

Computer-Aided Reasoning for Software

Solver-Aided Languages

courses.cs.washington.edu/courses/cse507/18sp/

Emina Torlak

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Today

Last lecture

- Program synthesis

Today

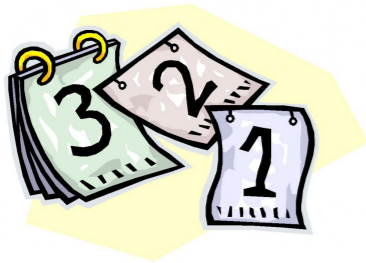
- Solver-aided languages

Announcements

- Next Wednesday: guest lecture by James Bornholt
- Project presentations next Friday in class
 - 13 min per team: 10 min presentation + 3 min questions
- Project reports and prototypes due next Friday at 11:00pm



How to build your own solver-aided tool

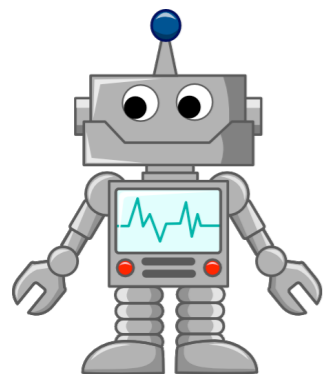


SDSL



SVM

SMT



The classic (hard) way to build a tool

What is hard about building a solver-aided tool?

An easier way: tools as languages

How to build tools by stacking layers of languages.

Behind the scenes: symbolic virtual machine

How Rosette works so you don't have to.

A last look: a few recent applications

Cool tools built with Rosette!

How to build your own solver-aided tool

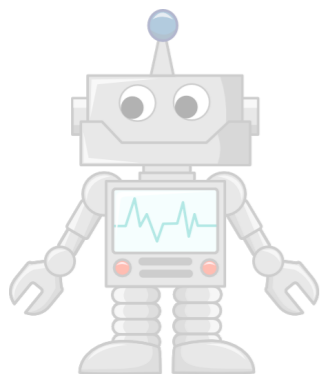


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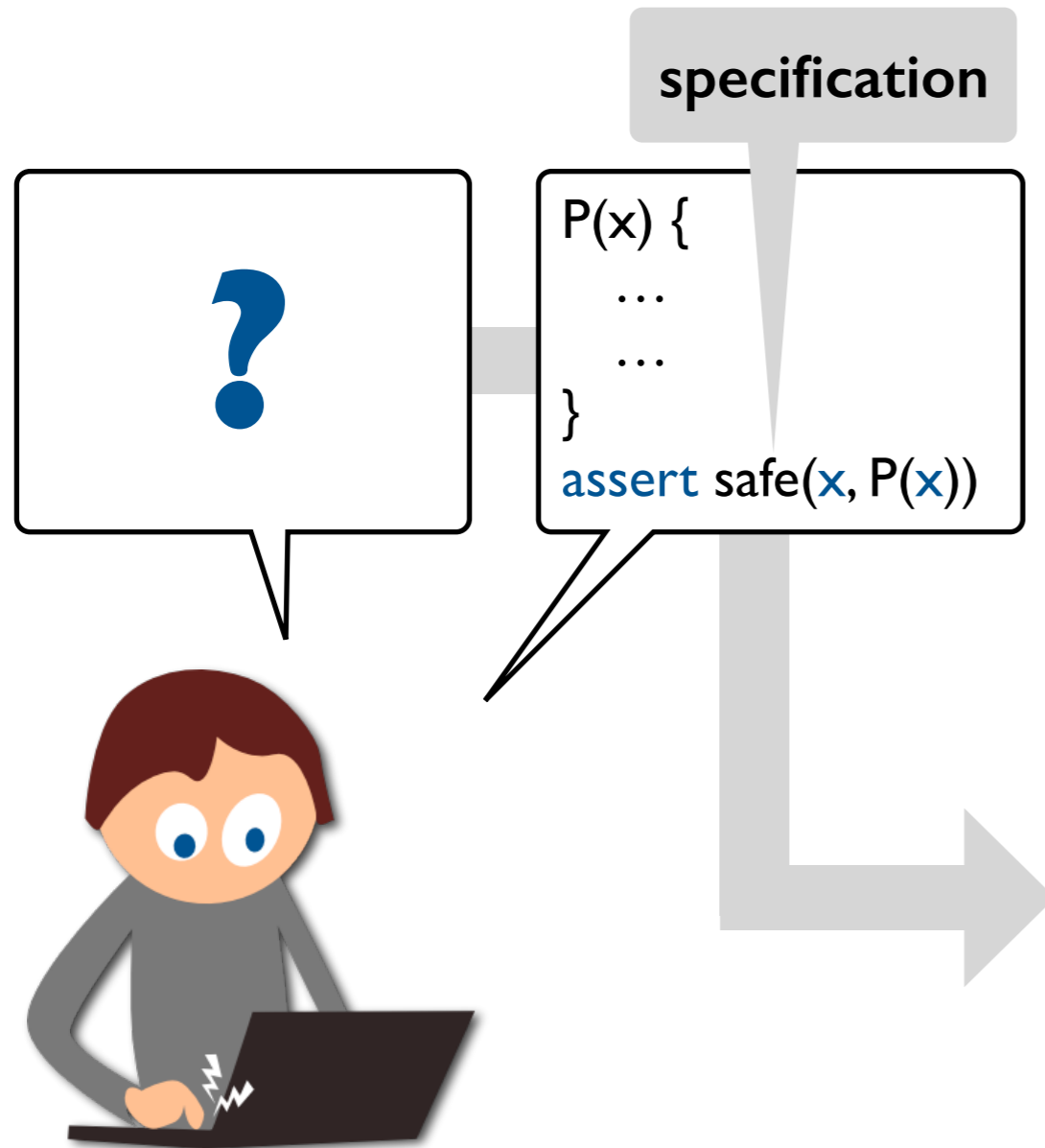
Behind the scenes: symbolic virtual machine

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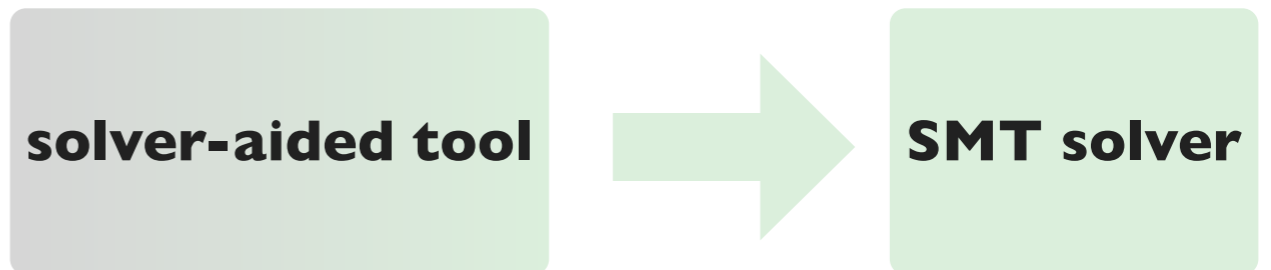
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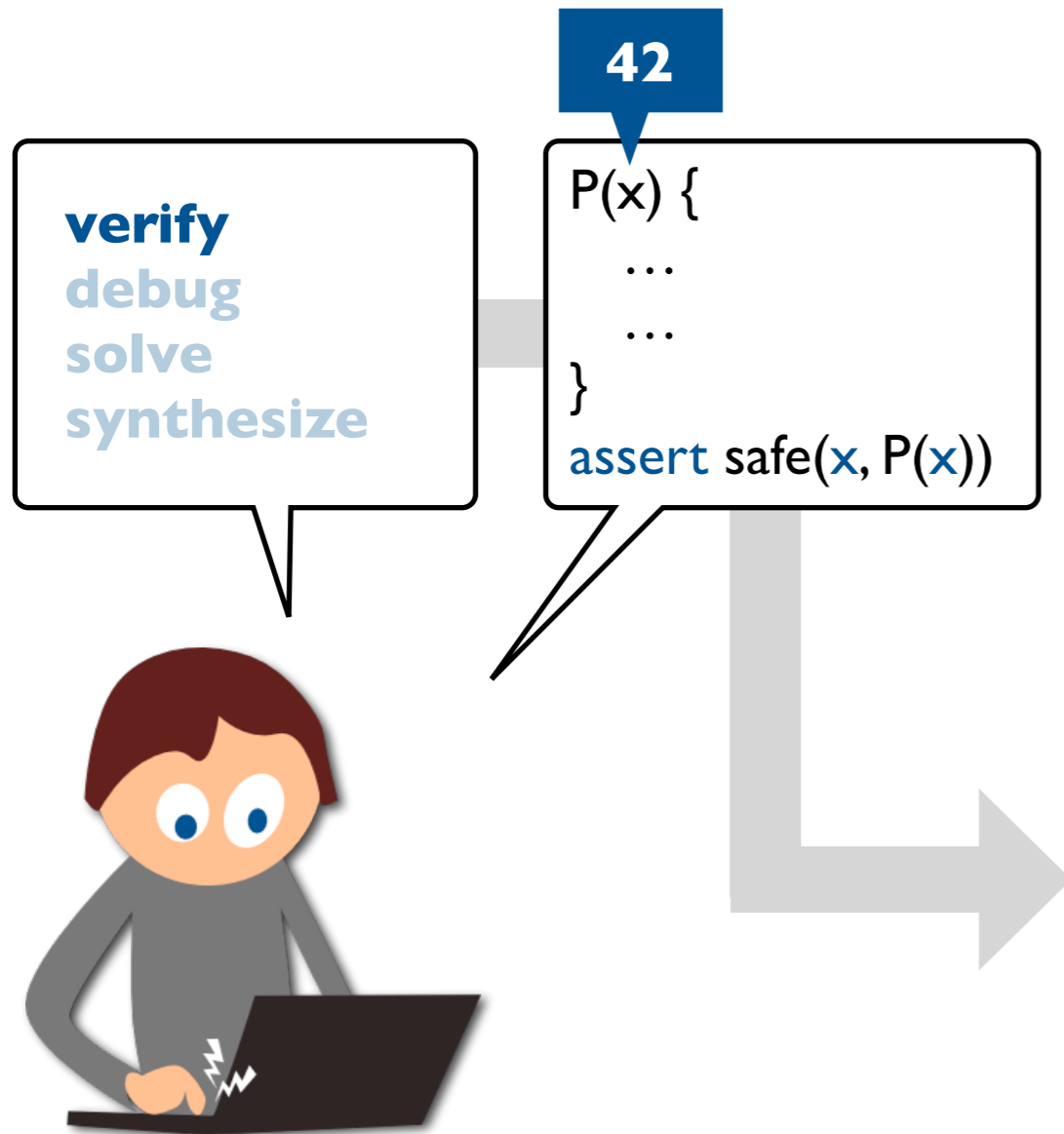
The classic (hard) way to build a tool



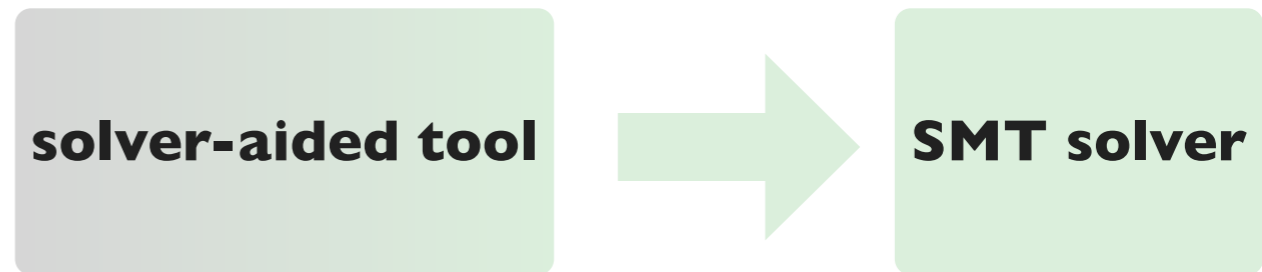
Recall the solver-aided programming tool chain: the tool reduces a query about program behavior to an SMT problem.



The classic (hard) way to build a tool

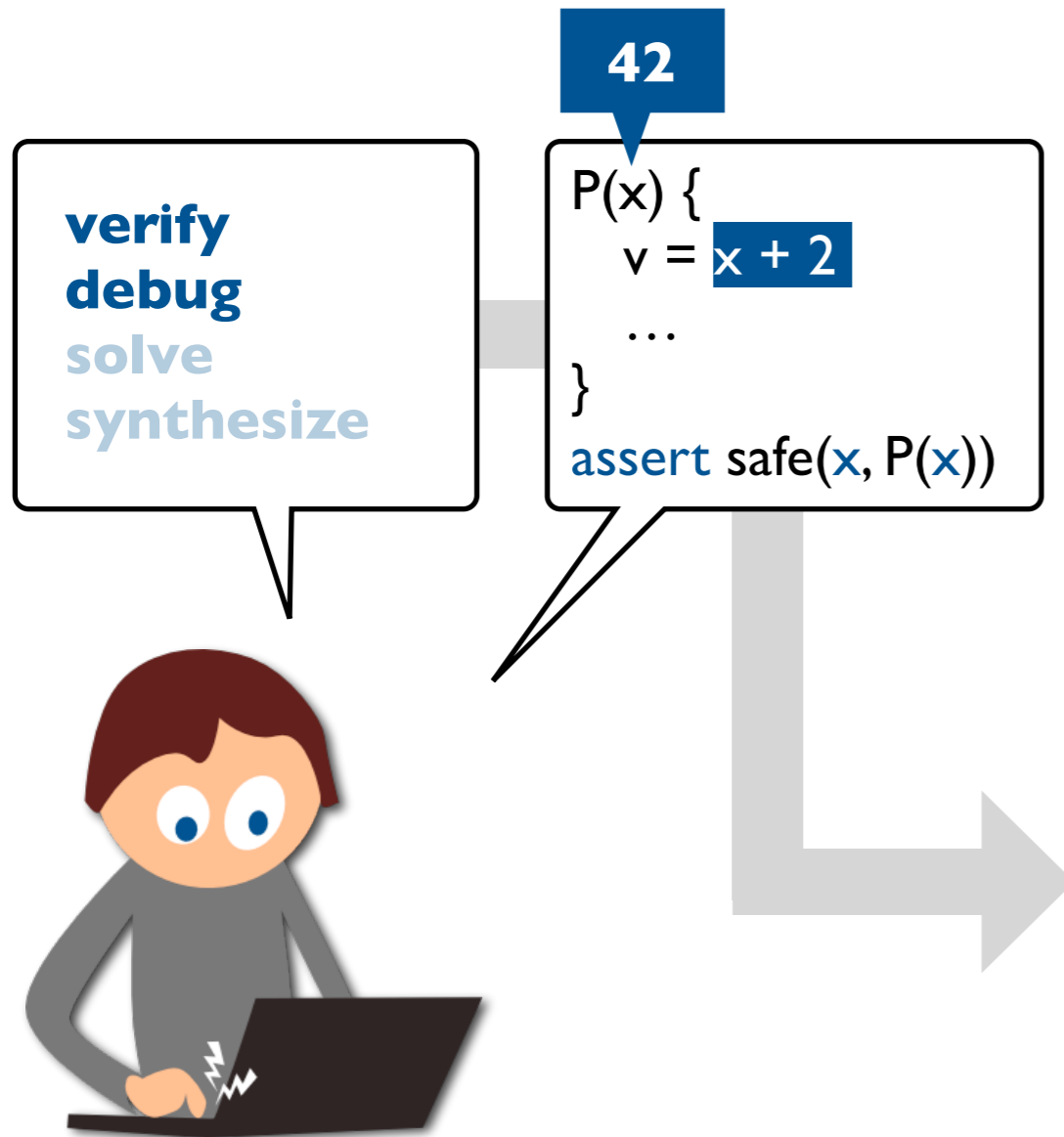


Find an input on which the program fails.

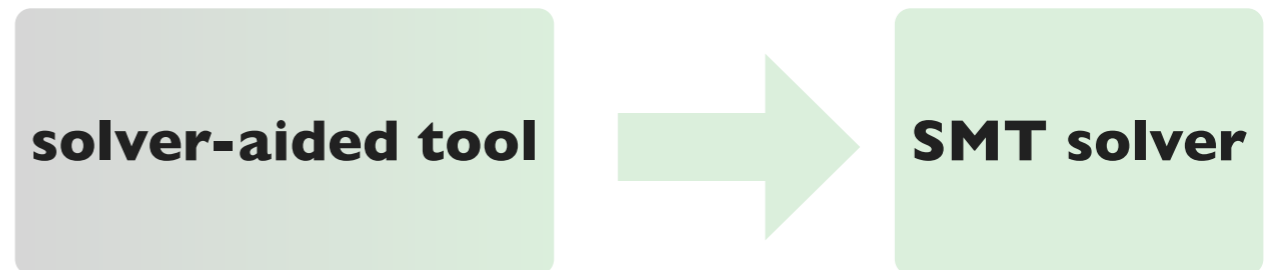


$\exists x . \neg \text{safe}(x, P(x))$

The classic (hard) way to build a tool

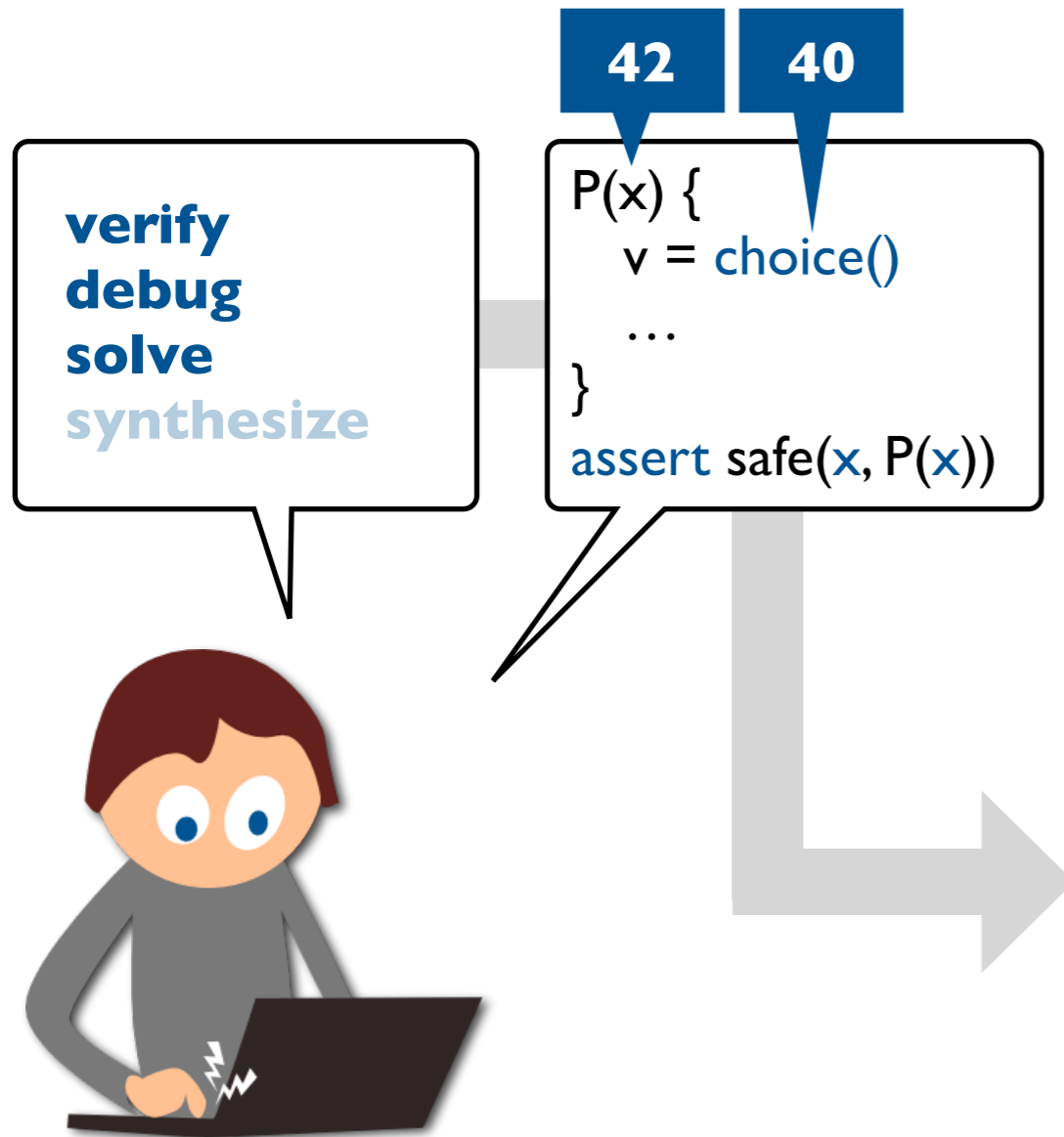


Find an input on which the program fails.
Localize bad parts of the program.



$\exists x . \neg \text{safe}(x, \mathbf{P}(x))$
 $x = 42 \wedge \text{safe}(x, \mathbf{P}(x))$

The classic (hard) way to build a tool

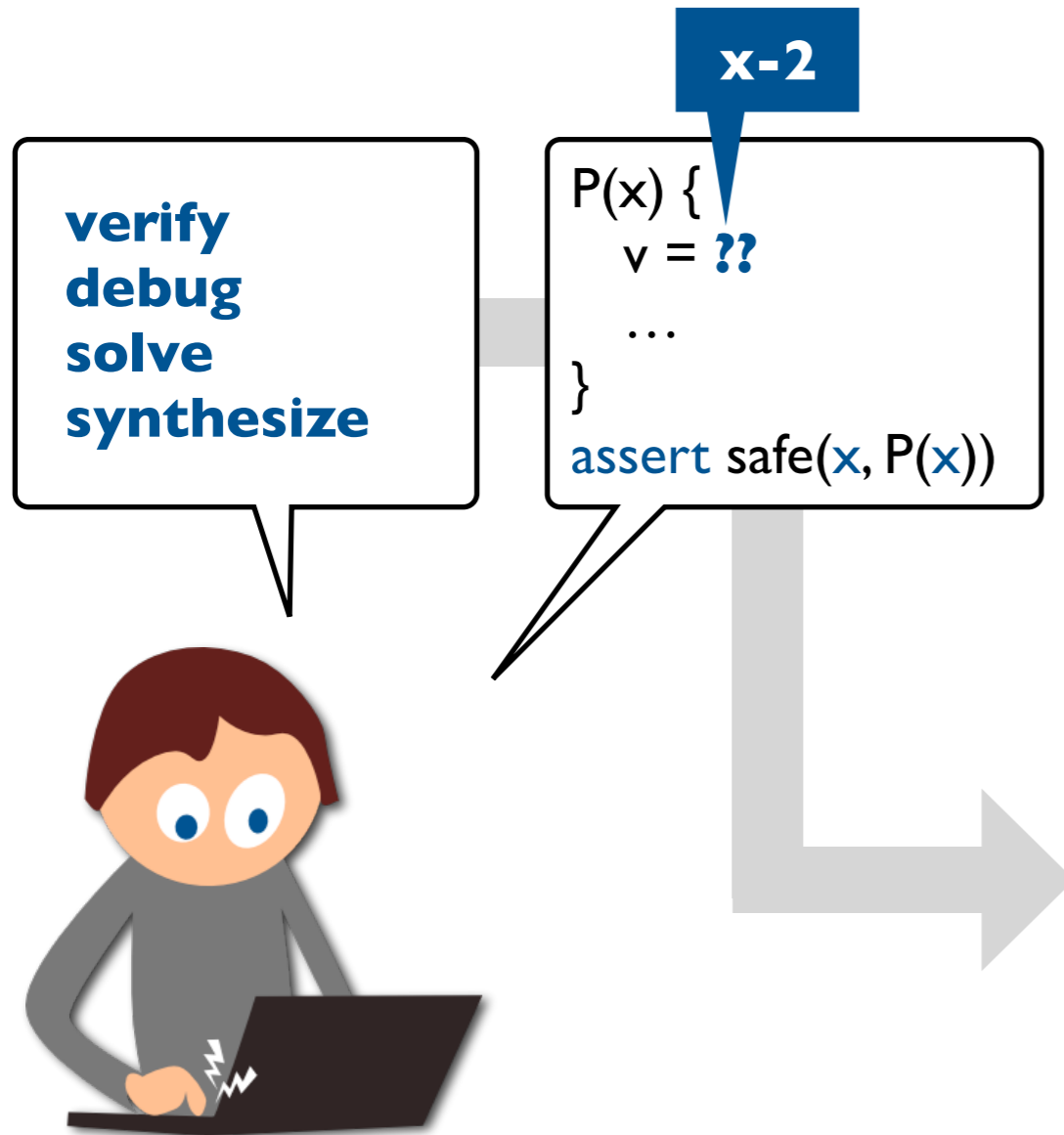


Find an input on which the program fails.
Localize bad parts of the program.
Find values that repair the failing run.

