

Computer-Aided Reasoning for Software

# **Solver-Aided Programming II**

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# Topics

## Last lecture

- Getting started with solver-aided programming.

## Today

- Going pro with solver-aided programming.

## Announcements

- HW1 is out.

A programming model that integrates solvers into the language, providing constructs for program verification, synthesis, and more.

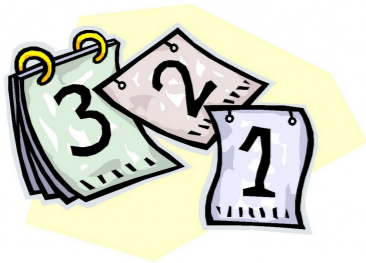
**ROSETTE**

**Solver-aided programming in two parts:**  
**(1) getting started and (2) going pro**

How to use a solver-aided language: the workflow, constructs, and gotchas.

How to build your own solver-aided tool via direct symbolic evaluation or language embedding.

# How to build your own solver-aided tool or language

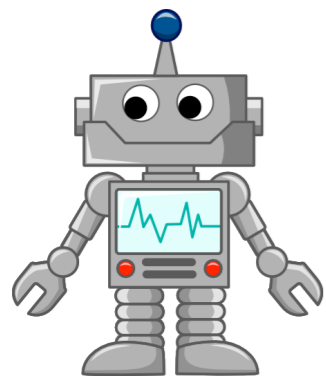


**SDSL**



**SVM**

**SMT**



## **The classic (hard) way to build a tool**

What is hard about building a solver-aided tool?

## **An easier way: tools as languages**

How to build tools by stacking layers of languages.

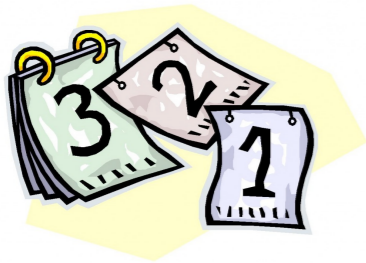
## **Behind the scenes: symbolic virtual machine**

How Rosette works so you don't have to.

## **A last look: a few recent applications**

Cool tools built with Rosette!

# How to build your own solver-aided tool or language

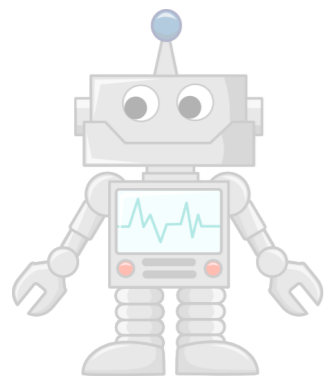


SDSL



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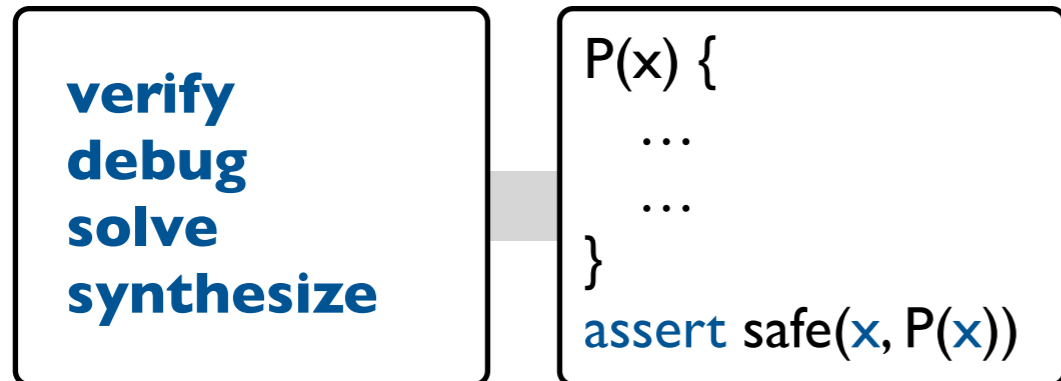
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# The classic (hard) way to build a tool

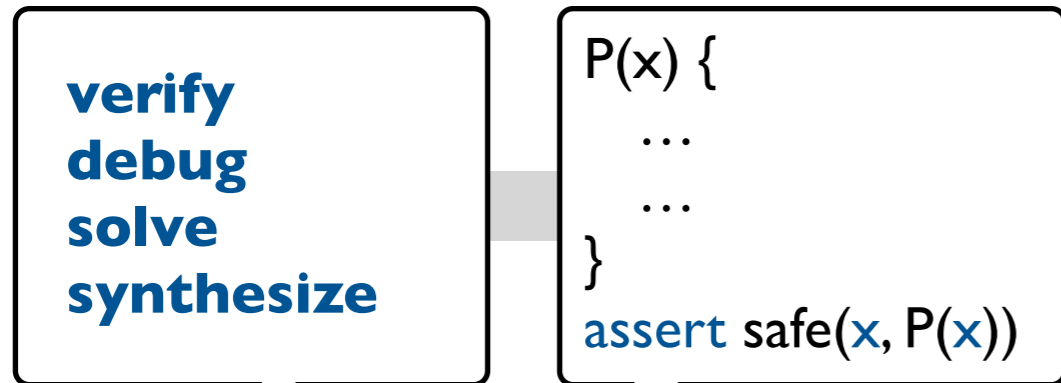


Recall the solver-aided programming tool chain: the tool reduces a query about program behavior to an SMT problem.



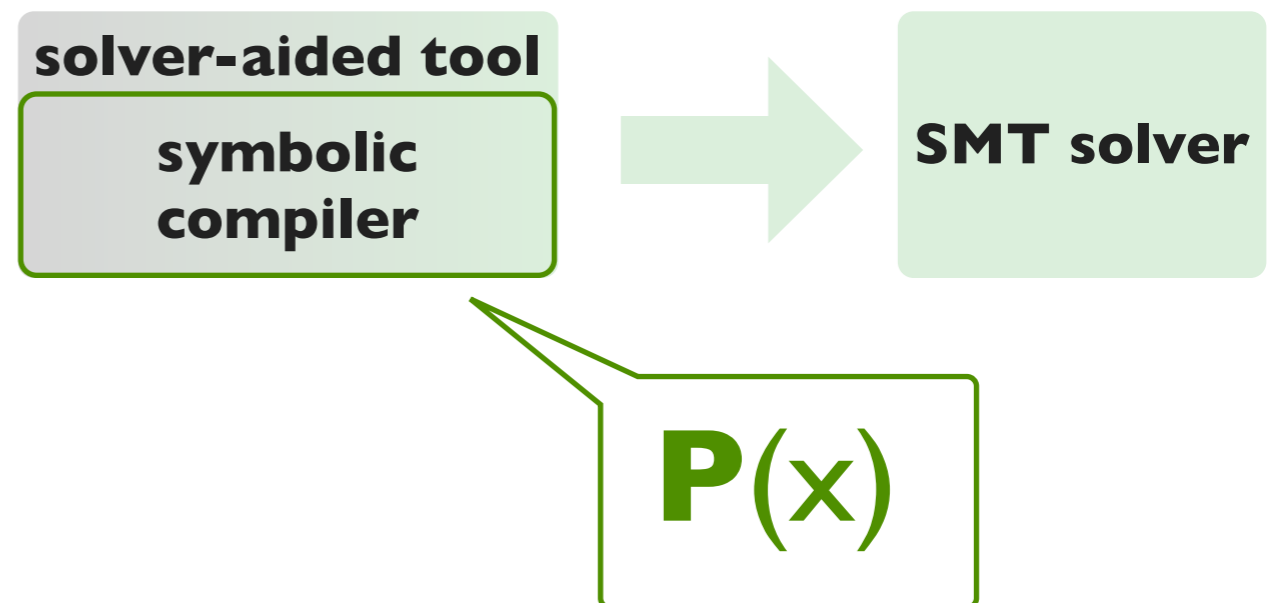
$\exists x . \neg \mathbf{safe}(x, \mathbf{P}(x))$   
 $x = 42 \wedge \mathbf{safe}(x, \mathbf{P}(x))$   
 $\exists v . \mathbf{safe}(42, \mathbf{P}_v(42))$   
 $\exists e . \forall x . \mathbf{safe}(x, \mathbf{P}_e(x))$

# The classic (hard) way to build a tool

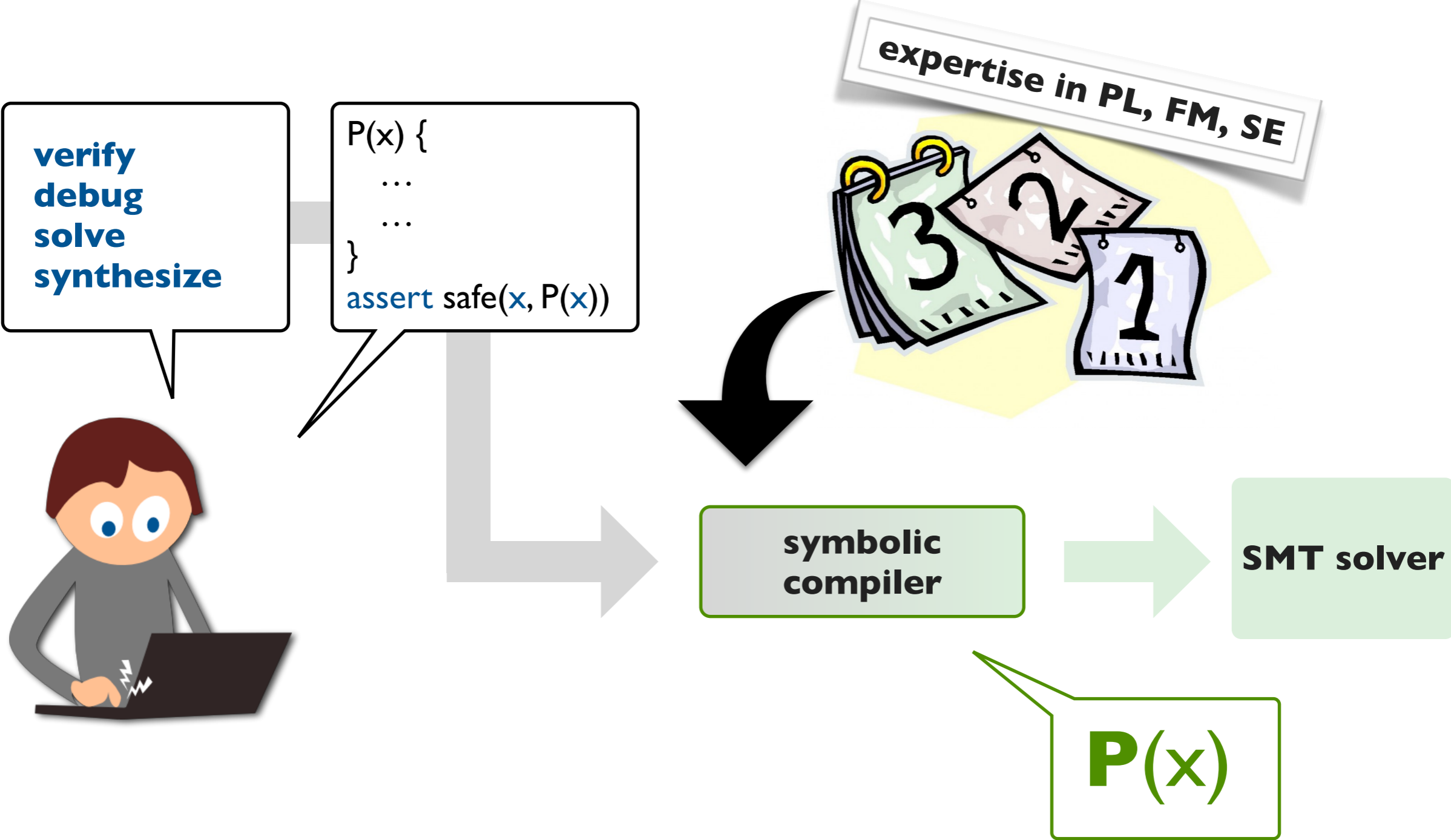


Recall the solver-aided programming tool chain: the tool reduces a query about program behavior to an SMT problem.

What all queries have in common: they need to translate programs to constraints!

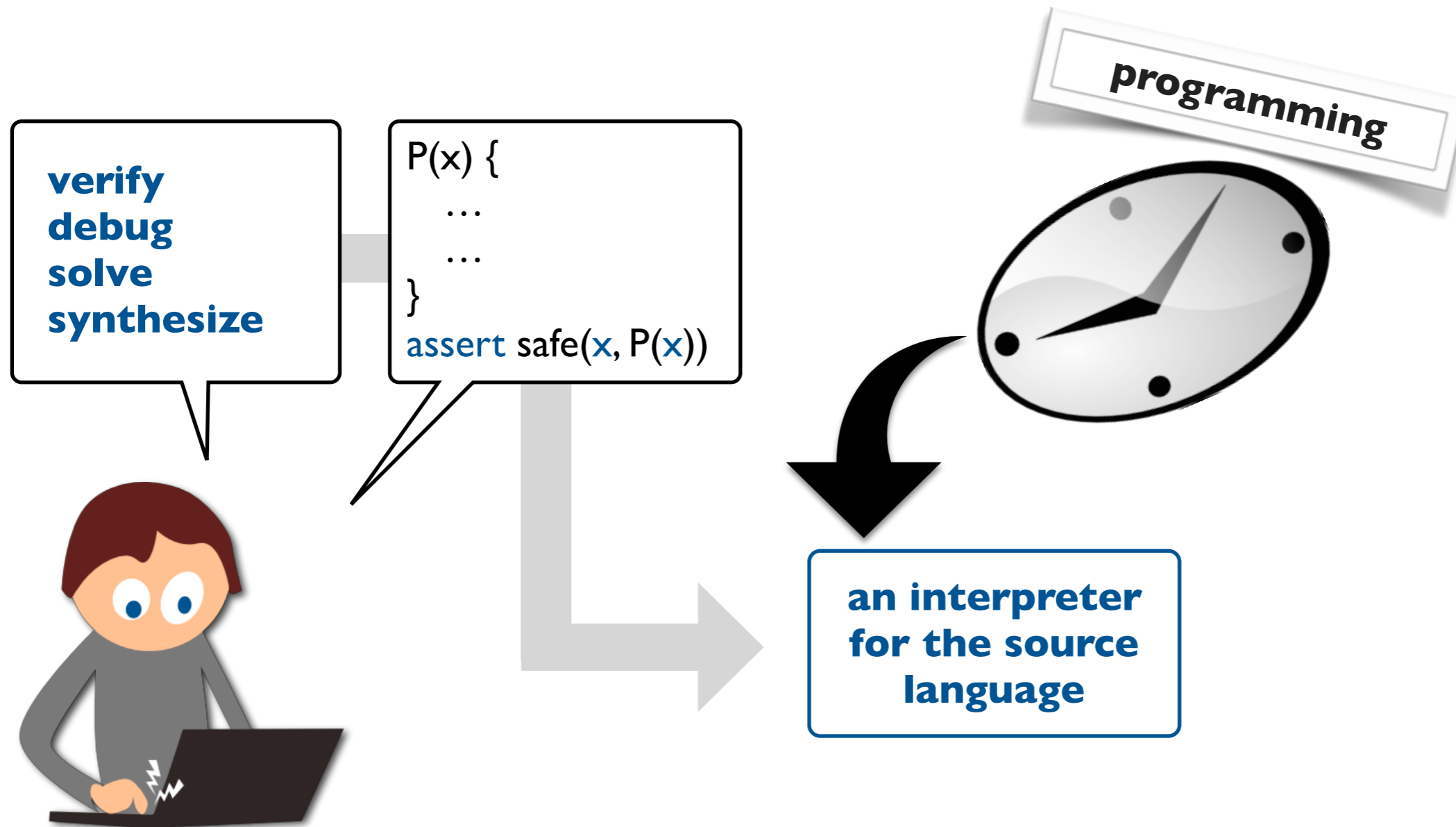


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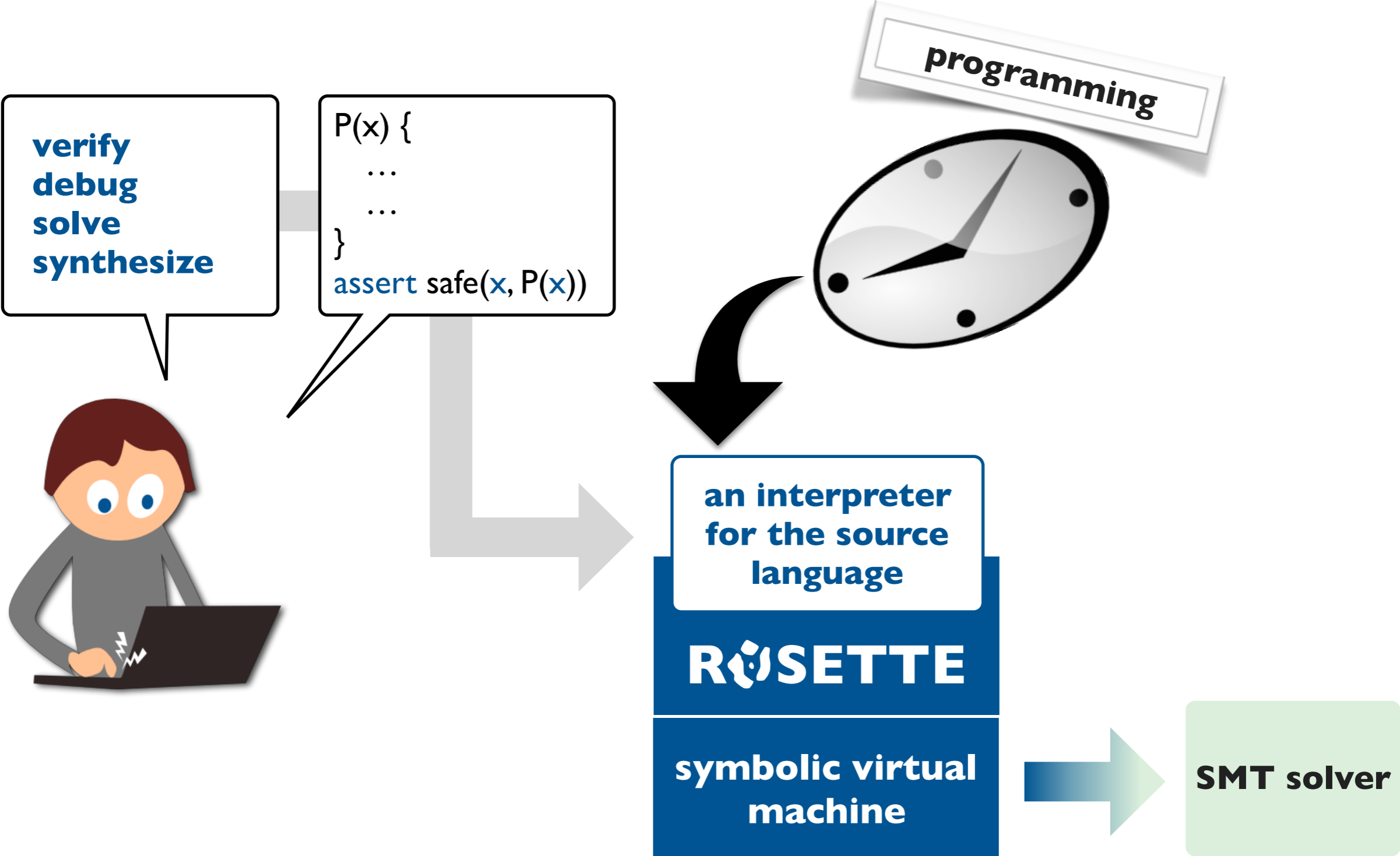




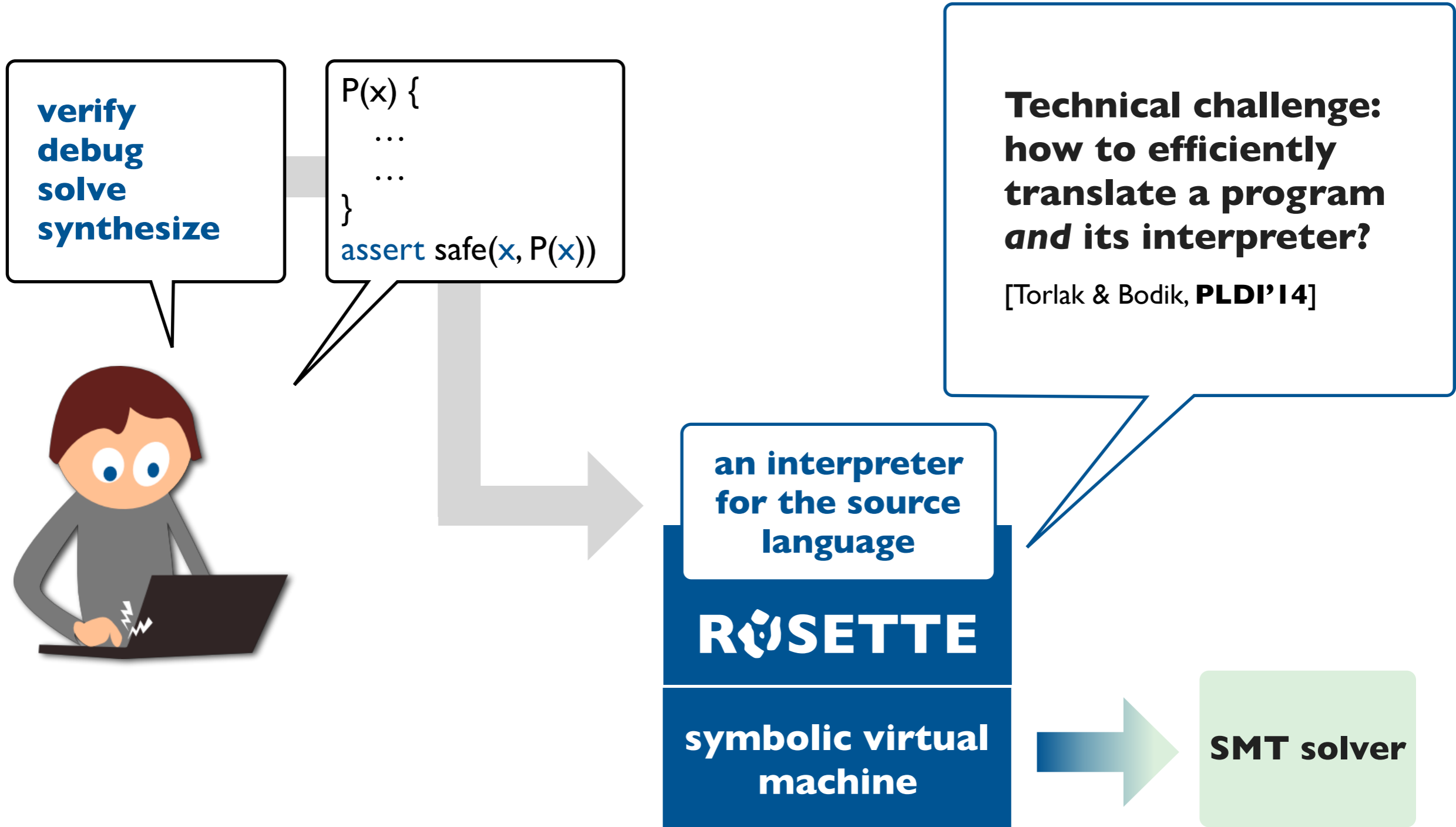
# Wanted: an easier way to build tools



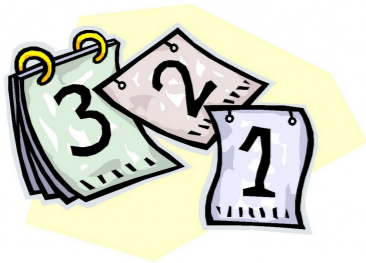
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# How to build your own solver-aided tool or language

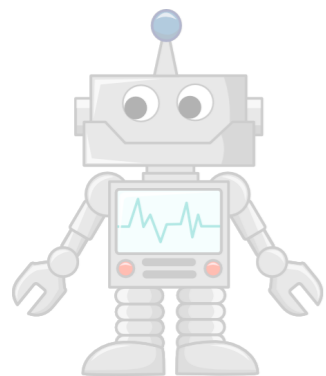


**SDSL**



**SVM**

**SMT**



## **The classic (hard) way to build a tool**

What is hard about building a solver-aided tool?

