or } bcs^{-1} \right) \quad f_{e} = \mathcal{N}(\hat{O}_{t}, V_{e}^{-1}) \quad \text{observe} \\ V_{e} = \frac{\int_{t}^{2} \chi_{t} \chi_{s}^{-1} + \lambda I}{\int_{t}^{2} \Theta_{e}} = V_{e}^{-1} \int_{s_{t}}^{1} \chi_{s} y_{s} \\ \text{Suppose} \quad \mathbb{E}\left[y_{e} \mid \chi_{e} \right] = f(\chi_{e}) \quad \text{where } f \text{ is arbitrary.} \\ \text{but } \left\{ 3 O_{e} \in \mathbb{R}^{d} : \max_{\chi} | (\chi_{t}, Q_{b}) - f(\chi_{t})| \leq \varepsilon. \\ \text{Then } H_{e} \quad elimination \quad a_{t} \int_{s_{t}}^{T} f(\chi_{t}) - f(\chi_{e}) \right] \leq d \sqrt{Thy} \left[\chi_{t} \right] + T d\sqrt{\varepsilon}. \end{array}$$

Suppose we have some algorithm that pulls arms
$$\pi_1, \pi_2, \dots$$

and it has how regrels $\sum_{t=1}^{T} \langle \pi_t - \pi_{t-1} \partial_t \rangle \leq R_T$
Then if I choose $3 = \min(\{\pi_t, \pi_t\})$ then
 $\mathbb{E}[\langle \pi_t, -\pi_t, \partial_t \rangle] \leq \frac{R_T}{T}$
"opline to batch conversion.

$$\frac{Proof}{E[\langle X_{A} - X_{3}, \partial_{\mu} \rangle]} = \sum_{\epsilon} P(3=\epsilon) \langle X_{\epsilon} - X_{\epsilon}, \partial_{\mu} \rangle$$

$$= \frac{1}{T} \sum_{\epsilon=1}^{T} \langle X_{\epsilon} - X_{\epsilon}, \partial_{\mu} \rangle$$

$$= \frac{R_{T}}{T}$$
We say XEX is E-good if $\langle X_{A} - X, \partial_{\mu} \rangle \leq \mathcal{E}$.
$$\Longrightarrow E \lim_{\epsilon \to \infty} |VCB| \quad \text{can find} \quad \mathcal{E} - good \quad \text{arm} \quad (\text{in expectation})$$
after is $\mathcal{E} - \frac{d|\partial_{\mu}|X|}{\Delta} d^{2}$

$$\int \Delta^2 v \mathcal{E}^2 \qquad \Delta = \min_{x \neq x_p} \langle x_p - x_p \rangle$$

 $min = \Lambda \equiv \Pi \equiv \chi Y$ $max = V \equiv U \equiv \chi + Y$

If Grophinal design then constructed LS estimator, then once

$$T \ge \frac{d\log|X| \wedge d^2}{\Delta^2 \vee \varepsilon^2}$$
, agree $\langle X, \hat{\Theta} \rangle$ is ε -good w.h.p.

Best arm identitication for Linear Bandits.
Soare et 2014 example:

$$0: \pi_2 is best$$

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 $1 \neq x$
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 $1 \neq x$
 $1 \neq$