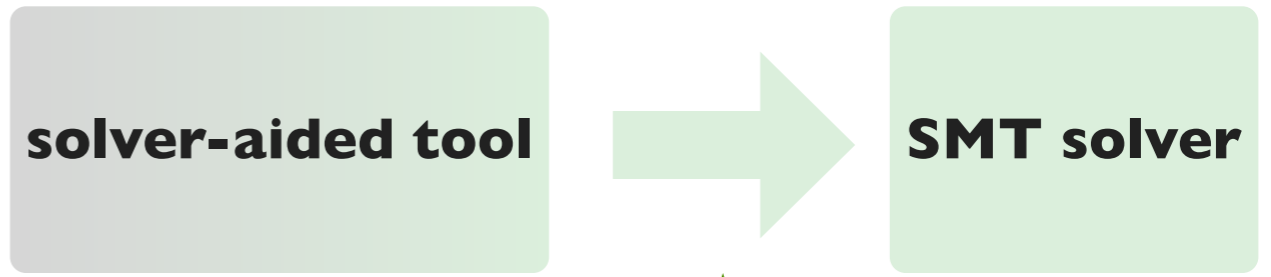


$\exists x . \neg \mathbf{safe}(x, \mathbf{P}(x))$
 $x = 42 \wedge \mathbf{safe}(x, \mathbf{P}(x))$
 $\exists v . \mathbf{safe}(42, \mathbf{P}_v(42))$

The classic (hard) way to build a tool

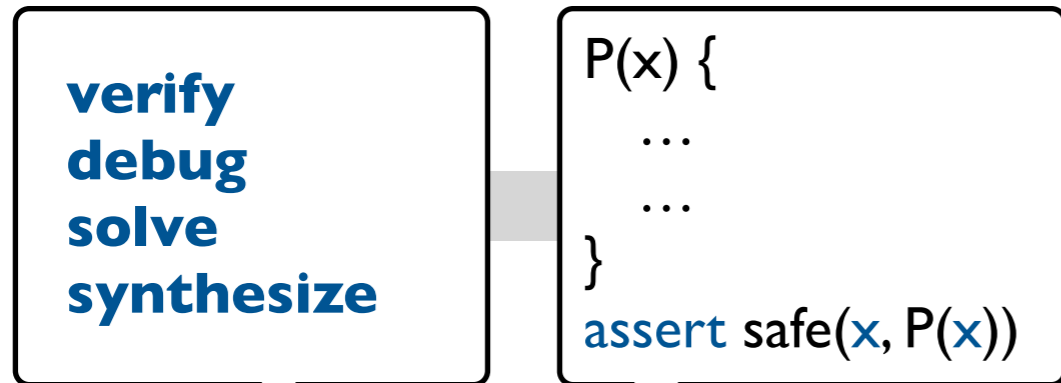


- Find an input on which the program fails.
- Localize bad parts of the program.
- Find values that repair the failing run.
- Find code that repairs the program.

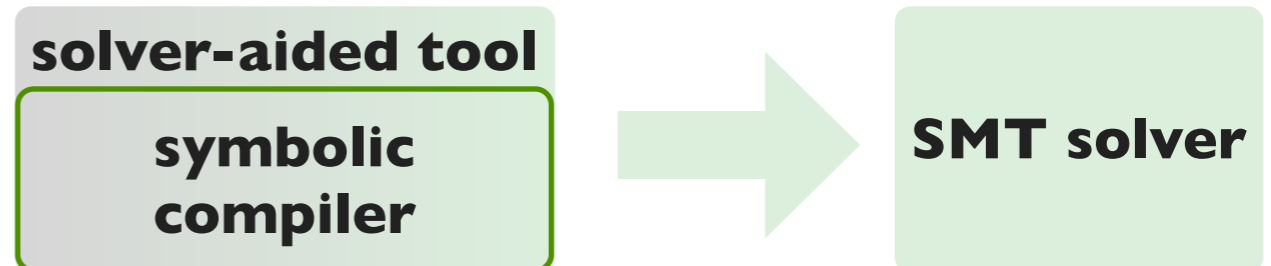


$\exists x . \neg \mathbf{safe}(x, \mathbf{P}(x))$
 $x = 42 \wedge \mathbf{safe}(x, \mathbf{P}(x))$
 $\exists v . \mathbf{safe}(42, \mathbf{P}_v(42))$
 $\exists e . \forall x . \mathbf{safe}(x, \mathbf{P}_e(x))$

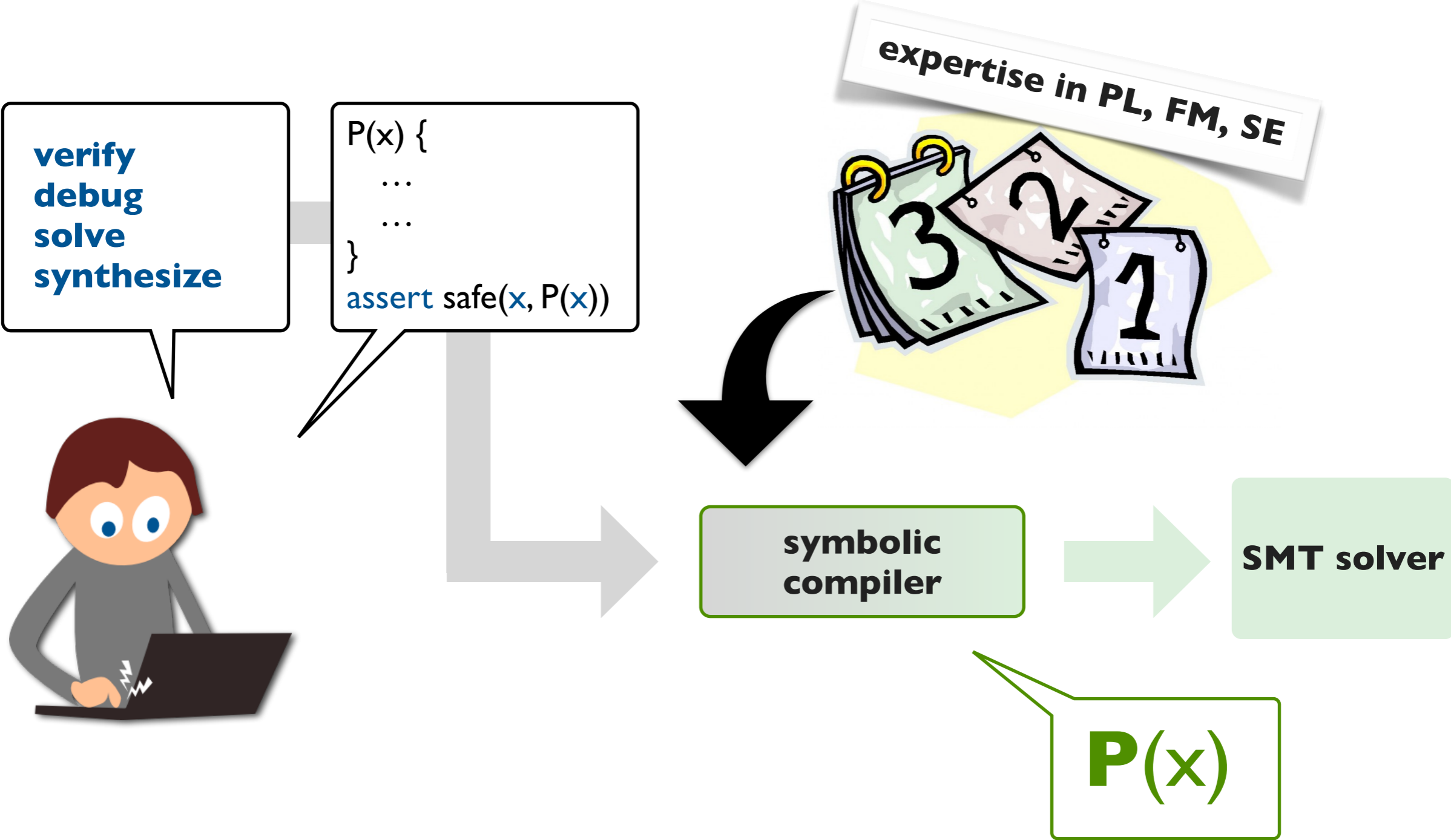
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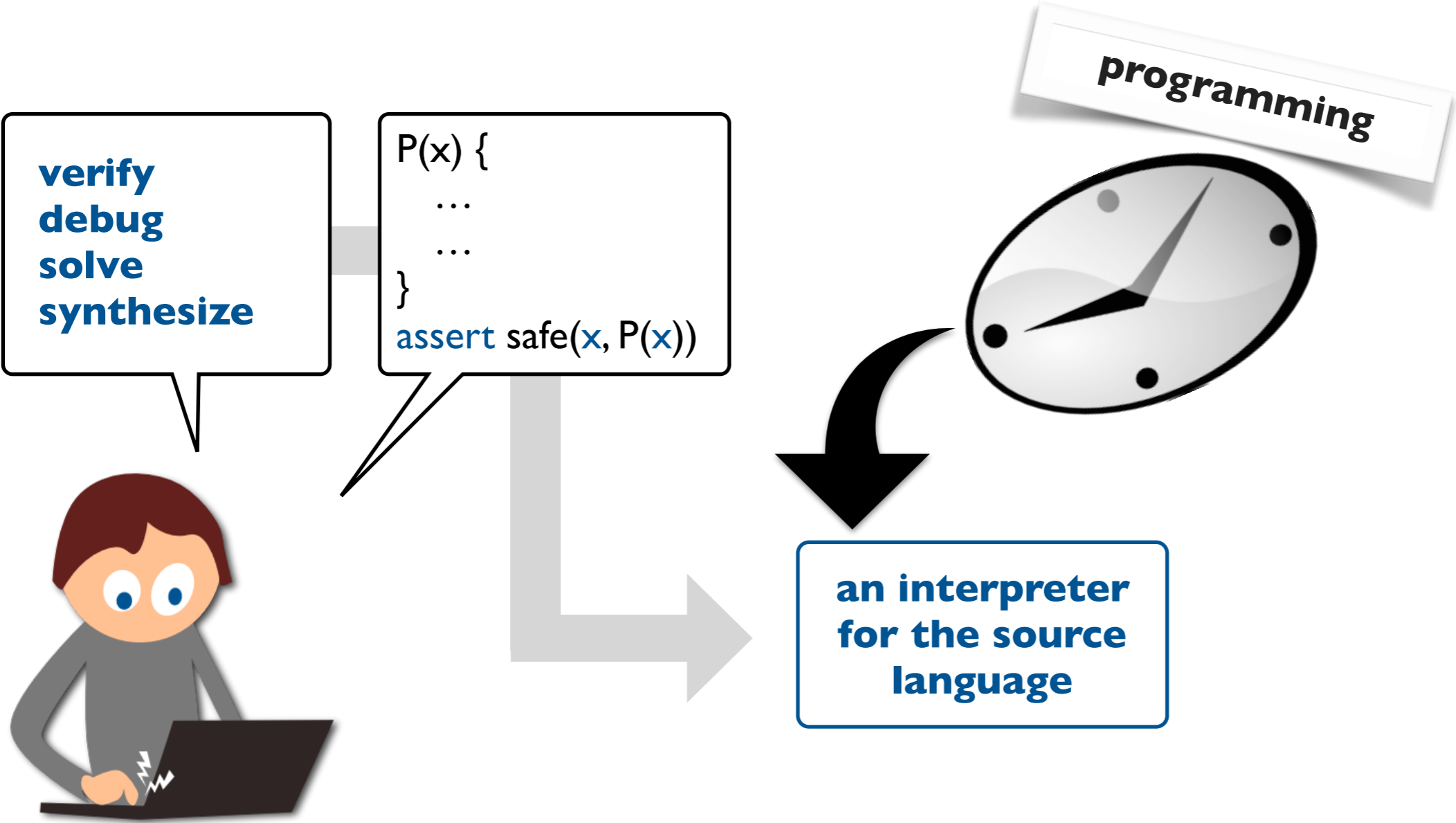
What all queries have in common: they need to translate programs to constraints!



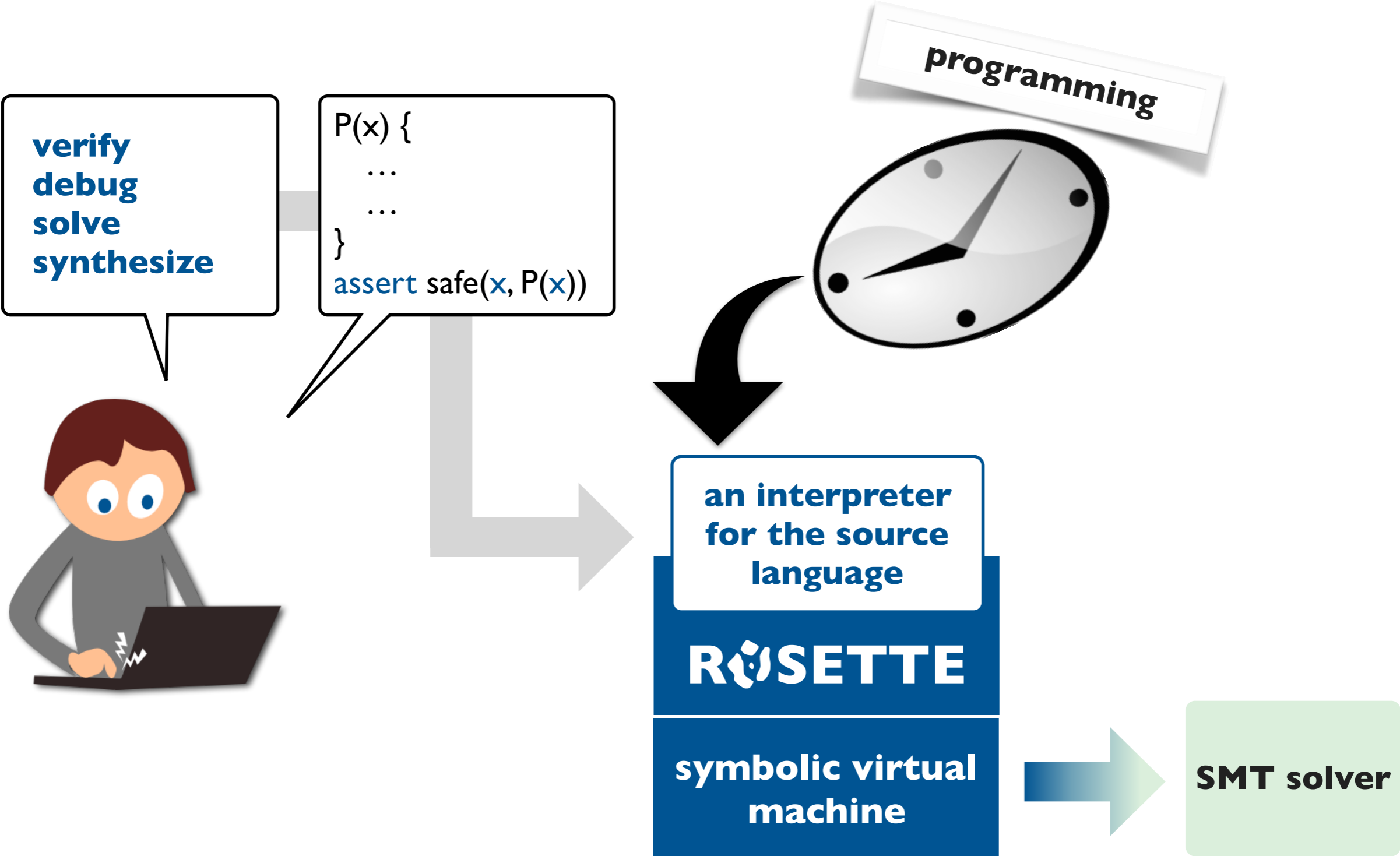
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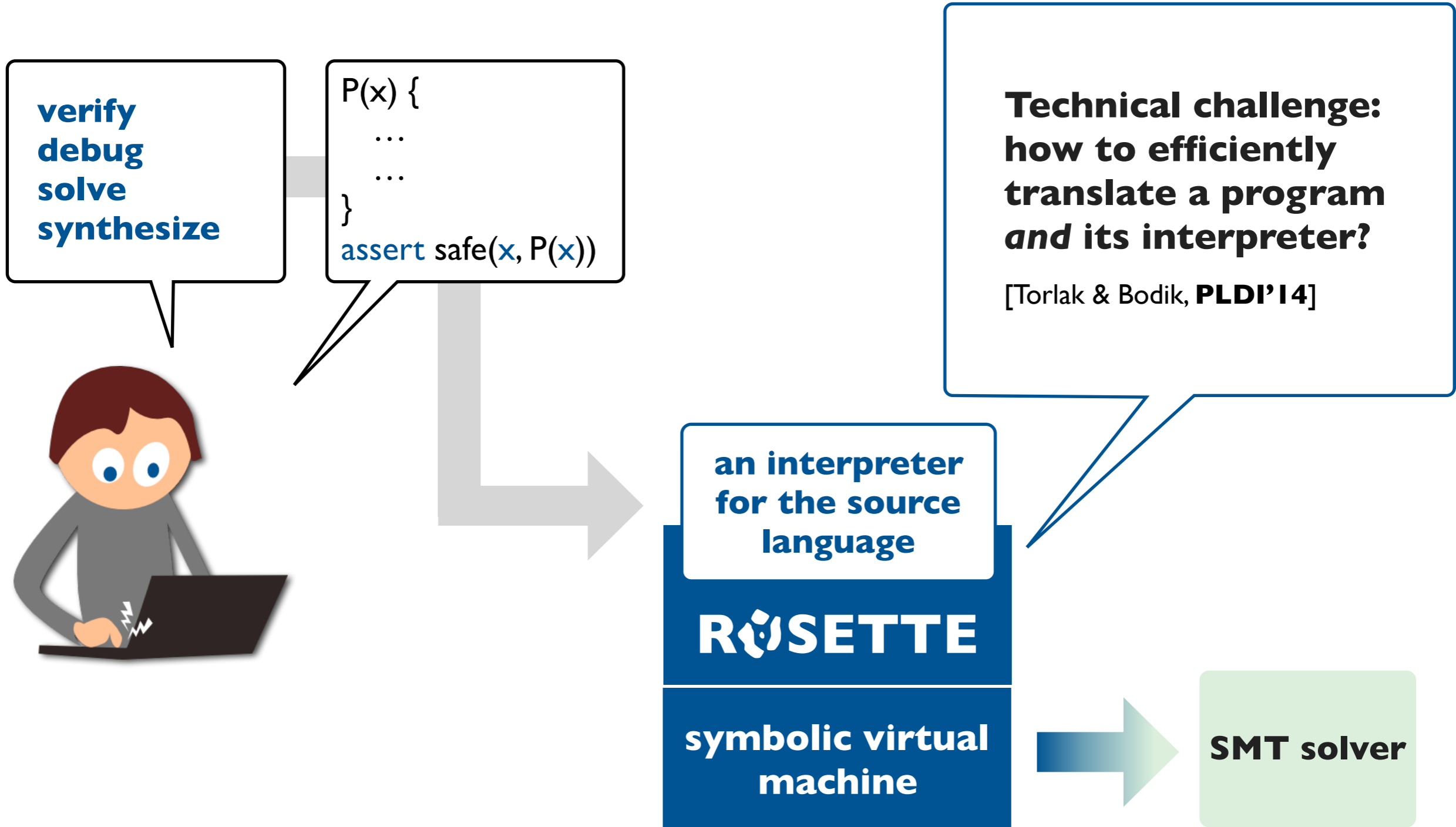
Wanted: an easier way to build tools



Wanted: an easier way to build tools



Wanted: an easier way to build tools



How to build your own solver-aided tool

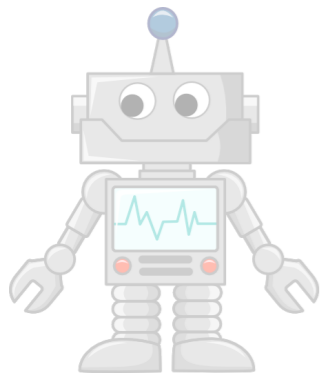


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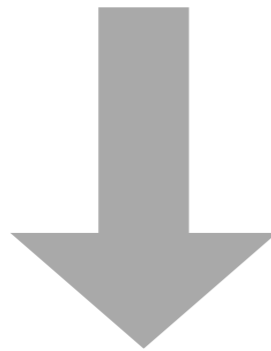
How Rosette works so you don't have to.

A last look: a few recent applications

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Layers of classic languages: DSLs and hosts

**domain-specific language
(DSL)**



host language

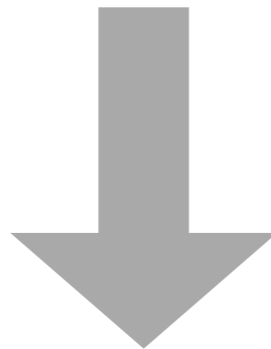
A formal language that is specialized to a particular application domain and often limited in capability.

A high-level language for implementing DSLs, usually with meta-programming features.

Layers of classic languages: DSLs and hosts

**domain-specific language
(DSL)**

library
(*shallow*)
embedding



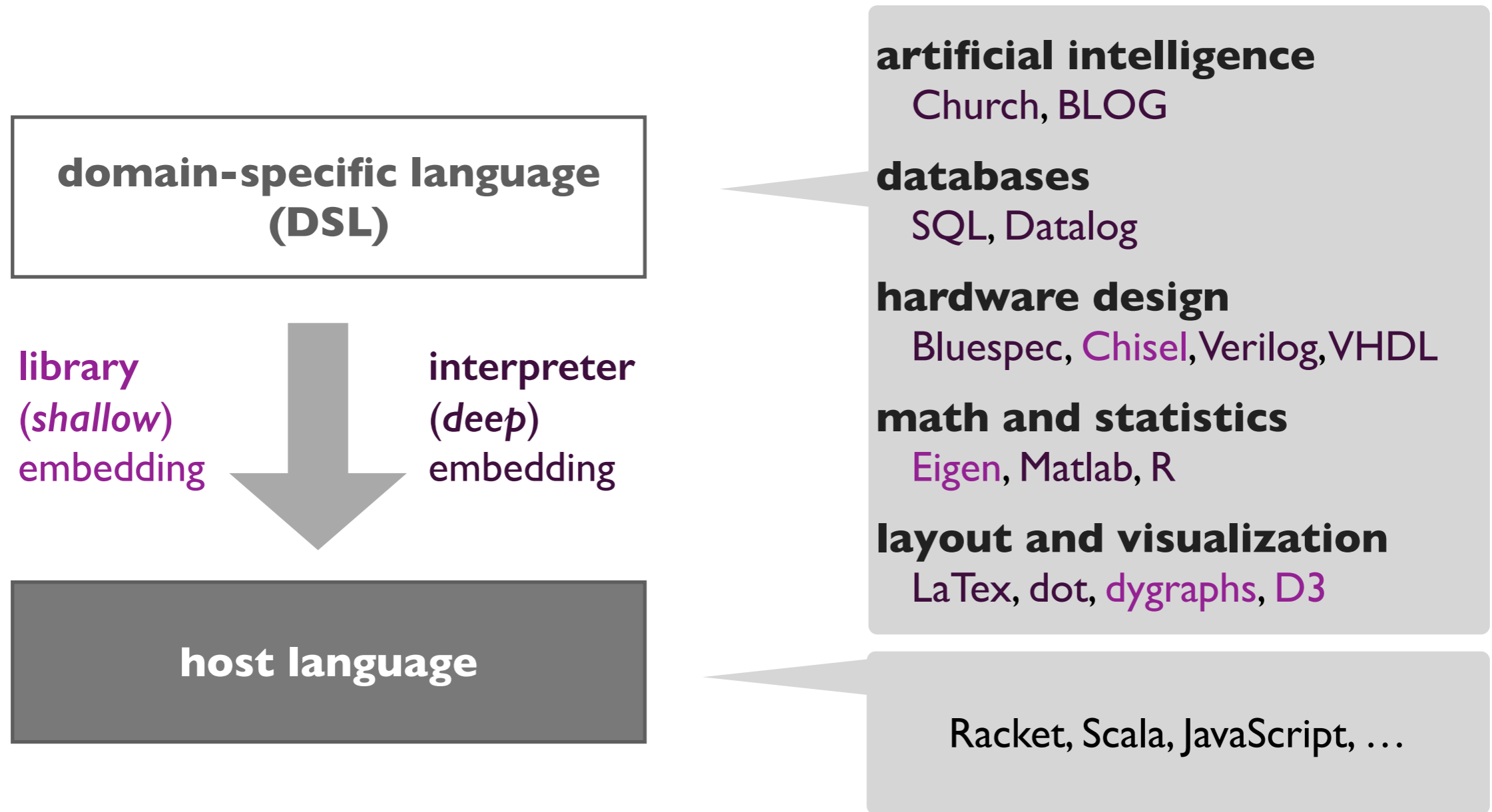
interpreter
(*deep*)
embedding

host language

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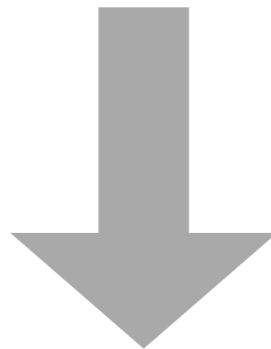
Layers of classic languages: many DSLs and hosts



Layers of classic languages: why DSLs?