## **An easier way: tools as languages**

How to build tools by stacking layers of languages.

## **Behind the scenes: symbolic virtual machine**

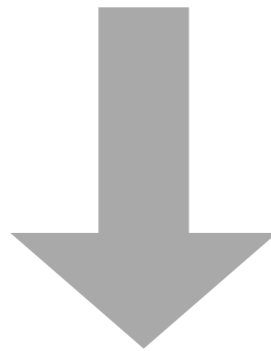
How Rosette works so you don't have to.

## **A last look: a few recent applications**

Cool tools built with Rosette!

# Layers of classic languages: DSLs and hosts

**domain-specific language  
(DSL)**



**host language**

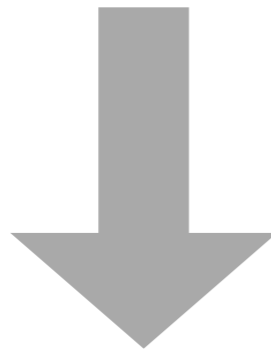
A formal language that is specialized to a particular application domain and often limited in capability.

A high-level language for implementing DSLs, usually with meta-programming features.

# Layers of classic languages: DSLs and hosts

**domain-specific language  
(DSL)**

library  
(*shallow*)  
embedding



interpreter  
(*deep*)  
embedding

**host language**

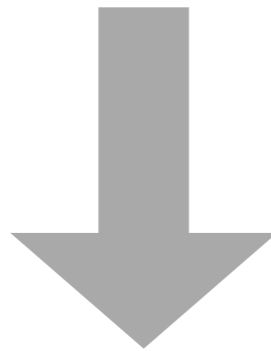
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# Layers of classic languages: many DSLs and hosts

**domain-specific language  
(DSL)**

library  
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interpreter  
(*deep*)  
embedding

**host language**

**artificial intelligence**

Church, BLOG

**databases**

SQL, Datalog

**hardware design**

Bluespec, Chisel, Verilog, VHDL

**math and statistics**

Eigen, Matlab, R

**layout and visualization**

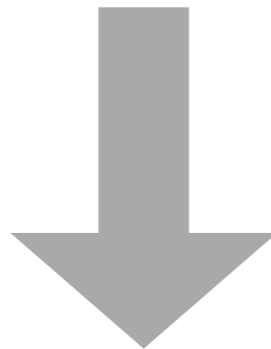
LaTeX, dot, dygraphs, D3

Racket, Scala, JavaScript, ...

# Layers of classic languages: why DSLs?

**domain-specific language  
(DSL)**

library  
(*shallow*)  
embedding



interpreter  
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**host language**

Eigen / Matlab  
 $C = A * B$

C / Java  

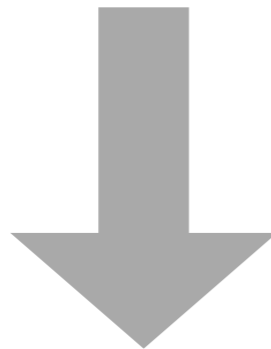
```
for (i = 0; i < n; i++)  
  for (j = 0; j < m; j++)  
    for (k = 0; k < p; k++)  
      C[i][k] += A[i][j] * B[j][k]
```



# Layers of classic languages: why DSLs?

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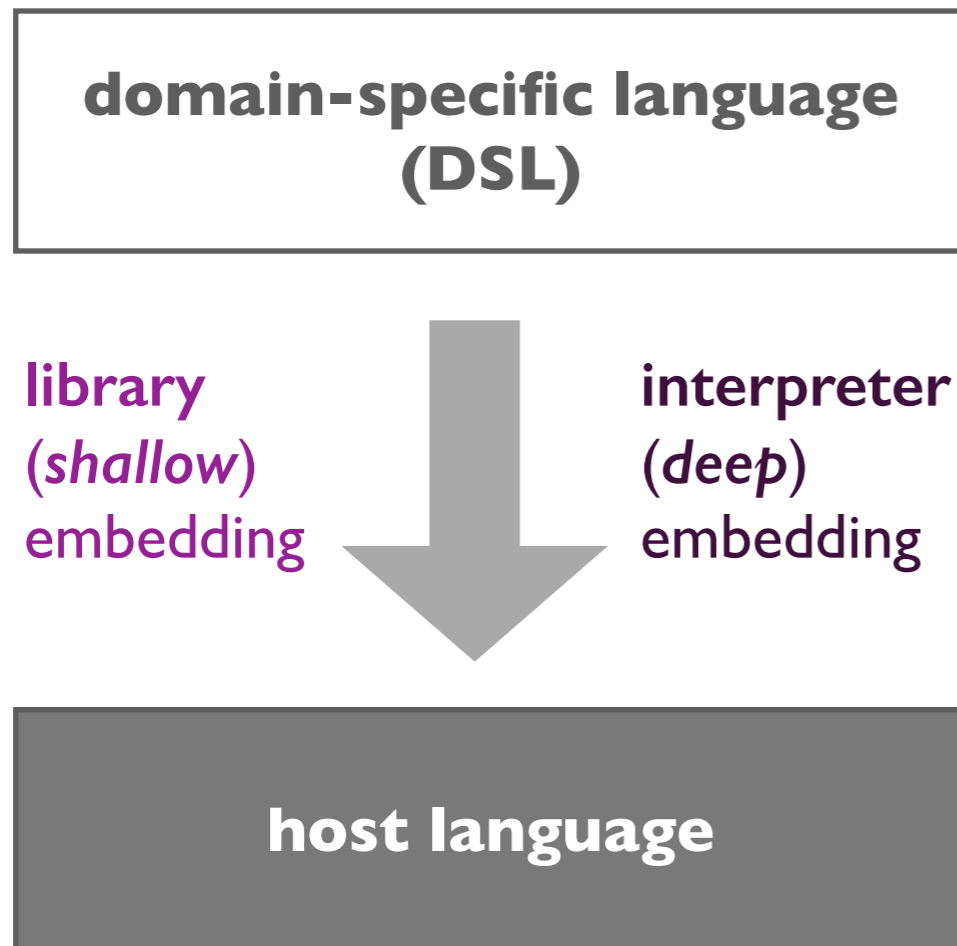
**host language**

Easier for people to read,  
write, and get right.

`C = A * B` Eigen / Matlab

`for (i = 0; i < n; i++)  
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 C[i][k] += A[i][j] * B[j][k]` C / Java

# Layers of classic languages: why DSLs?



Easier for people to read, write, and get right.

`C = A * B` Eigen / Matlab  
[associativity]

Easier for tools to analyze.

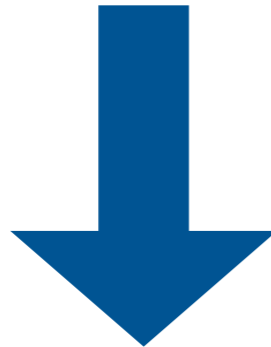
`C / Java`  

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# Layers of solver-aided languages

**solver-aided domain-specific language (SDSL)**

library  
(*shallow*)  
embedding



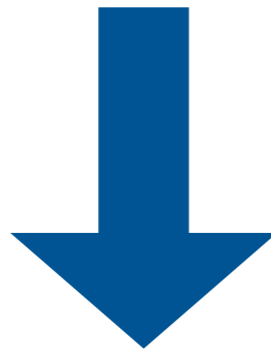
interpreter  
(*deep*)  
embedding

**solver-aided host language**

# Layers of solver-aided languages: tools as SDSLs

**solver-aided domain-specific language (SDSL)**

library  
(*shallow*)  
embedding



interpreter  
(*deep*)  
embedding

**ROSETTE**

## **education and games**

Enlearn, RuleSy (VMCAI'18),  
Nonograms (FDG'17), UCB feedback  
generator (ITiCSE'17)

## **synthesis-aided compilation**

LinkiTools, Chlorophyll (PLDI'14),  
GreenThumb (ASPLOS'16)

## **type system soundness**

Bonsai (POPL'18)

## **computer architecture**

MemSynth (PLDI'17)

## **databases**

Cosette (CIDR'17)

## **radiation therapy control**

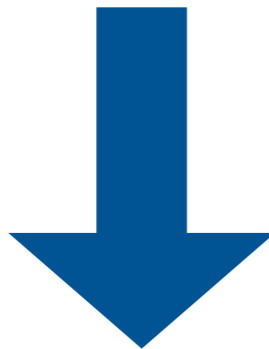
Neutrons (CAV'16)

**... and more**

# Layers of solver-aided languages: tools as SDSLs

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**... and more**

# A tiny example SDSL

```
def bvmax(r0, r1) :  
    r2 = bvsge(r0, r1)  
    r3 = bvneg(r2)  
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return r6
```

**BV**: A tiny assembly-like language for writing fast, low-level library functions.

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We want to **test, verify, debug,** and **synthesize** programs in the BV SDSL.

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```

We want to **test, verify, debug,** and **synthesize** programs in the BV SDSL.

**BV:** A tiny assembly-like language for writing fast, low-level library functions.

1. interpreter [10 LOC]
2. verifier [free]
3. debugger [free]
4. synthesizer [free]



# A tiny example SDSL



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```
> bvmax(-2, -1)
```

# A tiny example SDSL

RÖSETTE

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parse

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(out opcode in ...)

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**interpret**

# ROSETTE

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```
`(-2 -1)
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- ▶ pattern matching
- ▶ dynamic evaluation
- ▶ first-class & higher-order procedures
- ▶ side effects

```
(define (interpret prog inputs)  
  (make-registers prog inputs)  
  (for ([stmt prog])  
    (match stmt  
      [(list out opcode in ...)   
       (define op (eval opcode))  
       (define args (map load in))  
       (store out (apply op args))]))  
  (load (last)))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> verify(bvmax, max)
```

**query**

# R<sup>o</sup>SETTE

```
(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> verify(bvmax, max)
```

query

ROSETTE

Creates two fresh symbolic values of type 32-bit integer and binds them to the variables x and y.

```
(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
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  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> verify(bvmax, max)
```

query

# ROSETTE

Creates two fresh symbolic values of type 32-bit integer and binds them to the variables x and y.

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(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

Symbolic values can be used just like concrete values of the same type.

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> verify(bvmax, max)
```

query

Creates two fresh symbolic values of type 32-bit integer and binds them to the variables *x* and *y*.

```
(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

(*verify expr*) searches for a concrete interpretation of symbolic values that causes *expr* to fail.

Symbolic values can be used just like concrete values of the same type.



# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
return r6
```

```
> verify(bvmax, max)  
[0, -2]
```



query

R<sup>0</sup>SETTE

```
(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
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  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> verify(bvmax, max)  
[0, -2]
```

```
> bvmax(0, -2)  
-1
```



R<sup>0</sup>SETTE

```
(define-symbolic x y int32?)  
(define in (list x y))  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

ROSETTE

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
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  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> debug(bvmax, max, [0, -2])
```

query

```
(define in (list (int32 0) (int32 -2)))  
(debug [register?]  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

RÔSETTE

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> debug(bvmax, max, [0, -2])
```

query



```
(define in (list (int32 0) (int32 -2)))  
(debug [register?]  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(??, ??)  
  r5 = bvand(r3, ??)  
  r6 = bvxor(??, ??)  
  return r6  
  
> synthesize(bvmax, max)
```

query

ROSETTE

```
(define-symbolic x y int32?)  
(define in (list x y))  
(synthesize  
  #:forall in  
  #:guarantee  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))))
```

# A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r1)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> synthesize(bvmax, max)
```

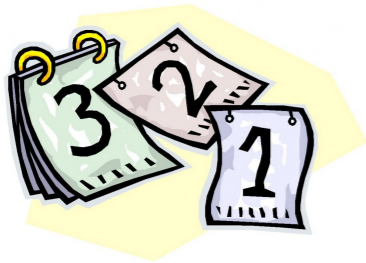


**query**

ROSETTE

```
(define-symbolic x y int32?)  
(define in (list x y))  
(synthesize  
  #:forall in  
  #:guarantee  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))))
```

# How to build your own solver-aided tool or language

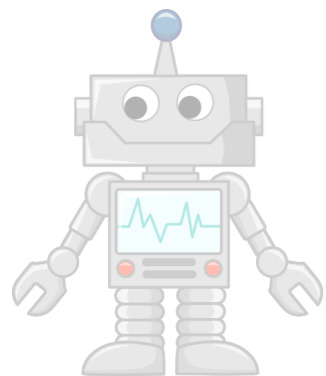


**SDSL**



**SVM**

**SMT**



## **The classic (hard) way to build a tool**

What is hard about building a solver-aided tool?

## **An easier way: tools as languages**

How to build tools by stacking layers of languages.

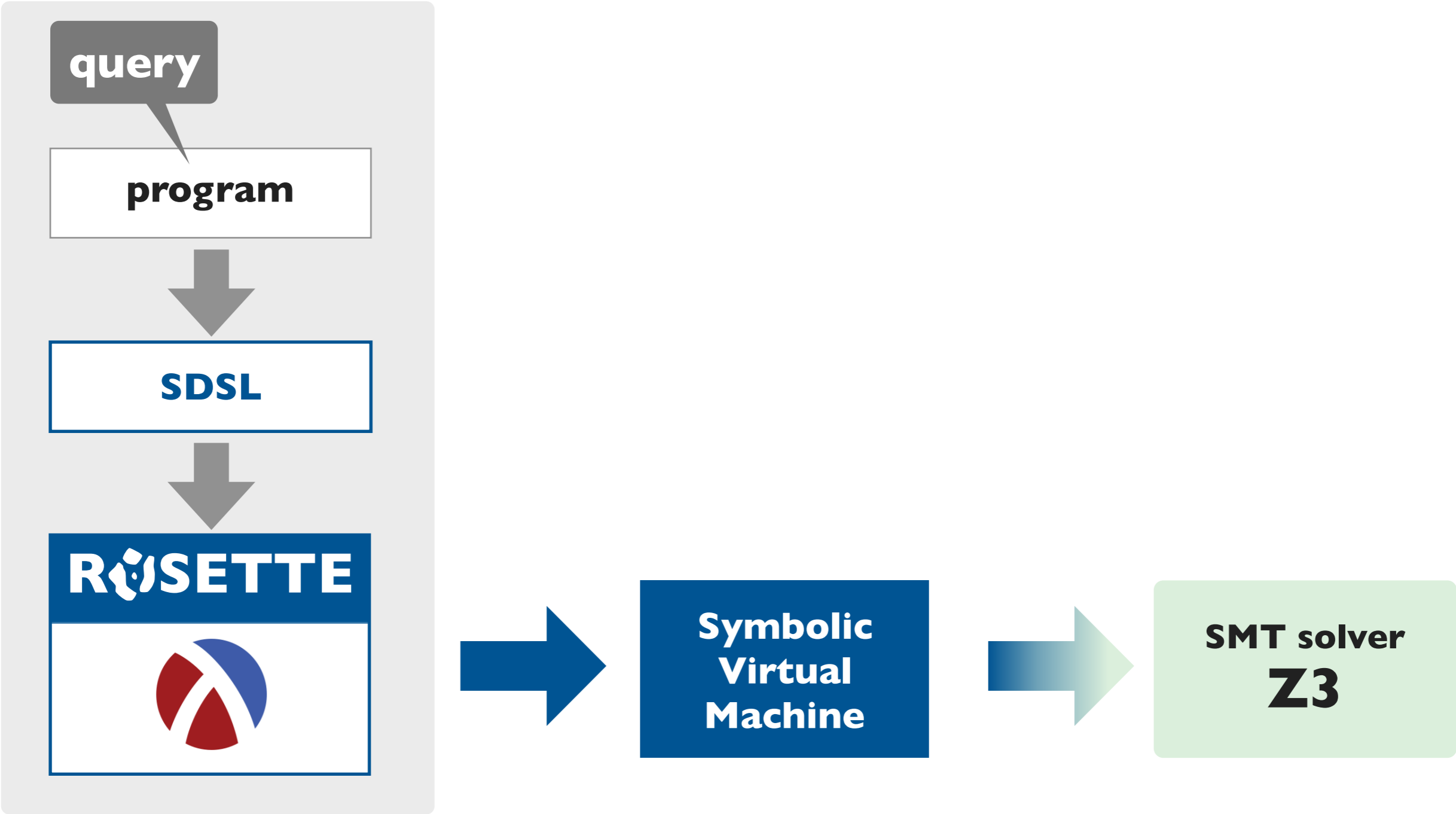
## **Behind the scenes: symbolic virtual machine**

How Rosette works so you don't have to.

## **A last look: a few recent applications**

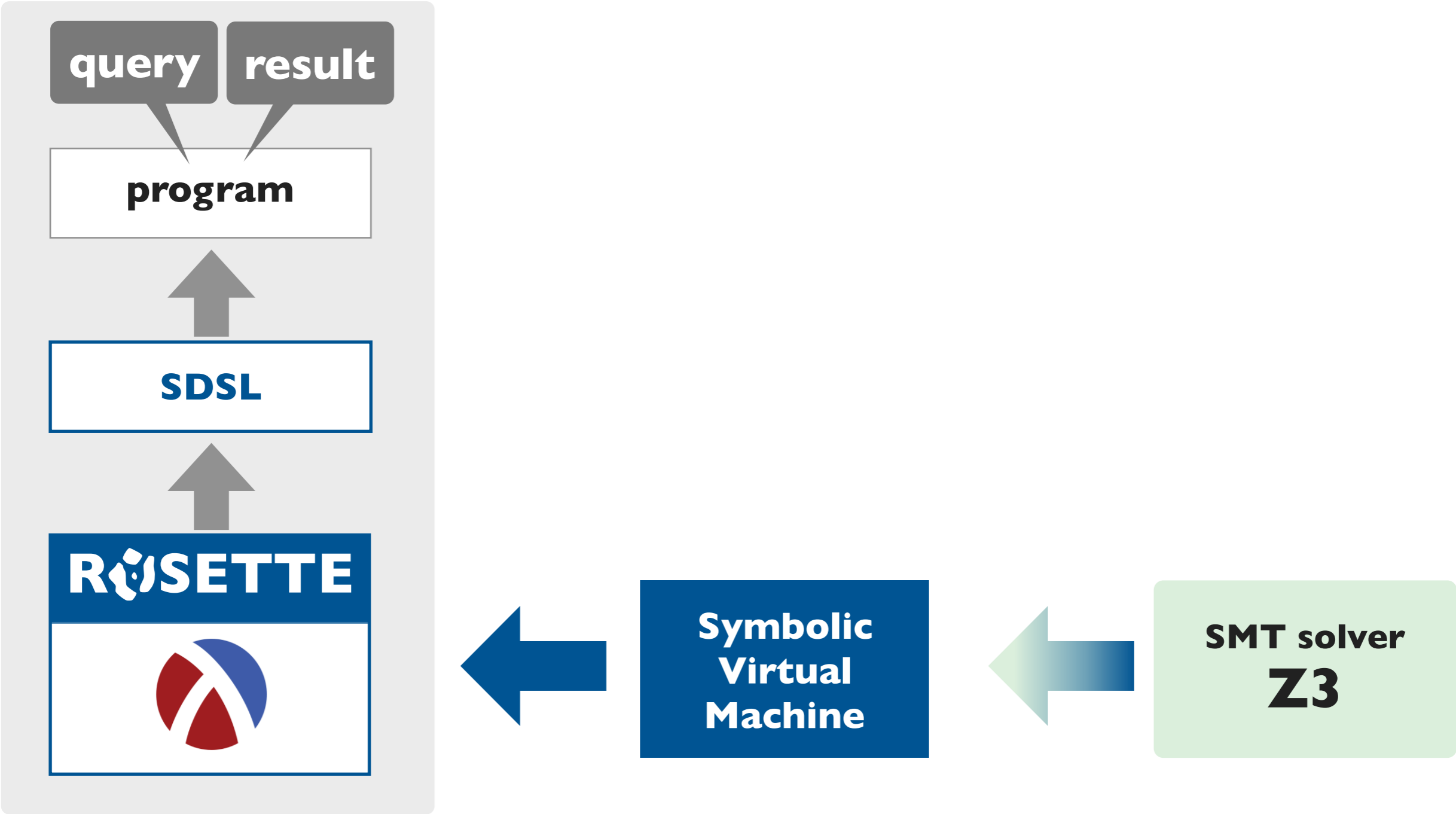
Cool tools built with Rosette!

# How it all works: a big picture view

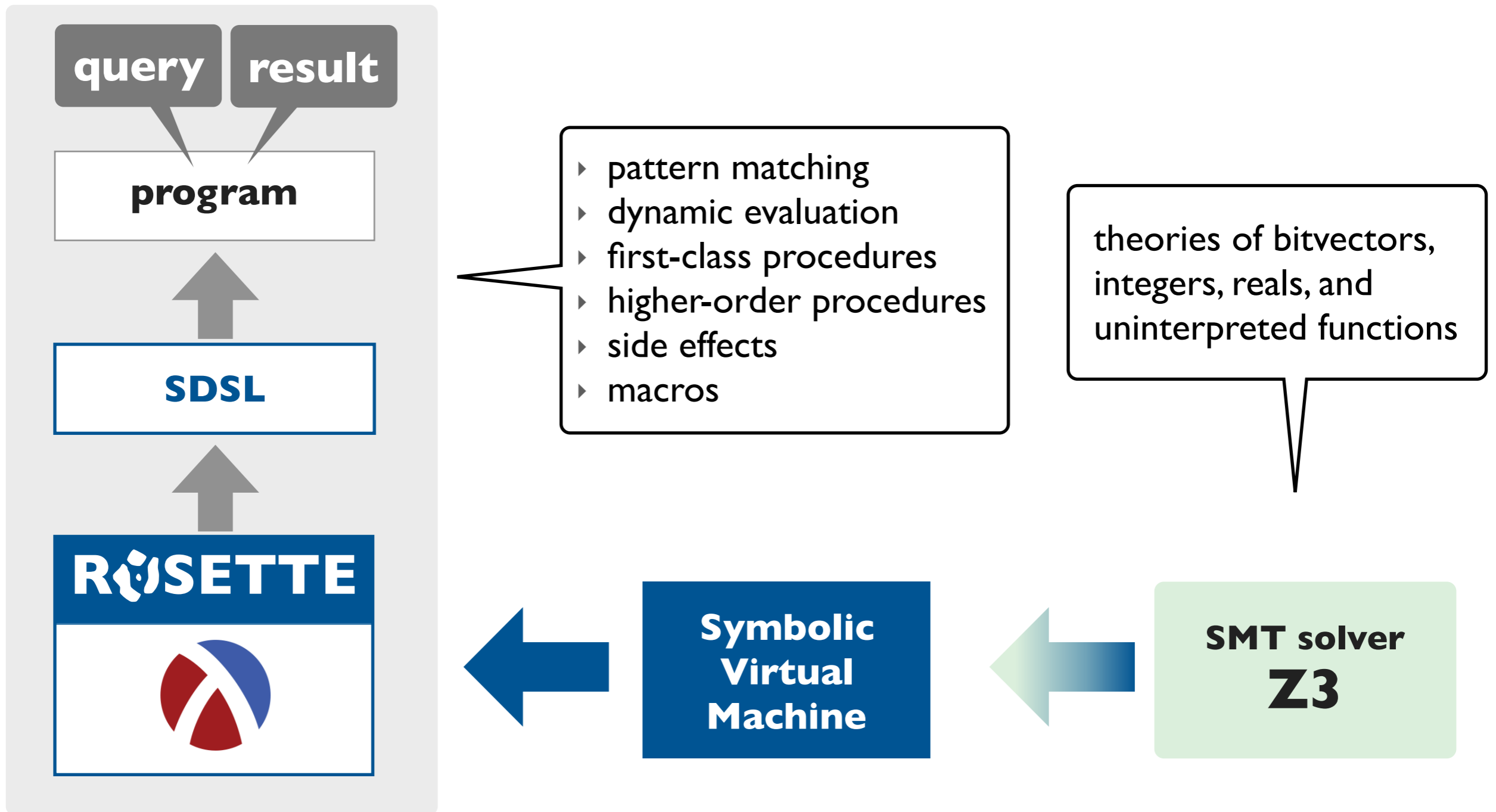




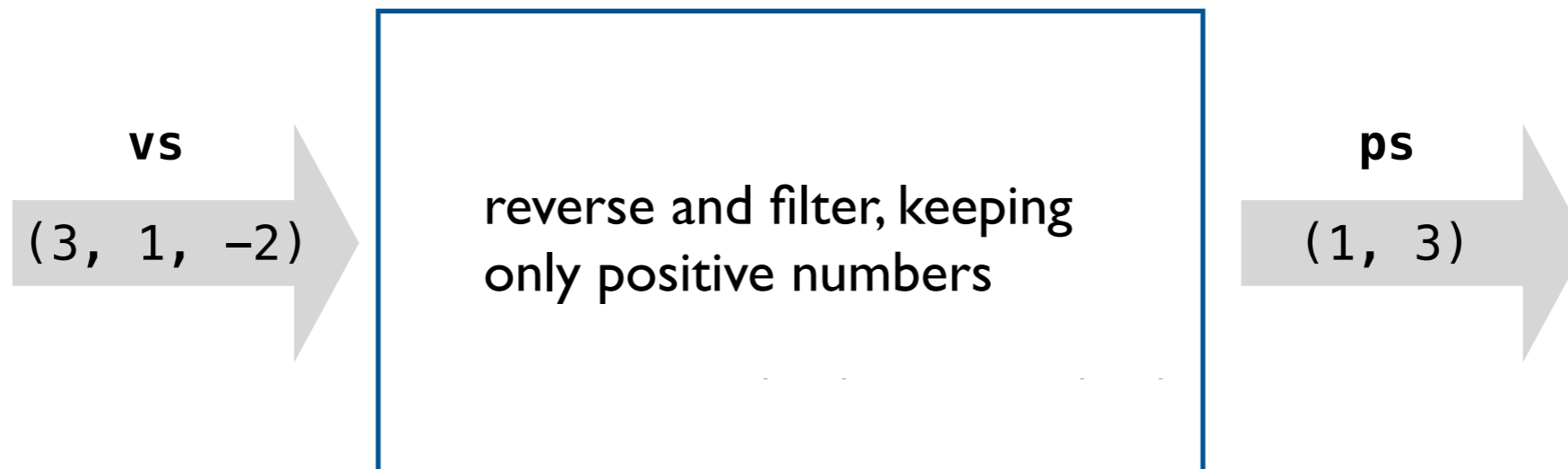
# How it all works: a big picture view



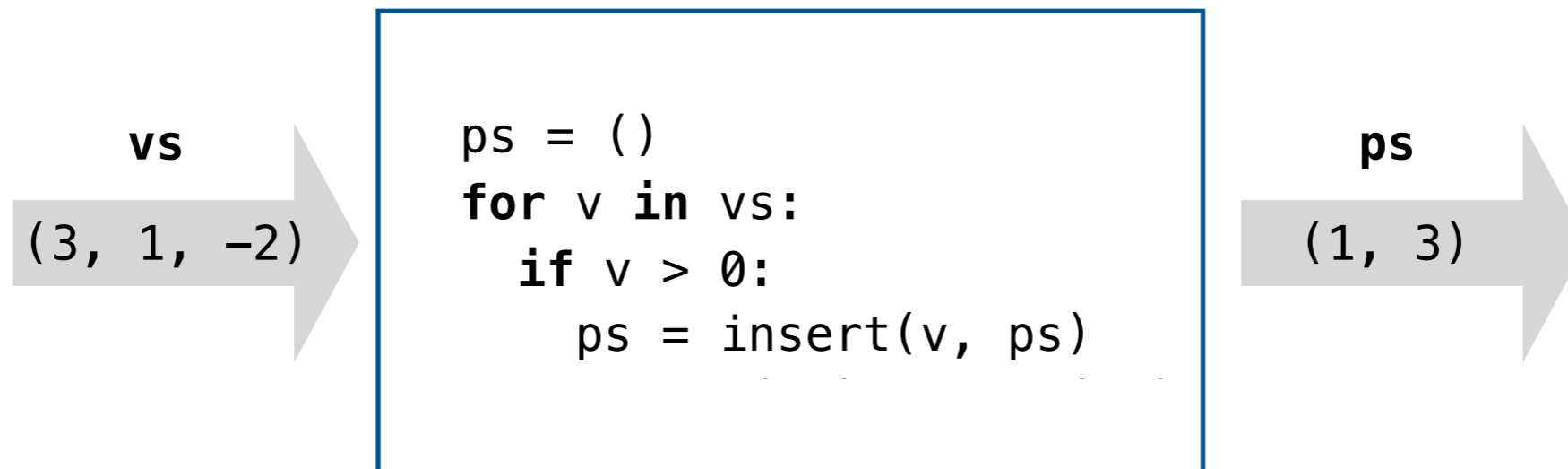
# How it all works: a big picture view



# Translation to constraints by example



# Translation to constraints by example



# Translation to constraints by example

**vs**

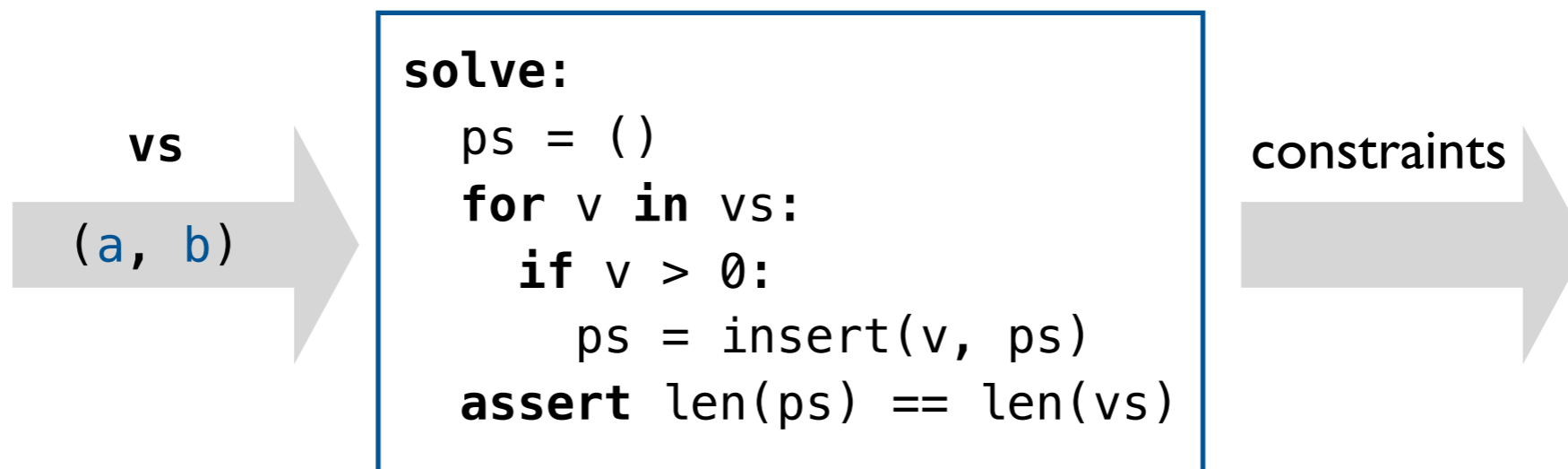


