**Computer-Aided Reasoning for Software** 

# **Practical Applications of SAT**

# Today

#### **Past 2 lectures**

• The theory and mechanics of SAT solving

#### Today

- Practical applications of SAT
- Variants of the SAT problem
- Motivating the next lecture on SMT

# A brief history of SAT solving and applications



# Bounded Model Checking (BMC) & Configuration Management

# **Bounded Model Checking (in general)**

Given a system and a property, BMC checks if the property is satisfied by all executions of the system with  $\leq$ k steps, on all inputs of size  $\leq$ n.

We will focus on **safety properties** (i.e., making sure a bad state, such as an assertion violation, is not reached).

### **Bounded Model Checking (in general)**



# **BMC by example**



# **BMC** by example

```
int daysToYear(int days) {
  int year = 1980;
  while (days > 365) {
    int oldDays = days;
    if (isLeapYear(year)) {
      if (days > 366) {
        days -= 366;
        year += 1;
      }
    } else {
      days -= 365;
      year += 1;
    }
    assert days < oldDays;</pre>
  }
  return year;
}
```

#### **The Zune Bug:** on December 31, 2008, all first generation Zune players from Microsoft became unresponsive because of this code. What's

Infinite loop triggered on the last day of every leap year.

wrong?

A desired safety property: the value of the days variable decreases in every loop iteration.

# **BMC** step I of 4: finitize loops

```
int daysToYear(int days) {
  int year = 1980;
  if (days > 365) {
    int oldDays = days;
    if (isLeapYear(year)) {
      if (days > 366) {
        days -= 366;
        year += 1;
      }
    } else {
      days -= 365;
      year += 1;
    }
    assert days < oldDays;</pre>
    assert days <= 365;</pre>
  return year;
}
```

- Unwind all loops k times (e.g., k=1), and add an unwinding assertion at the end.
- If a CEX violates a program assertion, we have found a buggy behavior of length ≤k.
- If a CEX violates an unwinding assertion, the program has no buggy behavior of length ≤k, but it may have a longer one.
- If there is no CEX, the program is correct for all k!

### BMC step I of 4: finitize loops & inline calls

```
int daysToYear(int days) {
  int year = 1980;
  if (days > 365) {
    int oldDays = days;
    if (isLeapYear(year)) {
      if (days > 366) {
        days -= 366;
        year += 1;
      }
    } else {
      days -= 365;
      year += 1;
    }
    assert days < oldDays;</pre>
    assert days <= 365;</pre>
  }
  return year;
}
```

Assume call to isLeapYear is inlined (replaced with the procedure body). We'll keep it for readability.

```
int daysToYear(int days) {
  int year = 1980;
  if (days > 365) {
    int oldDays = days;
    if (isLeapYear(year)) {
      if (days > 366) {
        days -= 366;
        year += 1;
      }
    } else {
      days -= 365;
      year += 1;
    }
    assert days < oldDays;</pre>
    assert days <= 365;</pre>
  }
  return year;
}
```

```
int days;
int year = 1980;
if (days > 365) {
  int oldDays = days;
  if (isLeapYear(year)) {
    if (days > 366) {
      days = days - 366;
      year = year + 1;
    }
  } else {
    days = days - 365;
   year = year + 1;
  }
  assert days < oldDays;</pre>
  assert days <= 365;</pre>
return year;
```

Convert to **Static Single Assignment** (SSA) form:

```
int days<sub>0</sub>;
int year<sub>0</sub> = 1980;
if (days<sub>0</sub> > 365) {
   int oldDays<sub>0</sub> = days<sub>0</sub>;
   if (isLeapYear(year<sub>0</sub>)) {
      if (days<sub>0</sub> > 366) {
         days_1 = days_0 - 366;
         year_1 = year_0 + 1;
      }
   } else {
      days_3 = days_0 - 365;
      year_3 = year_0 + 1;
   }
   assert days<sub>4</sub> < oldDays<sub>0</sub>;
   assert days<sub>4</sub> <= 365;</pre>
return year<sub>5</sub>;
```