**domain-specific language
(DSL)**

library
(*shallow*)
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host language

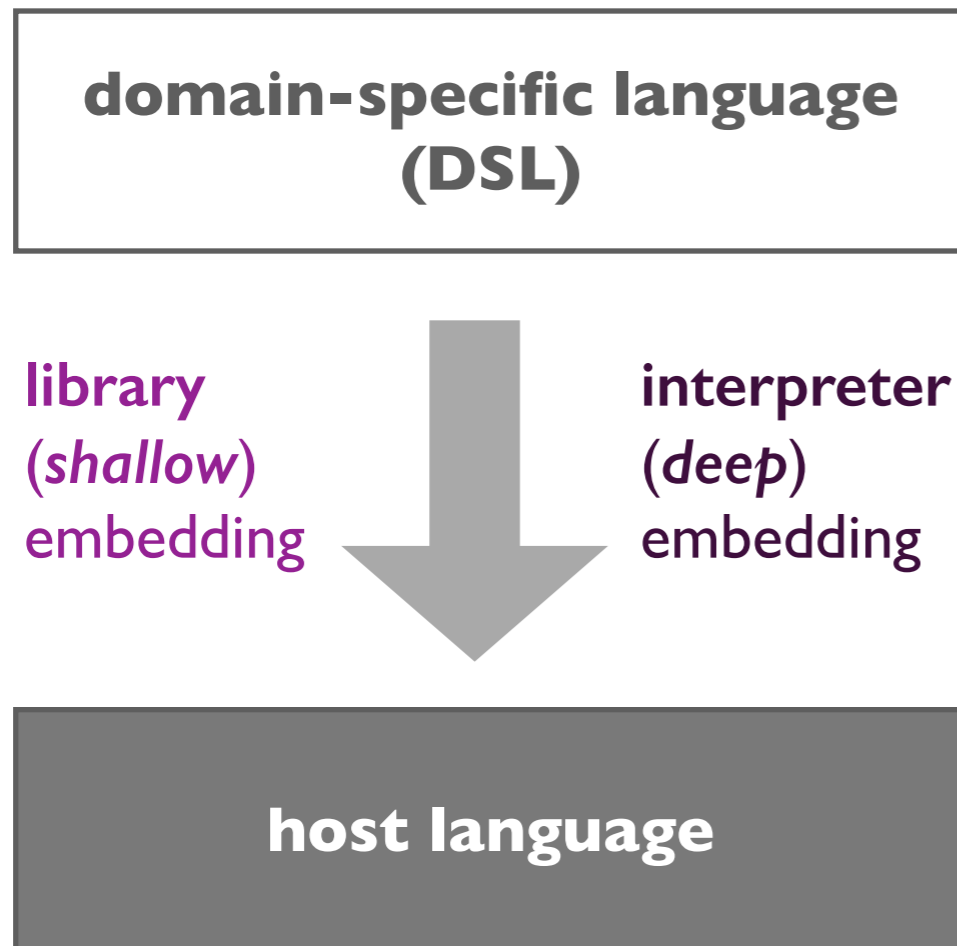
Eigen / Matlab

```
C = A * B
```

C / Java

```
for (i = 0; i < n; i++)  
  for (j = 0; j < m; j++)  
    for (k = 0; k < p; k++)  
      C[i][k] += A[i][j] * B[j][k]
```

Layers of classic languages: why DSLs?



Easier for people to read, write, and get right.

Eigen / Matlab
 $C = A * B$
[associativity]

Easier for tools to analyze.

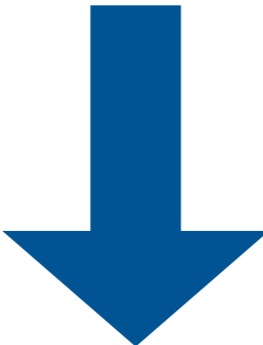
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Layers of solver-aided languages

solver-aided domain-specific language (SDSL)

library
(*shallow*)
embedding



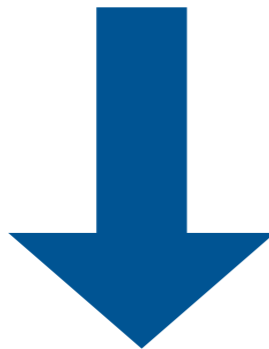
interpreter
(*deep*)
embedding

solver-aided host language

Layers of solver-aided languages: tools as SDSLs

solver-aided domain-specific language (SDSL)

library
(*shallow*)
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ROSETTE

education and games

Enlearn, RuleSy (VMCAI'18),
Nonograms (FDG'17), UCB feedback
generator (ITiCSE'17)

synthesis-aided compilation

LinkiTools, Chlorophyll (PLDI'14),
GreenThumb (ASPLOS'16)

type system soundness

Bonsai (POPL'18)

computer architecture

MemSynth (PLDI'17)

databases

Cosette (CIDR'17)

radiation therapy control

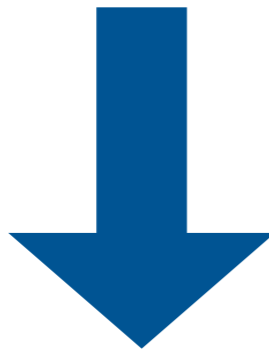
Neutrons (CAV'16)

... and more

Layers of solver-aided languages: tools as SDSLs

solver-aided domain-specific language (SDSL)

library
(*shallow*)
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radiation therapy control

Neutrons (CAV'16)

... and more

The anatomy of a solver-aided host language



=



+

```
(define-symbolic id type)  
(define-symbolic* id type)
```

**symbolic
values**

```
(assert expr)
```

assertions

```
(verify expr)
```

```
(debug [type ...+] expr)
```

```
(solve expr)
```

```
(synthesize
```

```
  #:forall expr
```

```
  #:guarantee expr)
```

queries

A tiny example SDSL

```
def bvmax(r0, r1) :  
    r2 = bvsge(r0, r1)  
    r3 = bvneg(r2)  
    r4 = bvxor(r0, r2)  
    r5 = bvand(r3, r4)  
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return r6
```

BV: A tiny assembly-like language for writing fast, low-level library functions.

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We want to **test, verify, debug,** and **synthesize** programs in the BV SDSL.

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BV: A tiny assembly-like language for writing fast, low-level library functions.

1. interpreter [10 LOC]
2. verifier [free]
3. debugger [free]
4. synthesizer [free]

A tiny example SDSL

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```
> bvmax(-2, -1)
```

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```
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parse

```
(define bvmax  
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(out opcode in ...)

A tiny example SDSL

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RÖSETTE

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```
`(-2 -1)
```

interpret

```
(define (interpret prog inputs)  
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1	-1
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ROSETTE

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       (define op (eval opcode))  
       (define args (map load in))  
       (store out (apply op args))]))  
  (load (last)))
```

A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> bvmax(-2, -1)  
-1
```

ROSETTE

```
(define bvmax  
  `((2 bvsge 0 1)  
    (3 bvneg 2)  
    (4 bvxor 0 2)  
    (5 bvand 3 4)  
    (6 bvxor 1 5)))
```

- ▶ pattern matching
- ▶ dynamic evaluation
- ▶ first-class & higher-order procedures
- ▶ side effects

```
(define (interpret prog inputs)  
  (make-registers prog inputs)  
  (for ([stmt prog])  
    (match stmt  
      [(list out opcode in ...)   
       (define op (eval opcode))  
       (define args (map load in))  
       (store out (apply op args))]))  
  (load (last)))
```

A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
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  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> verify(bvmax, max)
```

query →

RŌ**S**ETTE

```
(define-symbolic* in (bitvector 32) [2])  
(verify  
  (assert (equal? (interpret bvmax in)  
                   (interpret max in))))
```


A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> verify(bvmax, max)  
(0, -2)
```



query

R₀SETTE

```
(define-symbolic* in (bitvector 32) [2])  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
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A tiny example SDSL

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  r2 = bvsge(r0, r1)  
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  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> verify(bvmax, max)  
(0, -2)
```

```
> bvmax(0, -2)  
-1
```



ROSETTE

```
(define-symbolic* in (bitvector 32) [2])  
(verify  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

A tiny example SDSL

ROSETTE

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> debug(bvmax, max, '(0, -2))
```

query

```
(define in (list (bv 0 32) (bv -2 32)))  
(debug [integer?]  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

A tiny example SDSL

R⁰SETTE

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r2)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6
```

```
> debug(bvmax, max, '(0, -2))
```

query

```
(define in (list (bv 0 32) (bv -2 32)))  
(debug [integer?]  
  (assert (equal? (interpret bvmax in)  
                   (interpret max in))))
```

A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(??, ??)  
  r5 = bvand(r3, ??)  
  r6 = bvxor(??, ??)  
  return r6  
  
> synthesize(bvmax, max)
```

query

ROSETTE

```
(define-symbolic* in (bitvector 32) [2])  
(synthesize  
  #:forall in  
  #:guarantee  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))
```

A tiny example SDSL

```
def bvmax(r0, r1) :  
  r2 = bvsge(r0, r1)  
  r3 = bvneg(r2)  
  r4 = bvxor(r0, r1)  
  r5 = bvand(r3, r4)  
  r6 = bvxor(r1, r5)  
  return r6  
  
> synthesize(bvmax, max)
```



query

ROSETTE

```
(define-symbolic* in (bitvector 32) [2])  
(synthesize  
  #:forall in  
  #:guarantee  
  (assert (equal? (interpret bvmax in)  
                  (interpret max in))))))
```

How to build your own solver-aided tool

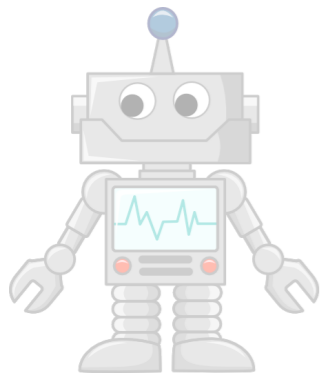


SDSL



SVM

SMT



The classic (hard) way to build a tool

What is hard about building a solver-aided tool?

An easier way: tools as languages

How to build tools by stacking layers of languages.

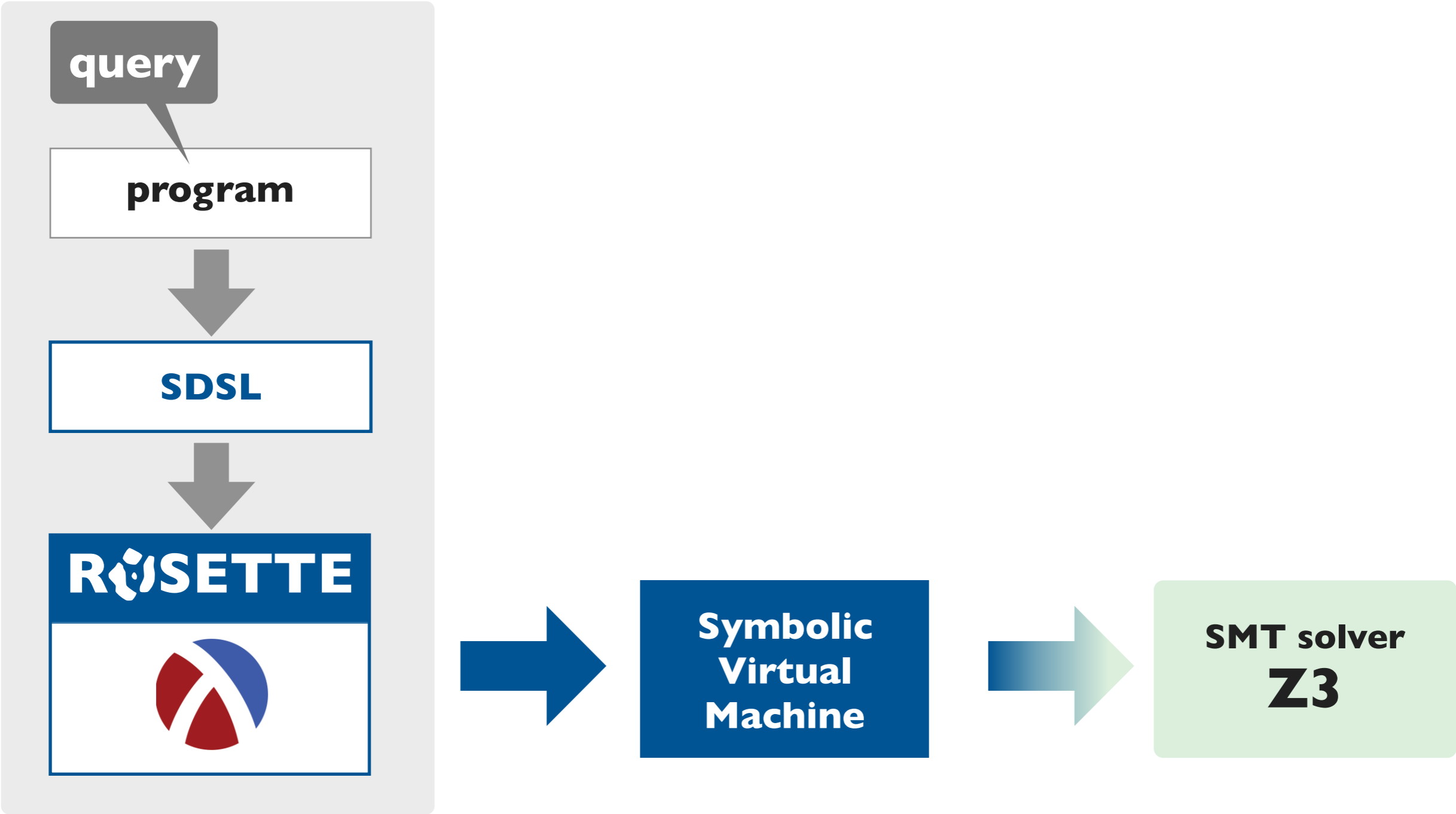
Behind the scenes: symbolic virtual machine

How Rosette works so you don't have to.

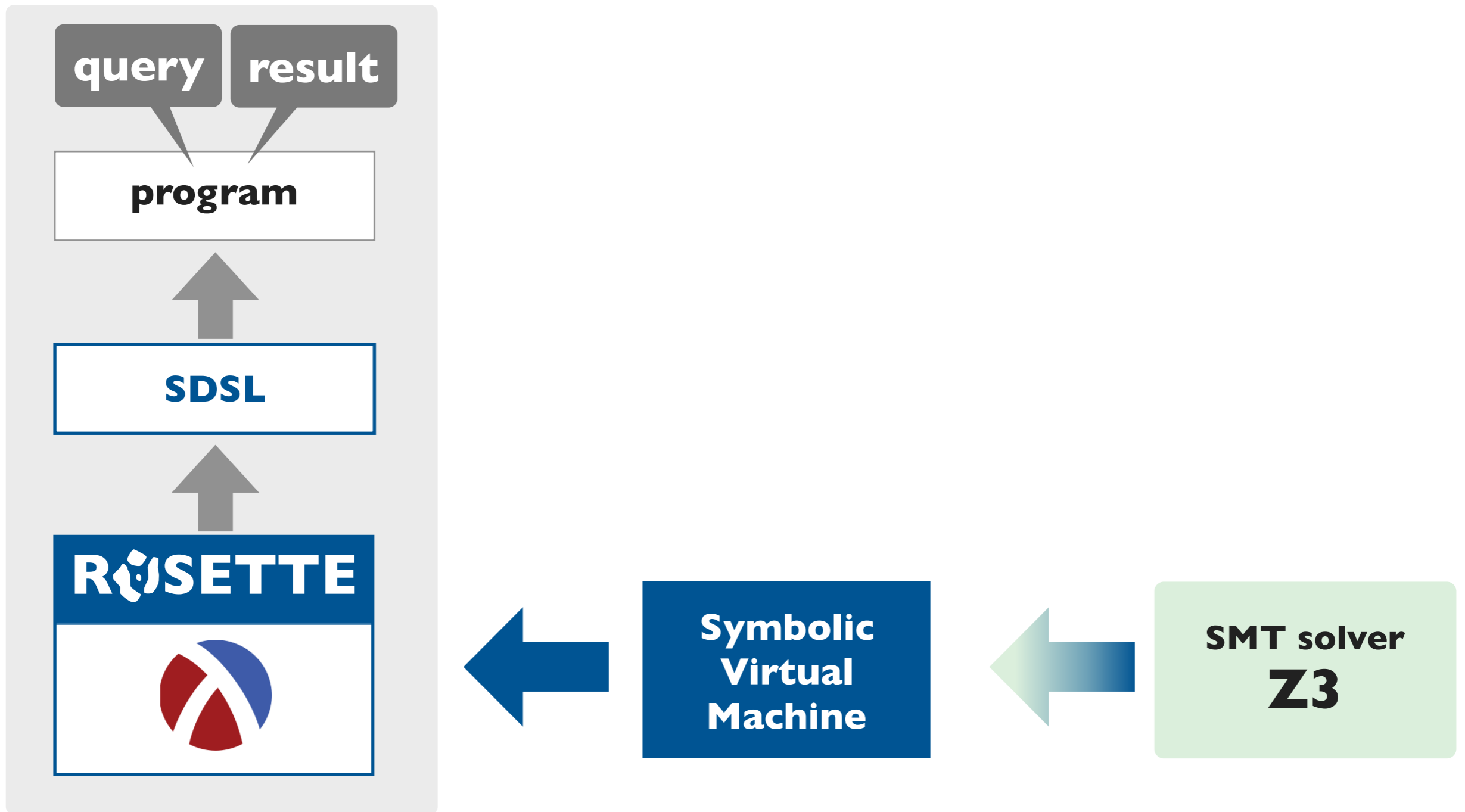
A last look: a few recent applications

Cool tools built with Rosette!

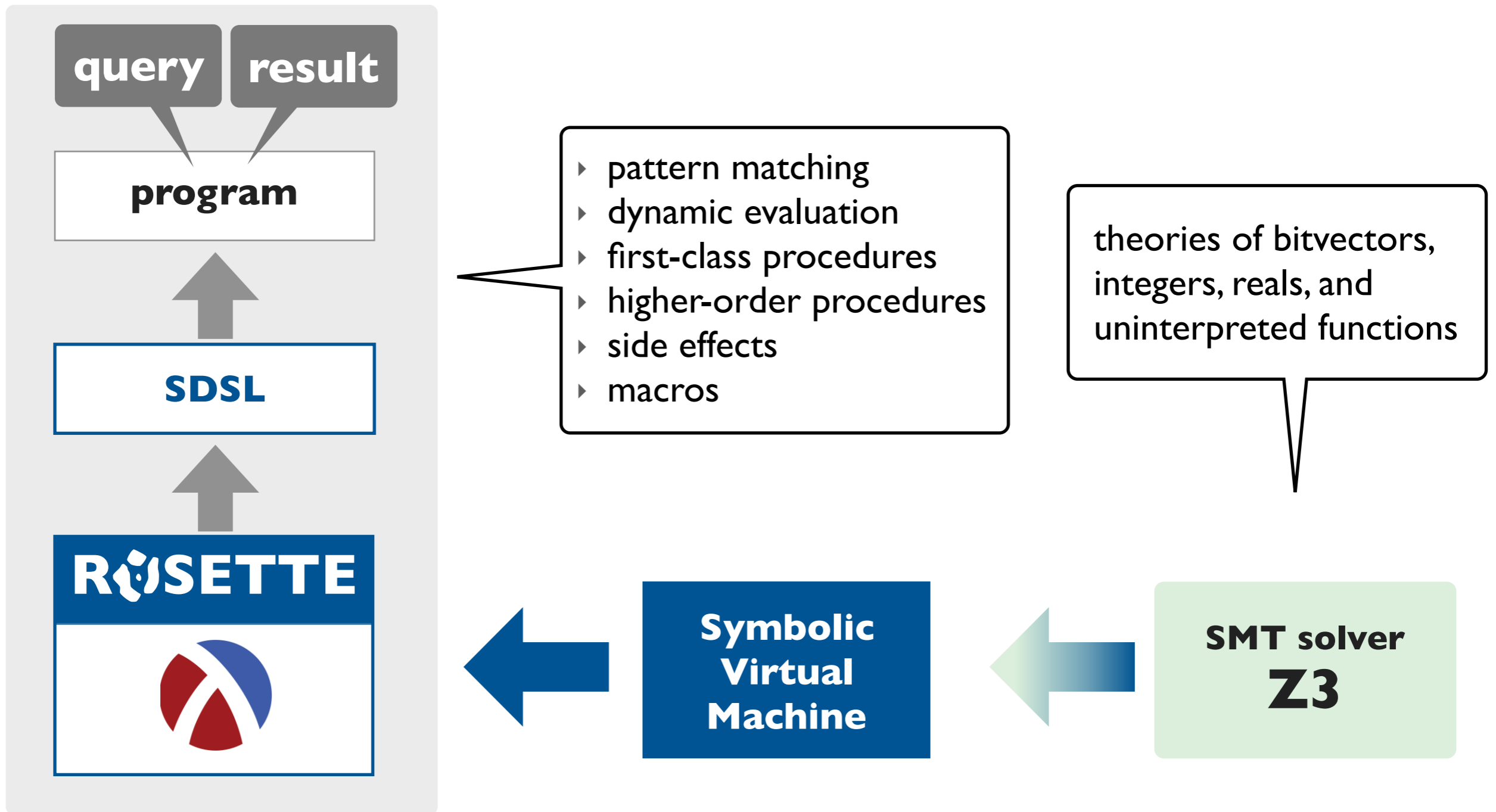
How it all works: a big picture view



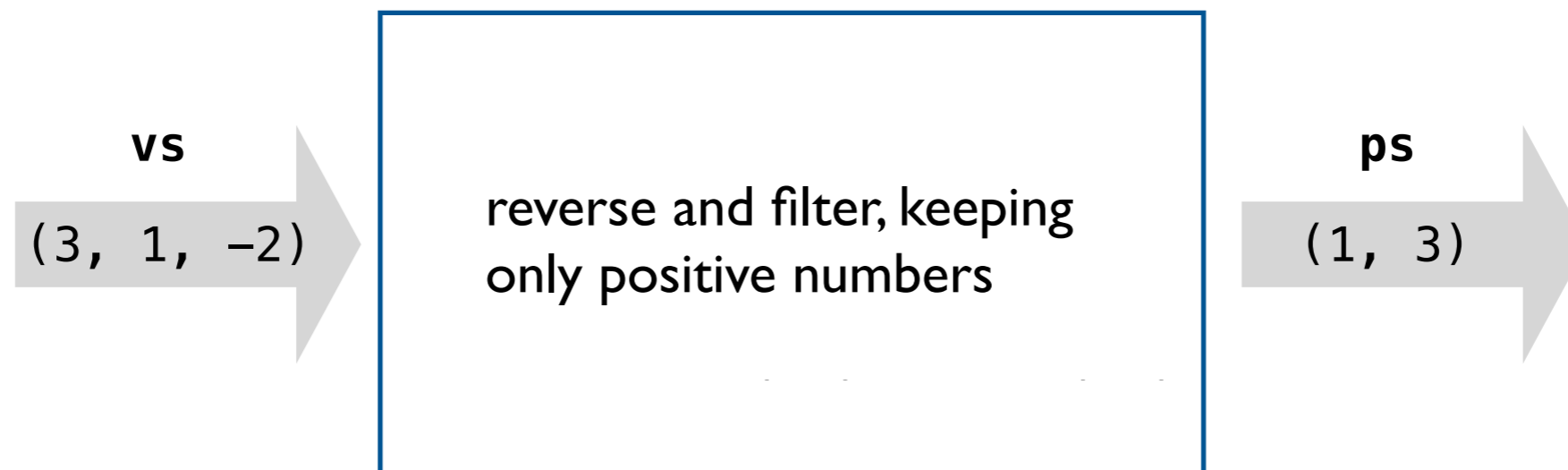
How it all works: a big picture view



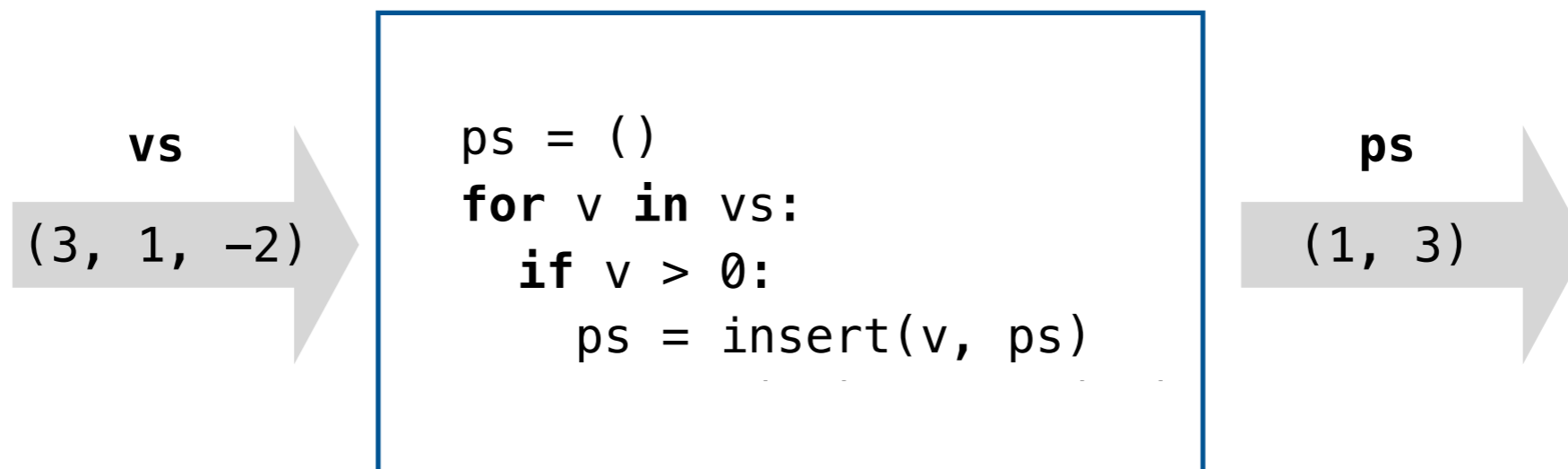
How it all works: a big picture view



Translation to constraints by example



Translation to constraints by example



Translation to constraints by example

vs

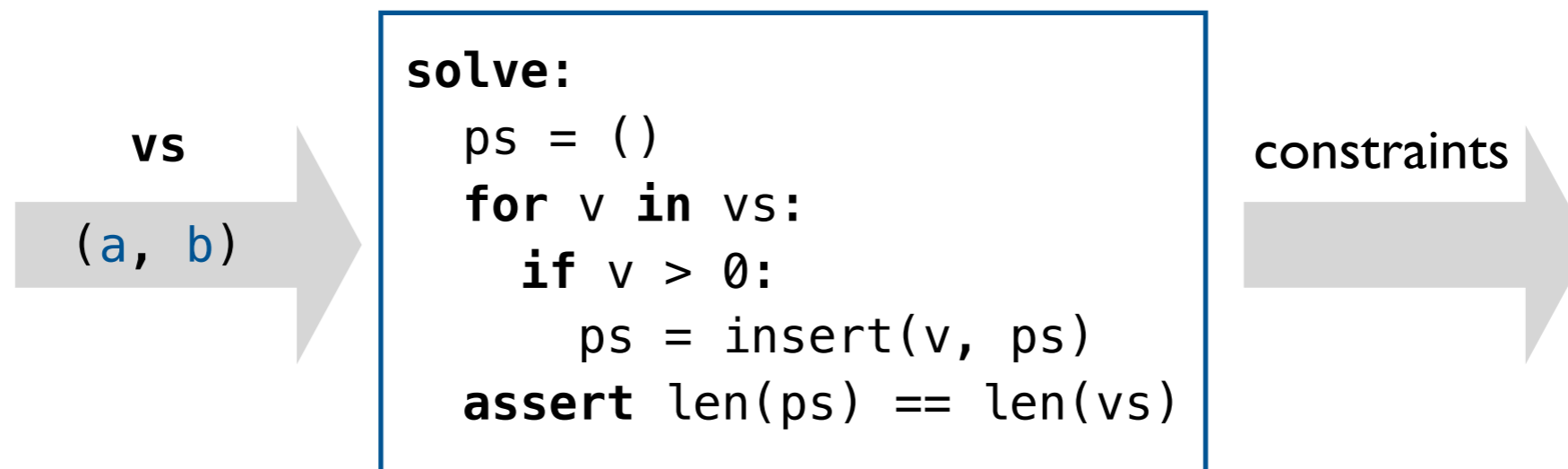