```
solve:  
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

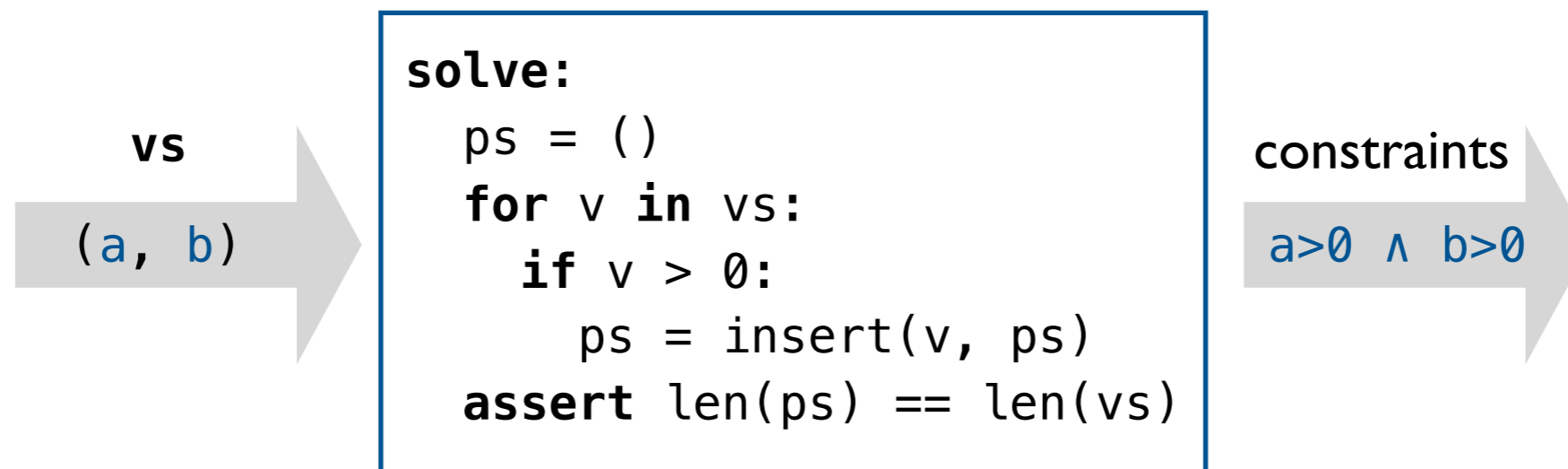
**constraints**



# Translation to constraints by example



# Translation to constraints by example

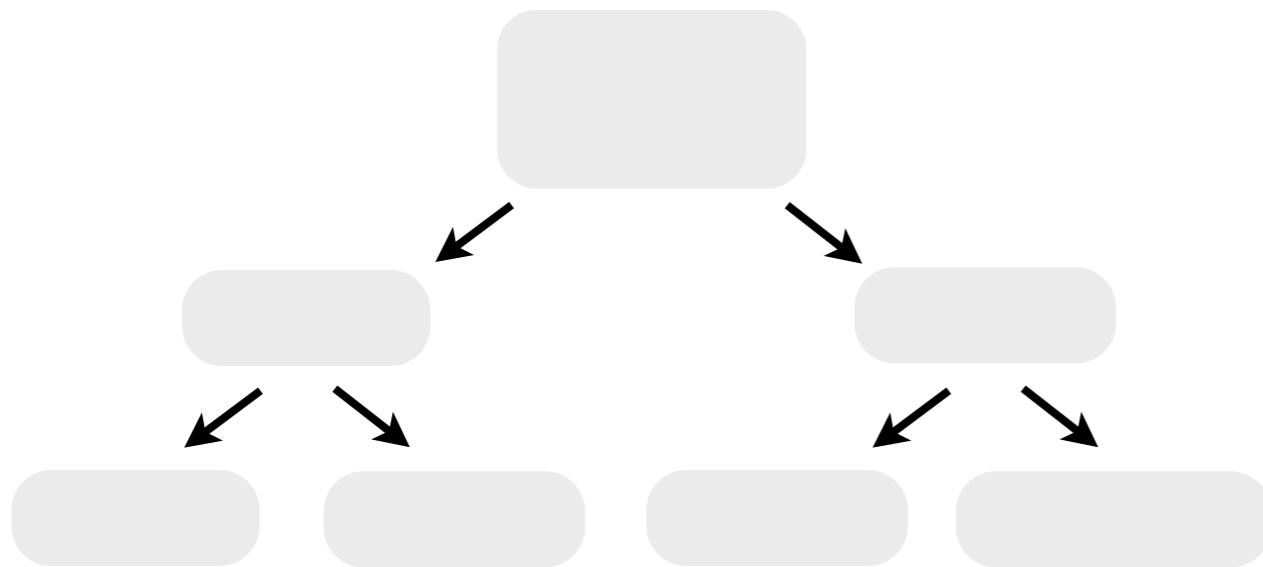


# Design space of precise symbolic encodings

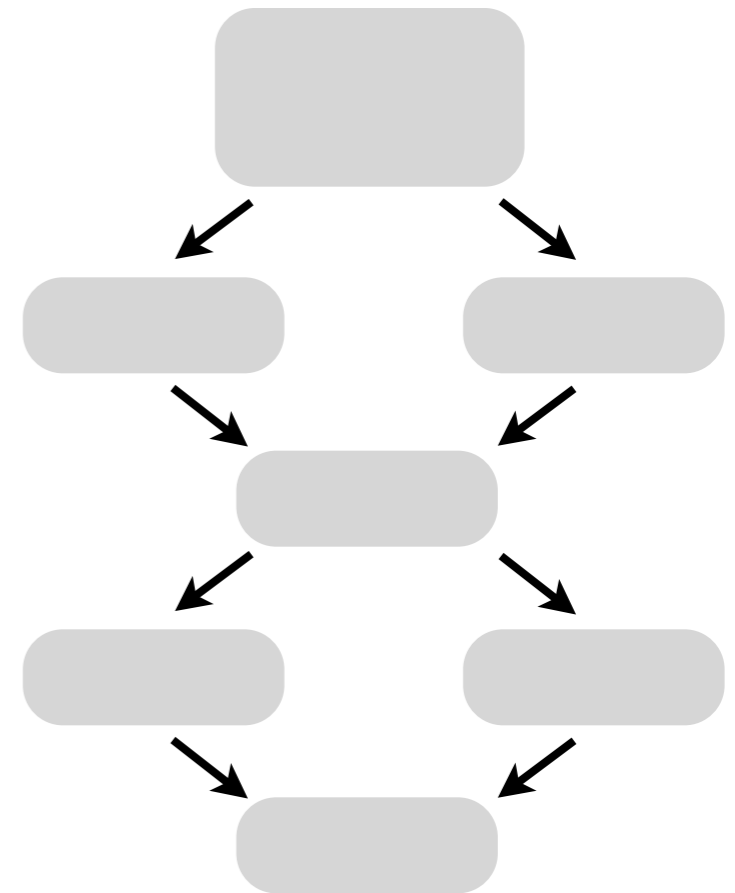
**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