#### Convert to **Static Single Assignment** (SSA) form:

- Replace each assignment to a variable v with a definition of a fresh variable v<sub>i</sub>.
- Change uses of variables so that they refer to the correct definition (version).

```
int days<sub>0</sub>;
int year<sub>0</sub> = 1980;
boolean g_0 = (days_0 > 365);
int oldDays<sub>0</sub> = days<sub>0</sub>;
boolean g_1 = isLeapYear(year_0);
boolean g_2 = days_0 > 366;
days_1 = days_0 - 366;
year_1 = year_0 + 1;
days_2 = \varphi(g_1 \& g_2, days_1, days_0); \blacktriangleleft
year<sub>2</sub> = \varphi(g_1 \& g_2, year_1, year_0);
days_3 = days_0 - 365;
year_3 = year_0 + 1;
days<sub>4</sub> = \varphi(g_1, days_2, days_3);
year<sub>4</sub> = \varphi(g_1, year_2, year_3);
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days<sub>4</sub> <= 365;</pre>
year<sub>5</sub> = \varphi(g_0, year_4, year_0);
return year5;
```

#### Convert to **Static Single Assignment** (SSA) form:

- Replace each assignment to a variable v with a definition of a fresh variable v<sub>i</sub>.
- Change uses of variables so that they refer to the correct definition (version).
- Make conditional dependences explicit with gated φ nodes.

```
int days<sub>0</sub>;
int year<sub>0</sub> = 1980;
boolean g_0 = (days_0 > 365);
int oldDays<sub>0</sub> = days<sub>0</sub>;
boolean g_1 = isLeapYear(year_0);
boolean g_2 = days_0 > 366;
days_1 = days_0 - 366;
year_1 = year_0 + 1;
days_2 = \varphi(g_1 \& g_2, days_1, days_0);
year<sub>2</sub> = \varphi(g_1 \& g_2, year_1, year_0);
days_3 = days_0 - 365;
year_3 = year_0 + 1;
days<sub>4</sub> = \varphi(g_1, days_2, days_3);
year<sub>4</sub> = \varphi(g_1, year_2, year_3);
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days<sub>4</sub> <= 365;</pre>
year<sub>5</sub> = \varphi(g_0, year_4, year_0);
return year5;
```

```
int days<sub>0</sub>;
int year<sub>0</sub> = 1980;
if (days<sub>0</sub> > 365) {
   int oldDays<sub>0</sub> = days<sub>0</sub>;
   if (isLeapYear(year<sub>0</sub>)) {
      if (days<sub>0</sub> > 366) {
         days_1 = days_0 - 366;
         year_1 = year_0 + 1;
      }
   } else {
      days_3 = days_0 - 365;
      year_3 = year_0 + 1;
   }
   assert days<sub>4</sub> < oldDays<sub>0</sub>;
   assert days4 <= 365;</pre>
}
return year<sub>5</sub>;
```

```
int days<sub>0</sub>;
int year<sub>0</sub> = 1980;
boolean g_0 = (days_0 > 365);
int oldDays<sub>0</sub> = days<sub>0</sub>;
boolean g_1 = isLeapYear(year_0);
boolean g_2 = days_0 > 366;
days_1 = days_0 - 366;
year_1 = year_0 + 1;
days<sub>2</sub> = \varphi(g_1 \& g_2, days_1, days_0);
year<sub>2</sub> = \varphi(g_1 \& \& g_2, year_1, year_0);
days_3 = days_0 - 365;
year_3 = year_0 + 1;
days<sub>4</sub> = \varphi(g_1, days_2, days_3);
year<sub>4</sub> = \varphi(g_1, year_2, year_3);
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days<sub>4</sub> <= 365;</pre>
year<sub>5</sub> = \varphi(g_0, year_4, year_0);
return year<sub>5</sub>;
```