```
solve:  
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

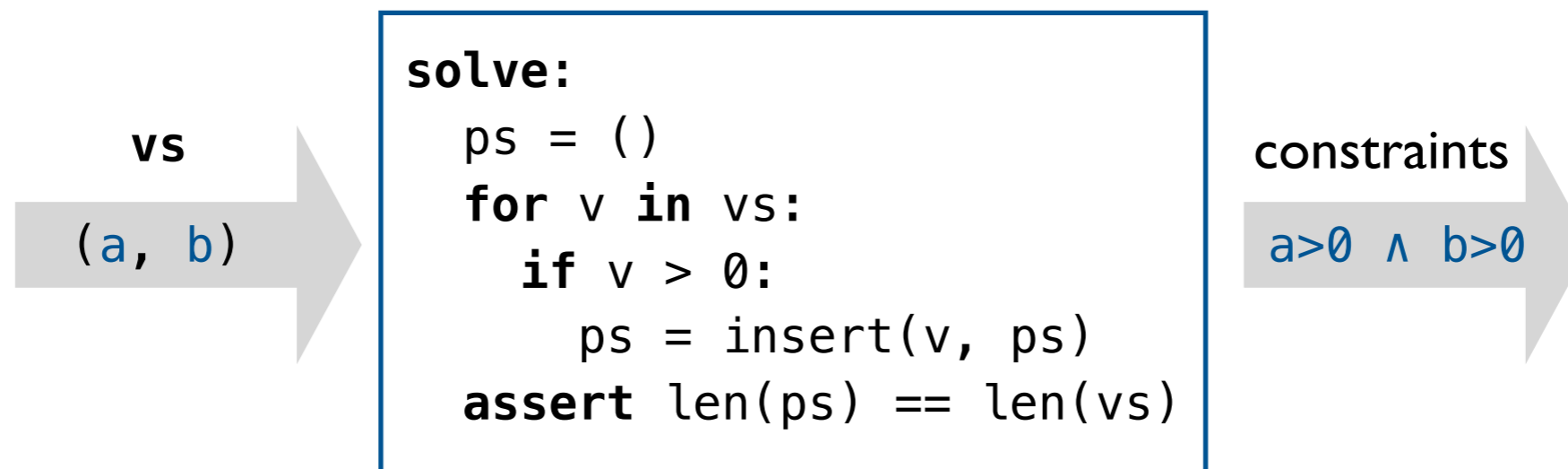
constraints



Translation to constraints by example



Translation to constraints by example

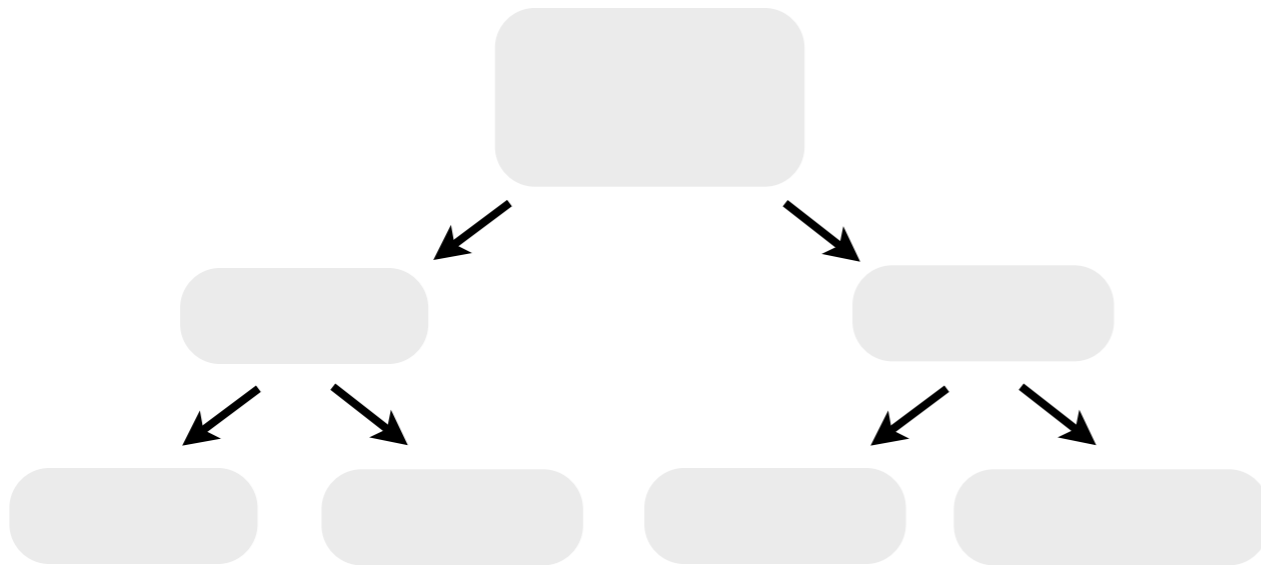


Design space of precise symbolic encodings

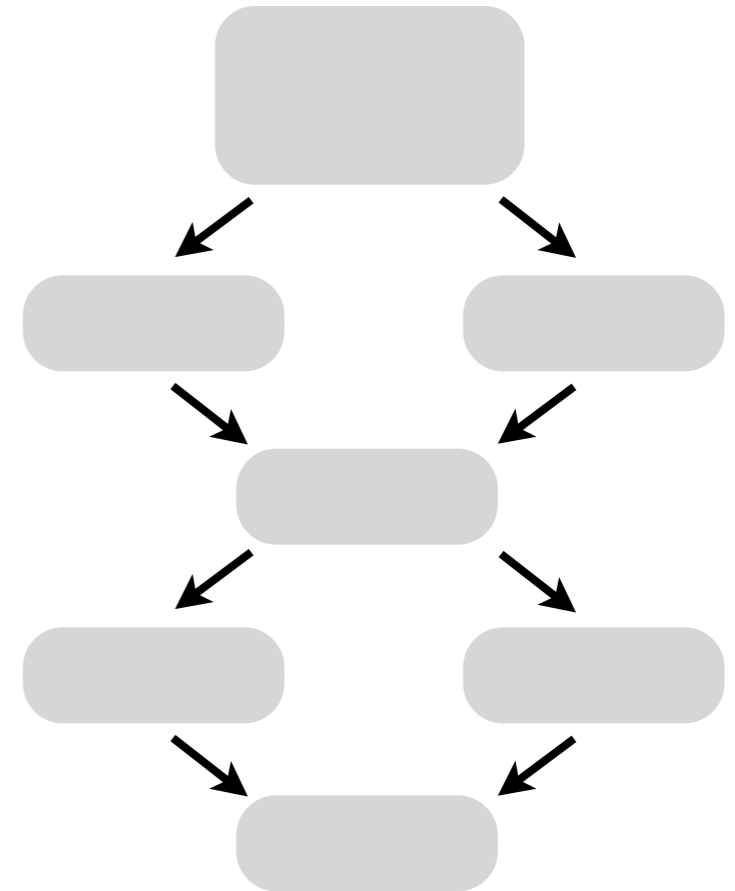
solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

symbolic execution



bounded model checking

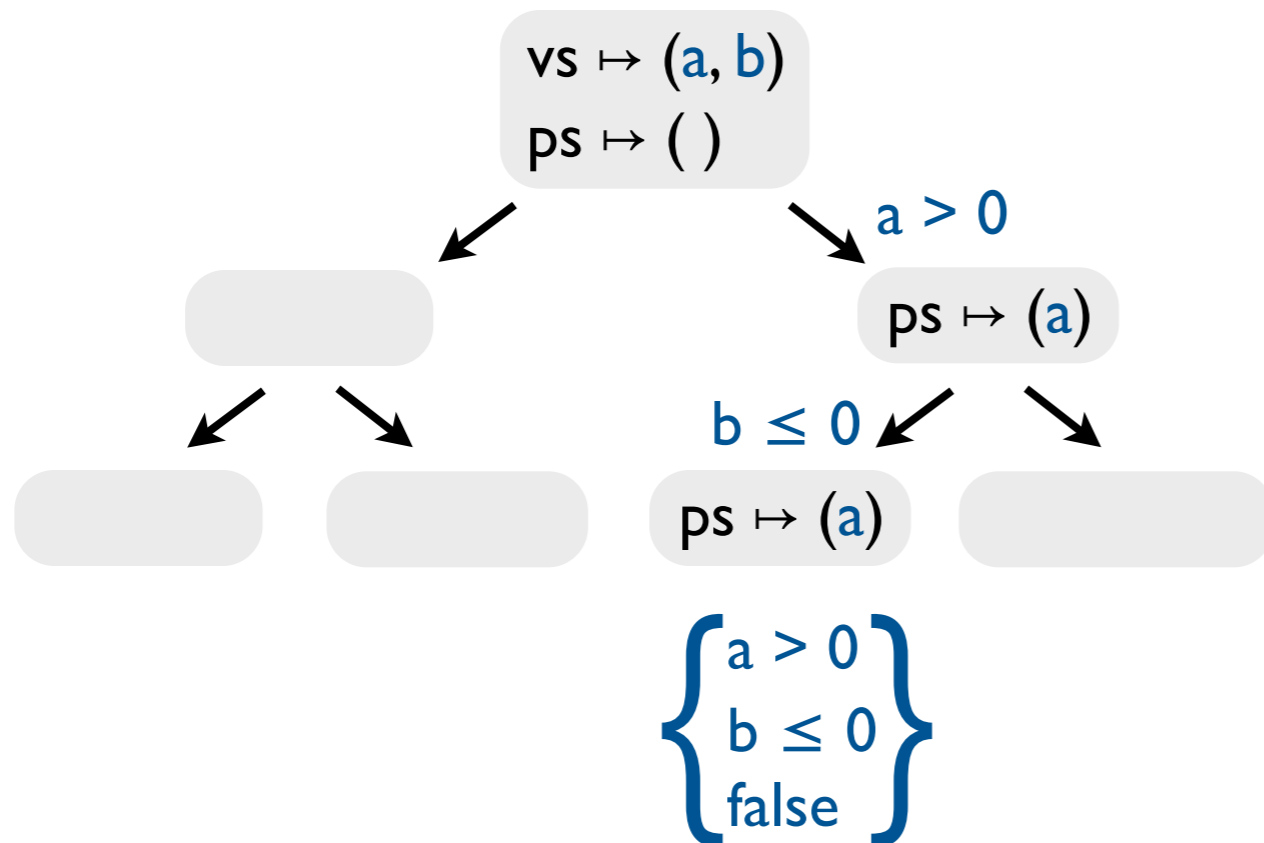


Design space of precise symbolic encodings

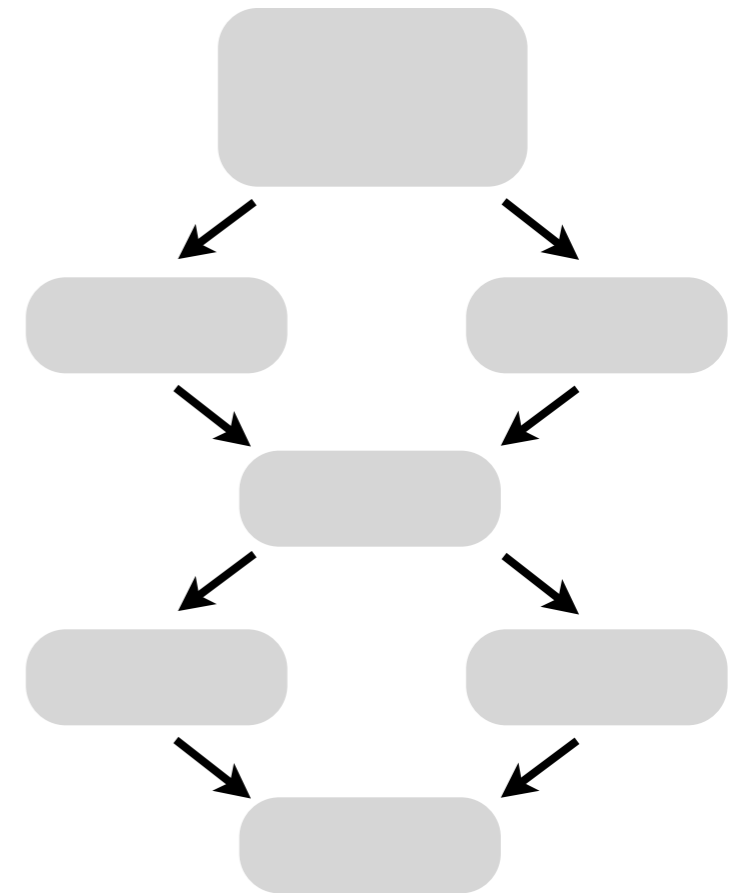
solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

symbolic execution



bounded model checking



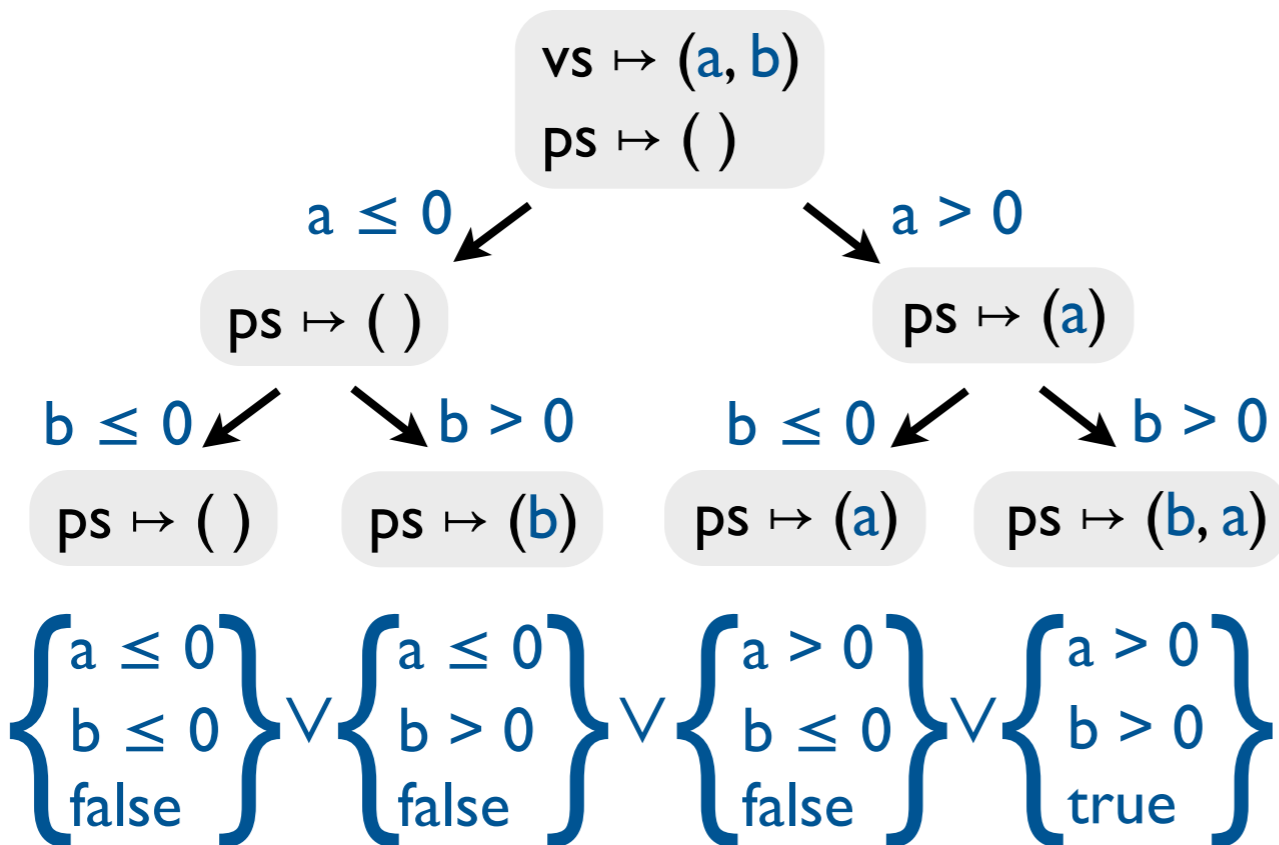
Design space of precise symbolic encodings

solve:

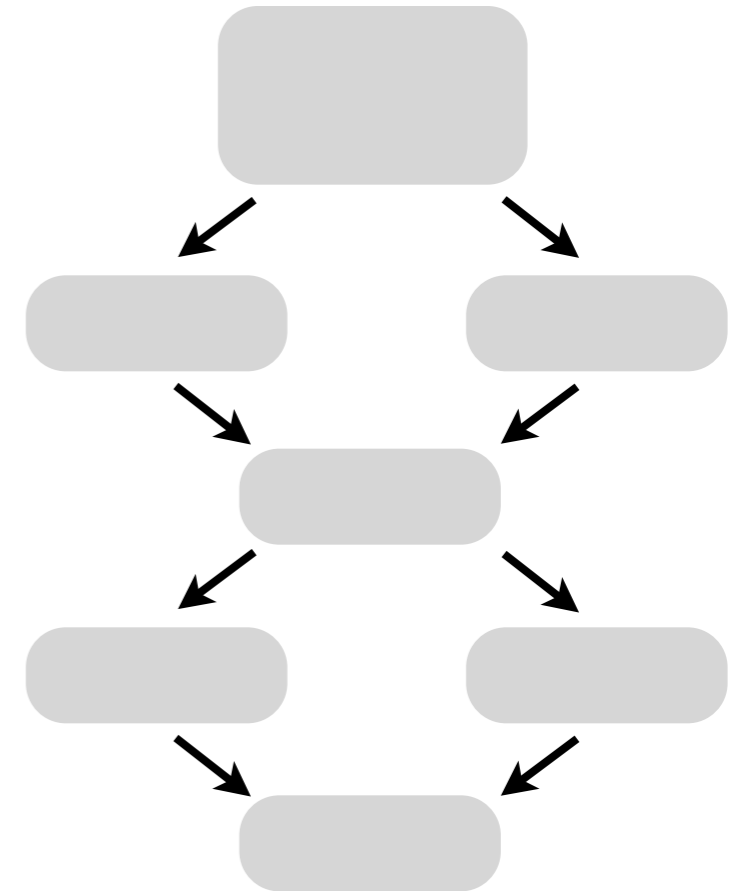
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking



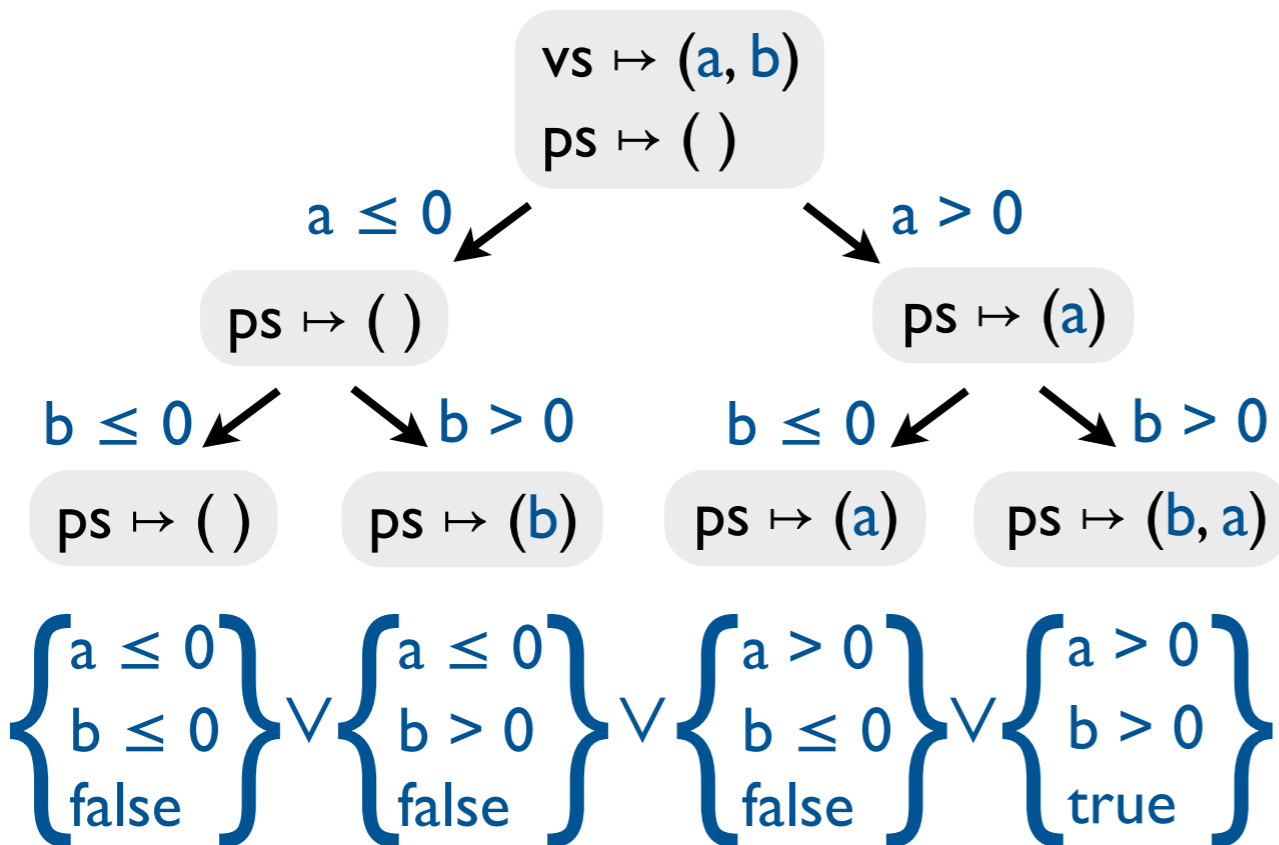
Design space of precise symbolic encodings

solve:

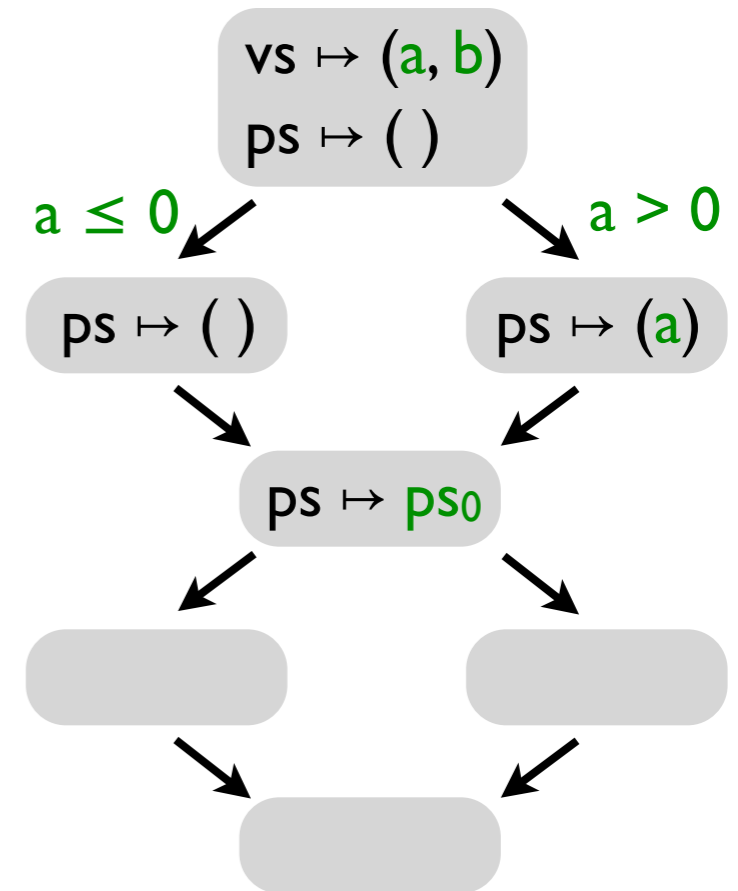
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking



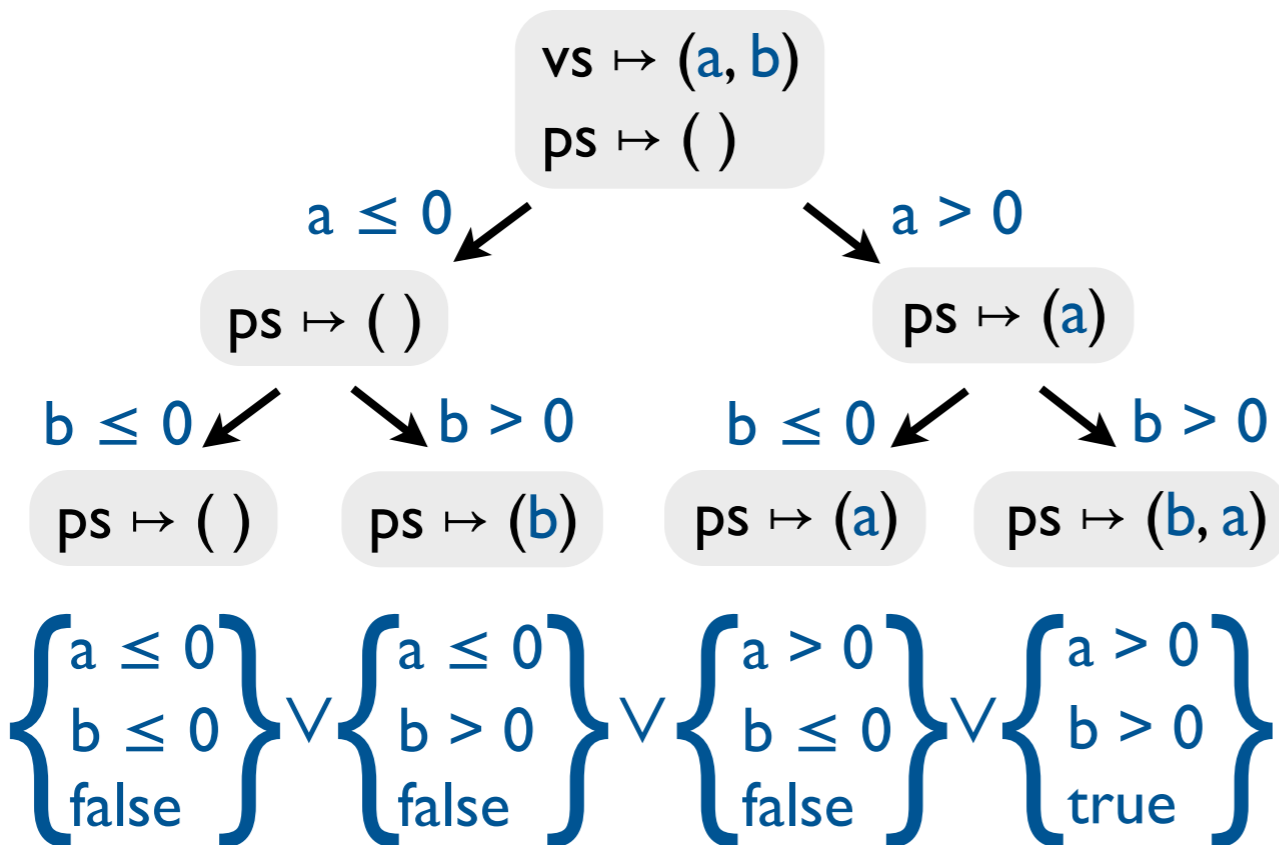
Design space of precise symbolic encodings

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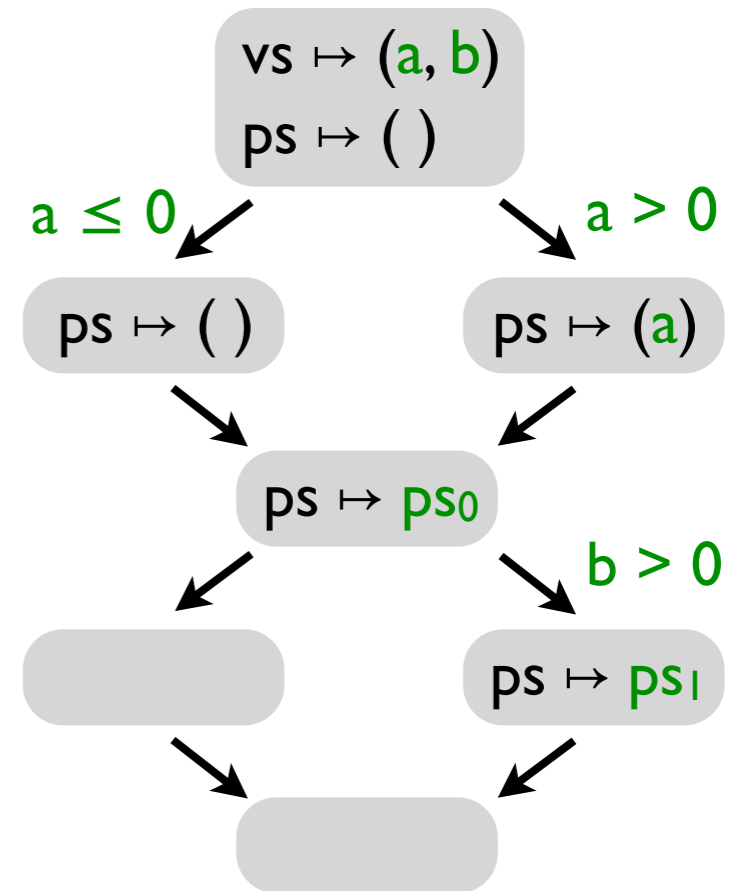
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking



$ps_0 = \text{ite}(a > 0, (a), ())$
 $ps_1 = \text{insert}(b, ps_0)$

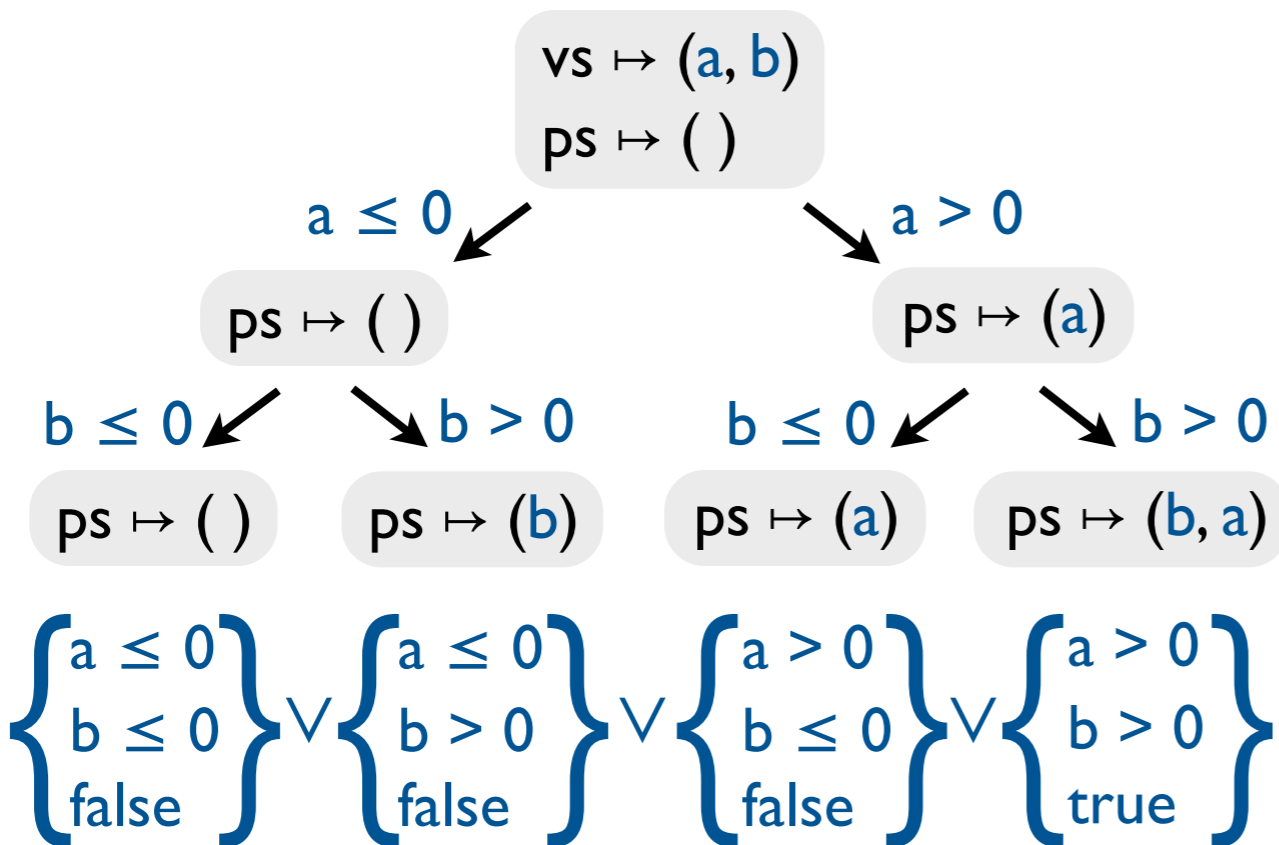
Design space of precise symbolic encodings

solve:

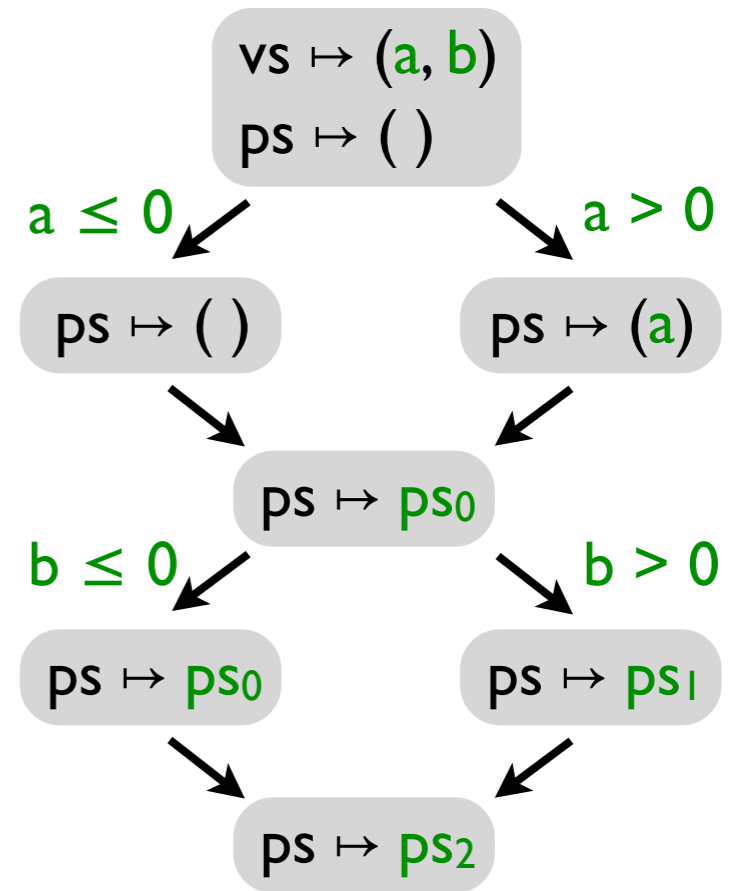
```

ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
    
```

symbolic execution



bounded model checking



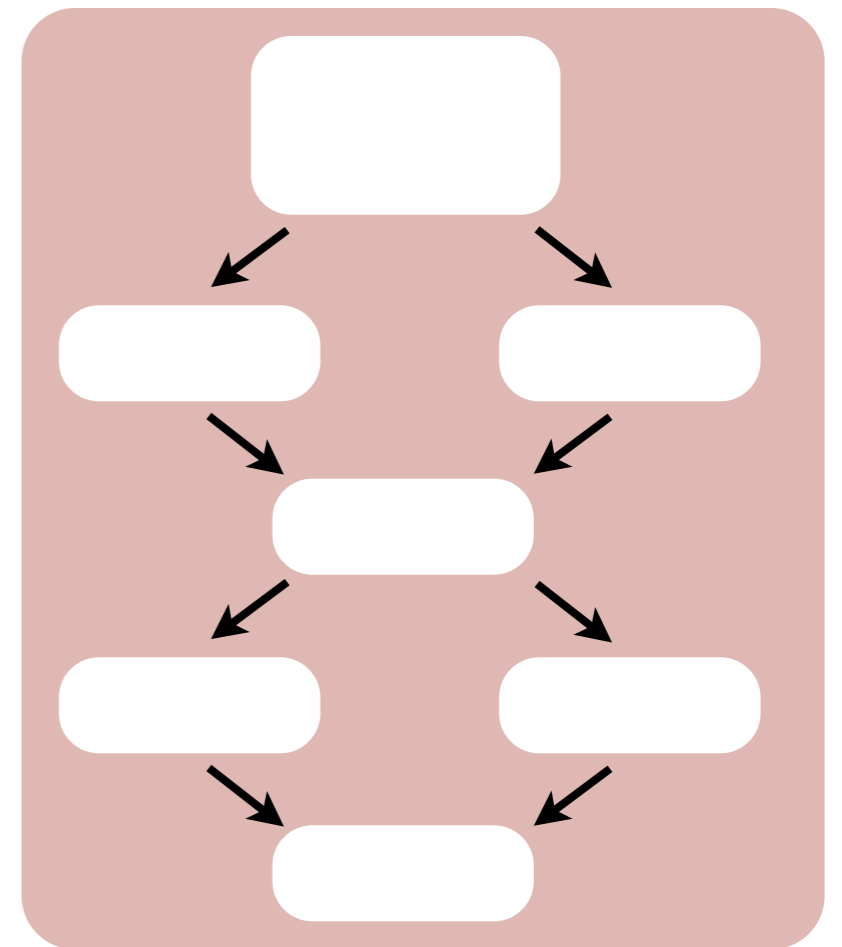
```

ps0 = ite(a > 0, (a), ())
ps1 = insert(b, ps0)
ps2 = ite(b > 0, ps0, ps1)
assert len(ps2) = 2
    
```

A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



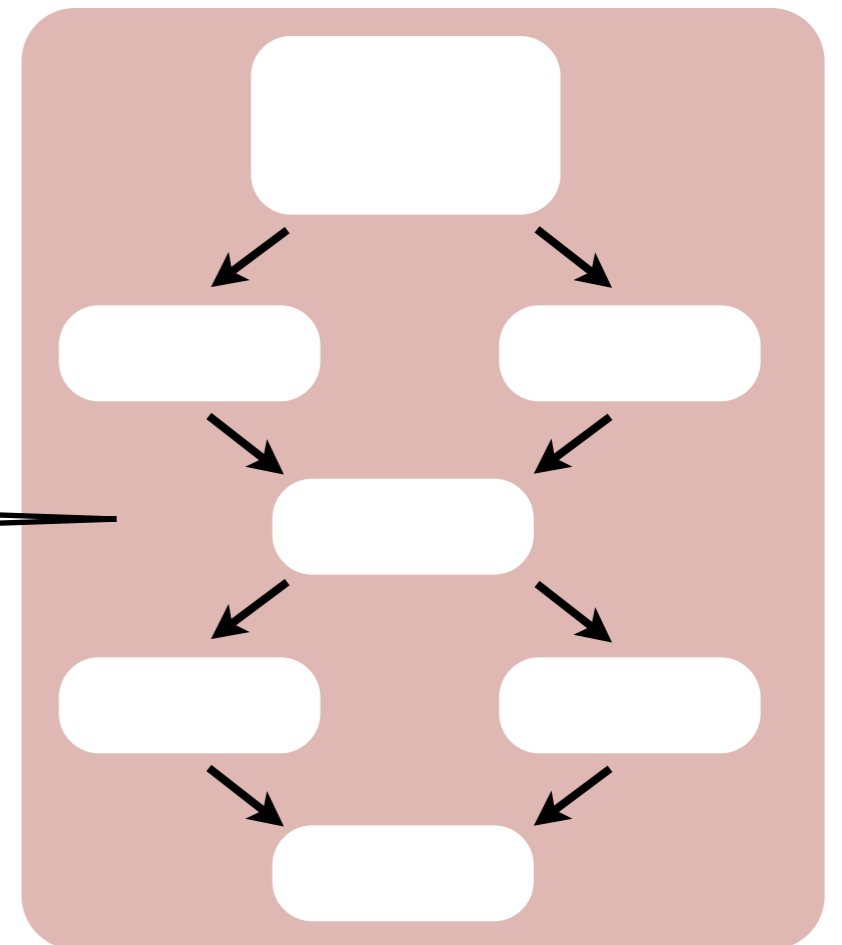
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Merge values of

- ▶ primitive types: **symbolically**
- ▶ immutable types: **structurally**
- ▶ all other types: **via unions**



$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



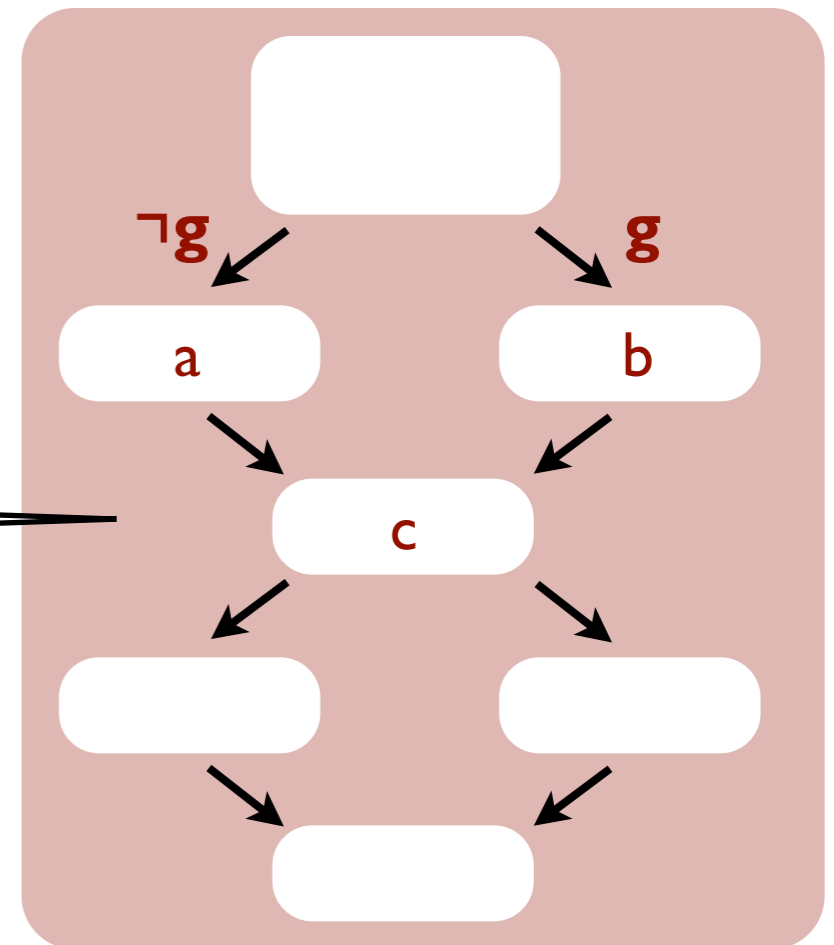
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Merge values of

- ▶ primitive types: **symbolically**
- ▶ immutable types: **structurally**
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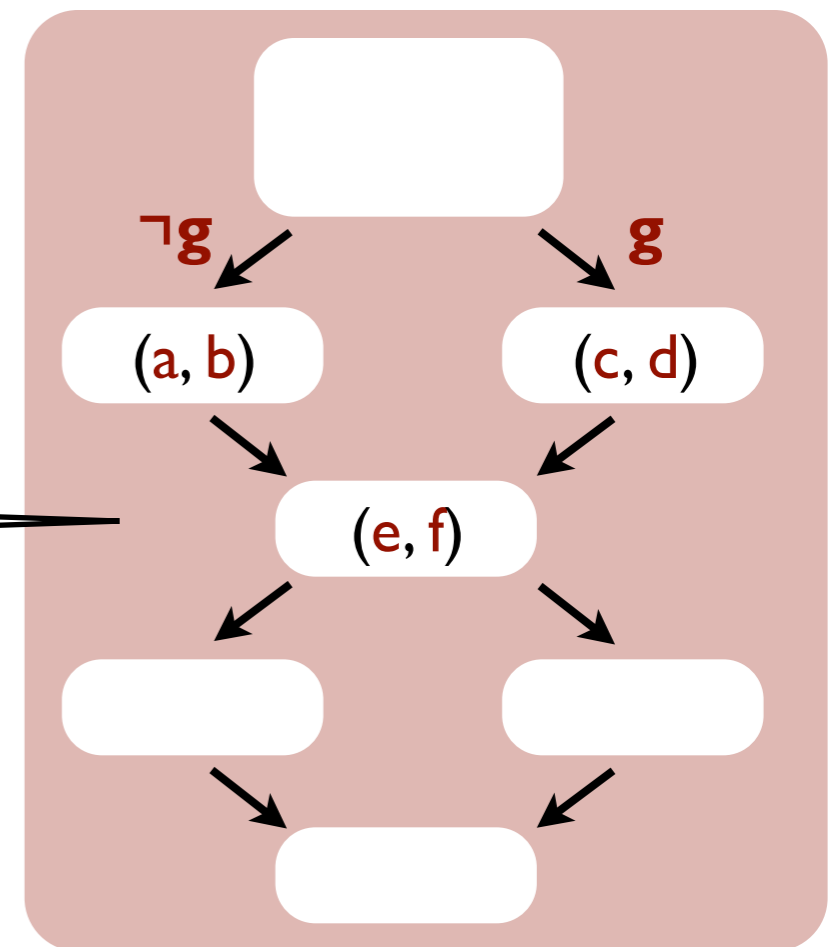
$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



Merge values of

- ▶ primitive types: *symbolically*
- ▶ immutable types: *structurally*
- ▶ all other types: *via unions*

$\left\{ \begin{array}{l} a > 0 \\ b > 0 \\ \text{true} \end{array} \right\}$



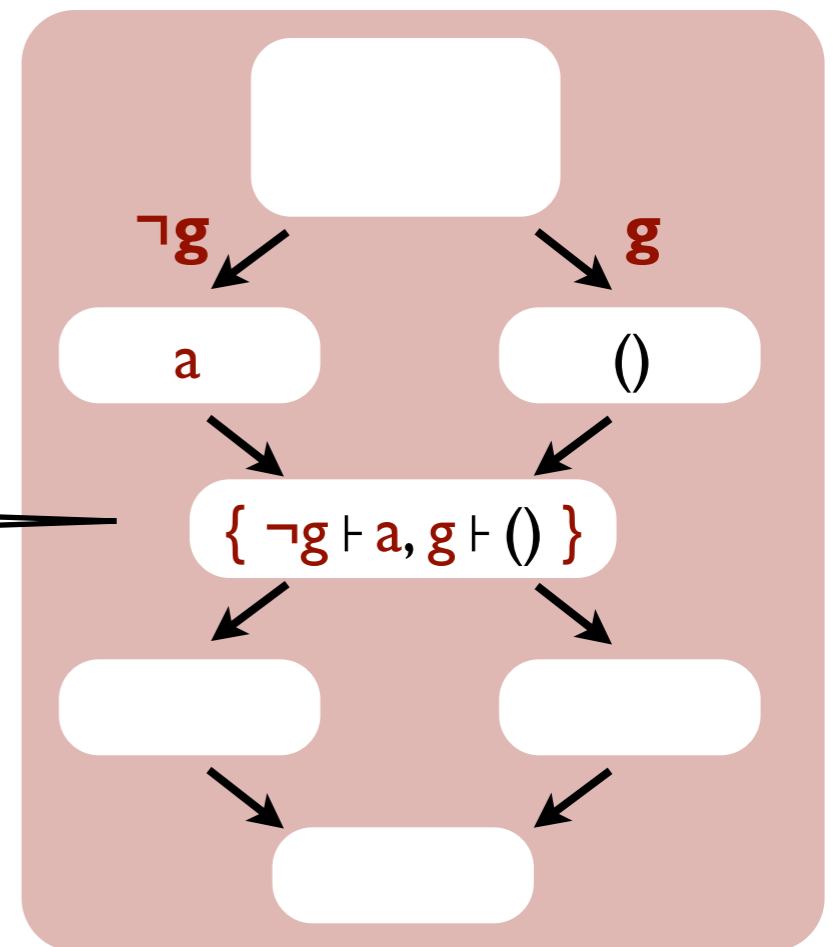
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Merge values of

- ▶ primitive types: *symbolically*
- ▶ immutable types: *structurally*
- ▶ all other types: via **unions**