symbolic execution



bounded model checking



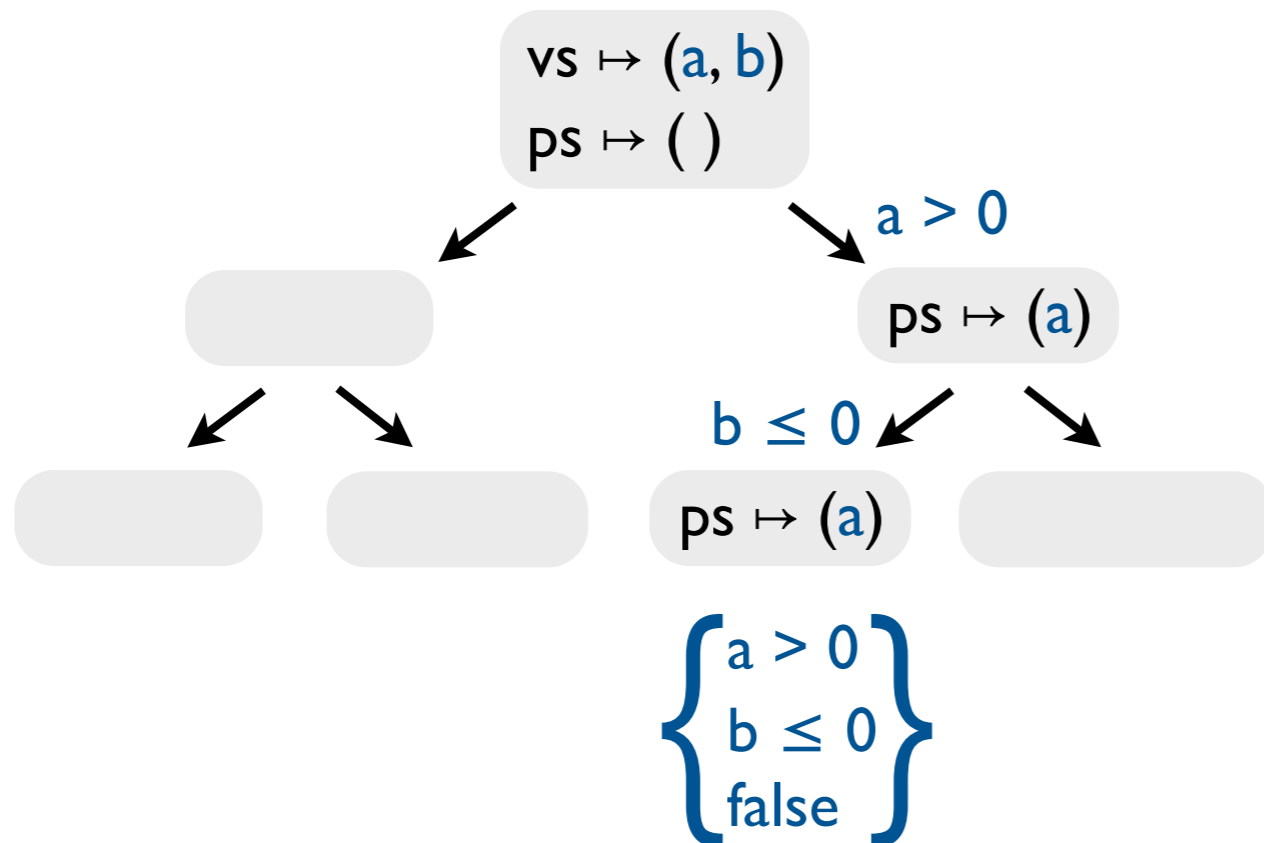


# Design space of precise symbolic encodings

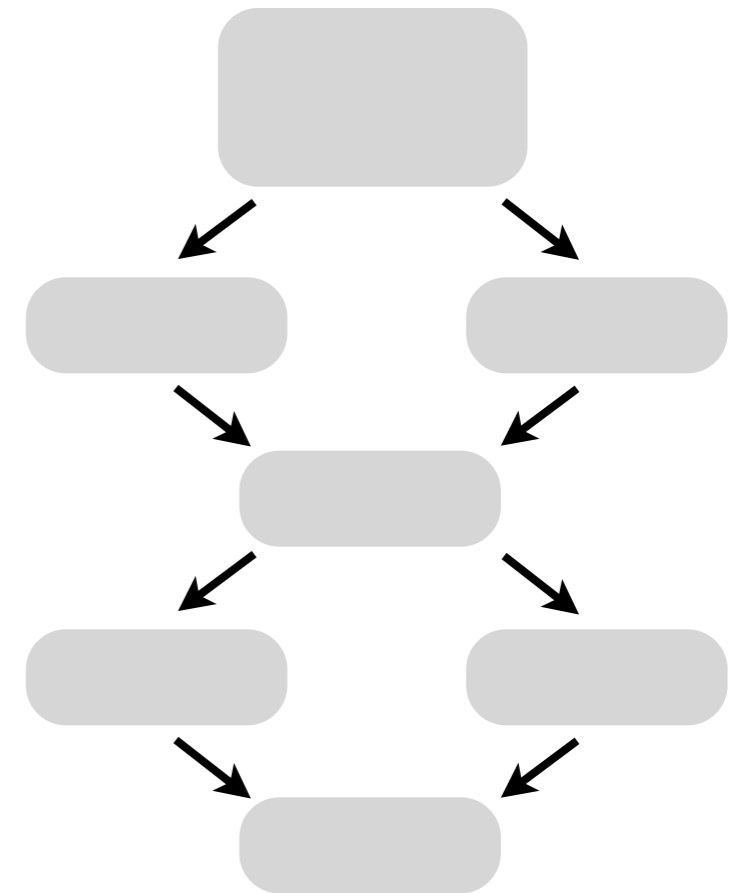
solve:

```
ps = ()  
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    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

symbolic execution



bounded model checking

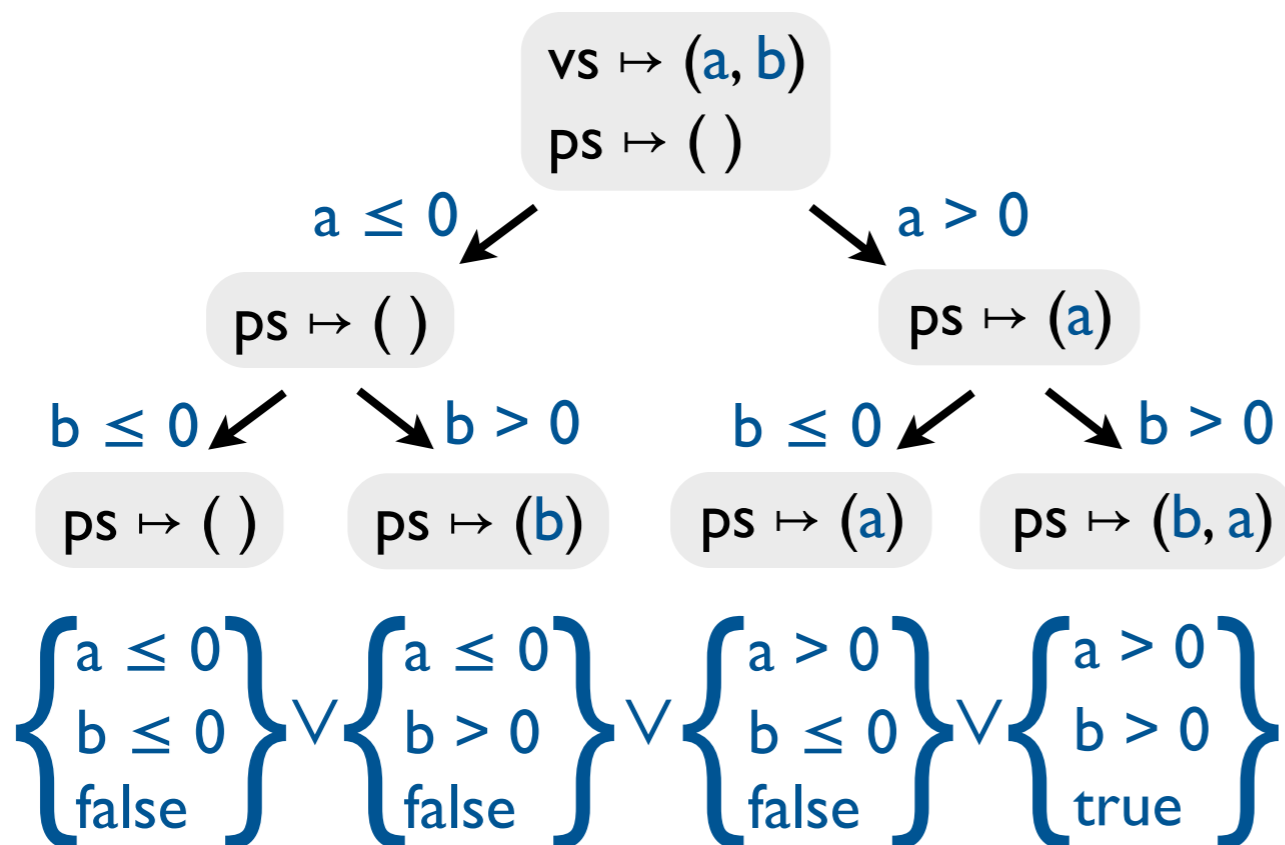


# Design space of precise symbolic encodings

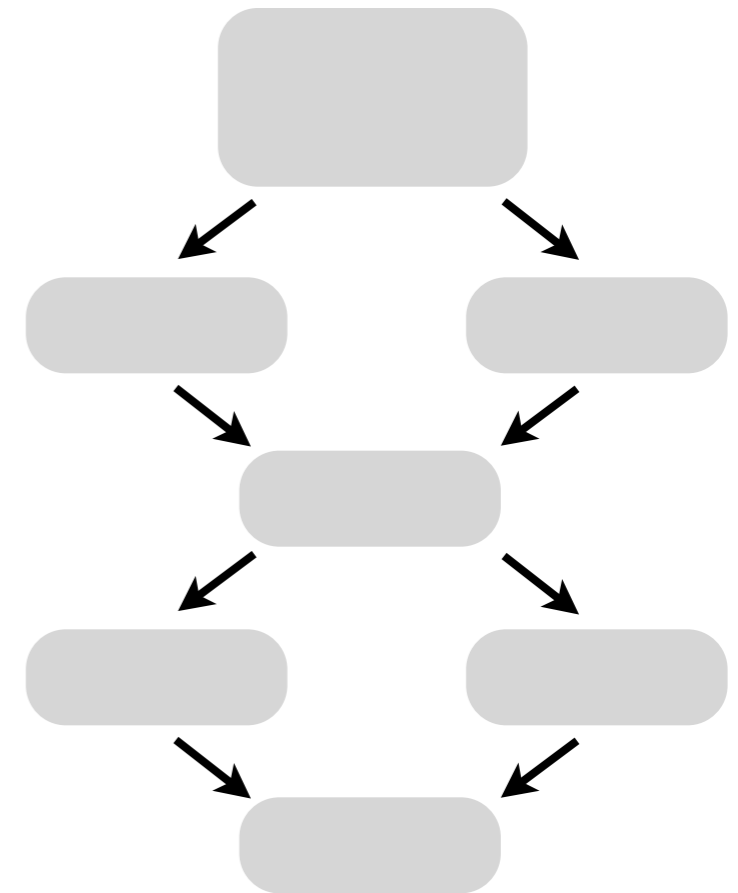
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```

symbolic execution



bounded model checking



# Design space of precise symbolic encodings

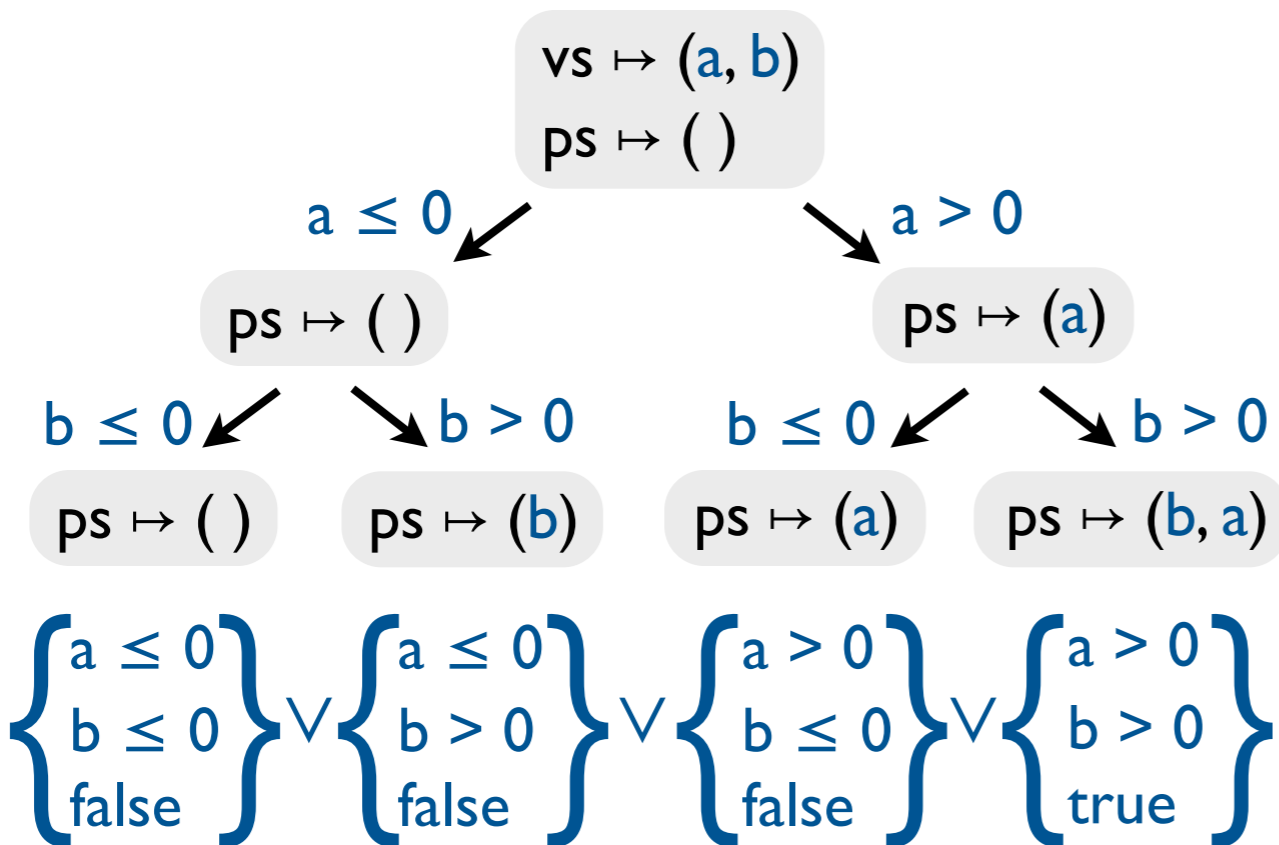
solve:

```

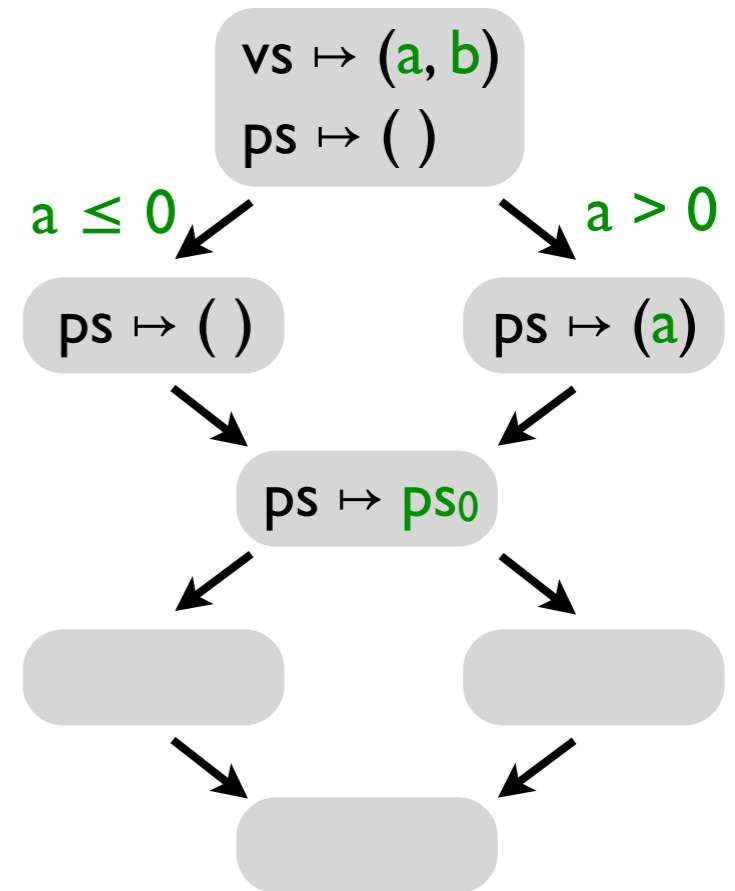
ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)

```

symbolic execution



bounded model checking



$$ps_0 = \text{ite}(a > 0, (a), ( ))$$

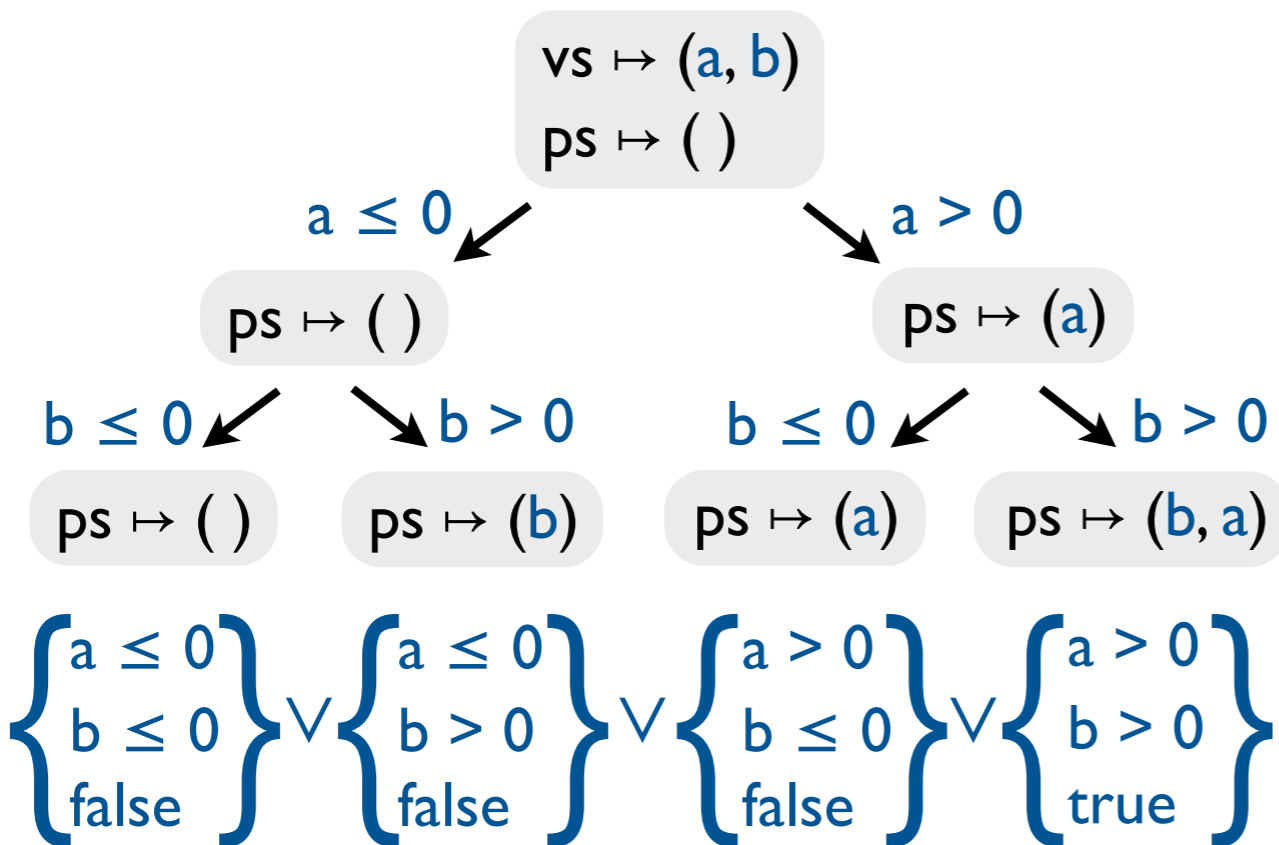
# Design space of precise symbolic encodings

solve:

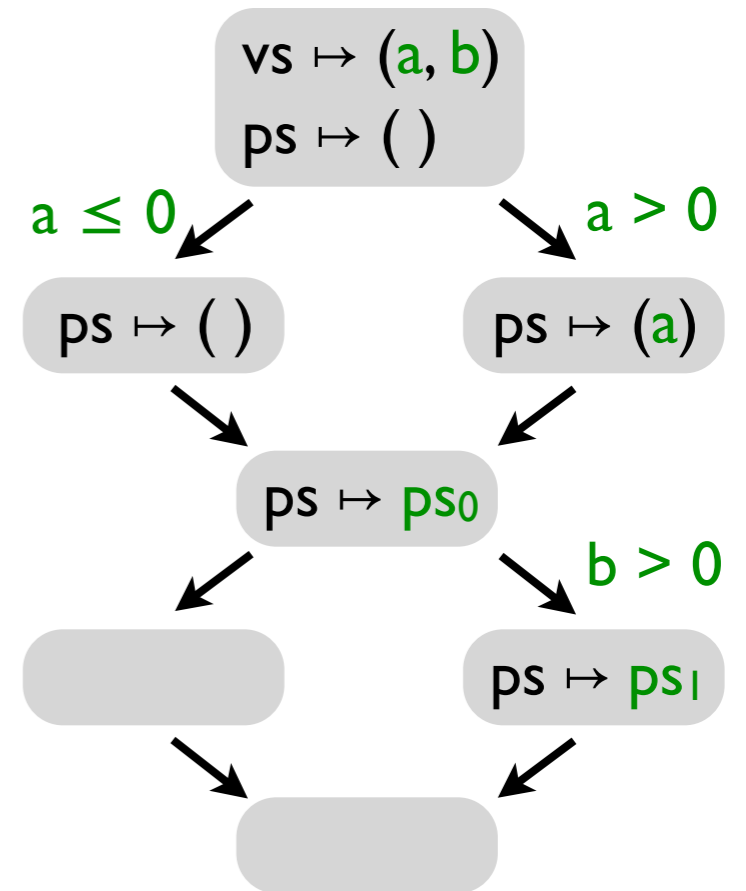
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking



$ps_0 = \text{ite}(a > 0, (a), ())$   
 $ps_1 = \text{insert}(b, ps_0)$

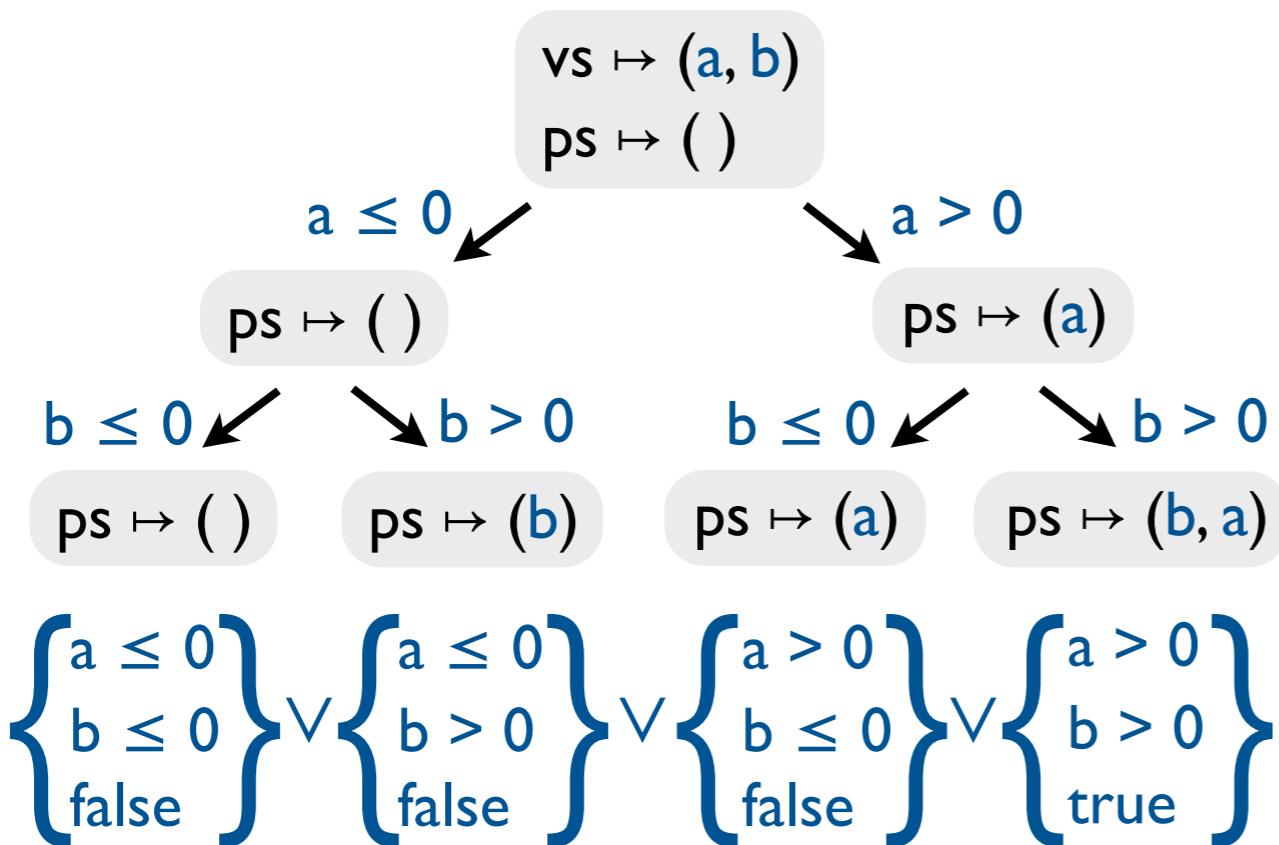
# Design space of precise symbolic encodings

solve:

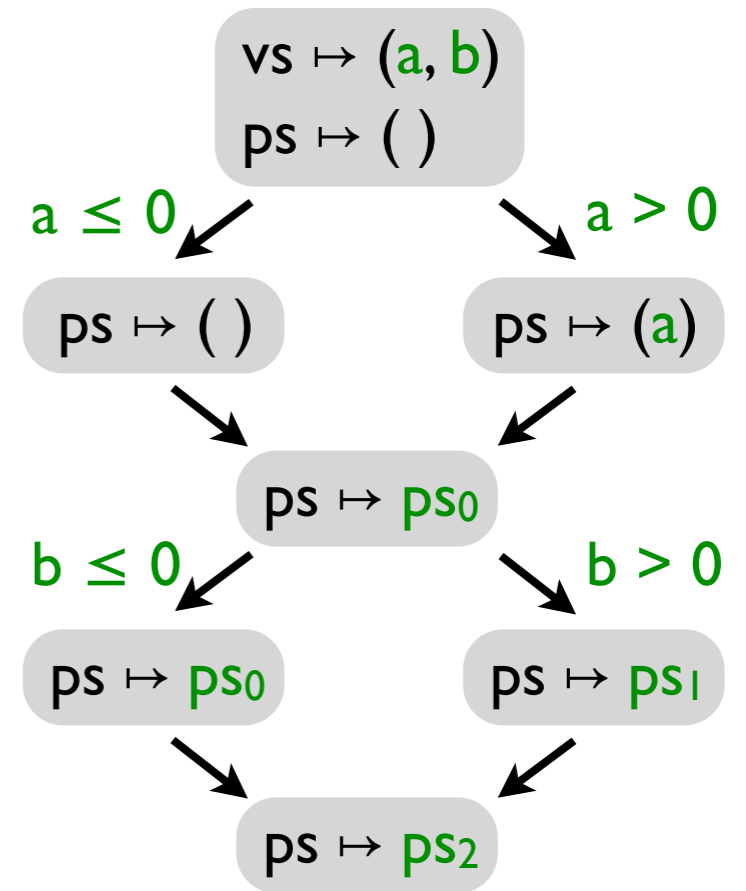
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking

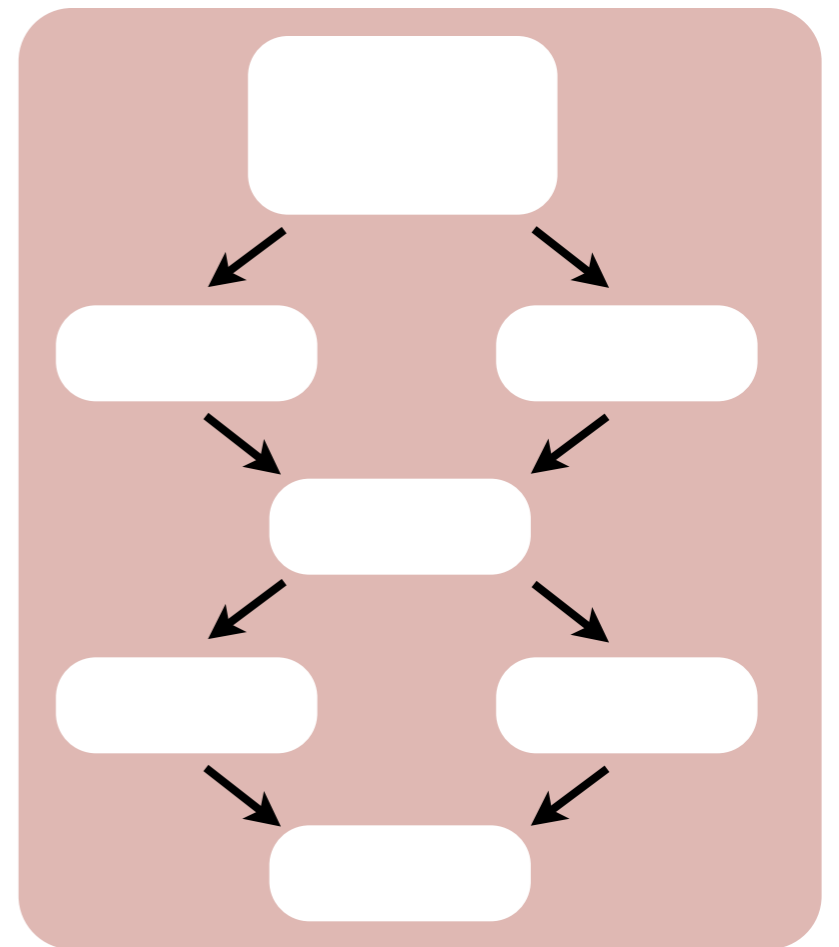


$ps_0 = \text{ite}(a > 0, (a), ())$   
 $ps_1 = \text{insert}(b, ps_0)$   
 $ps_2 = \text{ite}(b > 0, ps_0, ps_1)$   
 $\text{assert len}(ps_2) = 2$

# A new design: type-driven state merging

**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



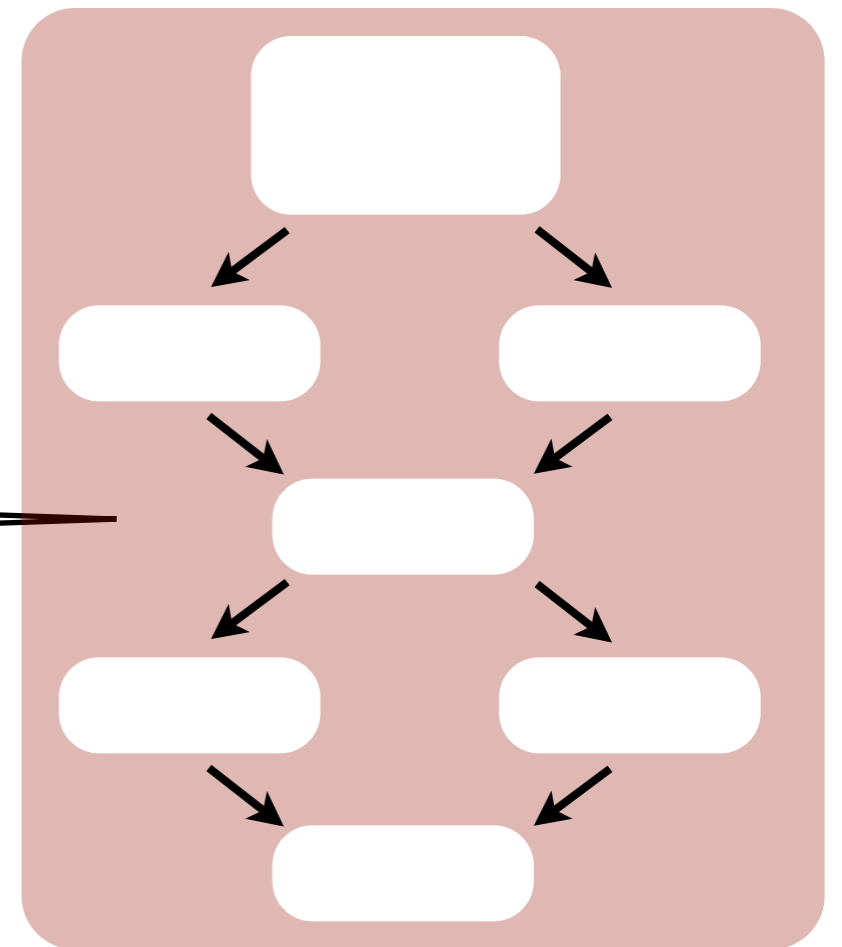
# A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

## Merge instances of

- ▶ primitive types: **symbolically**
- ▶ value types: **structurally**
- ▶ all other types: **via unions**



$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



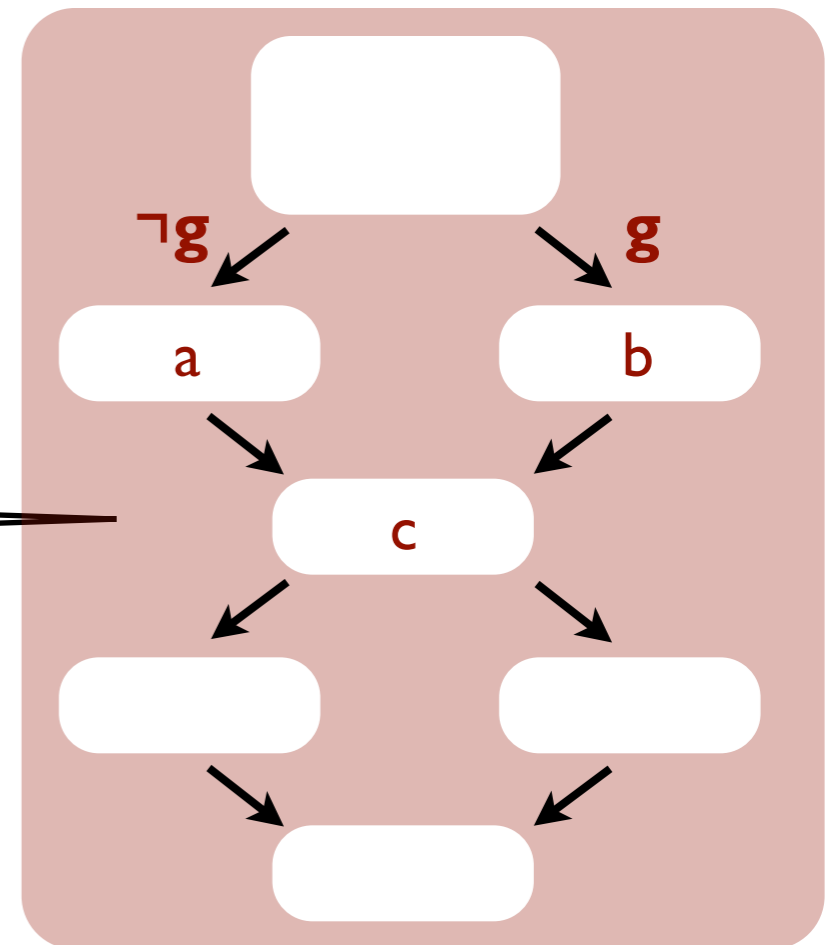
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$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$





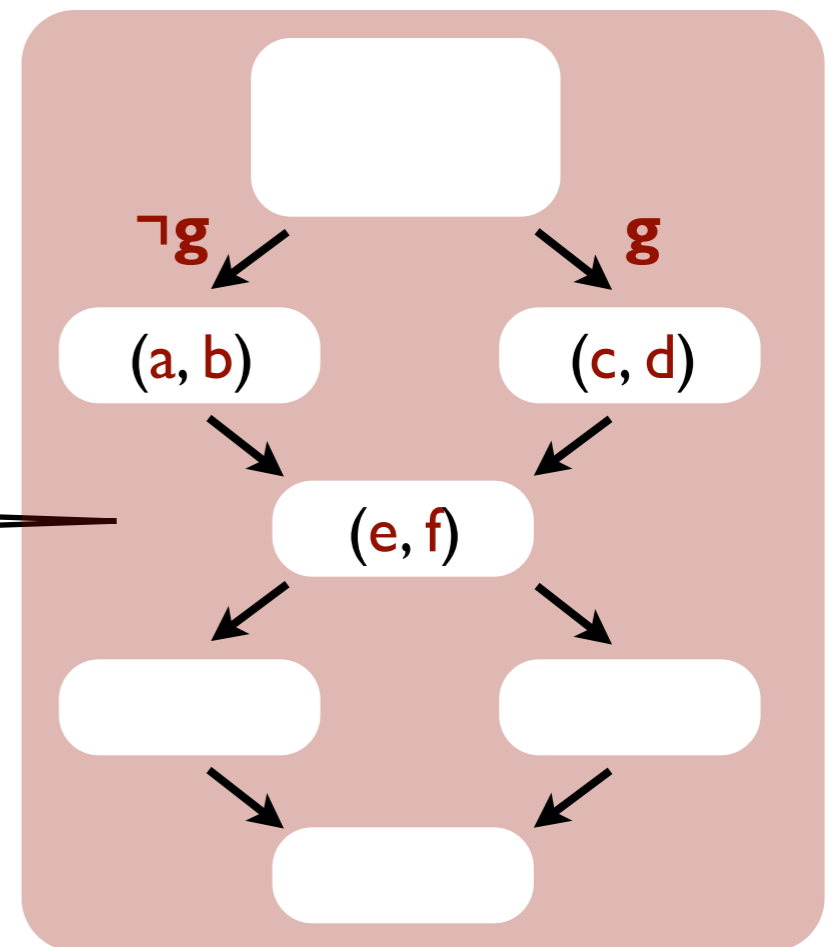
# A new design: type-driven state merging

solve:

```
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    if v > 0:  
        ps = insert(v, ps)  
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```

## Merge instances of

- ▶ primitive types: *symbolically*
- ▶ value types: *structurally*
- ▶ all other types: *via unions*



$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



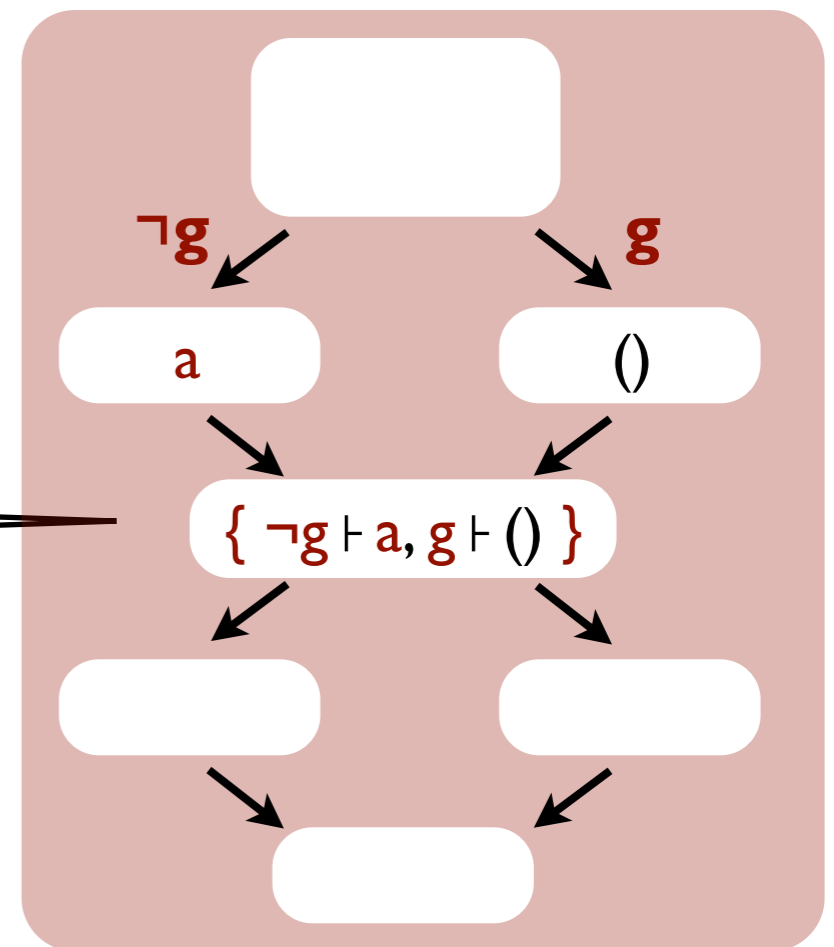
# A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

## Merge instances of

- ▶ primitive types: *symbolically*
- ▶ value types: *structurally*
- ▶ all other types: via **unions**



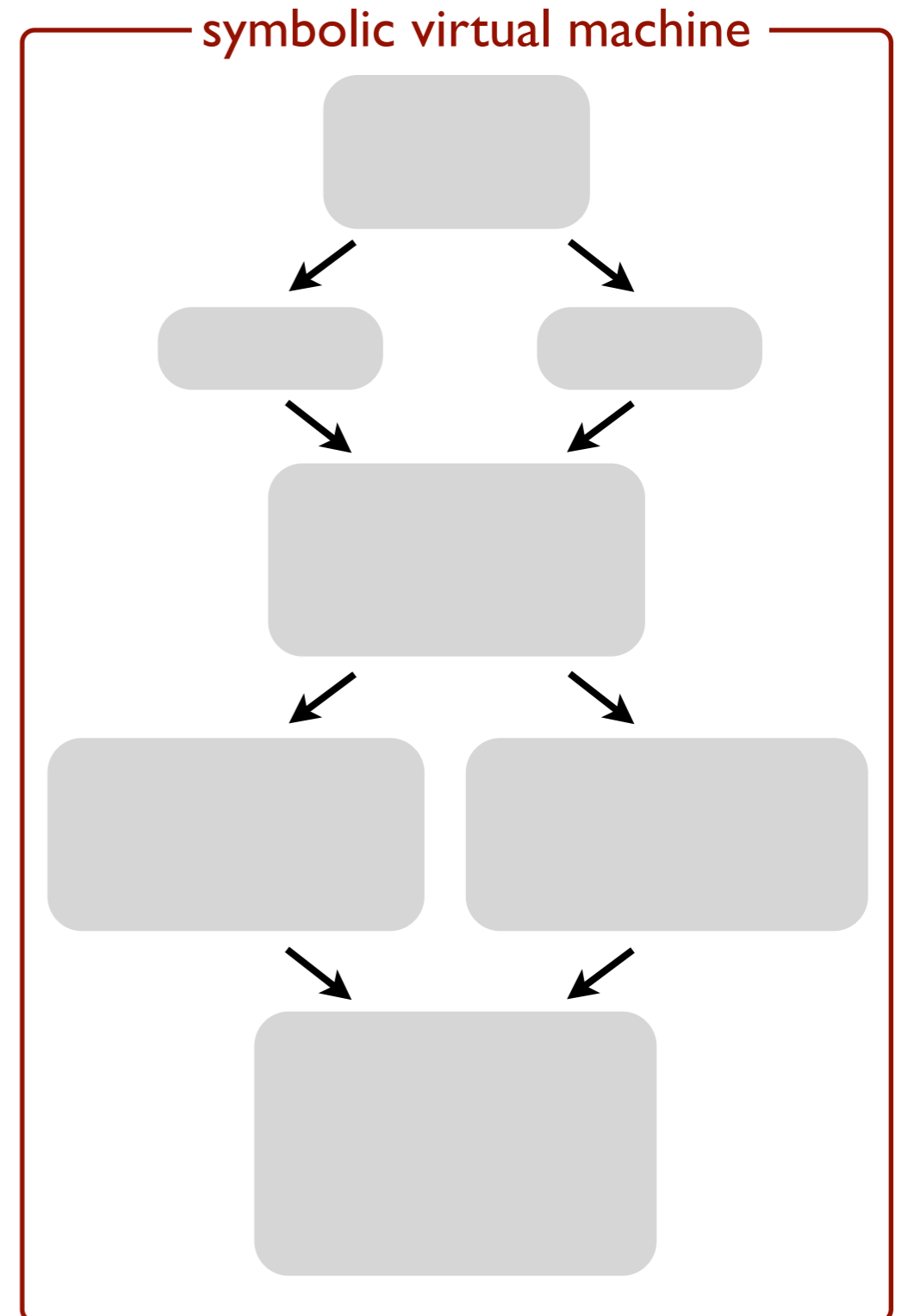
$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