We can now read off the equations that encode the program semantics, and the assertions to be checked.

```
int year<sub>0</sub> = 1980;
boolean g_0 = (days_0 > 365);
int oldDays<sub>0</sub> = days<sub>0</sub>;
boolean g_1 = isLeapYear(year_0);
boolean g_2 = days_0 > 366;
days_1 = days_0 - 366;
year_1 = year_0 + 1;
days<sub>2</sub> = \varphi(g_1 \& g_2, days_1, days_0);
year<sub>2</sub> = \varphi(g_1 \& \& g_2, year_1, year_0);
days_3 = days_0 - 365;
year_3 = year_0 + 1;
days<sub>4</sub> = \varphi(g_1, days_2, days_3);
year<sub>4</sub> = \varphi(g_1, year_2, year_3);
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days4 <= 365;</pre>
```

```
year_0 = 1980;
g_0 = (days_0 > 365);
oldDays_0 = days_0;
g_1 = isLeapYear(year_0);
g_2 = days_0 > 366;
days_1 = days_0 - 366;
year_1 = year_0 + 1;
days<sub>2</sub> = \varphi(g_1 \& g_2, days_1, days_0);
year<sub>2</sub> = \varphi(g_1 \& \& g_2, year_1, year_0);
days_3 = days_0 - 365;
year_3 = year_0 + 1;
days<sub>4</sub> = \varphi(g_1, days_2, days_3);
year<sub>4</sub> = \varphi(g_1, year_2, year_3);
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days4 <= 365;</pre>
```

```
year_0 = 1980 \land
g_0 = (days_0 > 365) \wedge
oldDays_0 = days_0 \land
q_1 = isLeapYear(year_0) \land
g_2 = days_0 > 366 \land
days_1 = days_0 - 366 \land
year_1 = year_0 + 1 \land
days<sub>2</sub> = \varphi(g_1 \land g_2, days_1, days_0) \land
year<sub>2</sub> = \varphi(g_1 \land g_2, year_1, year_0) \land
days_3 = days_0 - 365 \land
year_3 = year_0 + 1 \land
days<sub>4</sub> = \varphi(g_1, days_2, days_3) \wedge
year<sub>4</sub> = \varphi(g_1, year_2, year_3) \wedge
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days4 <= 365;</pre>
```

```
year_0 = 1980 \land
g_0 = (days_0 > 365) \wedge
oldDays_0 = days_0 \land
q_1 = isLeapYear(year_0) \land
g_2 = days_0 > 366 \land
days_1 = days_0 - 366 \land
year_1 = year_0 + 1 \land
days<sub>2</sub> = ite(g_1 \land g_2, days<sub>1</sub>, days<sub>0</sub>) \land
year<sub>2</sub> = ite(g_1 \land g_2, year<sub>1</sub>, year<sub>0</sub>) \land
days_3 = days_0 - 365 \land
year_3 = year_0 + 1 \land
days<sub>4</sub> = ite(g_1, days<sub>2</sub>, days<sub>3</sub>) \wedge
year<sub>4</sub> = ite(g_1, year<sub>2</sub>, year<sub>3</sub>) \wedge
assert days<sub>4</sub> < oldDays<sub>0</sub>;
assert days4 <= 365;</pre>
```

```
year_0 = 1980 \land
g_0 = (days_0 > 365) \wedge
oldDays_0 = days_0 \land
g_1 = isLeapYear(year_0) \land
g_2 = days_0 > 366 \land
days_1 = days_0 - 366 \land
year_1 = year_0 + 1 \land
days<sub>2</sub> = ite(g_1 \land g_2, days<sub>1</sub>, days<sub>0</sub>) \land
year<sub>2</sub> = ite(g_1 \land g_2, year<sub>1</sub>, year<sub>0</sub>) \land
days_3 = days_0 - 365 \land
year_3 = year_0 + 1 \land
days<sub>4</sub> = ite(g_1, days<sub>2</sub>, days<sub>3</sub>) \wedge
year<sub>4</sub> = ite(g_1, year<sub>2</sub>, year<sub>3</sub>) \wedge
(\neg(days_4 < oldDays_0) \lor
 ¬(days<sub>4</sub> <= 365))
```

We can now read off the equations that encode the program semantics, and the assertions to be checked.

A solution to this formula is a sound counterexample: an interpretation for all logical variables that satisfies the program semantics (for up to k unwindings) but violates at least one of the assertions.