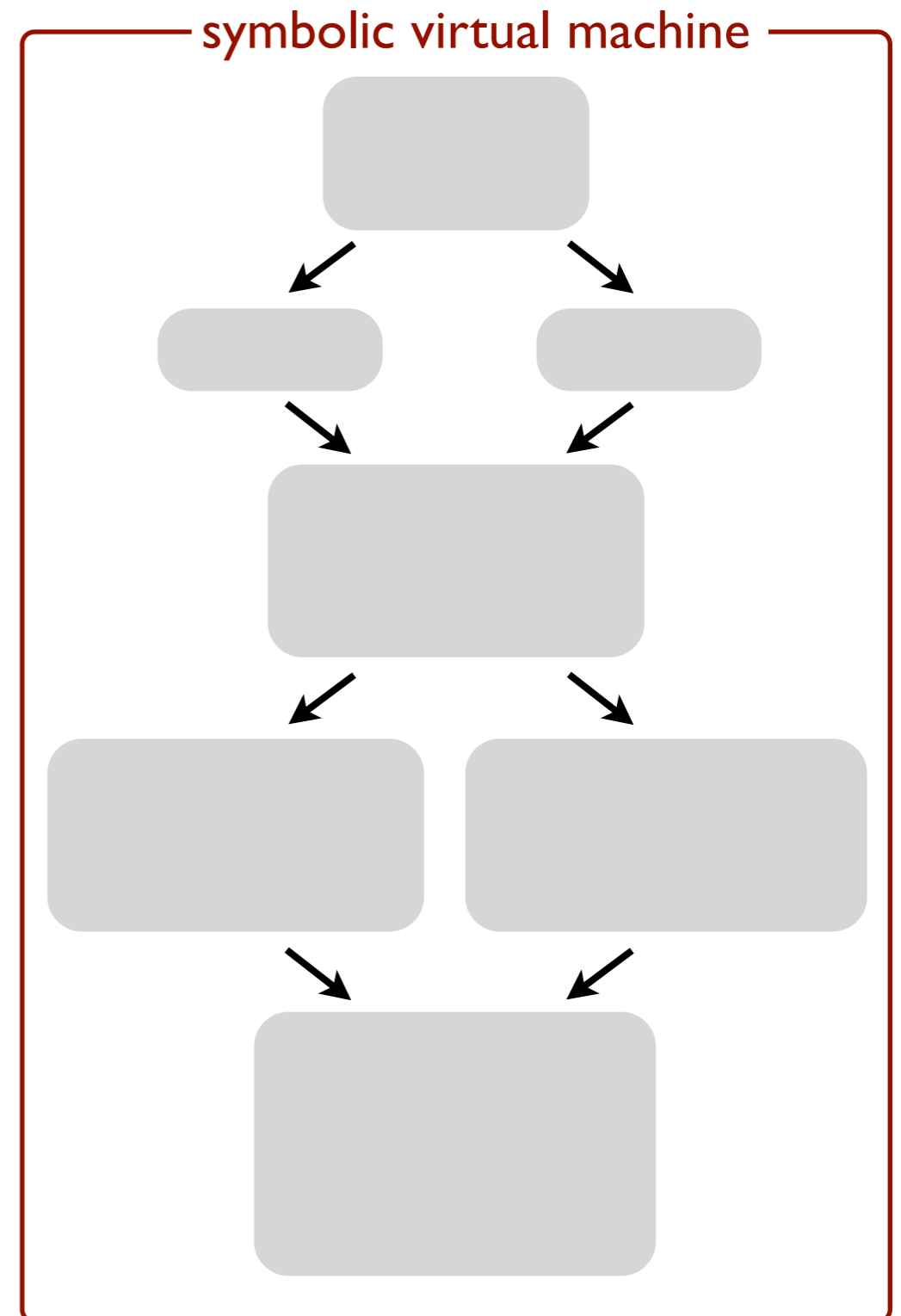
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A new design: type-driven state merging

solve:

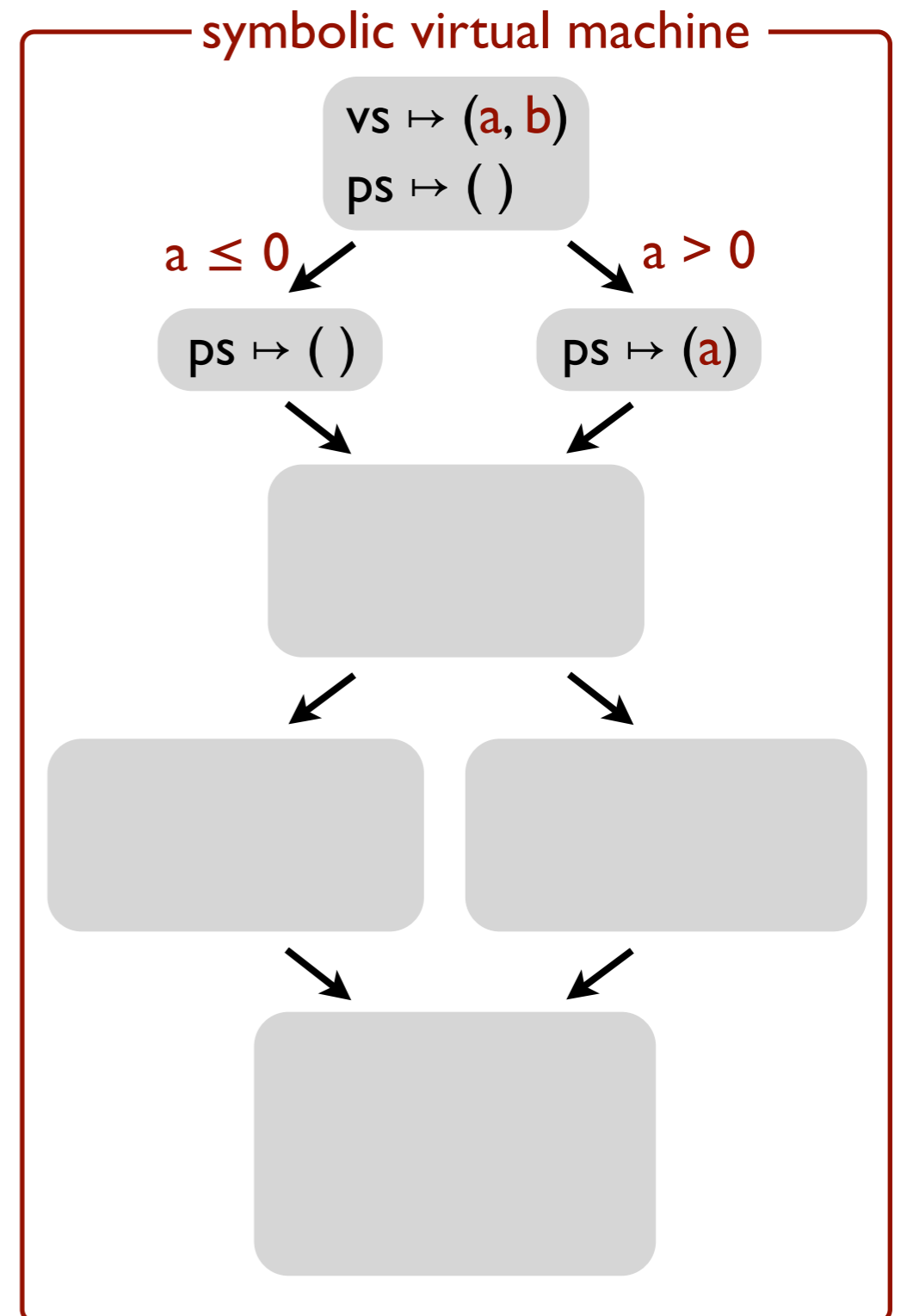
```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```



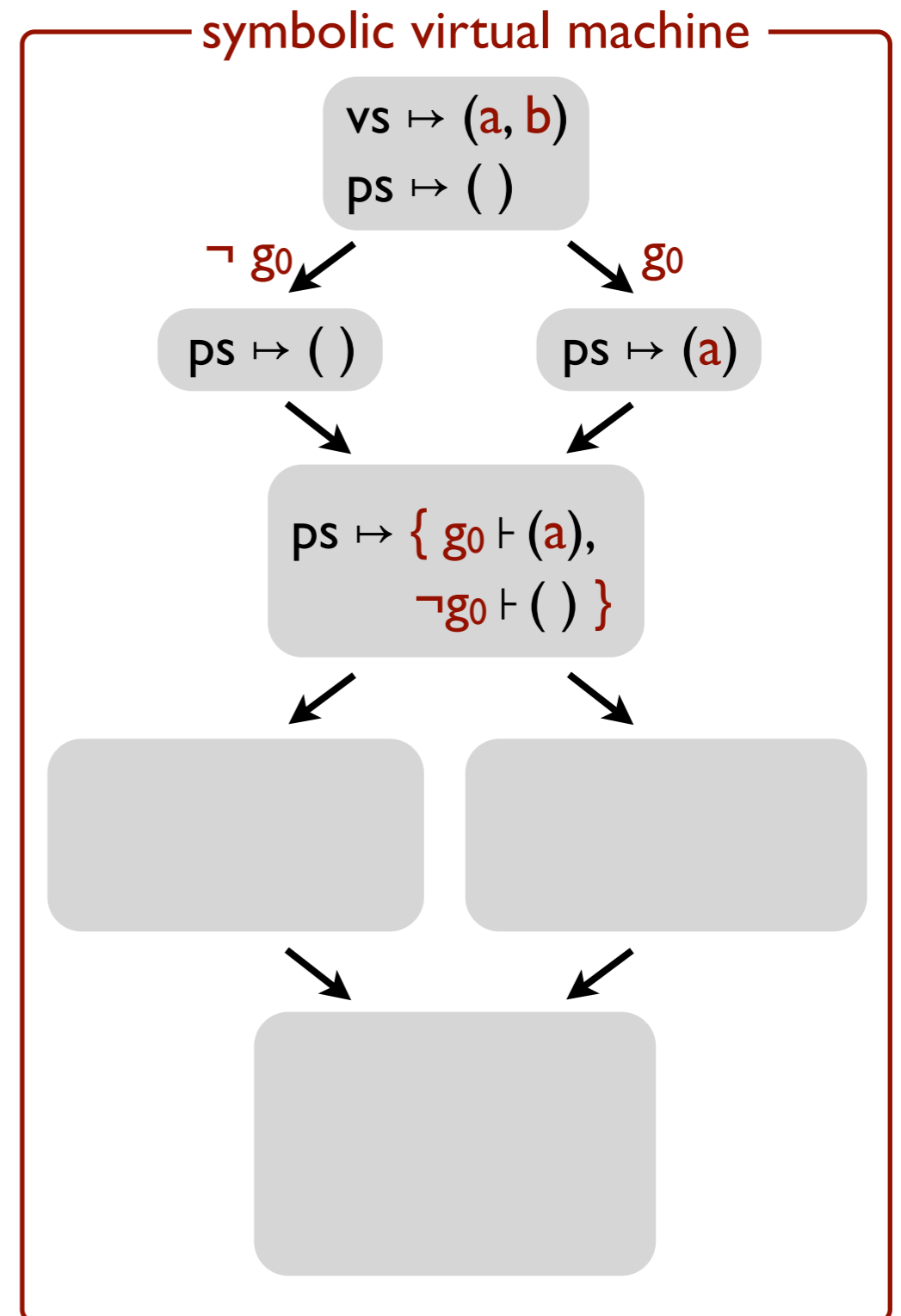
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Symbolic union: a set of guarded values, with disjoint guards.

$g_0 = a > 0$



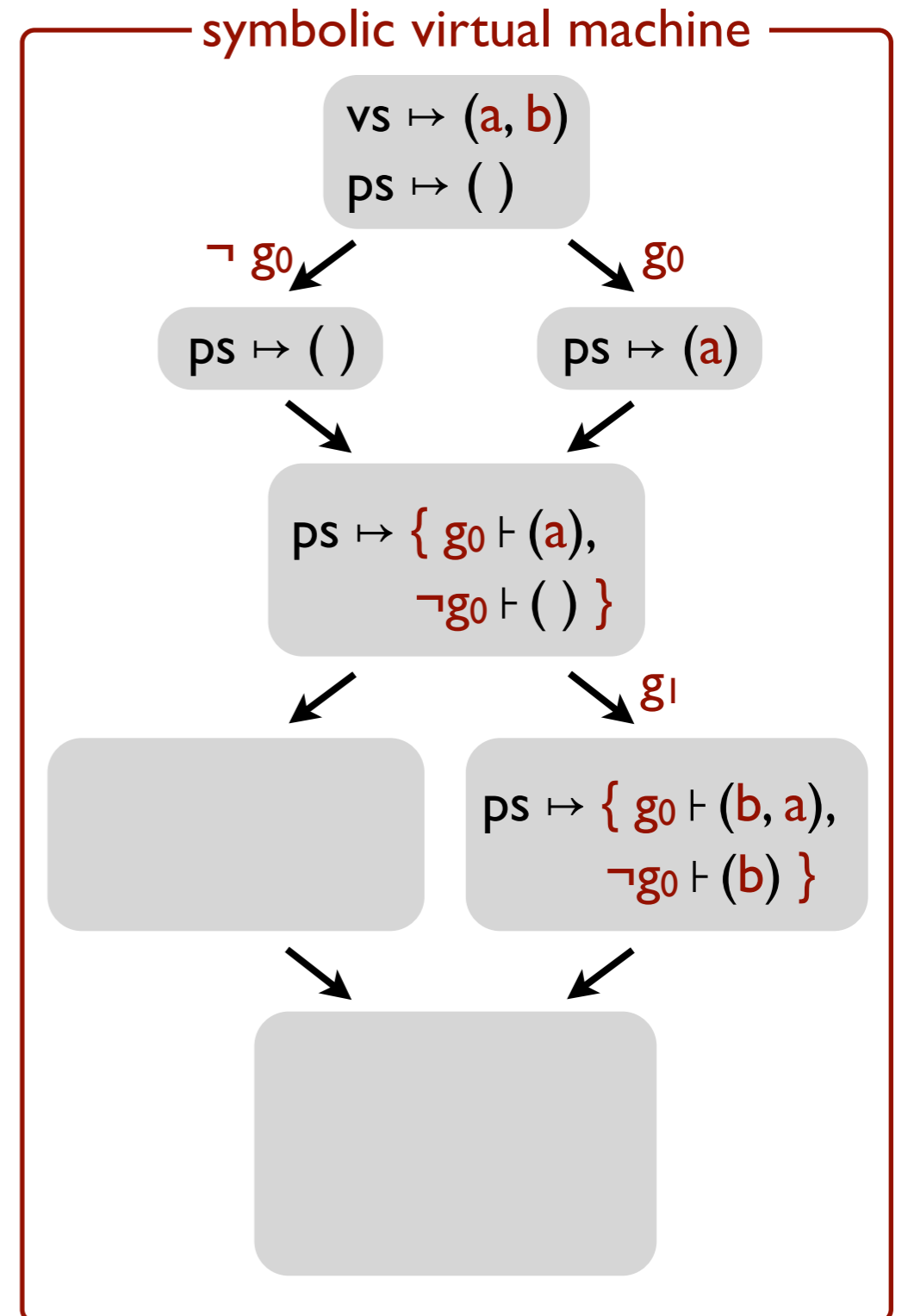
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Execute insert
concretely on all
lists in the union.

$g_0 = a > 0$
 $g_1 = b > 0$

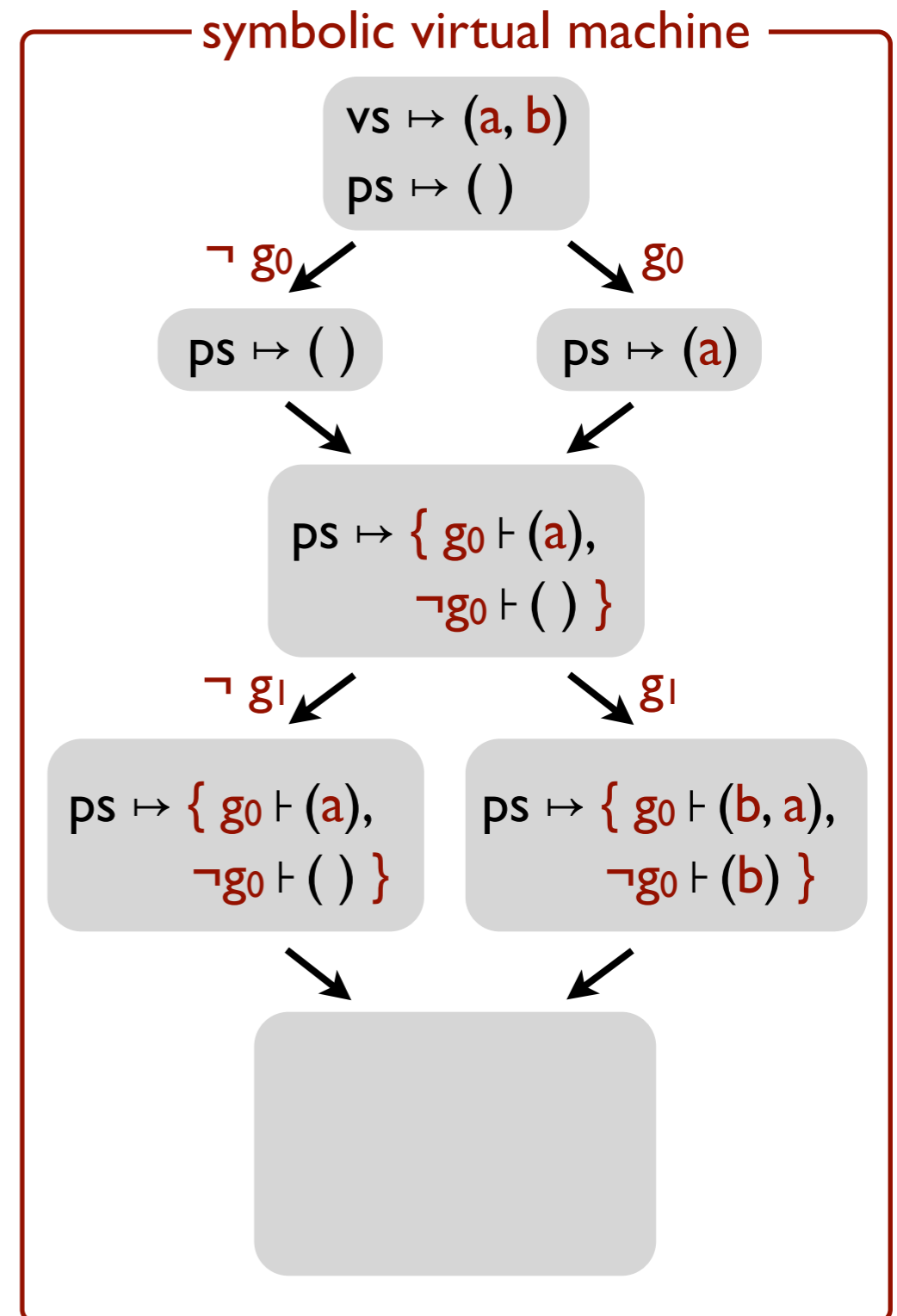


A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

$g_0 = a > 0$
 $g_1 = b > 0$



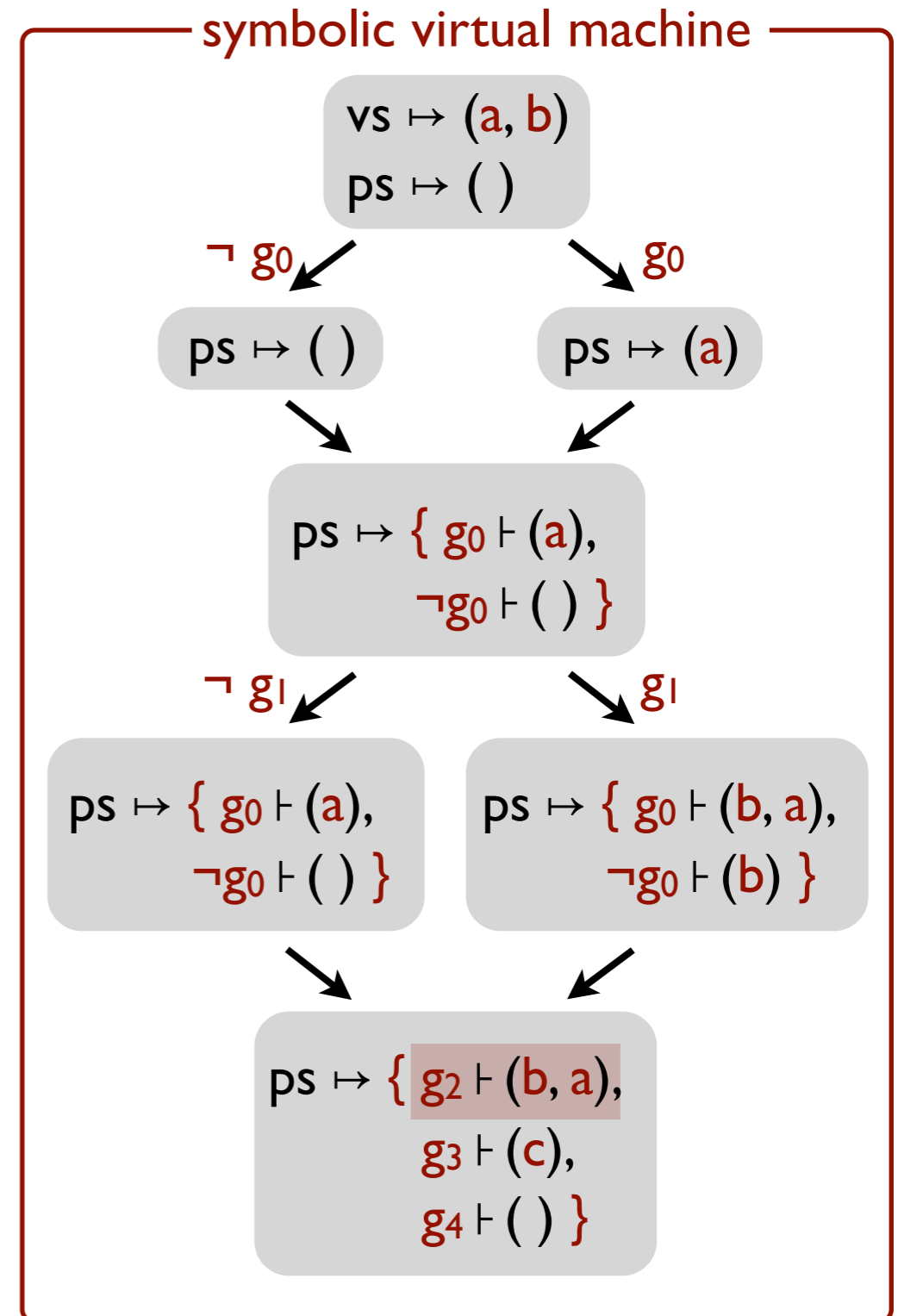
A new design: type-driven state merging

solve:

```
ps = ()  
for v in vs:  
    if v > 0:  
        ps = insert(v, ps)  
assert len(ps) == len(vs)
```

Evaluate len concretely on all lists in the union; assertion true only on the list guarded by g_2 .