# A new design: type-driven state merging

**solve:**

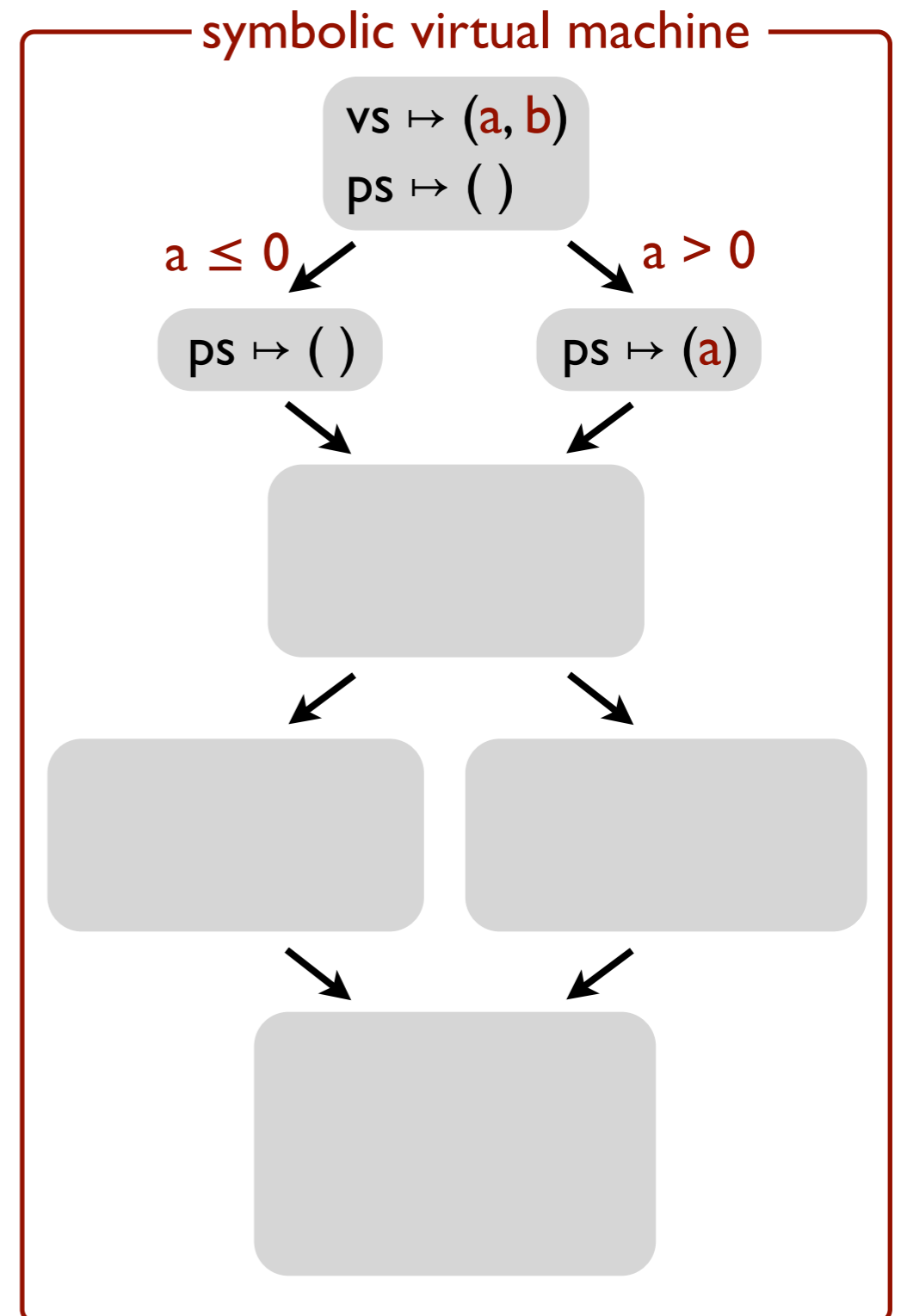
```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



# A new design: type-driven state merging

**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



# A new design: type-driven state merging

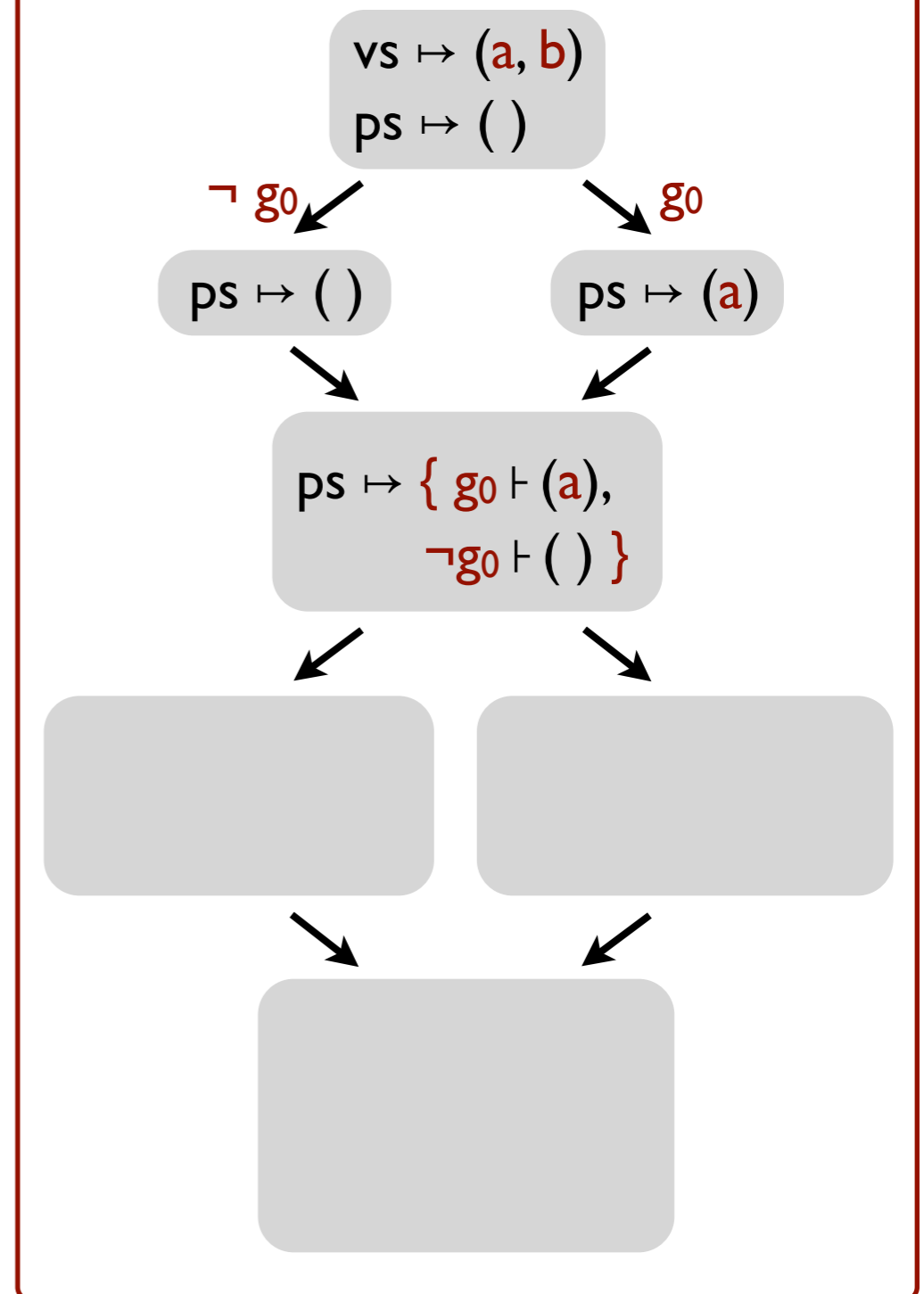
**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Symbolic union: a set of guarded values, with disjoint guards.

$g_0 = a > 0$

symbolic virtual machine



# A new design: type-driven state merging

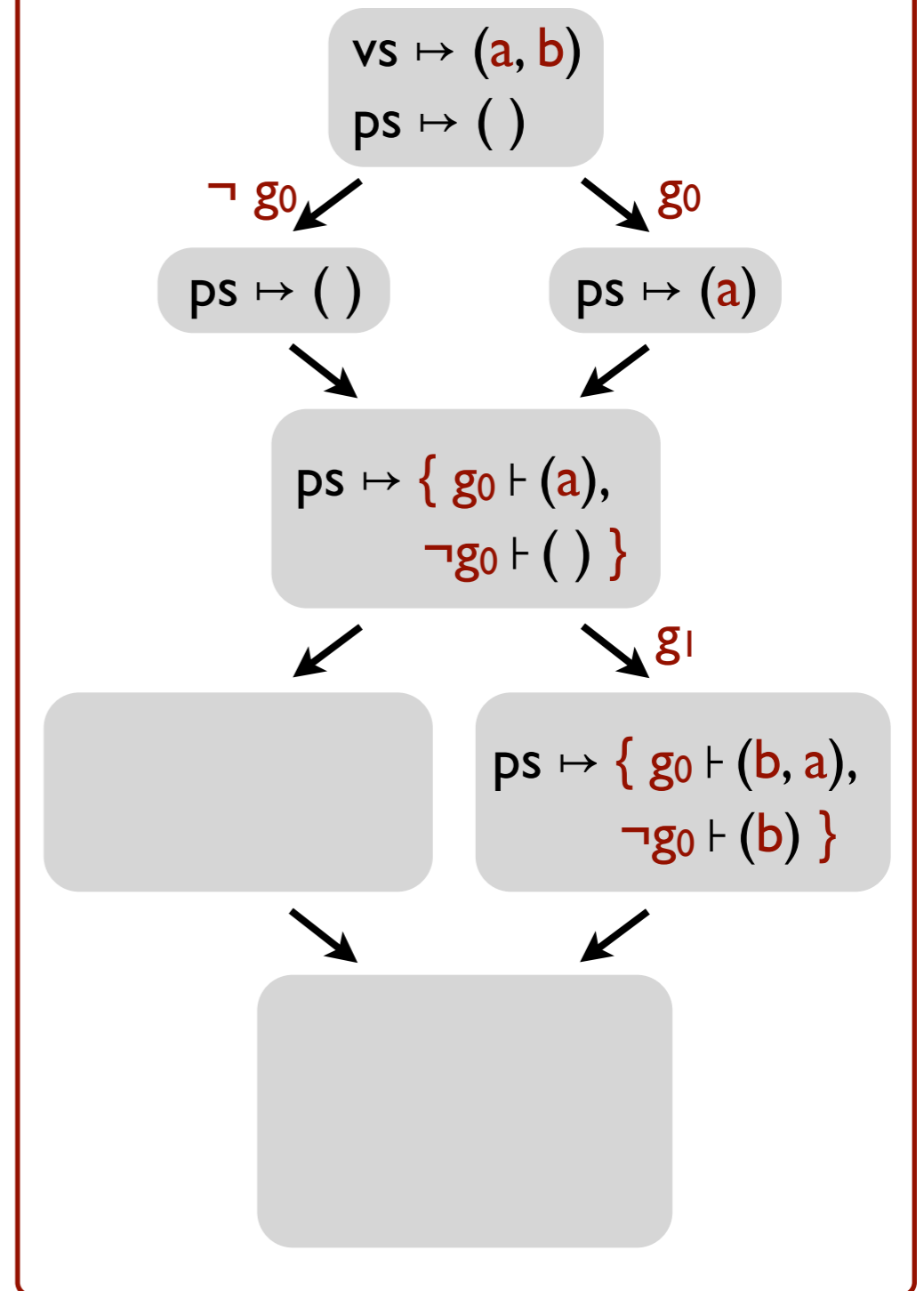
**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Execute insert  
concretely on all  
lists in the union.

$g_0 = a > 0$   
 $g_1 = b > 0$

symbolic virtual machine

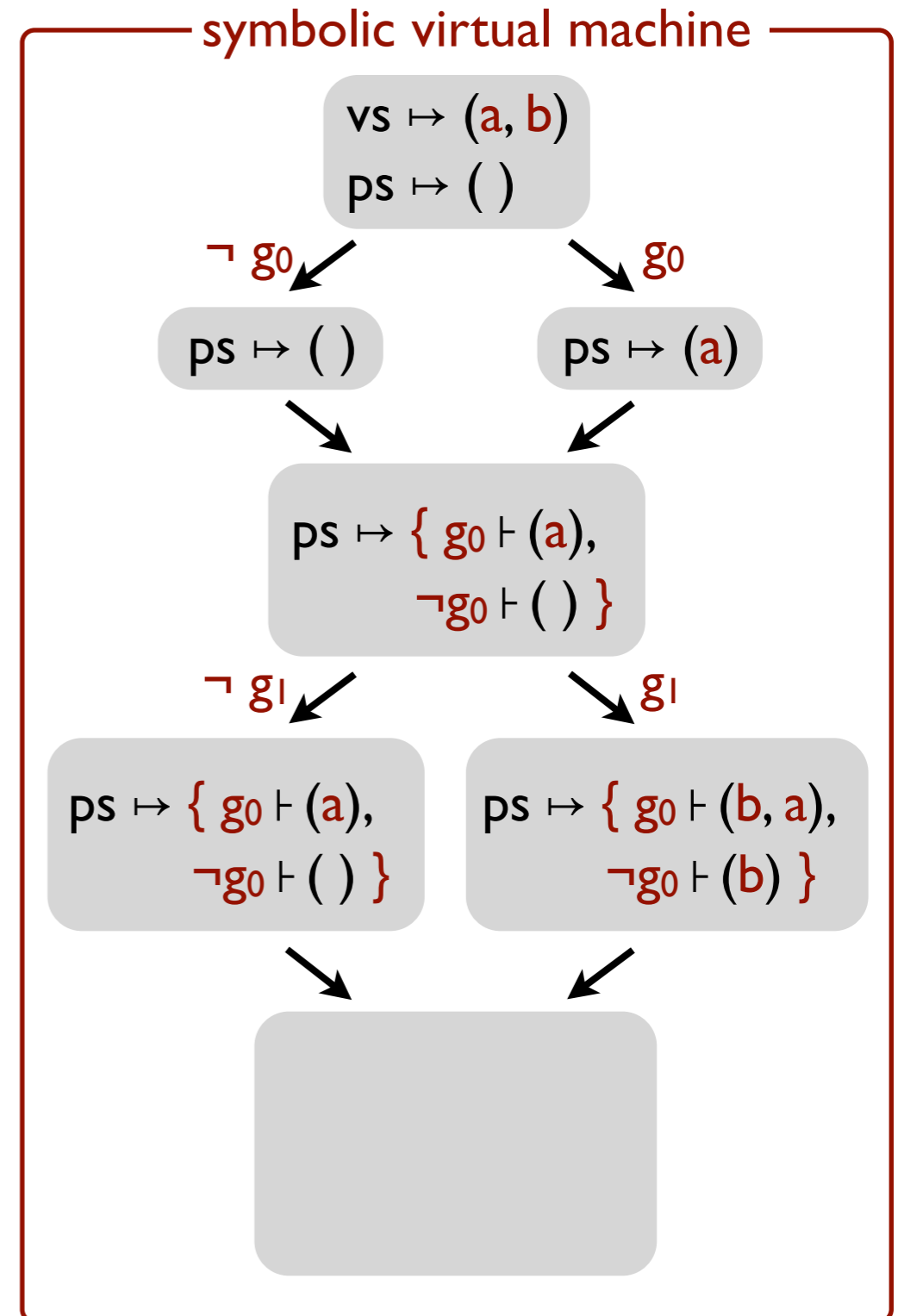


# A new design: type-driven state merging

**solve:**

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

$g_0 = a > 0$   
 $g_1 = b > 0$



# A new design: type-driven state merging

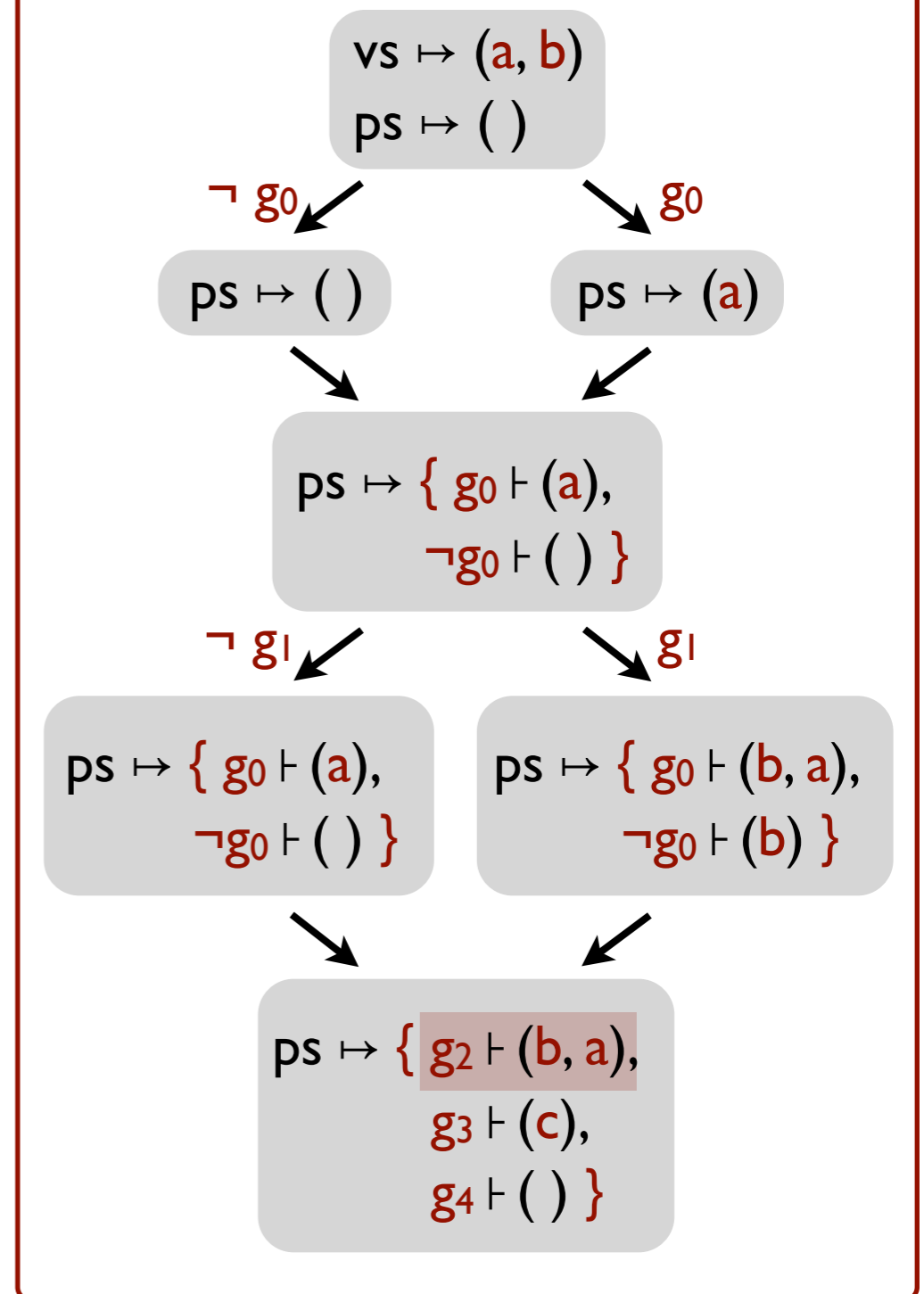
solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Evaluate len concretely on all lists in the union; assertion true only on the list guarded by  $g_2$ .

```
g0 = a > 0  
g1 = b > 0  
g2 = g0 ∧ g1  
g3 = ¬(g0 ⇔ g1)  
g4 = ¬g0 ∧ ¬g1  
c = ite(g1, b, a)  
assert g2
```

symbolic virtual machine





# A new design: type-driven state merging

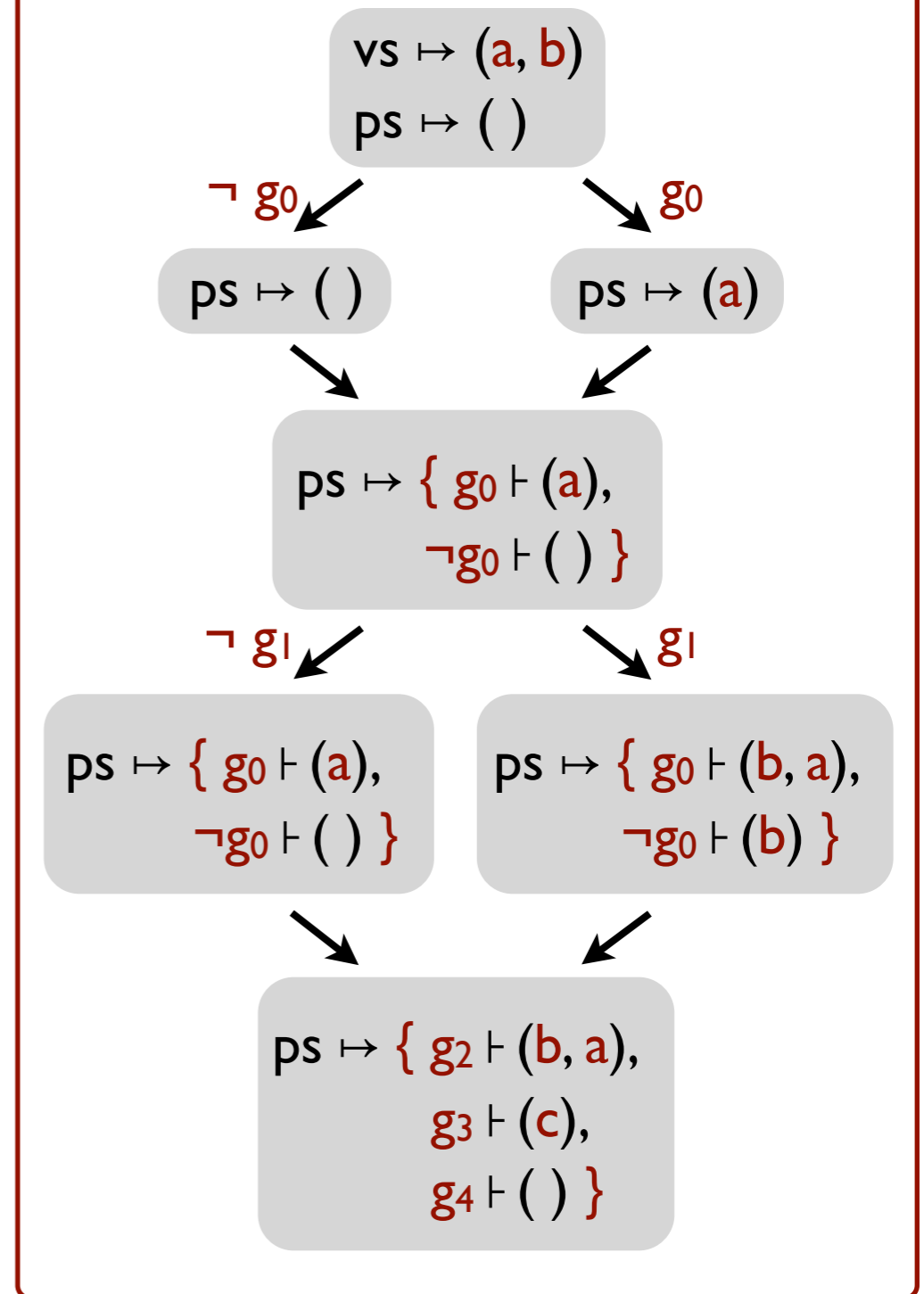
solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

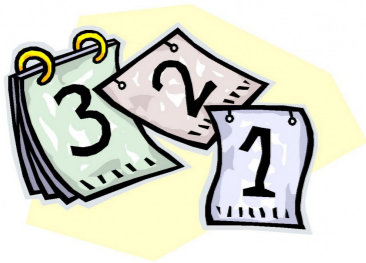
polynomial encoding  
concrete evaluation