### **BMC** step 4 of 4: convert into CNF



#### **BMC** counterexample for k=I

```
int daysToYear(int days) {-
                                   days = 366
  int year = 1980;
 while (days > 365) {
    if (isLeapYear(year)) {
      if (days > 366) {
        days -= 366;
       year += 1;
      }
    } else {
      days -= 365;
      year += 1;
    }
  }
  return year;
}
```

# Bounded Model Checking (BMC) & Configuration Management

# **Configuration Management**

Given a configuration, consisting of a set of components, their dependencies, and conflicts:

- Decide if a new component can be added to the configuration.
- Add the component while optimizing some linear function.
- If the component cannot be added, find a way to add it by removing as few conflicting components from the current configuration as possible.



# Deciding if a component can be installed



To install a, CNF constraints are:  $(\neg a \lor b) \land (\neg a \lor c) \land (\neg a \lor z) \land$   $(\neg b \lor d) \land$   $(\neg c \lor d \lor e) \land (\neg c \lor f \lor g) \land$   $(\neg d \lor \neg e) \land$   $(\neg y \lor z) \land$  $a \land z$ 

Conflict: d and e cannot both be installed.

### **Optimal installation**



Assume f and g are 5MB and 2MB each, and all other components are IMB. How to install a, while minimizing total size?

$$\begin{array}{l} (\neg a \lor b) \land (\neg a \lor c) \land (\neg a \lor z) \land \\ (\neg b \lor d) \land \\ (\neg c \lor d \lor e) \land (\neg c \lor f \lor g) \land \\ (\neg d \lor \neg e) \land \\ (\neg y \lor z) \land \\ a \land z \end{array}$$

### **Optimal installation**



Assume f and g are 5MB and 2MB each, and all other components are IMB. How to install a, while minimizing total size? Pseudo-boolean solvers accept a linear function to minimize, in addition to a (weighted) CNF.

 $\min_{a_{1}|x_{1}| + \dots + a_{ln}x_{n} \ge b_{1} \land \dots \land \\ a_{k_{1}|x_{1}| + \dots + a_{k_{n}}x_{n} \ge b_{k}$ 

$$\begin{array}{l} (\neg a \lor b) \land (\neg a \lor c) \land (\neg a \lor z) \land \\ (\neg b \lor d) \land \\ (\neg c \lor d \lor e) \land (\neg c \lor f \lor g) \land \\ (\neg d \lor \neg e) \land \\ (\neg y \lor z) \land \\ a \land z \end{array}$$

### **Optimal installation**



Assume f and g are 5MB and 2MB each, and all other components are IMB. How to install a, while minimizing total size? Pseudo-boolean solvers accept a linear function to minimize, in addition to a (weighted) CNF.

min 
$$a + b + c + d + e + 5f + 2g + y + 0z$$
  
 $(-a + b \ge 0) \land (-a + c \ge 0) \land (-a + z \ge 0) \land$   
 $(-b + d \ge 0) \land$   
 $(-c + d + e \ge 0) \land (-c + f + g \ge 0) \land$   
 $(-d + -e \ge -1) \land$   
 $(-y + z \ge 0) \land$   
 $(a \ge 1) \land (z \ge 1)$ 

### Installation in the presence of conflicts



a cannot be installed because it requires b, which requires d, which conflicts with e. Partial MaxSAT solver takes as input a set of **hard** clauses and a set of **soft** clauses, and it produces an assignment that satisfies all hard clauses and the greatest number of soft clauses.

To install a, while minimizing the number of removed components, Partial MaxSAT constraints are:

hard:  $(\neg a \lor b) \land (\neg a \lor c) \land (\neg a \lor z) \land$  $(\neg b \lor d) \land$  $(\neg c \lor d \lor e) \land (\neg c \lor f \lor g) \land$  $(\neg d \lor \neg e) \land (\neg y \lor z) \land a$ 

**soft:**  $e \wedge z$ 

# Summary

#### Today

- SAT solvers have been used successfully in many applications & domains
- But reducing problems to SAT is a lot like programming in assembly ...
- We need higher-level logics!

#### **Next lecture**

• On to richer logics: introduction to Satisfiability Modulo Theories (SMT)