```
g0 = a > 0  
g1 = b > 0  
g2 = g0 ^ g1  
g3 = ¬(g0 ⇔ g1)  
g4 = ¬g0 ^ ¬g1  
c = ite(g1, b, a)  
assert g2
```



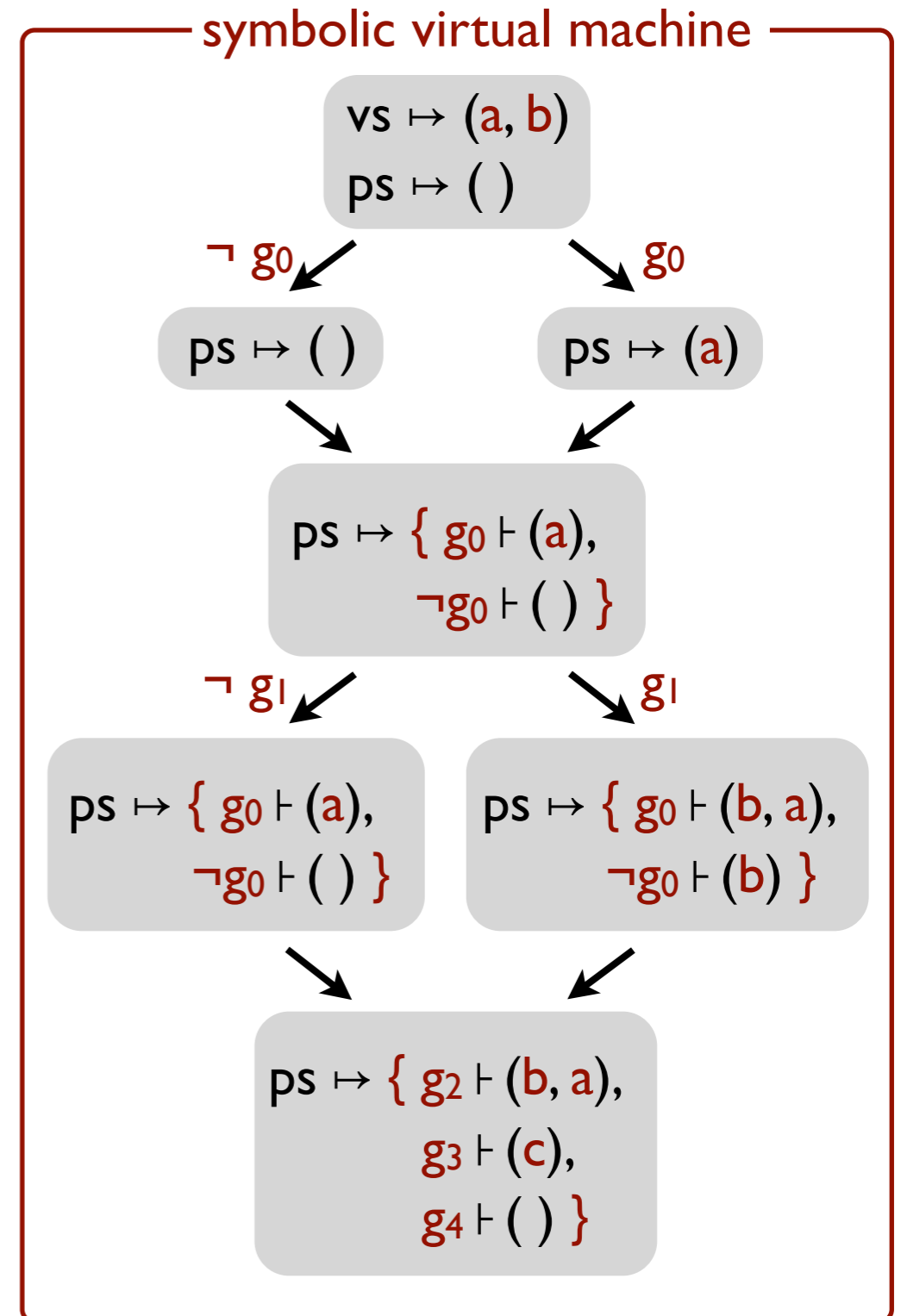
A new design: type-driven state merging

solve:

```
ps = ()
for v in vs:
    if v > 0:
        ps = insert(v, ps)
assert len(ps) == len(vs)
```

polynomial encoding
concrete evaluation

```
g0 = a > 0
g1 = b > 0
g2 = g0 ^ g1
g3 = ¬(g0 ⇔ g1)
g4 = ¬g0 ^ ¬g1
c = ite(g1, b, a)
assert g2
```



How to build your own solver-aided tool

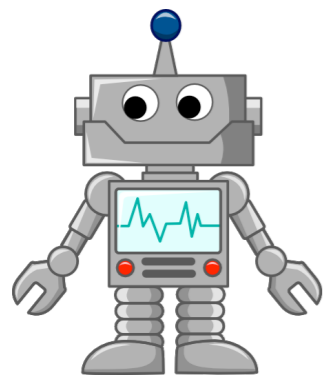


SDSL



SVM

SMT



The classic (hard) way to build a tool

What is hard about building a solver-aided tool?

An easier way: tools as languages

How to build tools by stacking layers of languages.

Behind the scenes: symbolic virtual machine

How Rosette works so you don't have to.

A last look: a few recent applications

Cool tools built with Rosette!

Chlorophyll: ultra low-power computing

Instructions/Second vs Power

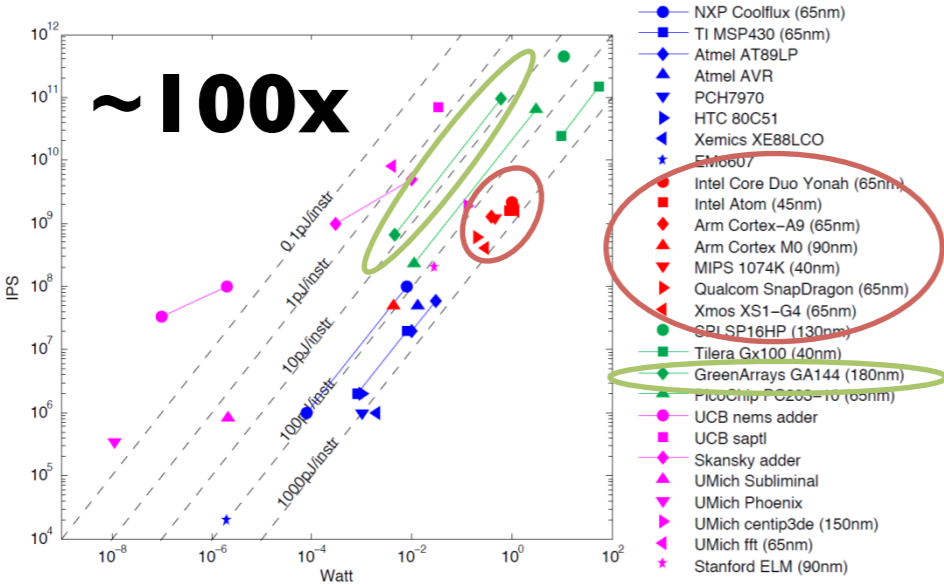
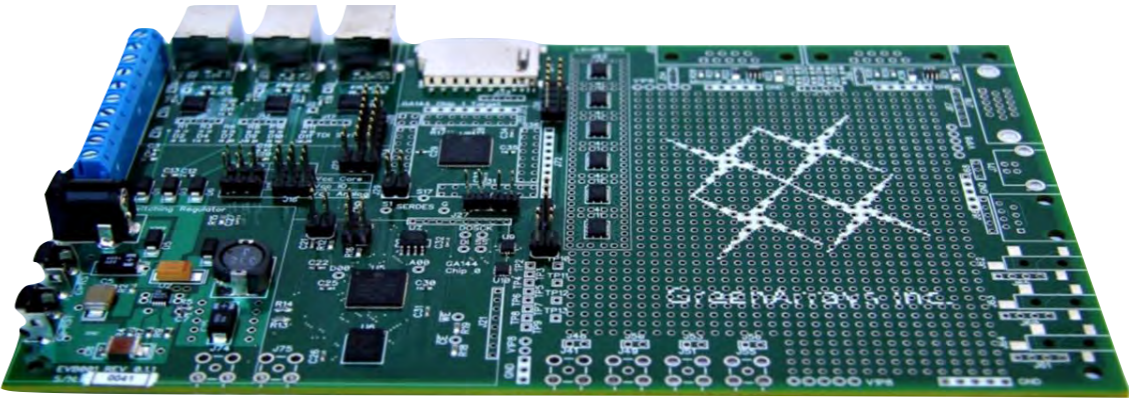


Figure by Per Ljung

GreenArrays GA144 Processor



Chlorophyll: ultra low-power computing

GreenArrays GA144 Processor

- ▶ Stack-based 18-bit architecture
- ▶ 32 instructions
- ▶ 8 x 18 array of asynchronous cores
- ▶ No shared resources (cache, memory)
- ▶ Limited communication, neighbors only
- ▶ < 300 byte memory per core

Manual program partitioning:
break programs up into a pipeline
with a few operations per core.

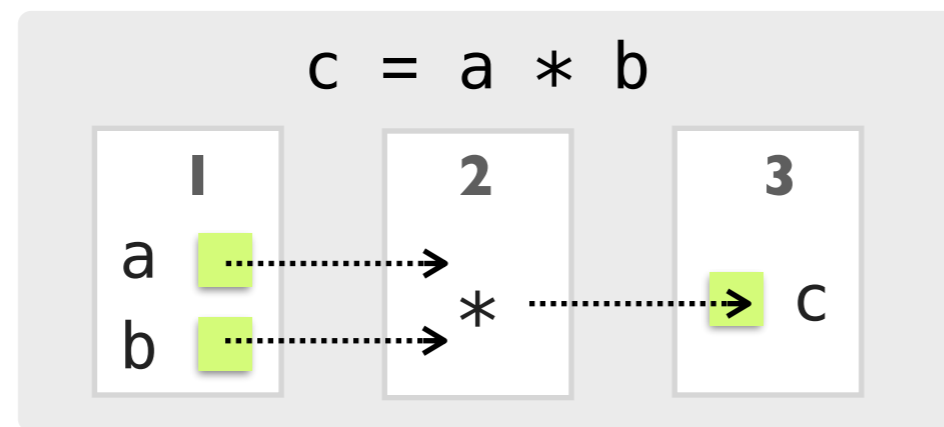


Drawing by Mangpo Phothilimthana

Chlorophyll: ultra low-power computing

GreenArrays GA144 Processor

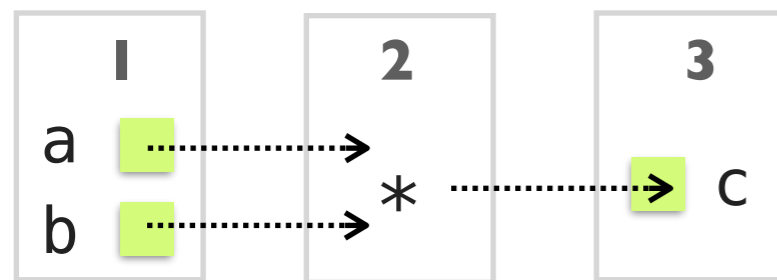
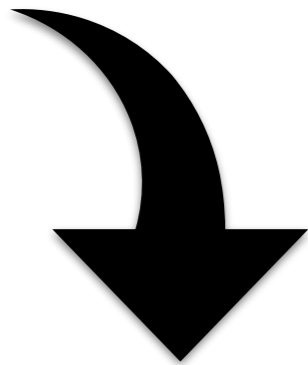
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- ▶ < 300 byte memory per core



Drawing by Mangpo Phothilimthana

Chlorophyll: ultra low-power computing

```
int a, b;  
int c = a * b;
```

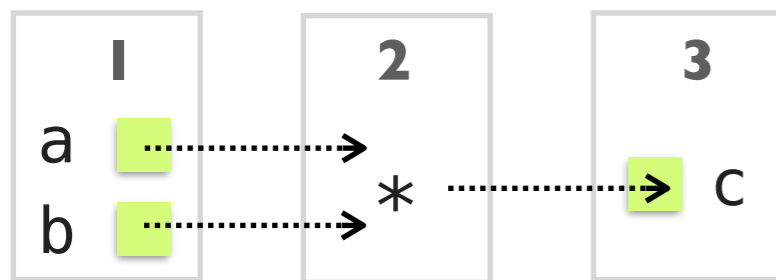
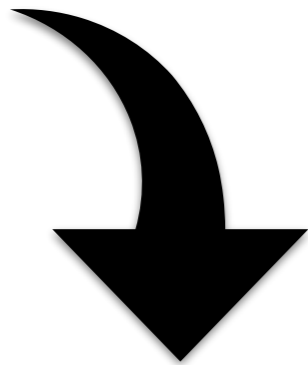


Synthesizes placement of code and data onto cores, by type-checking a program sketch in a C-like DSL.

Chlorophyll: ultra low-power computing

```
int@1 a, b;  
int@3 c = a *@2 b;
```

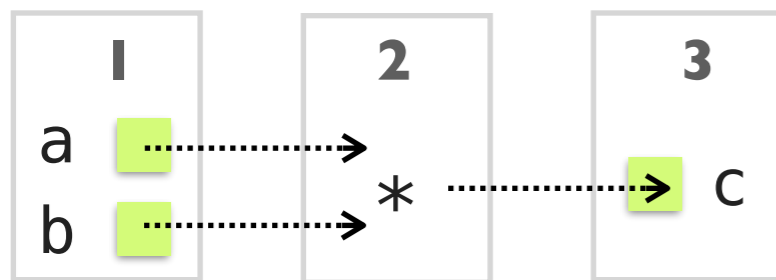
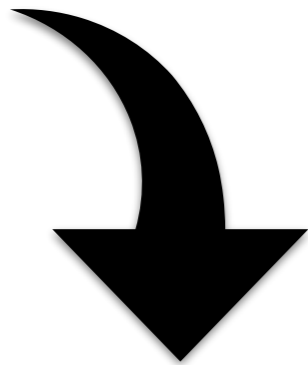
Synthesizes placement of code and data onto cores, by **type-checking a program sketch** in a C-like DSL.



Chlorophyll: ultra low-power computing

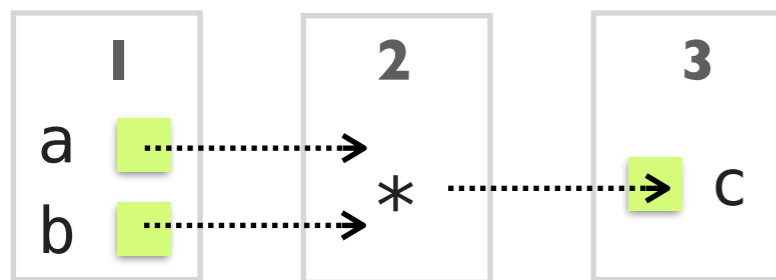
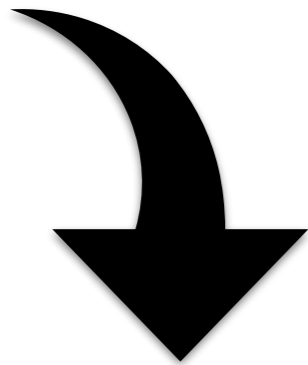
```
int@?? a, b;  
int@?? c = a *@?? b;
```

Synthesizes placement of code and data onto cores, by type-checking a program **sketch** in a C-like DSL.

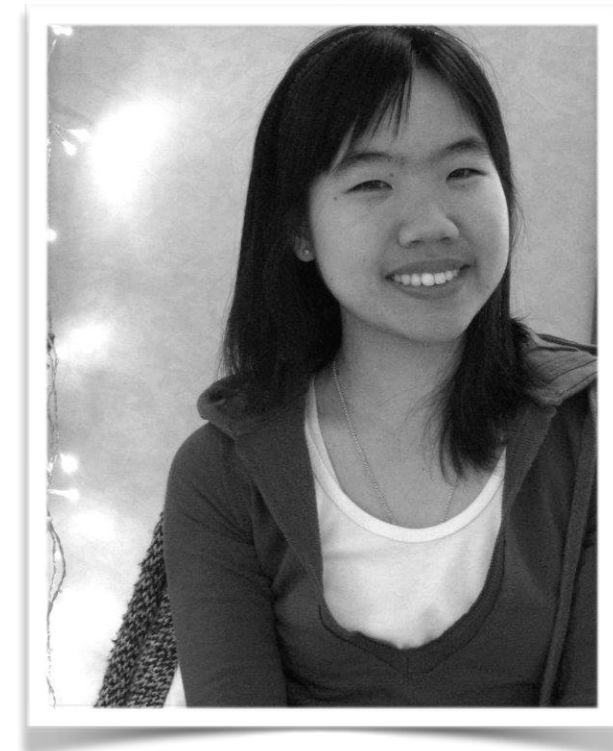


Chlorophyll: ultra low-power computing

```
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int@?? c = a *@?? b;
```



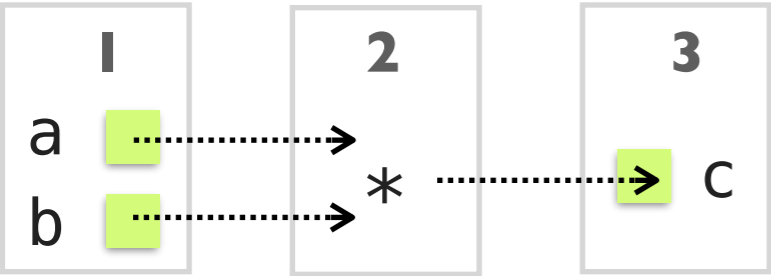
**Built by a first-year
grad in a few weeks**



Phitchaya Mangpo Phothilimthana

Chlorophyll: ultra low-power computing