```
g0 = a > 0  
g1 = b > 0  
g2 = g0 ∧ g1  
g3 = ¬(g0 ⇔ g1)  
g4 = ¬g0 ∧ ¬g1  
c = ite(g1, b, a)  
assert g2
```

symbolic virtual machine



# How to build your own solver-aided tool or language

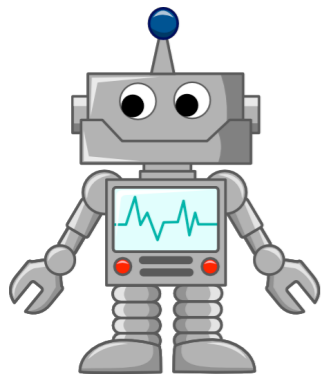


**SDSL**



**SVM**

**SMT**



## **The classic (hard) way to build a tool**

What is hard about building a solver-aided tool?

## **An easier way: tools as languages**

How to build tools by stacking layers of languages.

## **Behind the scenes: symbolic virtual machine**

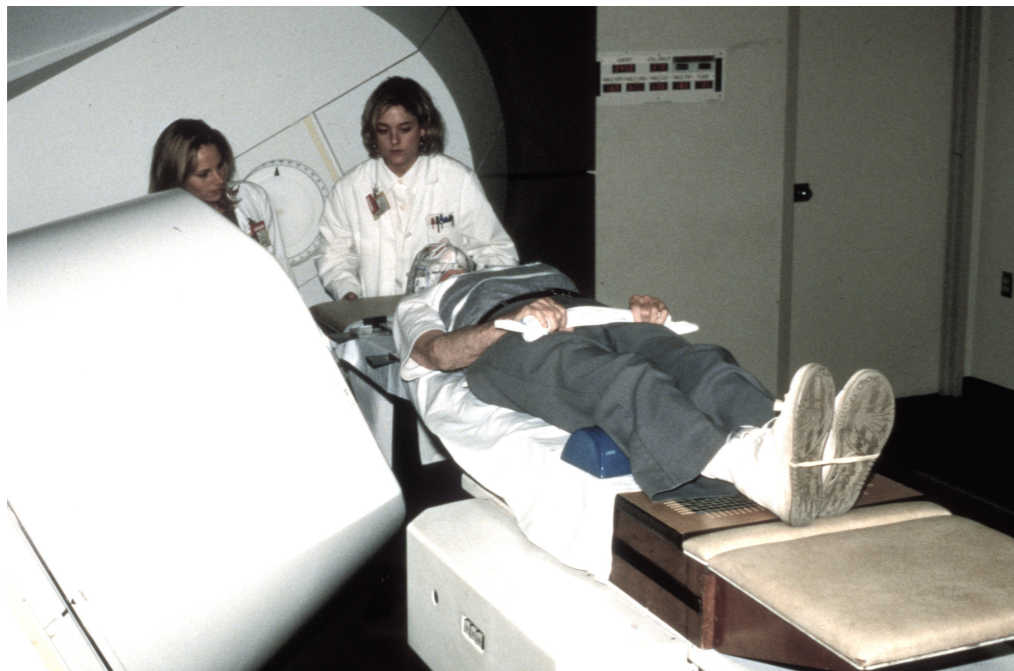
How Rosette works so you don't have to.

## **A last look: a few recent applications**

Cool tools built with Rosette!

# Verifying a radiation therapy system

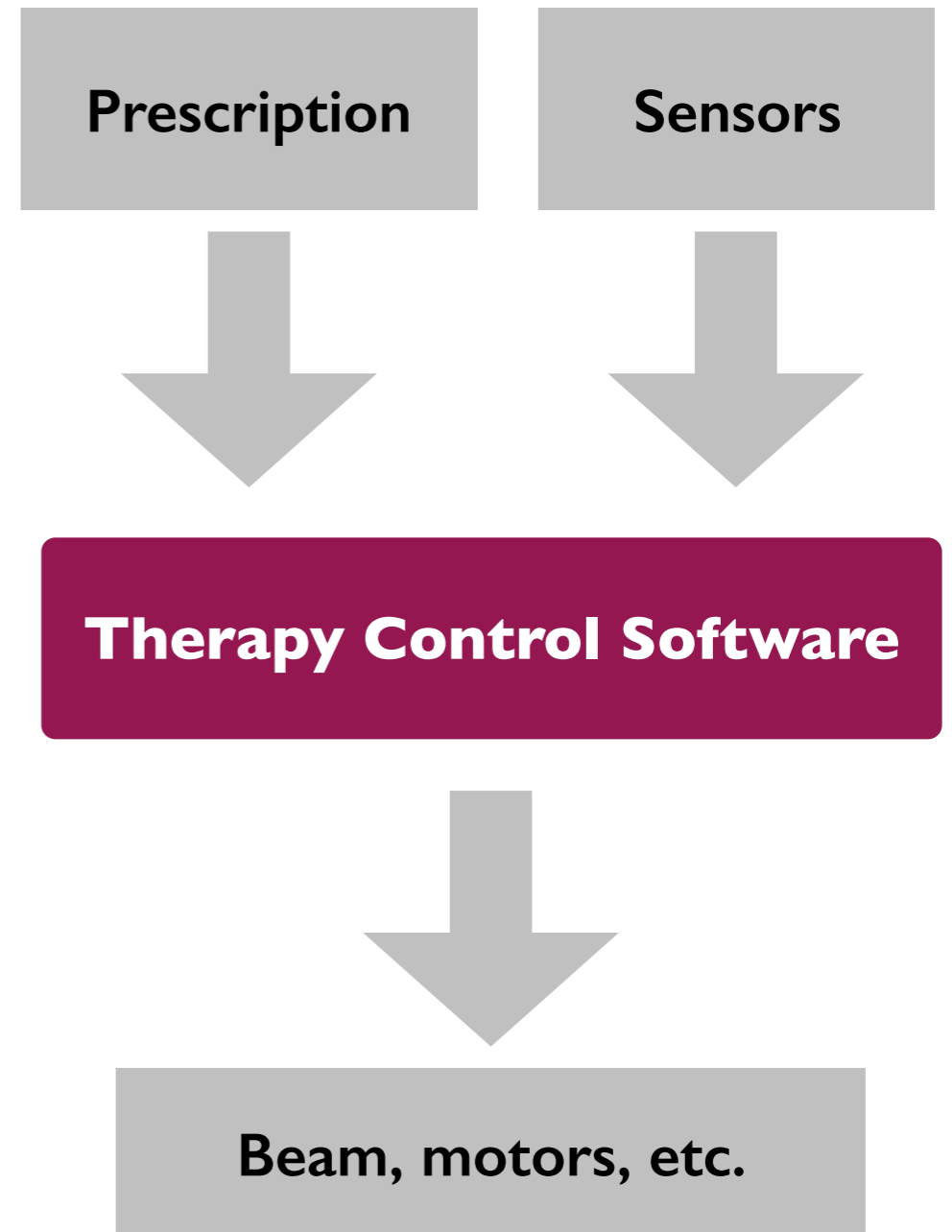
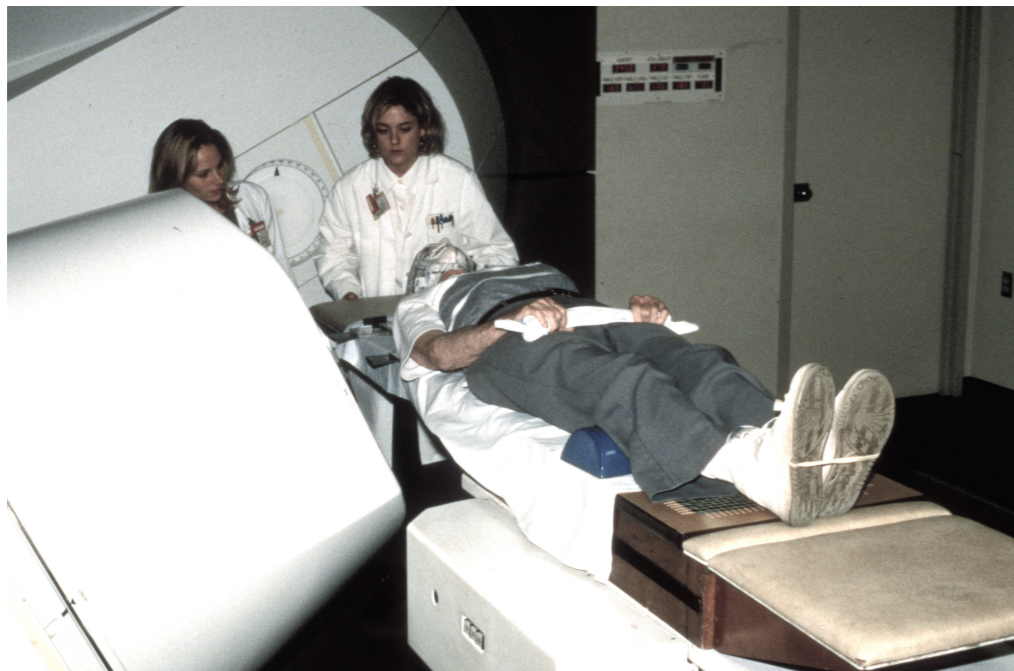
## Clinical Neutron Therapy System (CNTS) at UW



- 30 years of incident-free service.
- Controlled by custom software, built by CNTS engineering staff.
- Third generation of Therapy Control software built recently.

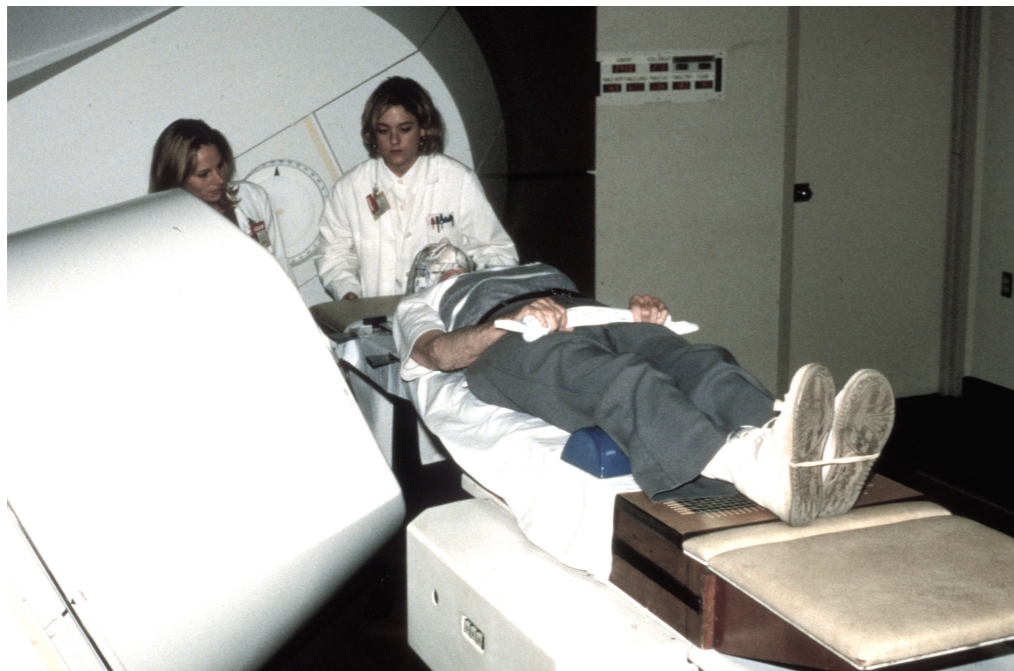
# Verifying a radiation therapy system

## Clinical Neutron Therapy System (CNTS) at UW



# Verifying a radiation therapy system

## Clinical Neutron Therapy System (CNTS) at UW

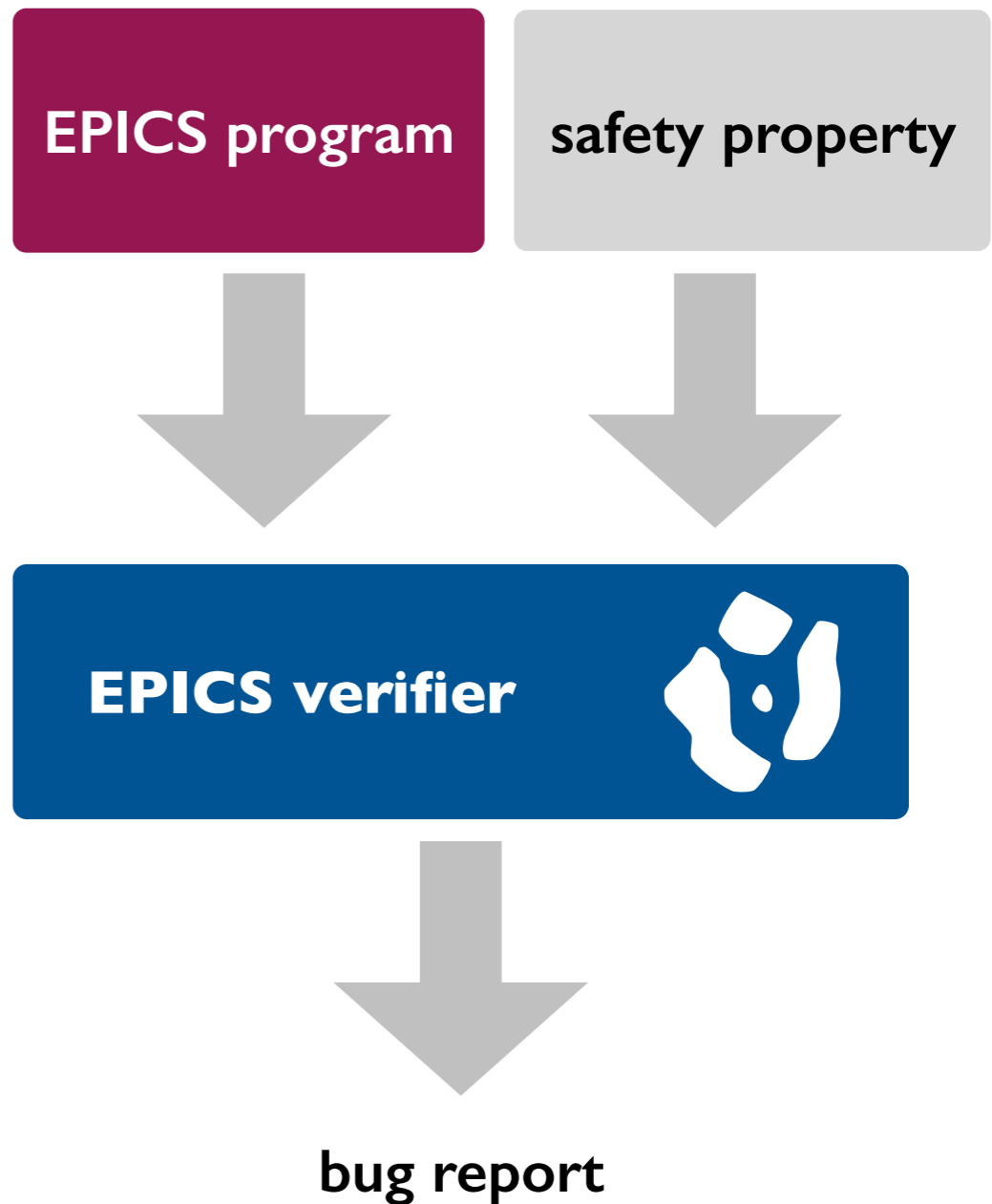
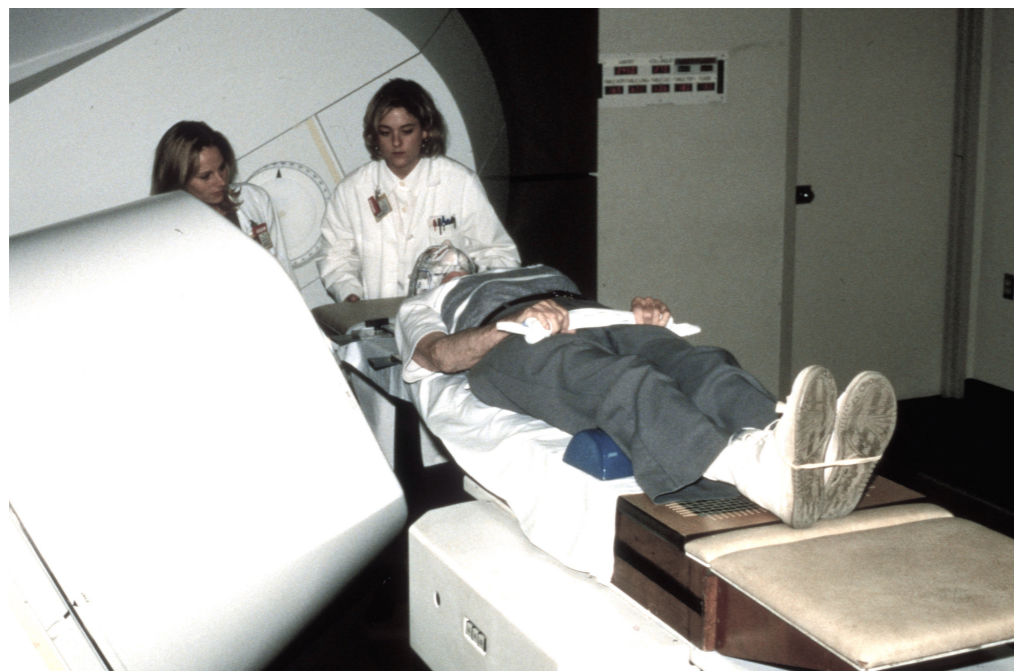


Experimental Physics and Industrial Control System (EPICS) Dataflow Language

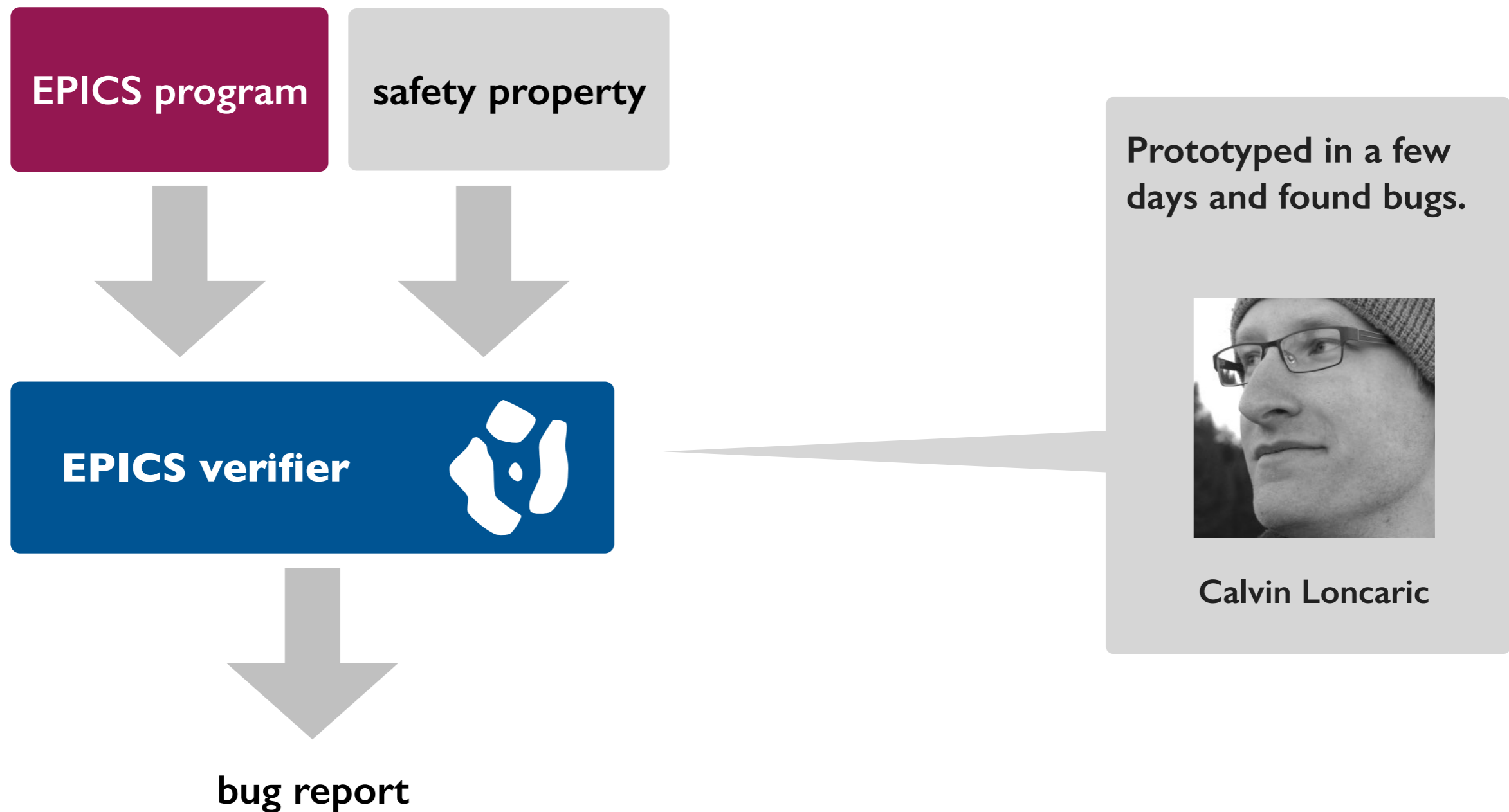
**Therapy Control Software**

# Verifying a radiation therapy system

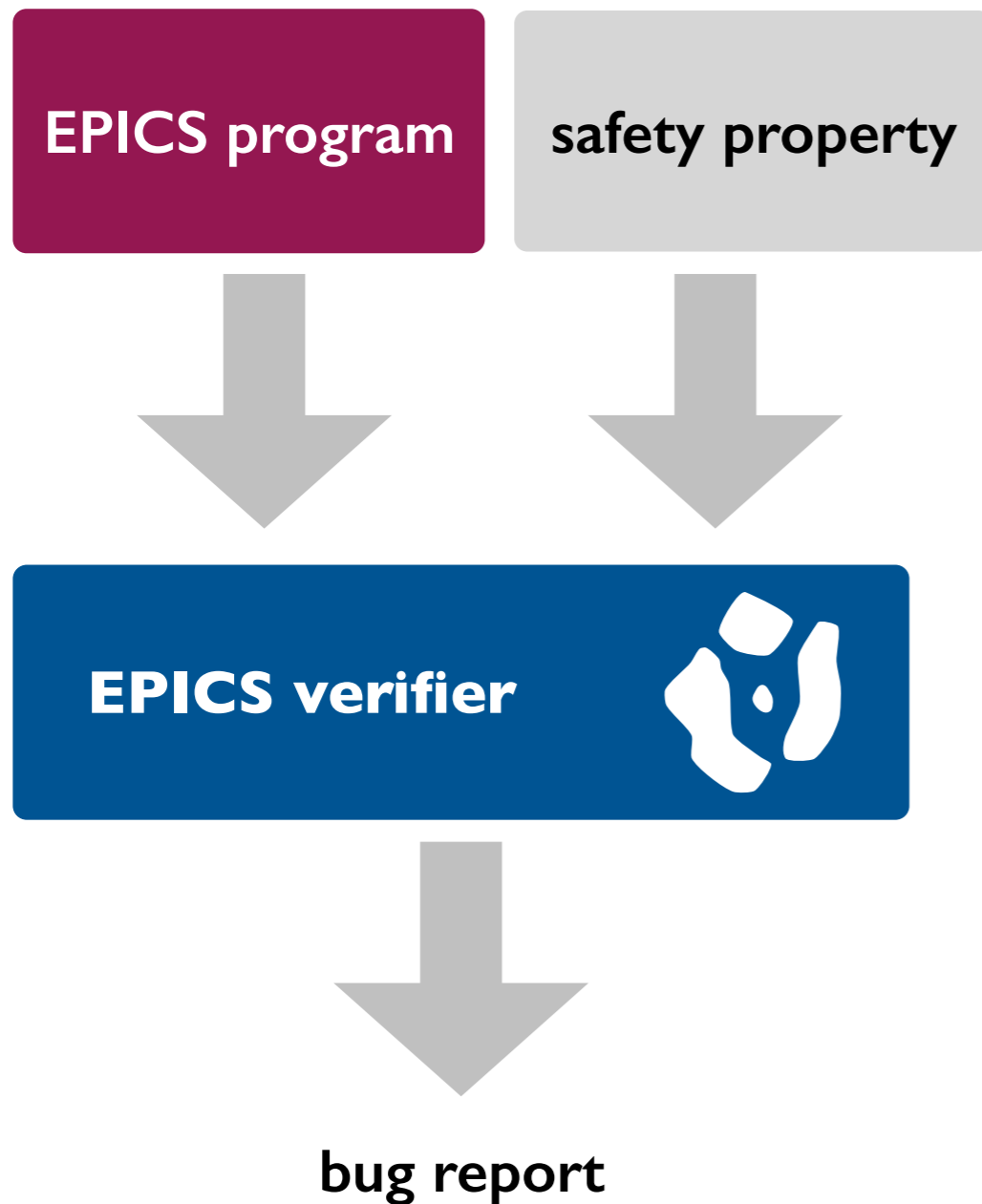
## Clinical Neutron Therapy System (CNTS) at UW



# Verifying a radiation therapy system



# Verifying a radiation therapy system



[Pernsteiner et al.,  
CAV'16]

Found safety-critical defects in a pre-release version of the therapy control software. Used by CNTS staff to verify changes to the controller.



# Synthesizing memory models

Memory consistency models  
define memory reordering  
behaviors on multiprocessors.

$$\begin{array}{c|c} x = y = 0 & \\ \hline a = x & b = y \\ y = 1 & x = 1 \\ \hline a \equiv b \equiv 1 & \end{array}$$

# Synthesizing memory models

Memory consistency models define memory reordering behaviors on multiprocessors.

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Forbidden by sequential consistency.

Allowed by x86 and other hardware memory models.

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Forbidden by sequential consistency.

Allowed by x86 and other hardware memory models.

Formalizing memory models is hard: e.g., PowerPC formalized over 7 publications in 2009-2015.

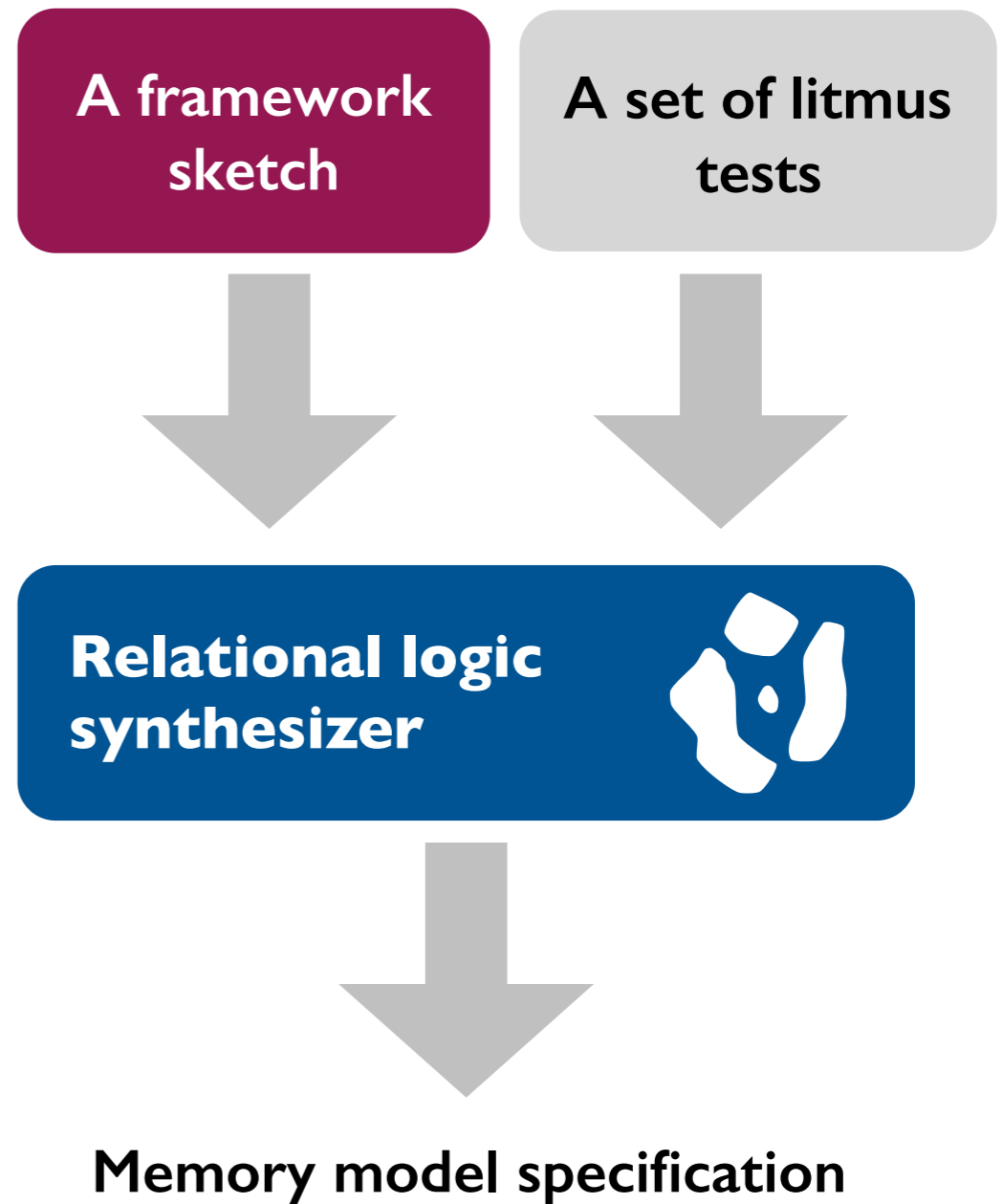
# Synthesizing memory models

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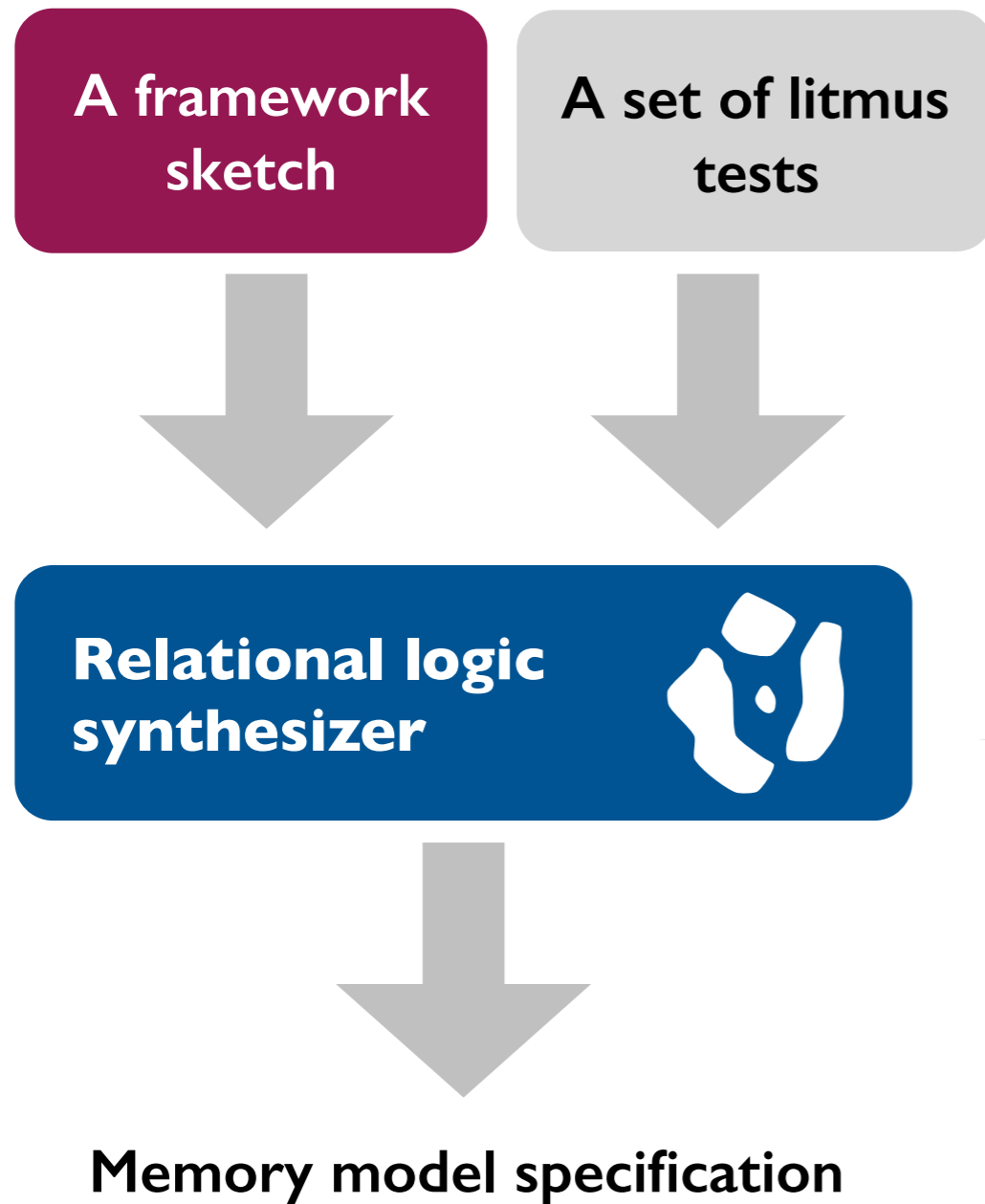
$x = y = 0$	
$a = x$	$b = y$
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# Synthesizing memory models

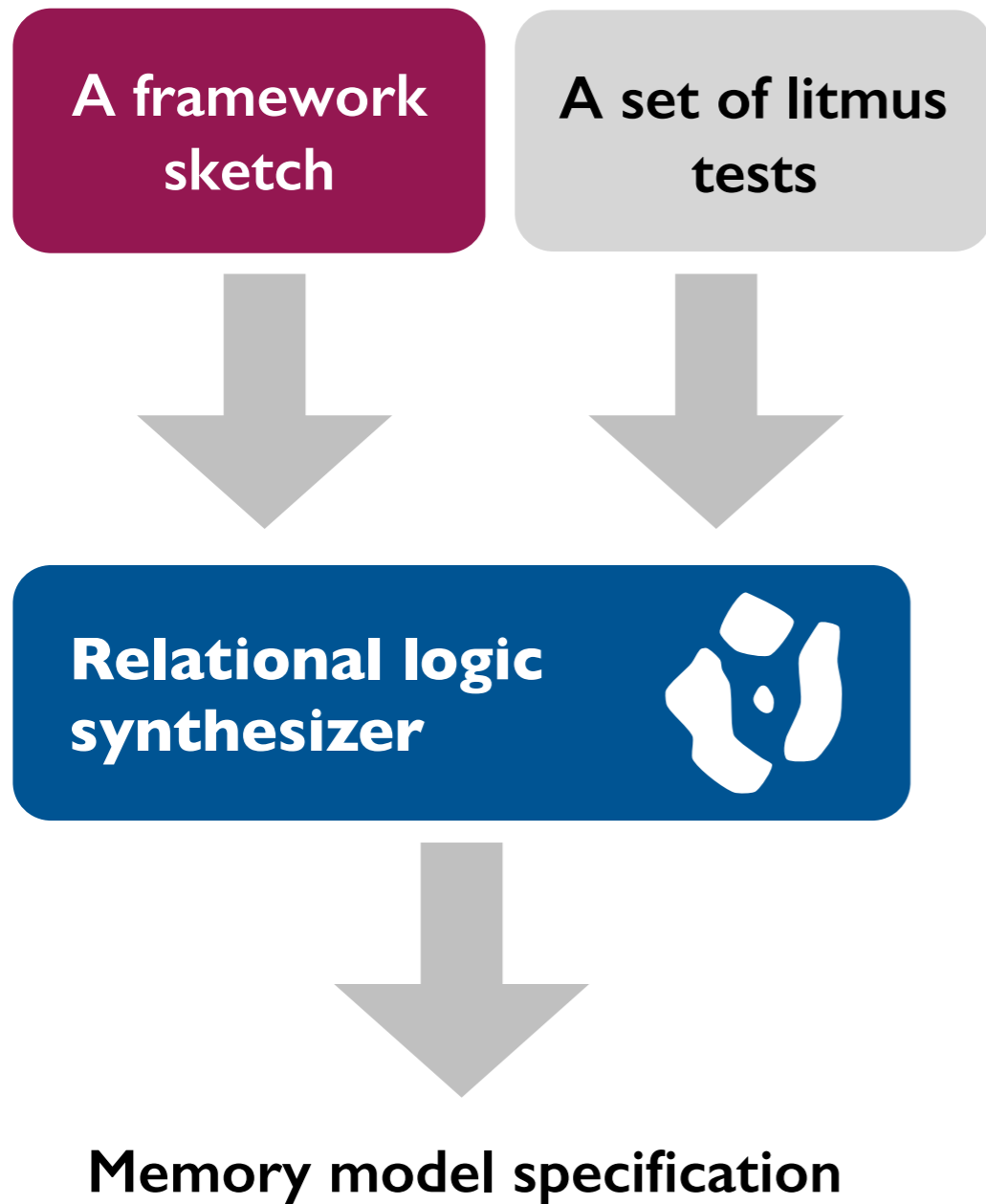


Prototyped in a few weeks and synthesized real memory models.



James Bornholt

# Synthesizing memory models



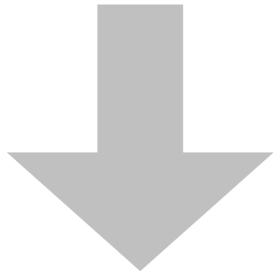
[Bornholt and Torlak, PLDI'17]

Synthesized PowerPC in 12 seconds from 768 previously published tests.