```
int@?? a, b;  
int@?? c = a *@?? b;
```



With Chlorophyll, it took one afternoon to build a set of apps that took 3 months to build manually.

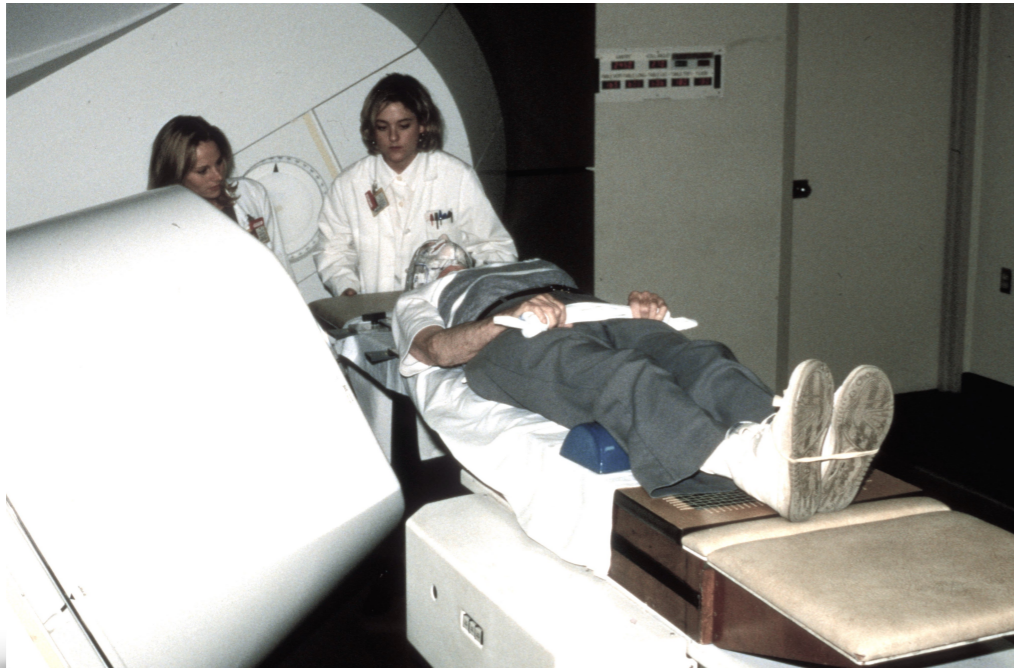
[Phothilimthana et al.,
PLDI'14]

Neutrons: verifying a radiotherapy system

Clinical Neutron Therapy System (CNTS) at UW

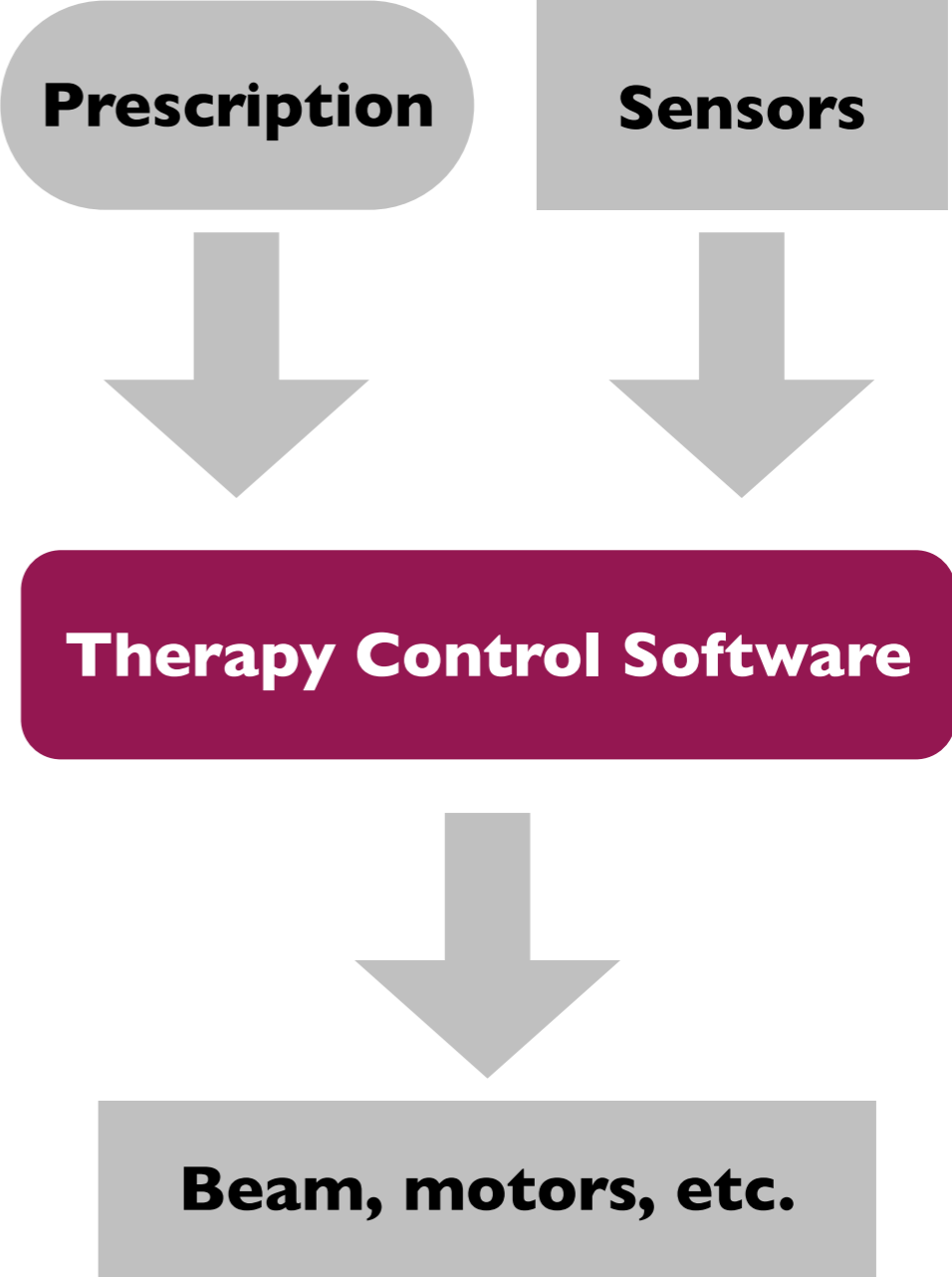
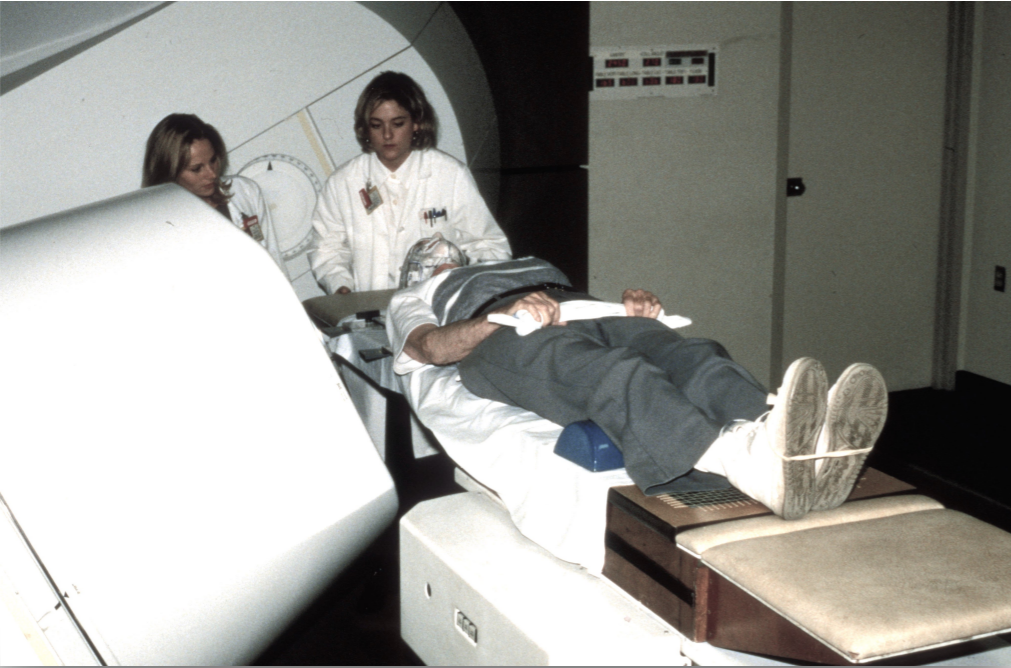


- 30 years of incident-free service.
- Controlled by custom software, built by CNTS engineering staff.
- Third generation of Therapy Control software built recently.

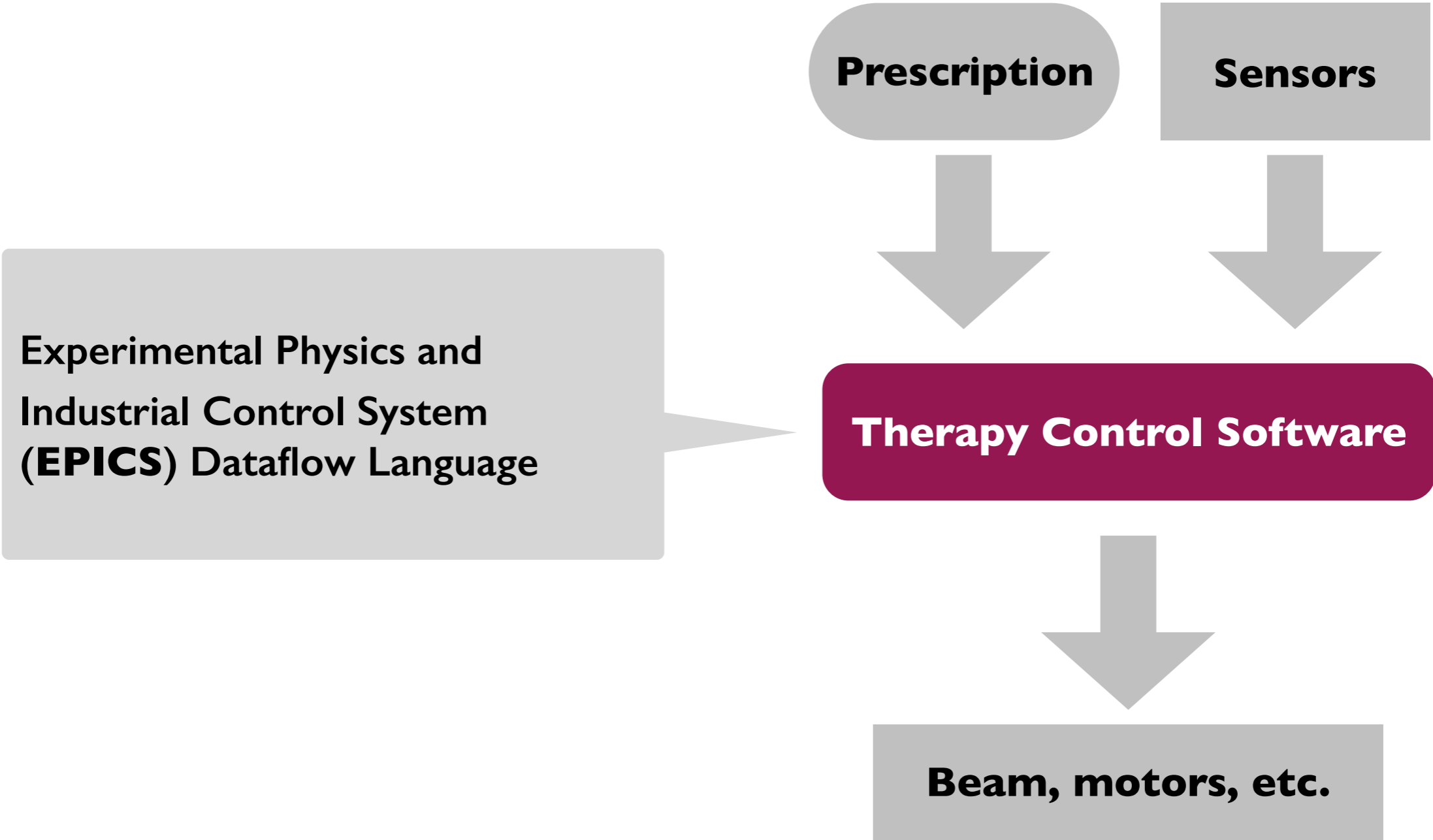


Neutrons: verifying a radiotherapy system

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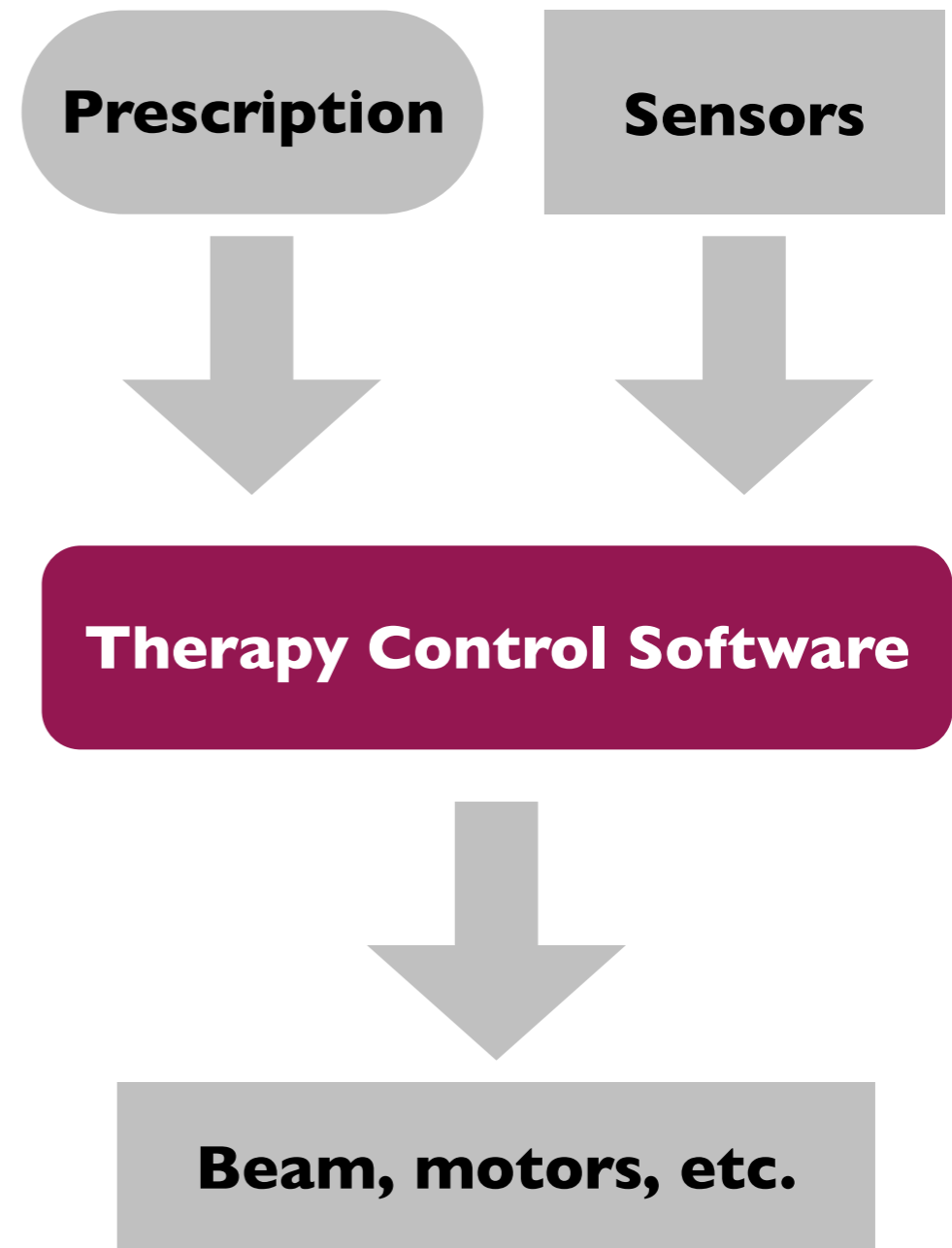
Neutrons: verifying a radiotherapy system



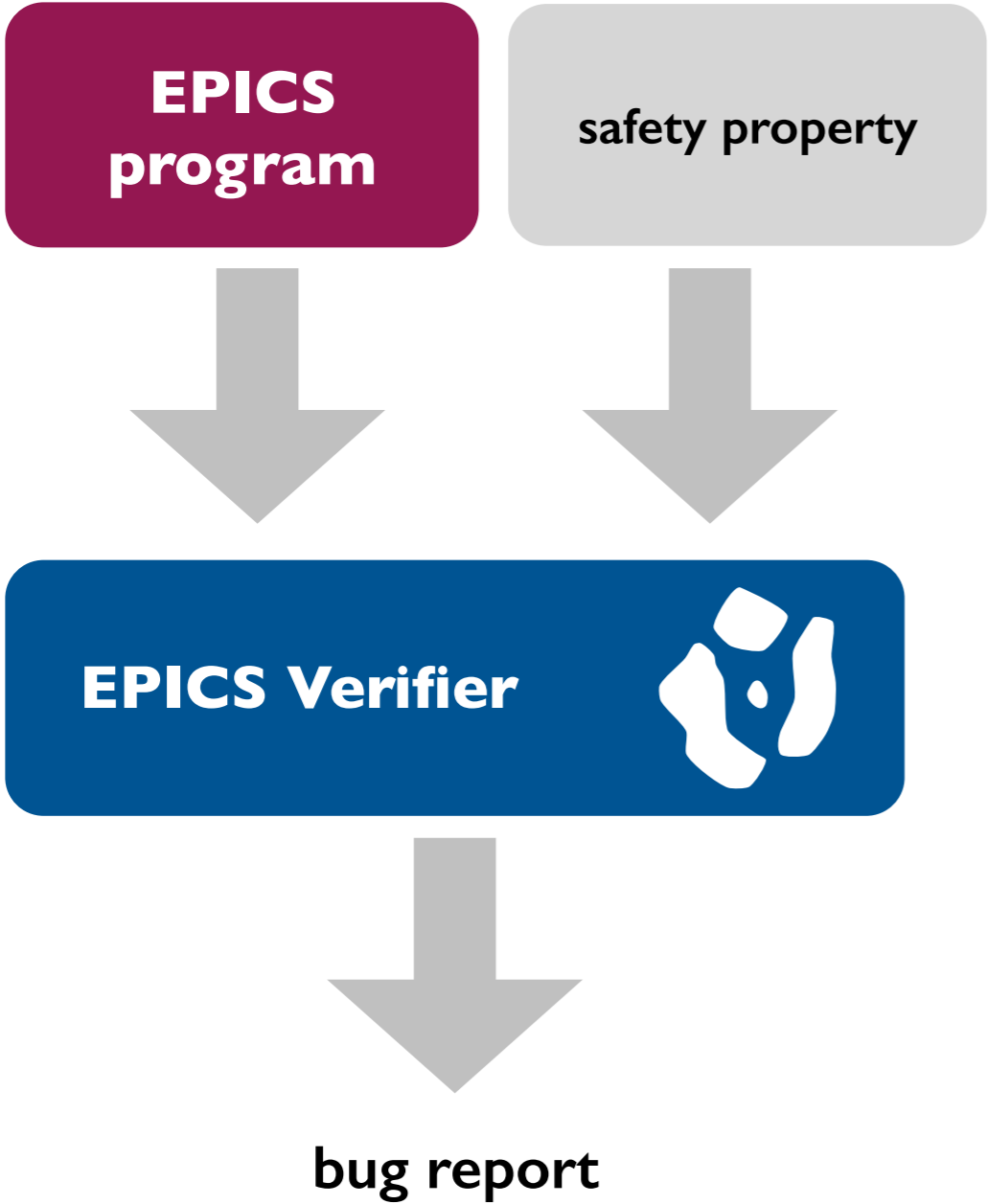
Neutrons: verifying a radiotherapy system

EPICS documentation / semantics

The Maximize Severity attribute is one of NMS (Non-Maximize Severity), MS (Maximize Severity), MSS (Maximize Status and Severity) or MSI (Maximize Severity if Invalid). It determines whether alarm severity is propagated across links. If the attribute is MSI only a severity of `INVALID_ALARM` is propagated; settings of MS or MSS propagate all alarms that are more severe than the record's current severity. For input links the alarm severity of the record referred to by the link is propagated to the record containing the link. For output links the alarm severity of the record containing the link is propagated to the record referred to by the link. If the severity is changed the associated alarm status is set to `LINK_ALARM`, except if the attribute is MSS when the alarm status will be copied along with the severity.



Neutrons: verifying a radiotherapy system

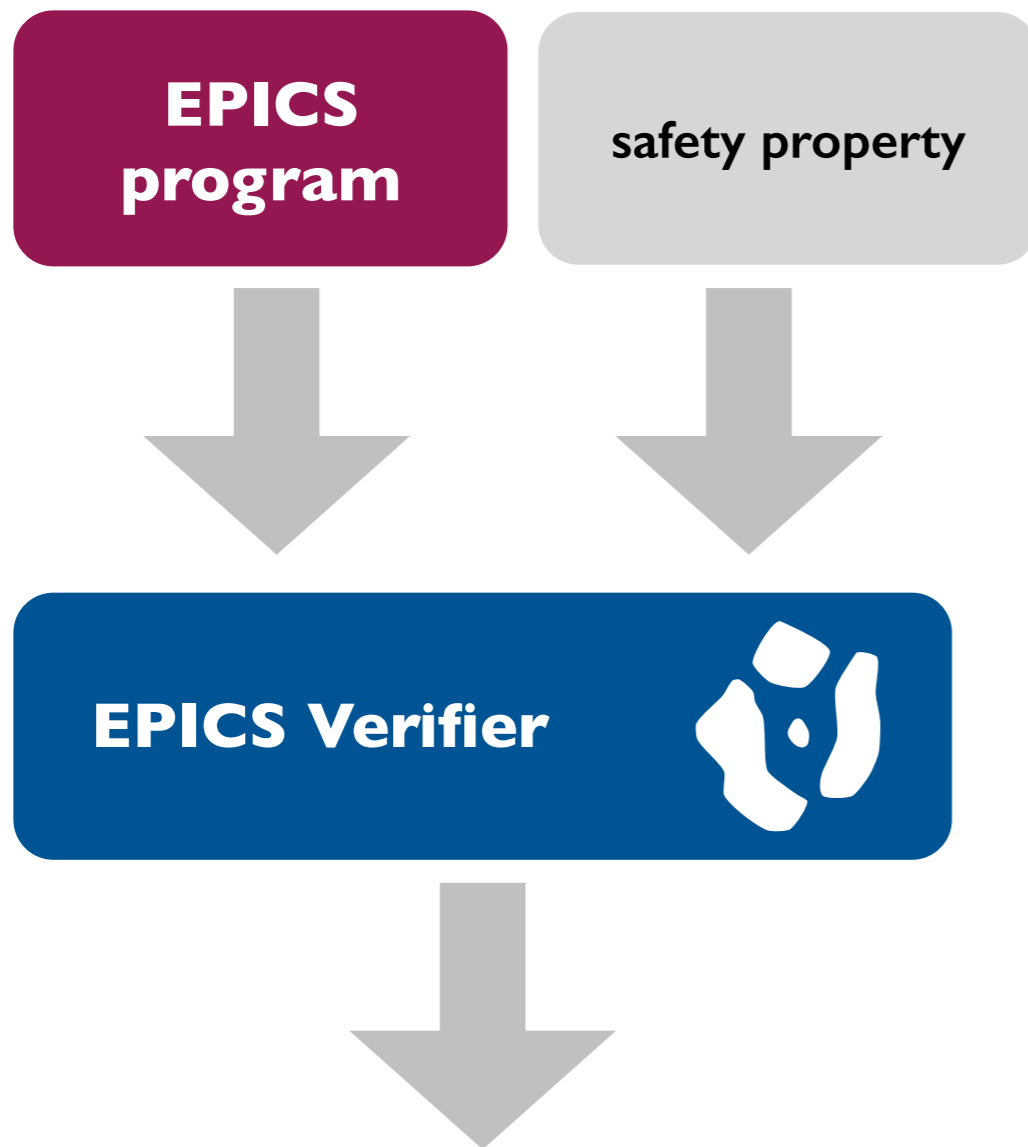


Built by a 2nd year grad in a few days



Calvin Loncaric

Neutrons: verifying a radiotherapy system



Found a bug in the EPICS runtime!
Therapy Control depended on this
bug for correct operation.



[Pernsteiner et al., CAV'16]

MemSynth: synthesizing memory models

Memory consistency models
define memory reordering
behaviors on multiprocessors.

$$\begin{array}{c|c} x = y = 0 & \\ \hline a = x & b = y \\ y = 1 & x = 1 \\ \hline a \equiv b \equiv 1 & \end{array}$$

MemSynth: synthesizing memory models

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Forbidden by sequential consistency.

Allowed by x86 and other hardware memory models.

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Forbidden by sequential consistency.

Allowed by x86 and other hardware memory models.

Formalizing memory models is hard: e.g., PowerPC formalized over 7 publications in 2009-2015.

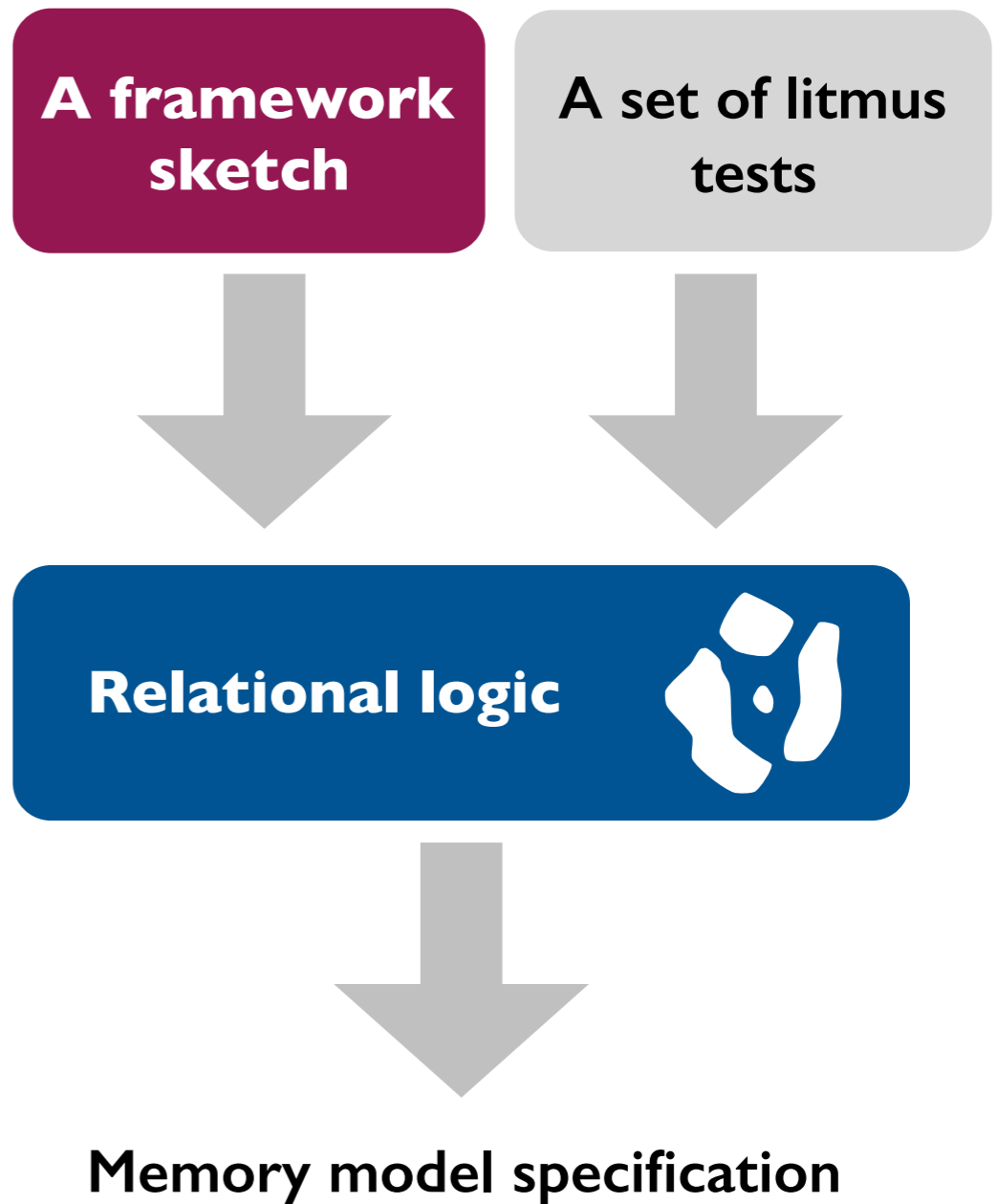
MemSynth: synthesizing memory models

Memory consistency models define memory reordering behaviors on multiprocessors.

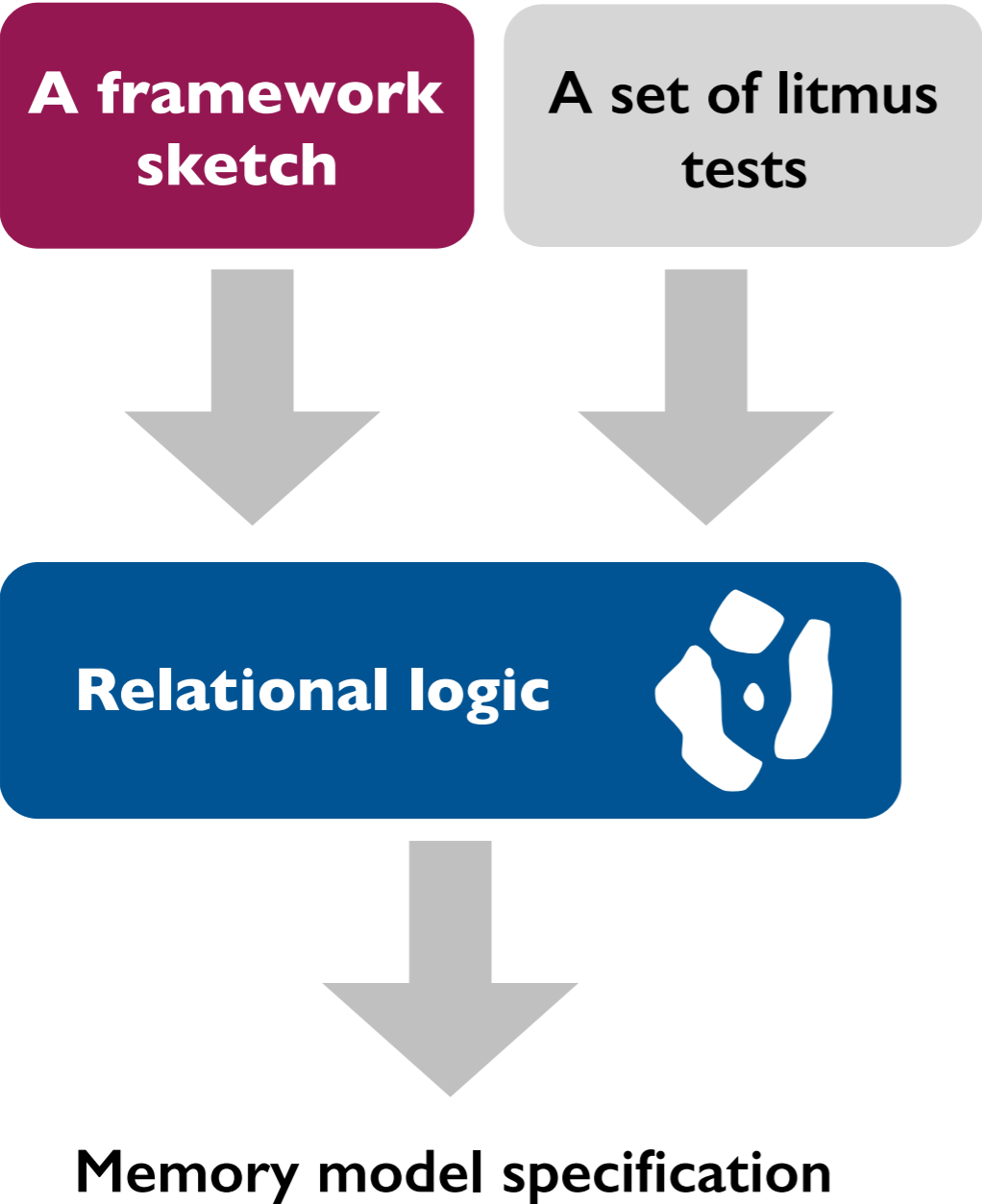
$x = y = 0$	
$a = x$	$b = y$
$y = 1$	$x = 1$
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MemSynth: synthesizing memory models

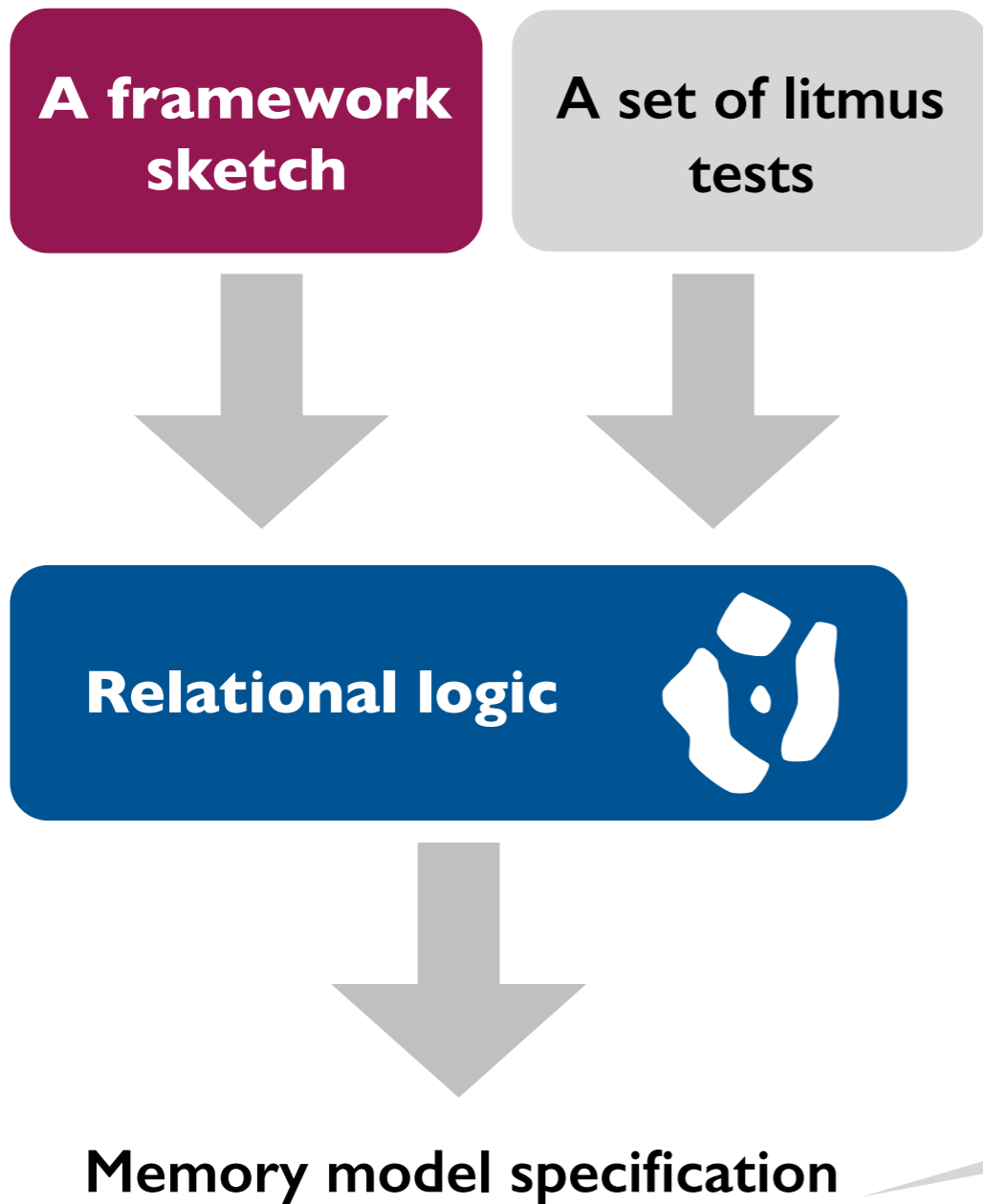


Built by a 2nd year grad in a few weeks



James Bornholt

MemSynth: synthesizing memory models



[Bornholt and Torlak, PLDI'17]

Synthesized PowerPC in 12 seconds from 768 previously published tests. Synthesized x86 in 2 seconds from Intel's litmus tests. Discovered 4 tests are missing from the Intel manual.



Thanks for a great quarter!