Synthesized x86 in 2 seconds from Intel's litmus tests. Discovered 4 tests are missing from the Intel manual.

# Synthesizing strategies for games and education

		1	2	1	
	1	1	1	1	1
0					
3					
1 1 1					
1 1					
1					



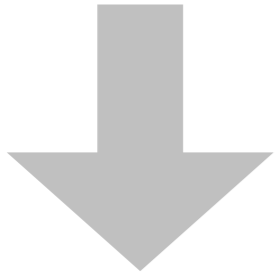
		1	2	1	
	1	1	1	1	1
0	×	×	×	×	×
3	×	■	■	■	×
1 1 1	■	×	■	×	■
1 1	×	■	×	■	×
1	×	×	■	×	×

**Nonograms** game mechanics:

The numbered hints describe how many contiguous blocks of cells are filled with *true*. Cells filled with *true* are marked as a black square and cells filled with *false* as a red X.

# Synthesizing strategies for games and education

		1	2	1	
	1	1	1	1	1
0					
3					
1 1 1					
1 1					
1					



		1	2	1	
	1	1	1	1	1
0	×	×	×	×	×
3	×	■	■	■	×
1 1 1	■	×	■	×	■
1 1	×	■	×	■	×
1	×	×	■	×	×

## Nonograms game mechanics:

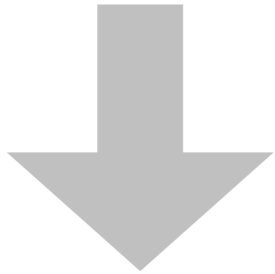
The numbered hints describe how many contiguous blocks of cells are filled with *true*. Cells filled with *true* are marked as a black square and cells filled with *false* as a red X.

A computer solves puzzles by reducing the game mechanics to backtracking search, but human players solve puzzles by using multiple **strategies** to make progress without guessing. Finding these strategies is a key challenge in game design, and is usually done through human testing.



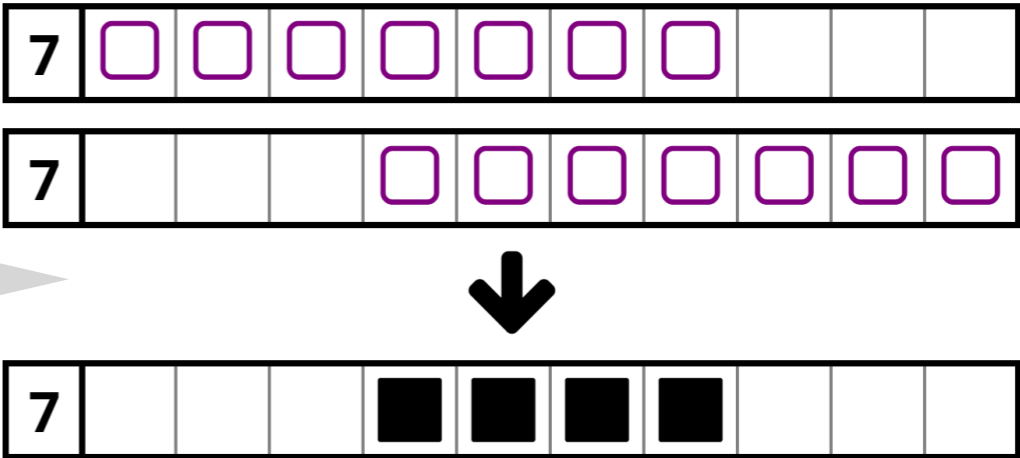
# Synthesizing strategies for games and education

		1	2	1	
	1	1	1	1	1
0					
3					
1 1 1					
1 1					
1					



		1	2	1	
	1	1	1	1	1
0	×	×	×	×	×
3	×	■	■	■	×
1 1 1	■	×	■	×	■
1 1	×	■	×	■	×
1	×	×	■	×	×

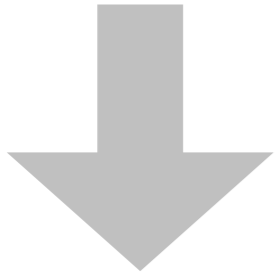
The 'big hint' strategy.



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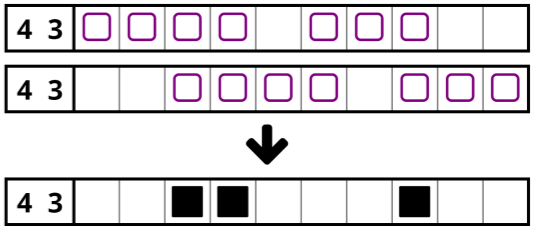
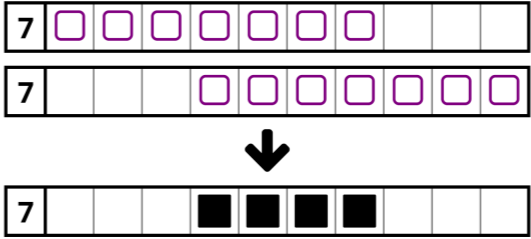
# Synthesizing strategies for games and education

		1	2	1	
	1	1	1	1	1
0					
3					
1 1 1					
1 1					
1					



		1	2	1	
	1	1	1	1	1
0	×	×	×	×	×
3	×	■	■	■	×
1 1 1	■	×	■	×	■
1 1	×	■	×	■	×
1	×	×	■	×	×

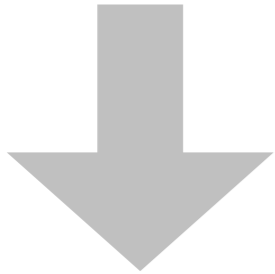
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# Synthesizing strategies for games and education

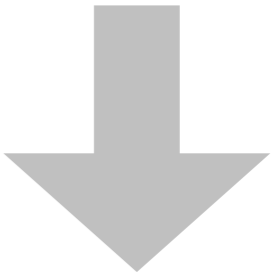
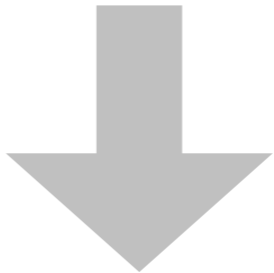
		1	2	1	
	1	1	1	1	1
0					
3					
1 1 1					
1 1					
1					



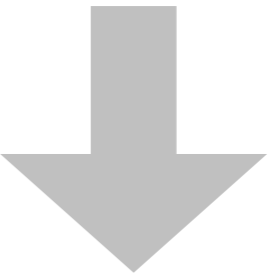
		1	2	1	
	1	1	1	1	1
0	×	×	×	×	×
3	×	■	■	■	×
1 1 1	■	×	■	×	■
1 1	×	■	×	■	×
1	×	×	■	×	×

Game mechanics

Game states for training and testing

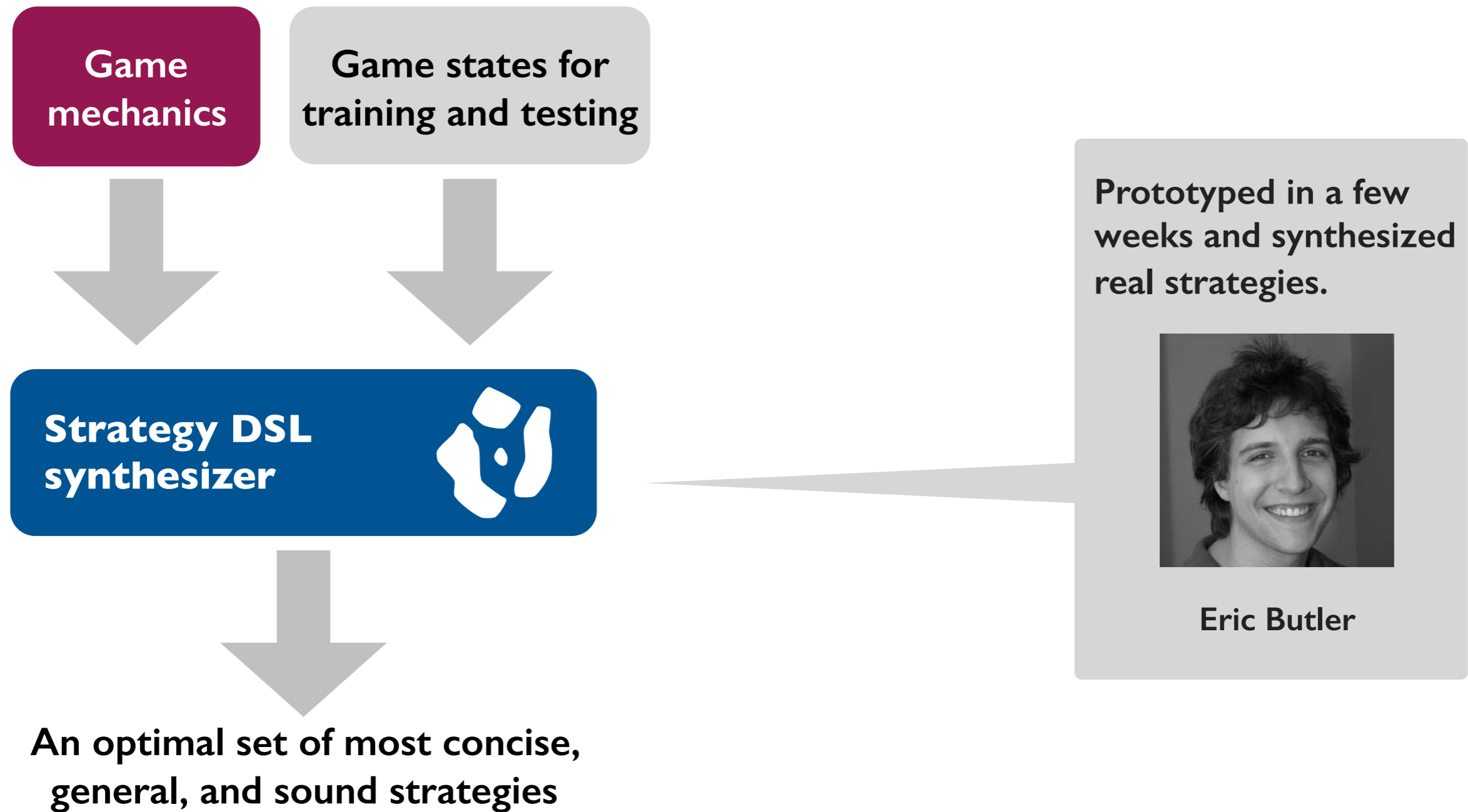


Strategy DSL synthesizer 

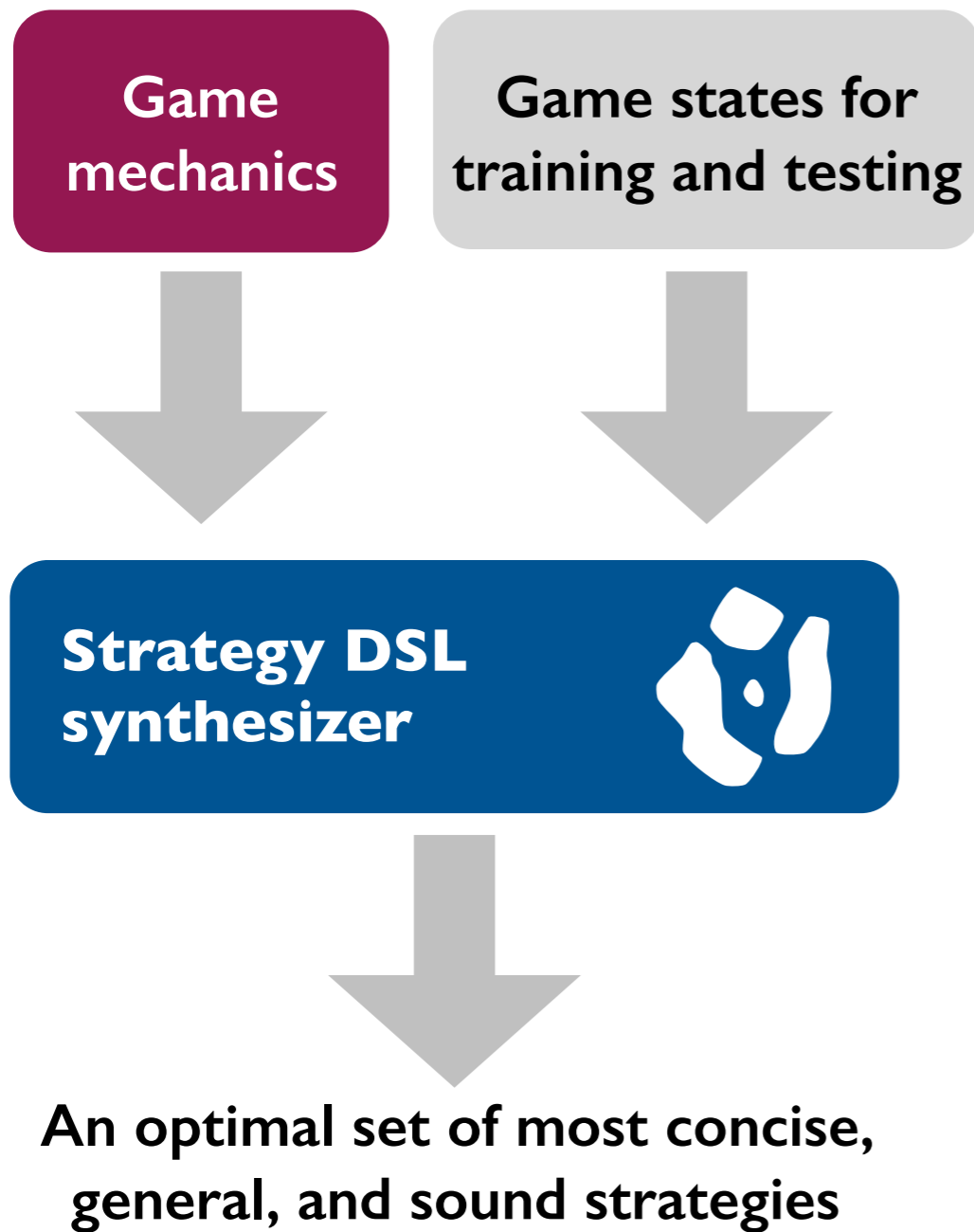


An optimal set of most concise, general, and sound strategies

# Synthesizing strategies for games and education



# Synthesizing strategies for games and education



[Butler et al., FDG'17, VMCAI'18]

Synthesized strategies that outperform documented strategies for Nonograms, both in terms of coverage and quality.

Also used to synthesize strategies for solving K-12 algebra and proofs for propositional logic, recovering and outperforming textbook strategies for these domains.

# Summary

## Today

- Going pro with solver-aided programming.

## Next lecture

- Getting started with SAT solving!